

Graduate Institute of Electronics Engineering, NTU



## FPGA Implementation of In-Memory Search Macro with Range Encoding

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## Outline

- ❖ Introduction to few-shot learning
- ❖ BORE range encoding scheme
- ❖ IMS system architecture
- ❖ Implementation on FPGA
- ❖ Result
- ❖ Embedding dimension reduction
- ❖ Analysis of PCA (Principle Component Analysis)
- ❖ Analysis of quantization method
- ❖ Modification of AutoEncoder method

P2

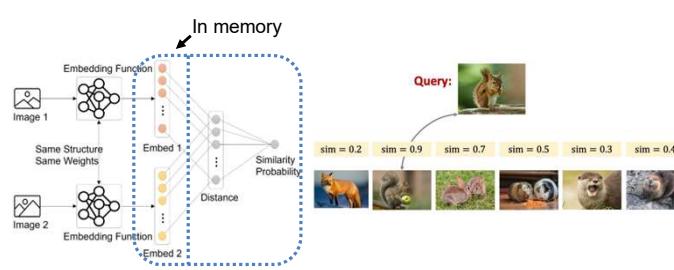
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## Few-Shot Learning

- ❖ In few-shot learning, we compare similarity between query and supporting data in memory
  - ❖ Process data with NN, store embeddings into memory
  - ❖ Compute similarity between query and supporting embeddings



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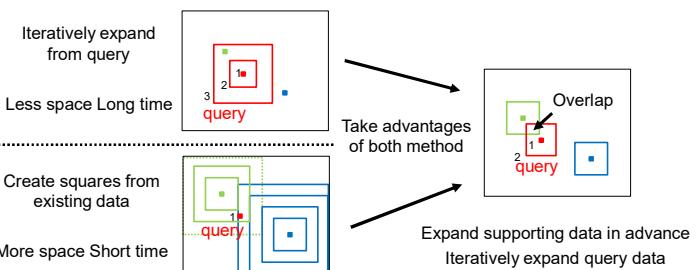
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## Similarity Search

- ❖ Which class does query belong to?
  - ❖ Iterative vs one-shot method

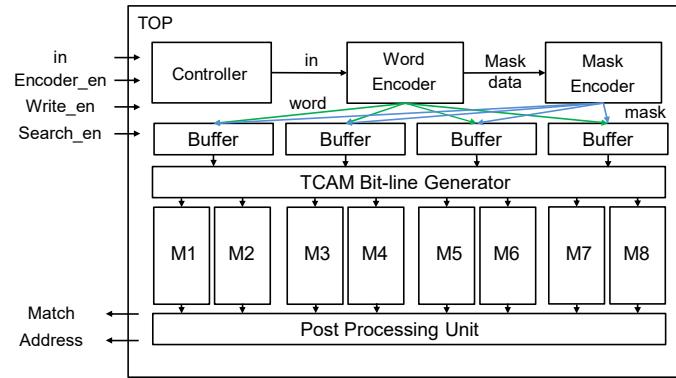


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## System Architecture

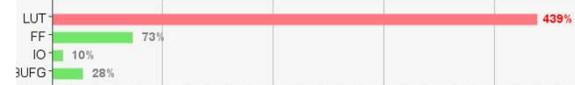


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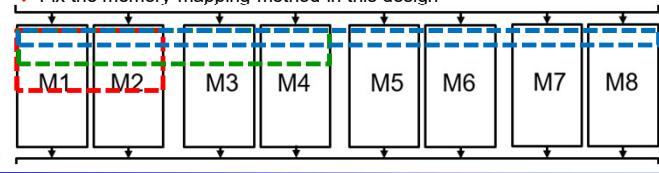


## Direct Implementation

- Some Issue happened when implementing on FPGA directly
  - Too complicated
  - FPGA board has limited ALU resources



- Reduce the use of MEM
- Fix the memory mapping method in this design

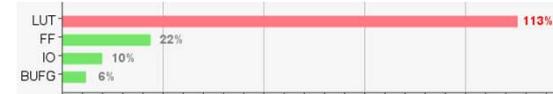


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## Direct Implementation

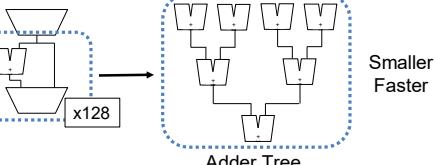
- Some Issue happened when implementing on FPGA directly
  - After removing unnecessary blocks
  - Still not simple enough



