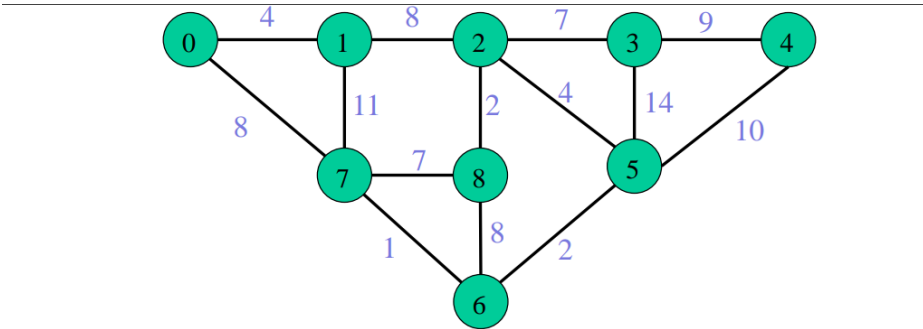


Greedy Algorithm: Please must sort the data before algorithm

	Item	PQ	
	<u>Dijkstra</u> 即从一点到所有点的最短距离	Yes	start to all calculate the shortest path Running time: $V+E$
	Huffman prefix tree	Yes	Full tree + left branch is 0 + right branch is 1 Alphabet has 27 characters(26 letters and space) Running time: $n\log n$
Mini Spanning Tree	Prim	Yes	Select the node randomly Choose the shortest edge every time Running time:
	Kruskal Union Find	Yes	Select the shortest edge firstly , 整体逻辑首先对边进行 Sort , 每次运行选择权重最小的边。 Running time: $E\log E+E$
	Activity Selection		Sort按照结束和开始时间都可以 重点识别最大的子序列, 即最多能安排课程 (并不代表时间和收益最大) Running time: $n\log n$
	Interval Scheduling		Sort按照结束和开始时间都可以 重点是最小的教室数量安排所有的课程 Running time: $n\log n$

Dijkstra

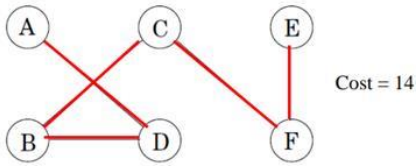
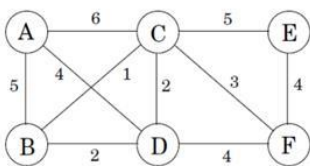
	Step	Code: s-start node; l- edge weight	time
	PQ	Dij(G, s, l): Initialize PQ	
	Define infinite for all vertex	For v in V dist(v) == infinite Q.insert(v) dist(s) = 0	V
	Find the shortest path	While Q not empty: v = Q.pop() For (v, w) in G: If dist(v) + l(v,w) < dist(w): dist(w) = dist(v) + l(v,w) Q.append(w)	V+E



Iter	PQ (non-inf) nodes	d(0)	d(1)	d(2)	d(3)	d(4)	d(5)	d(6)	d(7)	d(8)
0	[0]	0	∞	∞	∞	∞	∞	∞	∞	∞
1	[1, 7]	0	4	∞	∞	∞	∞	∞	8	∞
2	[7, 2]	0	4	12	∞	∞	∞	∞	8	∞
3	[6, 2, 8]	0	4	12	∞	∞	∞	9	8	15
4	[5, 2, 8]	0	4	12	∞	∞	11	9	8	15
5	[2, 8, 4, 3]	0	4	12	25	21	11	9	8	15
6	[8, 3, 4]	0	4	12	19	21	11	9	8	14
7	[3, 4]	0	4	12	19	21	11	9	8	14
8	[4]	0	4	12	19	21	11	9	8	14
9	[]	0	4	12	19	21	11	9	8	14

