

Generalising the Astrometric Uncertainty Function in the Era of the Rubin Observatory's LSST

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Photometric Observations

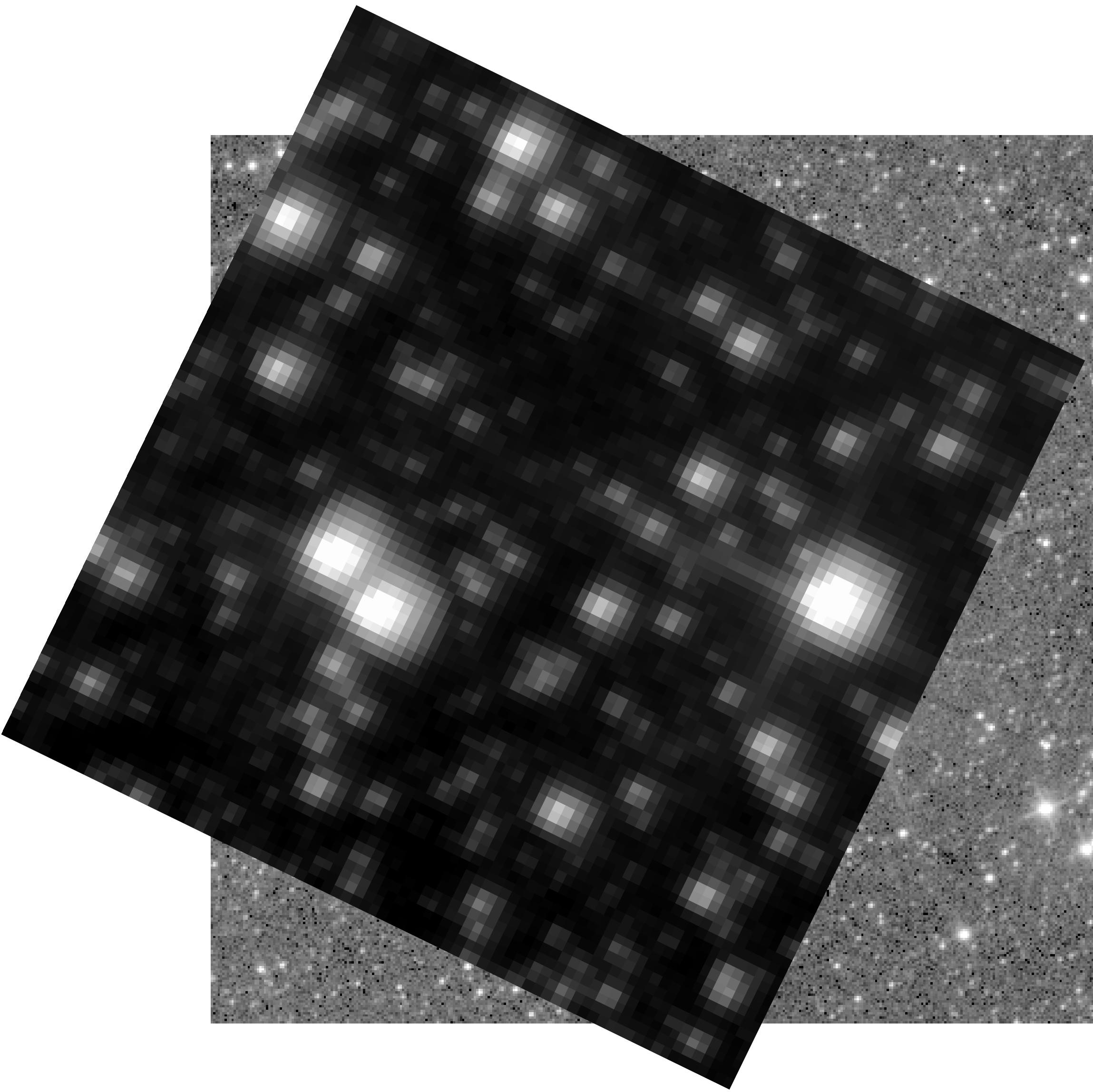


WISE - Wright et al. (2010)

WISE W1

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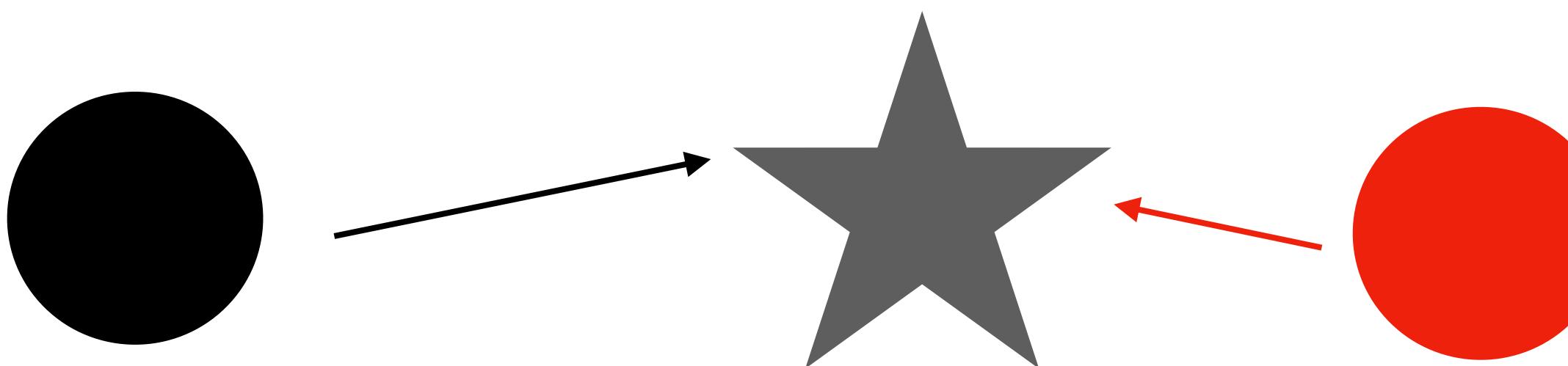
Photometric Observations



WISE - Wright et al. (2010)
TESS - Ricker et al. (2015)

TESS T
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Counterpart Assignment



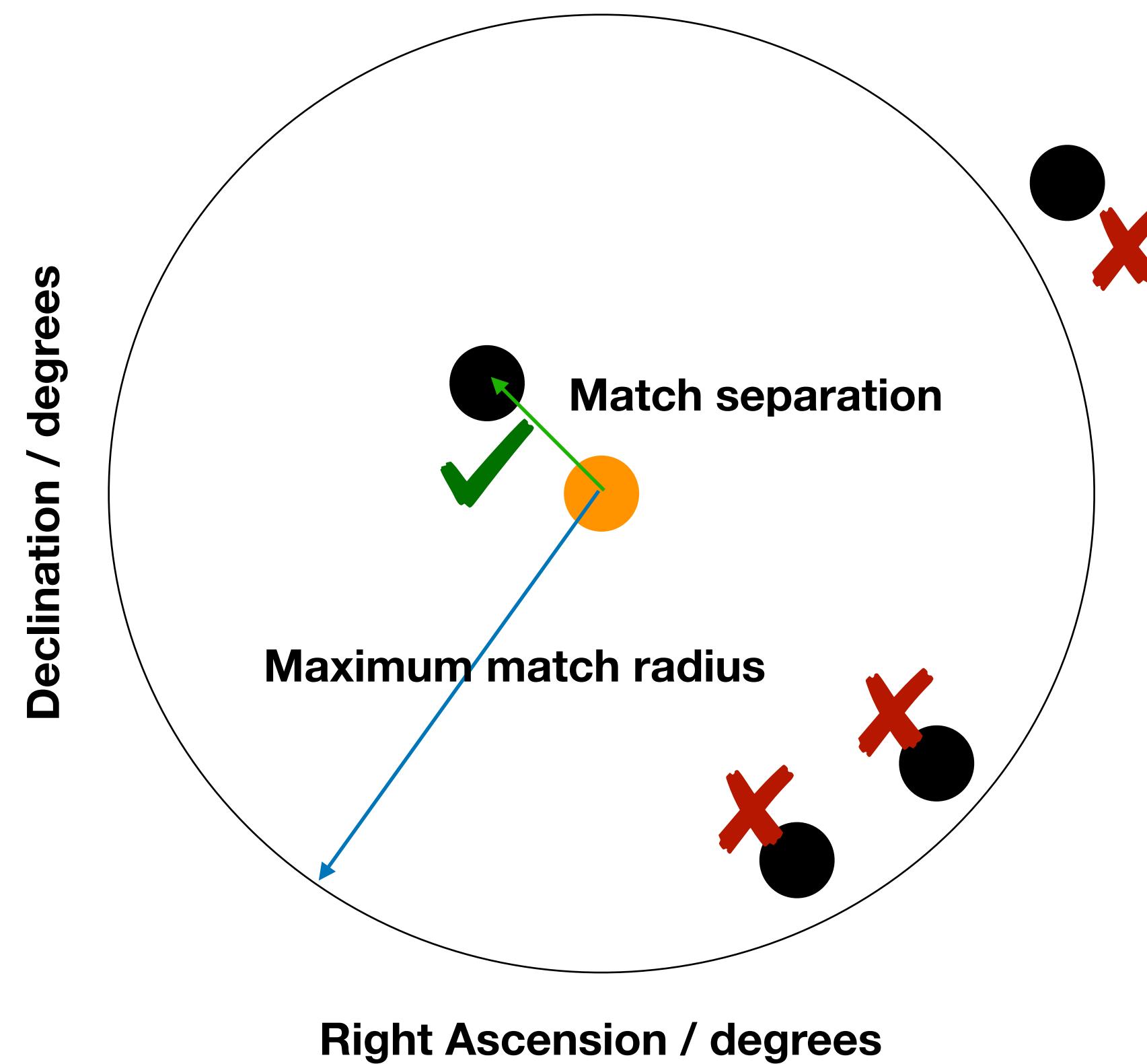
— or —



Catalogue Cross-Matching

How to assign the most likely counterparts – or decide if two sources are counterparts or not?