Rewrite memory macro

```
for (j = 1; j < 128; j=j+1) begin
  if(...)
    result[i][j]=1+result[i][j-1];
  else
    result[i][j]=result[i][j-1];
end
```

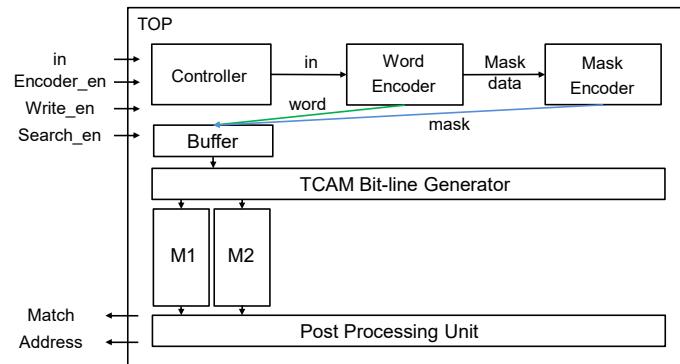
Large 3D array



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## Revised System Architecture



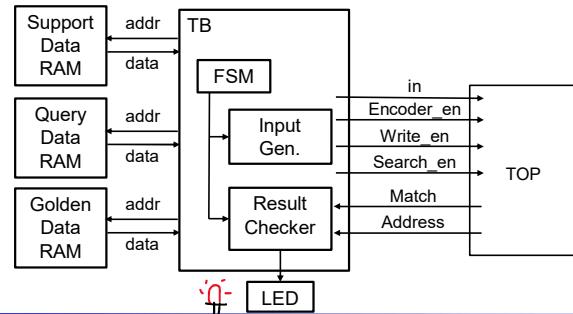
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## Input Stimuli Generation

- Input stimuli were provided by testbench → Non-synthesizable
  - Rewrite testbench into a synthesizable module
  - Using RAM on FPGA board to preload data



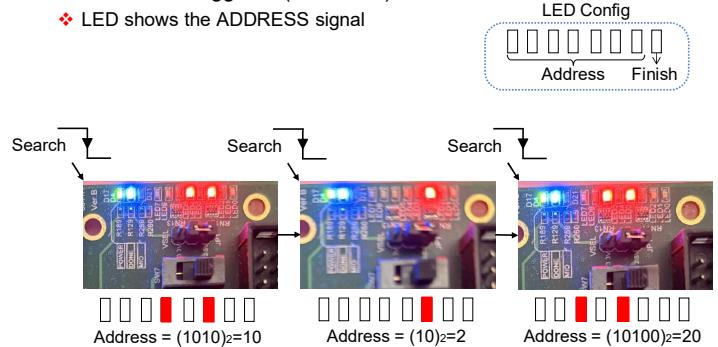
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## Result

- After start signal is sent, TB receives MATCH signal from TOP once Search SW is triggered (active low)
  - LED shows the ADDRESS signal



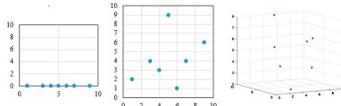
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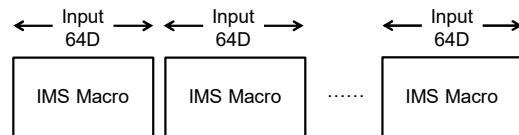


## Curse of Dimensionality

- As dimensions increases, data become increasingly sparse, causing traditional algorithms to struggle



- The number of dimensions should meet the HW provided by MXIC
  - 64-dimensional INT3 L2-norm search



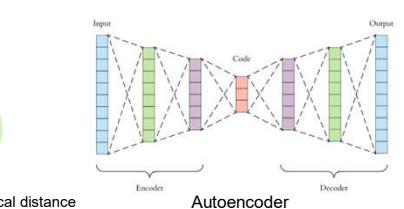
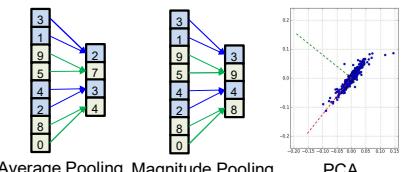
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## Methods of Dimension Reduction

- Linear
  - Pooling
    - Average Pooling
    - Magnitude Pooling
  - Principle Component Analysis
- Non-Linear
  - UMAP
  - Autoencoder (AE)



