

Enabling Cool Rubin Science with Robust Cross-Matches in the Faint, Crowded LSST Sky

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2024 RUBIN SOLAR NEIGHBORHOOD ULTRACOOL DWARFS MEETING - 26/JAN/24

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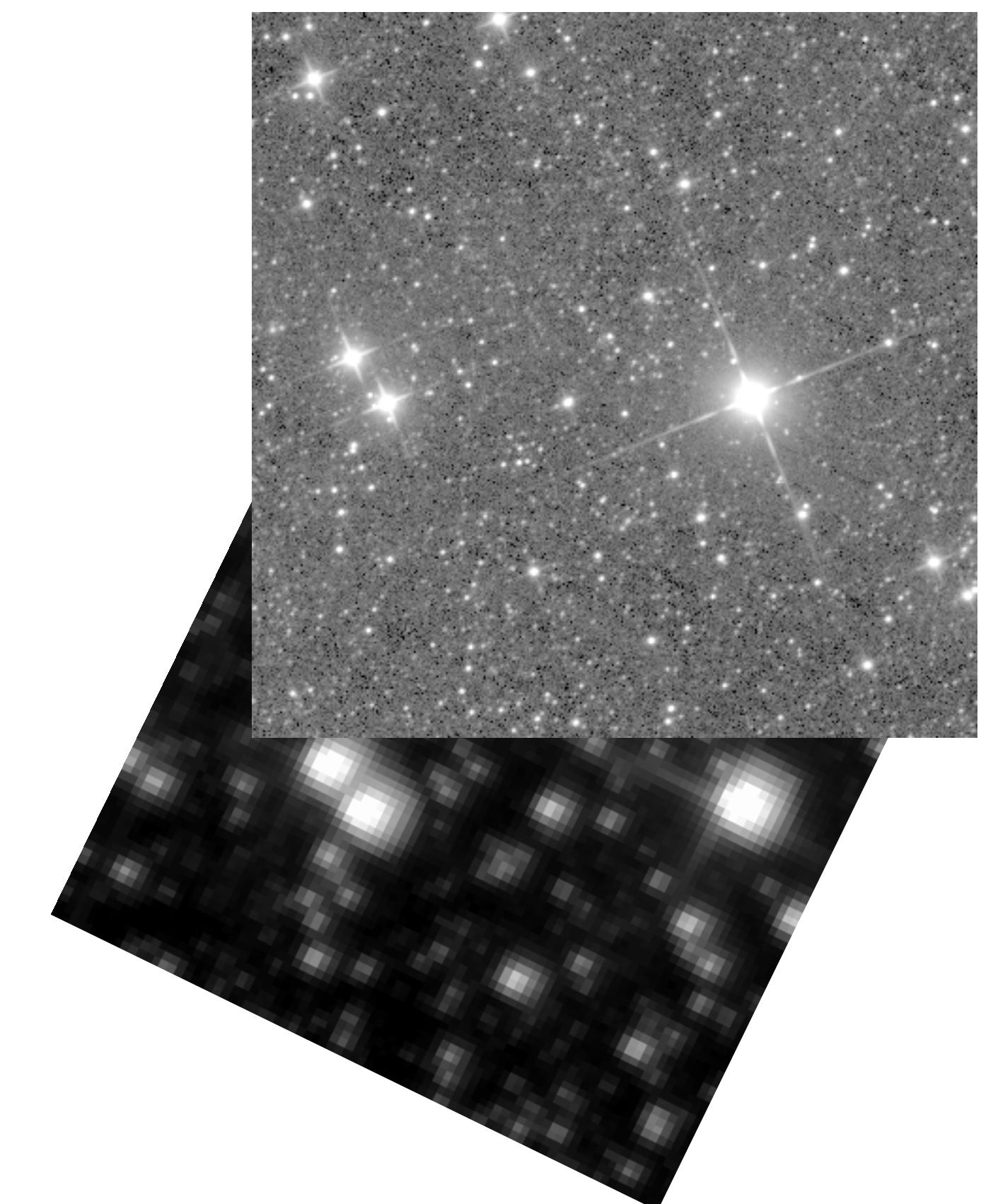
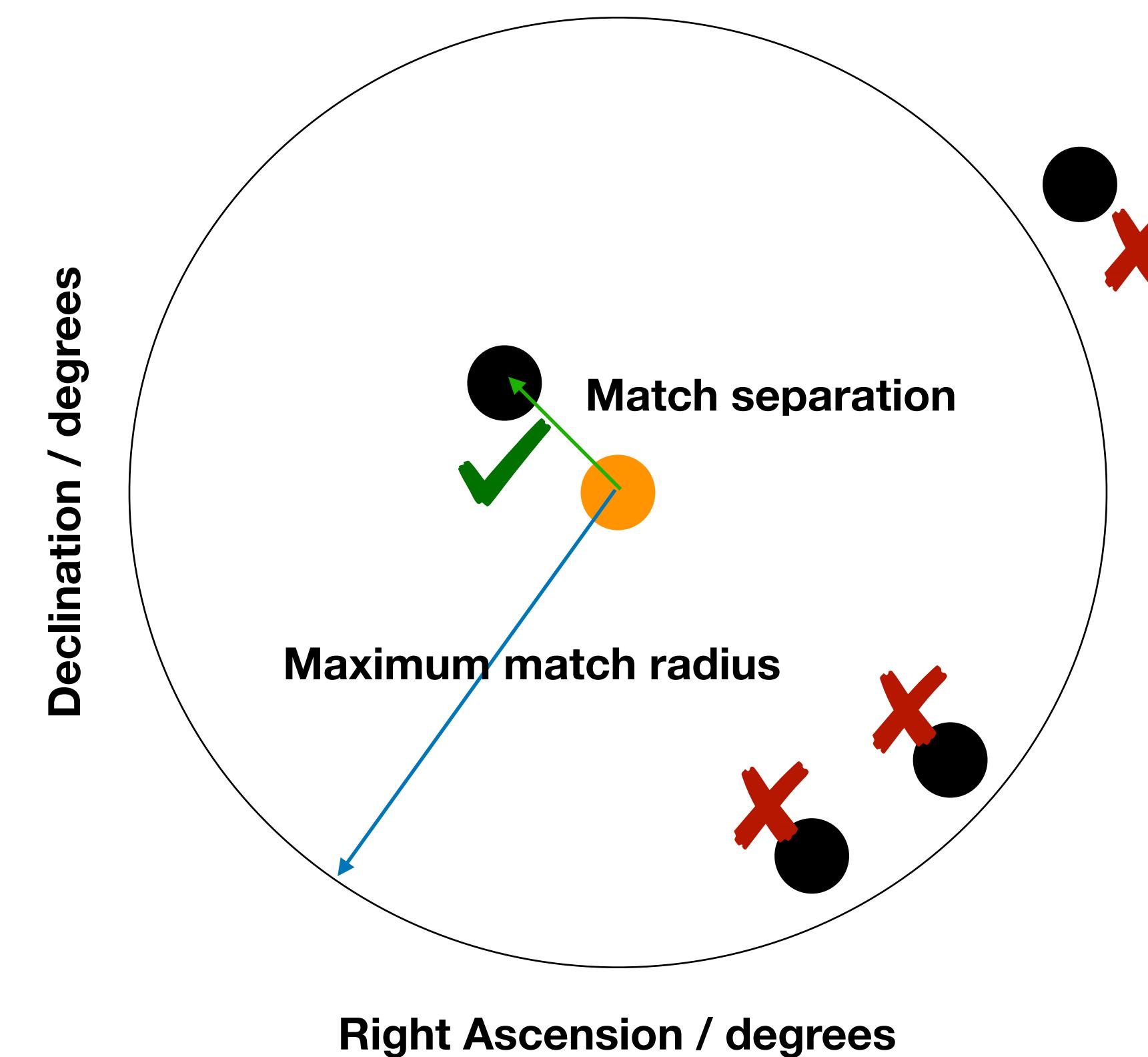
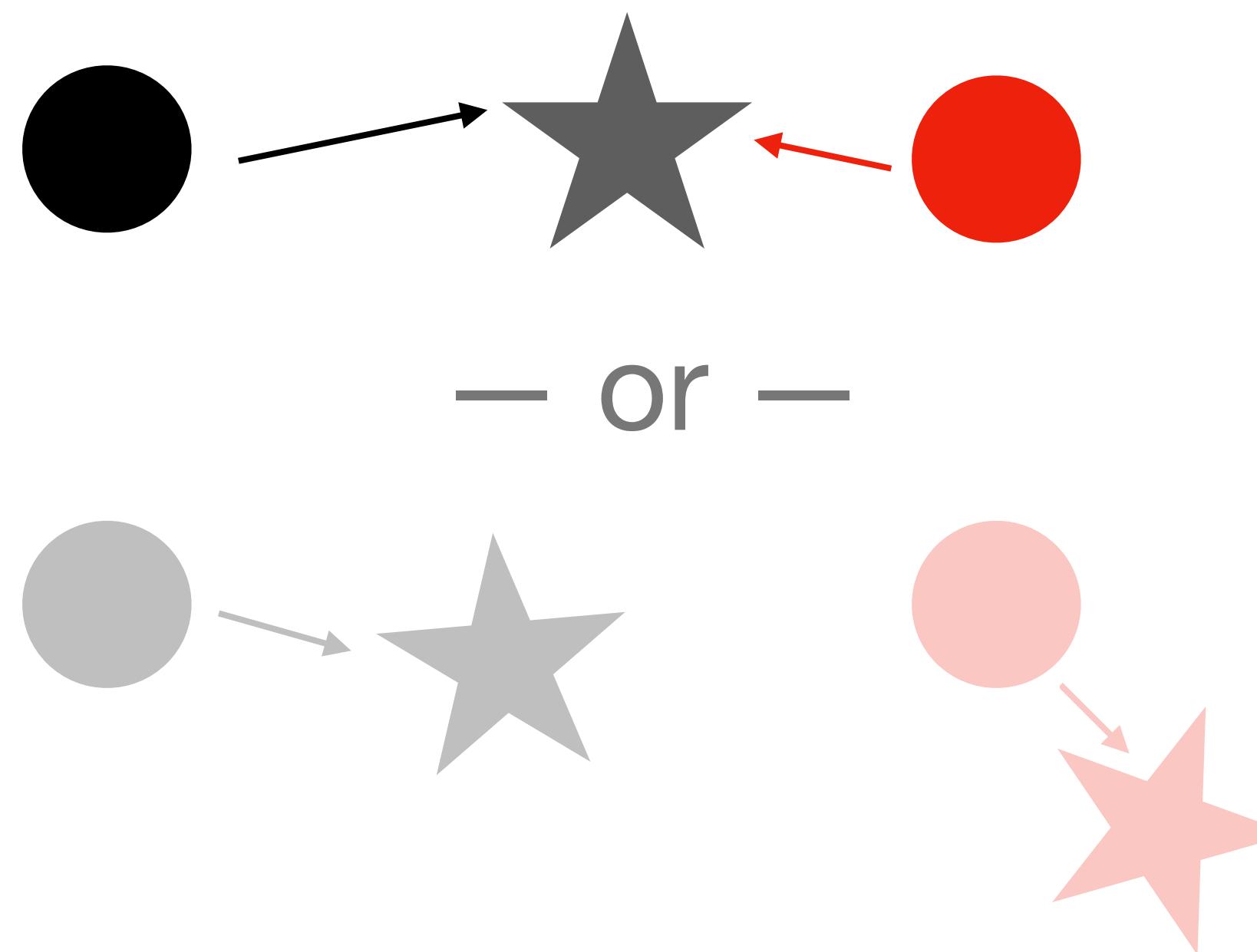
UK
LSST:UK Consortium



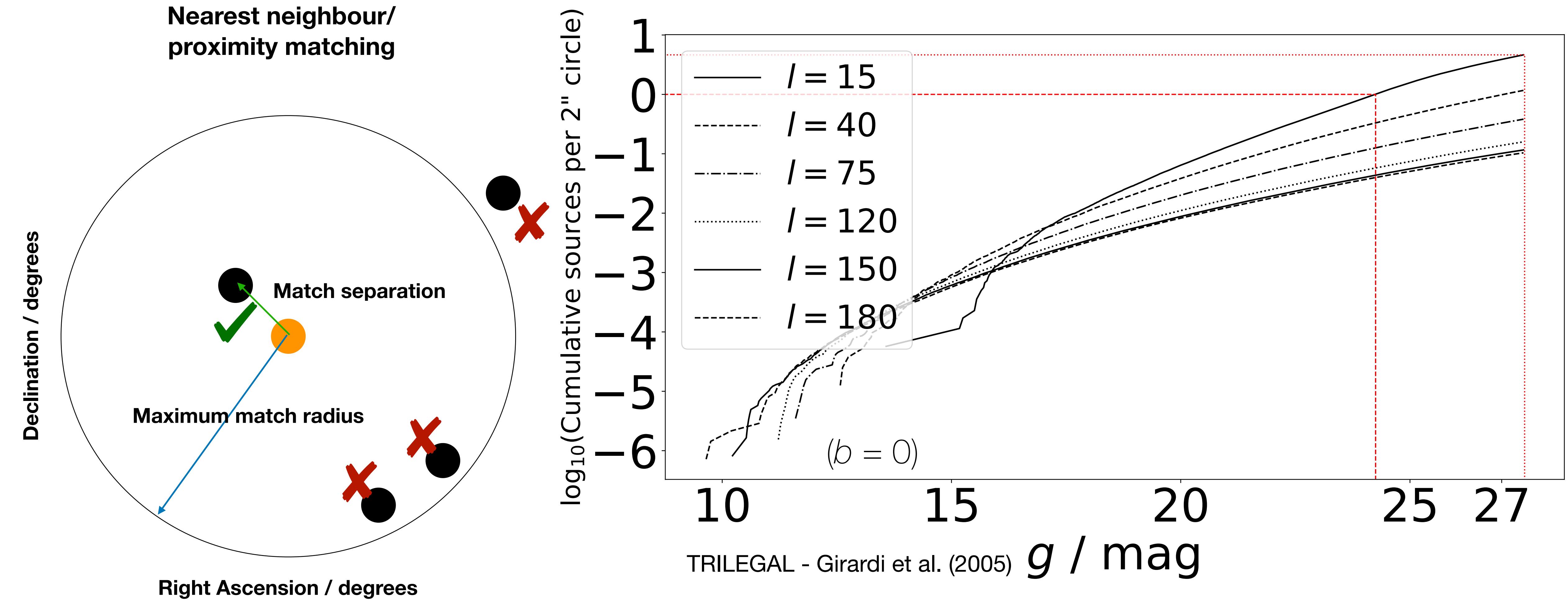
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“Simple” Cross-Matching