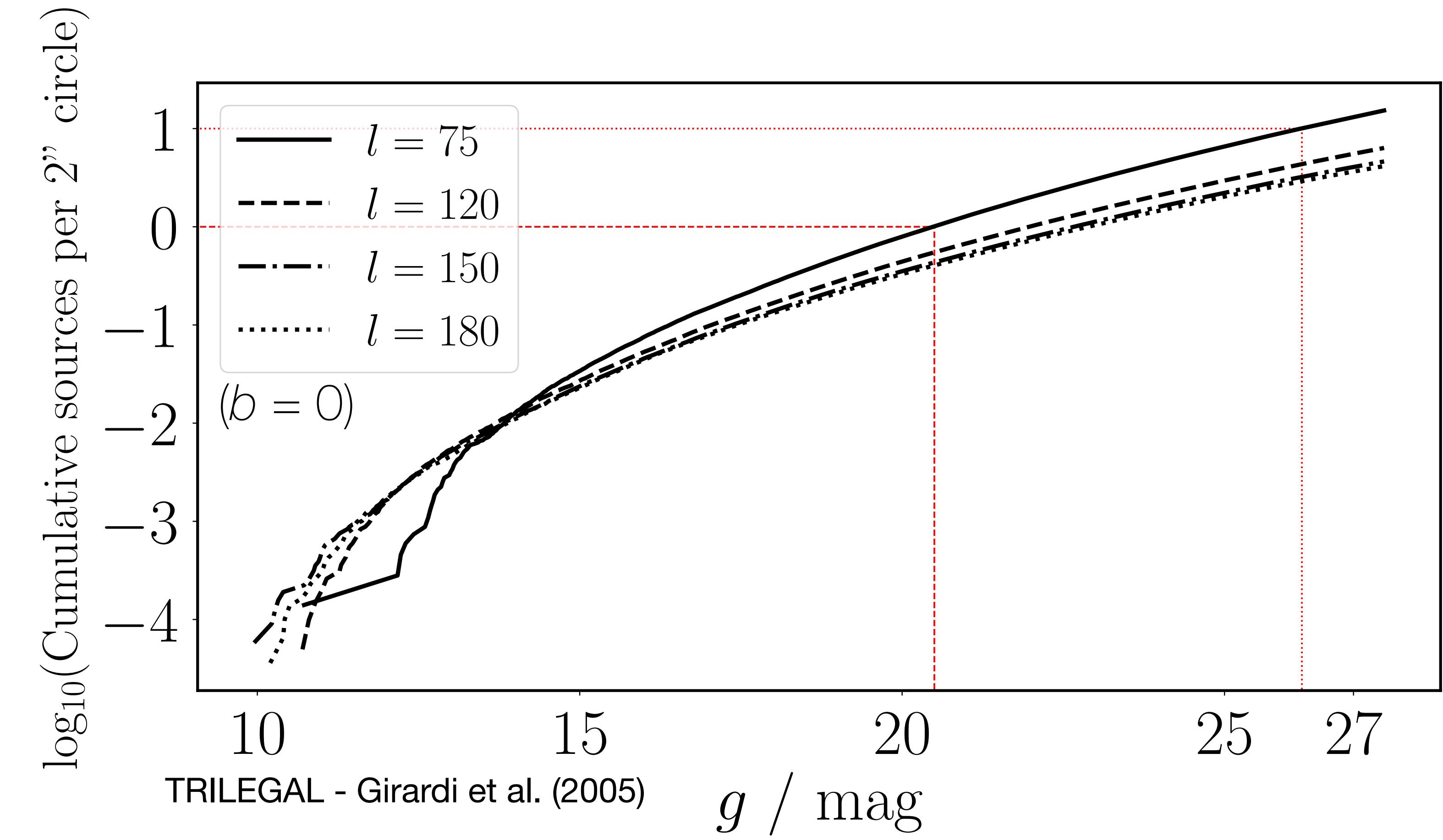
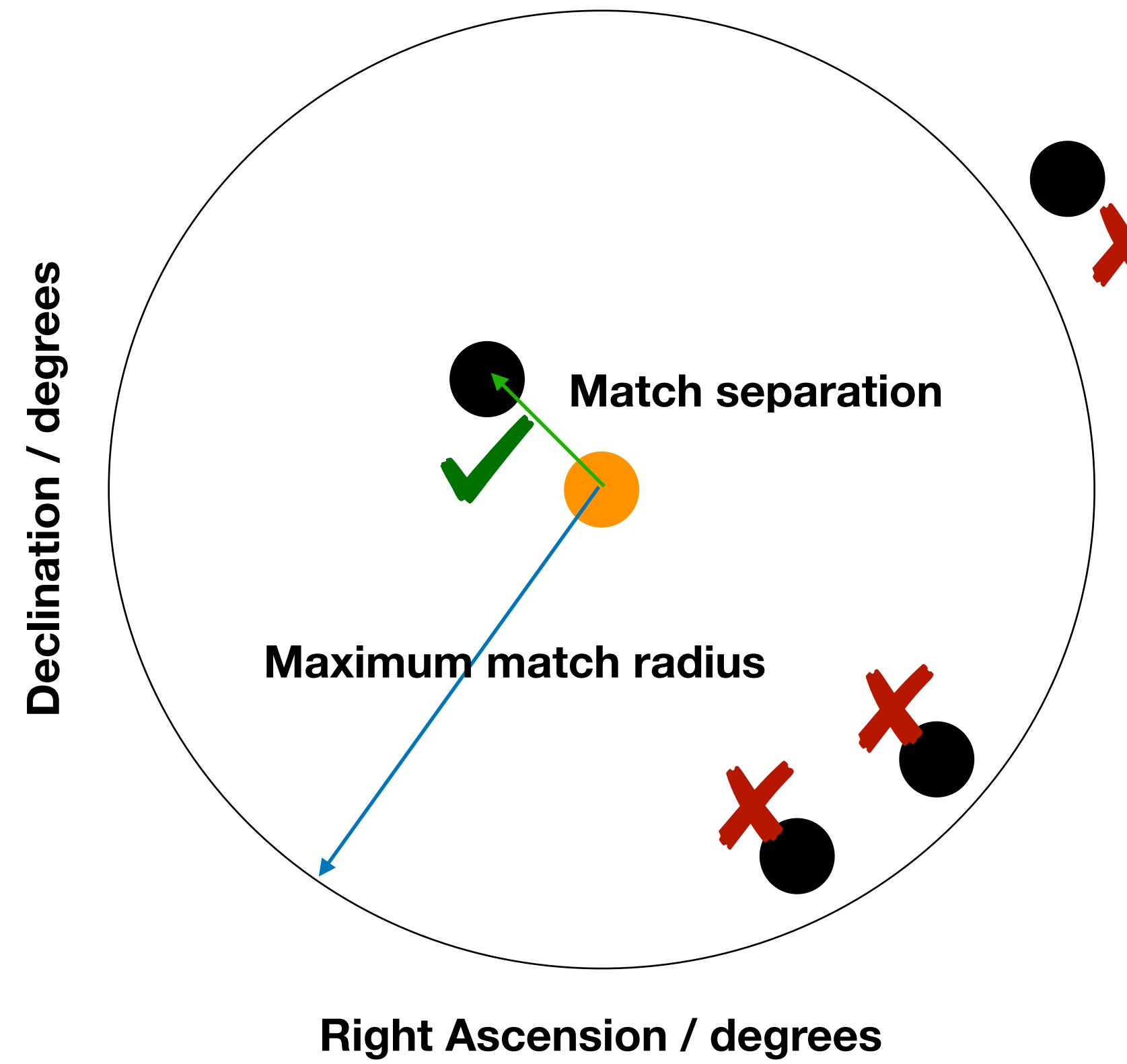
**Nearest neighbour/
proximity matching**



Catalogue Cross-Matching

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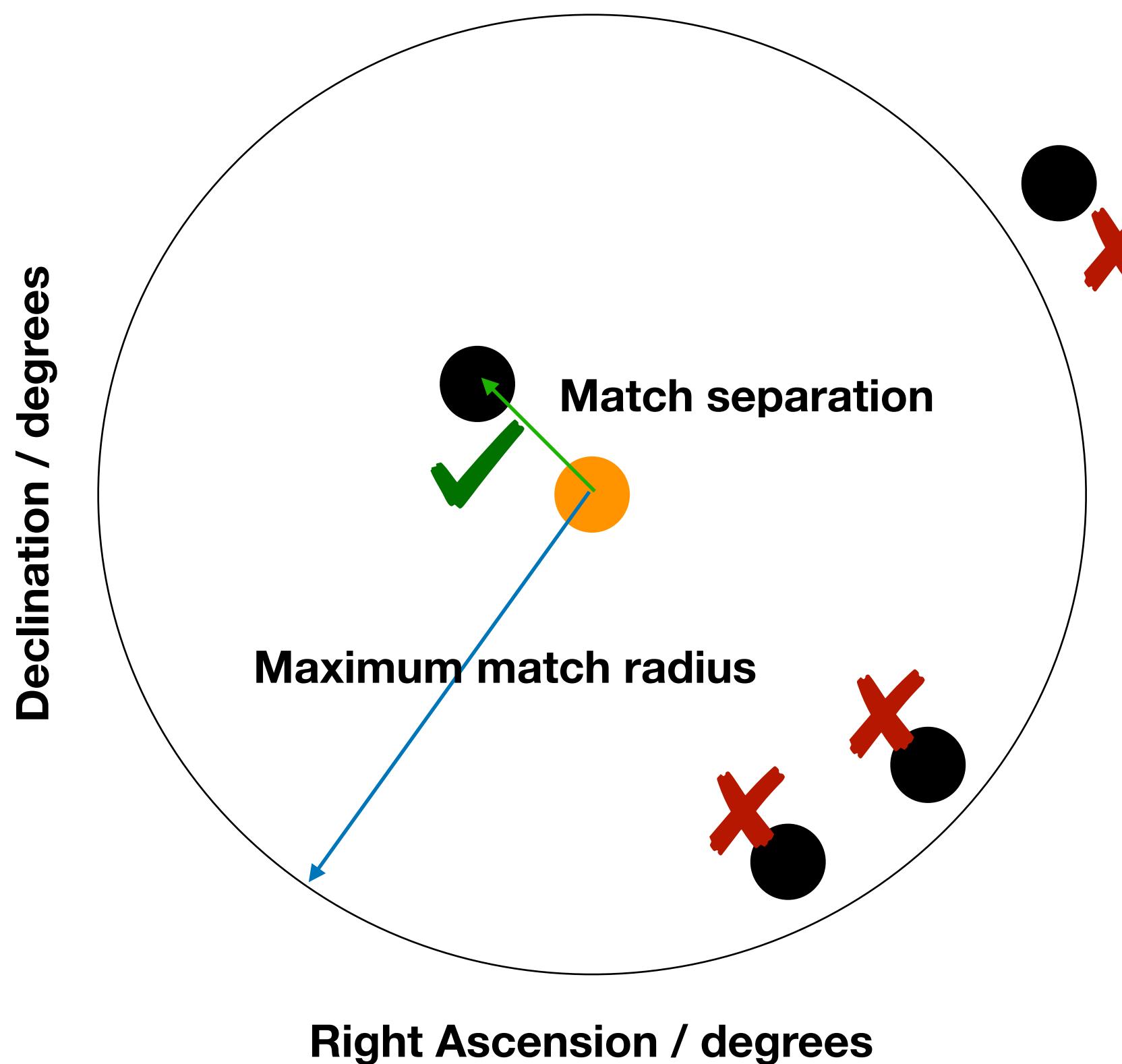
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Nearest neighbour/
proximity matching



Probabilistic matching

$$dp_{\text{id}} = Qr \exp\left(\frac{-r^2}{2}\right) dr.$$

Wolstencroft et al. (1986)

$$p(D|H) = \int p(\mathbf{m}|H) \prod_{i=1}^n p_i(x_i|\mathbf{m}, H) d^3m$$

Budavári & Szalay (2008)

$$dp(r|c) = 2\lambda r \times e^{-\lambda r^2} dr$$

de Ruiter, Willis, & Arp (1977)

$$R_j = \frac{L_j}{\sum_i L_i + (1 - Q)} \quad L = \frac{q(m, c) f(x, y)}{n(m, c)}$$