Closer points → exponential decay to maintain local distance  
Farther points → inverse-polynomial to maintain global distance

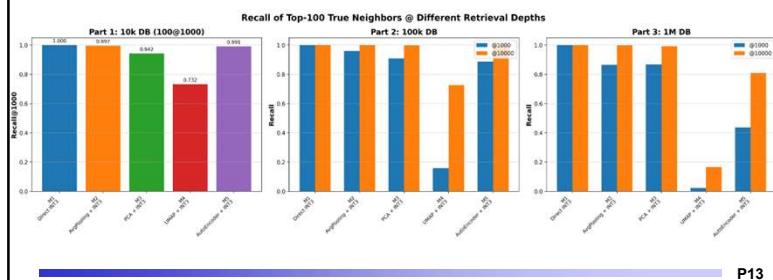
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## Experimental Results (SIFT-1M)

- ❖ Using SIFT-1M dataset
  - ❖ Vector dimension: 128 -> 64
  - ❖ Quantization method: min-max quantization
  - ❖ Avg. Pooling > PCA >= AE > UMAP



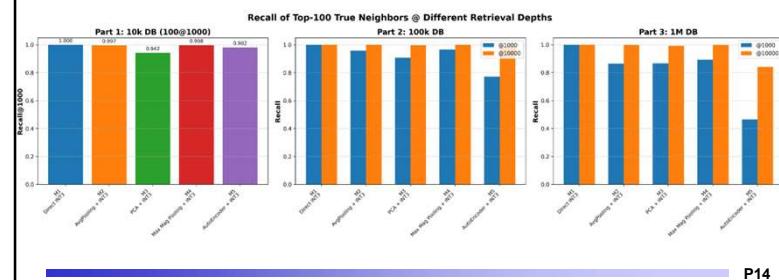
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## Experimental Results (SIFT-1M)

- ❖ Using SIFT-1M dataset
  - ❖ Vector dimension: 128 -> 64
  - ❖ Quantization method: min-max quantization
  - ❖ Since the performance of UMAP is worst, it is replaced by magnitude pooling
  - ❖ Avg. Pooling = Mag. Pooling >= PCA >= AE



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## Experimental Results (Omniglot)

- ❖ Using Omniglot 20-way-5-shot experiment
  - ❖ Embedding dimension: 128 -> 64
  - ❖ Quantization method: min-max quantization
  - ❖ AE = Avg. Pooling = PCA >= Mag. Pooling



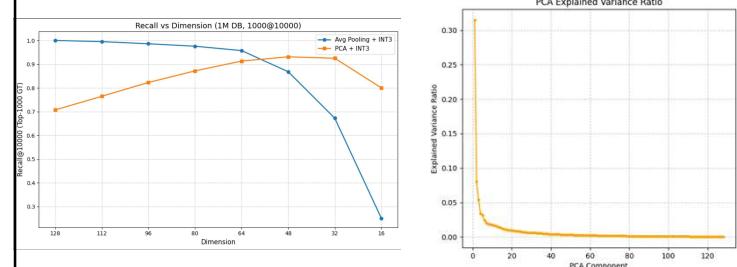
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## Analysis of PCA

- ❖ PCA seems cannot win against average pooling
  - ❖ Is this true for all dimensions?
  - ❖ Why PCA achieves better recall rate when dim < 60
  - ❖ Too much noise from less representative dimensions
  - ❖ Low explained var. from dim 60 to 128



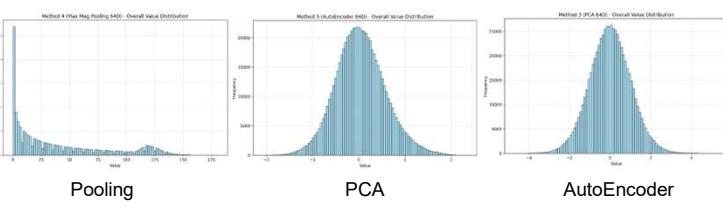
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## Data Distribution under Different Methods

- ❖ What does the distributions look like after different dimension reduction methods
  - ❖ Some methods produces long-tail distributions
  - ❖ Others produces bell-shaped distributions
  - ❖ Can our quantization method fit all of these distributions?

