

* An important identity;

If f is scalar form, then $\text{Curl grad } f = 0$ or $\nabla \times \nabla f = 0$.

$$\nabla \times \nabla f = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{vmatrix} = (f_{zy} - f_{yz})\vec{i} + (f_{xz} - f_{zx})\vec{j} + (f_{yx} - f_{xy})\vec{k} = 0.$$

$$\left\{ \begin{array}{l} \text{If the second partial derivatives are continuous;} \\ \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x} \quad (\text{Schwarz's Theorem}) \end{array} \right\}$$

Conservative Fields and Stoke's Theorem

Theorem: $\text{Curl } \vec{F} = 0$ Related to Closed-Loop Property

If $\nabla \times \vec{F} = 0$ at every point of simply connected, open region D in space, then any piecewise smooth closed path C in D ;

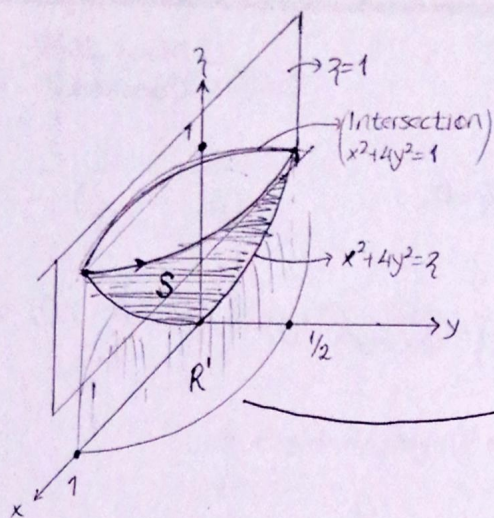
$$\oint_C \vec{F} \cdot d\vec{r} = 0.$$

HW: Let surface S be the elliptical paraboloid $z = x^2 + 4y^2$ lying beneath the plane $z = 1$.

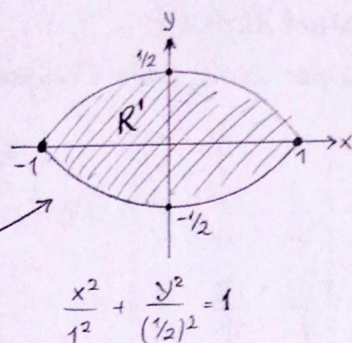
We define the orientation of S by taking the inner normal vector \vec{n} to the surface which is normal having a positive \vec{k} component. Find the flux of the curl $\nabla \times \vec{F}$ across the S in the direction \vec{n} for the vector field $\vec{F} = y\vec{i} - xz\vec{j} + xz^2\vec{k}$.

$$\underbrace{\oint_C \vec{F} \cdot d\vec{r}}_{(1)} = \underbrace{\iint_S (\nabla \times \vec{F}) \cdot \vec{n} \, d\sigma}_{(2)}$$

(Stoke's Theorem)

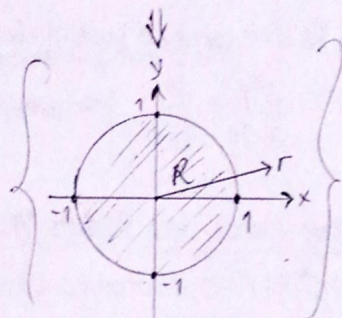


\Rightarrow



$$\begin{aligned} x &= a \cos \theta \\ y &= b \sin \theta \\ J &= ab r \\ dA &= ab r dr d\theta \end{aligned}$$

$$\begin{aligned} x &= r \cos \theta \\ y &= \frac{r}{2} \sin \theta \quad (a=1, b=1/2) \\ J &= \frac{r}{2} \\ dA &= \frac{r}{2} dr d\theta \end{aligned} \quad \begin{aligned} 0 &\leq r \leq 1 \\ 0 &\leq \theta \leq 2\pi \end{aligned}$$



$$z = x^2 + 4y^2 \Rightarrow G(x, y, z) = z - x^2 - 4y^2 = 0 \Rightarrow \vec{n} = \frac{\nabla G}{|\nabla G|} = \frac{-2x\vec{i} - 8y\vec{j} + \vec{k}}{\sqrt{4x^2 + 64y^2 + 1}}$$

$$\vec{n} \cdot \vec{k} = \frac{1}{\sqrt{4x^2 + 64y^2 + 1}}$$

$$d\sigma = \frac{dA}{|\vec{n} \cdot \vec{k}|} = \frac{dx dy}{|\vec{n} \cdot \vec{k}|} = \sqrt{4x^2 + 64y^2 + 1} dx dy$$