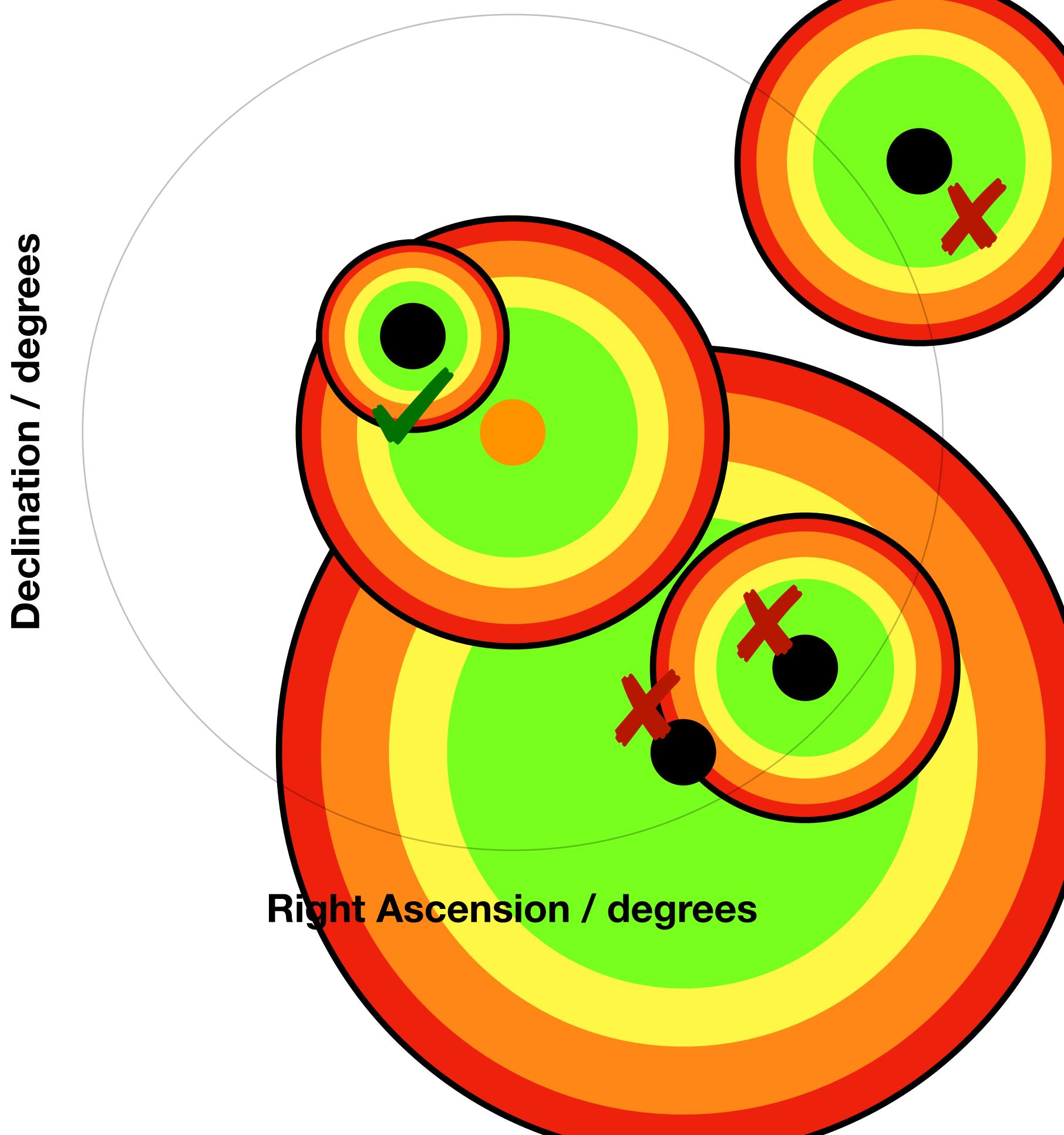
Sutherland & Saunders (1992)

$$P(i) = \frac{\frac{Xc(m_i) g(\Delta x_i, \Delta y_i)}{Nf(m_i)}}{1 - X + \sum_j \frac{Xc(m_j) g(\Delta x_j, \Delta y_j)}{Nf(m_j)}}$$

Naylor, Broos, & Feigelson (2013)

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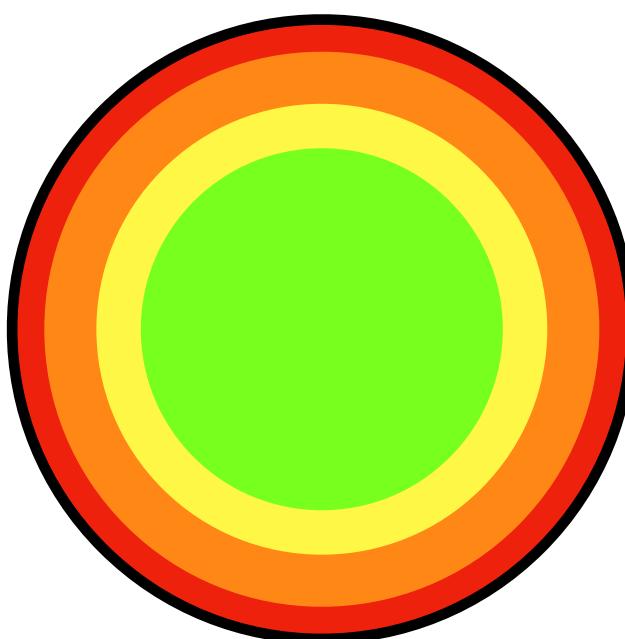
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Budavári & Szalay (2008)

One assumption made in all of these works: positional errors of sources are Gaussian!



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Sutherland & Saunders (1992)

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Separation Likelihood Function

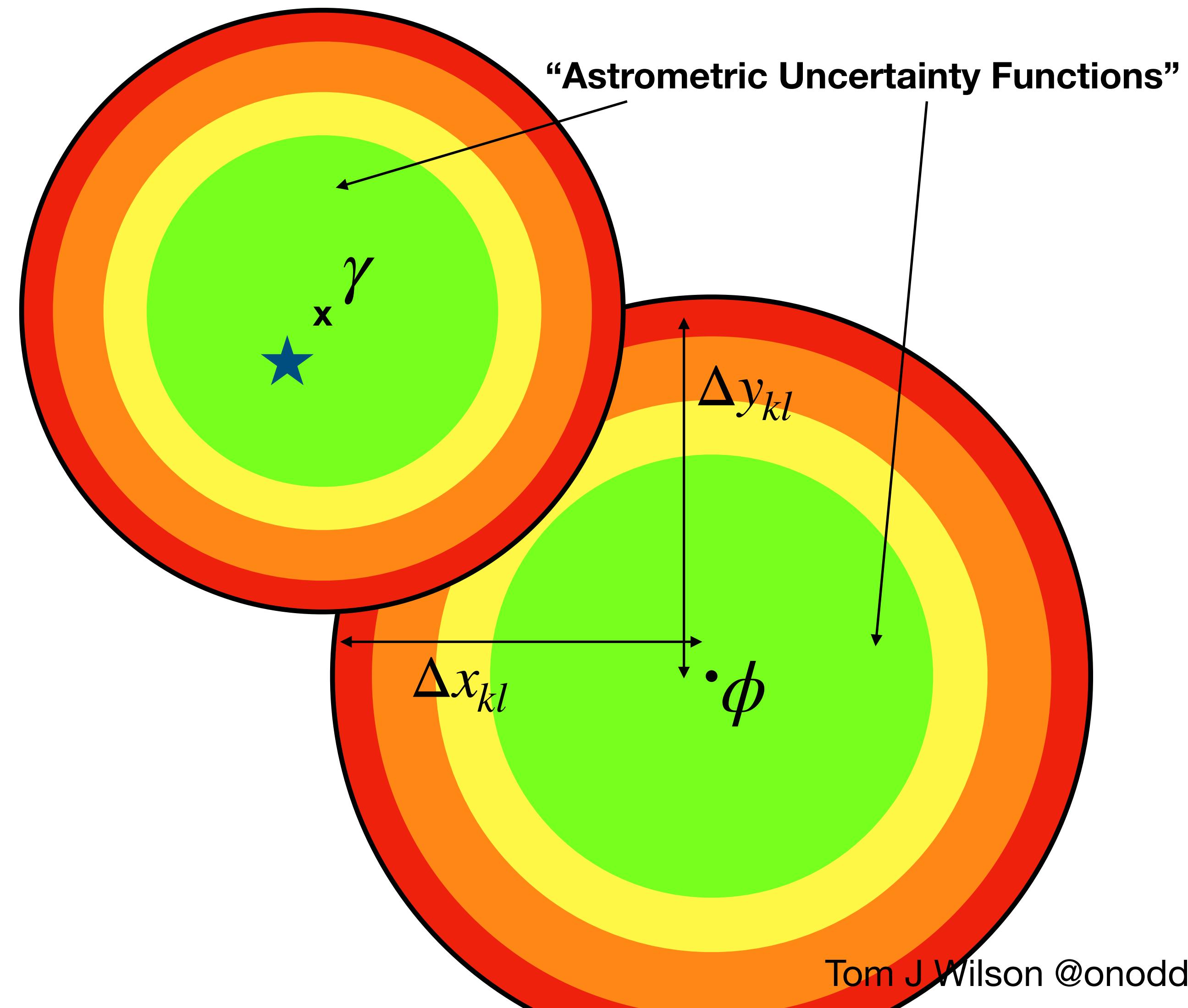
$$g(x_k, y_k, x_l, y_l) = \iint_{-\infty}^{+\infty} h_\gamma(x_0 - x_k, y_0 - y_k) h_\phi(x_l - x_0, y_l - y_0) p(x_0, y_0) dx_0 dy_0$$

Wilson & Naylor (2018a)

$$= N_c \times (h_\gamma * h_\phi)(\Delta x_{kl}, \Delta y_{kl})$$

$$g(\Delta x, \Delta y, \sigma) \propto (2\pi\sigma^2)^{-1} \exp\left(-\frac{1}{2} \frac{\Delta x^2 + \Delta y^2}{\sigma^2}\right) \text{ where } \sigma^2 = \sigma_1^2 + \sigma_2^2$$

