Gungnir's Standard Code Library[*]

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[*] https://github.com/footoredo/Gungnir

Contents

Chapter 1 计算几何

1.1 二维

1.1.1 基础

```cpp
int sign(DB x) {
    return (x > eps) - (x < -eps);
}
DB msqrt(DB x) {
    return sign(x) > 0 ? sqrt(x) : 0;
}

struct Point {
    DB x, y;
    Point rotate(DB ang) const {  // 逆时针旋转 ang 弧度
        return Point(cos(ang) * x - sin(ang) * y,
                cos(ang) * y + sin(ang) * x);
    }
    Point turn90() const {  // 逆时针旋转 90 度
        return Point(-y, x);
    }
    Point unit() const {
        return *this / len();
    }
};
DB dot(const Point& a, const Point& b) {
    return a.x * b.x + a.y * b.y;
}
DB det(const Point& a, const Point& b) {
    return a.x * b.y - a.y * b.x;
}
#define cross(p1,p2,p3) ((p2.x-p1.x)*(p3.y-p1.y)-(p3.x-p1.x)*(p2.y-p1.y))
#define crossOp(p1,p2,p3) sign(cross(p1,p2,p3))
bool isLL(const Line& l1, const Line& l2, Point& p) {  // 直线与直线交点
    DB s1 = det(l2.b - l2.a, l1.a - l2.a),
       s2 = -det(l2.b - l2.a, l1.b - l2.a);
    if (!sign(s1 + s2)) return false;
    p = (l1.a * s2 + l1.b * s1) / (s1 + s2);
    return true;
}
bool onSeg(const Line& l, const Point& p) {  // 点在线段上
    return sign(det(p - l.a, l.b - l.a)) == 0 && sign(dot(p - l.a, p - l.b)) <= 0;
}
Point projection(const Line & l, const Point& p) {
    return l.a + (l.b - l.a) * (dot(p - l.a, l.b - l.a) / (l.b - l.a).len2());
}
DB disToLine(const Line& l, const Point& p) {  // 点到 * 直线 * 距离
    return fabs(det(p - l.a, l.b - l.a) / (l.b - l.a).len());
}
DB disToSeg(const Line& l, const Point& p) {  // 点到线段距离
    return sign(dot(p - l.a, l.b - l.a)) * sign(dot(p - l.b, l.a - l.b)) == 1 ? disToLine(l, p) : std::min((p - l.a).len(), (p - l.b).len());
}
// 圆与直线交点
bool isCL(Circle a, Line l, Point& p1, Point& p2) {
    DB x = dot(l.a - a.o, l.b - l.a),
       y = (l.b - l.a).len2(),
       d = x * x - y * ((l.a - a.o).len2() - a.r * a.r);
    if (sign(d) < 0) return false;
    Point p = l.a - ((l.b - l.a) * (x / y)), delta = (l.b - l.a) * (msqrt(d) / y);
    p1 = p + delta; p2 = p - delta;
    return true;
}
//圆与圆的交面积
DB areaCC(const Circle& c1, const Circle& c2) {
    DB d = (c1.o - c2.o).len();
    if (sign(d - (c1.r + c2.r)) >= 0) return 0;
    if (sign(d - std::abs(c1.r - c2.r)) <= 0) {
        DB r = std::min(c1.r, c2.r);
        return r * r * PI;
    }
    DB x = (d * d + c1.r * c1.r - c2.r * c2.r) / (2 * d),
        t1 = acos(x / c1.r), t2 = acos((d - x) / c2.r);
    return c1.r * c1.r * t1 + c2.r * c2.r * t2 - d * c1.r * sin(t1);
}
// 圆与圆交点
bool isCC(Circle a, Circle b, P& p1, P& p2) {
    DB s1 = (a.o - b.o).len();
    if (sign(s1 - a.r - b.r) > 0 || sign(s1 - std::abs(a.r - b.r)) < 0) return false;
    DB s2 = (a.r * a.r - b.r * b.r) / s1;
    DB aa = (s1 + s2) * 0.5, bb = (s1 - s2) * 0.5;
    P o = (b.o - a.o) * (aa / (aa + bb)) + a.o;
    P delta = (b.o - a.o).unit().turn90() * msqrt(a.r * a.r - aa * aa);
    p1 = o + delta, p2 = o - delta;
    return true;
}
// 求点到圆的切点，按关于点的顺时针方向返回两个点
bool tanCP(const Circle &c, const Point &p0, Point &p1, Point &p2) {
    double x = (p0 - c.o).len2(), d = x - c.r * c.r;
    if (d < eps) return false; // 点在圆上认为没有切点
    Point p = (p0 - c.o) * (c.r / x);
    Point delta = ((p0 - c.o) * (-c.r * sqrt(d) / x)).turn90();
    p1 = c.o + p + delta;
    p2 = c.o + p - delta;
    return true;
}
// 求圆到圆的外共切线，按关于 c1.o 的顺时针方向返回两条线
vector<Line> extanCC(const Circle &c1, const Circle &c2) {
    vector<Line> ret;
    if (sign(c1.r - c2.r) == 0) {
        Point dir = c2.o - c1.o;
        dir = (dir * (c1.r / dir.len())).turn90();
        ret.push_back(Line(c1.o + dir, c2.o + dir));
        ret.push_back(Line(c1.o - dir, c2.o - dir));
    } else {
        Point p = (c1.o * -c2.r + c2.o * c1.r) / (c1.r - c2.r);
        Point p1, p2, q1, q2;
        if (tanCP(c1, p, p1, p2) && tanCP(c2, p, q1, q2)) {
            if (c1.r < c2.r) swap(p1, p2), swap(q1, q2);
            ret.push_back(Line(p1, q1));
            ret.push_back(Line(p2, q2));
        }
    }
    return ret;
}
// 求圆到圆的内共切线，按关于 c1.o 的顺时针方向返回两条线
std::vector<Line> intanCC(const Circle &c1, const Circle &c2) {
    std::vector<Line> ret;
    Point p = (c1.o * c2.r + c2.o * c1.r) / (c1.r + c2.r);
    Point p1, p2, q1, q2;
    if (tanCP(c1, p, p1, p2) && tanCP(c2, p, q1, q2)) { // 两圆相切认为没有切线
        ret.push_back(Line(p1, q1));
        ret.push_back(Line(p2, q2));
    }
    return ret;
}
bool contain(vector<Point> polygon, Point p) { // 判断点 p 是否被多边形包含，包括落在边界上
    int ret = 0, n = polygon.size();
    for(int i = 0; i < n; ++ i) {
        Point u = polygon[i], v = polygon[(i + 1) % n];
        if (onSeg(Line(u, v), p)) return true;  // Here I guess.
        if (sign(u.y - v.y) <= 0) swap(u, v);
        if (sign(p.y - u.y) > 0 || sign(p.y - v.y) <= 0) continue;
        ret += sign(det(p, v, u)) > 0;
    }
    return ret & 1;
}
// 用半平面 (q1,q2) 的逆时针方向去切凸多边形
```

```
std::vector<Point> convexCut(const std::vector<Point>&ps, Point q1, Point q2) {
    std::vector<Point> qs; int n = ps.size();
    for (int i = 0; i < n; ++i) {
        Point p1 = ps[i], p2 = ps[(i + 1) % n];
        int d1 = crossOp(q1,q2,p1), d2 = crossOp(q1,q2,p2);
        if (d1 >= 0) qs.push_back(p1);
        if (d1 * d2 < 0) qs.push_back(isSS(p1, p2, q1, q2));
    }
    return qs;
}
// 求凸包
std::vector<Point> convexHull(std::vector<Point> ps) {
    int n = ps.size(); if (n <= 1) return ps;
    std::sort(ps.begin(), ps.end());
    std::vector<Point> qs;
    for (int i = 0; i < n; qs.push_back(ps[i ++]))
        while (qs.size() > 1 && sign(det(qs[qs.size() - 2], qs.back(), ps[i])) <= 0)
            qs.pop_back();
    for (int i = n - 2, t = qs.size(); i >= 0; qs.push_back(ps[i --]))
        while ((int)qs.size() > t && sign(det(qs[qs.size() - 2], qs.back(), ps[i])) <=
  ↪ 0)
            qs.pop_back();
    return qs;
```

