

DMTF Application Modeling and Extensions for Behavior

Karl Schopmeyer

k.schopmeyer@opengroup.org

Presentation for GGF12 CIM GS sessions

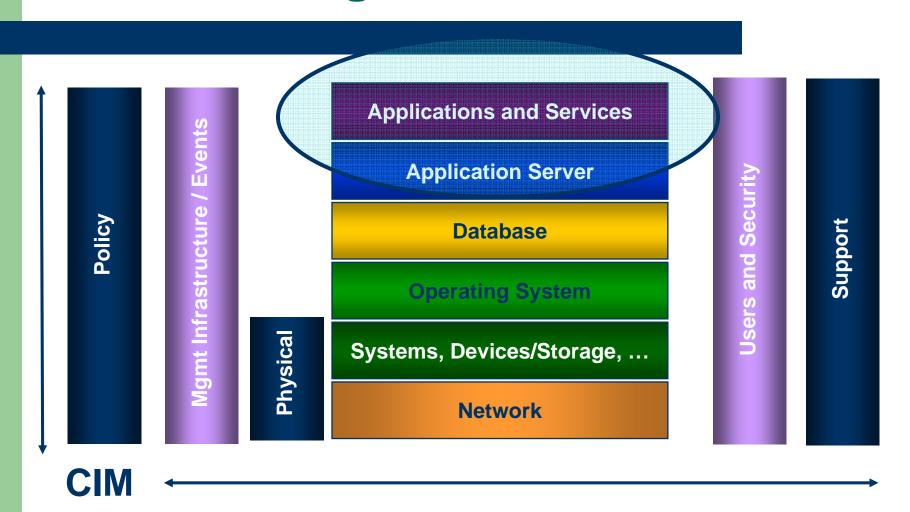


Subjects

- Overview of DMTF / Open Group work in Applications Management
- New Work, Modeling Behavior and State Management in DMTF



CIM's Coverage





Application Management Modeling Overview

- Characteristics of an Application Management Model
 - Lifecycle management
 - Definition, Deployment, Installation, Configuration, Execution Control
 - Runtime management
 - Performance management, Service Level (QOS) management Problem Management, fault analysis, etc.
 - Inventory Management
 - ...
- Contributing Management Information to the next Higher layer
 - Business Process Management
 - Service Level Management



Goals

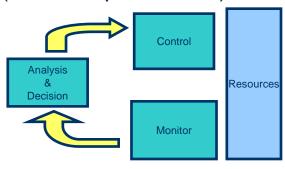
- Management of wide range of applications
 - Distributed
 - Dynamic
 - Multicomponent
 - Large-scale
- Active management of applications as services
 - Not just Monitoring
 - Active, adaptive management



Model Components that Come Together for Application Management

Managing The Application

- Lifecycle (Deployment, Installation, Configuration, Execute)
- Runtime (modeling the runtime structure, managing performance, Service Levels, fault determinations, ...)
- Measuring Application Traffic Flow
 - Metrics, Unit of Work (UOW), ARM API
- Automation
 - From monitoring to management
 - From management to adaptive management (service optimization)
 - Policy
 - Service Levels, Quality of Service





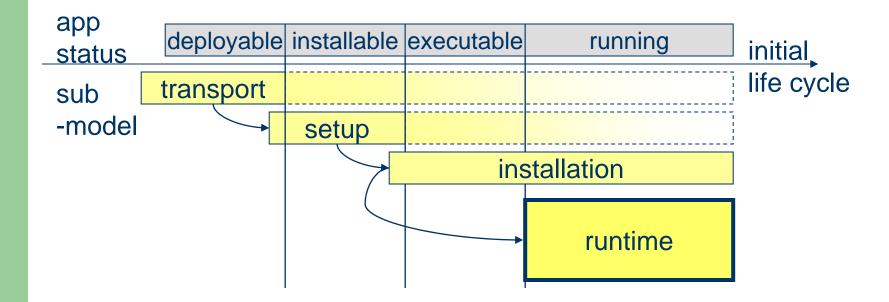
The Applicable DMTF Groups

- Application Work Group
 - Runtime Model
 - Lifecycle Model
 - J2EE JSR 77 Model
 - Metrics
 - Unit of Work
- Database Work Group
 - Database model
- Policy and SLA Work Group
 - Policies



