

A

A

B

B

C

C

D

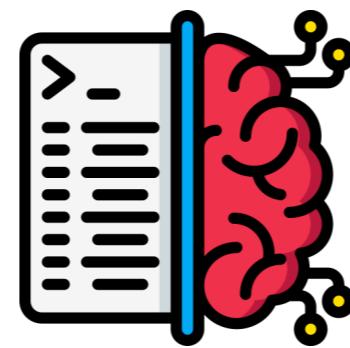
D

E

E

F

F



Robot LEGO Controller

PCB Pages

01-Microcontroller and Extras
File: 01-Microcontroller and Extras.kicad_sch
02-System Power Supply and USB
File: 02-System Power Supply and USB.kicad_sch
03-System Inputs A
File: 03-System Inputs A.kicad_sch
04-System Inputs B
File: 04-System Inputs B.kicad_sch
05-System Outputs A
File: 05-System Outputs A.kicad_sch
06-System Outputs B
File: 06-System Outputs B.kicad_sch

Power Rail

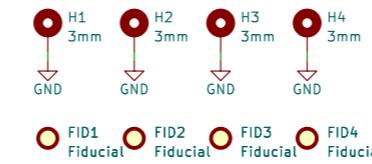
+3.3V	3V3 Power Supply (LDO 4V2)
+5V	5V Power Supply (Boost 4V2)
+9V	9V Power Supply (Boost 4V2)
+4.2V	4V2 Main Power Supply Rail
VBUS	[5-12]V USB Input Supply
+BATT	Battery Voltage 3.7V-4.2V
	Ground