Convolution



Separation Likelihood Function

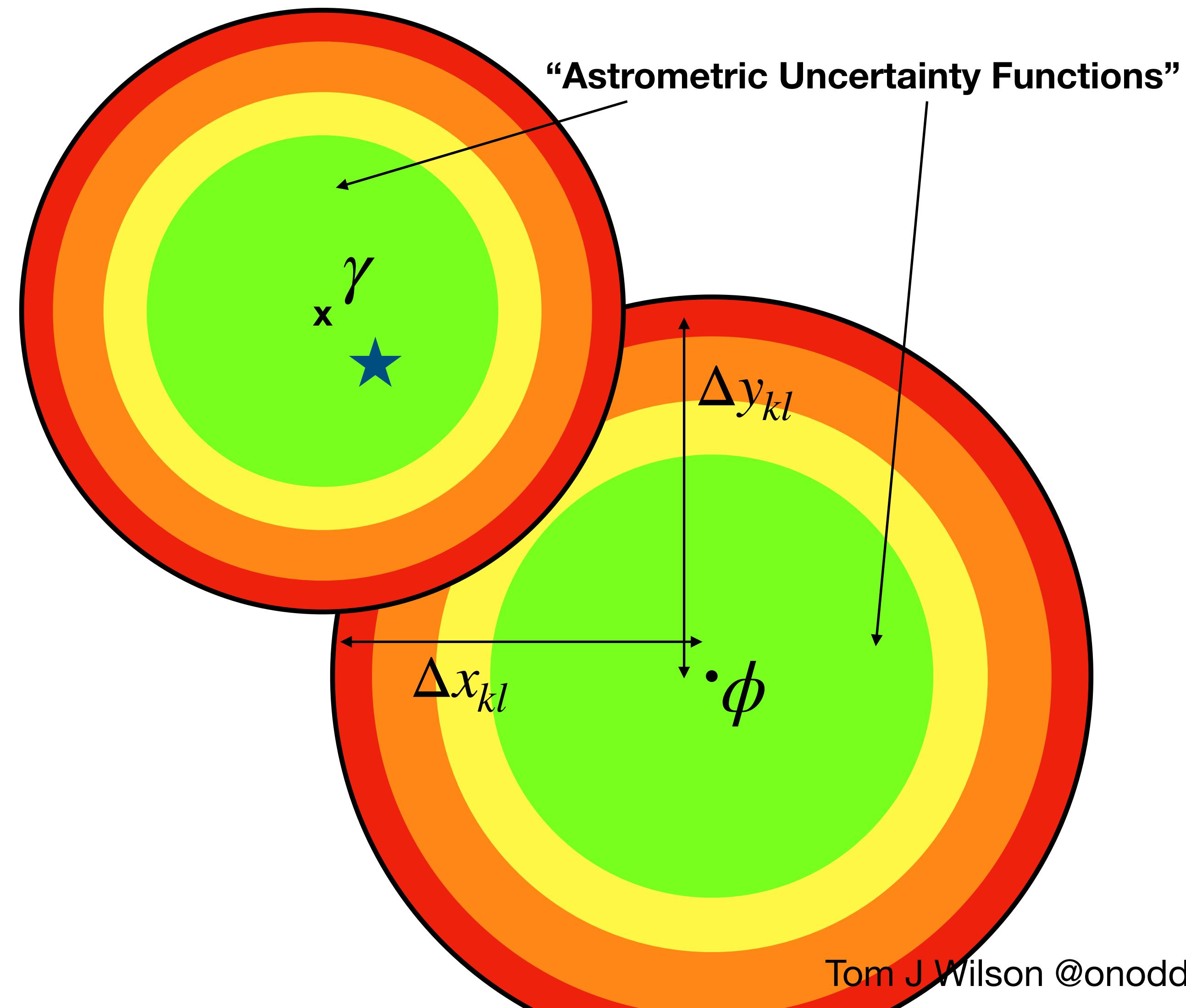
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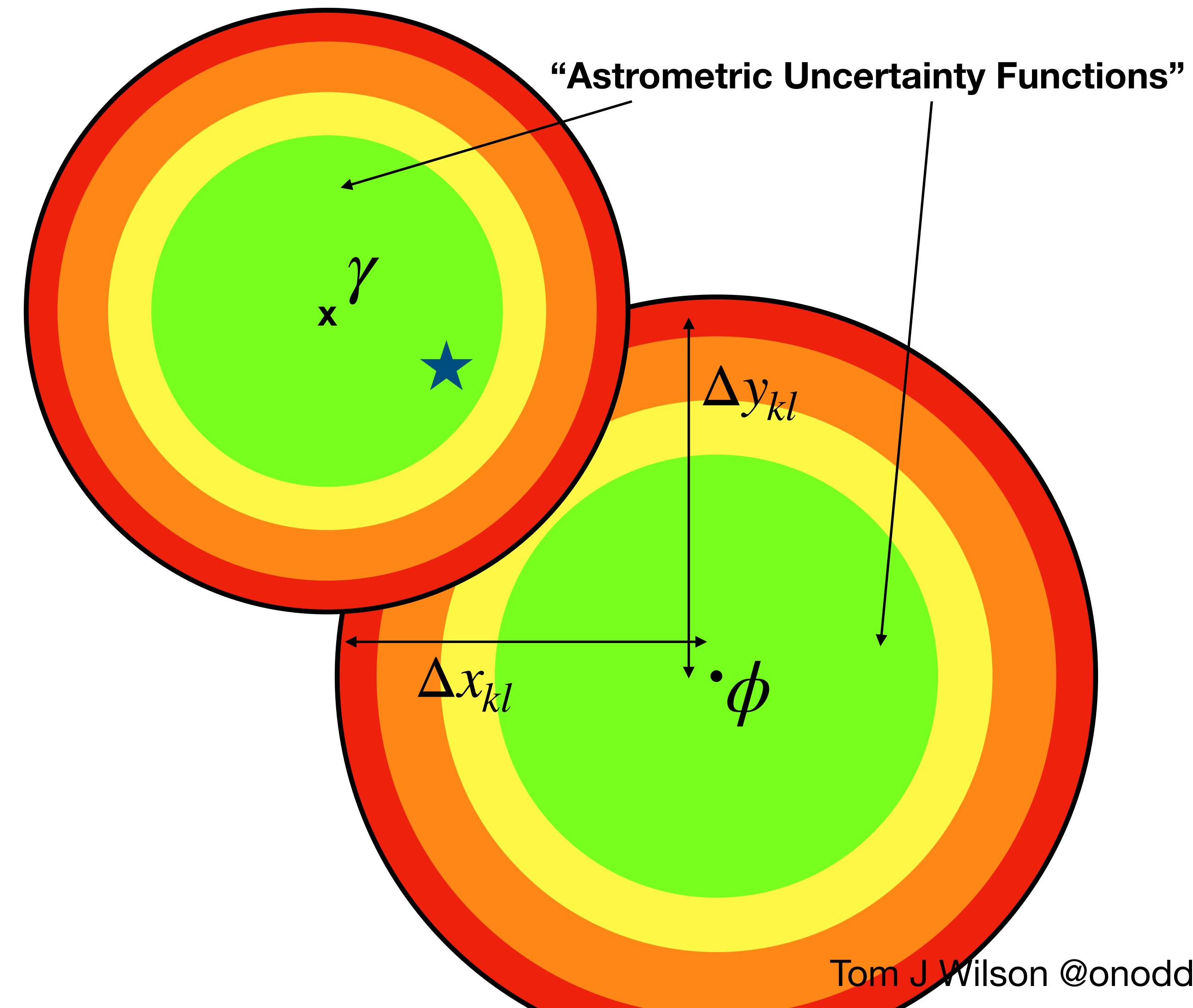
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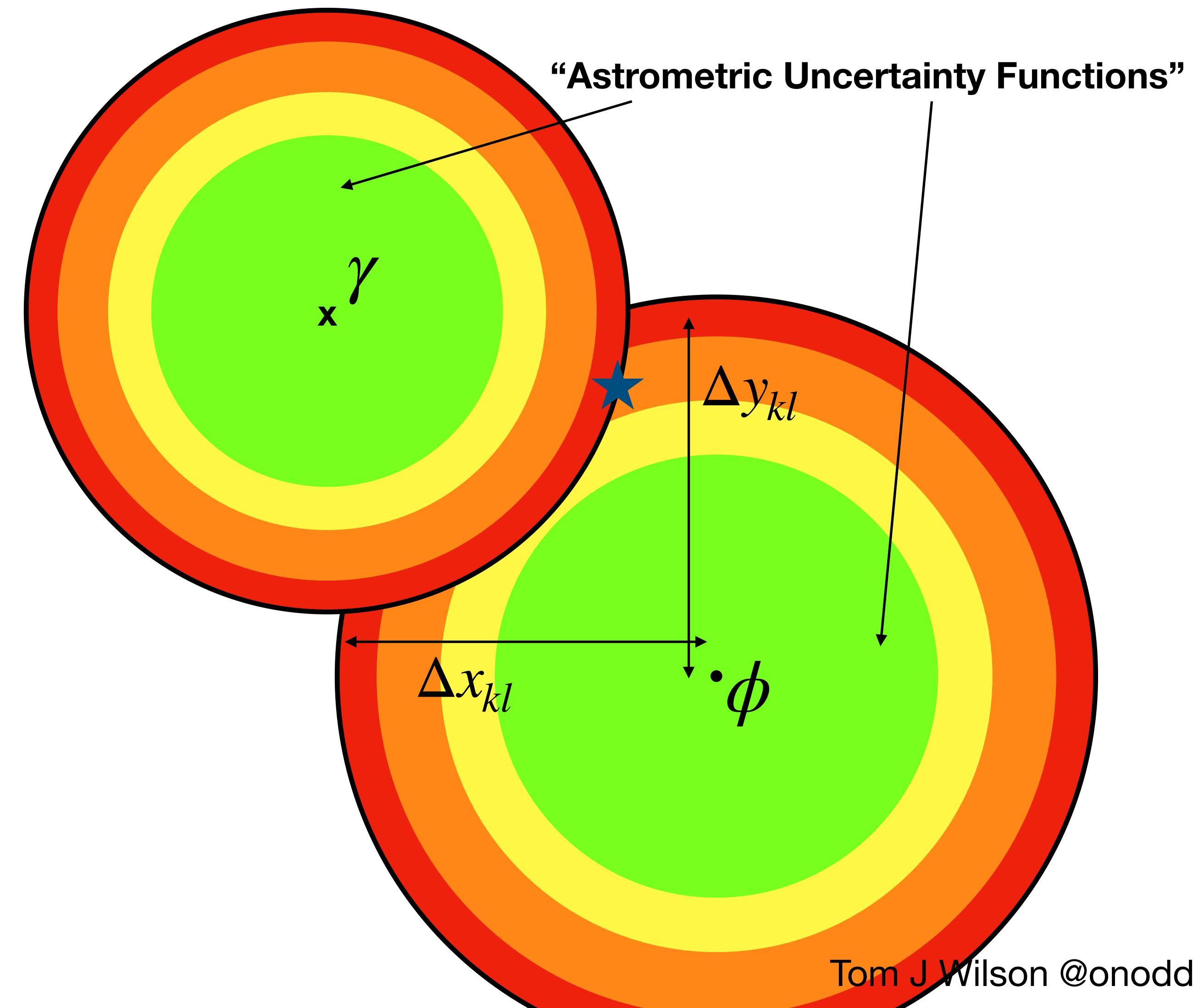
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Wilson & Naylor (2018a)