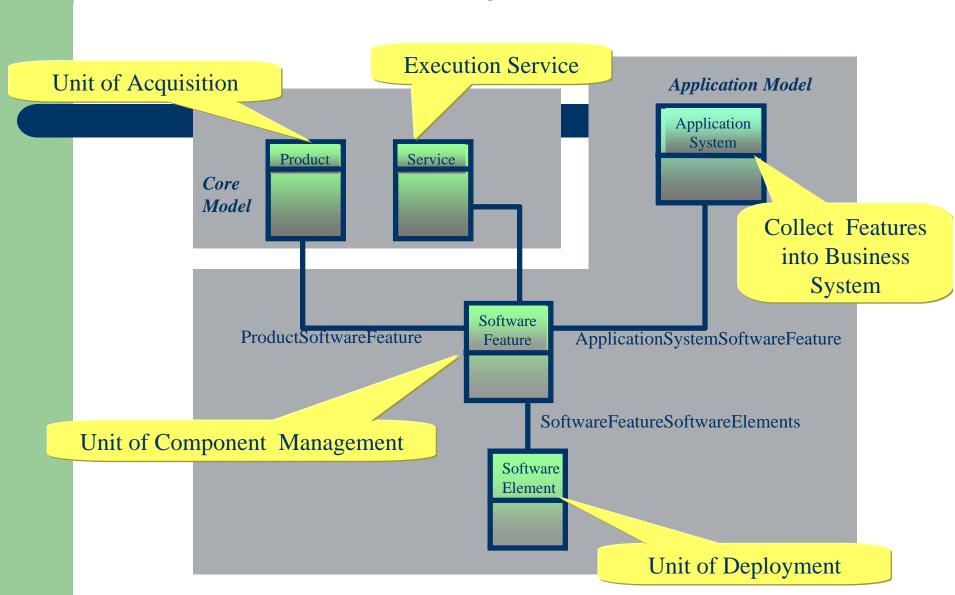
Application Management

- Lifecycle Model
- Runtime Model





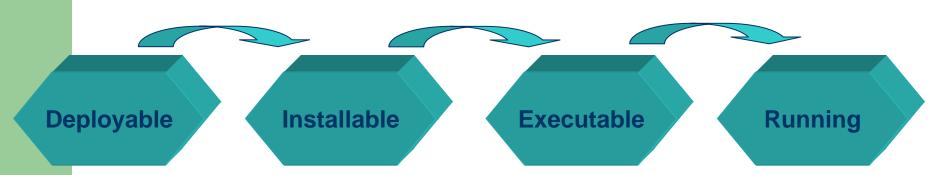
Lifecycle Model Overview





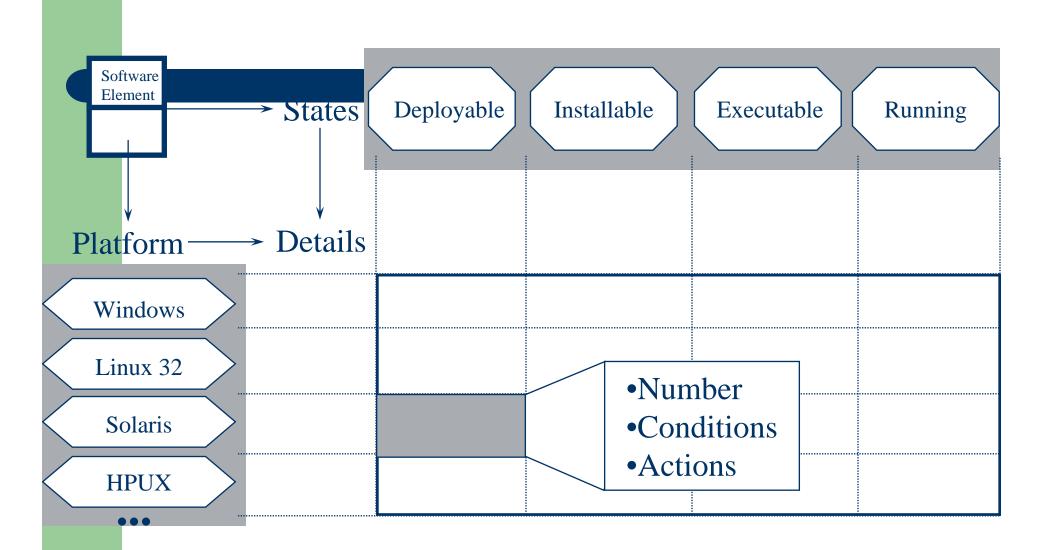
Application Life Cycle

- Critical states in process of transition from development to operational
- Applies to lowest-level component
 - Software Elements
- States



