

Indoor Positioning Using the OpenHPS Framework

Maxim Van de Wynckel, Beat Signer


*Web & Information Systems Engineering Lab
Vrije Universiteit Brussel*



What is OpenHPS?



An Open Source Hybrid Positioning System


OpenHPS

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[BLOG](#)
[GITHUB](#)

Documentation

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[Installation](#)
[Modules](#)

Basic Concepts

[Data Object](#)
[Data Frame](#)

Advanced Concepts

[Remote Service](#)
[Threading](#)

Miscellaneous

[Examples](#)

uid

timestamp

source

CameraObject

uid: "camera", position: { x: 2, y: 5, z: 3 }, projection: ..., width: 1280, height: 1024

Image

DataObject

Detected object

DataObject

Detected object

DataObject

Detected object

VideoDataFrame

uid

timestamp

source

DataObject

uid: "lmsensor", position: { x: 0, y: 0, linearVelocity: { x: 1, y: 0 } }

Acceleration

Sensor Frequency

IMUDataFrame

uid

timestamp

source

RFRceiverObject

uid: "wifiscanner", relativePositions: [{ obj: "AP1", distance: 5 }, { obj: "AP2", distance: 8 }]

AP1 DataObject

uid: "AP1", position: { x: 0, y: 0 }

AP2 DataObject

uid: "AP2", position: { x: 15, y: 3 }

RFDDataFrame

uid

timestamp

source

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uid: "camera", position: { x: 2, y: 5, z: 3 }, projection: ..., width: 1280, height: 1024

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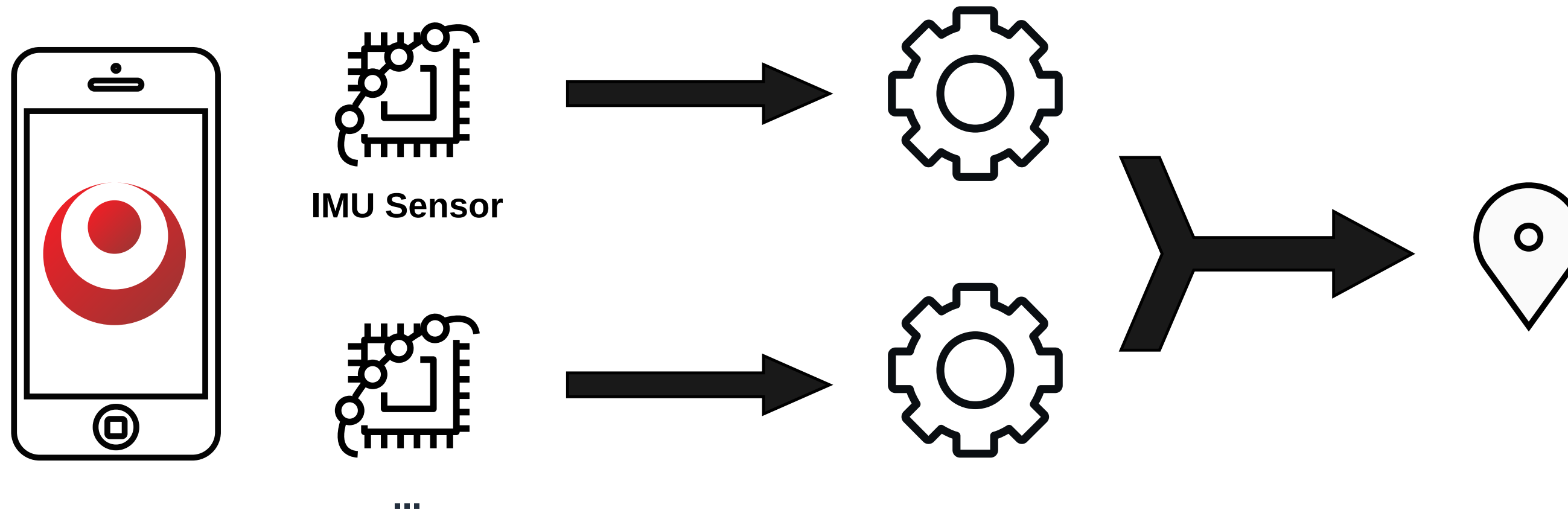
What is OpenHPS?



