Gungnir's Standard Code Library

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计算几何

1.1 二维

1.1.1 基础

```
typedef double DB;
  const DB eps = 1e-8;
  int sign(DB x) {
      return x < -eps ? -1 : (x > eps ? 1 : 0);
5
  }
6
7
  DB msqrt(DB x) {
8
      return sign(x) > 0 ? sqrt(x) : 0;
9 }
10
  struct Point {
11
      DB x, y;
12
13
      Point(): x(0), y(0) {}
14
      Point(DB x, DB y): x(x), y(y) {}
15
      Point operator+(const Point &rhs) const {
          return Point(x + rhs.x, y + rhs.y);
16
17
      Point operator-(const Point &rhs) const {
18
           return Point(x - rhs.x, y - rhs.y);
19
20
21
      Point operator*(DB k) const {
22
          return Point(x * k, y * k);
23
      Point operator/(DB k) const {
24
          assert(sign(k));
25
           return Point(x / k, y / k);
26
27
      Point rotate(DB ang) const { // 逆时针旋转 ang 弧度
28
           return Point(cos(ang) * x - sin(ang) * y,
29
                   cos(ang) * y + sin(ang) * x);
30
31
      Point turn90() const { // 逆时针旋转 90 度
32
          return Point(-y, x);
33
34
```

CHAPTER 1. 计算几何

```
35 | }:
36 DB dot(const Point& a, const Point& b) {
37
       return a.x * b.x + a.y * b.y;
38
  DB det(const Point& a, const Point& b) {
39
40
       return a.x * b.y - a.y * b.x;
  }
41
  bool isLL(const Line& l1, const Line& l2, Point& p) { // 直线与直线交点
42
      DB s1 = det(l2.b - l2.a, l1.a - l2.a),
43
          s2 = -det(l2.b - l2.a, l1.b - l2.a);
44
       if (!sign(s1 + s2)) return false;
45
46
      p = (l1.a * s2 + l1.b * s1) / (s1 + s2);
       return true;
47
48 }
  bool onSeg(const Line& l, const Point& p) { // 点在线段上
49
50
       return sign(det(p - l.a, l.b - l.a)) == 0 \& sign(dot(p - l.a, p - l.b)) <= 0;
51 }
52 DB disToLine(const Line& l, const Point& p) { // 点到直线距离
      return fabs(det(p - l.a, l.b - l.a) / (l.b - l.a).len());
53
54
  | }
  |DB disToSeg(const Line& l, const Point& p) { // 点到线段距离
55
      return sign(dot(p - l.a, l.b - l.a)) * sign(dot(p - l.b, l.a - l.b)) == 1 ? disToLine(l, p) :
56

    std::min((p - l.a).len(), (p - l.b).len());
  }
57
  // 圆与直线交点
58
59
  bool isCL(Circle a, Line l, Point& p1, Point& p2) {
      DB x = dot(l.a - a.o, l.b - l.a),
60
          y = (l.b - l.a).len2(),
61
          d = x * x - y * ((l.a - a.o).len2() - a.r * a.r);
62
       if (sign(d) < 0) return false;</pre>
63
      Point p = l.a - ((l.b - l.a) * (x / y)), delta = (l.b - l.a) * (msqrt(d) / y);
65
      p1 = p + delta; p2 = p - delta;
66
       return true;
  | }
67
68 // 求凸包
  std::vector<Point> convexHull(std::vector<Point> ps) {
69
       int n = ps.size(); if (n <= 1) return ps;</pre>
70
       std::sort(ps.begin(), ps.end());
71
72
      std::vector<Point> qs;
73
       for (int i = 0; i < n; qs.push_back(ps[i ++]))</pre>
           while (qs.size() > 1 \&\& sign(det(qs[qs.size() - 2], qs.back(), ps[i])) <= 0)
74
75
               qs.pop_back();
       for (int i = n - 2, t = qs.size(); i \ge 0; qs.push_back(ps[i --]))
76
           while ((int)qs.size() > t \& sign(det(qs[qs.size() - 2], qs.back(), ps[i])) <= 0)
77
78
               qs.pop_back();
79
       return qs;
80
  | }
```