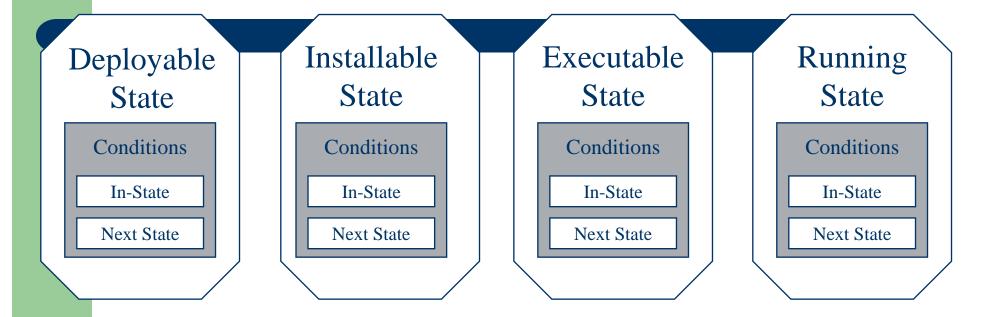


Refining Software Element





Software Element Conditions



Conditions are situations that are expect to exist or not exist in an environment

In-State Conditions are characteristics of an environment that contains an element

Next-State Conditions are characteristics that need to be true in the target environment for the next state of a software element.

DMTF

Software Element Conditions

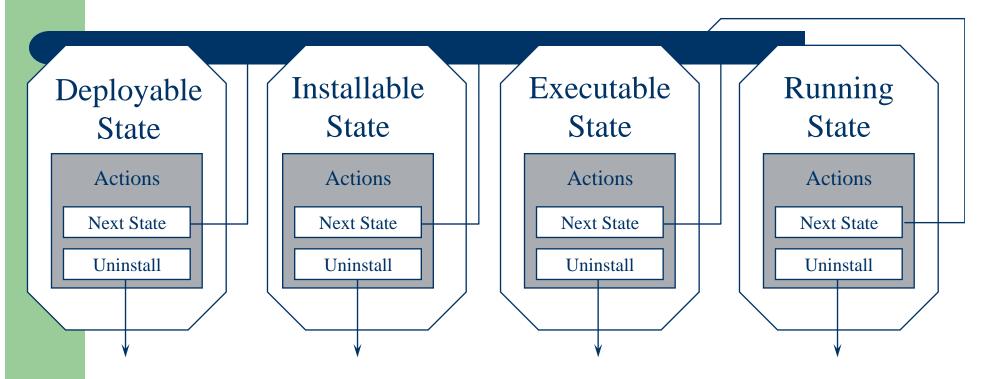
Coi	ndition	In-State Interpretation	Next-State Interpretation
	mory quirements	Minimum Amount of memory required to transition into the <i>current</i> state.	Minimum amount of memory required to transition into the <i>next</i> state
Dis	k Space	Minimum amount of disk space required to transition into the <i>current</i> state.	Minimum amount of disk space required to transition into the <i>next</i> state.
Swa	ap Space	Minimum amount of swap space required to transition into the <i>current</i> state.	Minimum amount of swap space required to transition into the <i>next</i> state.



Software Element Conditions

Condition	In-State Interpretation	Next-State Interpretation	
Architecture	The architecture required by a software element in the current state.	The architecture required by the software element to transition into the <i>next</i> state.	
Files	A file that is expect to exist or not exist when a software element is in the <i>current</i> state.	-	
Directories	A directory that is expect to exist or not exist when a software element is in the <i>current</i> state.	A directory this is expect to exist or not exist before a software element transitions into the <i>next</i> state.	
OS Version	The version or ranges of versions a software element requires in its <i>current</i> state.	The version or ranges of versions a software element elements requires before it transitions into the <i>next</i> state.	
Software Elements	A software element that is expect to exist or not exist when a software element is in the <i>current</i> state.	A software element that is expect to exist or not exist before a software element transitions into the <i>next</i> state.	