PCB Revision

ID0	ID1	Revision
0	0	PCB Rev A

Variant

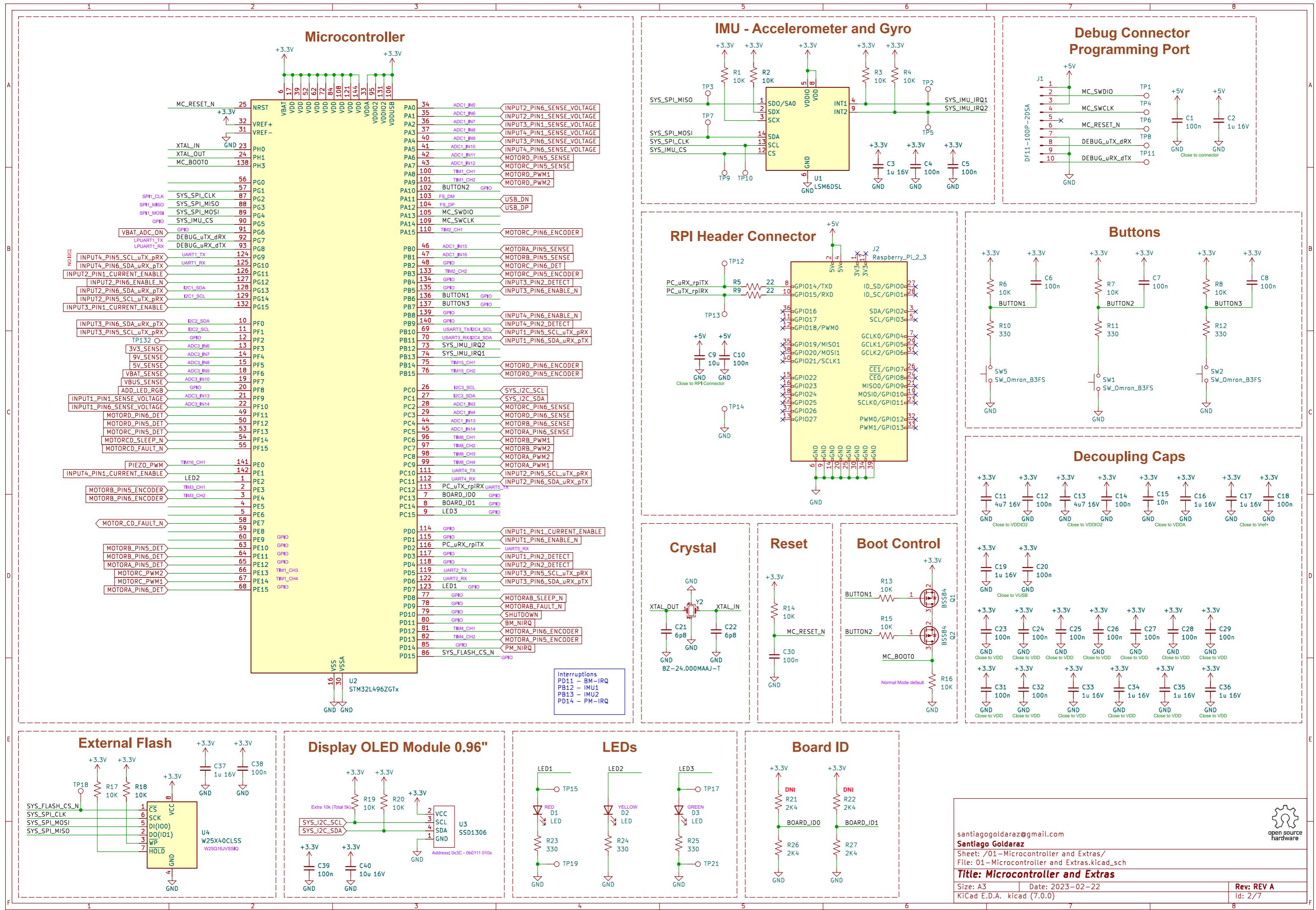
Var	Description
V1	Production

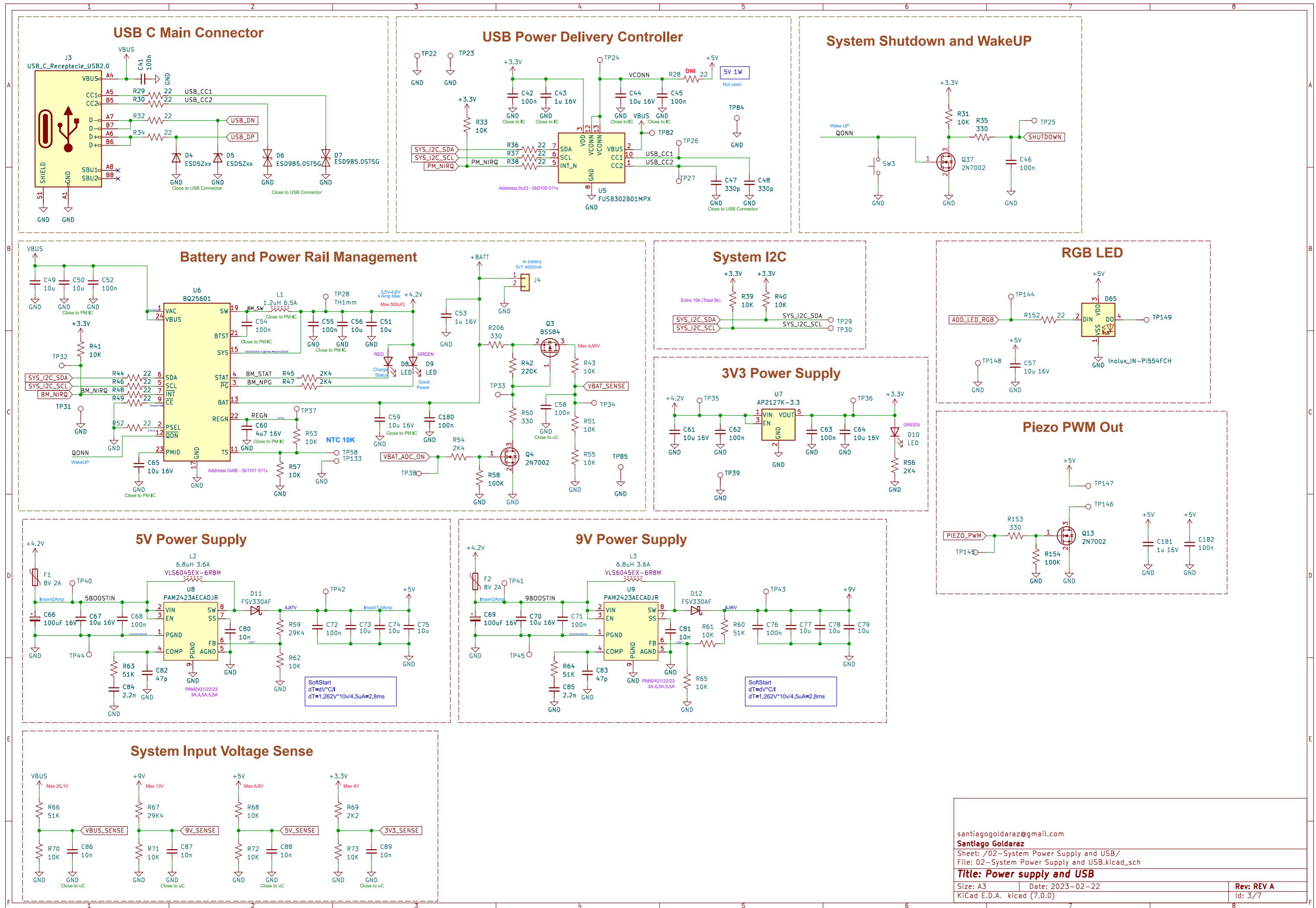


SYMBOL3
open source hardware
SYMBOL2
Lego Robot Controller
SYMBOL1
designed by SGGTAV

santiagogoldaraz@gmail.com
Santiago Goldaraz
Sheet: /
File: RobotLegController.kicad_sch
Title: Robot Lego Controller
Size: A3 Date: 2023-02-22
KiCad E.D.A. kicad (7.0.0) Rev: REV A
Id: 1/7