Prim

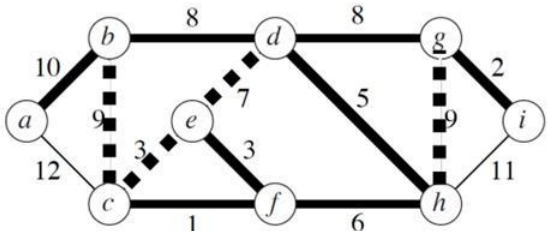
	Step	Code: s-start node; l- edge weight	time
	初始化将所有点为无穷大	Prim(G, w): For v in V: cost(v) = infinite Prev(v) = nil	红色字体: VlogV
	任意选择一个点作为起点	pick any initial node as u cost(u) = 0 PQ.append(u)	
	运用PQ逻辑每次对相邻最小的进行弹出	While PQ: v = PQ.pop()	
	将新发现的最小边的点加到PQ	For each {u, z} in G[v]: If cost[z] > w(u,z) cost[z] = w(u,z) Prev(z) = u PQ.append(z)	蓝色字体: ElogE



Set S	A	B	C	D	E	F
{}	0/nil	∞/nil	∞/nil	∞/nil	∞/nil	∞/nil
A		5/A	6/A	4/A	∞/nil	∞/nil
A, D		2/D	2/D		∞/nil	4/D
A, D, B			1/B		∞/nil	4/D
A, D, B, C					5/C	3/C
A, D, B, C, F					4/F	

Kruskal

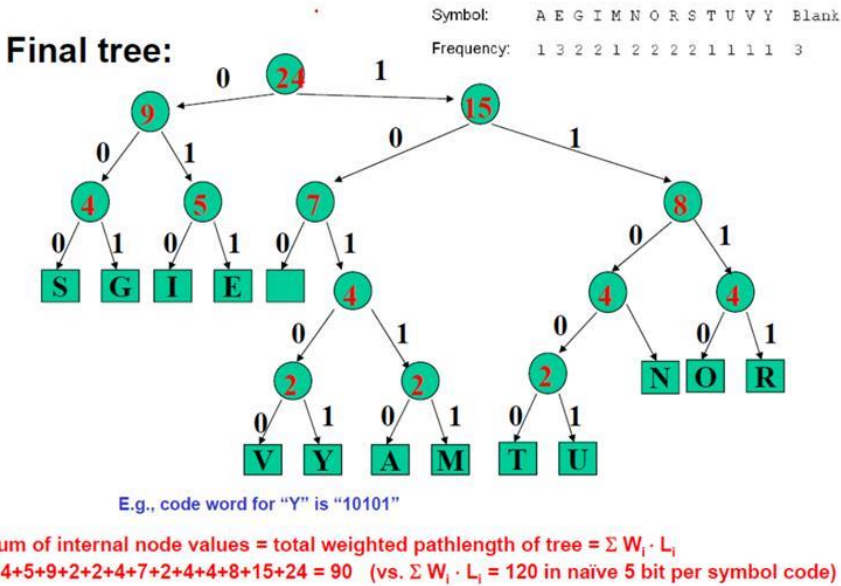
	Step	Code: s-start node; l- edge weight	time
	提取每个边的权重，然后增加到PQ	<pre>MST-KRUSKAL(G, w) 1 $A = \emptyset$ 2 for each vertex $v \in G.V$ 3 MAKE-SET(v) 4 create a single list of the edges in $G.E$ 5 sort the list of edges into monotonically increasing order by weight w 6 for each edge (u, v) taken from the sorted list in order 7 if FIND-SET(u) \neq FIND-SET(v) 8 $A = A \cup \{(u, v)\}$ 9 UNION(u, v) 10 return A</pre>	第一部分 时间复杂度最高为 ElogE
	从最小权重开始Loop		
	Union Find判断它们是否相同		
	如果不相同将它们添加		第二部分 就是边的比较 E



- (c, f) : safe
- (g, i) : safe
- (e, f) : safe
- (c, e) : reject
- (d, h) : safe
- (f, h) : safe
- (e, d) : reject
- (b, d) : safe
- (d, g) : safe
- (b, c) : reject
- (g, h) : reject
- (a, b) : safe

Huffman

	Step	Code:	time
Place the elements into PQ	1.Find to root nodes with smallest value 2.Create a new root node with two small nodes as children	Human(C, prob)	第一部分 由于x有n个，每次PQ为logn
Remove the first two elements		For x in C: PQ.append(x)	nlogn
Combine 2 elements with root		For i = 1 to len(C) -1: x = PQ.pop() y = PQ.pop() z = x + y PQ.append(z)	nlogn
Insert the new element into PQ		Return PQ.pop()	



