



Partb) int (compute Median (root) { find the size from root size (root & size) if rize is even index1 = size/2 index 2 = index 1+1 find data at index 1, assign to data 1 Turing helper find data at index 2, arrigh to datar2) method return the average of datal and data2 index = size/2+1 return the data at index using helper method 3 find Data (root, index) if size of left subtree is equal to index - 1 return root & data else if index is smaller or equal to sixe of left subtree return find Data (root > left, in alex) else return find Data (root > right, index) Il size attribute is added to tree noder

Compute Median method gets the size of the tree from the rest and decider how to compute the median. If the size is odd, median is simply the node at the middle. If the size is even median is the average of two nodes at the middle. After computing the indexes, helper method find Data is called to acquire the data at necessary indexes. find Data only traverses the necessary points of the tree and thince it is an AVL tree the time complexity in O(log N). Keeping the size in the noder is a choice time order to compute the vize of the tree which would decrease the efficiency.

Part c)
bool check AVL (root) {

if root in NULL

return true

get the heightr of left and right subtreer
if absolute of their difference >1
return false

else

check bolonce of left subtree ? recursive check bolonce of right subtree? return true if they are both bolonced else

return false

This algorithm starts from the root and compared the balance of each node until it finds an imbalance. If the height attribute is kept in three node, like checking the balance would take O(1) time, so time complexity is O(n) at worst case where all the nodes one visited and checked and O(1) at best case where the root has an imbalance. If the height is not stoned at nodes computing the height will have O(n) time complexity which will make the method run at O(n2) time.

If we have the same number of computers and the requests it is certain that we will get the minimum process time. So, if we start the tries from N/2 computers, we can determine in which half we should keep trying. For example if the waiting time does not exceed the given time we can try with N/4 computers and continue in the same manner recursively until we found the minimum number of computers that door not exceed the waiting time. Similarly if the vaiting time exceeds the given time for N/2 computers, we can search the upper half necursively. This method will make the time complexity O(log N), which is way more efficient for very large number of requests.