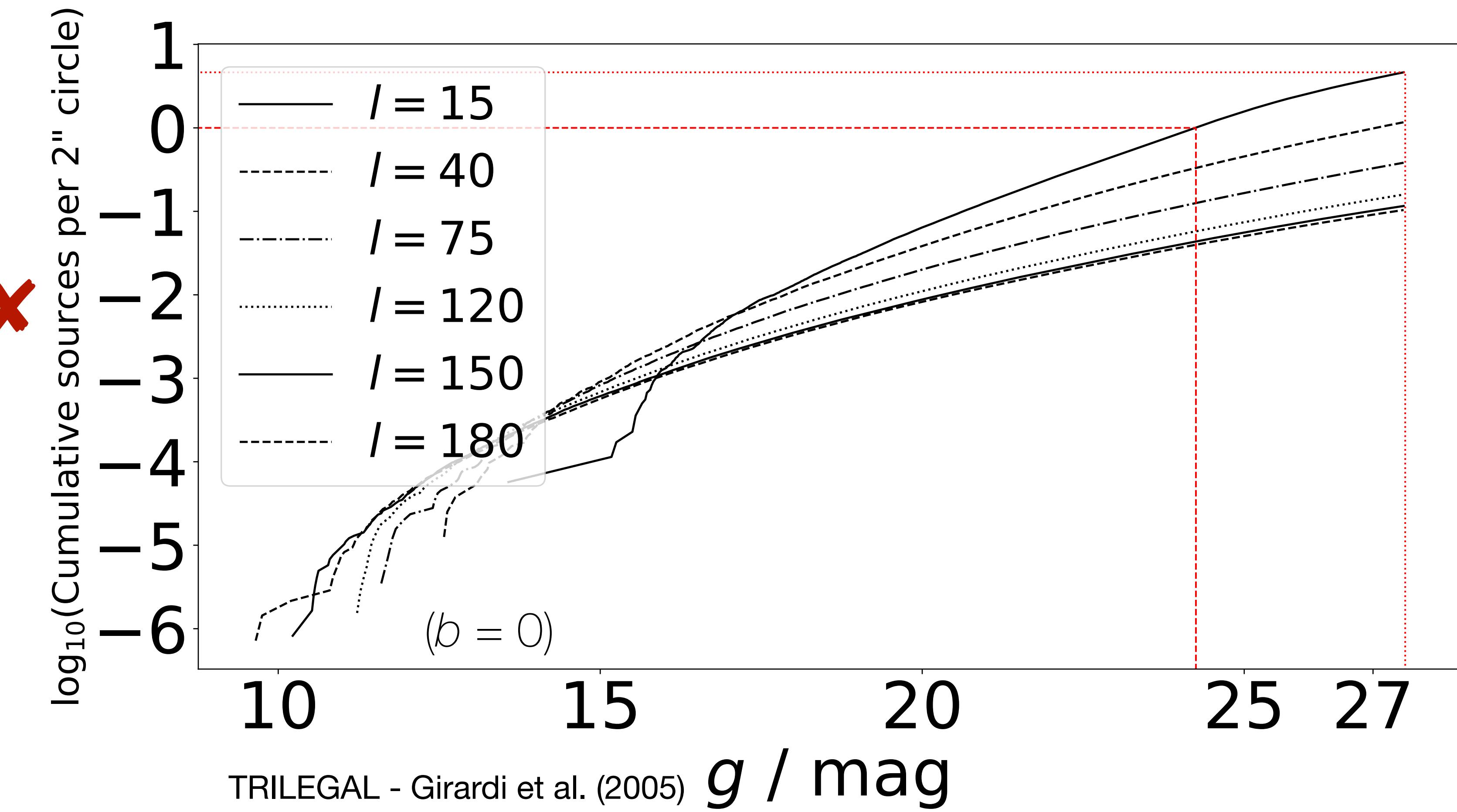
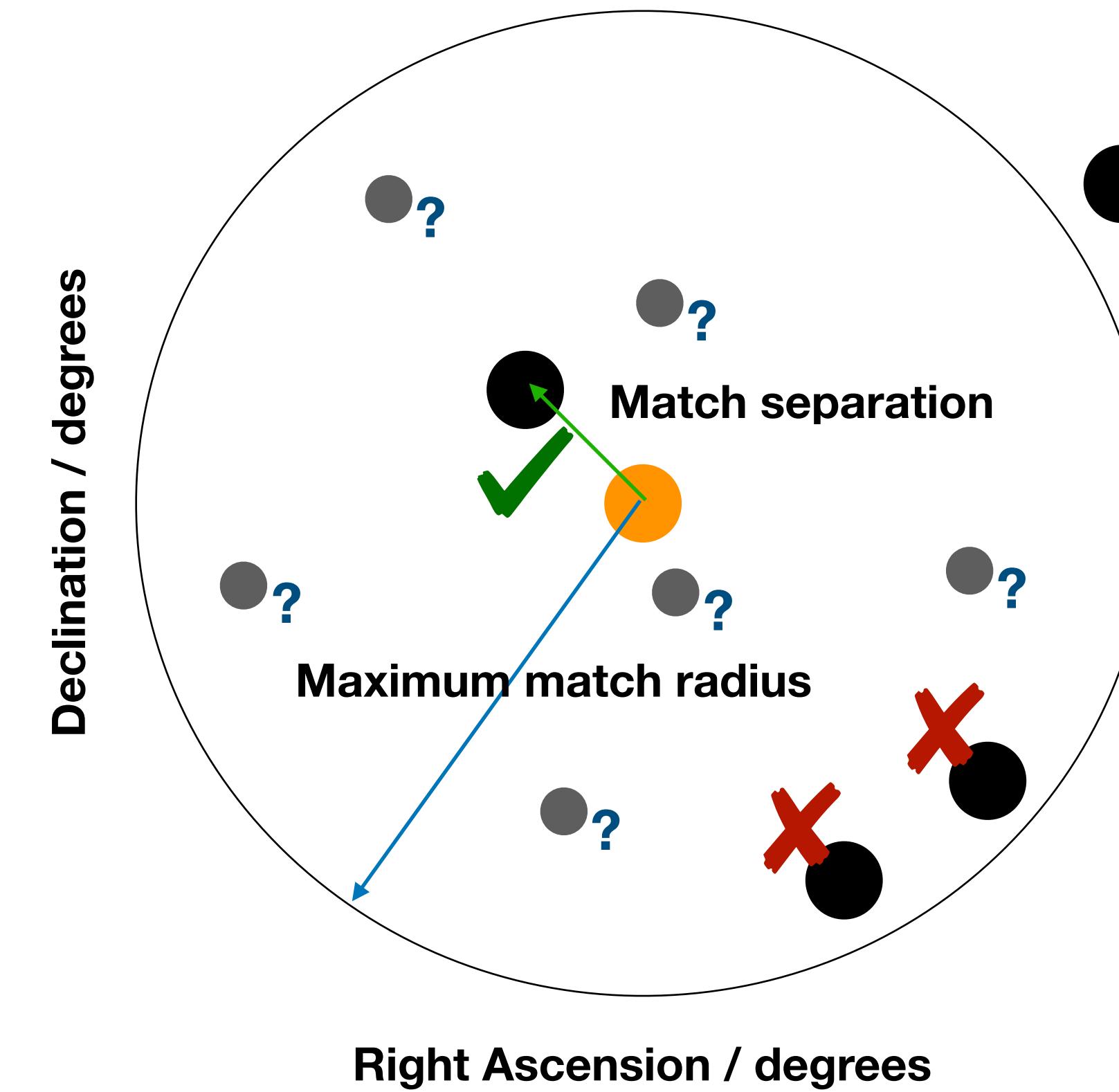
The Problem With LSST



The Problem With LSST

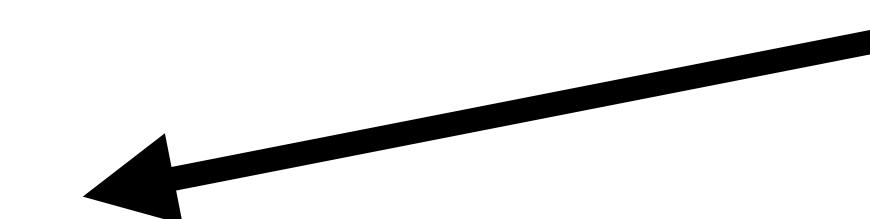
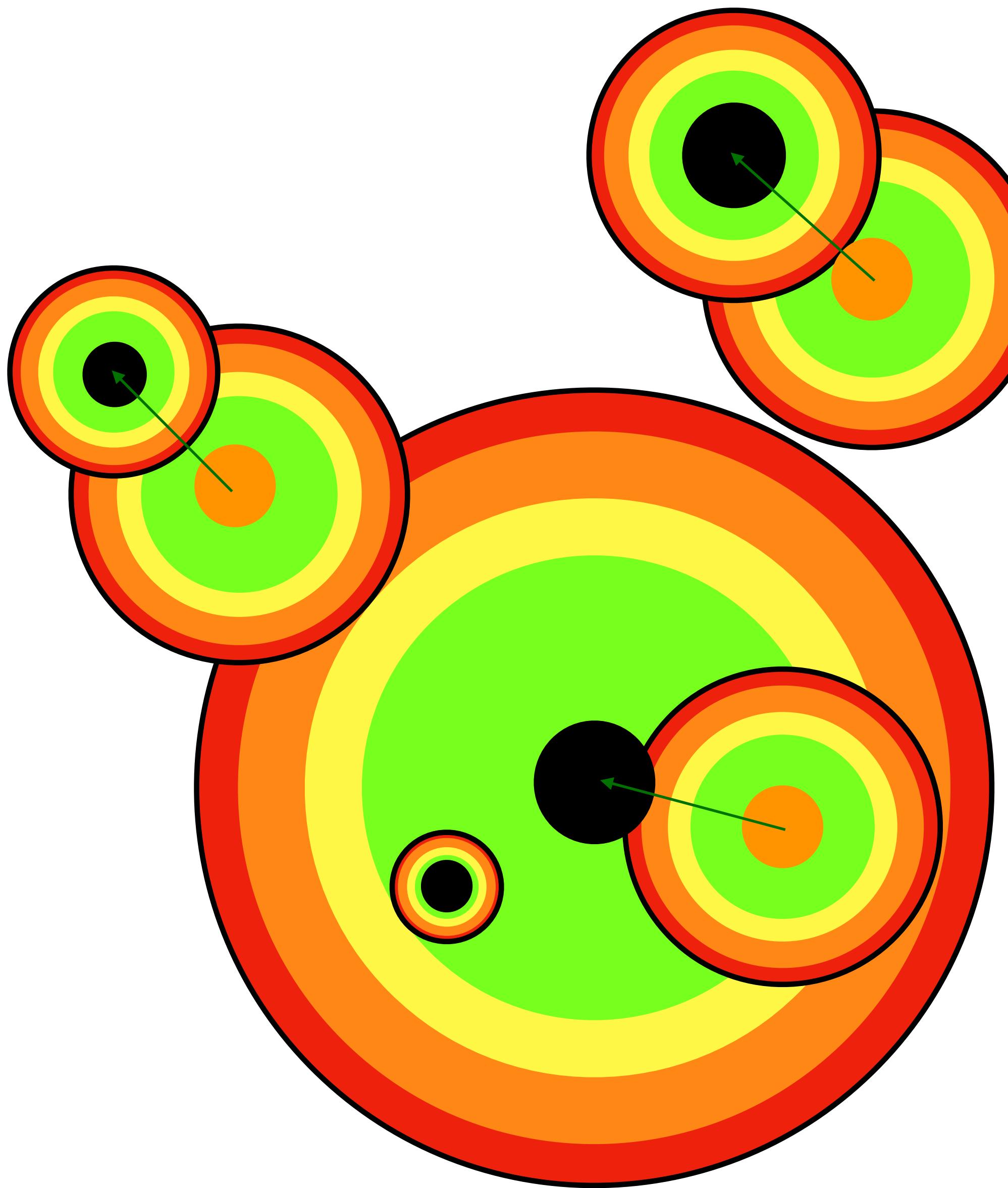
(It's still a few randomly placed objects in every match radius at high Galactic latitudes)

Nearest neighbour/
proximity matching



Nearest-neighbour matching *will not* work in the era of Rubin!

Probabilistic Cross-Matching



Probability of two sources having their on-sky separation given the hypothesis they are counterparts

$$P(\zeta, \lambda, k | \gamma, \phi) = \frac{1}{K} \times \prod_{\delta \notin \zeta \cap \delta \in \gamma} N_\gamma f_\gamma^\delta \prod_{\omega \notin \lambda \cap \omega \in \phi} N_\phi f_\phi^\omega \prod_{i=1}^k N_c G_{\gamma\phi}^{\zeta_i \lambda_i} c_{\gamma\phi}^{\zeta_i \lambda_i}$$

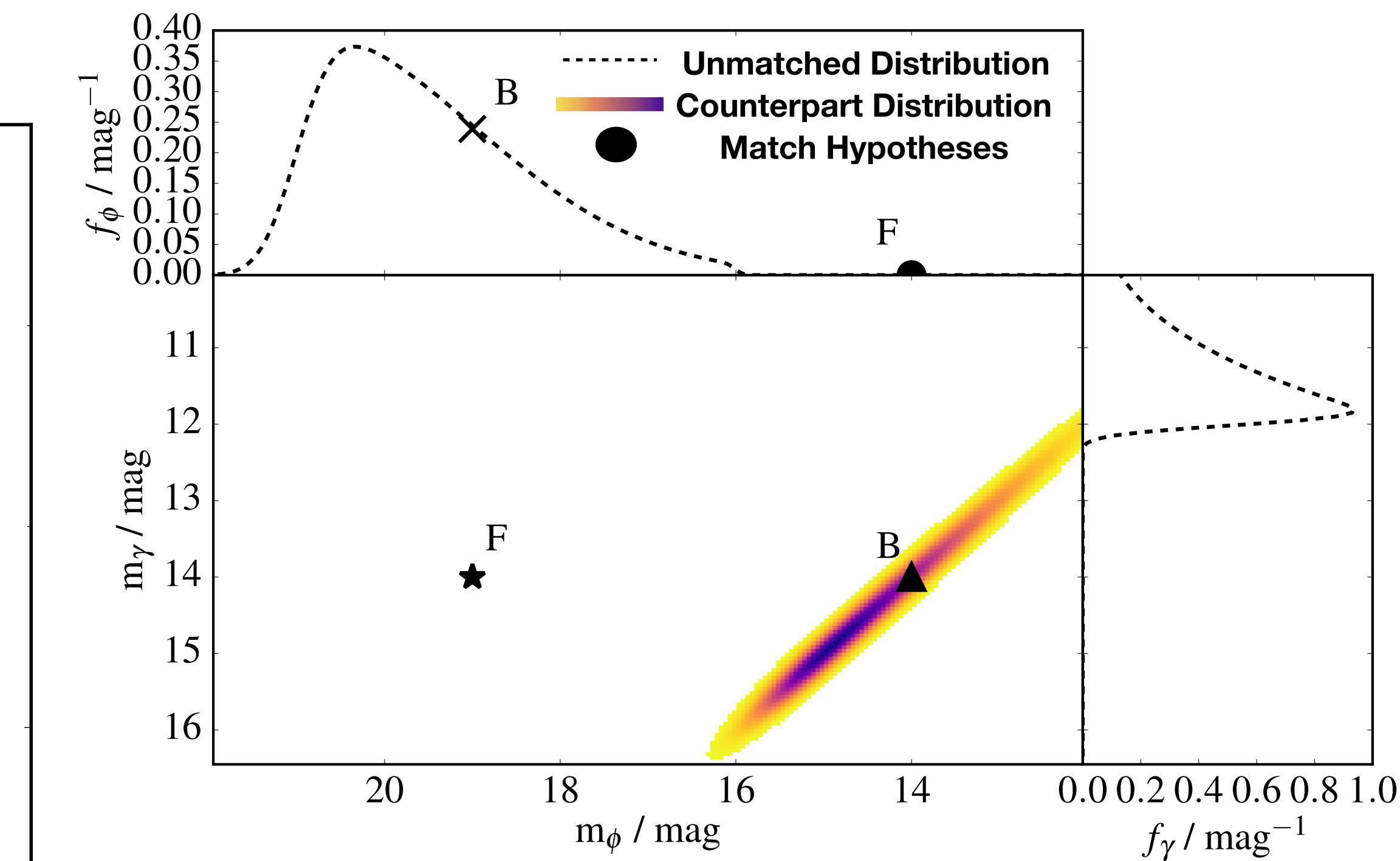
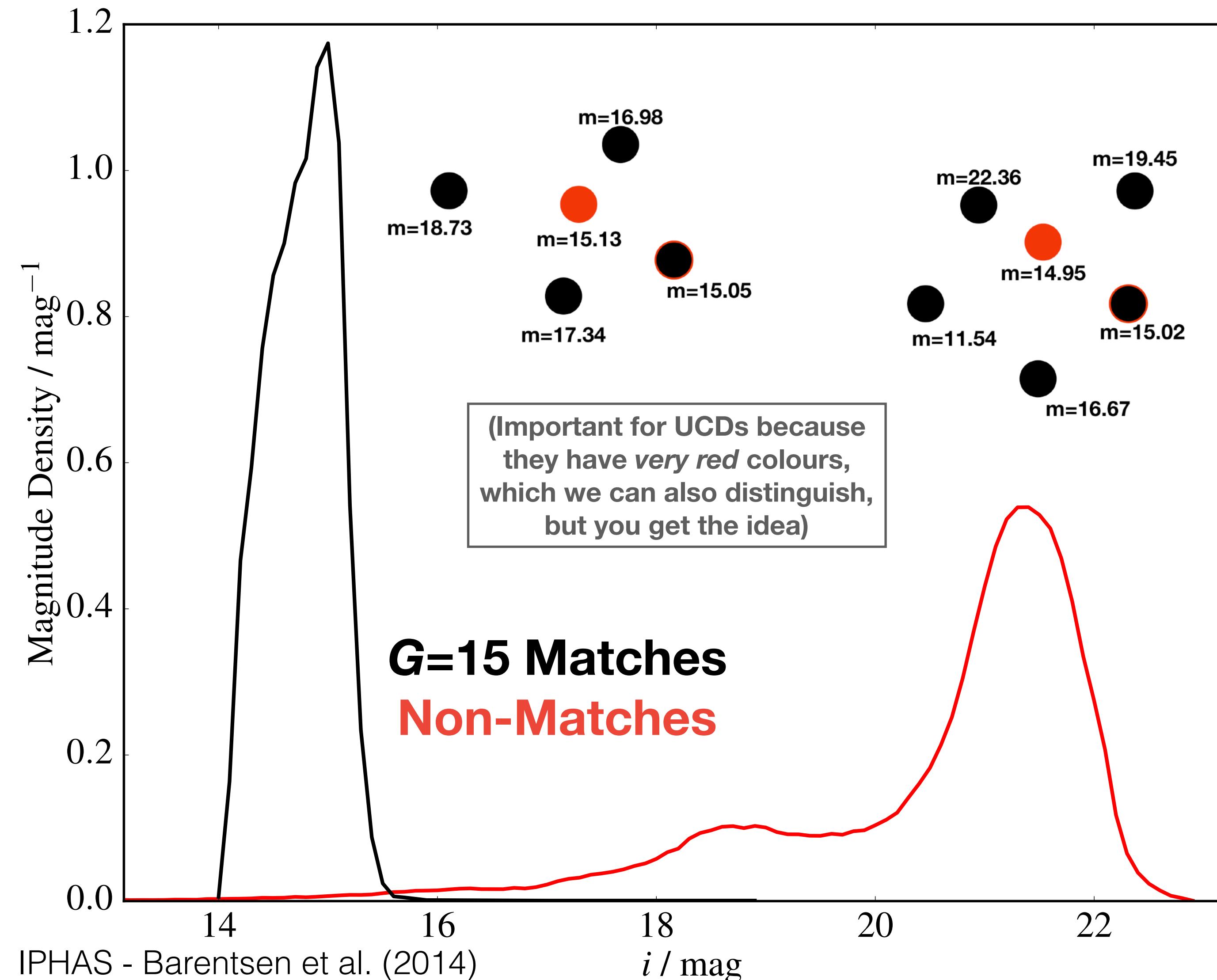
Wilson & Naylor (2018a)