1.1.2 凸包

```
// 凸包中的点按逆时针方向
struct Convex {
int n;
```

1.1. 二维 7

```
std::vector<Point> a, upper, lower;
4
5
       void make_shell(const std::vector<Point>& p,
               std::vector<Point>& shell) { // p needs to be sorted.
6
           clear(shell); int n = p.size();
7
           for (int i = 0, j = 0; i < n; i++, j++) {
8
               for (; j \ge 2 \&\& sign(det(shell[j-1] - shell[j-2],
9
                               p[i] - shell[j-2])) \leftarrow 0; --j) shell.pop_back();
10
               shell.push_back(p[i]);
11
           }
12
13
       void make_convex() {
14
           std::sort(a.begin(), a.end());
15
16
           make_shell(a, lower);
           std::reverse(a.begin(), a.end());
17
           make_shell(a, upper);
18
           a = lower; a.pop_back();
19
20
           a.insert(a.end(), upper.begin(), upper.end());
21
           if ((int)a.size() >= 2) a.pop_back();
           n = a.size();
22
       }
23
       void init(const std::vector<Point>& _a) {
24
           clear(a); a = _a; n = a.size();
25
           make_convex();
26
27
       }
       void read(int _n) { // Won't make convex.
28
29
           clear(a); n = _n; a.resize(n);
           for (int i = 0; i < n; i++)
30
               a[i].read();
31
32
       std::pair<DB, int> get_tangent(
33
               const std::vector<Point>& convex, const Point& vec) {
34
           int l = 0, r = (int)convex.size() - 2;
35
           assert(r >= 0);
36
37
           for (; l + 1 < r; ) {
38
               int mid = (l + r) / 2;
               if (sign(det(convex[mid + 1] - convex[mid], vec)) > 0)
39
40
                   r = mid;
               else l = mid;
41
42
           return std::max(std::make_pair(det(vec, convex[r]), r),
43
44
                   std::make_pair(det(vec, convex[0]), 0));
45
       int binary_search(Point u, Point v, int l, int r) {
46
           int s1 = sign(det(v - u, a[l % n] - u));
47
           for (; l + 1 < r; ) {
48
               int mid = (l + r) / 2;
49
               int smid = sign(det(v - u, a[mid % n] - u));
50
               if (smid == s1) l = mid;
51
52
               else r = mid;
           }
53
           return 1 % n;
54
55
       // 求凸包上和向量 vec 叉积最大的点,返回编号,共线的多个切点返回任意一个
56
       int get_tangent(Point vec) {
57
```

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```
std::pair<DB, int> ret = get_tangent(upper, vec);
58
          ret.second = (ret.second + (int)lower.size() - 1) % n;
59
          ret = std::max(ret, get_tangent(lower, vec));
60
          return ret.second;
61
62
      // 求凸包和直线 u, v 的交点, 如果不相交返回 false, 如果有则是和 (i, next(i)) 的交点, 交在点上不确
63
     → 定返回前后两条边其中之一
      bool get_intersection(Point u, Point v, int &i0, int &i1) {
64
          int p0 = get_tangent(u - v), p1 = get_tangent(v - u);
65
          if (sign(det(v - u, a[p0] - u)) * sign(det(v - u, a[p1] - u)) <= 0) {
66
              if (p0 > p1) std::swap(p0, p1);
67
68
              i0 = binary_search(u, v, p0, p1);
              i1 = binary_search(u, v, p1, p0 + n);
69
              return true;
70
71
          else return false;
72
73
      }
74
 };
```

1.2 三维

1.2.1 基础

```
// 三维绕轴旋转,大拇指指向 axis 向量方向,四指弯曲方向转 w 弧度
2
  Point rotate(const Point& s, const Point& axis, DB w) {
3
      DB x = axis.x, y = axis.y, z = axis.z;
4
      DB s1 = x * x + y * y + z * z, ss1 = msqrt(s1),
5
         cosw = cos(w), sinw = sin(w);
      DB a[4][4];
6
7
      memset(a, 0, sizeof a);
8
      a[3][3] = 1;
      a[0][0] = ((y * y + z * z) * cosw + x * x) / s1;
9
      a[0][1] = x * y * (1 - cosw) / s1 + z * sinw / ss1;
10
      a[0][2] = x * z * (1 - cosw) / s1 - y * sinw / ss1;
11
      a[1][0] = x * y * (1 - cosw) / s1 - z * sinw / ss1;
12
13
      a[1][1] = ((x * x + z * z) * cosw + y * y) / s1;
      a[1][2] = y * z * (1 - cosw) / s1 + x * sinw / ss1;
14
      a[2][0] = x * z * (1 - cosw) / s1 + y * sinw / ss1;
15
      a[2][1] = y * z * (1 - cosw) / s1 - x * sinw / ss1;
16
      a[2][2] = ((x * x + y * y) * cos(w) + z * z) / s1;
17
      DB ans [4] = \{0, 0, 0, 0\}, c[4] = \{s.x, s.y, s.z, 1\};
18
      for (int i = 0; i < 4; ++ i)
19
           for (int j = 0; j < 4; ++ j)
20
               ans[i] += a[j][i] * c[j];
21
       return Point(ans[0], ans[1], ans[2]);
22
23 }
```

数论

2.1 求逆元