Software Element Actions



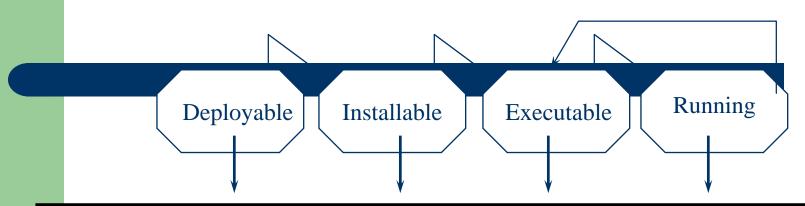
Actions are a sequence of operations

Next State Actions create a software element in a particular state.

Uninstall Actions properly remove a software element



Software Element Actions



A	ctions	Description	
Γ	Directory	An action to create or remove a directory.	
F	ile	An action to create or remove a file.	
F	Re-boot	An action the signals the need to reboot the computer system.	
	Execute Program	An action that execute a program. This can be the install script or program (e.g., setup.exe) when a software element in the installable state transitions to the executable state.	



Application Management and SLAs

- The Business issue is providing services, not just the applications.
- SLAs are the contractual/agreement model for service level
- SLOs(service Level Objectives) are the service goals required to satisfy SLAs.
- Both the systems and the applications are part of the service level determination



Application Management and SLAs

- Typical runtime service level parameters
 - User perspective on performance
 - Interactive responsiveness
 - Transaction Response time / Time to accomplish
 - Throughput / How many simultaneous users or how many things can be done in a defined time
 - Batch turnaround
 - Critical deadlines (e.g. end-of-month processing)
 - Availability
 - Percentage of time service is available
 - Maximum limits on service-down times
- Other non-runtime SLA issues
 - Recoverability
 - Data Integrity
 - Problem responsiveness
 - Affordability



Goals of Application Measurement

- Provide Monitors for
 - Service Level management
 - Need information and controls so that analysis can be done and decisions made and implemented
 - Business and Business Process management
- Provide Application Controls for
 - Fault Determination
 - Performance characteristic attribution
 - Application monitor, management and manipulation in terms of application components, aggregation into whole to support SLOs



OR

- Monitor to provide information for SLA reporting
- Provide controls for SLA tuning
- Provide means to find why not meeting SLAs

It is not enough to know you have a problem if you do not know why or how to solve the problem.

It is even more worthless to have a means for defining SLAsAnd SLOs and no means to measure them on the system.



What are Applications?

- Complex collections of software components
- Multilayered functionally
 - E.g. Presentation, application, database, etc.
- Dynamically assembled
- GOALS of DMTF Runtime Management
 - Model the components as viewed in runtime including the interactions
 - Aggregate the information into the whole
 - Disaggregate information from whole into the components



Application Runtime Manageability Requirements

- Define logical runtime structure of complex applications
- Define Application components/layers
- Support distributed and dynamic applications
- Relate physical structures and logical runtime structures
- Model usage of system resources as viewed by the application
- Model dataflow between components and applications and between applications
- Relate Unit of Work information to runtime structure
- Allow monitor and control of application state
- Support fault management
- Aggregate information from components to the whole