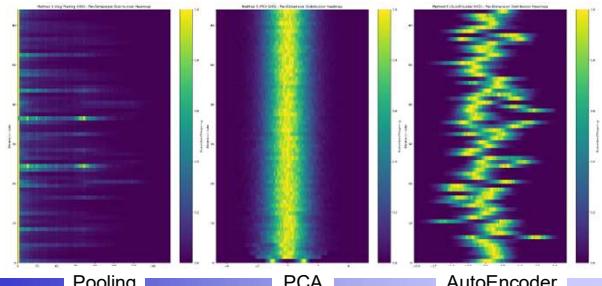


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## Data Distribution under Different Methods

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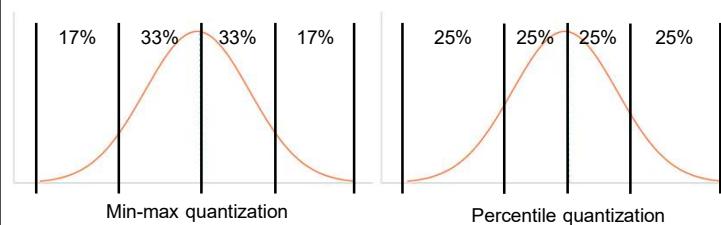
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## Quantization Makes Big Differences

- ❖ New quantization method : Percentile Quantization
  - ❖ Quantize data according to its percentile among all data
  - ❖ Non-linear quantization
  - ❖ Better to distinguish top-k nearest neighbors



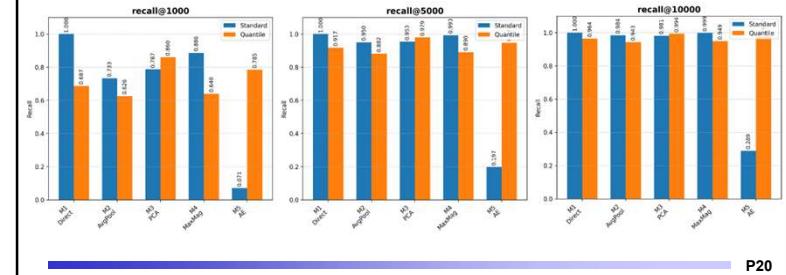
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## Experimental Results

- ❖ Percentile quantization boosts the recall rate of AutoEncoder method
  - ❖ Embedding dimension: 128 -> 64
  - ❖ Blue: Min-max Quantization. Orange: Percentile Quantization
  - ❖ Min-max -> better for long-tail distribution
  - ❖ Percentile -> better for bell-shaped distribution



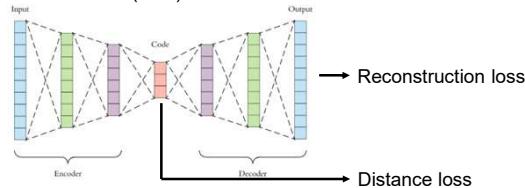
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## Modification of AutoEncoder

- ❖ Original AutoEncoders consider reconstruction loss as loss function
  - ❖ Construct a low dimension space
  - ❖ Can it preserve distance information?

- ❖ New loss function
  - ❖ Distance loss = MSE(distance before and after dimension reduction)
  - ❖  $k \times \text{reconstruction loss} + (1 - k) \times \text{distance loss}$



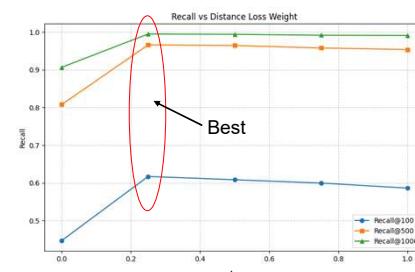
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## Experimental Results

- ❖ New loss function
  - ❖  $k \times \text{reconstruction loss} + (1 - k) \times \text{distance loss}$
  - ❖ Recall rate increased significantly by adding distance loss into loss function
  - ❖ Considering both reconstruction and distance info achieves best recall rate



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## Conclusion

- ❖ Embedding dimension reduction
  - ❖ Average pooling is simple but effective
- ❖ Analysis of PCA (Principle Component Analysis)
  - ❖ PCA outperforms average pooling when dimensions < 60
- ❖ Analysis of quantization method
  - ❖ Min-max quantization is better for pooling methods
  - ❖ Quantile is better for PCA and AutoEncoders
- ❖ Modification of AutoEncoder method
  - ❖ Preserving distance information increases recall rate
  - ❖ Best recall @ reconstruction : distance = 3 : 1

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