Probability of sources having their brightnesses given they are unrelated to one another (“field stars”)

Probability of sources having their brightnesses given they are counterparts

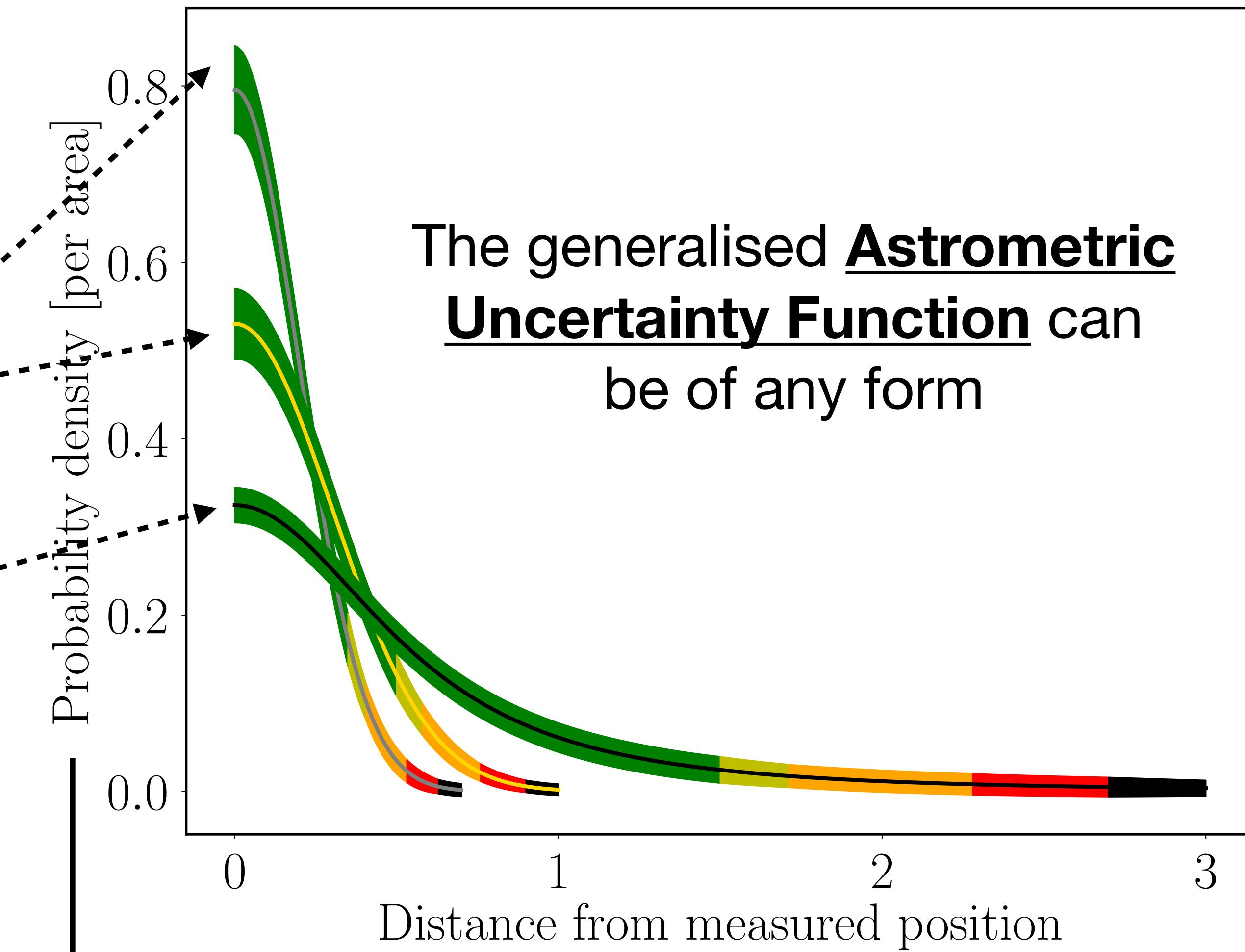
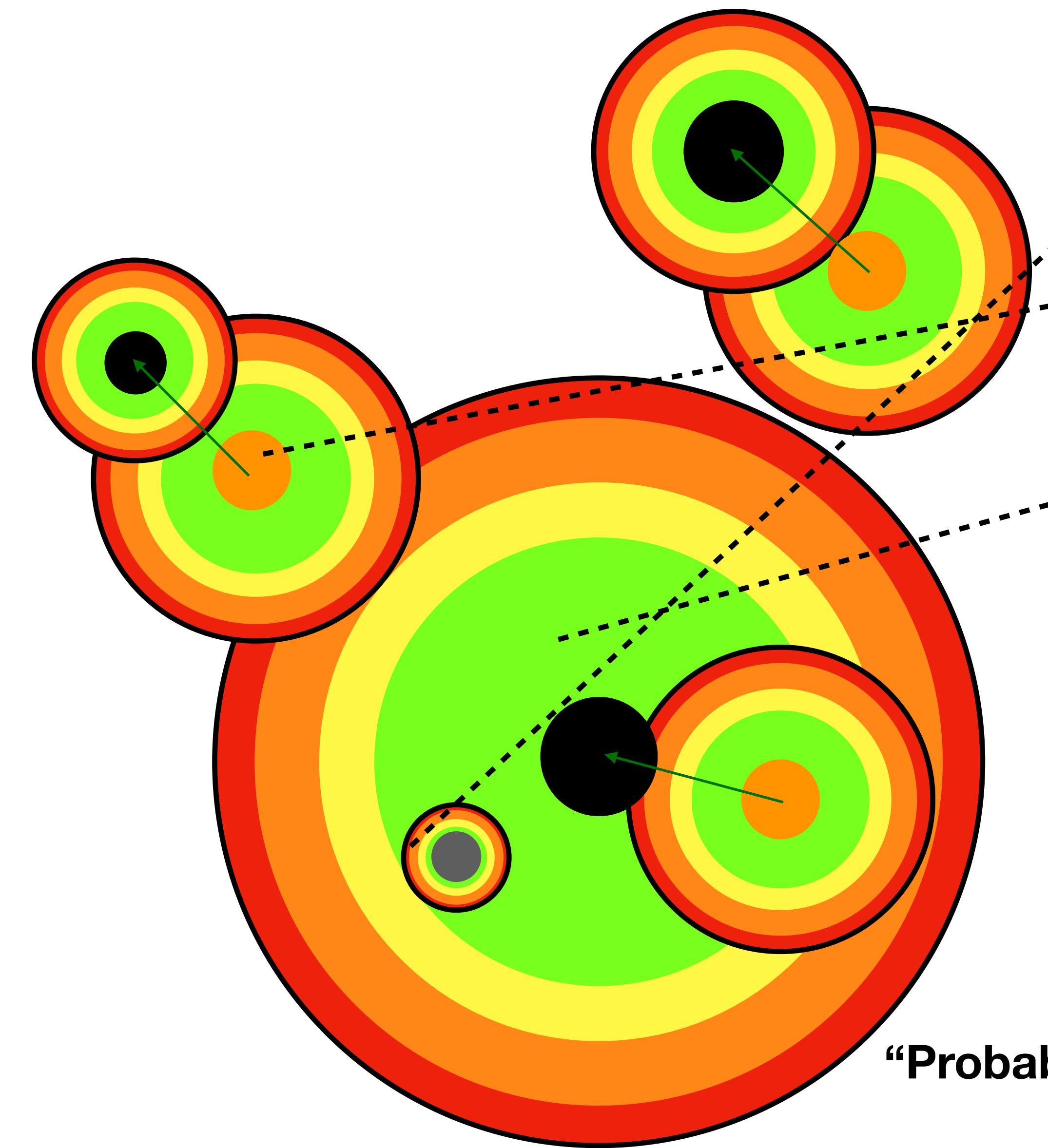
Including Magnitude Information: Rejecting False Positives

$$P(\zeta, \lambda, k | \gamma, \phi) = \frac{1}{K} \times \prod_{\delta \notin \zeta \cap \delta \in \gamma} N_\gamma f_\gamma^\delta \prod_{\omega \notin \lambda \cap \omega \in \phi} N_\phi f_\phi^\omega \prod_{i=1}^k N_c G_{\gamma\phi}^{\zeta_i \lambda_i} c_{\gamma\phi}^{\zeta_i \lambda_i}$$

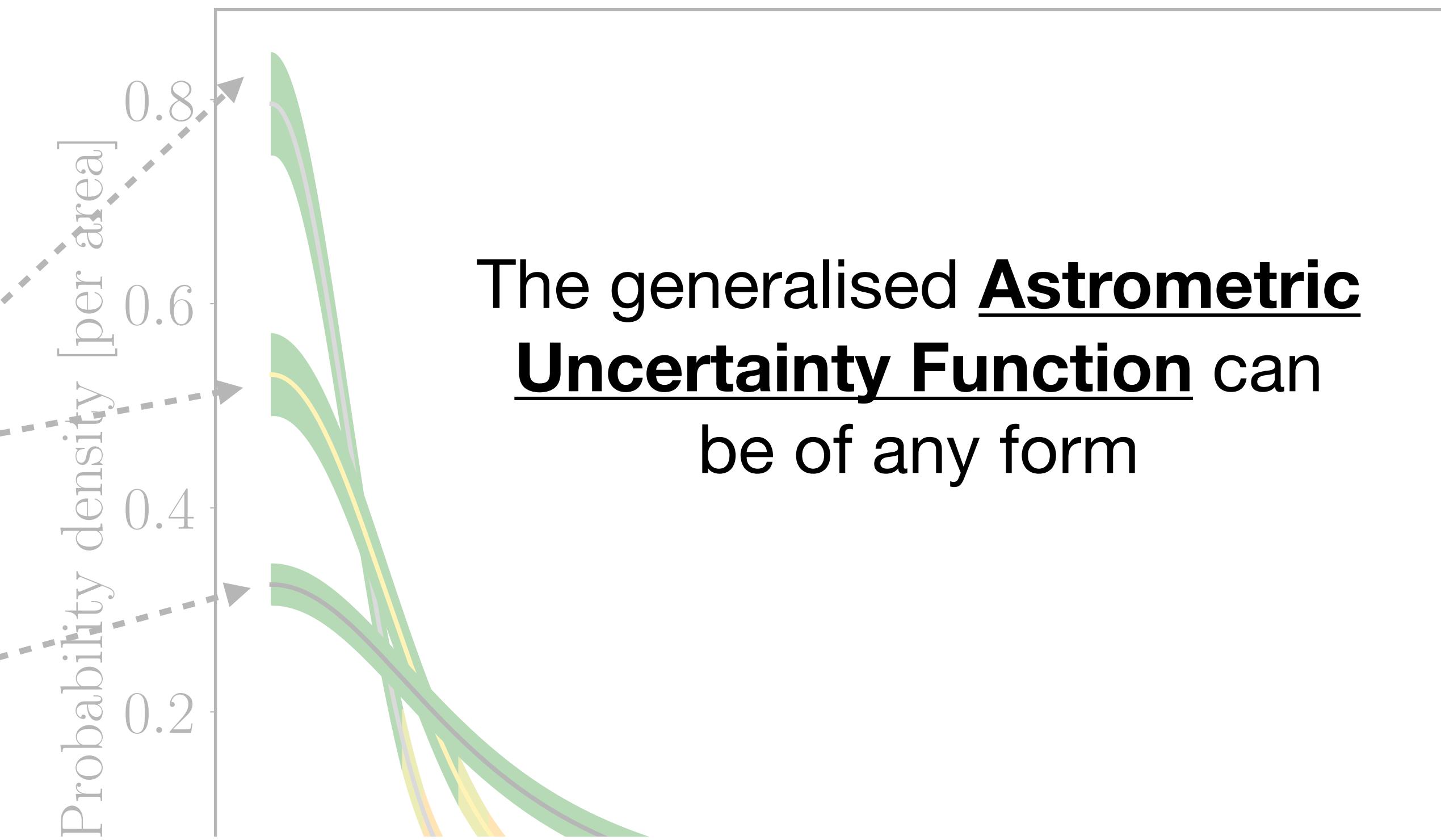
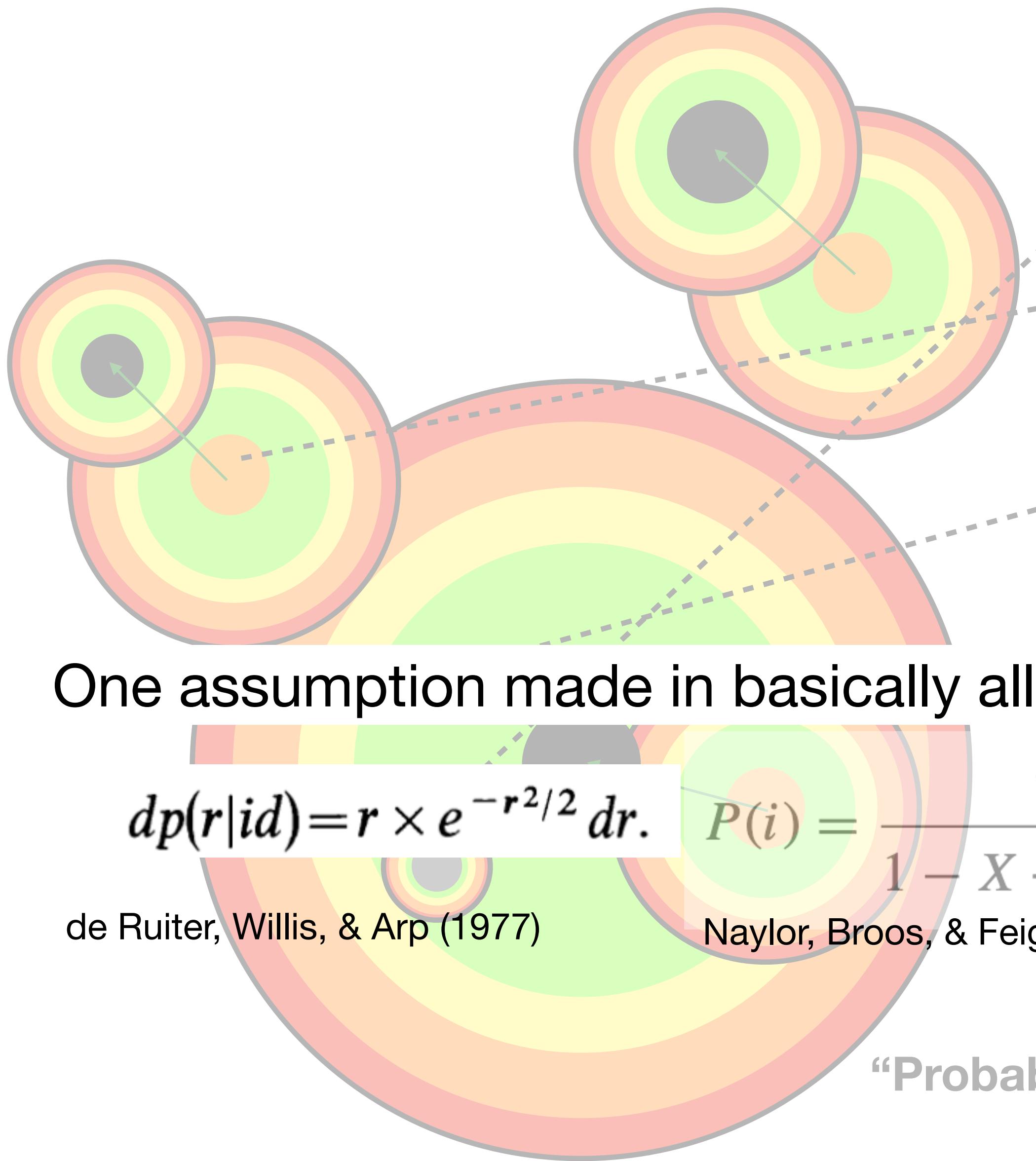