1.1.2 凸包

```
// 凸包中的点按逆时针方向
struct Convex {
    int n;
    std::vector<Point> a, upper, lower;
    void make_shell(const std::vector<Point>& p,
            std::vector<Point>& shell) {  // p needs to be sorted.
        clear(shell); int n = p.size();
        for (int i = 0, j = 0; i < n; i++, j++) {
            for (; j >= 2 && sign(det(shell[j-1] - shell[j-2],
                            p[i] - shell[j-2])) <= 0; --j) shell.pop_back();
            shell.push_back(p[i]);
        }
    }
    void make_convex() {
        std::sort(a.begin(), a.end());
        make_shell(a, lower);
        std::reverse(a.begin(), a.end());
        make_shell(a, upper);
        a = lower; a.pop_back();
        a.insert(a.end(), upper.begin(), upper.end());
        if ((int)a.size() >= 2) a.pop_back();
        n = a.size();
    }
    void init(const std::vector<Point>& _a) {
        clear(a); a = _a; n = a.size();
        make_convex();
    }
    void read(int _n) {  // Won't make convex.
        clear(a); n = _n; a.resize(n);
        for (int i = 0; i < n; i++)
            a[i].read();
    }
    std::pair<DB, int> get_tangent(
            const std::vector<Point>& convex, const Point& vec) {
        int l = 0, r = (int)convex.size() - 2;
        assert(r >= 0);
        for (; l + 1 < r; ) {
            int mid = (l + r) / 2;
            if (sign(det(convex[mid + 1] - convex[mid], vec)) > 0)
                r = mid;
            else l = mid;
        }
        return std::max(std::make_pair(det(vec, convex[r]), r),
                std::make_pair(det(vec, convex[0]), 0));
    }
    int binary_search(Point u, Point v, int l, int r) {
        int s1 = sign(det(v - u, a[l % n] - u));
        for (; l + 1 < r; ) {
            int mid = (l + r) / 2;
            int smid = sign(det(v - u, a[mid % n] - u));
            if (smid == s1) l = mid;
            else r = mid;
        }
        return l % n;
    }
    // 求凸包上和向量 vec 叉积最大的点，返回编号，共线的多个切点返回任意一个
    int get_tangent(Point vec) {
        std::pair<DB, int> ret = get_tangent(upper, vec);
        ret.second = (ret.second + (int)lower.size() - 1) % n;
        ret = std::max(ret, get_tangent(lower, vec));
        return ret.second;
    }
    // 求凸包和直线 u, v 的交点，如果不相交返回 false，如果有则是和 (i, next(i)) 的
  ↪ 交点，交在点上不确定返回前后两条边其中之一
    bool get_intersection(Point u, Point v, int &i0, int &i1) {
        int p0 = get_tangent(u - v), p1 = get_tangent(v - u);
        if (sign(det(v - u, a[p0] - u)) * sign(det(v - u, a[p1] - u)) <= 0) {
            if (p0 > p1) std::swap(p0, p1);
            i0 = binary_search(u, v, p0, p1);
            i1 = binary_search(u, v, p1, p0 + n);
            return true;
        }
        else return false;
    }
};
```

1.1.3 三角形的心

```
Point inCenter(const Point &A, const Point &B, const Point &C) { // 内心
    double a = (B - C).len(), b = (C - A).len(), c = (A - B).len(),
        s = fabs(det(B - A, C - A)),
        r = s / p;
    return (A * a + B * b + C * c) / (a + b + c);
}
Point circumCenter(const Point &a, const Point &b, const Point &c) { // 外心
    Point bb = b - a, cc = c - a;
    double db = bb.len2(), dc = cc.len2(), d = 2 * det(bb, cc);
    return a - Point(bb.y * dc - cc.y * db, cc.x * db - bb.x * dc) / d;
}
Point othroCenter(const Point &a, const Point &b, const Point &c) { // 垂心
    Point ba = b - a, ca = c - a, bc = b - c;
    double Y = ba.y * ca.y * bc.y,
           A = ca.x * ba.y - ba.x * ca.y,
           x0 = (Y + ca.x * ba.y * b.x - ba.x * ca.y * c.x) / A,
           y0 = -ba.x * (x0 - c.x) / ba.y + ca.y;
    return Point(x0, y0);
}
```

1.1.4 半平面交

```
struct Point {
    int quad() const { return sign(y) == 1 || (sign(y) == 0 && sign(x) >= 0);}
};
struct Line {
    bool include(const Point &p) const { return sign(det(b - a, p - a)) > 0; }
    Line push() const{ // 将半平面向外推 eps
        const double eps = 1e-6;
        Point delta = (b - a).turn90().norm() * eps;
        return Line(a - delta, b - delta);
    }
};
bool sameDir(const Line &l0, const Line &l1) { return parallel(l0, l1) &&
  ↪ sign(dot(l0.b - l0.a, l1.b - l1.a)) == 1; }
bool operator < (const Point &a, const Point &b) {
    if (a.quad() != b.quad()) {
        return a.quad() < b.quad();
    } else {
        return sign(det(a, b)) > 0;
    }
}
bool operator < (const Line &l0, const Line &l1) {
    if (sameDir(l0, l1)) {
        return l1.include(l0.a);
    } else {
        return (l0.b - l0.a) < (l1.b - l1.a);
    }
}
bool check(const Line &u, const Line &v, const Line &w) { return w.include(intersect(u, v)); }
vector<Point> intersection(vector<Line> &l) {
    sort(l.begin(), l.end());
    deque<Line> q;
    for (int i = 0; i < (int)l.size(); ++i) {
        if (i && sameDir(l[i], l[i - 1])) {
            continue;
        }
        while (q.size() > 1 && !check(q[q.size() - 2], q[q.size() - 1], l[i])) q.pop_back();
        while (q.size() > 1 && !check(q[1], q[0], l[i])) q.pop_front();
        q.push_back(l[i]);
    }
    while (q.size() > 2 && !check(q[q.size() - 2], q[q.size() - 1], q[0])) q.pop_back();
    while (q.size() > 2 && !check(q[1], q[0], q[q.size() - 1])) q.pop_front();
    vector<Point> ret;
    for (int i = 0; i < (int)q.size(); ++i) ret.push_back(intersect(q[i], q[(i + 1) % q.size()]));
    return ret;
}
```

1.1.5 圆交面积及重心

```
struct Event {
    Point p;
    double ang;
    int delta;
    Event (Point p = Point(0, 0), double ang = 0, double delta = 0) : p(p), ang(ang), delta(delta) {}
};
bool operator < (const Event &a, const Event &b) {
    return a.ang < b.ang;
}
void addEvent(const Circle &a, const Circle &b, vector<Event> &evt, int &cnt) {
    double d2 = (a.o - b.o).len2(),
           dRatio = ((a.r - b.r) * (a.r + b.r) / d2 + 1) / 2,
           pRatio = sqrt(-(d2 - sqr(a.r - b.r)) * (d2 - sqr(a.r + b.r)) / (d2 * d2 * 4));
    Point d = b.o - a.o, p = d.rotate(PI / 2),
          q0 = a.o + d * dRatio + p * pRatio,
          q1 = a.o + d * dRatio - p * pRatio;
    double ang0 = (q0 - a.o).ang(),
           ang1 = (q1 - a.o).ang();
    evt.push_back(Event(q1, ang1, 1));
    evt.push_back(Event(q0, ang0, -1));
    cnt += ang1 > ang0;
}
bool issame(const Circle &a, const Circle &b) { return sign((a.o - b.o).len()) == 0 && sign(a.r - b.r) == 0; }
bool overlap(const Circle &a, const Circle &b) { return sign(a.r - b.r - (a.o - b.o).len()) >= 0; }
bool intersect(const Circle &a, const Circle &b) { return sign((a.o - b.o).len() - a.r - b.r) < 0; }
Circle c[N];
double area[N];  // area[k] -> area of intersections >= k.
Point centroid[N];
bool keep[N];
void add(int cnt, DB a, Point c) {
    area[cnt] += a;
    centroid[cnt] = centroid[cnt] + c * a;
}
void solve(int n) {
    for (int i = 0; i < n; ++ i){
        keep[i] = true;
        for (int j = 0; j < n; ++ j) if (i != j) {
            if ((issame(c[i], c[j]) && i < j) || (!issame(c[i], c[j]) && overlap(c[j], c[i]))){
                keep[i] = false;
                break;
            }
        }
    }
    int C = 0;
    for (int i = 0; i < n; ++ i)
        if (keep[i]) c[C ++] = c[i];
    for (int i = 1; i <= C; ++ i) {
        area[i] = 0;
        centroid[i] = Point(0, 0);
    }
    for (int i = 0; i < C; ++i) {
        int cnt = 1;
        vector<Event> evt;
        for (int j = 0; j < C; ++j) {
            if (j != i && intersect(c[i], c[j])) {
                addEvent(c[i], c[j], evt, cnt);
            }
        }
        if (evt.size() == 0u) {
            add(cnt, PI * c[i].r * c[i].r, c[i].o);
        } else {
            sort(evt.begin(), evt.end());
            evt.push_back(evt.front());
            for (int j = 0; j + 1 < (int)evt.size(); ++j) {
                cnt += evt[j].delta;
                add(cnt, det(evt[j].p, evt[j + 1].p) / 2, (evt[j].p + evt[j + 1].p) / 3);
                double ang = evt[j + 1].ang - evt[j].ang;
                if (ang < 0) {
                    ang += PI * 2;
                }
                if (sign(ang) == 0) continue;
                add(cnt, ang * c[i].r * c[i].r / 2, c[i].o +
                    Point(sin(ang1) - sin(ang0), -cos(ang1) + cos(ang0)) * (2 / (3 * ang) * c[i].r));
                add(cnt, -sin(ang) * c[i].r * c[i].r / 2, (c[i].o + evt[j].p + evt[j + 1].p) / 3);
            }
        }
    }
    for (int i = 1; i <= C; ++ i)
        if (sign(area[i])) {
            centroid[i] = centroid[i] / area[i];
        }
}
```