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & -xz & xz^2 \end{vmatrix} = x\vec{i} - z^2\vec{j} - (z+1)\vec{k}$$

$$(\nabla \times \vec{F}) \cdot \vec{n} = \frac{-2x^2 + 8yz^2 - (z+1)}{\sqrt{4x^2 + 64y^2 + 1}}$$

$$\begin{aligned} \textcircled{2}: \iint_S (\nabla \times \vec{F}) \cdot \vec{n} d\sigma &= \iint_{R_{xy}} \frac{-2x^2 + 8yz^2 - (z+1)}{\sqrt{4x^2 + 64y^2 + 1}} \cdot \sqrt{4x^2 + 64y^2 + 1} dx dy = \iint_{R_{xy}} (-2x^2 + 8yz^2 - (z+1)) dx dy \\ &= \int_0^{2\pi} \int_0^1 (-2r^2 \cos^2 \theta + 8 \left(\frac{r^2}{2} \sin^2 \theta\right) (r^2) - (r^2 + 1)) \frac{r}{2} dr d\theta = -\pi. \end{aligned}$$

$$\textcircled{1}: C: \begin{cases} x^2 + 4y^2 = z, z=1 \\ x = r \cos \theta & x = \cos \theta & dx = -\sin \theta d\theta \\ y = \frac{1}{2} \sin \theta \quad (r=1) \Rightarrow y = \frac{1}{2} \sin \theta \Rightarrow dy = \frac{1}{2} \cos \theta d\theta, 0 \leq \theta \leq 2\pi \\ z=1 & z=1 & dz=0 \end{cases}$$

$$\begin{aligned} \oint_C \vec{F} \cdot d\vec{r} &= \oint_C P dx + Q dy + R dz = \oint_C y dx - xz dy + xz^2 dz = \oint_C y dx - x dy \\ &= \int_0^{2\pi} \left(\frac{1}{2} \sin \theta (-\sin \theta d\theta) - (\cos \theta) \left(\frac{1}{2} \cos \theta d\theta \right) \right) = -\pi \end{aligned}$$

$\textcircled{1} = \textcircled{2}$. Verified. ✓

The Divergence Theorem

Divergence theorem states that the net outward flux of a vector field across a closed surface in space can be calculated by integrated the divergence of the field over the region enclosed by the surface.

Divergence in Three Dimensions

The divergence of a vector field,

$$\vec{F} = P(x, y, z)\vec{i} + Q(x, y, z)\vec{j} + R(x, y, z)\vec{k}$$

is the scalar function;

$$\nabla \cdot \vec{F} = \left(\frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k} \right) (P\vec{i} + Q\vec{j} + R\vec{k}) = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}.$$

If \vec{F} is the velocity field of a flowing gas, the value of $\text{div } \vec{F}$ at a point (x, y, z) , is the rate at which the gas is compressing or expanding at (x, y, z) . The divergence is the flux per unit volume or flux density at the point.

The divergence theorem says that under suitable conditions, the outward flux of a vector field across a closed surface equals the triple integral of the divergence of the field over the region enclosed by the surface.

Divergence Theorem

Let \vec{F} be a vector field whose components have continuous first partial derivatives and let S be a piecewise smooth oriented closed surface. The flux of \vec{F} across S in the direction of surface's outward unit normal field \vec{n} equals the integral of $\nabla \cdot \vec{F}$ over the region D enclosed by the surface.

$$\underbrace{\iint_S \vec{F} \cdot \vec{n} \, ds}_{\text{Outward Flux}} = \underbrace{\iiint_D (\nabla \cdot \vec{F}) \, dV}_{\text{Divergence Integral}} \quad (\text{DIVERGENCE THEOREM})$$