The photometry-based likelihoods (c and f) allow us to mitigate high false positive rate in crowded fields, but now we need the position-based likelihood G

Probabilistic Cross-Matching: the AUF



Probabilistic Cross-Matching: the AUF



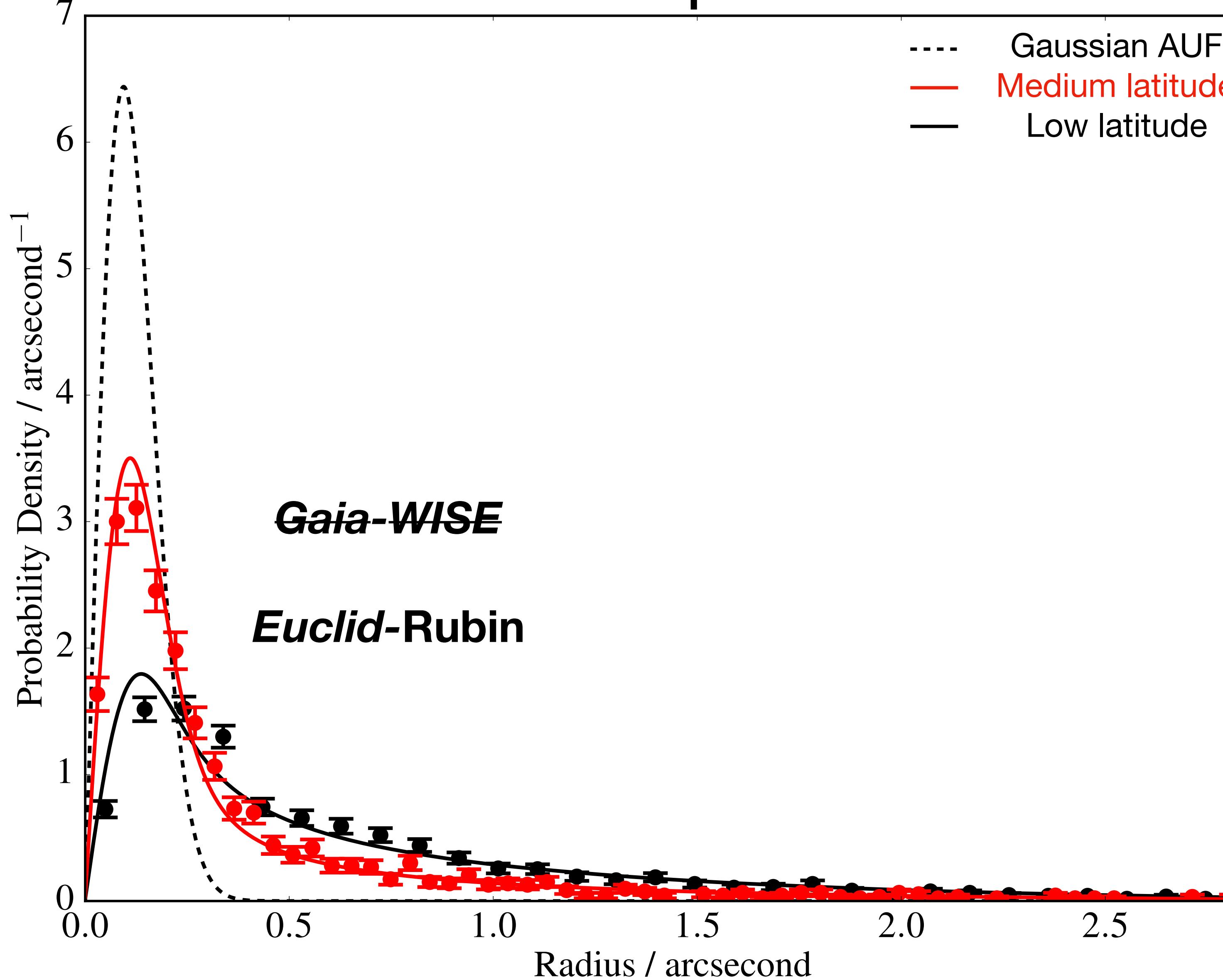
$$p(D|H) = \int p(m|H) \prod_{i=1}^n p_i(x_i|m, H) d^3m$$

$\frac{Xc(m_i) g(\Delta x_i, \Delta y_i)}{Nf(m_i)}$ 0 $\frac{Xc(m_j) g(\Delta x_j, \Delta y_j)}{Nf(m_j)}$

Distance from measured position

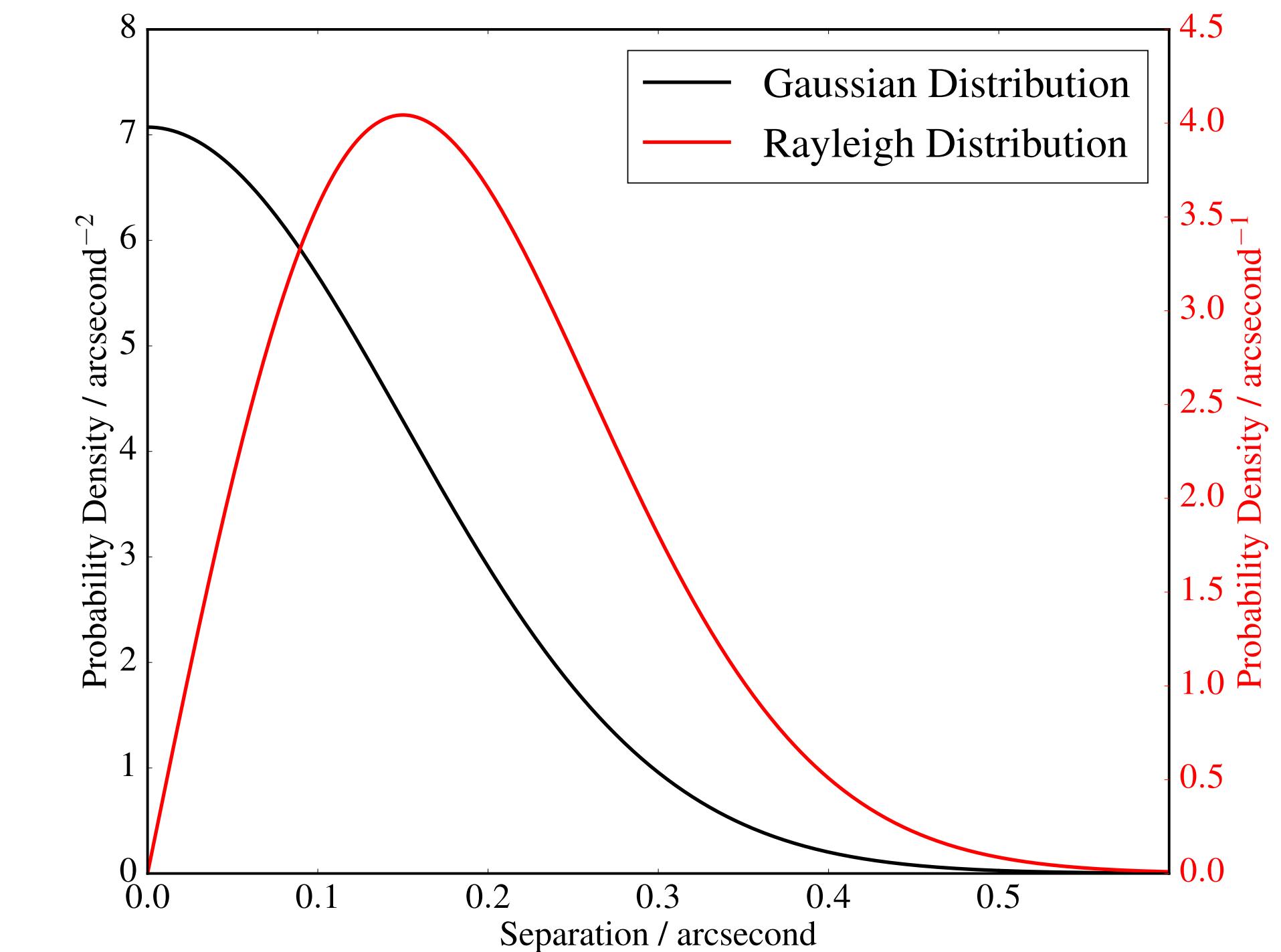
Budavári & Szalay (2008)

Additional Components of the AUF

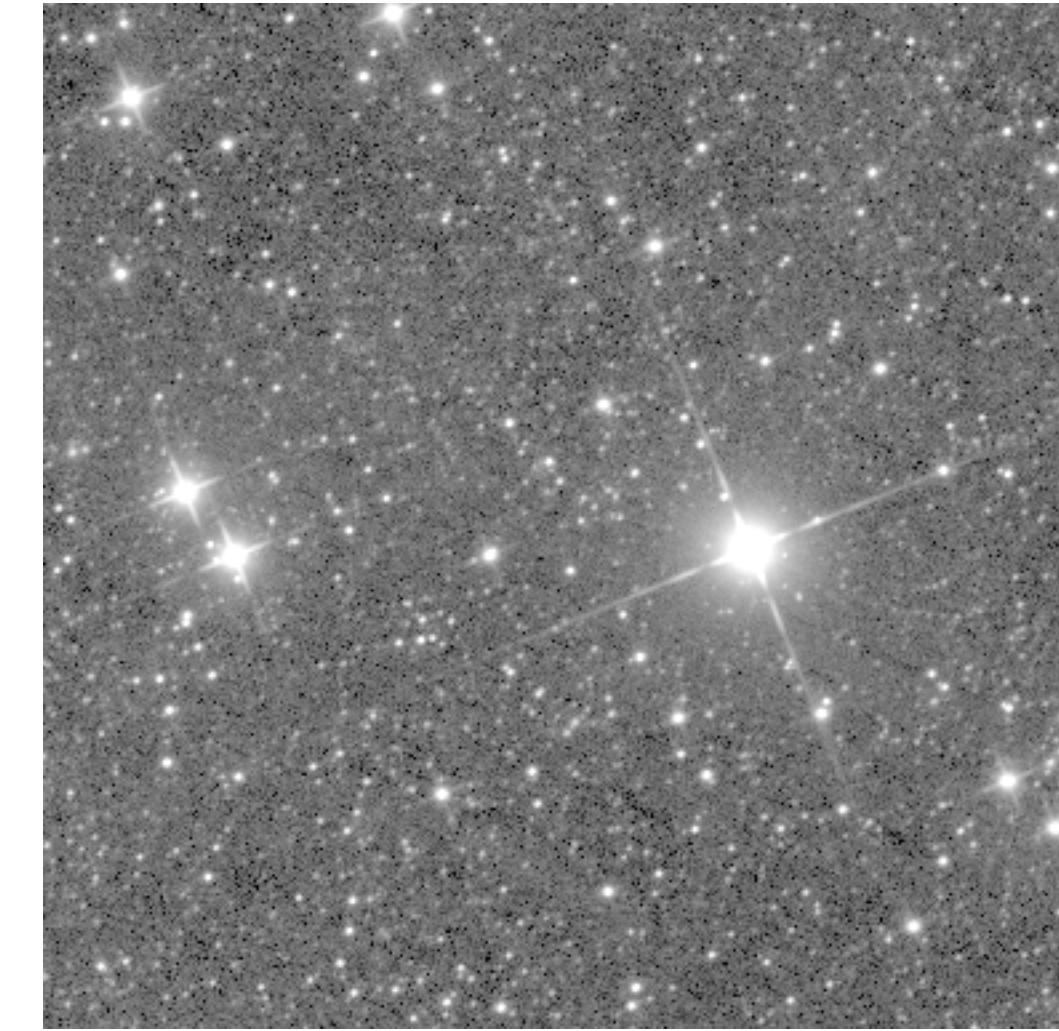
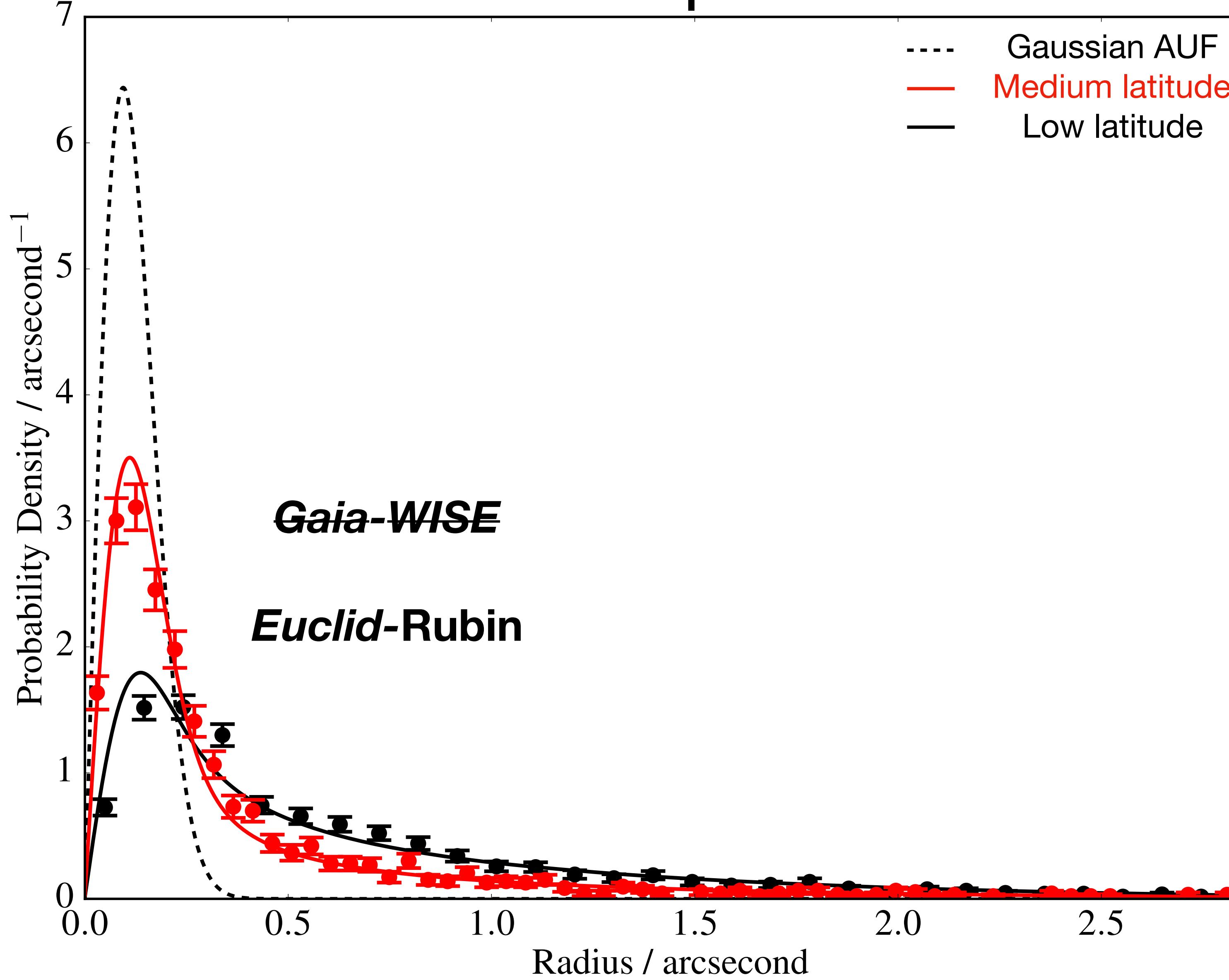


$$g(x, y, \sigma) = (2\pi\sigma^2)^{-1} \exp\left(-\frac{1}{2}\frac{x^2 + y^2}{\sigma^2}\right)$$

$$g(r, \sigma) = \frac{r}{\sigma^2} \exp\left(-\frac{1}{2}\frac{r^2}{\sigma^2}\right)$$