1.2 三维

1.2.1 基础

```
// 三维绕轴旋转，大拇指指向 axis 向量方向，四指弯曲方向转 w 弧度
Point rotate(const Point& s, const Point& axis, DB w) {
    DB x = axis.x, y = axis.y, z = axis.z;
    DB s1 = x * x + y * y + z * z, ss1 = msqrt(s1),
       cosw = cos(w), sinw = sin(w);
    DB a[4][4];
    memset(a, 0, sizeof a);
    a[3][3] = 1;
    a[0][0] = ((y * y + z * z) * cosw + x * x) / s1;
    a[0][1] = x * y * (1 - cosw) / s1 + z * sinw / ss1;
    a[0][2] = x * z * (1 - cosw) / s1 - y * sinw / ss1;
    a[1][0] = x * y * (1 - cosw) / s1 - z * sinw / ss1;
    a[1][1] = ((x * x + z * z) * cosw + y * y) / s1;
    a[1][2] = y * z * (1 - cosw) / s1 + x * sinw / ss1;
    a[2][0] = x * z * (1 - cosw) / s1 + y * sinw / ss1;
    a[2][1] = y * z * (1 - cosw) / s1 - x * sinw / ss1;
    a[2][2] = ((x * x + y * y) * cos(w) + z * z) / s1;
    DB ans[4] = {0, 0, 0, 0}, c[4] = {s.x, s.y, s.z, 1};
    for (int i = 0; i < 4; ++ i)
        for (int j = 0; j < 4; ++ j)
            ans[i] += a[j][i] * c[j];
    return Point(ans[0], ans[1], ans[2]);
}
```

1.2.2 凸包

```
__inline P cross(const P& a, const P& b) {
    return P(
            a.y * b.z - a.z * b.y,
            a.z * b.x - a.x * b.z,
            a.x * b.y - a.y * b.x
        );
}

__inline DB mix(const P& a, const P& b, const P& c) {
    return dot(cross(a, b), c);
}

__inline DB volume(const P& a, const P& b, const P& c, const P& d) {
    return mix(b - a, c - a, d - a);
}

struct Face {
    int a, b, c;
    __inline Face() {}
    __inline Face(int _a, int _b, int _c):
        a(_a), b(_b), c(_c) {}
    __inline DB area() const {
        return 0.5 * cross(p[b] - p[a], p[c] - p[a]).len();
    }
    __inline P normal() const {
        return cross(p[b] - p[a], p[c] - p[a]).unit();
    }
    __inline DB dis(const P& p0) const {
        return dot(normal(), p0 - p[a]);
    }
};

std::vector<Face> face, tmp;  // Should be O(n).
int mark[N][N], Time, n;

__inline void add(int v) {
    ++ Time;
    clear(tmp);
    for (int i = 0; i < (int)face.size(); ++ i) {
        int a = face[i].a, b = face[i].b, c = face[i].c;
        if (sign(volume(p[v], p[a], p[b], p[c])) > 0) {
            mark[a][b] = mark[b][a] = mark[a][c] =
                mark[c][a] = mark[b][c] = mark[c][b] = Time;
        }
        else {
            tmp.push_back(face[i]);
        }
    }
    clear(face); face = tmp;
    for (int i = 0; i < (int)tmp.size(); ++ i) {
        int a = face[i].a, b = face[i].b, c = face[i].c;
        if (mark[a][b] == Time) face.emplace_back(v, b, a);
        if (mark[b][c] == Time) face.emplace_back(v, c, b);
        if (mark[c][a] == Time) face.emplace_back(v, a, c);
        assert(face.size() < 500u);
    }
}

void reorder() {
    for (int i = 2; i < n; ++ i) {
        P tmp = cross(p[i] - p[0], p[i] - p[1]);
        if (sign(tmp.len())) {
            std::swap(p[i], p[2]);
            for (int j = 3; j < n; ++ j)
                if (sign(volume(p[0], p[1], p[2], p[j]))) {
                    std::swap(p[j], p[3]);
                    return;
                }
        }
    }
}

void build_convex() {
    reorder();
    clear(face);
    face.emplace_back(0, 1, 2);
    face.emplace_back(0, 2, 1);
    for (int i = 3; i < n; ++ i)
        add(i);
}
```

Chapter 2 数论

2.1 $O(m^2 \log n)$ 求线性递推数列第 n 项

Given $a_0, a_1, \ldots, a_{m-1}$
$a_n = c_0 \times a_{n-m} + \cdots + c_{m-1} \times a_{n-1}$
Solve for $a_n = v_0 \times a_0 + v_1 \times a_1 + \cdots + v_{m-1} \times a_{m-1}$

```
void linear_recurrence(long long n, int m, int a[], int c[], int p) {
    long long v[M] = {1 % p}, u[M << 1], msk = !!n;
    for(long long i(n); i > 1; i >>= 1) {
        msk <<= 1;
    }
    for(long long x(0); msk; msk >>= 1, x <<= 1) {
        fill_n(u, m << 1, 0);
        int b(!!(n & msk));
        x |= b;
        if(x < m) {
            u[x] = 1 % p;
        }else {
            for(int i(0); i < m; i++) {
                for(int j(0), t(i + b); j < m; j++, t++) {
                    u[t] = (u[t] + v[i] * v[j]) % p;
                }
            }
            for(int i((m << 1) - 1); i >= m; i--) {
                for(int j(0), t(i - m); j < m; j++, t++) {
                    u[t] = (u[t] + c[j] * u[i]) % p;
                }
            }
        }
        copy(u, u + m, v);
    }
    //a[n] = v[0] * a[0] + v[1] * a[1] + ... + v[m - 1] * a[m - 1].
    for(int i(m); i < 2 * m; i++) {
        a[i] = 0;
        for(int j(0); j < m; j++) {
            a[i] = (a[i] + (long long)c[j] * a[i + j - m]) % p;
        }
    }
    for(int j(0); j < m; j++) {
        b[j] = 0;
        for(int i(0); i < m; i++) {
            b[j] = (b[j] + v[i] * a[i + j]) % p;
        }
    }
    for(int j(0); j < m; j++) {
        a[j] = b[j];
    }
}
```

2.2 求逆元

```
void ex_gcd(long long a, long long b, long long &x, long long &y) {
    if (b == 0) {
        x = 1;
        y = 0;
        return;
    }
    long long xx, yy;
    ex_gcd(b, a % b, xx, yy);
    y = xx - a / b * yy;
    x = yy;
}

long long inv(long long x, long long MODN) {
    long long inv_x, y;
    ex_gcd(x, MODN, inv_x, y);
    return (inv_x % MODN + MODN) % MODN;
}
```

2.3 中国剩余定理

```
// 返回 (ans, M)，其中 ans 是模 M 意义下的解
std::pair<long long, long long> CRT(const std::vector<long long>& m, const std::vector<long long>& a) {
    long long M = 1, ans = 0;
    int n = m.size();
    for (int i = 0; i < n; i++) M *= m[i];
    for (int i = 0; i < n; i++) {
        ans = (ans + (M / m[i]) * a[i] % M * inv(M / m[i], m[i])) % M;  // 可能需要大整数相乘取模
    }
    return std::make_pair(ans, M);
}
```

2.4 素性测试

```
int strong_pseudo_primetest(long long n,int base) {
    long long n2=n-1,res;
    int s=0;
    while(n2%2==0) n2>>=1,s++;
    res=powmod(base,n2,n);
    if((res==1)||(res==n-1)) return 1;
    s--;
    while(s>=0) {
        res=mulmod(res,res,n);
        if(res==n-1) return 1;
        s--;
    }
    return 0; // n is not a strong pseudo prime
}
int isprime(long long n) {
    static LL testNum[]={2,3,5,7,11,13,17,19,23,29,31,37};
    static LL lim[]={4,0,1373653LL,25326001LL,25000000000LL,2152302898747LL,3474749660383LL,341550071728321LL,0,0,0,0};
    if(n<2||n==3215031751LL) return 0;
    for(int i=0;i<12;++i){
        if(n<lim[i]) return 1;
        if(strong_pseudo_primetest(n,testNum[i])==0) return 0;
    }
```

```
    return 1;
}
```