```
void ex_gcd(long long a, long long b, long long &x, long long &y) {
      if (b == 0) {
2
           x = 1;
3
           y = 0;
4
           return;
5
6
       long long xx, yy;
8
       ex_gcd(b, a % b, xx, yy);
      y = xx - a / b * yy;
9
10
       x = yy;
  }
11
12
  long long inv(long long x, long long MODN) {
13
       long long inv_x, y;
14
       ex_gcd(x, MODN, inv_x, y);
15
       return (inv_x % MODN + MODN) % MODN;
16
17 }
```

2.2 中国剩余定理

```
1 // 返回 (ans, M), 其中 ans 是模 M 意义下的解
  std::pair<long long, long long> CRT(const std::vector<long long>& m, const std::vector<long long>& a) {
3
      long long M = 1, ans = 0;
      int n = m.size();
4
      for (int i = 0; i < n; i++) M *= m[i];
5
      for (int i = 0; i < n; i++) {
6
          ans = (ans + (M / m[i]) * a[i] % M * inv(M / m[i], m[i])) % M; // 可能需要大整数相乘取模
7
8
9
      return std::make_pair(ans, M);
10 }
```

10 CHAPTER 2. 数论

代数

3.1 快速傅里叶变换

```
// n 必须是 2 的次幂
2
  void fft(Complex a[], int n, int f) {
      for (int i = 0; i < n; ++i)
3
           if (R[i] < i) swap(a[i], a[R[i]]);</pre>
      for (int i = 1, h = 0; i < n; i <<= 1, h++) {
5
           Complex wn = Complex(cos(pi / i), f * sin(pi / i));
6
           Complex w = Complex(1, 0);
7
8
           for (int k = 0; k < i; ++k, w = w * wn) tmp[k] = w;
9
           for (int p = i \ll 1, j = 0; j < n; j += p) {
10
               for (int k = 0; k < i; ++k) {
                   Complex x = a[j + k], y = a[j + k + i] * tmp[k];
11
                   a[j + k] = x + y; a[j + k + i] = x - y;
12
13
           }
14
      }
15
16 }
```

12 CHAPTER 3. 代数

字符串

4.1 后缀自动机

```
struct Sam {
2
       static const int MAXL = MAXN * 2; // MAXN is original length
3
       static const int alphabet = 26; // sometimes need changing
4
       int l, last, cnt, trans[MAXL][alphabet], par[MAXL], sum[MAXL], seq[MAXL], mxl[MAXL], size[MAXL]; //
     \hookrightarrow mxl is maxlength, size is the size of right
5
       char str[MAXL];
       inline void init() {
6
           l = strlen(str + 1); cnt = last = 1;
8
           for (int i = 0; i \le l * 2; ++i) memset(trans[i], 0, sizeof(trans[i]));
           memset(par, 0, sizeof(*par) * (l * 2 + 1));
9
10
           memset(mxl, 0, sizeof(*mxl) * (l * 2 + 1));
           memset(size, 0, sizeof(*size) * (l * 2 + 1));
11
12
       inline void extend(int pos, int c) {
13
           int p = last, np = last = ++cnt;
14
           mxl[np] = mxl[p] + 1; size[np] = 1;
15
           for (; p && !trans[p][c]; p = par[p]) trans[p][c] = np;
16
17
           if (!p) par[np] = 1;
18
           else {
19
               int q = trans[p][c];
               if (mxl[p] + 1 == mxl[q]) par[np] = q;
20
               else {
21
                   int nq = ++cnt;
22
                   mxl[nq] = mxl[p] + 1;
23
                   memcpy(trans[nq], trans[q], sizeof(trans[nq]));
25
                   par[nq] = par[q];
26
                   par[np] = par[q] = nq;
                   for (; trans[p][c] == q; p = par[p]) trans[p][c] = nq;
27
               }
28
           }
29
30
31
       inline void buildsam() {
           for (int i = 1; i <= l; ++i) extend(i, str[i] - 'a');
32
           memset(sum, 0, sizeof(*sum) * (l * 2 + 1));
33
           for (int i = 1; i <= cnt; ++i) sum[mxl[i]]++;</pre>
34
           for (int i = 1; i \le l; ++i) sum[i] += sum[i - 1];
35
```

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```
for (int i = cnt; i; --i) seq[sum[mxl[i]]--] = i;
for (int i = cnt; i; --i) size[par[seq[i]]] += size[seq[i]];
}
}
sam;
```