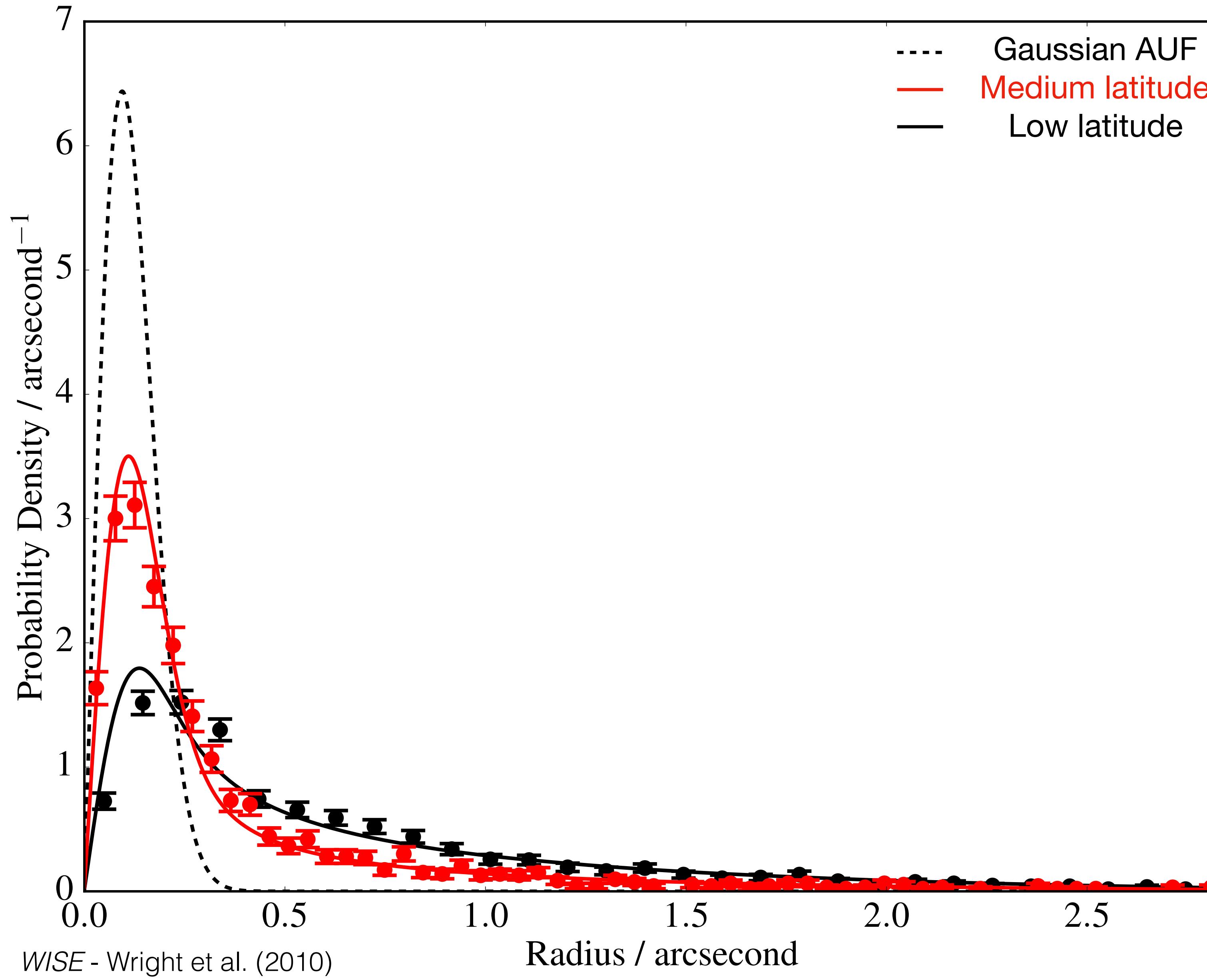
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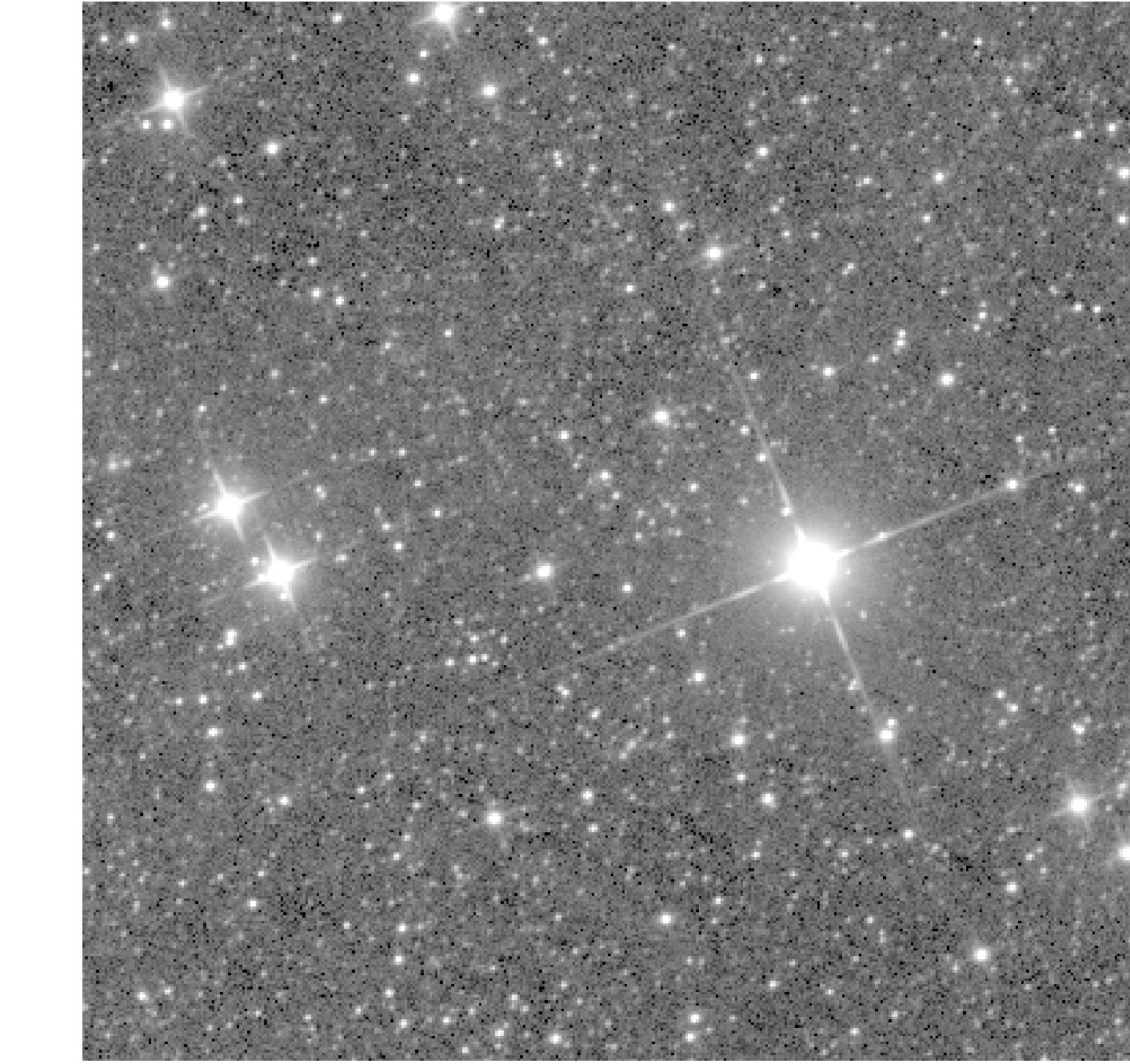
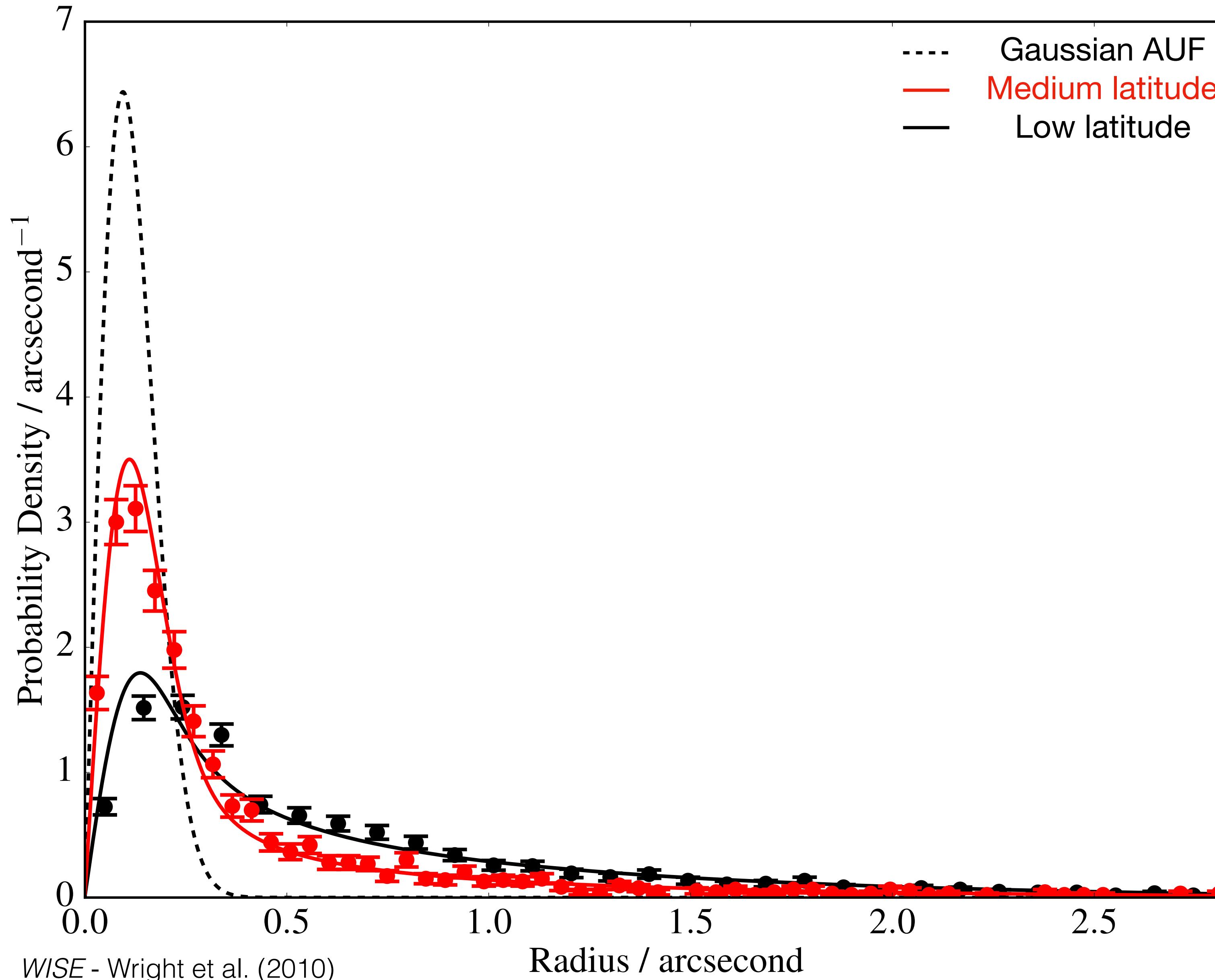
Convolution