2.5 质因数分解

```
int ansn; LL ans[1000];
LL func(LL x,LL n){ return(mod_mul(x,x,n)+1)%n; }
LL Pollard(LL n){
    LL i,x,y,p;
    if(Rabin_Miller(n)) return n;
    if(!(n&1)) return 2;
    for(i=1;i<20;i++){
        x=i; y=func(x,n); p=gcd(y-x,n);
        while(p==1) {x=func(x,n); y=func(func(y,n),n); p=gcd((y-x+n)%n,n)%n;}
        if(p==0||p==n) continue;
        return p;
    }
}
void factor(LL n){
    LL x;
    x=Pollard(n);
    if(x==n){ ans[ansn++]=x; return; }
    factor(x), factor(n/x);
}
```

2.6 线下整点

```
// $\sum_{i=0}^{n-1}\lfloor\frac{a+bi}{m}\rfloor$, $n,m,a,b>0$
LL solve(LL n,LL a,LL b,LL m){
    if(b==0) return n*(a/m);
    if(a>=m) return n*(a/m)+solve(n,a%m,b,m);
    if(b>=m) return (n-1)*n/2*(b/m)+solve(n,a,b%m,m);
    return solve((a+b*n)/m,(a+b*n)%m,m,b);
}
```

Chapter 3 代数

3.1 快速傅里叶变换

```
// n 必须是 2 的次幂
void fft(Complex a[], int n, int f) {
    for (int i = 0; i < n; ++i)
        if (R[i] < i) swap(a[i], a[R[i]]);
    for (int i = 1, h = 0; i < n; i <<= 1, h++) {
        Complex wn = Complex(cos(pi / i), f * sin(pi / i));
        Complex w = Complex(1, 0);
        for (int k = 0; k < i; ++k, w = w * wn) tmp[k] = w;
        for (int p = i << 1, j = 0; j < n; j += p) {
            for (int k = 0; k < i; ++k) {
                Complex x = a[j + k], y = a[j + k + i] * tmp[k];
                a[j + k] = x + y; a[j + k + i] = x - y;
            }
        }
    }
}
```

3.2 自适应辛普森积分

```
namespace adaptive_simpson {
    template<typename function>
    inline double area(function f, const double &left, const double &right) {
        double mid = (left + right) / 2;
        return (right - left) * (f(left) + 4 * f(mid) + f(right)) / 6;
    }

    template<typename function>
    inline double simpson(function f, const double &left, const double &right, const double &eps, const double &area_sum) {
        double mid = (left + right) / 2;
        double area_left = area(f, left, mid);
        double area_right = area(f, mid, right);
        double area_total = area_left + area_right;
        if (fabs(area_total - area_sum) <= 15 * eps) {
            return area_total + (area_total - area_sum) / 15;
        }
        return simpson(f, left, right, eps / 2, area_left) + simpson(f, mid, right, eps / 2, area_right);
    }

    template<typename function>
    inline double simpson(function f, const double &left, const double &right, const double &eps) {
        return simpson(f, left, right, eps, area(f, left, right));
    }
}
```

3.3 单纯形

```
const double eps = 1e-8;
// max{c * x | Ax <= b, x >= 0} 的解，无解返回空的 vector，否则就是解.
vector<double> simplex(vector<vector<double> > &A, vector<double> b, vector<double> c) {
    int n = A.size(), m = A[0].size() + 1, r = n, s = m - 1;
    vector<vector<double> > D(n + 2, vector<double>(m + 1));
    vector<int> ix(n + m);
    for(int i = 0; i < n + m; i++)  {
        ix[i] = i;
    }
    for(int i = 0; i < n; i++) {
        for(int j = 0; j < m - 1; j++) {
            D[i][j] = -A[i][j];
        }
        D[i][m - 1] = 1;
        D[i][m] = b[i];
        if (D[r][m] > D[i][m]) {
            r = i;
        }
    }

    for(int j = 0; j < m - 1; j++) {
        D[n][j] = c[j];
    }
    D[n + 1][m - 1] = -1;
    for(double d; ;) {
        if (r < n) {
            swap(ix[s], ix[r + m]);
            D[r][s] = 1. / D[r][s];
            for(int j = 0; j <= m; j++) {
                if (j != s) {
                    D[r][j] *= -D[r][s];
                }
            }
            for(int i = 0; i <= n + 1; i++) {
                if (i != r) {
                    for(int j = 0; j <= m; j++) {
                        if (j != s) {
                            D[i][j] += D[r][j] * D[i][s];
                        }
                    }
                    D[i][s] *= D[r][s];
                }
            }
        }
        r = -1, s = -1;
        for(int j = 0; j < m; j++) {
            if (s < 0 || ix[s] > ix[j]) {
                if (D[n + 1][j] > eps || D[n + 1][j] > -eps && D[n][j] > eps) {
                    s = j;
                }
            }
        }
        if (s < 0) {
            break;
        }
        for(int i = 0; i < n; i++) {
            if (D[i][s] < -eps) {
                if (r < 0 || (d = D[r][m] / D[r][s] - D[i][m] / D[i][s]) < -eps
                    || d < eps && ix[r + m] > ix[i + m]) {

                    r = i;
                }
            }
        }

        if (r < 0) {
            return vector<double> ();
        }
    }
    if (D[n + 1][m] < -eps) {
        return vector<double> ();
    }

    vector<double> x(m - 1);
    for(int i = m; i < n + m; i++) {
        if (ix[i] < m - 1) {
            x[ix[i]] = D[i - m][m];
        }
    }
    return x;
}
```

Chapter 4 字符串

4.1 后缀数组

```
const int MAXN = MAXL * 2 + 1;
int a[MAXN], x[MAXN], y[MAXN], c[MAXN], sa[MAXN], rank[MAXN], height[MAXN];
void calc_sa(int n) {
    int m = alphabet, k = 1;
    memset(c, 0, sizeof(*c) * (m + 1));
    for (int i = 1; i <= n; ++i) c[x[i] = a[i]]++;
    for (int i = 1; i <= m; ++i) c[i] += c[i - 1];
    for (int i = n; i; --i) sa[c[x[i]]--] = i;
    for (; k <= n; k <<= 1) {
        int tot = k;
        for (int i = n - k + 1; i <= n; ++i) y[i - n + k] = i;
        for (int i = 1; i <= n; ++i)
            if (sa[i] > k) y[++tot] = sa[i] - k;
        memset(c, 0, sizeof(*c) * (m + 1));
        for (int i = 1; i <= n; ++i) c[x[i]]++;
        for (int i = 1; i <= m; ++i) c[i] += c[i - 1];
        for (int i = n; i; --i) sa[c[x[y[i]]]--] = y[i];
        for (int i = 1; i <= n; ++i) y[i] = x[i];
        tot = 1; x[sa[1]] = 1;
        for (int i = 2; i <= n; ++i) {
            if (max(sa[i], sa[i - 1]) + k > n || y[sa[i]] != y[sa[i - 1]] || y[sa[i] + k] != y[sa[i - 1] + k]) ++tot;
            x[sa[i]] = tot;
        }
        if (tot == n) break; else m = tot;
    }
}
void calc_height(int n) {
    for (int i = 1; i <= n; ++i) rank[sa[i]] = i;
    for (int i = 1; i <= n; ++i) {
        height[rank[i]] = max(0, height[rank[i - 1]] - 1);
        if (rank[i] == 1) continue;
        int j = sa[rank[i] - 1];
        while (max(i, j) + height[rank[i]] <= n && a[i + height[rank[i]]] == a[j + height[rank[i]]]) ++height[rank[i]];
    }
}
```

4.2 后缀自动机

```
static const int MAXL = MAXN * 2;  // MAXN is original length
static const int alphabet = 26;  // sometimes need changing
int l, last, cnt, trans[MAXL][alphabet], par[MAXL], sum[MAXL], seq[MAXL], mxl[MAXL], size[MAXL];  // mxl is maxlength, size is the size of right
char str[MAXL];
inline void init() {
    l = strlen(str + 1); cnt = last = 1;
    for (int i = 0; i <= l * 2; ++i) memset(trans[i], 0, sizeof(trans[i]));
    memset(par, 0, sizeof(*par) * (l * 2 + 1));
    memset(mxl, 0, sizeof(*mxl) * (l * 2 + 1));
    memset(size, 0, sizeof(*size) * (l * 2 + 1));
}
inline void extend(int pos, int c) {
    int p = last, np = last = ++cnt;
    mxl[np] = mxl[p] + 1; size[np] = 1;
    for (; p && !trans[p][c]; p = par[p]) trans[p][c] = np;
    if (!p) par[np] = 1;
    else {
        int q = trans[p][c];
        if (mxl[p] + 1 == mxl[q]) par[np] = q;
        else {
            int nq = ++cnt;
            mxl[nq] = mxl[p] + 1;
            memcpy(trans[nq], trans[q], sizeof(trans[nq]));
            par[nq] = par[q];
            par[np] = par[q] = nq;
            for (; trans[p][c] == q; p = par[p]) trans[p][c] = nq;
        }
    }
}
inline void buildsam() {
    for (int i = 1; i <= l; ++i) extend(i, str[i] - 'a');
    memset(sum, 0, sizeof(*sum) * (l * 2 + 1));
    for (int i = 1; i <= cnt; ++i) sum[mxl[i]]++;
    for (int i = 1; i <= l; ++i) sum[i] += sum[i - 1];
    for (int i = cnt; i; --i) seq[sum[mxl[i]]--] = i;
    for (int i = cnt; i; --i) size[par[seq[i]]] += size[seq[i]];
}
```