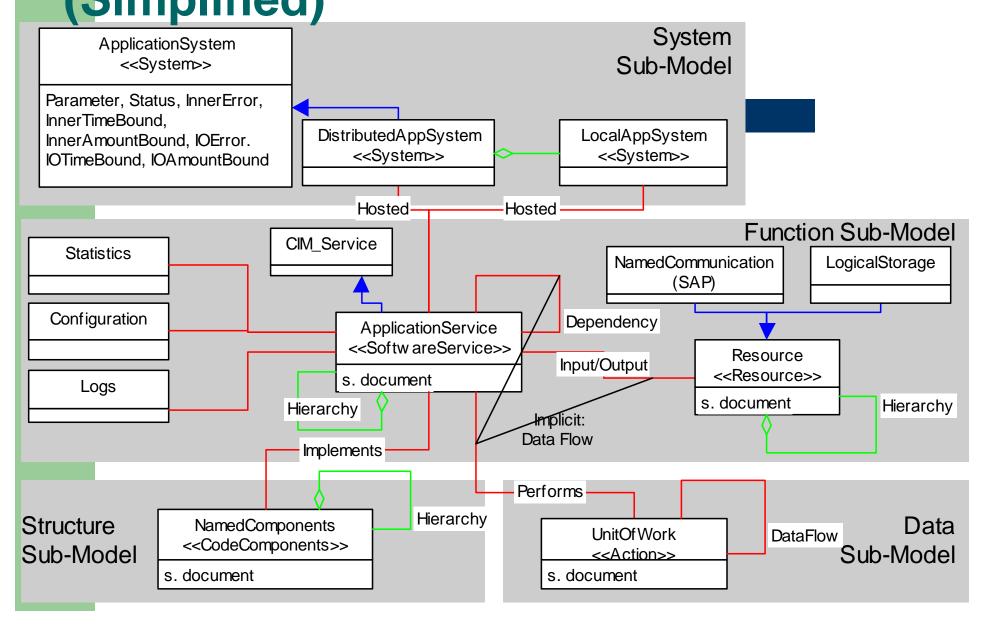


Modeling FCAPS

- Fault
 - Indications
 - Error and status properties (counter, information)
 - Log-entries, traces, etc.
- Performance
 - Base metrics (IO, timebound metrics, etc.)
 - UoW
 - Metric properties
 - Statistics
- Configuration
 - Persistent configuration information: configuration, settings
 - Control: methods
 - Current configuration: object properties, support classes, associations

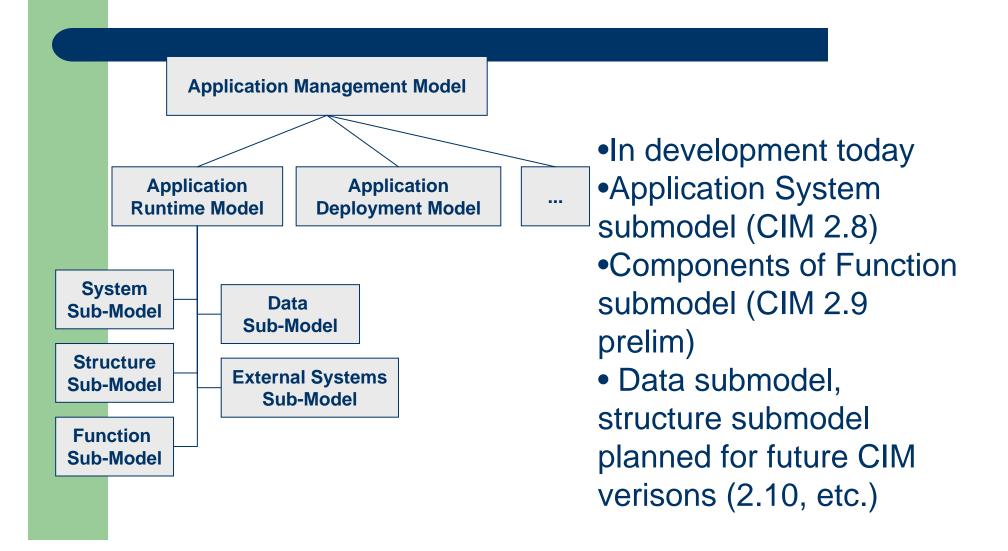


App Runtime Model Concepts (Simplified)





Application Model Hierarchy





Measuring Traffic Service

Goals

- Identify and measure traffic characteristics (response time, metric information associated with the traffic, etc.)
- DMTF Unit of Work(UOW)
 - Model dedicated to the concept of modeling time intervals
- Open Group ARM
 - API dedicated to instrumenting for measurement of time intervals.



