

观测器

$$Q_g = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 1 & 4 & 4 \end{bmatrix} \quad \text{rank}(Q_g) = 3 \quad \text{能观}$$

$$T = \begin{bmatrix} 1 & 1 & 1 \\ -1 & -1 & 0 \\ 1 & 2 & 4 \end{bmatrix}$$

$$\tilde{A} = \begin{bmatrix} 0 & 0 & 4 \\ 1 & 0 & -8 \\ 0 & 1 & 5 \end{bmatrix}$$

$$\tilde{b}^T = [3 \quad -3 \quad 1]$$

$$\tilde{c}^T = [0 \quad 0 \quad 1]$$

$$f^*(s) = (s+2)(s+3)(s+4) = s^3 + 9s^2 + 26s + 24$$

$$\tilde{f}(s) = s^3 - 5s^2 + 8s - 4$$

$$\tilde{M} = [-28 \quad -18 \quad -14]^T$$

观测器方程:

$$\dot{\hat{x}} = (A + MC)\hat{x} + Bu - My$$