Additional Components of the AUF

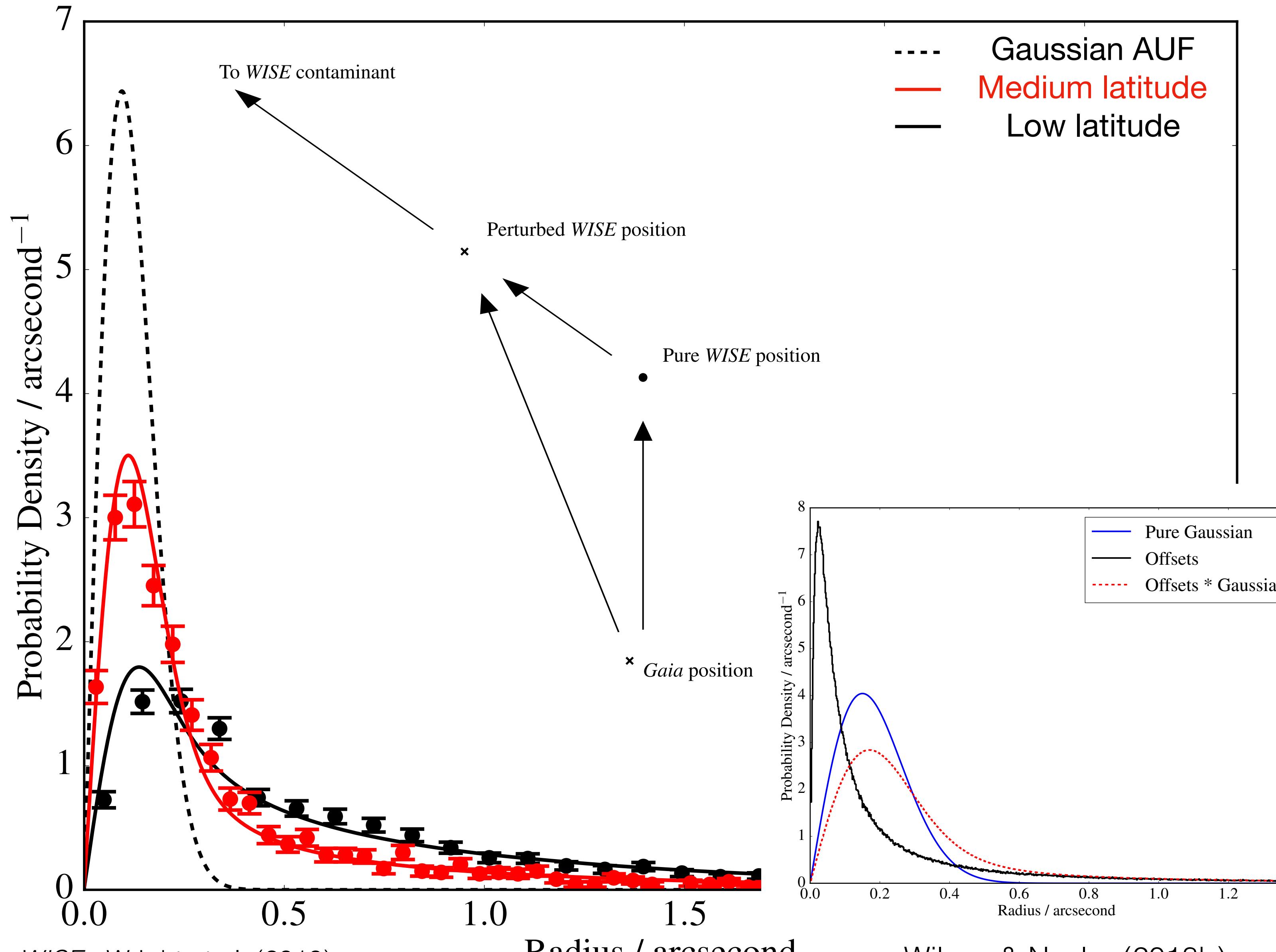


Additional Components of the AUF

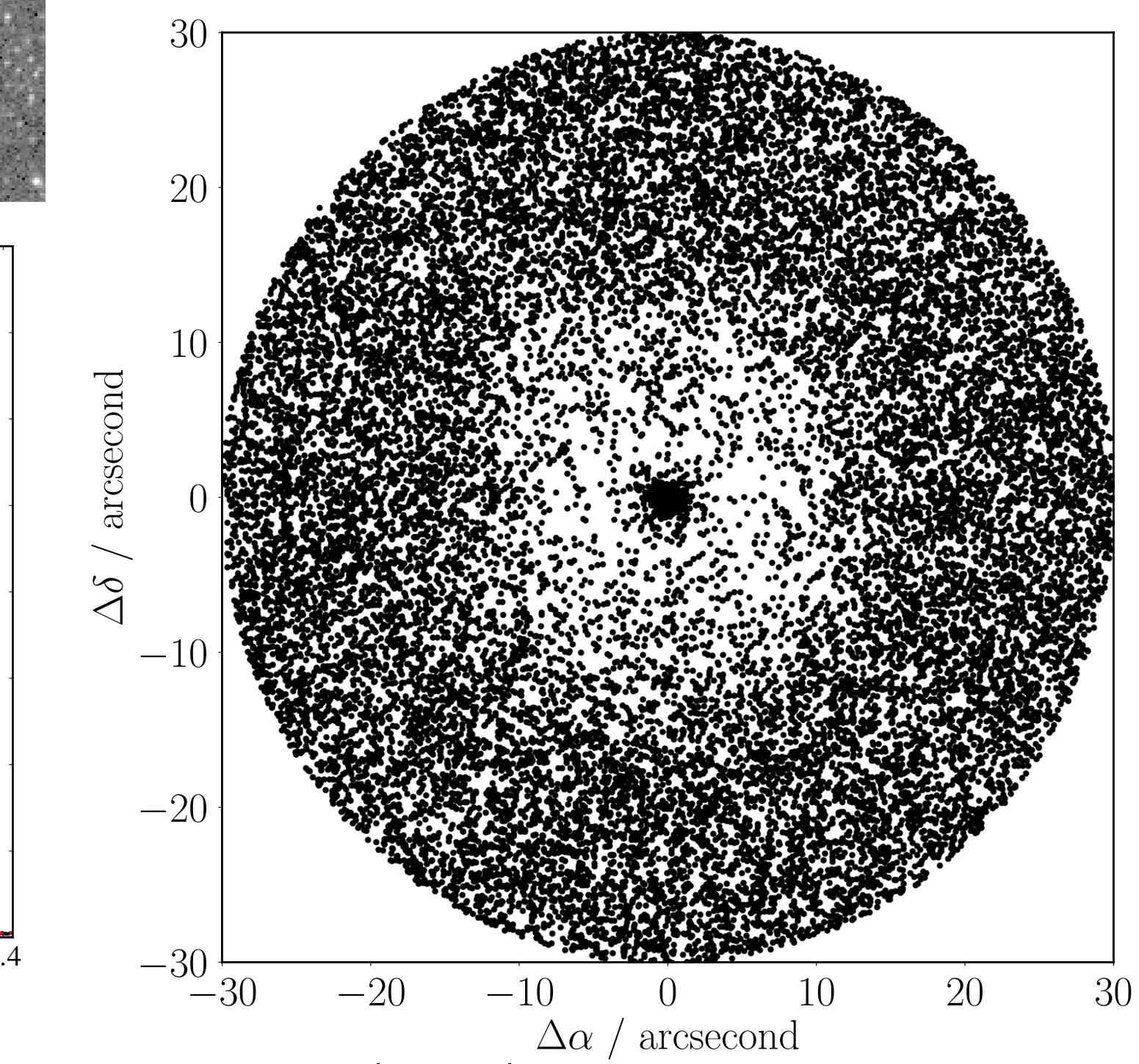
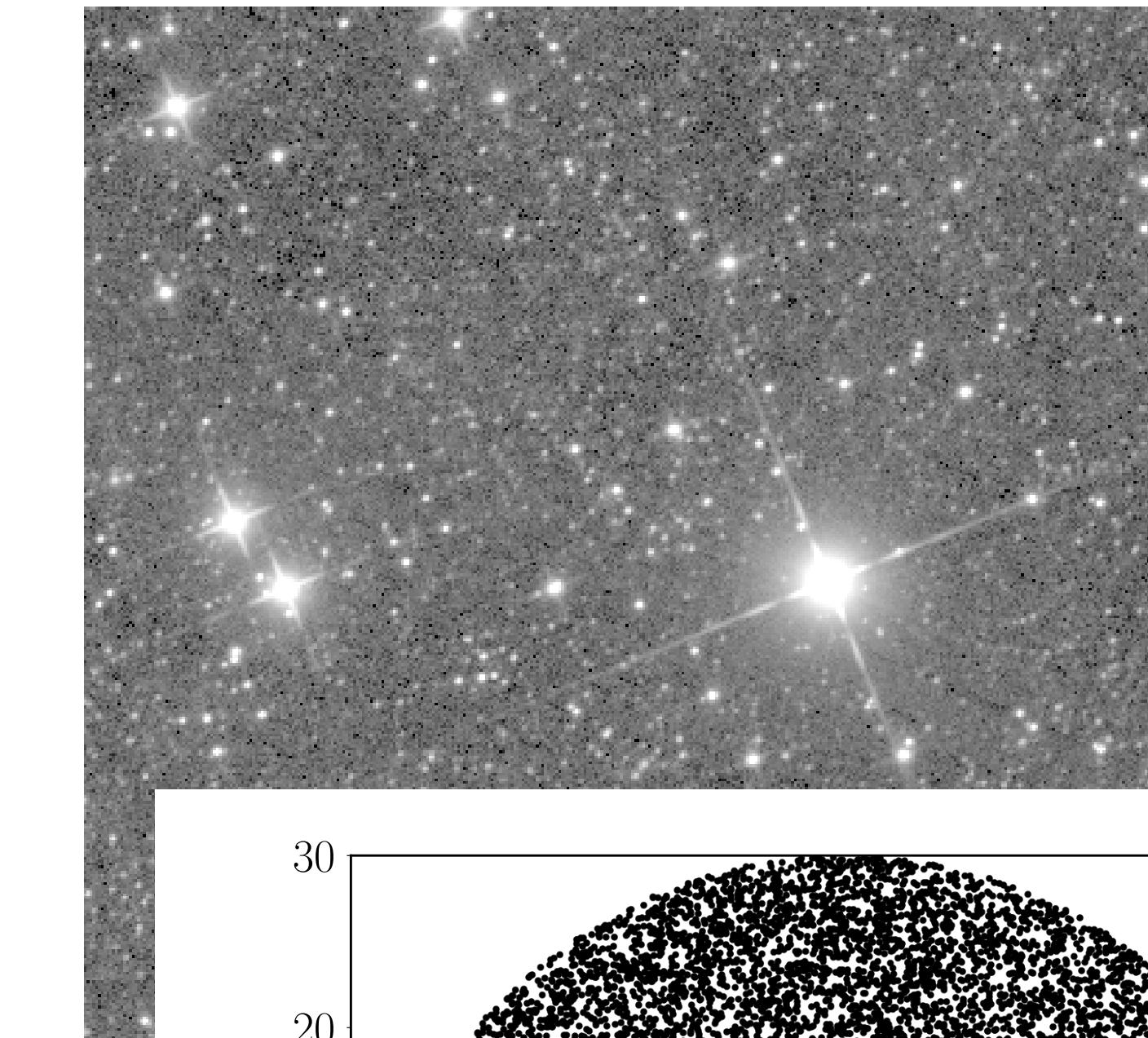


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Additional Components of the AUF



Wilson & Naylor (2018b)