APPL

APPLICATION

Modeling The Transaction - UOW

- Measure a time interval
- Identify the transaction
- Identify the application
- Provides information for correlation of multiple measurements
- Provides information to understand component UofWork (parent/child units of work)
- Provides metric information places for resource, etc. information
- Marry with the instrumentation technology ARM



Unit of Work

- Defines a type of work
- Represents a UOW that has started and may have completed executing
- Associated to a UOW definition
- Provides information such as:
 - Response or elapsed time
 - Status
 - Active, Suspended, Completed (with status), Aborted
 - Metric Information about the UOW
- Examples
 - Update account balance
 - Execute batch
 - Query Data server
 - Execute subroutine



Status

UOW model

- Model Developed by DMTF Application Work Group
- Corresponds today to ARM 1, 2, 3
- Working on ARM 4 equivalent model

ARM

- ARM API for C and Java today (Open Group Standard
- Version 4 extend model to more useful metrics, correlation.

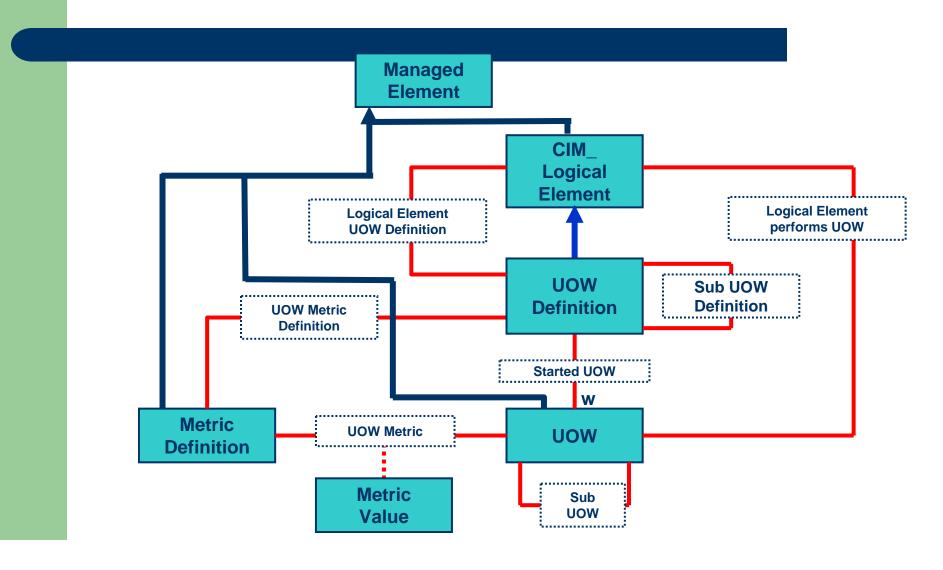


Metrics Model

- Capture dynamic metric information
- Provide means to do predefine structuring and organization of the data
 - Time series
 - Computation such as summing, averaging, etc.



Metrics and UOW model





Other DMTF Work

- Service Level Agreements and Service Level Objectives
- Policy



Modeling Behavior

 Behavior and State, Extending CIM to Behavioral Control



CIM includes Behavior Today

- The model includes methods which represent behavior(ex. Start(), Stop())
- Some specific classes (ex. application model) have been able to model specific behaviorial characteristics (Deployment states and checks and actions classes.



BUT

- Cannot define behavioral interactions between classes
 - Change to instance of class A causes creation of instance of Class b and an association to be established between A and B.
- Cannot impose behavioral control on instances
 - Ex. Accept this method only when this property set.
 - Model cannot define when a Start() method should be allowed



Modeling Behavior and State

The Issues

- Today CIM is an Information model
- CIM Information plus model behavior = manageability model

Objectives

- Allow states and state control on CIM Classes
- Define inter-object Actions
- Define state transitions that that invoke actions



Growth of the Information model to a Management model

Managed Services

From Information model
To information and behavior
model

Management Services

Managed Services

Model

Manageability Model Managed Services Model (tomorrow)

Manageability Objects (Today)



Requirements for Behavioral Control

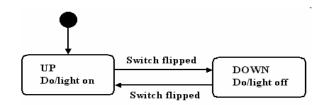
- Define state for CIM Objects
- Define state transitions so that object owners can control state changes
- Define inputs that can control states
- Define Actions that affect other parts of the model
- Provide concepts for hiearchial aggregation and disaggregation of state