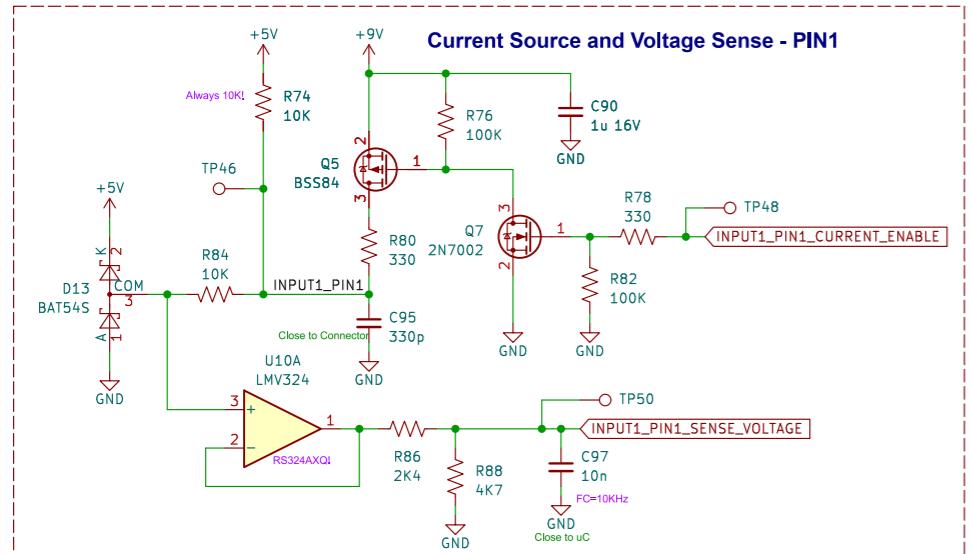






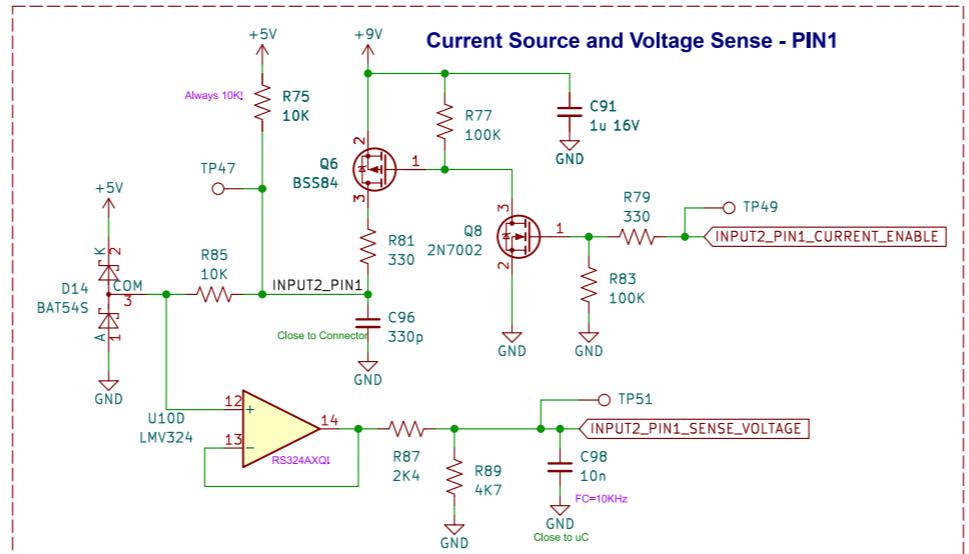
General SENSOR Input 1

Current Source and Voltage Sense - PIN1

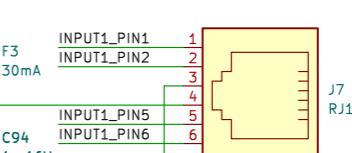


General SENSOR Input 2

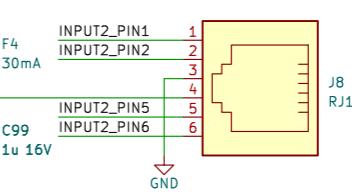
Current Source and Voltage Sense - PIN1



Main Sensor Connector 1

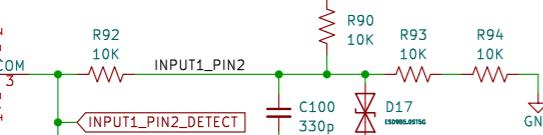


Main Sensor Connector 2

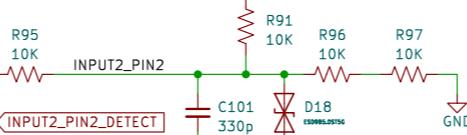


Pin 1. ADC@5 V ref, 9V With resistor limiter
 Pin 2. GPIO, Auto ID functionality
 Pin 3. Ground
 Pin 4. VCC 5 V
 Pin 5. Digital I/O, SCL (I₂C), UART RX
 Pin 6. Digital I/O, SDA (I₂C), ADC@5 V ref, UART TX