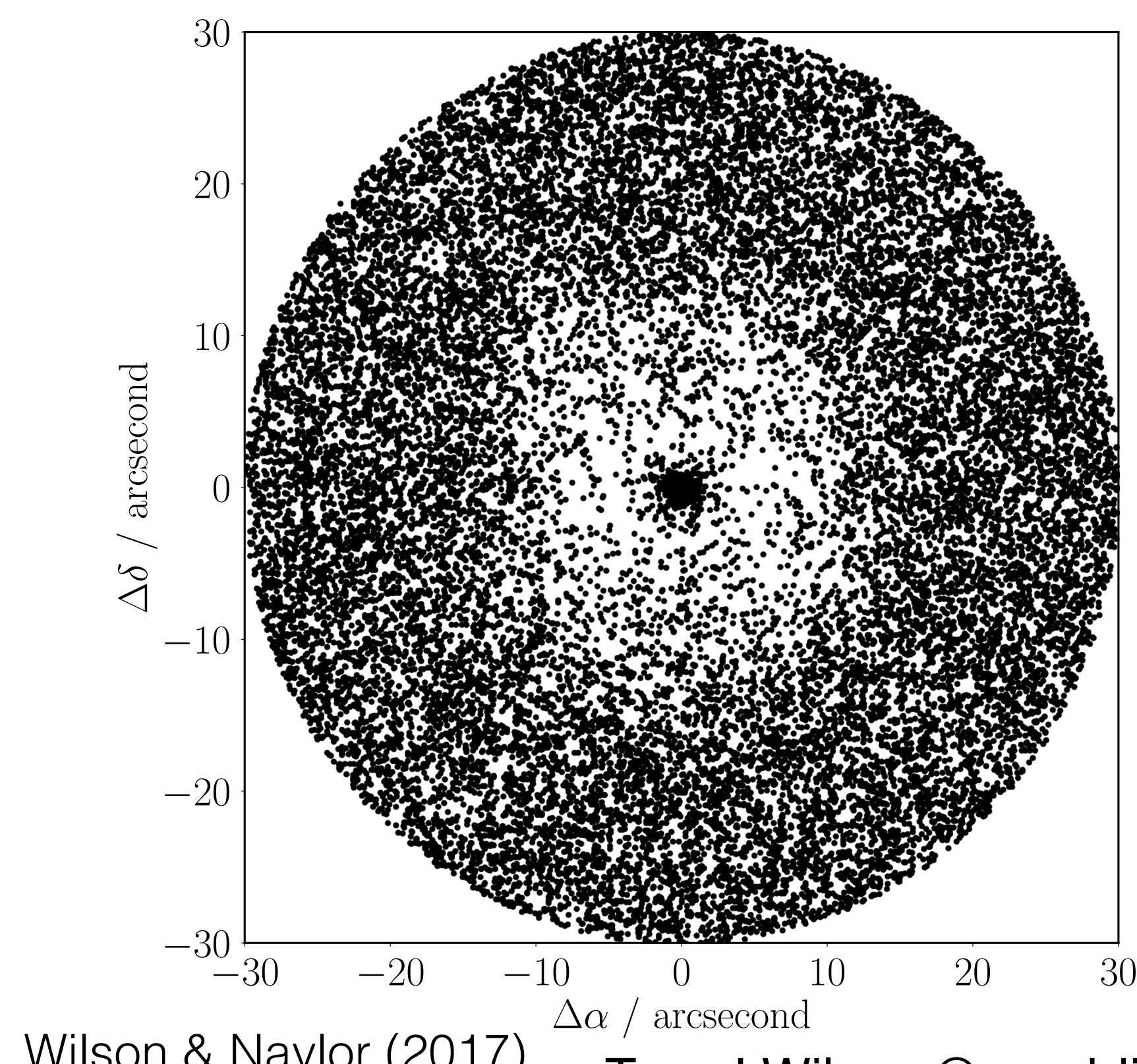
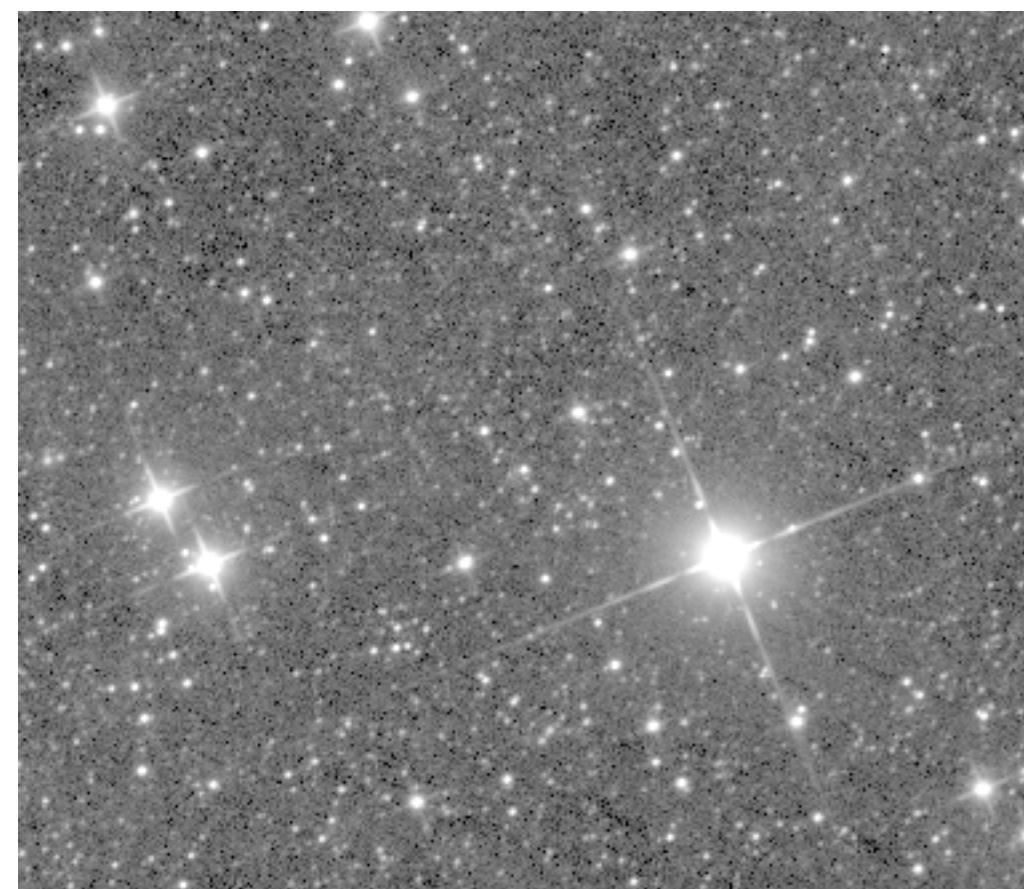
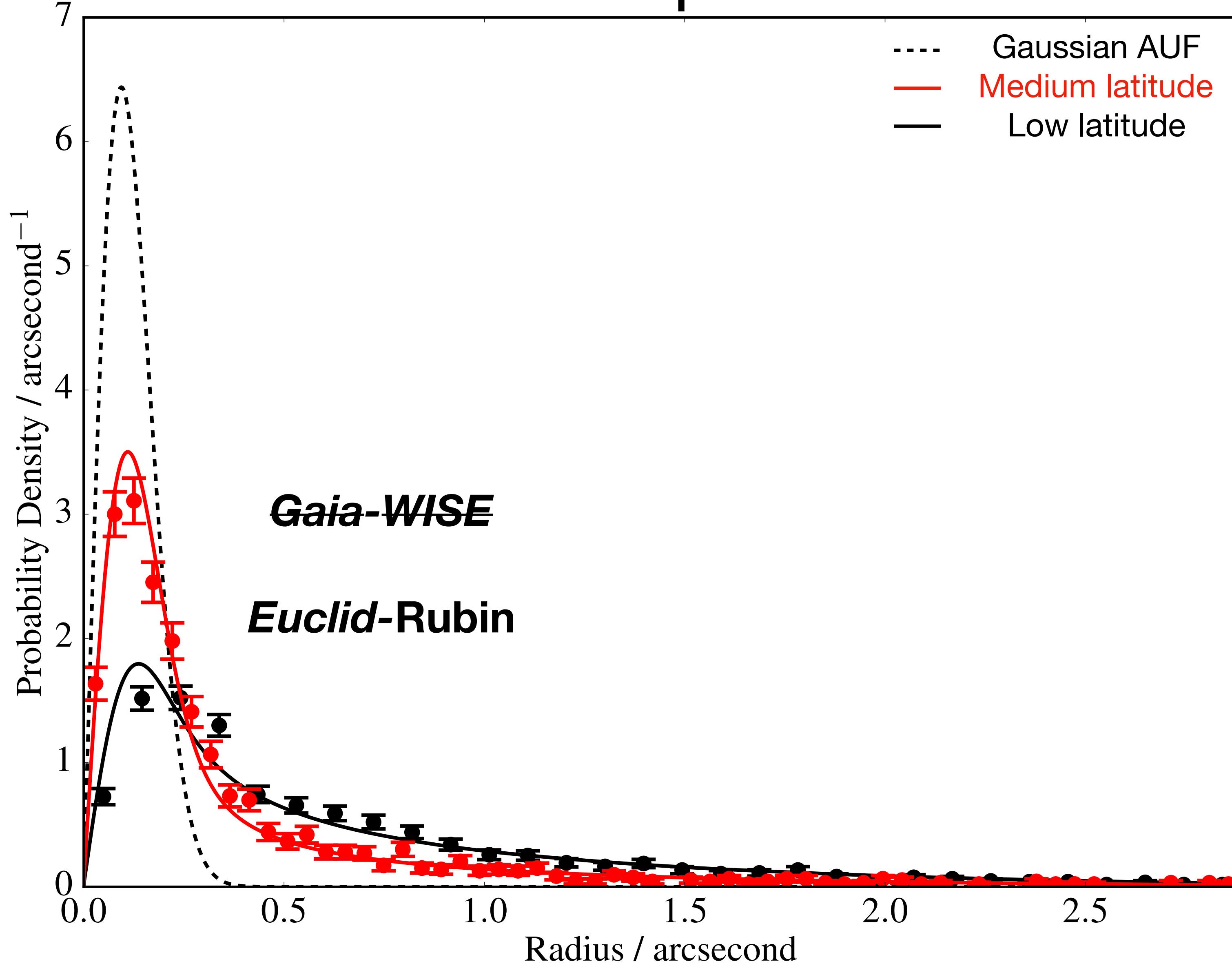