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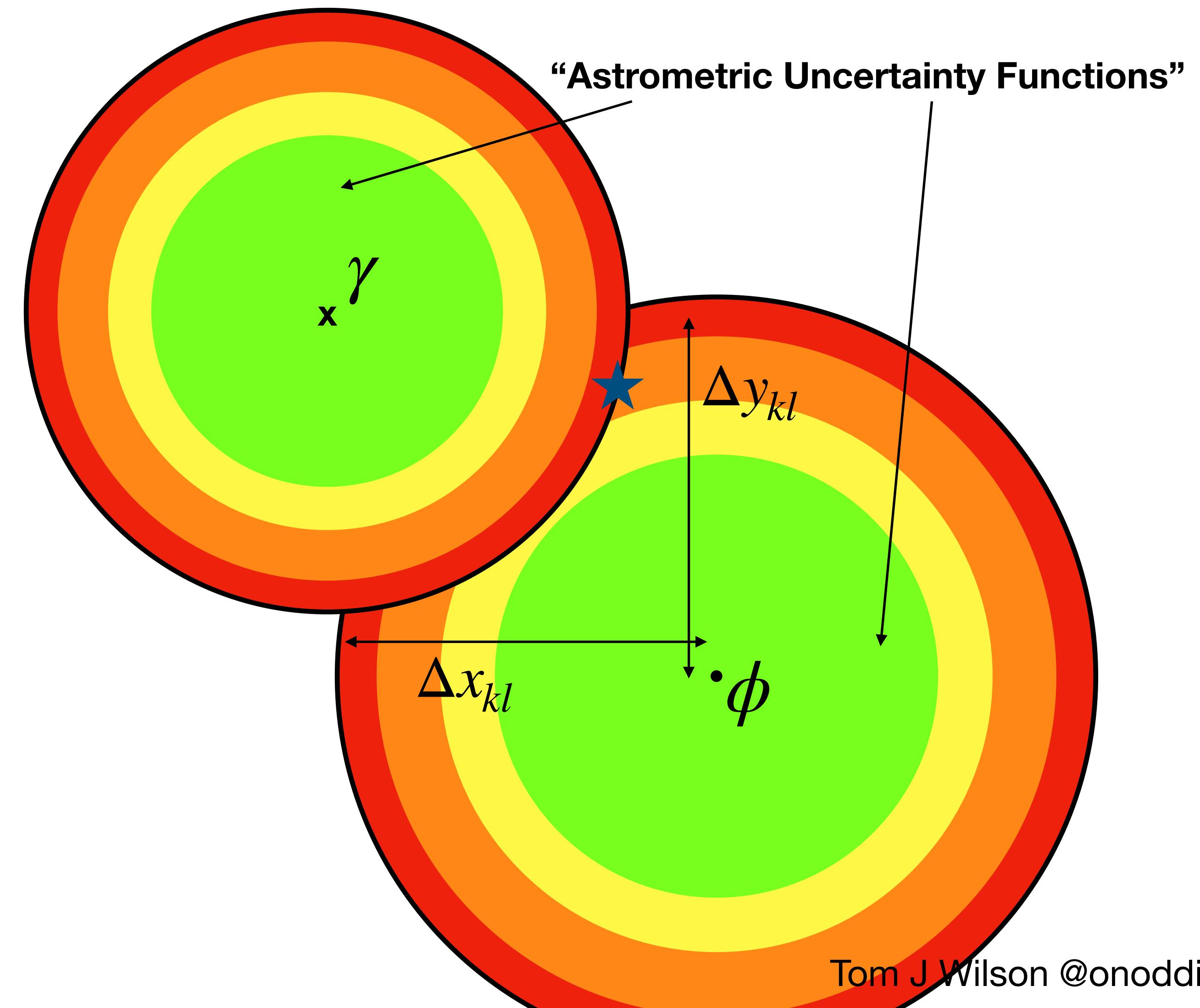
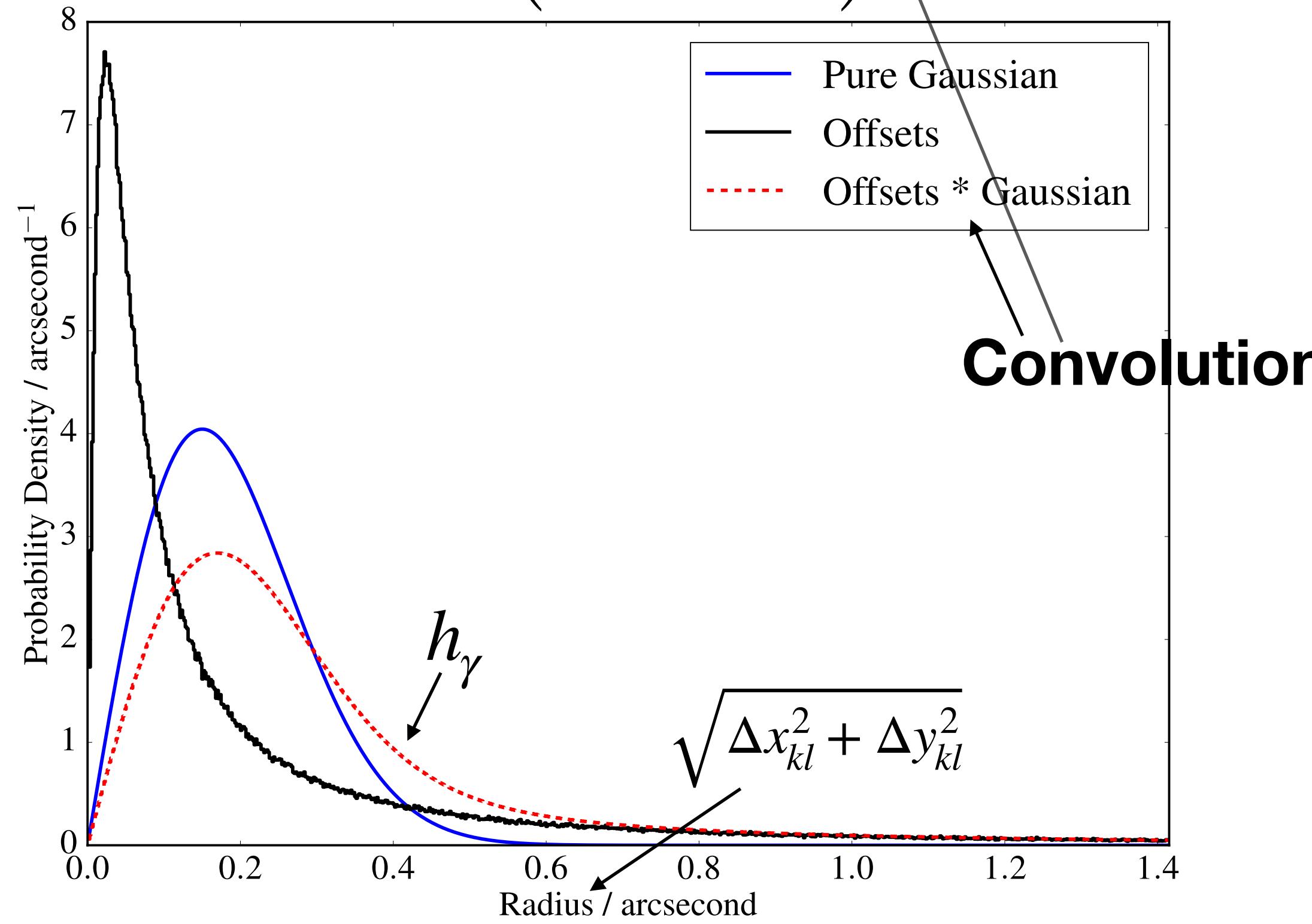
Separation Likelihood Function

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Calculating the Astrometric Uncertainty Function

The issue: new components of the AUF are not analytic, and numerical convolutions are computationally expensive

$$\iint_{-\infty}^{+\infty} h_\gamma(x_0 - x_k, y_0 - y_k) h_\phi(x_l - x_0, y_l - y_0) p(x_0, y_0) dx_0 dy_0$$

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The solution: do convolution in Fourier space

$$F(\rho) = \mathcal{F}(f(x))$$

$$(f * g)(x) = \mathcal{F}^{-1}(F \cdot G)$$

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The issue: Fourier transforms in two dimensions are still computationally difficult

$$\mathcal{F}(g(u, v)) = \iint_{-\infty}^{+\infty} g(x, y) \exp[-j2\pi(ux + vy)] dx dy$$

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The solution: assume circular symmetry and reduce to one-dimensional Hankel (Fourier-Bessel) transform

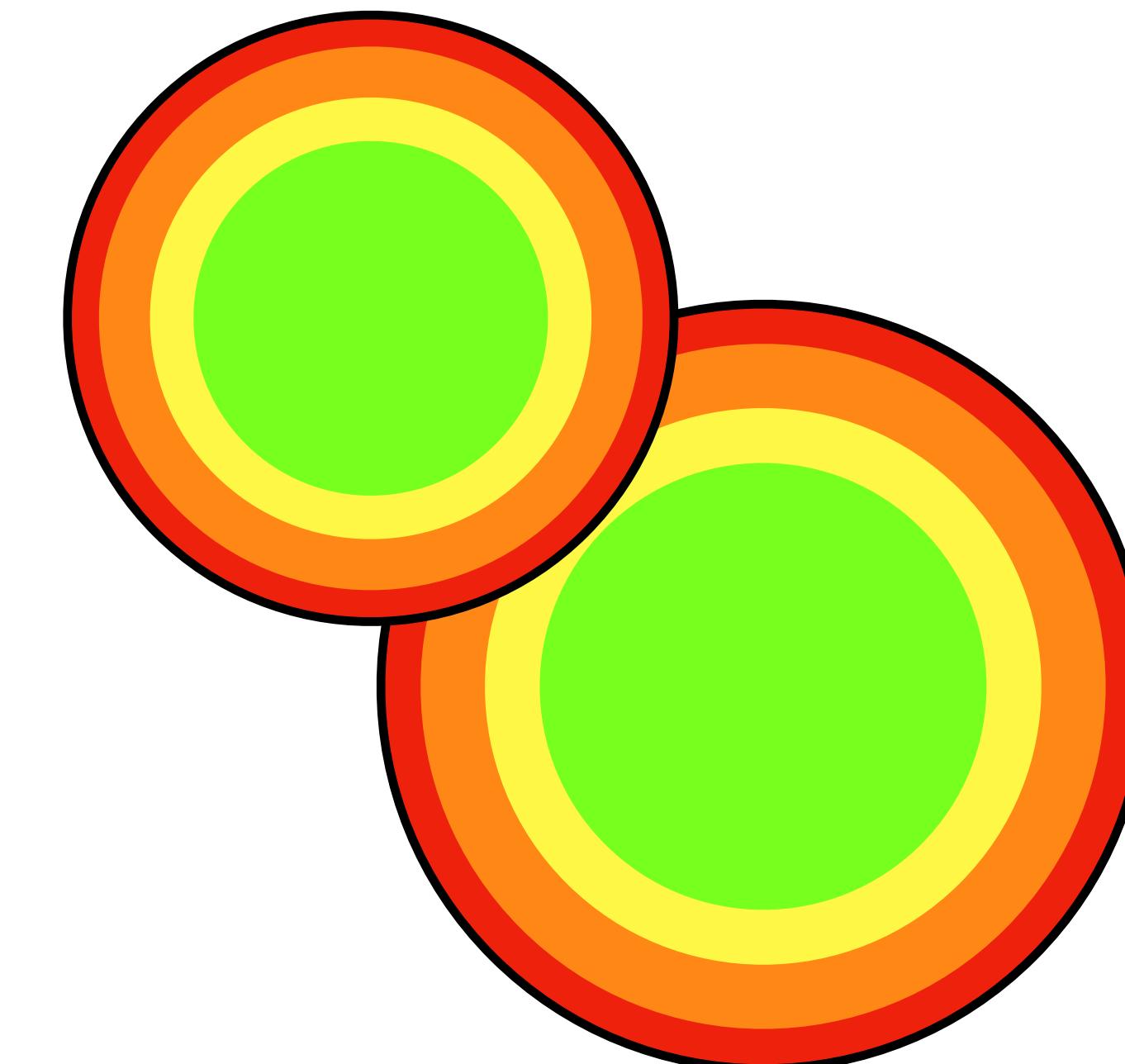
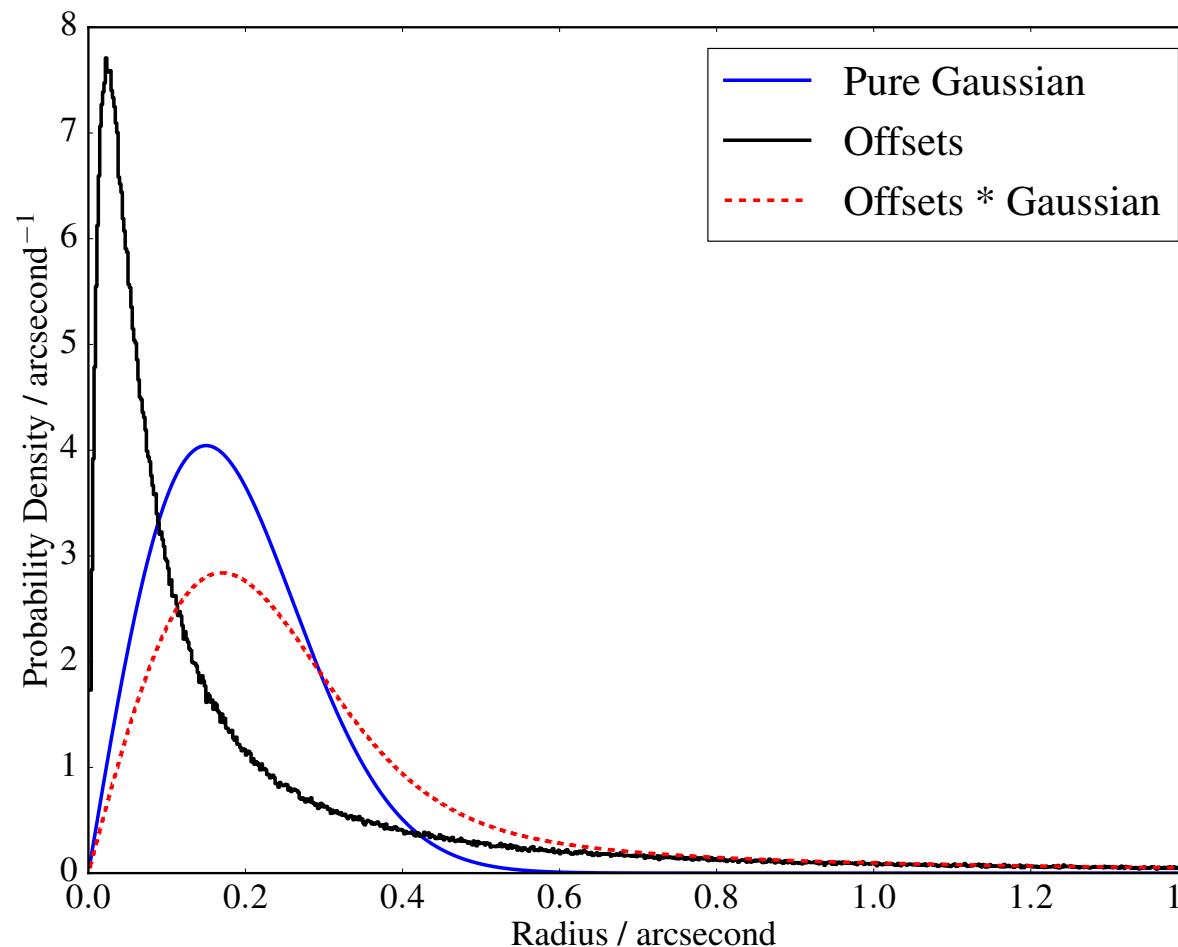
$$G(\rho, \phi) = G(\rho) = 2\pi \int_0^{\infty} r g(r) J_0(2\pi r \rho) dr$$