4.3 EX 后缀自动机

```
inline void add_node(int x, int &last) {
    int lastnode = last;
    if (c[lastnode][x]) {
        int nownode = c[lastnode][x];
        if (l[nownode] == l[lastnode] + 1) last = nownode;
        else {
            int auxnode = ++cnt; l[auxnode] = l[lastnode] + 1;
            for (int i = 0; i < alphabet; ++i) c[auxnode][i] = c[nownode][i];
            par[auxnode] = par[nownode]; par[nownode] = auxnode;
            for (; lastnode && c[lastnode][x] == nownode; lastnode = par[lastnode]) {
                c[lastnode][x] = auxnode;
            }
            last = auxnode;
        }
    } else {
        int newnode = ++cnt; l[newnode] = l[lastnode] + 1;
        for (; lastnode && !c[lastnode][x]; lastnode = par[lastnode]) c[lastnode][x] = newnode;
        if (!lastnode) par[newnode] = 1;
        else {
            int nownode = c[lastnode][x];
            if (l[lastnode] + 1 == l[nownode]) par[newnode] = nownode;
            else {
                int auxnode = ++cnt; l[auxnode] = l[lastnode] + 1;
                for (int i = 0; i < alphabet; ++i) c[auxnode][i] = c[nownode][i];
                par[auxnode] = par[nownode]; par[nownode] = par[newnode] = auxnode;
                for (; lastnode && c[lastnode][x] == nownode; lastnode = par[lastnode]) {
                    c[lastnode][x] = auxnode;
                }
            }
        }
        last = newnode;
    }
}
```

4.4 回文自动机

```
int nT, nStr, last, c[MAXT][26], fail[MAXT], r[MAXN], l[MAXN], s[MAXN];
int allocate(int len) {
    l[nT] = len;
    r[nT] = 0;
    fail[nT] = 0;
    memset(c[nT], 0, sizeof(c[nT]));
    return nT++;
}
void init() {
    nT = nStr = 0;
    int newE = allocate(0);
    int newO = allocate(-1);
    last = newE;
    fail[newE] = newO;
    fail[newO] = newE;
    s[0] = -1;
}
void add(int x) {
    s[++nStr] = x;
    int now = last;
    while (s[nStr - l[now] - 1] != s[nStr]) now = fail[now];
    if (!c[now][x]) {
        int newnode = allocate(l[now] + 2), &newfail = fail[newnode];
        newfail = fail[now];
        while (s[nStr - l[newfail] - 1] != s[nStr]) newfail = fail[newfail];
        newfail = c[newfail][x];
        c[now][x] = newnode;
    }
    last = c[now][x];
    r[last]++;
}
void count() {
    for (int i = nT - 1; i >= 0; i--) {
        r[fail[i]] += r[i];
    }
}
```

Chapter 5 数据结构

5.1 KD-Tree

```
long long norm(const long long &x) {
    //    For manhattan distance
    return std::abs(x);
    //    For euclid distance
    return x * x;
}

struct Point {
    int x, y, id;

    const int& operator [] (int index) const {
        if (index == 0) {
            return x;
        } else {
            return y;
        }
    }

    friend long long dist(const Point &a, const Point &b) {
        long long result = 0;
        for (int i = 0; i < 2; ++i) {
            result += norm(a[i] - b[i]);
        }
        return result;
    }
} point[N];

struct Rectangle {
    int min[2], max[2];

    Rectangle() {
        min[0] = min[1] = INT_MAX;  // sometimes int is not enough
        max[0] = max[1] = INT_MIN;
    }

    void add(const Point &p) {
        for (int i = 0; i < 2; ++i) {
            min[i] = std::min(min[i], p[i]);
            max[i] = std::max(max[i], p[i]);
        }
    }

    long long dist(const Point &p) {
        long long result = 0;
        for (int i = 0; i < 2; ++i) {
            //    For minimum distance
            result += norm(std::min(std::max(p[i], min[i]), max[i]) - p[i]);
            //    For maximum distance
            result += std::max(norm(max[i] - p[i]), norm(min[i] - p[i]));
        }
        return result;
    }
};

struct Node {
    Point seperator;
    Rectangle rectangle;
    int child[2];

    void reset(const Point &p) {
        seperator = p;
        rectangle = Rectangle();
        rectangle.add(p);
        child[0] = child[1] = 0;
    }
} tree[N << 1];

int size, pivot;

bool compare(const Point &a, const Point &b) {
    if (a[pivot] != b[pivot]) {
        return a[pivot] < b[pivot];
    }
    return a.id < b.id;
}

// 左閉右開: build(1, n + 1)
int build(int l, int r, int type = 1) {
    pivot = type;
    if (l >= r) {
        return 0;
    }
    int x = ++size;
    int mid = l + r >> 1;
    std::nth_element(point + l, point + mid, point + r, compare);
    tree[x].reset(point[mid]);
    for (int i = l; i < r; ++i) {
        tree[x].rectangle.add(point[i]);
    }
    tree[x].child[0] = build(l, mid, type ^ 1);
    tree[x].child[1] = build(mid + 1, r, type ^ 1);
    return x;
}

int insert(int x, const Point &p, int type = 1) {
    pivot = type;
    if (x == 0) {
        tree[++size].reset(p);
        return size;
    }
    tree[x].rectangle.add(p);
    if (compare(p, tree[x].seperator)) {
        tree[x].child[0] = insert(tree[x].child[0], p, type ^ 1);
    } else {
        tree[x].child[1] = insert(tree[x].child[1], p, type ^ 1);
    }
    return x;
}

// For minimum distance
// For maximum: 下面递归 query 时 0, 1 换顺序;< and >;min and max
void query(int x, const Point &p, std::pair<long long, int> &answer, int type = 1) {
    pivot = type;
    if (x == 0 || tree[x].rectangle.dist(p) > answer.first) {
        return;
    }
    answer = std::min(answer,
             std::make_pair(dist(tree[x].seperator, p), tree[x].seperator.id));
    if (compare(p, tree[x].seperator)) {
        query(tree[x].child[0], p, answer, type ^ 1);
        query(tree[x].child[1], p, answer, type ^ 1);
    } else {
        query(tree[x].child[1], p, answer, type ^ 1);
        query(tree[x].child[0], p, answer, type ^ 1);
    }
}

std::priority_queue<std::pair<long long, int> > answer;

void query(int x, const Point &p, int k, int type = 1) {
    pivot = type;
    if (x == 0 || (int)answer.size() == k && tree[x].rectangle.dist(p) > answer.top().first) {
        return;
    }
    answer.push(std::make_pair(dist(tree[x].seperator, p), tree[x].seperator.id));
    if ((int)answer.size() > k) {
        answer.pop();
    }
    if (compare(p, tree[x].seperator)) {
        query(tree[x].child[0], p, k, type ^ 1);
        query(tree[x].child[1], p, k, type ^ 1);
    } else {
        query(tree[x].child[1], p, k, type ^ 1);
        query(tree[x].child[0], p, k, type ^ 1);
    }
}
```