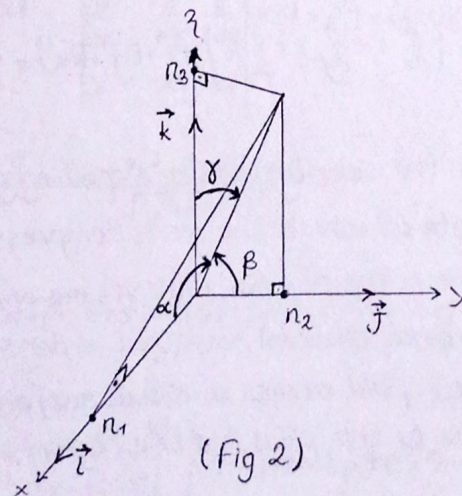
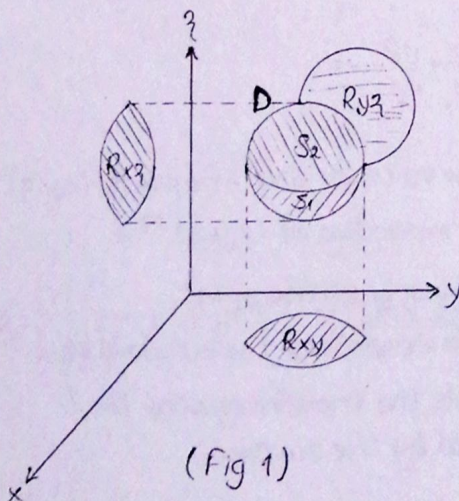
Proof of the Divergence Theorem

To prove the divergence theorem, we take the components of \vec{F} to have continuous first partial derivatives. We first assume that D is a convex region with no holes or bubbles, such as a solid ball, cube or ellipsoid and that S is a piecewise smooth surface. In addition, we assume that any line perpendicular to the xy -plane at an interior point of the region R_{xy} that is the projection of D on the xy -plane intersects the surface S in exactly two points producing surfaces.

$$S_1 : z = f_1(x, y), \quad (x, y) \text{ in } R_{xy}$$

$$S_2 : z = f_2(x, y), \quad (x, y) \text{ in } R_{xy}$$

with $f_1 \leq f_2$. We make similar assumptions about the projection of D onto the other coordinate planes. (Fig. 1)



The components of the unit normal vector

$$\vec{n} = n_1 \vec{i} + n_2 \vec{j} + n_3 \vec{k}$$

are the cosines of the angles α, β and γ that normal vector \vec{n} makes with $\vec{i}, \vec{j}, \vec{k}$. (Fig 2).

$$\left. \begin{aligned} \vec{n} \cdot \vec{i} &= n_1 = \frac{|\vec{n}| \cdot |\vec{i}|}{1} \cos \alpha = \cos \alpha \\ \vec{n} \cdot \vec{j} &= n_2 = \cos \beta \\ \vec{n} \cdot \vec{k} &= n_3 = \cos \gamma \end{aligned} \right\} \vec{n} = \cos \alpha \vec{i} + \cos \beta \vec{j} + \cos \gamma \vec{k}$$

$$\vec{F} = P(x, y, z) \vec{i} + Q(x, y, z) \vec{j} + R(x, y, z) \vec{k}$$

$$\vec{F} \cdot \vec{n} = P \cos \alpha + Q \cos \beta + R \cos \gamma$$

$$\Rightarrow \iint_S \vec{F} \cdot \vec{n} \, ds = \iint_S (P \cos \alpha + Q \cos \beta + R \cos \gamma) \, ds = \underbrace{\iint_S P \cos \alpha \, ds}_{I_3} + \underbrace{\iint_S Q \cos \beta \, ds}_{I_2} + \underbrace{\iint_S R \cos \gamma \, ds}_{I_1}$$

$$I_1 = \iint_S R \cos \gamma \, ds = \iint_{S_1} \underbrace{R \cos \gamma \, ds_1}_{dx dy} + \iint_{S_2} \underbrace{R \cos \gamma \, ds_2}_{dx dy} = - \iint_{R_{xy}} R(x, y, f_1(x, y)) \, dx dy + \iint_{R_{xy}} R(x, y, f_2(x, y)) \, dx dy$$

$$= \iint_{R_{xy}} [R(x, y, f_2(x, y)) - R(x, y, f_1(x, y))] \, dx dy$$

$$I_1 = \iiint_D \frac{\partial R}{\partial z} \, dV = \iint_{R_{xy}} \left(\int_{z=f_1(x, y)}^{z=f_2(x, y)} \frac{\partial R}{\partial z} \, dz \right) dA \quad \left\{ dV = dz dA \right\}$$

$$\Rightarrow I_2 = \iint_S Q \cos \beta \, ds = \iint_{R_{yz}} \left(\int_{y=g_1(x, z)}^{y=g_2(x, z)} \frac{\partial Q}{\partial y} \, dy \right) dA = \iiint_D \frac{\partial Q}{\partial y} \, dV$$

$$I_3 = \iint_S P \cos \alpha \, ds = \iint_{R_{yz}} \left(\int_{x=h_1(y, z)}^{x=h_2(y, z)} \frac{\partial P}{\partial x} \, dx \right) dA = \iiint_D \frac{\partial P}{\partial x} \, dV$$

$$\Rightarrow \iint_S \vec{F} \cdot \vec{n} \, ds = I_1 + I_2 + I_3 = \iiint_D \left(\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right) dV = \iiint_D (\nabla \cdot \vec{F}) dV$$

* Source :



$\text{div } F(x_0, y_0) > 0$
Gas is expanding.