Additional Components of the AUF



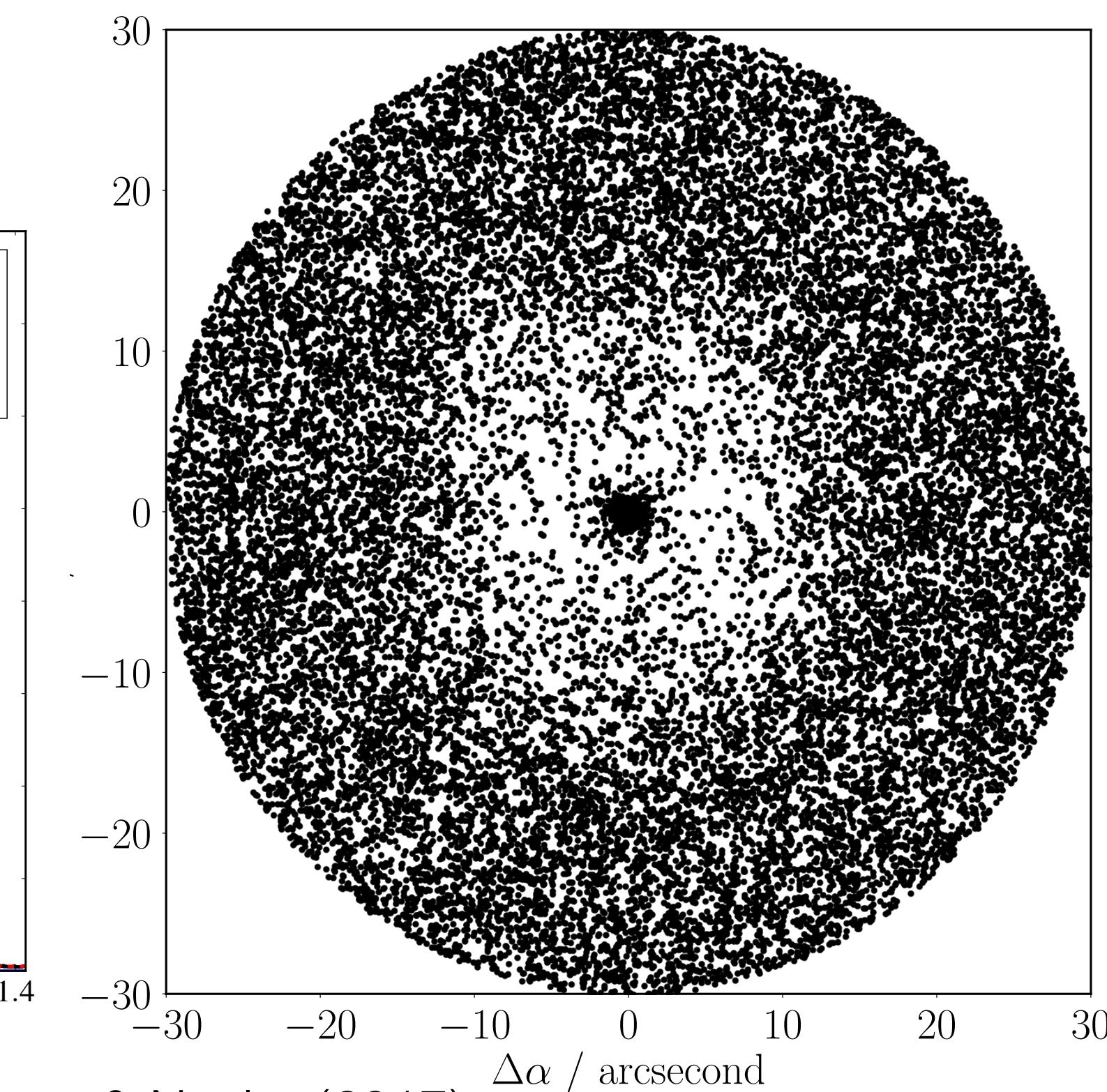
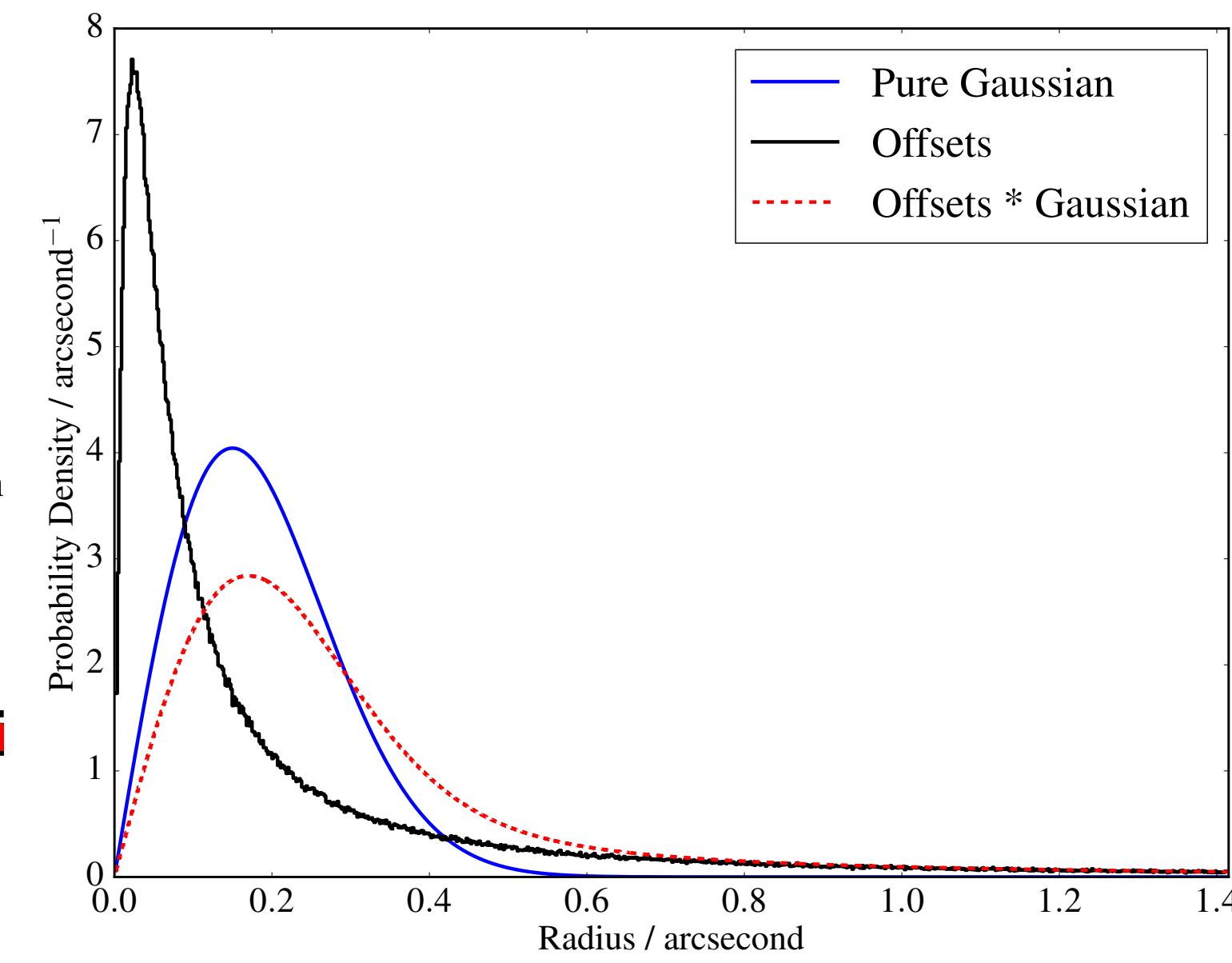
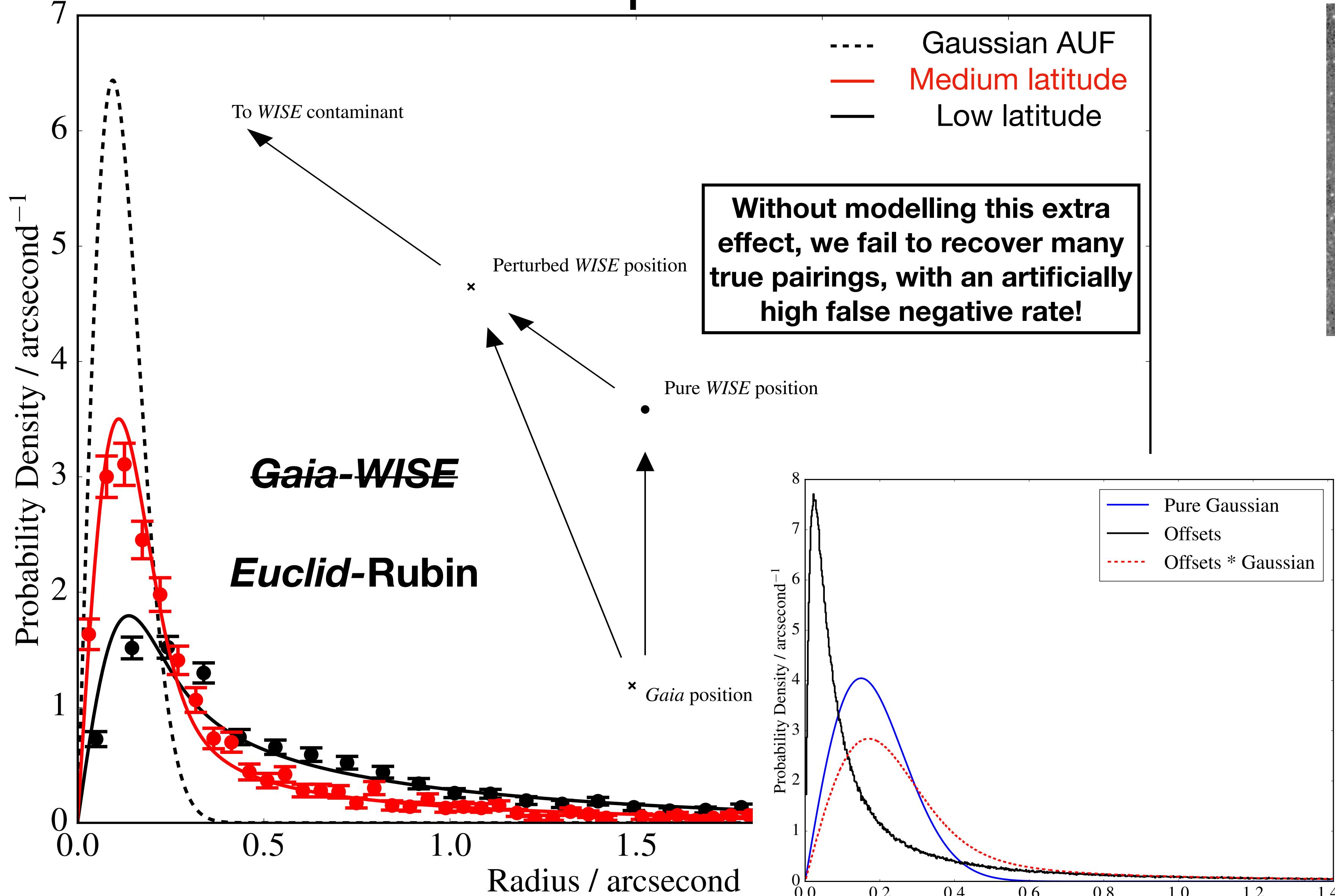
Additional Components of the AUF

(and any other systematic — e.g. proper motions, cf. Wilson 2023, RASTI)



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(and any other systematic – e.g. proper motions, cf. Wilson 2023, RASTI)



WISE - Wright et al. (2010)

Gaia DR2 - Gaia Collaboration, Brown A. G. A., et al. (2018)

Wilson & Naylor (2018b)

Wilson & Naylor (2017)

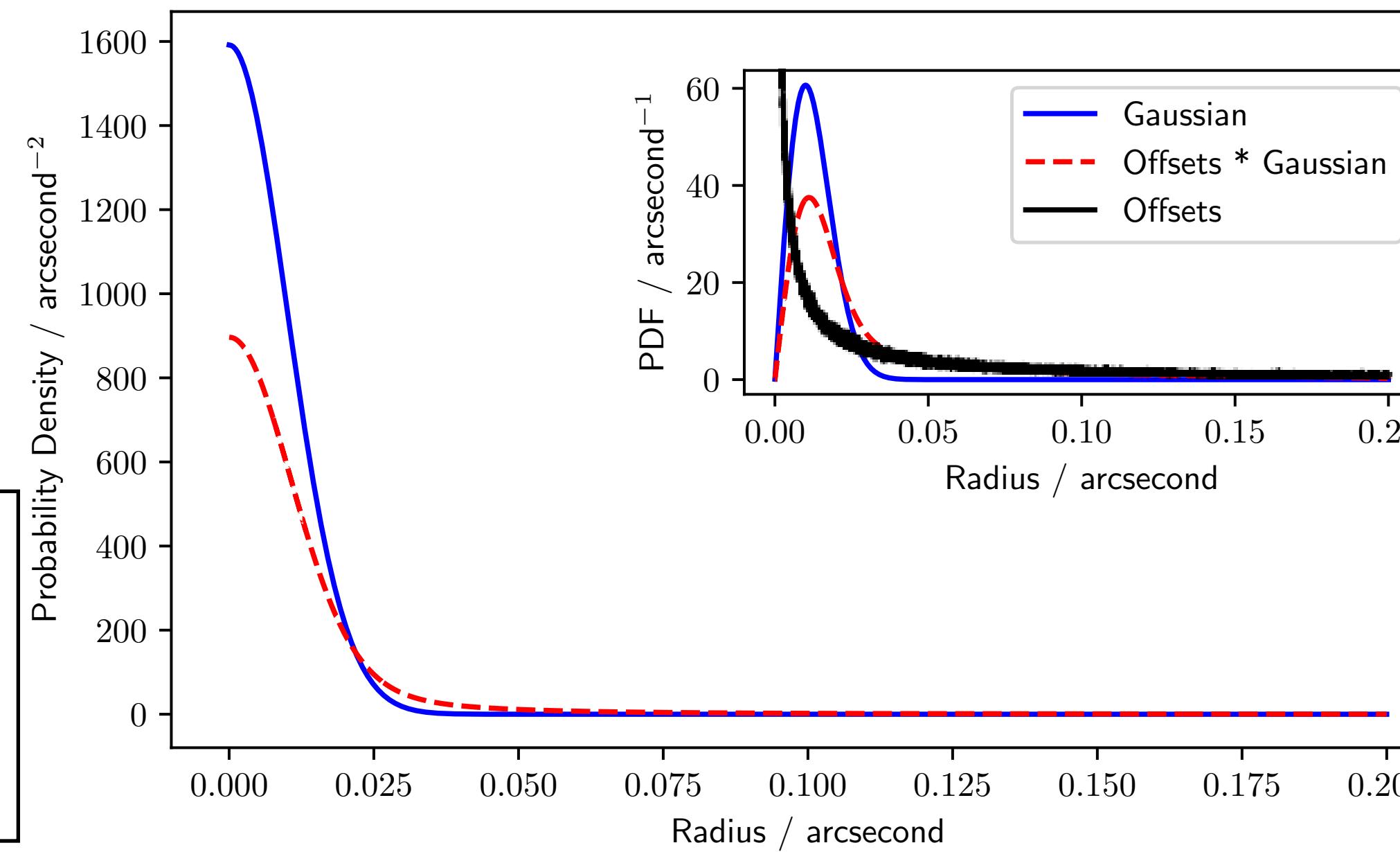
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The Rubin AUF: Galactic Plane