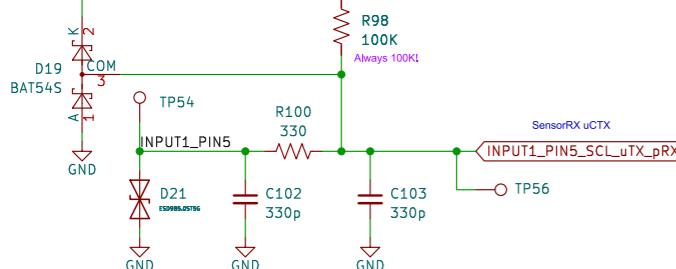
Detect Input - PIN2



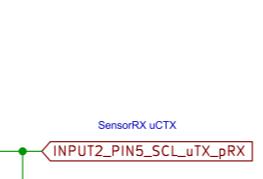
Detect Input - PIN2



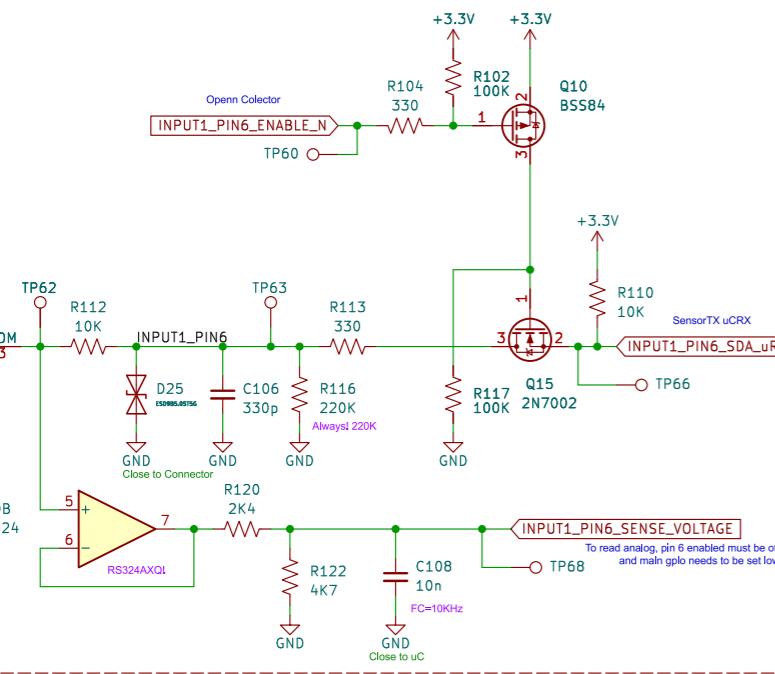
General OUTPUT - PIN5



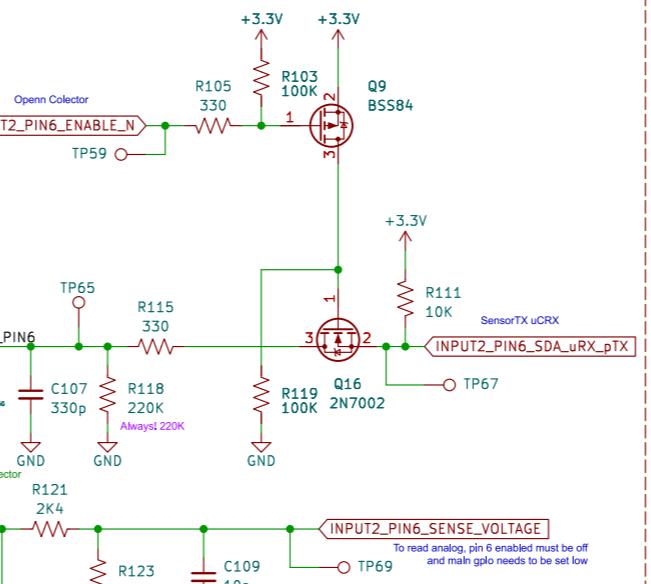