Well :



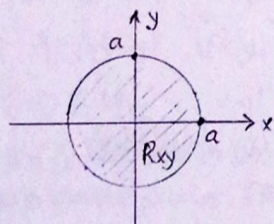
$\text{div } F(x_0, y_0) < 0$
Gas is compressing.

Examples

- 1) Evaluate both sides of divergence theorem formula for the expanding over field $\vec{F} = x\vec{i} + y\vec{j} + z\vec{k}$ over the sphere $x^2 + y^2 + z^2 = a^2$.
- 2) Find the flux of $\vec{F} = xy\vec{i} + yz\vec{j} + xz\vec{k}$ outward through the surface of the cube cut from the first octant by the planes $x=1, y=1, z=1$.
- 3) Let $\vec{F}(x, y, z) = 2x^2y\vec{i} - y^2\vec{j} + 4xz^2\vec{k}$, S is the portion of the cylinder $y^2 + z^2 = 9$ between the planes $x=0$ and $x=2$ in the first octant. Verify the divergence theorem.

Solutions

1)



$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \\ dA &= r dr d\theta \\ 0 &\leq r \leq a \\ 0 &\leq \theta \leq 2\pi \end{aligned}$$

$$\phi(x, y, z) = x^2 + y^2 + z^2 - a^2 = 0$$

$$\vec{n} = \frac{\nabla \phi}{|\nabla \phi|} = \frac{2x\vec{i} + 2y\vec{j} + 2z\vec{k}}{2a} = \frac{x}{a}\vec{i} + \frac{y}{a}\vec{j} + \frac{z}{a}\vec{k} \Rightarrow |\vec{n} \cdot \vec{k}| = \frac{z}{a} \Rightarrow \vec{F} \cdot \vec{n} = \frac{x^2}{a} + \frac{y^2}{a} + \frac{z^2}{a} = a$$

$$ds = \frac{dA}{|\vec{n} \cdot \vec{k}|} = \frac{dxdy}{|\vec{n} \cdot \vec{k}|} = \frac{a}{z} dxdy, z > 0$$

$$\iint_S \vec{F} \cdot \vec{n} \, ds = \iiint_D (\nabla \cdot \vec{F}) \, dV \quad (\text{Divergence Theorem})$$

S D
LHS ① RHS ②

$$\textcircled{1} \text{ LHS: } \iint_S \vec{F} \cdot \vec{n} \, ds = 2 \iint_S \vec{F} \cdot \vec{n} \, ds \quad (z \geq 0)$$

$$= 2 \iint_{xy} a \cdot \frac{a}{\sqrt{a^2 - x^2 - y^2}} \, dx \, dy = 2a^2 \int_{\theta=0}^{2\pi} \left(\int_{r=0}^a \frac{r}{\sqrt{a^2 - r^2}} \, dr \right) d\theta = 2a^2 \int_{\theta=0}^{2\pi} a \, d\theta = 4a^3\pi.$$

$$\left\{ \begin{array}{l} a^2 - r^2 = u^2 \\ -2r \, dr = 2u \, du \end{array} \right.$$

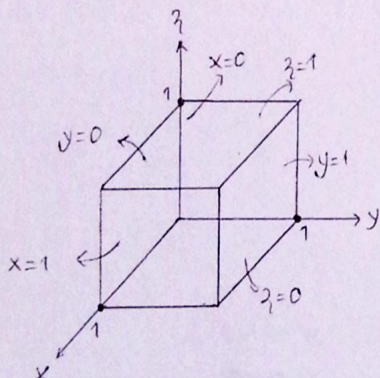
$$\textcircled{2} \text{ RHS: } \nabla \cdot \vec{F} = \frac{\partial(x)}{\partial x} + \frac{\partial(y)}{\partial y} + \frac{\partial(z)}{\partial z} = 3$$

$$\Rightarrow \iiint_D 3 \, dV = 3 \iiint_D dV = 4a^3\pi.$$

$\frac{4}{3}\pi a^3$ (Volume of D)