- 考点:
- 1.对应字母的code word
 - 2.Total Weight
 - 3. 画出这个图

Activity Selection

```
def recursive_activity_selector(s, f, r, k, n):
```

```
    # s: start times of activities
    # f: finish times of activities
    # r: rental incomes of activities
    # k: index of last selected activity
    # n: number of activities
```

```
    m = k + 1
    best_value = 0
    best_activities = []
```

```
    while m <= n and s[m] < f[k]: # check compatibility
        m += 1
```

```
    if m <= n:
        # Calculate the value for selecting the current activity
        value, activities = recursive_activity_selector(s, f, r, m, n)
```

```
        if value + r[m] > best_value:
            best_value = value + r[m]
            best_activities = activities + [m]
```

```
    return best_value, best_activities
```

Maximizing Rental Income

```
def recursive_activity_selector(s, f, k, n):
```

```
    m = k + 1
```

```
    # Find the first activity compatible with the activity at index k
```

```
    while m <= n and s[m] < f[k]:
        m += 1
```

最大的子序列

```
    # If there's a compatible activity
```

```
    if m <= n:
        # Select activity am and recursively find compatible activities
        return [m] + recursive_activity_selector(s, f, m, n)
```

```
    else:
        # Return an empty list if no compatible activity
        return []
```

```
def recursive_activity_selector_time(s, f, k, n):
```

```
    # s: start times of activities
    # f: finish times of activities
    # k: index of last selected activity
    # n: number of activities
```

```
    m = k + 1
    best_time = 0
    best_activities = []
```

Maximizing longest time

```
    while m <= n and s[m] < f[k]: # check compatibility
        m += 1
```

```
    if m <= n:
        # Calculate the time for selecting the current activity
        total_time, activities = recursive_activity_selector_time(s, f, m, n)

        time = (f[m] - s[m]) + total_time # Add duration of current activity
```

```
        if time > best_time:
            best_time = time
            best_activities = activities + [m]
```

```
    return best_time, best_activities
```

当前Code延伸可以实现最大收益以及最大时间

Interval Scheduling

```
def allocate_classrooms_by_end(lectures):  
    # Sort lectures by end times (second element of each tuple)  
    lectures.sort(key=lambda x: x[1]) # Sorting by end time  
  
    classrooms = [] # Each classroom is represented by a list of end times  
    num_classrooms = 0  
  
    for lecture in lectures:  
        start, end = lecture # start time and end time of the current lecture  
        allocated = False  
  
        # Check if the lecture can fit into any existing classroom  
        for i in range(num_classrooms):  
            if classrooms[i][-1] <= start: # If the last lecture in the classroom  
                classrooms[i].append(end) # Add this lecture's end time to the classroom  
                allocated = True  
                break  
  
        # If no existing classroom can accommodate the lecture, allocate a new classroom  
        if not allocated:  
            classrooms.append([end]) # Create a new classroom and add the lecture's end time  
            num_classrooms += 1 # Increment the classroom count  
  
    return num_classrooms, classrooms
```

- 1. **Sorting the lectures by their end times:**
 - We need to sort the list of `n` lectures based on their finish times.
 - The time complexity for sorting a list of size `n` is $O(n \log n)$ using algorithms like quicksort or mergesort.
- 2. **Allocating lectures to classrooms:**
 - After sorting, we iterate over each lecture and attempt to assign it to a classroom.
 - For each lecture, we check if it can fit into any of the previously allocated classrooms.
 - In the worst case, if there are `k` classrooms and the lecture doesn't fit into any of them, a new classroom will be allocated.
 - So, for each lecture, we perform at most `k` comparisons (one for each classroom).
 - In the worst case, the number of classrooms required will be equal to `n` (if no lectures can be scheduled in the same room), leading to a worst-case time complexity of $O(n * k)$, where `k` is the number of classrooms.

教室	End time
1	
2	
3	

首先比较第一个教室的结束时间，逐渐递增比较