General OUTPUT - PIN5



General INPUT - PIN6



General INPUT - PIN6



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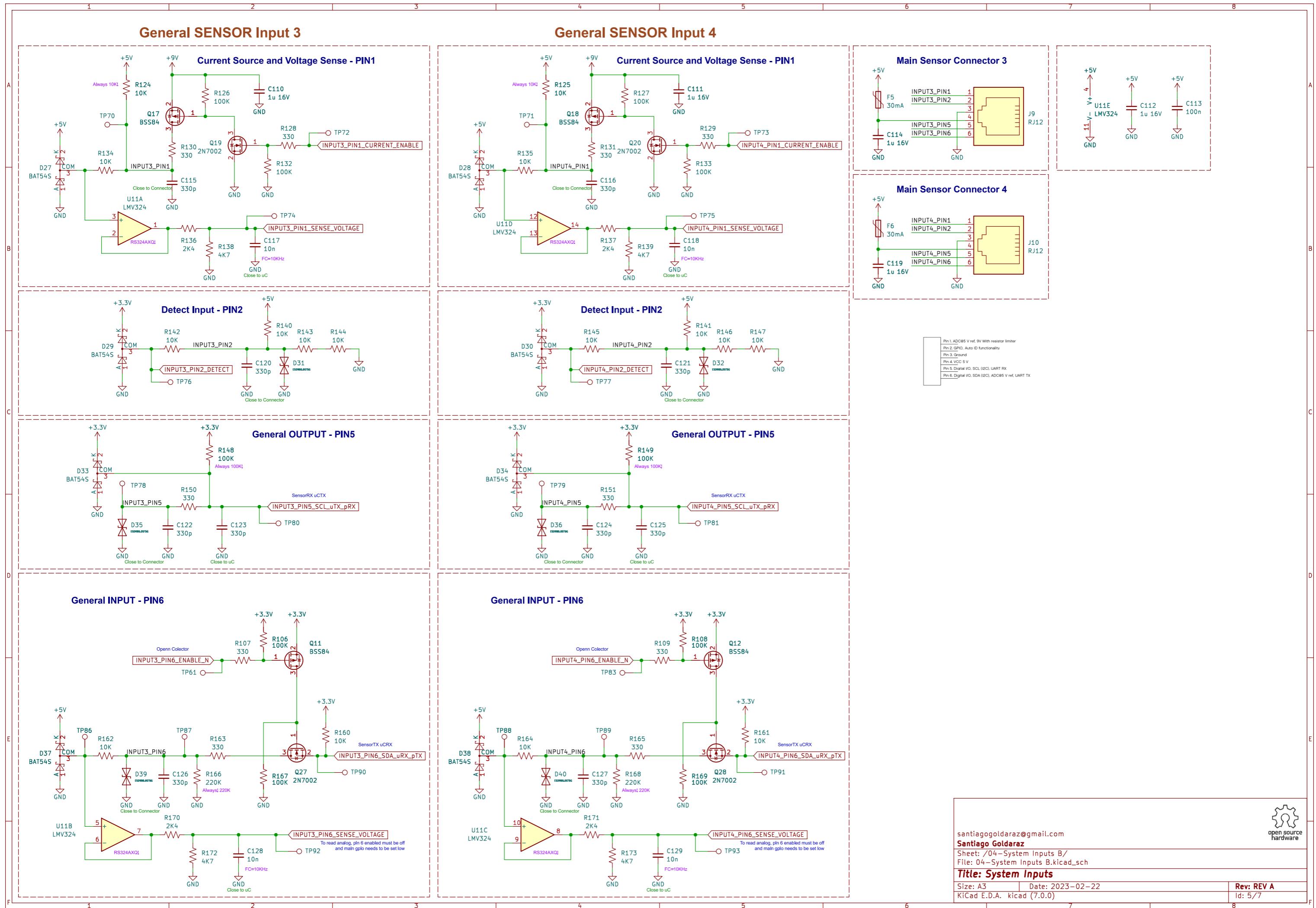
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