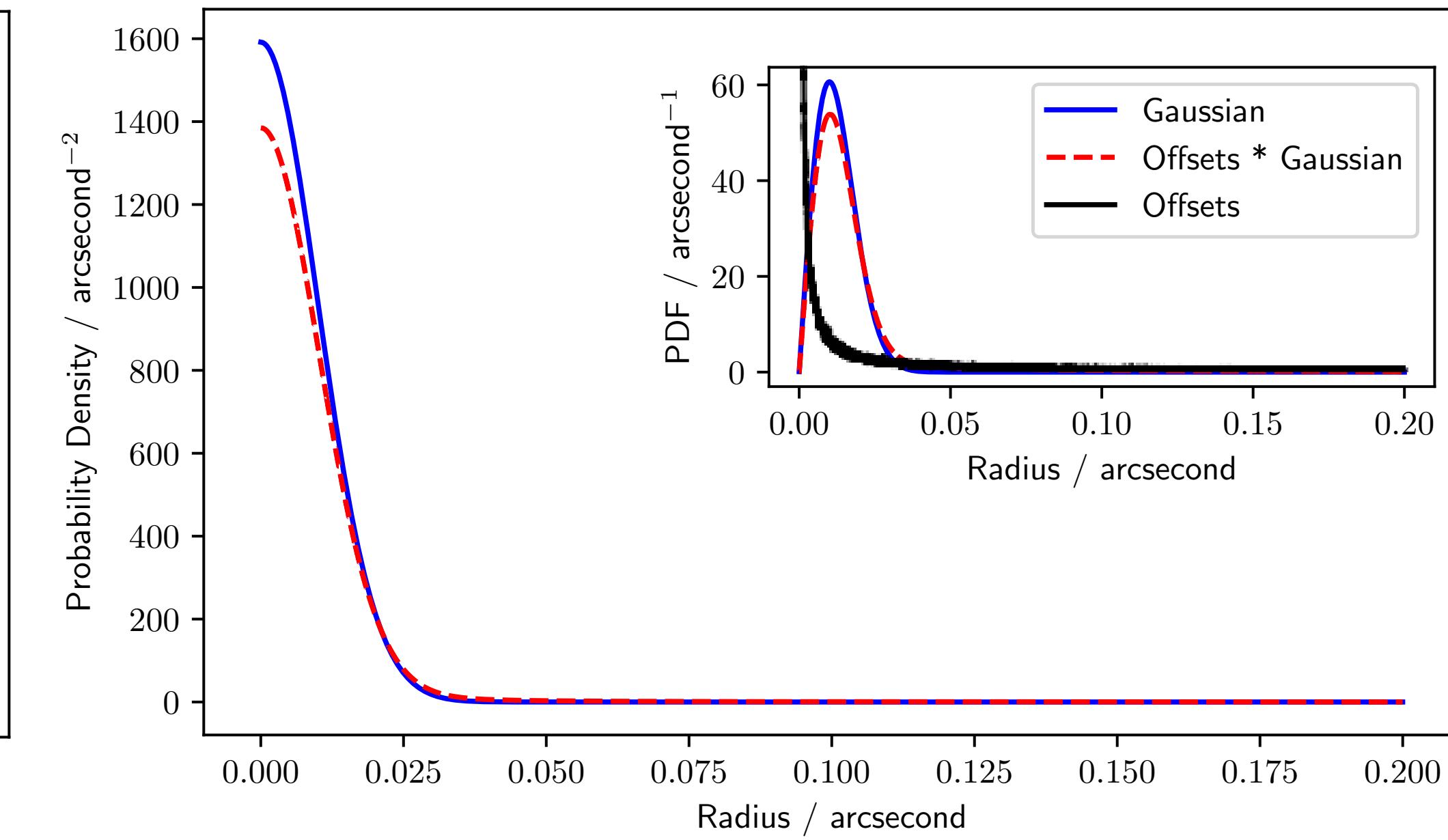
Galactic Centre

Single-visit

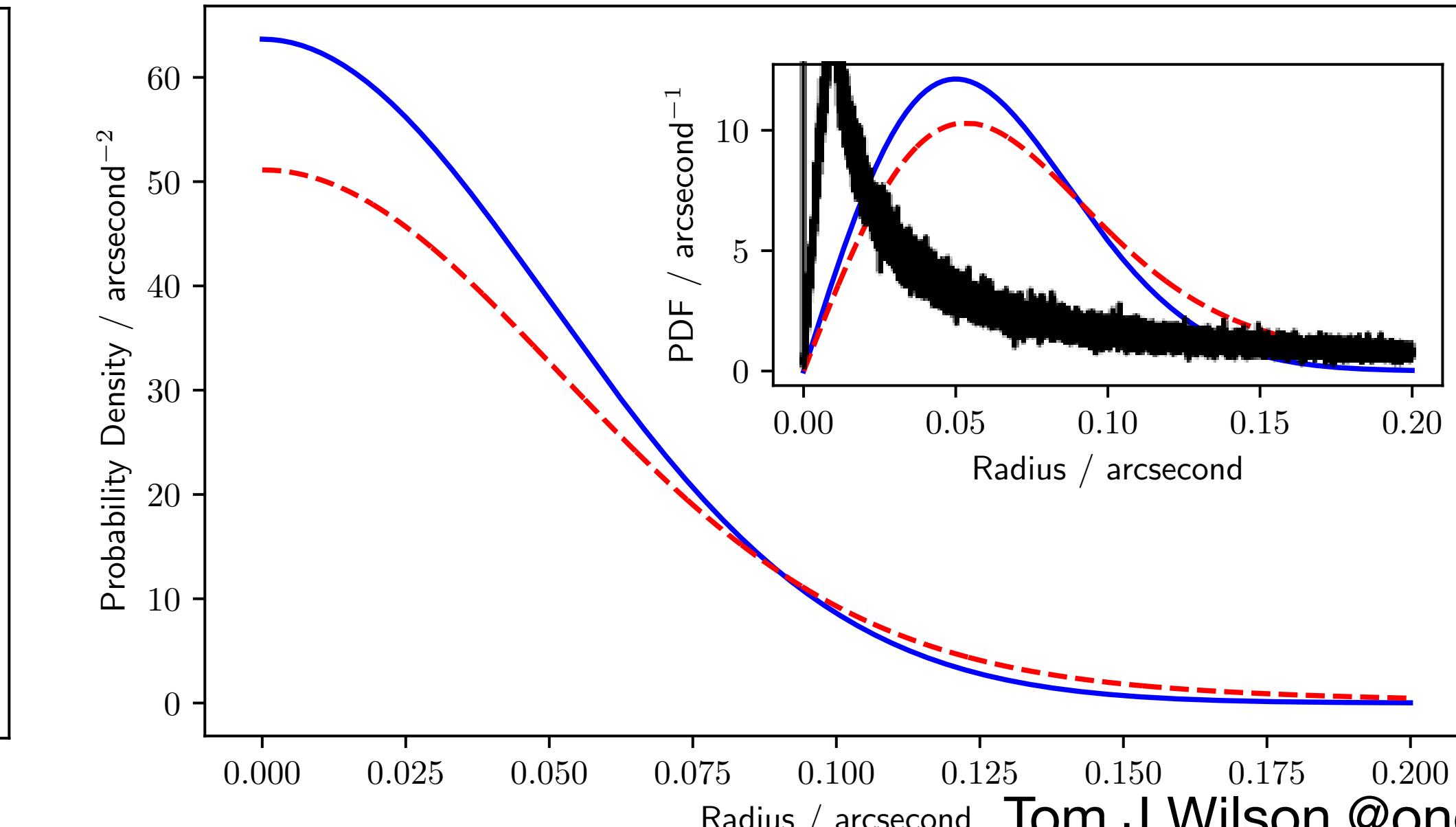
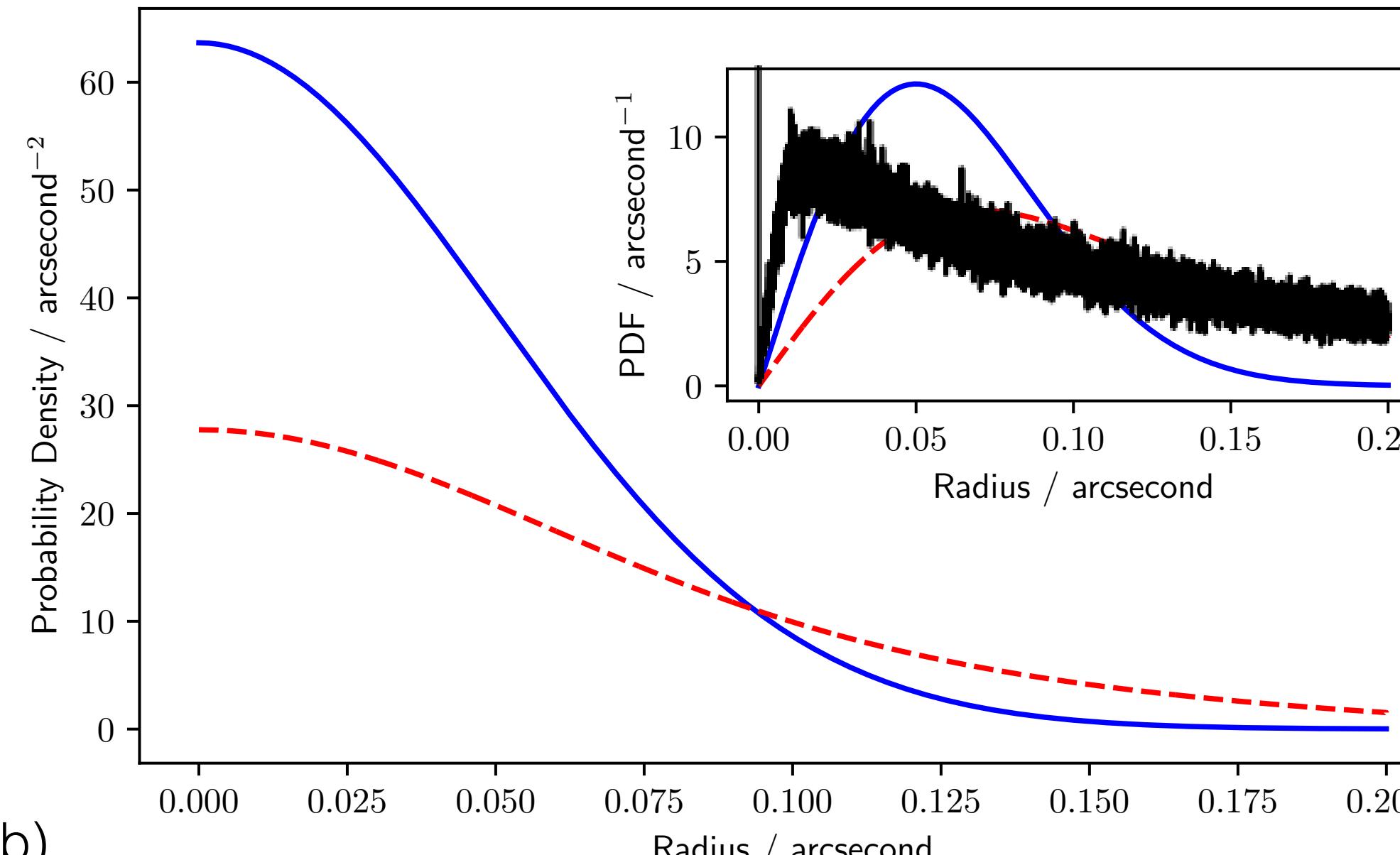
**Without modelling
this extra effect, we
fail to recover many
true pairings, with an
artificially high false
negative rate!**



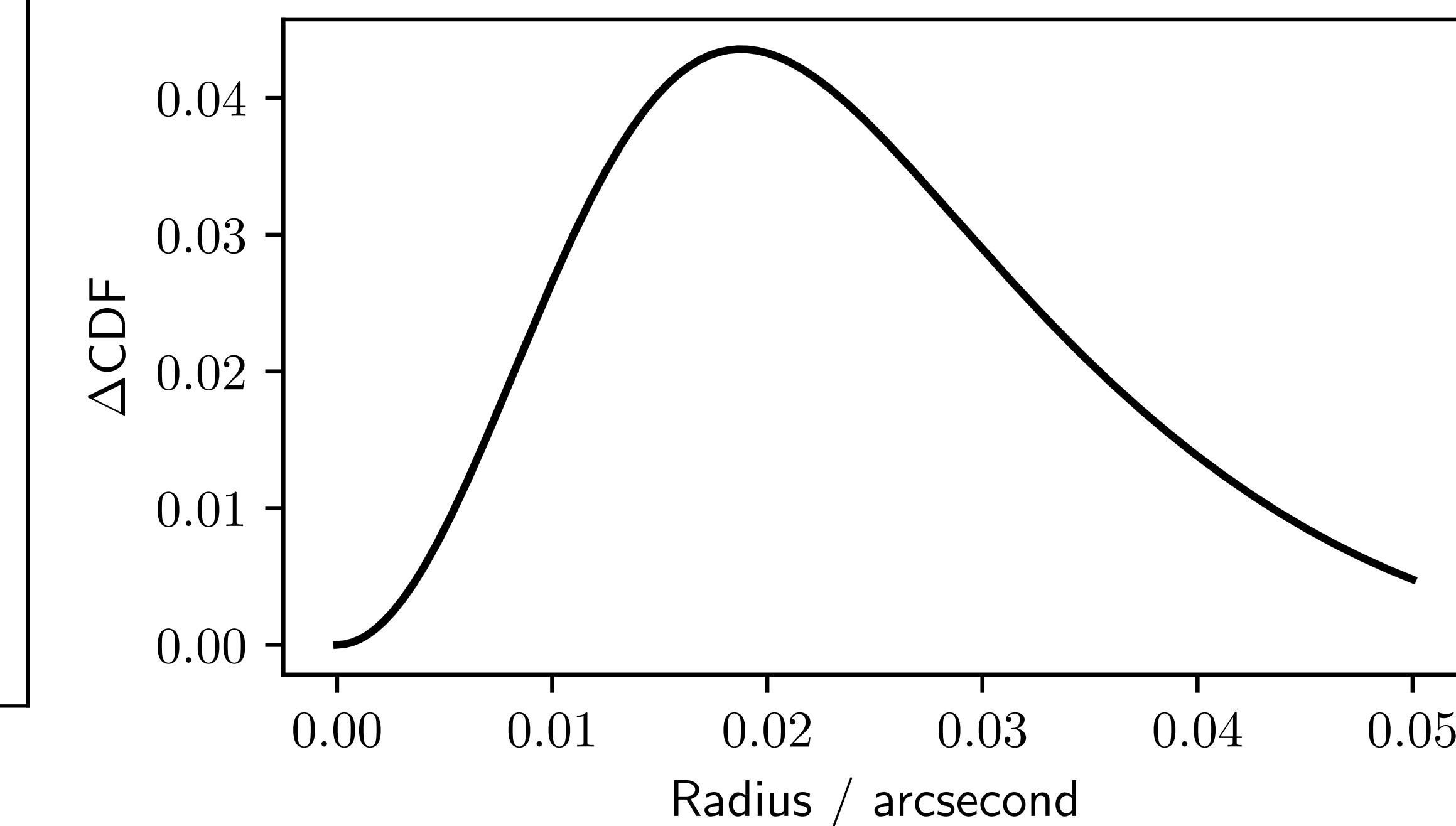
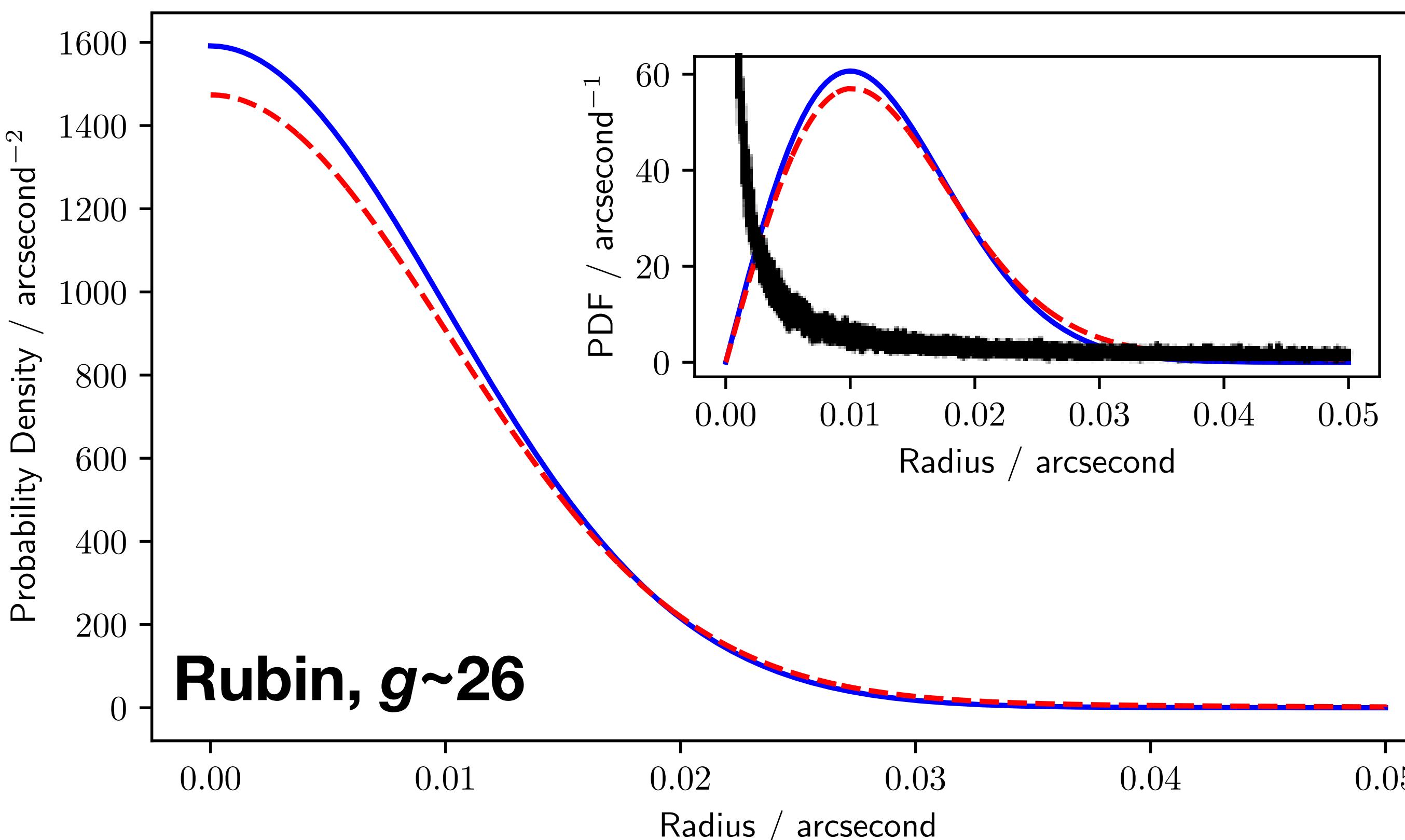
Not the Galactic Centre