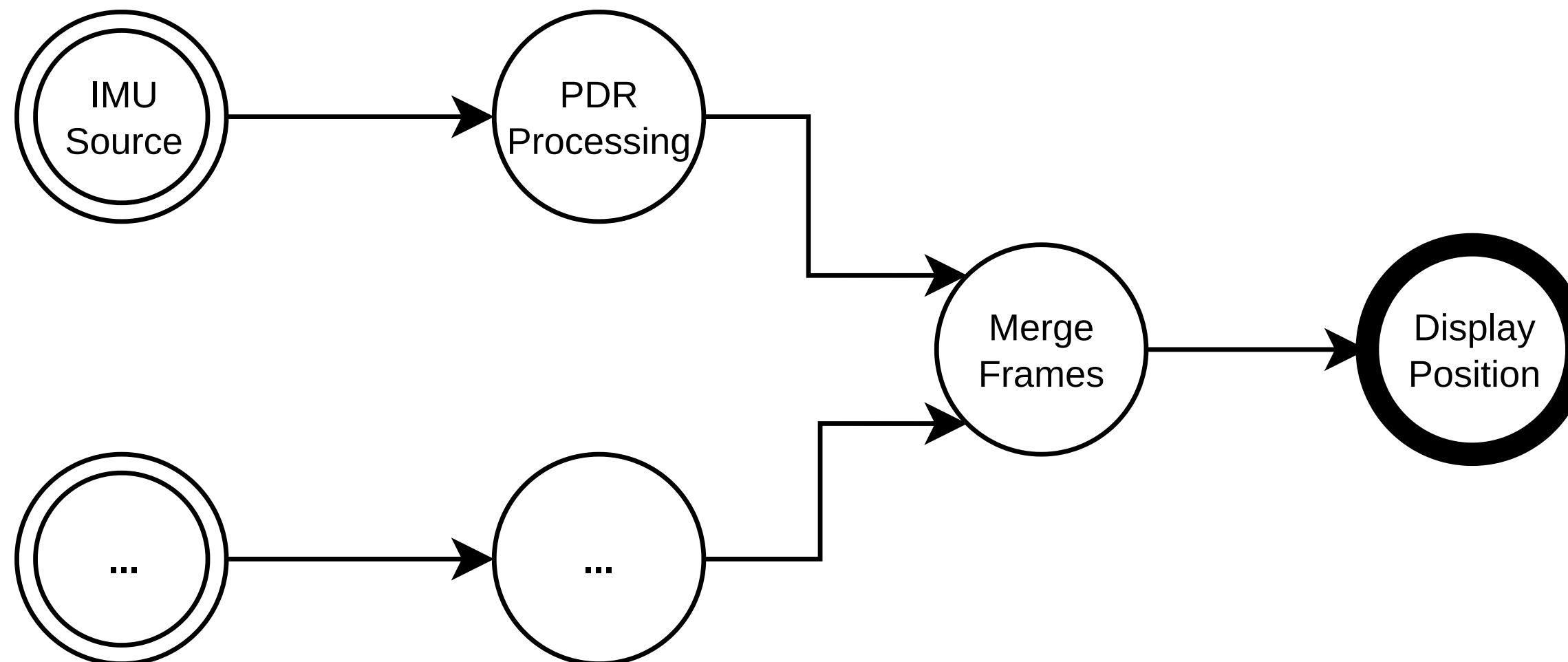
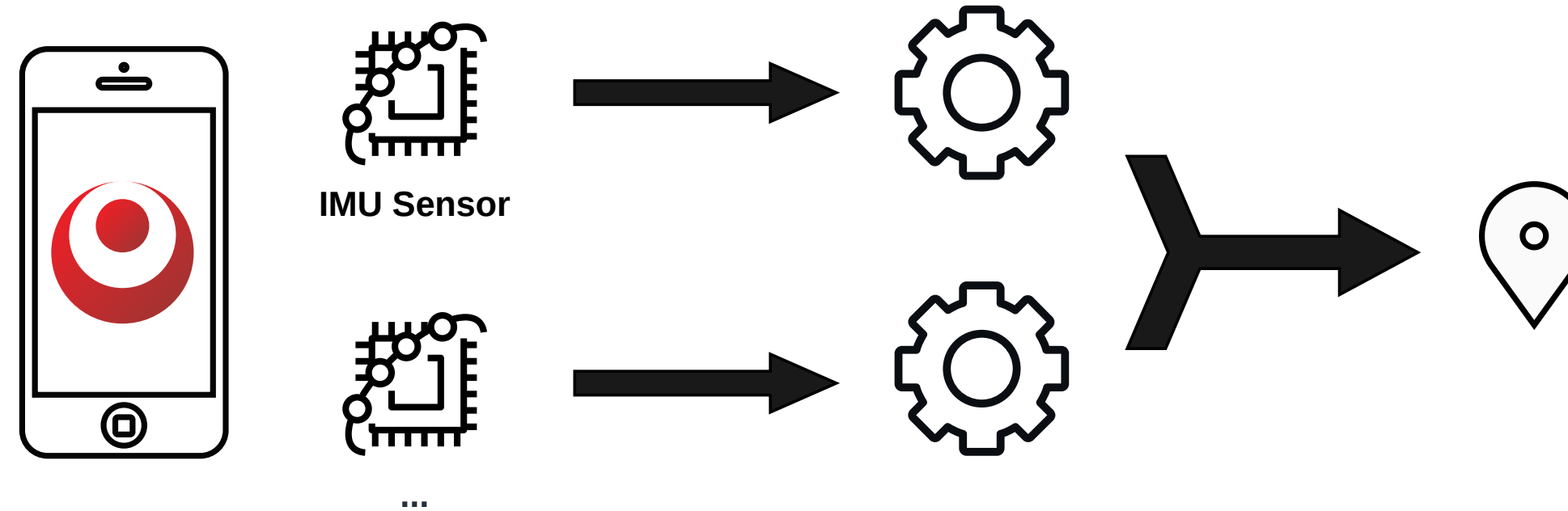
An Open Source Hybrid Positioning System