5.2 Treap

```
struct Node{
    int mn, key, size, tag;
    bool rev;
    Node* ch[2];
    Node(int mn, int key, int size): mn(mn), key(key), size(size), rev(0), tag(0){}
    void downtag();
    Node* update(){
        mn = min(ch[0] -> mn, min(key, ch[1] -> mn));
        size = ch[0] -> size + 1 + ch[1] -> size;
        return this;
    }
};
typedef pair<Node*, Node*> Pair;
Node *null, *root;
void Node::downtag(){
    if(rev){
        for(int i = 0; i < 2; i++)
            if(ch[i] != null){
                ch[i] -> rev ^= 1;
                swap(ch[i] -> ch[0], ch[i] -> ch[1]);
            }
        rev = 0;
    }
    if(tag){
        for(int i = 0; i < 2; i++)
            if(ch[i] != null){
                ch[i] -> key += tag;
                ch[i] -> mn += tag;
                ch[i] -> tag += tag;
            }
        tag = 0;
    }
}
int r(){
    static int s = 3023192386;
    return (s += (s << 3) + 1) & (~0u >> 1);
}
bool random(int x, int y){
    return r() % (x + y) < x;
}
Node* merge(Node *p, Node *q){
    if(p == null) return q;
    if(q == null) return p;
    p -> downtag();
    q -> downtag();
    if(random(p -> size, q -> size)){
        p -> ch[1] = merge(p -> ch[1], q);
        return p -> update();
    }else{
        q -> ch[0] = merge(p, q -> ch[0]);
        return q -> update();
    }
}
Pair split(Node *x, int n){
    if(x == null) return make_pair(null, null);
    x -> downtag();
    if(n <= x -> ch[0] -> size){
        Pair ret = split(x -> ch[0], n);
        x -> ch[0] = ret.second;
        return make_pair(ret.first, x -> update());
    }
    Pair ret = split(x -> ch[1], n - x -> ch[0] -> size - 1);
    x -> ch[1] = ret.first;
    return make_pair(x -> update(), ret.second);
}
pair<Node*, Pair> get_segment(int l, int r){
    Pair ret = split(root, l - 1);
    return make_pair(ret.first, split(ret.second, r - l + 1));
}
int main(){
    null = new Node(INF, INF, 0);
    null -> ch[0] = null -> ch[1] = null;
    root = null;
}
```

5.3 Link/cut Tree

```
inline void reverse(int x) {
    tr[x].rev ^= 1; swap(tr[x].c[0], tr[x].c[1]);
}

inline void rotate(int x, int k) {
    int y = tr[x].fa, z = tr[y].fa;
    tr[x].fa = z; tr[z].c[tr[z].c[1] == y] = x;
    tr[tr[x].c[k ^ 1]].fa = y; tr[y].c[k] = tr[x].c[k ^ 1];
    tr[x].c[k ^ 1] = y; tr[y].fa = x;
}

inline void splay(int x, int w) {
    int z = x; pushdown(x);
    while (tr[x].fa != w) {
        int y = tr[x].fa; z = tr[y].fa;
        if (z == w) {
            pushdown(z = y); pushdown(x);
            rotate(x, tr[y].c[1] == x);
            update(y); update(x);
        } else {
            pushdown(z); pushdown(y); pushdown(x);
            int t1 = tr[y].c[1] == x, t2 = tr[z].c[1] == y;
            if (t1 == t2) rotate(y, t2), rotate(x, t1);
            else rotate(x, t1), rotate(x, t2);
            update(z); update(y); update(x);
        }
    }
    update(x);
    if (x != z) par[x] = par[z], par[z] = 0;
}

inline void access(int x) {
    for (int y = 0; x; y = x, x = par[x]) {
        splay(x, 0);
        if (tr[x].c[1]) par[tr[x].c[1]] = x, tr[tr[x].c[1]].fa = 0;
        tr[x].c[1] = y; par[y] = 0; tr[y].fa = x; update(x);
    }
}

inline void makeroot(int x) {
    access(x); splay(x, 0); reverse(x);
}

inline void link(int x, int y) {
    makeroot(x); par[x] = y;
}

inline void cut(int x, int y) {
    access(x); splay(y, 0);
    if (par[y] != x) swap(x, y), access(x), splay(y, 0);
    par[y] = 0;
}

inline void split(int x, int y) {  // x will be the root of the tree
    makeroot(y); access(x); splay(x, 0);
}
```

Chapter 6 图论

6.1 基础

```
struct Graph {  // Remember to call .init()!
    int e, nxt[M], v[M], adj[N], n;
    bool base;
    __inline void init(bool _base, int _n = 0) {
        assert(n < N);
        n = _n; base = _base;
        e = 0; memset(adj + base, -1, sizeof(*adj) * n);
    }
    __inline int new_node() {
        adj[n + base] = -1;
        assert(n + base + 1 < N);
        return n++ + base;
    }
    __inline void ins(int u0, int v0) {  // directional
```

```
        assert(u0 < n + base && v0 < n + base);
        v[e] = v0; nxt[e] = adj[u0]; adj[u0] = e++;
        assert(e < M);
    }
    __inline void bi_ins(int u0, int v0) {  // bi-directional
        ins(u0, v0); ins(v0, u0);
    }
};
```

6.2 KM

```
struct KM {
    // Truly O(n^3)
    // 邻接矩阵，不能连的边设为 -INF，求最小权匹配时边权取负，但不能连的还是 -INF，使用时先对 1 -> n 调用 hungary() ，再 get_ans() 求值
    int w[N][N];
    int lx[N], ly[N], match[N], way[N], slack[N];
    bool used[N];
    void init() {
        for (int i = 1; i <= n; i++) {
            match[i] = 0;
            lx[i] = 0;
            ly[i] = 0;
            way[i] = 0;
        }
    }
    void hungary(int x) {
        match[0] = x;
        int j0 = 0;
        for (int j = 0; j <= n; j++) {
            slack[j] = INF;
            used[j] = false;
        }

        do {
            used[j0] = true;
            int i0 = match[j0], delta = INF, j1 = 0;
            for (int j = 1; j <= n; j++) {
                if (used[j] == false) {
                    int cur = -w[i0][j] - lx[i0] - ly[j];
                    if (cur < slack[j]) {
                        slack[j] = cur;
                        way[j] = j0;
                    }
                    if (slack[j] < delta) {
                        delta = slack[j];
                        j1 = j;
                    }
                }
            }
            for (int j = 0; j <= n; j++) {
                if (used[j]) {
                    lx[match[j]] += delta;
                    ly[j] -= delta;
                }
                else slack[j] -= delta;
            }
            j0 = j1;
        } while (match[j0] != 0);

        do {
            int j1 = way[j0];
            match[j0] = match[j1];
            j0 = j1;
        } while (j0);
    }

    int get_ans() {
        int sum = 0;
        for(int i = 1; i <= n; i++) {
            if (w[match[i]][i] == -INF) ; // 无解
            if (match[i] > 0) sum += w[match[i]][i];
        }
        return sum;
    }
} km;
```

6.3 点双连通分量

bcc.forest is a set of connected tree whose vertices are chequered with cut-vertex and BCC.

```
const bool BCC_VERTEX = 0, BCC_EDGE = 1;
struct BCC {  // N = N0 + M0. Remember to call init(&raw_graph).
    Graph *g, forest; // g is raw graph ptr.
    int dfn[N], DFN, low[N];
    int stack[N], top;
    int expand_to[N];      // Where edge i is expanded to in expaned graph.
    // Vertex i expaned to i.
    int compress_to[N];  // Where vertex i is compressed to.
    bool vertex_type[N], cut[N], compress_cut[N], branch[M];
    //std::vector<int> BCC_component[N];  // Cut vertex belongs to none.
    __inline void init(Graph *raw_graph) {
        g = raw_graph;
    }
    void DFS(int u, int pe) {
        dfn[u] = low[u] = ++DFN; cut[u] = false;
        if (!~g->adj[u]) {
            cut[u] = 1;
            compress_to[u] = forest.new_node();
            compress_cut[compress_to[u]] = 1;
        }
        for (int e = g->adj[u]; ~e; e = g->nxt[e]) {
            int v = g->v[e];
            if ((e ^ pe) > 1 && dfn[v] > 0 && dfn[v] < dfn[u]) {
                stack[top++] = e;
                low[u] = std::min(low[u], dfn[v]);
            }
            else if (!dfn[v]) {
                stack[top++] = e; branch[e] = 1;
                DFS(v, e);
                low[u] = std::min(low[v], low[u]);
                if (low[v] >= dfn[u]) {
                    if (!cut[u]) {
                        cut[u] = 1;
                        compress_to[u] = forest.new_node();
                        compress_cut[compress_to[u]] = 1;
                    }
                    int cc = forest.new_node();
                    forest.bi_ins(compress_to[u], cc);
                    compress_cut[cc] = 0;
                    //BCC_component[cc].clear();
                    do {
                        int cur_e = stack[--top];
                        compress_to[expand_to[cur_e]] = cc;
                        compress_to[expand_to[cur_e^1]] = cc;
                        if (branch[cur_e]) {
                            int v = g->v[cur_e];
                            if (cut[v])
                                forest.bi_ins(cc, compress_to[v]);
                            else {
                                //BCC_component[cc].push_back(v);
                                compress_to[v] = cc;
                            }
                        }
                    } while (stack[top] != e);
                }
            }
        }
    }
    void solve() {
        forest.init(g->base);
        int n = g->n;
        for (int i = 0; i < g->e; i++) {
            expand_to[i] = g->new_node();
        }
        memset(branch, 0, sizeof(*branch) * g->e);
        memset(dfn + g->base, 0, sizeof(*dfn) * n); DFN = 0;
        for (int i = 0; i < n; i++)
            if (!dfn[i + g->base]) {
                top = 0;
                DFS(i + g->base, -1);
            }
    }
} bcc;

bcc.init(&raw_graph);
bcc.solve();
// Do something with bcc.forest ...
```