Introduction to Fourier Optics - J.W. Goodman

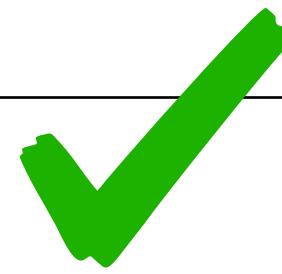
Counterpart Likelihoods In Practice

- 1) Gaussian, centroiding component of AUF has analytic Fourier-space expression**
- 2) Simulate many PSFs, derive sample of perturbations due to blended sources**
- 3) Fourier transform distribution of perturbations**
- 4) Convolution becomes 1-D multiplication and 1-D inverse Fourier transform**

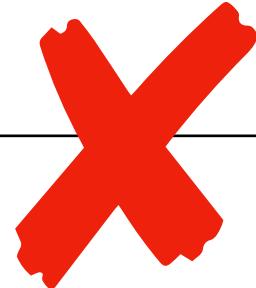
(Replace step 2 with your chosen extra sources of reasons why a source isn't measured at its "true" location!)



Calculating the Astrometric Uncertainty Function

Advantages: 

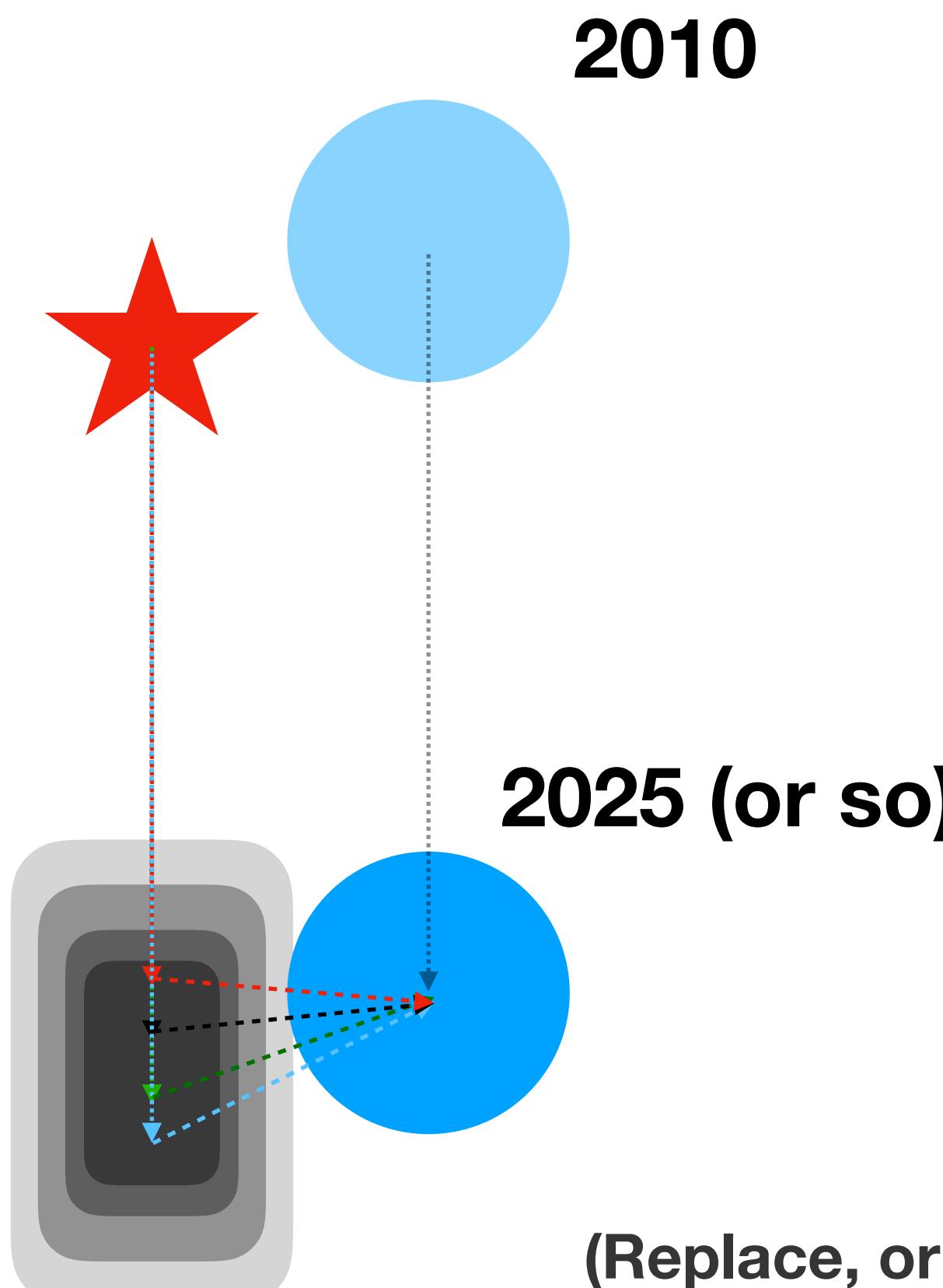
- **Allows for the generalisation of the AUF**
- Non-centroid AUF components crucial for crowded or faint fields
- Hankel Transform speeds up 2-D calculation

Disadvantages: 

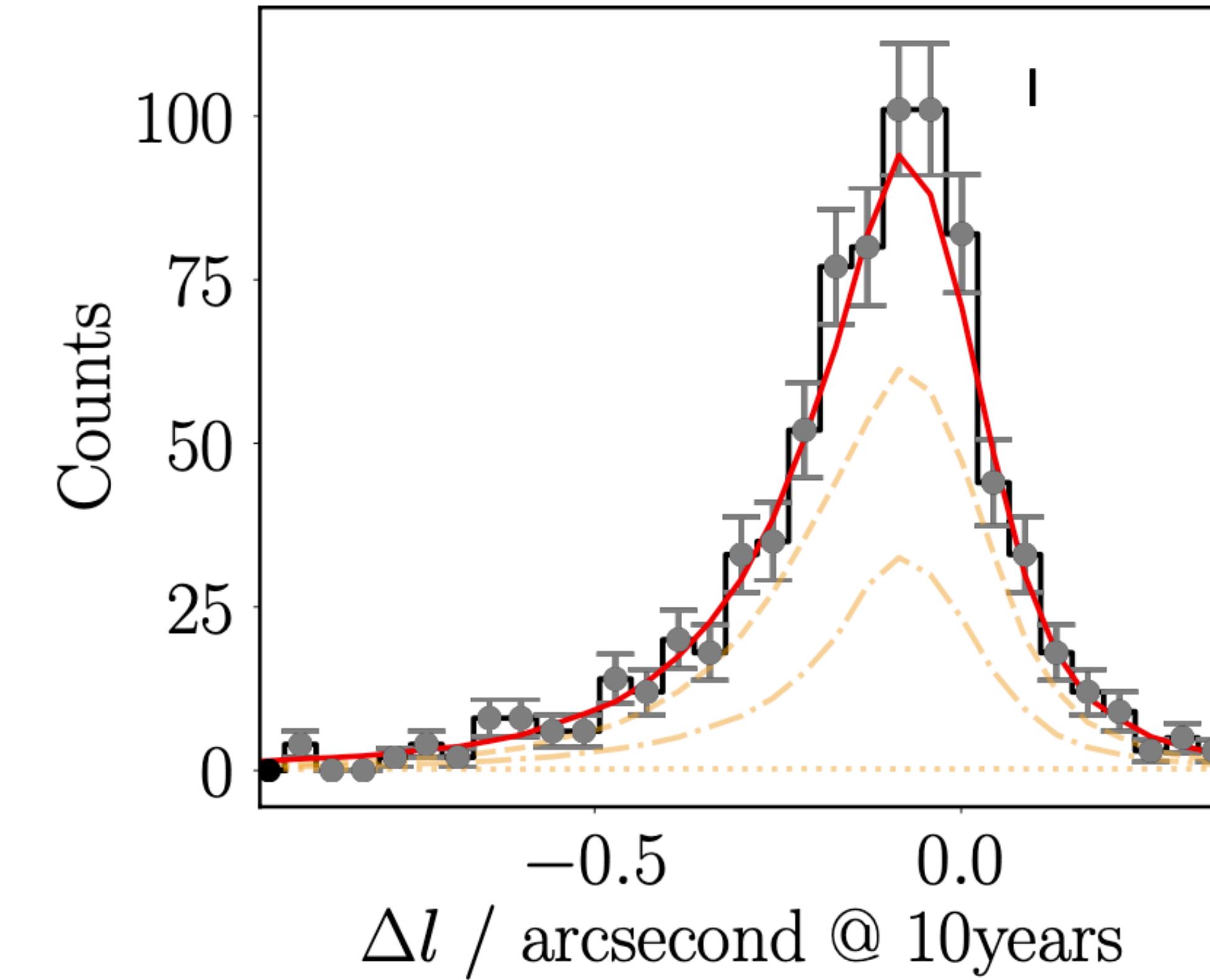
- Numerical precision needs sufficient integral resolution
- Requires all components of the AUF to be circularly symmetric

Including Unknown Proper Motions

Using a model for the distribution of potential proper motions, and hence astrometric drifts, of a source of a given sky position and brightness we can include “fast forwarding” of sources through time across different catalogues when individual proper motions are not known



(Replace, or add, your deviation
from “true” position here!)



Because this function works in *separation*, rather than pure *position*, space, we apply the distribution after the convolution to calculate G , but the same basic numerical framework applies.

$$G' = G * h'_{\text{pm}} \quad G = h_\gamma * h_\phi$$

$$h_\gamma = h_{\gamma, \text{centroding}} * h_{\gamma, \text{perturbation}}$$

Conclusions

- PDF describing positions of sources measured in photometric catalogues assumed Gaussian
- However, other components of the AUF are non-Gaussian – will be crucial for LSST (as with *WISE*)
- These might not be analytic, and hence require numerical methods to derive; simplifying assumption of circular symmetry enables convolutions to be performed in Fourier space with reasonable computation
- Models for contributions to offsets between sources for crowded field blending perturbations, and unknown proper motions – but mathematical framework flexible to all unknown kinds of separations
- Upcoming LSST:UK cross-match service macauff



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github.io [www](https://github.com/Onoddil/ma)

Wilson & Naylor, 2017, MNRAS, 468, 2517
Wilson & Naylor, 2018a, MNRAS, 473, 5570
Wilson & Naylor, 2018b, MNRAS, 481, 2148
<https://github.com/Onoddil/ma>cuff