$\textcircled{1} = \textcircled{2}$ Verified. ✓

2)



$$\underbrace{\iint_S \vec{F} \cdot \vec{n} \, ds}_{\textcircled{1}} = \underbrace{\iiint_D (\nabla \cdot \vec{F}) \, dV}_{\textcircled{2}}$$

$$\textcircled{1} \quad \iint_S \vec{F} \cdot \vec{n} \, ds = \iint_{S_1} \vec{F} \cdot \vec{n} \, ds_1 + \dots + \iint_{S_6} \vec{F} \cdot \vec{n} \, ds_6$$

$$S_1: x=0, \vec{n}_1 = -\vec{i}, \vec{F} \cdot \vec{n}_1 = -xy = 0, ds_1 = \frac{dA}{|\vec{n}_1 \cdot \vec{i}|} = \frac{dA}{|\vec{n}_1 \cdot \vec{i}|} = dy \, dz$$

$$\iint_{S_1} \vec{F} \cdot \vec{n}_1 \, ds_1 = 0 \quad (\text{Similarly } S_2 \text{ and } S_3 \text{ equal } 0.)$$

$$S_4: x=1, \vec{n}_4=\vec{i}, \vec{F} \cdot \vec{n}_4 = xy = y, ds_4 = \frac{dA}{|\vec{n}_4 \cdot \vec{i}|} = dydz$$

$$\iint_{S_4} \vec{F} \cdot \vec{n}_4 ds_4 = \iint_{R_{yz}} y dy dz = \int_{y=0}^1 \left(\int_{z=0}^1 y dz \right) dy = \frac{1}{2} \quad (\text{Similarly } S_5 \text{ and } S_6 \text{ equal } \frac{1}{2})$$

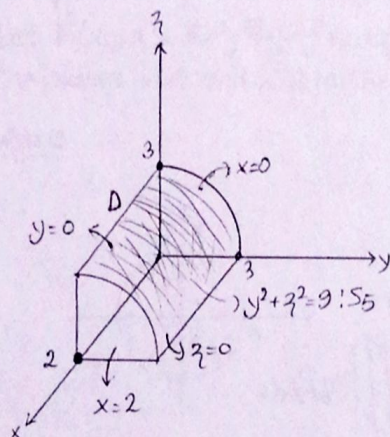
$$\Rightarrow \iint_S \vec{F} \cdot \vec{n} ds = 0 + 0 + 0 + \frac{1}{2} + \frac{1}{2} + \frac{1}{2} = \frac{3}{2}$$

$$\textcircled{2}: (\nabla \cdot \vec{F}) = y + z + x$$

$$\Rightarrow \iiint_D (\nabla \cdot \vec{F}) dV = \iiint_{R_{xyz}} \left(\int_{z=0}^1 (x+y+z) dz \right) dA = \frac{3}{2}$$

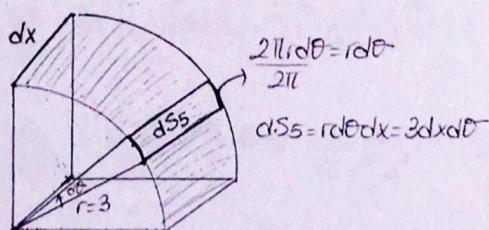
$\textcircled{1} = \textcircled{2}$ Verified. ✓

3)



$$\iiint_D (\nabla \cdot \vec{F}) dV = \iint_{R_{xy}} \left(\int_{z=0}^{\sqrt{9-y^2}} (\nabla \cdot \vec{F}) dz \right) dA = 180. \checkmark$$

*



$$y^2 + z^2 = 9$$

$$y = r \cos \theta$$

$$z = r \sin \theta$$

$$0 \leq r \leq 3$$

$$0 \leq \theta \leq \pi/2$$

$$\Rightarrow \iint_{S_5} \vec{F} \cdot \vec{n}_5 ds_5 = \iint_{S_5} \left(\frac{-y^3}{3} + \frac{4xz^3}{3} \right) ds_5 = \int_{x=0}^2 \left(\int_{\theta=0}^{\pi/2} \left(\frac{-r^3 \cos^3 \theta}{3} + \frac{4xr^3 \sin^3 \theta}{3} \right) 3 d\theta \right) dx = 180. \checkmark$$

r=3