Co-add

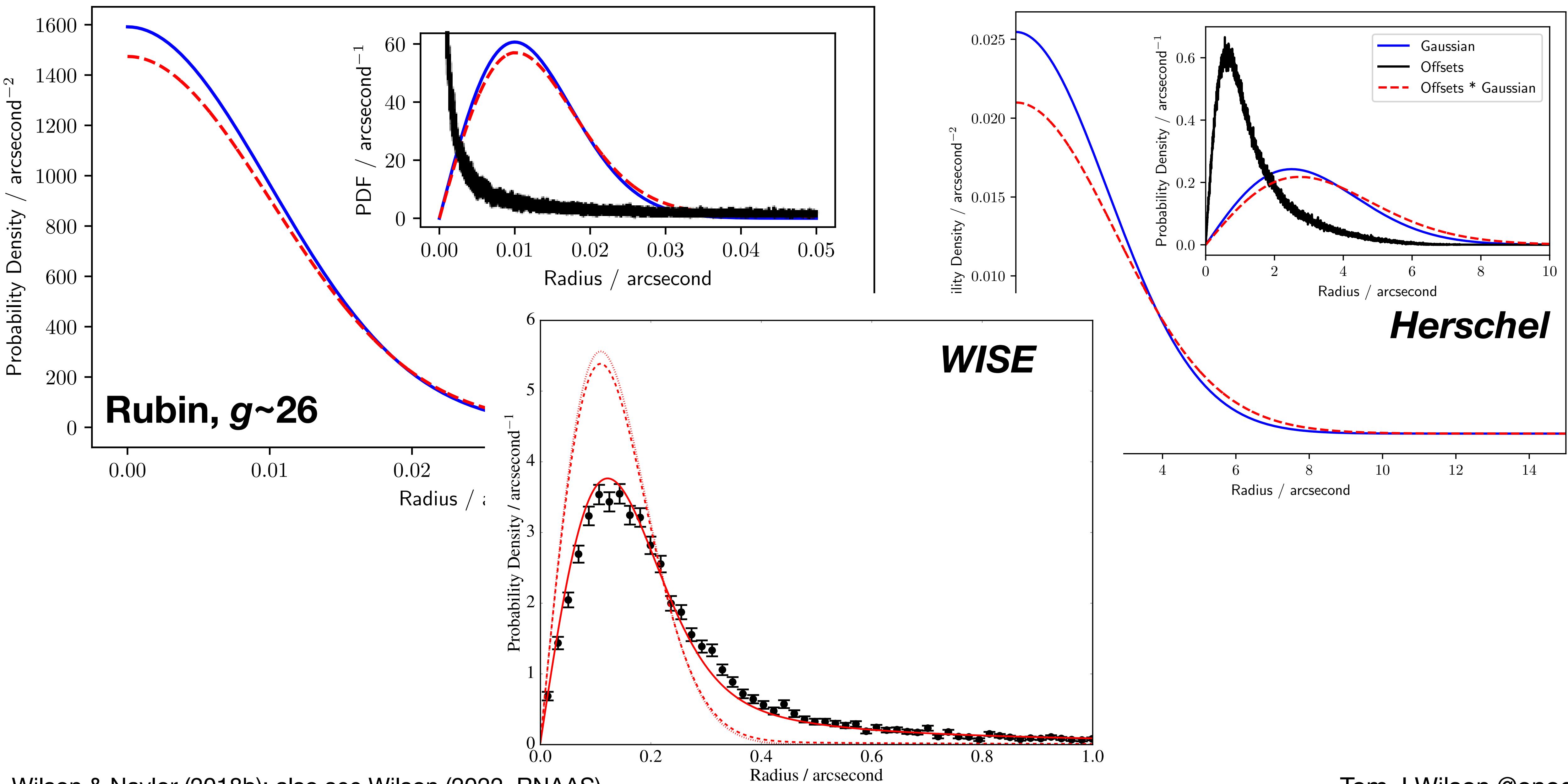


The Rubin AUF: Extra-Galactic

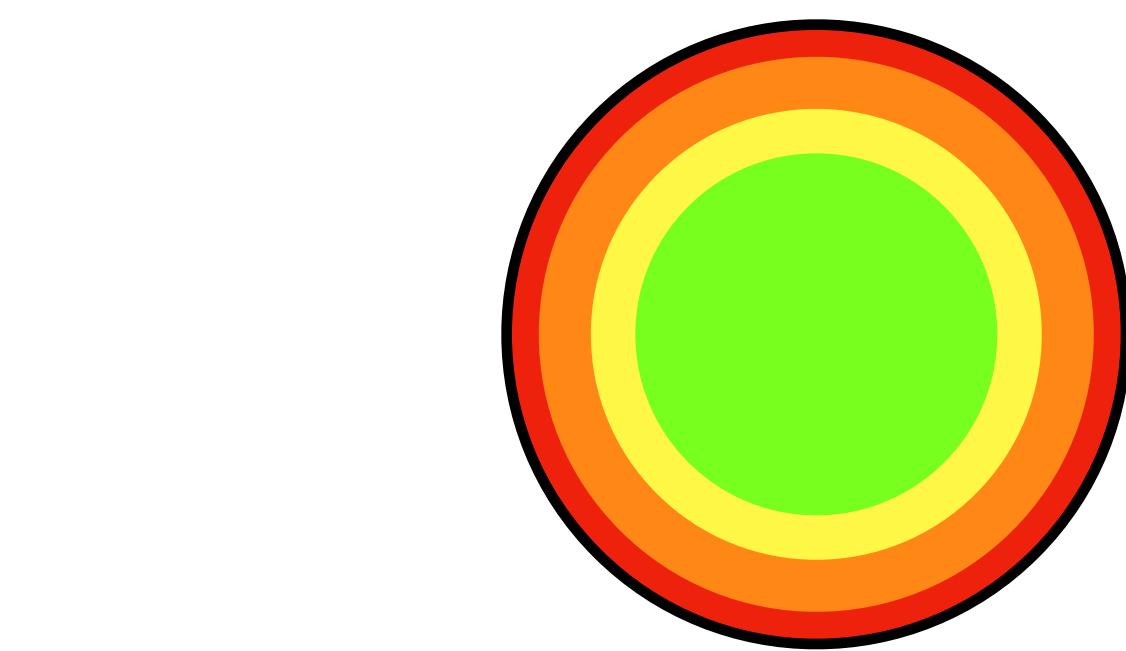
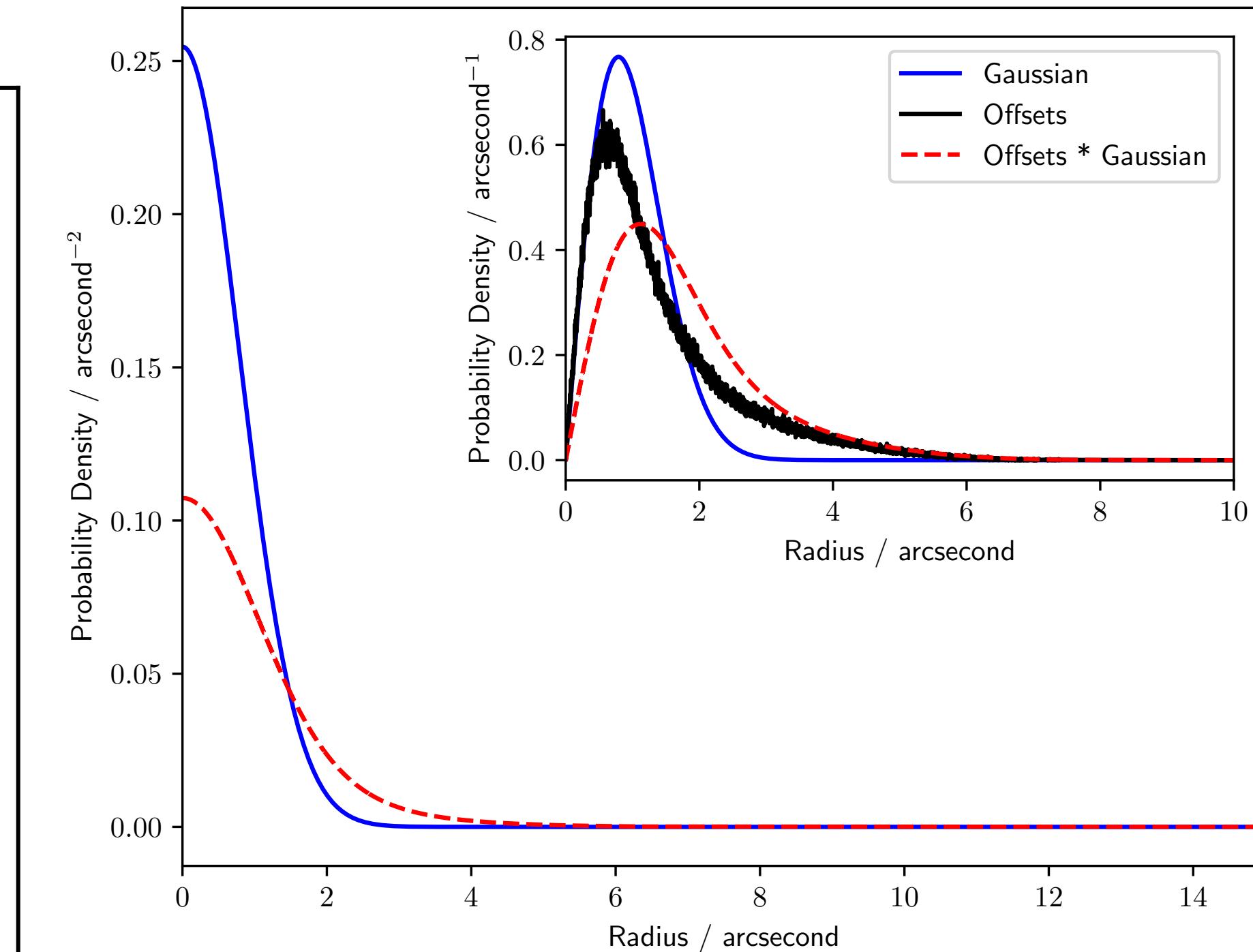
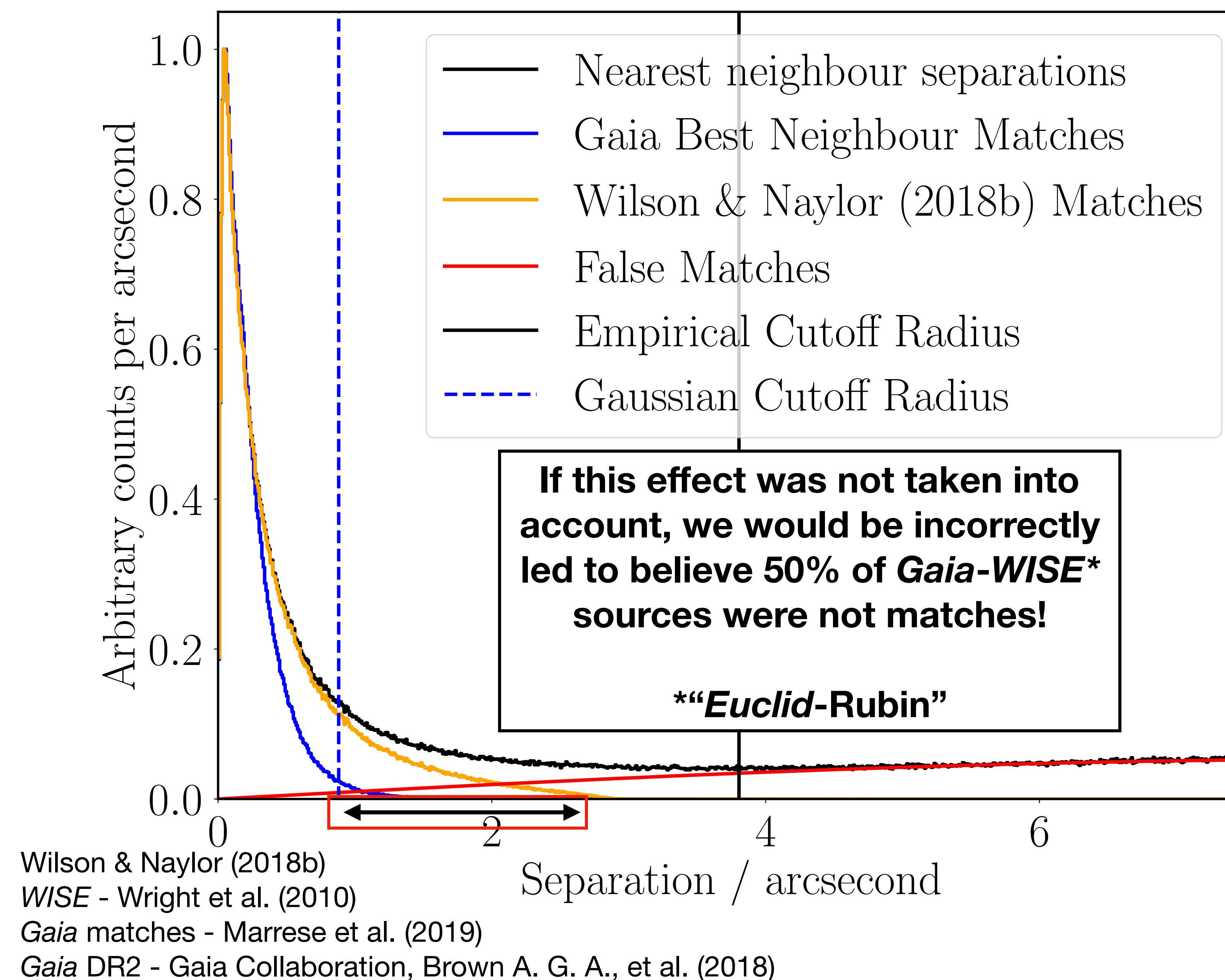


Without modelling this extra effect, we fail to recover many true pairings, with an artificially high false negative rate!

The Rubin AUF: Extra-Galactic



Match Separations

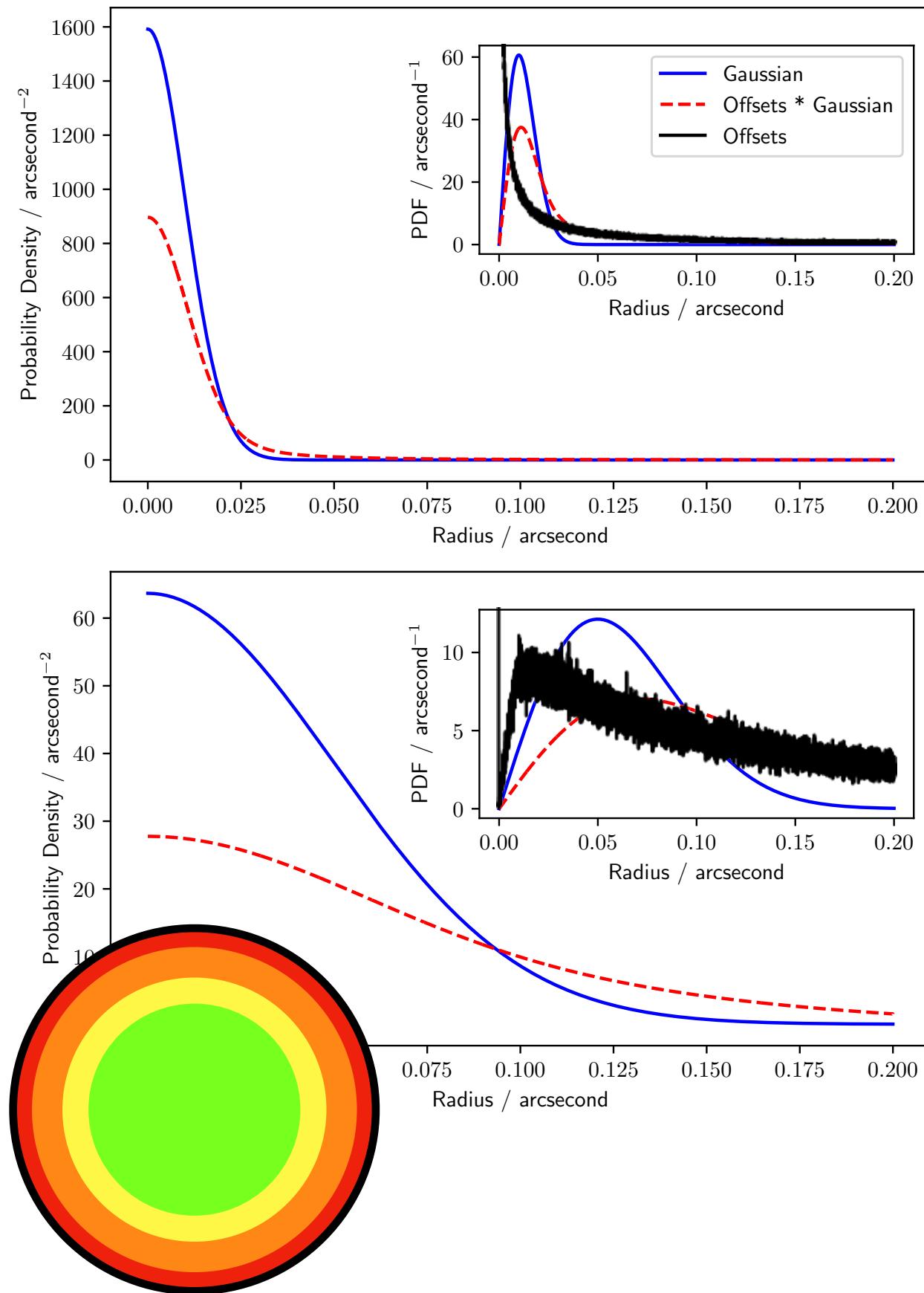


The AUF does not need to, and in fact quite often should not, be Gaussian!

Conclusions

- Our cross-match algorithms include two key elements to avoid issues with crowded & confused data
 - A generalised approach to the Astrometric Uncertainty Function allows for the full inclusion of the effects of perturbation due to blended sources – reduce false -ves!
 - Use of (two-sided) photometry to sort out multiple competing matches— reduce false +ves!
- Software package [macauff](#) developed to cross-match catalogues, including the effect of unresolved contaminant sources (and rejection of interloper objects using photometry in the static sky)
 - Developed through an IKC to Rubin/LSST:UK, matches planned to *Gaia*, *WISE*, *VISTA*, *SDSS*, ...
 - We have compute time to cross-match datasets — let me know your favourite combo, and what you need matched (to LSST or otherwise)!
- Incorporating this extension of position uncertainty into real-time matches allows for more robust counterpart identification in the alert stream and a more accurate and precise transient SED
- Furthermore, we can provide *statistical* information on the level of photometric contamination unresolved contaminant sources cause, which can be subtracted in a probabilistic framework!

Nearest-neighbour matching will not work in the era of Rubin!



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Wilson & Naylor, 2017, MNRAS, 468, 2517

Wilson & Naylor, 2018a, MNRAS, 473, 5570

Wilson & Naylor, 2018b, MNRAS, 481, 2148

Wilson, 2022, RNAAS, 6, 60

Wilson, 2023, RASTI, 2, 1

<https://github.com/macauff/macauff>



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