

ZADÁNÍ
BAKALÁŘSKÉ PRÁCE

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Katedra:	Katedra teorie programování
Název práce:	Simulating RoFI Platform in GazeboSim
Název práce anglicky:	Simulating RoFI Platform in GazeboSim
Zadání:	RoFIBots are metamorphic robots constructed from a bunch of autonomous modules. The modules have limited capability of locomotion, however, when connected together, they may perform interesting robotic tasks. The goal of the thesis is to design and implement a plugin in the GazeboSim tool to allow a visual and physical simulation of RoFIBots in a virtual environment. A case study to demonstrate what has to be done by a user to get some RoFIBot model into the simulator and to simulate the execution of some RoFIBot program will be part of the thesis.