

# Initial Apprentice Autonomous Altitude Flight Test

DATE: Possibly First Flight Test

## OBJECTIVE(S)

- A successful autonomous navigation of the Apprentice aircraft
- Verify that the Pixhawk will be able to control its altitude effectively during flight

## SUCCESS CRITERIA

- A successful mission implies the apprentice autonomously executes the following mission successfully:
  - Aircraft maintains altitude set in QGroundControl
  - Aircraft successfully changes to the set altitude between waypoints
  - Upon reaching planned waypoint, aircraft returns to home and original altitude
- Craft completes mission within the estimated time of completion given in QGroundControl

## SUPPLIES

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|--|--|
| <input type="checkbox"/> UAS   | <input type="checkbox"/> Receiver antenna for computer |
| <input type="checkbox"/> Taranis (fully charged)                                   | <input type="checkbox"/> Tape                          |
| <input type="checkbox"/> Battery (fully charged, plus spare)                       | <input type="checkbox"/> zip-ties                      |
| <input type="checkbox"/> Computer to run QGroundControl (fully charged, one spare) |  |
| <input type="checkbox"/> Cell phone with cellular data (fully charged, one spare)  |  |

## LOCATION:

Field or Airstrip

## TEST SYSTEM:

Apprentice/ Fall 2020 UAS

## TEST CONDITIONS:

Mild weather conditions and no more than 10 mph wind

## PROCEDURES

1. Complete Preflight Checklist
  - ☐ UAS is ready to fly
  - ☐ Team is briefed on safety concerns
  - ☐ Team is briefed on roles and objectives
  - ☐ Final Weather check
2. Complete Test-specific flight checklist
  - ☐ Create and upload mission plan to pixhawk (must be created on site)
3. Complete Electronics team pre-flight checklist
4. Complete Arming Procedure
5. Manually take off
6. Fly to first waypoint GPS location
  - ☐ Verify location via map view on QGroundControl
7. Flip the INSERT SWITCH HERE into INSERT SWITCH POSITION to switch the pixhawk into mission mode
8. Have the UAS fly to a different altitude

9. Verify the UAS completes its mission (See Mission plan and verification)
10. Once UAS has reached planned home, switch INSERT SWITCH HERE into INSERT SWITCH POSITION to switch the Pixhawk back into manual flight mode
11. Manually Land UAS
12. Disarm Pixhawk through QGroundControl
13. Flip ESC disarm switch on the Left side of the plane near the cockpit
14. Disconnect Battery
15. Visually inspect for any electronics damage
16. After the last flight disconnect in the following order:
  - ☐ Disconnect the battery
  - ☐ Turn off Taranis
  - ☐ Disconnect from QGroundControl
  - ☐ Measure battery voltage
  - ☐ Assess aircraft for damage

## TEST DATA

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## DEBRIEF

- Total Flight Time: \_\_\_\_\_
- Battery level pre-test: \_\_\_\_\_ | - Battery level post-test: \_\_\_\_\_ | - Power Consumption: \_\_\_\_\_
- Objectives met:
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- Test items that went well:
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- Test Items that did not go well/need to be improved:
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