A Very Simple Example

A Light Switch Example

- Two states
- One flip switch for control
- Transition Diagram



State Table

State /	Down	Up
Input		
Flip Switch	Up/Do Light on	Down/Do Light off



Example (Cont)

```
light
{
    String instanceID;

    [valuemap("0", "1"),
    values("on", "off")]
    Uint16 state = 0;

    Uint32 flip();
}
```

TODAY

- Not clear what is a state variable
- •Model does not define relation between method and state property.

```
State Transition Matris
light
                                      State /
                                                Down
                                                          Up
                                      Input
    String instanceID;
                                                Up/Do
                                                          Down/Do
                                      Flip
                                                Light on
                                                          Light off
                                      Switch
      [State(pointer),
      valuemap("0", "1"),
      values("on", "off")]
      Uint16 state = 0:
      Uint32 flip();
```

With Behavior Control

- •State clearly defined as state property and associated with a particular transition matrix
- •Clear behavior relation between method and state property



Example (cont)

CIM Client CIM Server

Light Provider

Light Resource

- Query state of light instances
- •Controls light with "flip" method

- •Set light to "initial state"
- •Accept "flip" method and control Light resource in accord with input.
- •Respond to flip with "good" response if state changed or "error" if it did not.
- •Respond to instance requests



Objectives of the Working Group

- Today CIM is an information model
- It does not allow managing behavior
 - Of objects
 - Between objects
- Objective
 - Define mechanisms that would allow behavior
 CIM objects and between objects to be defined.



Characteristics of a State Model

- Based on OMG UML StateDiagrams
- Able to generate CIM state definitions directly from UML tools



UML State Diagrams

- Hierarchical State Model
 - Hierarchical States (substate model)
 - State Transitions
- Based on event processing architecture
- Features
 - Guards
 - Entry and exit actions
 - Orthogonal Regions orthogonal regions detect the same events and respond to them "simultaneously"



Alternate definitions for State Transitions

- Language based Definition
- Extending the CIM MetaModel to include State, Transitions, Actions concepts
 - UML has an existing meta-model as a starting point
- Model State as instances of newly defined classes



```
List of method that
                         Class <MOName> {
                                                               can be used
                          actions ( « methodignored1 », ...,
                                                                                 Import a Package
                          import ( a Package.aPackageX.*; ) -
                          properties ( « prop1 », « prop 2 », ...) =
                                                                                                   List of properties for witch
 vei
                          the access right can be changed
                                 {« classe1:asso1:prop1 », « param1 »}-...);
              State
            Description
                                                                                      Declaration of
                          state <StateName> {
                                                                                      the parameters
                                                                  List of method
chai
                            ignore (« methodIgnored1 », ..);
                                                                    to ignored
                            on enter { do: an action; };
             5 types of
                            on exit { do: an action; };
                                                                                                       Action or Condition
  no
               event
                            on pre_invoke (« a methodId ») { do: an action; };
                                                                                                           description
              possible
                            on post invoke (« a methodld ») { do: an action; };
                            on exception ( « a methodld », « an exception ») { do: an action; }
                                                                                                             Condition or
                            access (« prop »,TYPE ACCESS );
                                                                                                           Synchronisation
          Definition of
          the access
                            transition («
                                             state Y ») {
          right
                              on at_event (a method , aji/mm/aaaa hh :mm: ss ) [, condition (.....) ] { do: an action; };
                              on call_event ( « a method » ) [, condition («java code returning a boolean ») ] { do: an action; } ;
             5 types of
                              on change_ event ( « Exp Bool en java » ) [, condition ( ... ) ] { do an action; } ;
              transition
                              on signal_ event ( « a Event_Type » [ , « propX =value1 »,... ] ) [, ★condition ( ... ) ] { do: an action; } ;
                              on time_ event ([«method »,] « durée» ) [, synchro ( « synchro StateName ») ] { do: an action; } ;
                event
               possible
                          } // fin de state
                                                                                                       Action or
                                                                                                      Condition
                           state_synchro <StateName> ( « tostateY » ) {
                                                                                                      description
                            loop ( laptime );
        Pseudo -state
                            condition ( { java code returning a boolean} );
         description
                            // then idem a normal state
                          } // fin de state_synchro
                            transition ( « fromstateX », « tostateY ») {condition ( « a condition » )} //compatibilité ascendante
```



Questions?