图论

5.1 基础

```
struct Graph { // Remember to call .init()!
       int e, nxt[M], v[M], adj[N], n;
2
3
       bool base;
       __inline void init(bool _base, int _n = 0) {
4
           assert(n < N);</pre>
5
6
           n = _n; base = _base;
           e = 0; memset(adj + base, -1, sizeof(*adj) * n);
8
       __inline int new_node() {
9
           adj[n + base] = -1;
10
           assert(n + base + 1 < N);
11
           return n++ + base;
12
13
       __inline void ins(int u0, int v0) { // directional
14
           assert(u0 < n + base && v0 < n + base);
15
           v[e] = v0; nxt[e] = adj[u0]; adj[u0] = e++;
16
17
           assert(e < M);</pre>
18
       __inline void bi_ins(int u0, int v0) { // bi-directional
19
           ins(u0, v0); ins(v0, u0);
20
       }
21
22 };
```

5.2 KM

```
struct KM {
2
     // Truly 0(n^3)
     // 邻接矩阵,不能连的边设为 -INF, 求最小权匹配时边权取负,但不能连的还是 -INF, 使用时先对 1 -> n
3
    → 调用 hungary() ,再 get_ans() 求值
     int w[N][N];
     int lx[N], ly[N], match[N], way[N], slack[N];
5
     bool used[N];
6
     void init() {
7
         for (int i = 1; i \le n; i++) {
8
            match[i] = 0;
```

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```
lx[i] = 0;
10
11
                ly[i] = 0;
                way[i] = 0;
12
           }
13
14
       void hungary(int x) {
15
           match[0] = x;
16
           int j0 = 0;
17
           for (int j = 0; j <= n; j++) {
18
                slack[j] = INF;
19
20
                used[j] = false;
           }
21
22
           do {
23
                used[j0] = true;
24
25
                int i0 = match[j0], delta = INF, j1 = 0;
26
                for (int j = 1; j \le n; j++) {
                    if (used[j] == false) {
27
                         int cur = -w[i0][j] - lx[i0] - ly[j];
28
                         if (cur < slack[j]) {</pre>
29
                             slack[j] = cur;
30
                             way[j] = j0;
31
32
                        }
33
                         if (slack[j] < delta) {</pre>
34
                             delta = slack[j];
                             j1 = j;
35
                        }
36
                    }
37
38
                }
                for (int j = 0; j \le n; j++) {
39
                    if (used[j]) {
40
                        lx[match[j]] += delta;
41
                         ly[j] -= delta;
42
43
44
                    else slack[j] -= delta;
45
                }
                j0 = j1;
46
           } while (match[j0] != 0);
47
48
           do {
49
50
                int j1 = way[j0];
51
                match[j0] = match[j1];
52
                j0 = j1;
           } while (j0);
53
       }
54
55
       int get_ans() {
56
57
           int sum = 0;
58
           for(int i = 1; i <= n; i++) {
                if (w[match[i]][i] == -INF); // 无解
59
                if (match[i] > 0) sum += w[match[i]][i];
60
61
62
           return sum;
       }
63
```

5.3. 点双连通分量 17

64 | } km;

5.3 点双连通分量

bcc.forest is a set of connected tree whose vertices are chequered with cut-vertex and BCC.