6.4 边双连通分量

```
struct BCC {
    Graph *g, forest;
    int dfn[N], low[N], stack[N], tot[N], belong[N], vis[N], top, dfs_clock;
    // tot[] is the size of each BCC, belong[] is the BCC that each node belongs to
    pair<int, int > ori[M]; // bridge in raw_graph(raw node)
    bool is_bridge[M];
    __inline void init(Graph *raw_graph) {
        g = raw_graph;
        memset(is_bridge, false, sizeof(*is_bridge) * g -> e);
        memset(vis + g -> base, 0, sizeof(*vis) * g -> n);
    }
    void tarjan(int u, int from) {
        dfn[u] = low[u] = ++dfs_clock; vis[u] = 1; stack[++top] = u;
        for (int p = g -> adj[u]; ~p; p = g -> nxt[p]) {
            if ((p ^ 1) == from) continue;
            int v = g -> v[p];
            if (vis[v]) {
                if (vis[v] == 1) low[u] = min(low[u], dfn[v]);
            } else {
                tarjan(v, p);
                low[u] = min(low[u], low[v]);
                if (low[v] > dfn[u]) is_bridge[p / 2] = true;
            }
        }
        if (dfn[u] != low[u]) return;
        tot[forest.new_node()] = 0;
        do {
            belong[stack[top]] = forest.n;
            vis[stack[top]] = 2;
            tot[forest.n]++;
            --top;
        } while (stack[top + 1] != u);
    }
    void solve() {
        forest.init(g -> base);
        int n = g -> n;
        for (int i = 0; i < n; ++i)
            if (!vis[i + g -> base]) {
                top = dfs_clock = 0;
                tarjan(i + g -> base, -1);
            }
        for (int i = 0; i < g -> e / 2; ++i)
            if (is_bridge[i]) {
                int e = forest.e;
                forest.bi_ins(belong[g -> v[i * 2]], belong[g -> v[i * 2 + 1]], g -> w[i * 2]);
                ori[e] = make_pair(g -> v[i * 2 + 1], g -> v[i * 2]);
                ori[e + 1] = make_pair(g -> v[i * 2], g -> v[i * 2 + 1]);
            }
    }
} bcc;
```

6.5 最小树形图

```
const int MAXN,INF;// INF >= sum( W_ij )
int from[MAXN + 10][MAXN * 2 + 10],n,m,edge[MAXN + 10][MAXN * 2 + 10];
int sel[MAXN * 2 + 10],fa[MAXN * 2 + 10],vis[MAXN * 2 + 10];
int getfa(int x){if(x == fa[x]) return x; return fa[x] = getfa(fa[x]);}
void liuzhu(){ // 1-base: root is 1, answer = (sel[i], i) for i in [2..n]
    fa[1] = 1;
    for(int i = 2; i <= n; ++i){
        sel[i] = 1; fa[i] = i;
        for(int j = 1; j <= n; ++j) if(fa[j] != i)
            if(from[j][i] = i, edge[sel[i]][i] > edge[j][i]) sel[i] = j;
    }
    int limit = n;
    while(1){
        int prelimit = limit; memset(vis, 0, sizeof(vis)); vis[1] = 1;
        for(int i = 2; i <= prelimit; ++i) if(fa[i] == i && !vis[i]){
            int j = i; while(!vis[j]) vis[j] = i, j = getfa(sel[j]);
            if(j == 1 || vis[j] != i) continue; vector<int> C; int k = j;
            do C.push_back(k), k = getfa(sel[k]); while(k != j);
            ++limit;
            for(int i = 1; i <= n; ++i){
                edge[i][limit] = INF, from[i][limit] = limit;
            }
            fa[limit] = vis[limit] = limit;
            for(int i = 0; i < int(C.size()); ++i){
                int x = C[i], fa[x] = limit;
                for(int j = 1; j <= n; ++j)
                    if(edge[j][x] != INF && edge[j][limit] > edge[j][x] - edge[sel[x]][x]){
                        edge[j][limit] = edge[j][x] - edge[sel[x]][x];
                        from[j][limit] = x;
                    }
            }
            for(int j=1;j<=n;++j) if(getfa(j)==limit) edge[j][limit] = INF;
            sel[limit] = 1;
            for(int j = 1; j <= n; ++j)
                if(edge[sel[limit]][limit] > edge[j][limit]) sel[limit] = j;
        }
        if(prelimit == limit) break;
    }
    for(int i = limit; i > 1; --i) sel[from[sel[i]][i]] = sel[i];
}
```

6.6 带花树

```
vector<int> link[maxn];
int n,match[maxn],Queue[maxn],head,tail;
int pred[maxn],base[maxn],start,finish,newbase;
bool InQueue[maxn],InBlossom[maxn];
void push(int u){ Queue[tail++]=u;InQueue[u]=true; }
int pop(){ return Queue[head++]; }
int FindCommonAncestor(int u,int v){
    bool InPath[maxn];
    for(int i=0;i<n;i++) InPath[i]=0;
    while(true){ u=base[u];InPath[u]=true;if(u==start) break;u=pred[match[u]]; }
    while(true){ v=base[v];if(InPath[v]) break;v=pred[match[v]]; }
    return v;
}
void ResetTrace(int u){
    int v;
    while(base[u]!=newbase){
        v=match[u];
        InBlossom[base[u]]=InBlossom[base[v]]=true;
        u=pred[v];
        if(base[u]!=newbase) pred[u]=v;
    }
}
void BlossomContract(int u,int v){
    newbase=FindCommonAncestor(u,v);
    for (int i=0;i<n;i++)
    InBlossom[i]=0;
    ResetTrace(u);ResetTrace(v);
    if(base[u]!=newbase) pred[u]=v;
    if(base[v]!=newbase) pred[v]=u;
    for(int i=0;i<n;++i)
    if(InBlossom[base[i]]){
        base[i]=newbase;
        if(!InQueue[i]) push(i);
    }
}
bool FindAugmentingPath(int u){
    bool found=false;
    for(int i=0;i<n;++i) pred[i]=-1,base[i]=i;
    for (int i=0;i<n;i++) InQueue[i]=0;
    start=u;finish=-1; head=tail=0; push(start);
    while(head<tail){
        int u=pop();
        for(int i=link[u].size()-1;i>=0;i--){
            int v=link[u][i];
            if(base[u]!=base[v]&&match[u]!=v)
                if(v==start||(match[v]>=0&&pred[match[v]]>=0))
                    BlossomContract(u,v);
                else if(pred[v]==-1){
                    pred[v]=u;
                    if(match[v]>=0) push(match[v]);
                    else{ finish=v; return true; }
                }
        }
    }
    return found;
}
void AugmentPath(){
    int u=finish,v,w;
    while(u>=0){ v=pred[u];w=match[v];match[v]=u;match[u]=v;u=w; }
}
void FindMaxMatching(){
    for(int i=0;i<n;++i) match[i]=-1;
    for(int i=0;i<n;++i) if(match[i]==-1) if(FindAugmentingPath(i)) AugmentPath();
}
```

6.7 Dominator Tree

```
vector<int> prec[N], succ[N];
vector<int> ord;
int stamp, vis[N];
int num[N];
int fa[N];
void dfs(int u) {
    vis[u] = stamp;
    num[u] = ord.size();
    ord.push_back(u);
    for (int i = 0; i < (int)succ[u].size(); ++i) {
        int v = succ[u][i];
        if (vis[v] != stamp) {
            fa[v] = u;
            dfs(v);
        }
    }
}
int fs[N], mins[N], dom[N], sem[N];
int find(int u) {
    if (u != fs[u]) {
        int v = fs[u];
        fs[u] = find(fs[u]);
        if (mins[v] != -1 && num[sem[mins[v]]] < num[sem[mins[u]]]) {
            mins[u] = mins[v];
        }
    }
    return fs[u];
}
void merge(int u, int v) { fs[u] = v; }
vector<int> buf[N];
int buf2[N];
void mark(int source) {
    ord.clear();
    ++stamp;
    dfs(source);
    for (int i = 0; i < (int)ord.size(); ++i) {
        int u = ord[i];
        fs[u] = u, mins[u] = -1, buf2[u] = -1;
    }
    for (int i = (int)ord.size() - 1; i > 0; --i) {
        int u = ord[i], p = fa[u];
        sem[u] = p;
        for (int j = 0; j < (int)prec[u].size(); ++j) {
            int v = prec[u][j];
            if (use[v] != stamp) continue;
            if (num[v] > num[u]) {
                find(v); v = sem[mins[v]];
            }
            if (num[v] < num[sem[u]]) {
                sem[u] = v;
            }
        }
        buf[sem[u]].push_back(u);
        mins[u] = u;
        merge(u, p);
        while (buf[p].size()) {
            int v = buf[p].back();
            buf[p].pop_back();
            find(v);
            if (sem[v] == sem[mins[v]]) {
                dom[v] = sem[v];
            } else {
                buf2[v] = mins[v];
            }
        }
    }
    dom[ord[0]] = ord[0];
    for (int i = 0; i < (int)ord.size(); ++i) {
        int u = ord[i];
        if (~buf2[u]) {
            dom[u] = dom[buf2[u]];
        }
    }
}
```