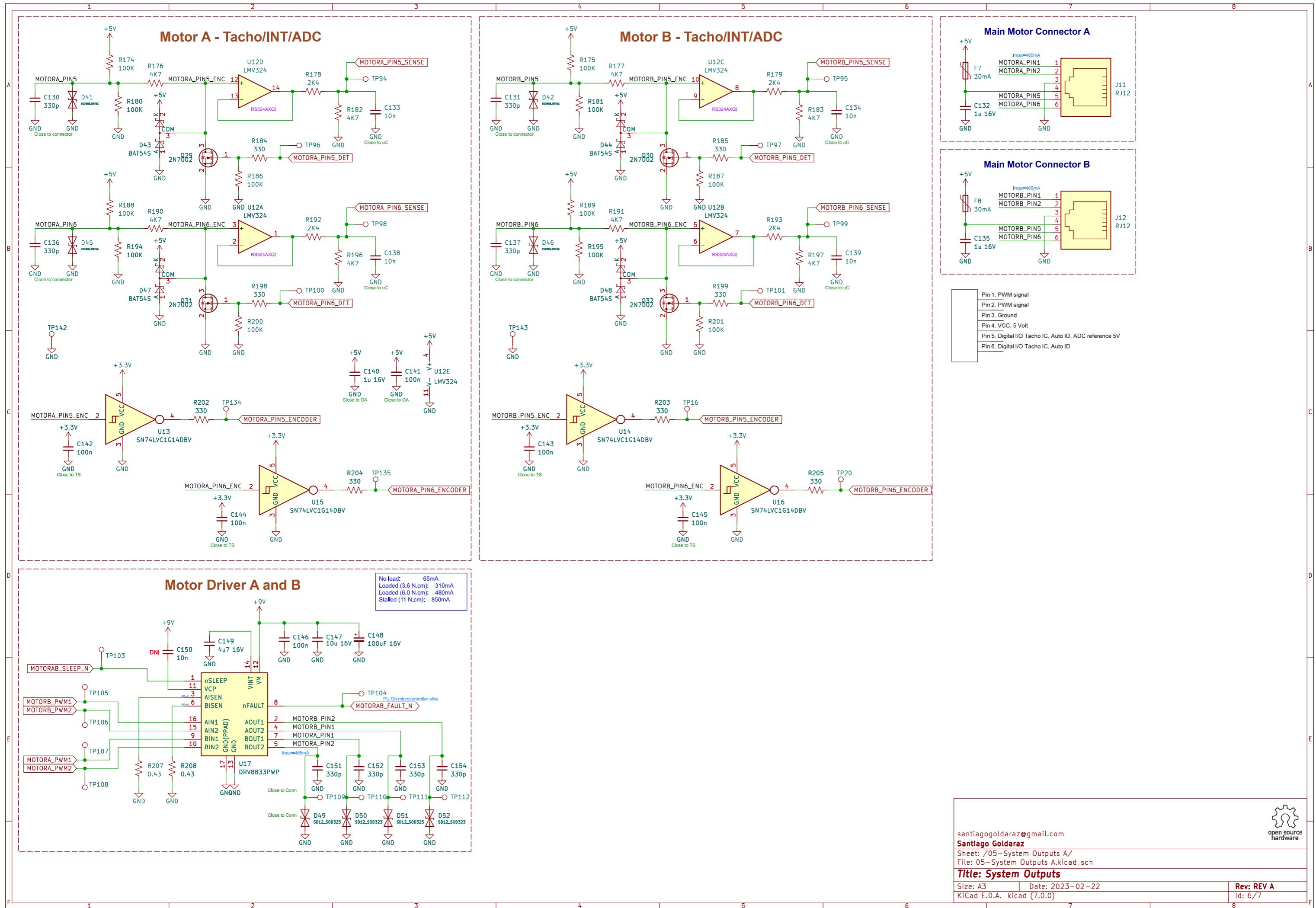
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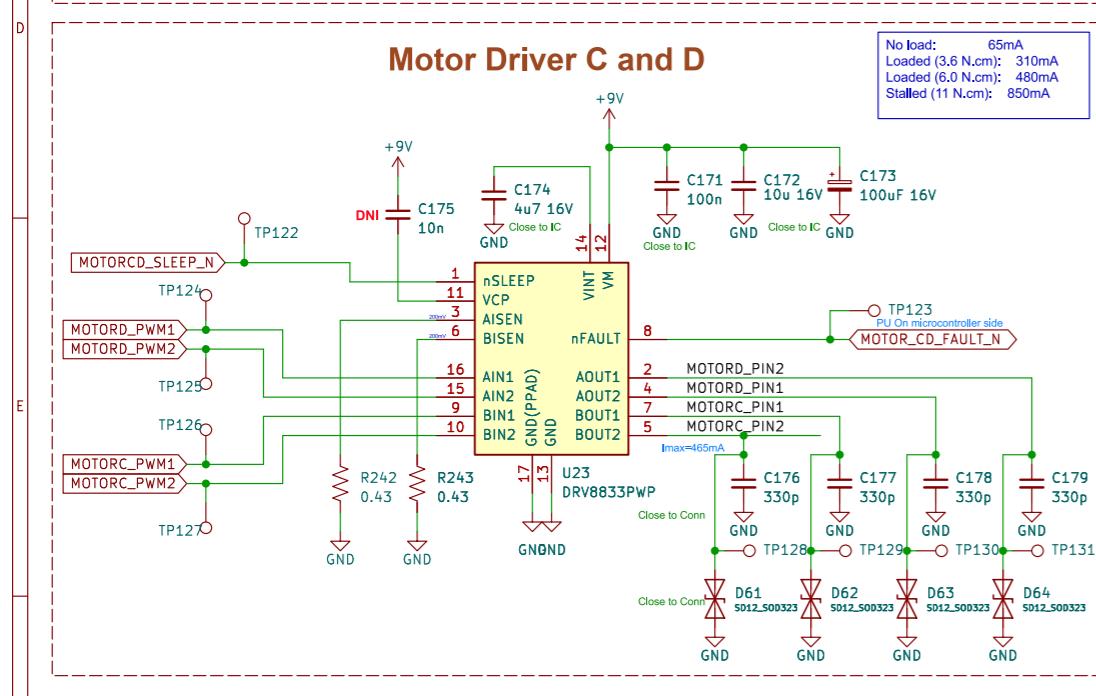
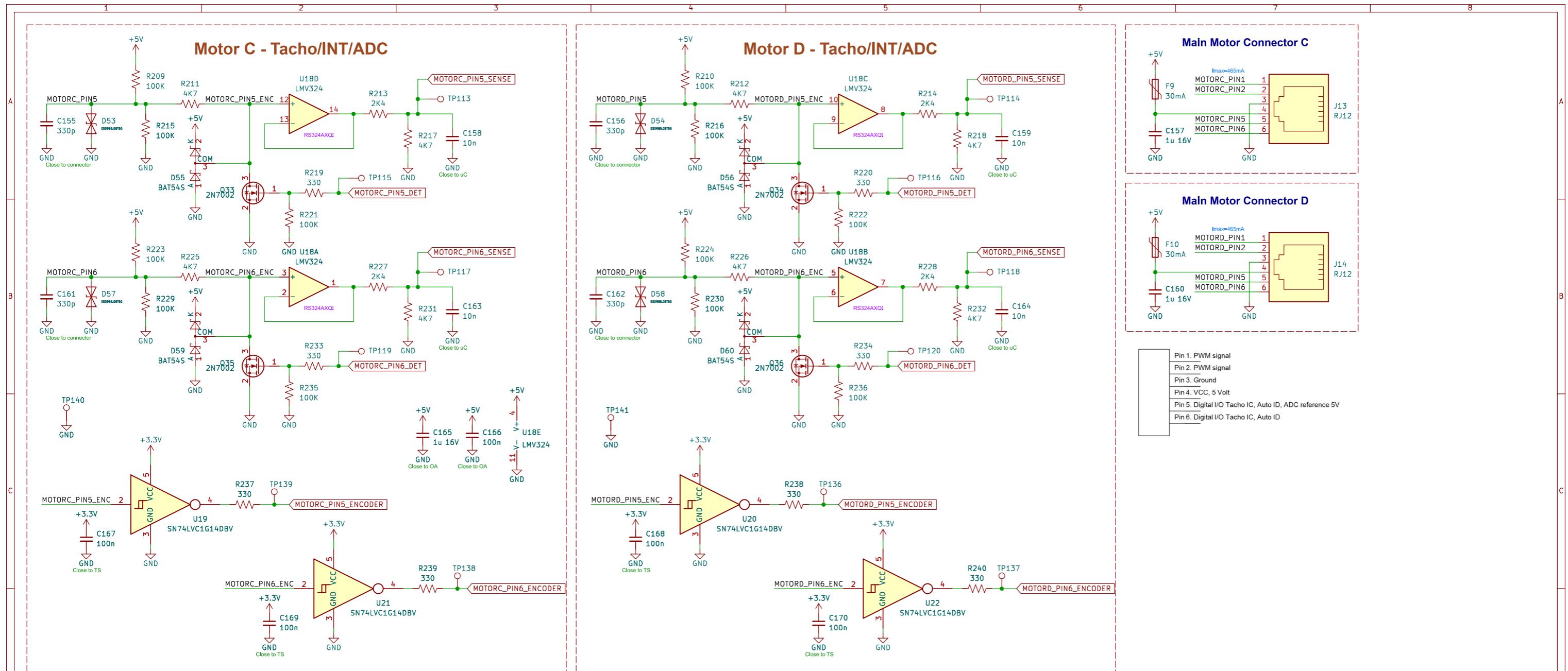
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Id: 4/7







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Sheet: /06-System Outputs B/
File: 06-System Outputs B.kicad_sch

Title: System Outputs

Size: A3 Date: 2023-02-22
KiCad E.D.A. kicad (7.0.0)



Rev: REV A
Id: 7/7