```
const bool BCC_VERTEX = 0, BCC_EDGE = 1;
  struct BCC { // N = N0 + M0. Remember to call init(&raw_graph).
2
       Graph *g, forest; // g is raw graph ptr.
3
4
       int dfn[N], DFN, low[N];
5
       int stack[N], top;
6
       int expand_to[N];
                               // Where edge i is expanded to in expaned graph.
       // Vertex i expaned to i.
       int compress_to[N]; // Where vertex i is compressed to.
8
       bool vertex_type[N], cut[N], compress_cut[N], branch[M];
9
       //std::vector<int> BCC_component[N]; // Cut vertex belongs to none.
10
       __inline void init(Graph *raw_graph) {
11
           g = raw_graph;
12
13
       }
       void DFS(int u, int pe) {
14
           dfn[u] = low[u] = ++DFN; cut[u] = false;
15
           if (!\sim g->adj[u]) {
16
17
               cut[u] = 1;
               compress_to[u] = forest.new_node();
18
19
               compress_cut[compress_to[u]] = 1;
20
           for (int e = g->adj[u]; \sim e; e = g->nxt[e]) {
21
22
               int v = g -> v[e];
               if ((e^p) > 1 \& dfn[v] > 0 \& dfn[v] < dfn[u]) {
23
                   stack[top++] = e;
24
                    low[u] = std::min(low[u], dfn[v]);
25
               }
26
               else if (!dfn[v]) {
                    stack[top++] = e; branch[e] = 1;
28
                   DFS(v, e);
29
30
                    low[u] = std::min(low[v], low[u]);
31
                    if (low[v] >= dfn[u]) {
                        if (!cut[u]) {
32
                            cut[u] = 1;
33
                            compress_to[u] = forest.new_node();
34
                            compress_cut[compress_to[u]] = 1;
35
                        }
36
37
                        int cc = forest.new_node();
38
                        forest.bi_ins(compress_to[u], cc);
                        compress_cut[cc] = 0;
39
                        //BCC_component[cc].clear();
40
41
                            int cur_e = stack[--top];
42
43
                            compress_to[expand_to[cur_e]] = cc;
                            compress_to[expand_to[cur_e^1]] = cc;
44
                            if (branch[cur_e]) {
45
                                int v = g->v[cur_e];
46
                                if (cut[v])
47
```

CHAPTER 5. 图论

```
forest.bi_ins(cc, compress_to[v]);
48
                                  else {
49
                                      //BCC_component[cc].push_back(v);
50
                                      compress to[v] = cc;
51
52
53
                         } while (stack[top] != e);
54
                    }
55
               }
56
           }
57
       }
58
59
       void solve() {
           forest.init(g->base);
60
           int n = g->n;
61
           for (int i = 0; i < g \rightarrow e; i + +) {
62
                expand_to[i] = g->new_node();
63
64
           memset(branch, 0, sizeof(*branch) * g->e);
65
           memset(dfn + g->base, 0, sizeof(*dfn) * n); DFN = 0;
66
           for (int i = 0; i < n; i++)
67
                if (!dfn[i + g->base]) {
68
                     top = 0;
69
                    DFS(i + g -> base, -1);
70
71
                }
72
73
  } bcc;
74
75
  bcc.init(&raw_graph);
76 bcc.solve();
  // Do something with bcc.forest ...
```

5.4 边双连通分量

```
1
   struct BCC {
2
       Graph *g, forest;
       int dfn[N], low[N], stack[N], tot[N], belong[N], vis[N], top, dfs_clock;
3
       // tot[] is the size of each BCC, belong[] is the BCC that each node belongs to
4
       pair<int, int > ori[M]; // bridge in raw_graph(raw node)
5
       bool is_bridge[M];
6
       __inline void init(Graph *raw_graph) {
7
8
           g = raw_graph;
9
           memset(is_bridge, false, sizeof(*is_bridge) * g -> e);
10
           memset(vis + g \rightarrow base, 0, sizeof(*vis) * g \rightarrow n);
11
       void tarjan(int u, int from) {
12
           dfn[u] = low[u] = ++dfs\_clock; vis[u] = 1; stack[++top] = u;
13
            for (int p = g \rightarrow adj[u]; \sim p; p = g \rightarrow nxt[p]) {
14
                if ((p ^ 1) == from) continue;
15
16
                int v = g \rightarrow v[p];
                if (vis[v]) {
17
                     if (vis[v] == 1) low[u] = min(low[u], dfn[v]);
18
                } else {
19
                    tarjan(v, p);
20
```

5.4. 边双连通分量 19

