## PeaPod - Design Proposal

Outlining a Proposal to the PeaPod Design Brief

Jayden Lefebvre - Lead Engineer jayden.lefebvre@mail.utoronto.ca

Nathan Chareunsouk, Navin Vanderwert, Chris Lansdale - Design Engineers

Revision 0.2 University of Toronto Agritech June 4th, 2021

# Contents

1	Introduction			
	1.1	Purpos	se	. 2
2	Design			
	2.1	Autom	nation	. 4
	2.2	Isolatio	on/Insulation and Housing	. 5
	2.3	Aerope	onics	. 6
	2.4	Enviro	onment Control	. 6
		2.4.1	Air Temperature	. 6
		2.4.2	Air Humidification	. 7
		2.4.3	Air Dehumidification	. 7
		2.4.4	Solution Temperature	. 7
		2.4.5	Solution Nutrients	. 7
		2.4.6	Solution pH	. 7
		2.4.7	Lighting	. 8

# 1 Introduction

## 1.1 Purpose

The purpose of this document is to outline the fuction and features of a proposal to the PeaPod Design Brief.

It accomplishes this by answering the following questions on a recursively-scoping basis:

- 1. **What** is the design? What does it accomplish/what is its function?
- 2. **How** does it accomplish this? What are its features?
- 3. **Why** that functionality? Why that way?

# 2 Design

Functions of the design are derived from the input and output requirements.

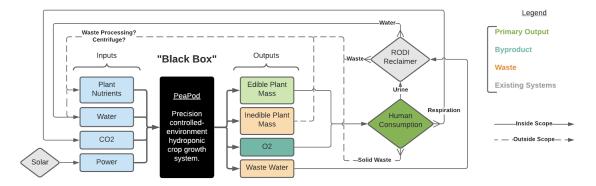


Figure 1: "Black box" input-output model of PeaPod.

Features of the design are developed to meet the function, and are derived from the opportunity statement:

PeaPod is "an <u>automated</u> and <u>isolated aeroponic</u> crop growth system, able to generate any <u>growth</u> <u>environment</u> from a combination of independent <u>environment parameters</u>, with both environment and crop growth <u>data collection</u>".

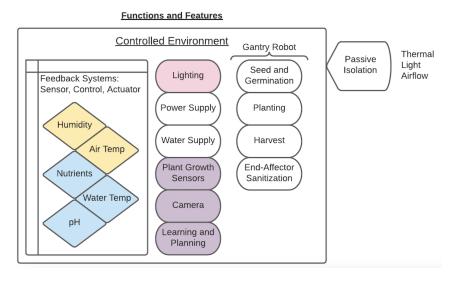


Figure 2: Features and feature types of PeaPod.

## 2.1 Automation

**What**: Performing growth-, maintenance-, and data-related tasks autonomously on the basis of both schedule and necessity.

## How:

- Schedule:
  - User inputs time/action pairs;
  - E.g. Water at 08:00, Turn light to setting X at 14:00;
  - Bonus: Can notify user if action's resource is missing (i.e. water tank low)
- Necessity:
  - "Sense, Plan, Act" robotics/control model:
    - 1. Senses current conditions;
    - 2. Plans a path to desired condition;
    - 3. Acts to change current condition to desired condition;

**Why**: Increased accuracy/precision over human interference, minimize human hours spent.

## 2.2 Isolation/Insulation and Housing

**What**: Isolates growth environment from exterior environment, provides structural integrity and mounting points.

**How**: Cube exoskeleton (aluminum extrusion) holds solid (acrylic/foam/corrugated board), internally-reflective (mylar) panels in place and aids in mounting plant growth platforms, lights, etc.

#### • Isolation:

- Heat Held in by mylar, blocked out by solid insulation via panels;
- Light Blocked out by panels, reflected in by mylar;
- Moisture Retained by caulking/other sealing around panels;

## • Mounting:

- Growth trays Mounted to rails fastened to aluminum extrusion channels;
- Lights Many boards mounted to sheet fastened to aluminum extrusion channels;
- Nozzles Mounted to inside-bottom face of growth tray;
- Sensors Mounted to various points (per-sensor), often fastened to aluminum extrusion channels;

**Why**: Increases thermal and light efficiency. Isolation increases safety against cross-contamination, pathogens, harmful substances. Simple and strong construction with dedicated mounting channels.

## 2.3 Aeroponics

**What**: Medium-free growing method that uses nutrients dissolved within atomized water.

**How**: High-pressure nozzles deliver atomized nutrient solution to plant roots. Uses parallel distribution topology.

- Pump fills tank with water that has nutrients dissolved within
- Tank uses an air bladder to hold water at desired PSI
- Switch checks line pressure and activates/deactivates pump to maintain PSI
- Solenoid ball valve feeds water to nozzle
- Nozzle atomizes water to ≈50 micron droplets
- T-quick connects with solenoid ball valves at every unit height feed individual trays

**Why**: No water parameter feedback, 98% more water efficient, minimizes pathogens and waste water.

## 2.4 Environment Control

The environment control feature can be broken up into **control systems** (2.4.1-2.4.3; sometimes in two parts) and **set systems** (2.4.4-2.4.7).

## 2.4.1 Air Temperature

**What**: Maintaining desired air temperature within the enclosure.

**How**: Thermoelectric heating/cooling system (peltier tiles w/ polarity switch, 'dimming' current control, PID) on a heat sink w/ fan, feedback from distributed temp sensors

**Why**: TECs have better space and energy efficiency, less complexity (no liquids, pressurized fluids, etc.), better control vs other methods. PID provides best control.

## 2.4.2 Air Humidification

**What**: Adding water vapour to air.

How: Ultrasonic nebulizer (piezo disc w/ custom driver circuit), RO water.

**Why**: Piezo for droplet size, commonly used; RO for purity of water vapour.

#### 2.4.3 Air Dehumidification

**What**: Absorbs water vapour from the air.

**How**: Silica gel bead cartridges with fans/valves to control airflow across.

**Why**: Non-toxic, safe, cheap, effective. Color-changing indication at saturation, easily reset by baking and recapturing water.

#### 2.4.4 Solution Temperature

**What**: Maintaining desired water temperature within the water store.

**How**: Same as 2.4.1; on a water block.

**Why**: Same as 2.4.1.

#### 2.4.5 Solution Nutrients

**What**: Precisely dosing the correct amount of various nutrients ( $K^+$ ,  $NO_3^-$ , etc.) to the water system at setup/water addition.

**How**: Syringe-like dosage via servo motor to set ppm based on fill volume.

**Why**: Syringe dosage is precise, easy to refill.

## 2.4.6 Solution pH

**What**: Precisely adds pH up/down solutions to set the solution pH at setup/water addition.

**How**: Same as 2.4.5.

**Why**: Same as 2.4.5.

## 2.4.7 Lighting

What: Wide spectrum precision LED lighting targeting PAR.

**How**: N LED series/colors, N controlled-current PWM drivers, M LEDs per series = NxM LEDs. Custom LED boards wired in series, one power board per tray, w/ diffusion.

**Why**: LED > every other type in every way, PWM easy protocol, CC because they're LEDs.