6.8 无向图最小割

```
int cost[maxn][maxn],seq[maxn],len[maxn],n,m,pop,ans;
bool used[maxn];
void Init(){
    int i,j,a,b,c;
    for(i=0;i<n;i++) for(j=0;j<n;j++) cost[i][j]=0;
    for(i=0;i<m;i++){
        scanf("%d %d %d",&a,&b,&c); cost[a][b]+=c; cost[b][a]+=c;
    }
    pop=n; for(i=0;i<n;i++) seq[i]=i;
}
void Work(){
    ans=inf; int i,j,k,l,mm,sum,pk;
    while(pop > 1){
        for(i=1;i<pop;i++) used[seq[i]]=0; used[seq[0]]=1;
        for(i=1;i<pop;i++) len[seq[i]]=cost[seq[0]][seq[i]];
        pk=0; mm=-inf; k=-1;
        for(i=1;i<pop;i++) if(len[seq[i]] > mm){ mm=len[seq[i]]; k=i; }
        for(i=1;i<pop;i++){
            used[seq[l=k]]=1;
            if(i==pop-2) pk=k;
            if(i==pop-1) break;
            mm=-inf;
            for(j=1;j<pop;j++) if(!used[seq[j]])
                if((len[seq[j]]+=cost[seq[l]][seq[j]]) > mm)
                    mm=len[seq[j]], k=j;
        }
        sum=0;
        for(i=0;i<pop;i++) if(i != k) sum+=cost[seq[k]][seq[i]];
        ans=min(ans,sum);
        for(i=0;i<pop;i++)
            cost[seq[k]][seq[i]]=cost[seq[i]][seq[k]]+=cost[seq[pk]][seq[i]];
        seq[pk]=seq[--pop];
    }
    printf("%d\n",ans);
}
```

Chapter 7 其他

7.1 Dancing Links

```
struct Node {
    Node *l, *r, *u, *d, *col;
    int size, line_no;
    Node() {
        size = 0; line_no = -1;
        l = r = u = d = col = NULL;
    }
} *root;

void cover(Node *c) {
    c->l->r = c->r; c->r->l = c->l;
    for (Node *u = c->d; u != c; u = u->d)
        for (Node *v = u->r; v != u; v = v->r) {
            v->d->u = v->u;
            v->u->d = v->d;
            -- v->col->size;
        }
}

void uncover(Node *c) {
    for (Node *u = c->u; u != c; u = u->u) {
        for (Node *v = u->l; v != u; v = v->l) {
            ++ v->col->size;
            v->u->d = v;
            v->d->u = v;
        }
    }
    c->l->r = c; c->r->l = c;
}

std::vector<int> answer;
bool search(int k) {
    if (root->r == root) return true;
    Node *r = NULL;
    for (Node *u = root->r; u != root; u = u->r)
        if (r == NULL || u->size < r->size)
            r = u;
    if (r == NULL || r->size == 0) return false;
    else {
        cover(r);
        bool succ = false;
        for (Node *u = r->d; u != r && !succ; u = u->d) {
            answer.push_back(u->line_no);
            for (Node *v = u->r; v != u; v = v->r)  // Cover row
                cover(v->col);
            succ |= search(k + 1);
            for (Node *v = u->l; v != u; v = v->l)
                uncover(v->col);
            if (!succ) answer.pop_back();
        }
        uncover(r);
        return succ;
    }
}

bool entry[CR][CC];
Node *who[CR][CC];
int cr, cc;

void construct() {
    root = new Node();
    Node *last = root;
    for (int i = 0; i < cc; ++ i) {
        Node *u = new Node();
        last->r = u; u->l = last;
        Node *v = u; u->line_no = i;
        last = u;
        for (int j = 0; j < cr; ++ j)
            if (entry[j][i]) {
                ++ u->size;
                Node *cur = new Node();
                who[j][i] = cur;
                cur->line_no = j;
                cur->col = u;
                cur->u = v; v->d = cur;
                v = cur;
            }
        v->d = u; u->u = v;
    }
    last->r = root; root->l = last;
    for (int j = 0; j < cr; ++ j) {
        Node *last = NULL;
        for (int i = cc - 1; i >= 0; -- i)
            if (entry[j][i]) {
                last = who[j][i];
                break;
            }
        for (int i = 0; i < cc; ++ i)
            if (entry[j][i]) {
                last->r = who[j][i];
                who[j][i]->l = last;
                last = who[j][i];
            }
    }
}

void destruct() {
    for (Node *u = root->r; u != root; ) {
        for (Node *v = u->d; v != u; ) {
            Node *nxt = v->d;
            delete(v);
            v = nxt;
        }
        Node *nxt = u->r;
        delete(u); u = nxt;
    }
    delete root;
}
```

7.2 蔡勒公式

```
int zeller(int y,int m,int d) {
    if (m<=2) y--,m+=12; int c=y/100; y%=100;
    int w=((c>>2)-(c<<1)+y+(y>>2)+(13*(m+1)/5)+d-1)%7;
    if (w<0) w+=7; return(w);
}
```

Chapter 8 技巧

8.1 真正的释放 STL 容器内存空间

```
template <typename T>
__inline void clear(T& container) {
```

```cpp
    container.clear();  // 或者删除了一堆元素
    T(container).swap(container);
}
```

8.2 无敌的大整数相乘取模

Time complexity $O(1)$.

```cpp
// 需要保证 x 和 y 非负
long long mult(long long x, long long y, long long MODN) {
    long long t = (x * y - (long long)((long double)x / MODN * y + 1e-3) * MODN) % MODN;
    return t < 0 ? t + MODN : t;
}
```

8.3 无敌的读入优化

```cpp
// getchar() 读入优化 << 关同步 cin << 此优化
// 用 isdigit() 会小幅变慢
// 返回 false 表示读到文件尾
namespace Reader {
    const int L = (1 << 15) + 5;
    char buffer[L], *S, *T;
    __inline bool getchar(char &ch) {
        if (S == T) {
            T = (S = buffer) + fread(buffer, 1, L, stdin);
            if (S == T) {
                ch = EOF;
                return false;
            }
        }
        ch = *S++;
        return true;
    }
    __inline bool getint(int &x) {
        char ch; bool neg = 0;
        for (; getchar(ch) && (ch < '0' || ch > '9'); ) neg ^= ch == '-';
        if (ch == EOF) return false;
        x = ch - '0';
        for (; getchar(ch), ch >= '0' && ch <= '9'; )
            x = x * 10 + ch - '0';
        if (neg) x = -x;
        return true;
    }
}
```

Chapter 9 提示

9.1 控制 cout 输出实数精度

```cpp
std::cout << std::fixed << std::setprecision(5);
```

9.2 vimrc

```
set nu
set sw=4
set sts=4
set ts=4
syntax on
set cindent
```

9.3 让 make 支持 c++ 11

In .bashrc or whatever:

```
export CXXFLAGS='-std=c++11 -Wall'
```

9.4 线性规划转对偶

$$\begin{array}{ll}\text{maximize } \mathbf{c}^T\mathbf{x} \\ \text{subject to } \mathbf{A}\mathbf{x} \le \mathbf{b}, \mathbf{x} \ge 0\end{array} \iff \begin{array}{ll}\text{minimize } \mathbf{y}^T\mathbf{b} \\ \text{subject to } \mathbf{y}^T\mathbf{A} \ge \mathbf{c}^T, \mathbf{y} \ge 0\end{array}$$

9.5 32-bit/64-bit 随机素数

32-bit	64-bit
73550053	1249292846855685773
148898719	1701750434419805569
189560747	3605499878424114901
459874703	5648316673387803781
1202316001	6125342570814357977
1431183547	6215155308775851301
1438011109	6294606778040623451
1538762023	6347330550446020547
1557944263	7429632924303725207
1981315913	8524720079480389849

9.6 NTT 素数及其原根

Prime	Primitive root
1053818881	7
1051721729	6
1045430273	3
1012924417	5
1007681537	3