```
21
                    low[u] = min(low[u], low[v]);
                     if (low[v] > dfn[u]) is_bridge[p / 2] = true;
22
                }
23
           }
24
           if (dfn[u] != low[u]) return;
25
           tot[forest.new_node()] = 0;
26
           do {
27
                belong[stack[top]] = forest.n;
28
                vis[stack[top]] = 2;
29
                tot[forest.n]++;
30
31
                --top;
           } while (stack[top + 1] != u);
32
       }
33
       void solve() {
34
           forest.init(g -> base);
35
            int n = g \rightarrow n;
36
            for (int i = 0; i < n; ++i)
37
                if (!vis[i + g -> base]) {
38
                    top = dfs_clock = 0;
39
                    tarjan(i + g \rightarrow base, -1);
40
                }
41
            for (int i = 0; i < g -> e / 2; ++i)
42
                if (is_bridge[i]) {
43
44
                    int e = forest.e;
                    forest.bi_ins(belong[g \rightarrow v[i * 2]], belong[g \rightarrow v[i * 2 + 1]], g \rightarrow w[i * 2]);
45
                    ori[e] = make_pair(g -> v[i * 2 + 1], g -> v[i * 2]);
46
                    ori[e + 1] = make_pair(g -> v[i * 2], g -> v[i * 2 + 1]);
47
48
49
50
  } bcc;
```

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技巧

6.1 真正的释放 STL 容器内存空间

```
template <typename T>
__inline void clear(T& container) {
    container.clear(); // 或者删除了一堆元素
    T(container).swap(container);
}
```

6.2 无敌的大整数相乘取模

Time complexity O(1).

```
// 需要保证 x 和 y 非负
long long mult(long long x, long long y, long long MODN) {
    long long t = (x * y - (long long)((long double)x / MODN * y + 1e-3) * MODN) % MODN;
    return t < 0 ? t + MODN : t;
}
```

6.3 无敌的读入优化

```
1 // getchar() 读入优化 << 关同步 cin << 此优化
2 // 用 isdigit() 会小幅变慢
3 // 返回 false 表示读到文件尾
  namespace Reader {
      const int L = (1 << 15) + 5;
      char buffer[L], *S, *T;
6
      __inline bool getchar(char &ch) {
7
          if (S == T) {
8
              T = (S = buffer) + fread(buffer, 1, L, stdin);
9
10
              if (S == T) {
                  ch = EOF;
11
                  return false;
12
              }
13
14
          ch = *S++;
15
```

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```
return true;
16
17
      __inline bool getint(int &x) {
18
19
           char ch; bool neg = 0;
           for (; getchar(ch) && (ch < '0' || ch > '9'); ) neg ^= ch == '-';
20
           if (ch == EOF) return false;
21
           x = ch - '0';
22
           for (; getchar(ch), ch >= '0' && ch <= '9'; )
23
              x = x * 10 + ch - '0';
24
           if (neg) x = -x;
25
26
           return true;
      }
27
28 }
```

6.4 控制 cout 输出实数精度

```
std::cout << std::fixed << std::setprecision(5);
```

提示

7.1 线性规划转对偶

$$\begin{array}{l} \text{maximize } \mathbf{c}^T \mathbf{x} \\ \text{subject to } \mathbf{A} \mathbf{x} \leq \mathbf{b}, \mathbf{x} \geq 0 \\ \end{array} \Longleftrightarrow \begin{array}{l} \text{minimize } \mathbf{y}^T \mathbf{b} \\ \text{subject to } \mathbf{y}^T \mathbf{A} \geq \mathbf{c}^T, \mathbf{y} \geq 0 \end{array}$$

7.2 32-bit/64-bit 随机素数

32-bit	64-bit
73550053	1249292846855685773
148898719	1701750434419805569
189560747	3605499878424114901
459874703	5648316673387803781
1202316001	6125342570814357977
1431183547	6215155308775851301
1438011109	6294606778040623451
1538762023	6347330550446020547
1557944263	7429632924303725207
1981315913	8524720079480389849