- ▶ Any technology
- ▶ Any algorithm
- ▶ Various use cases
- ▶ Flexible processing and output
 - Accuracy over battery consumption, reliability, ...
- ▶ Aimed towards
 - Developers
 - Researchers

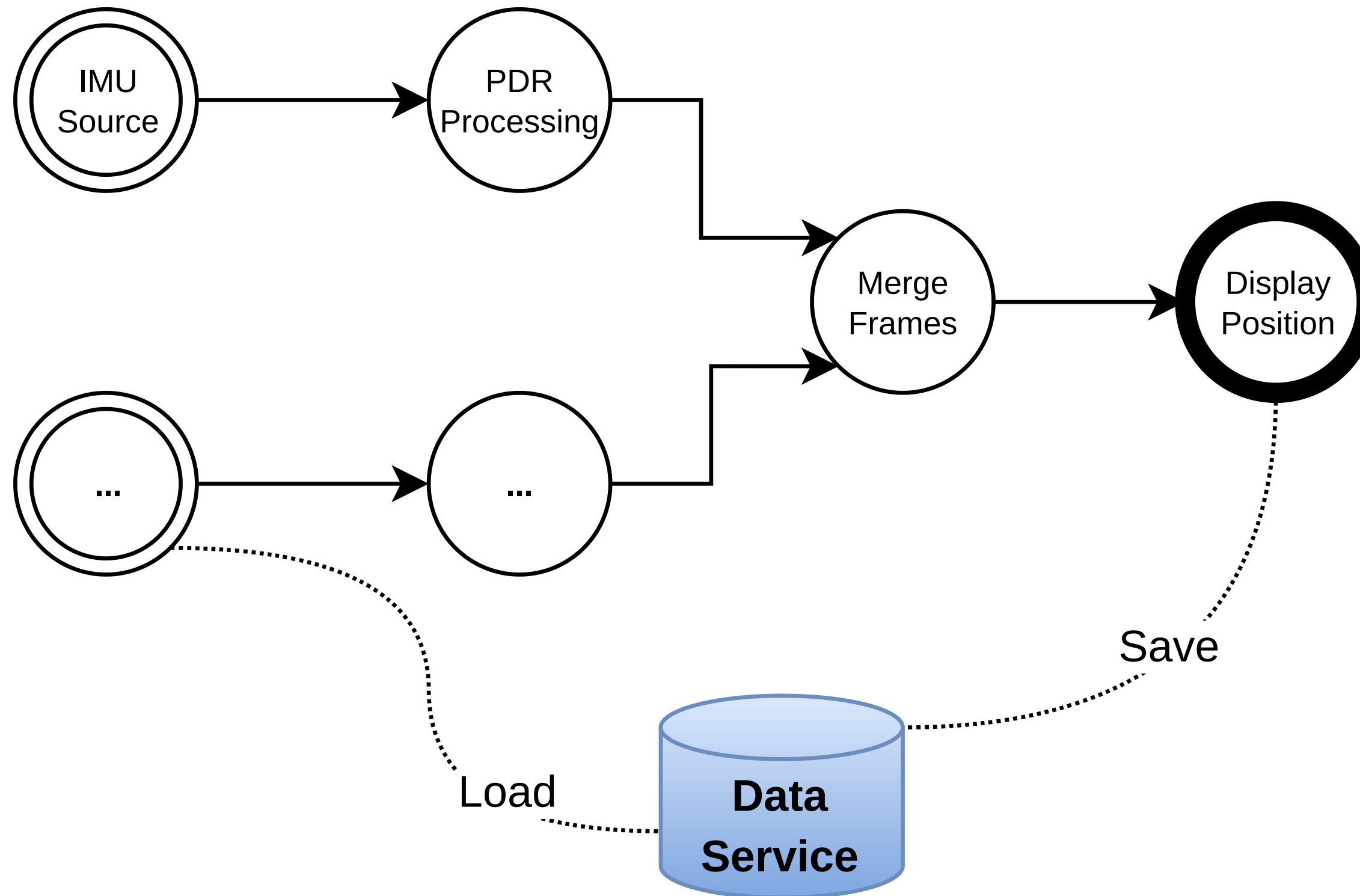
Process Network Design



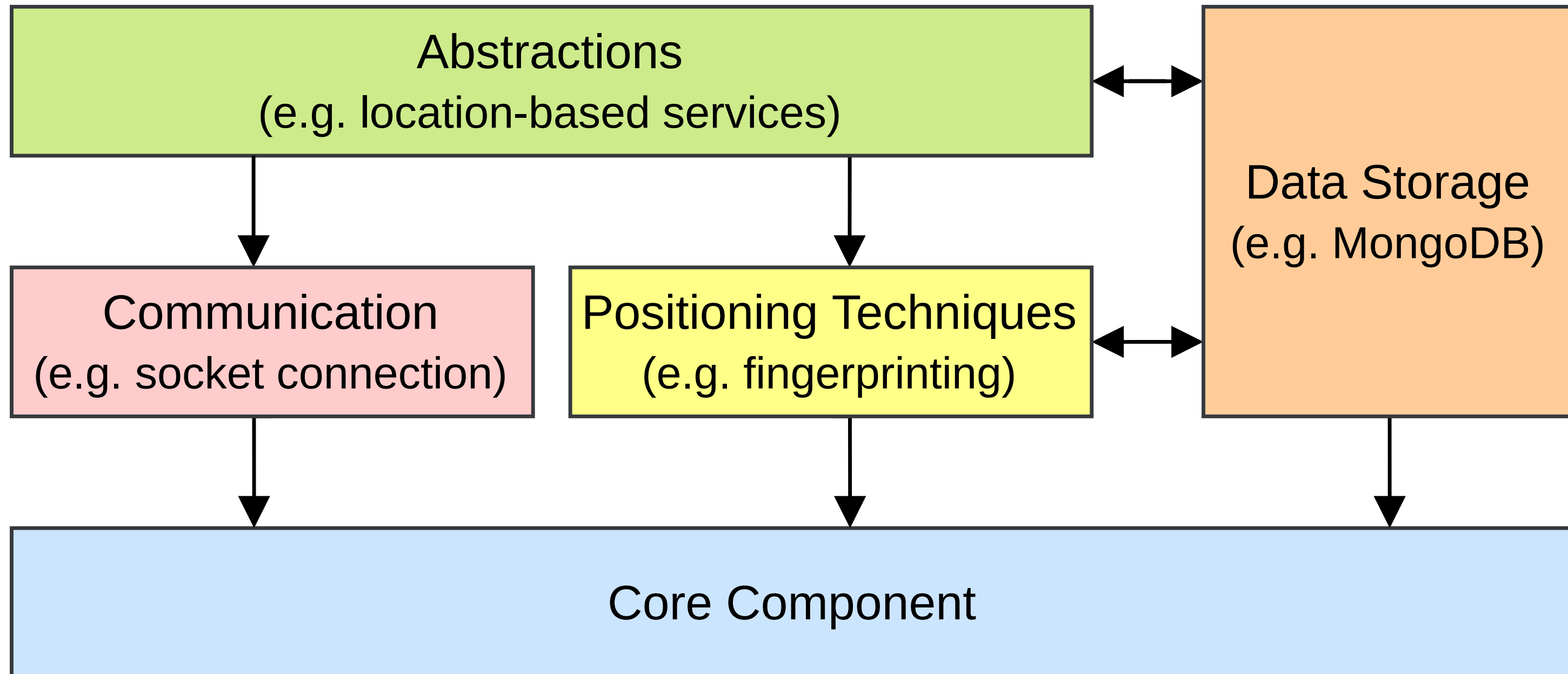
Process Network Design ...



Process Network Design ...



Modularity



Modularity ...

Communication

Socket, MQTT, REST API, ...

Data Storage

MongoDB, LocalStorage, RDF, ...

Positioning Algorithms

IMU, fingerprinting, OpenVSLAM, ...

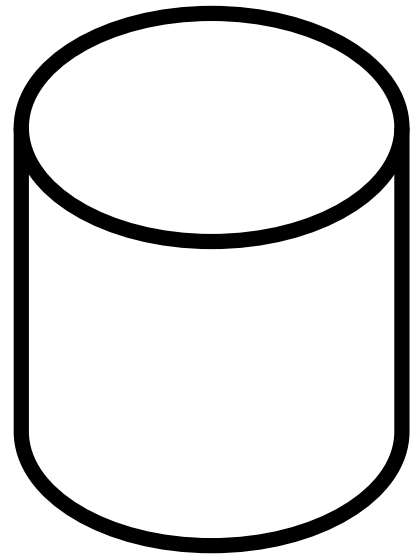
Abstractions

Geospatial, location-based services, geojson, ...

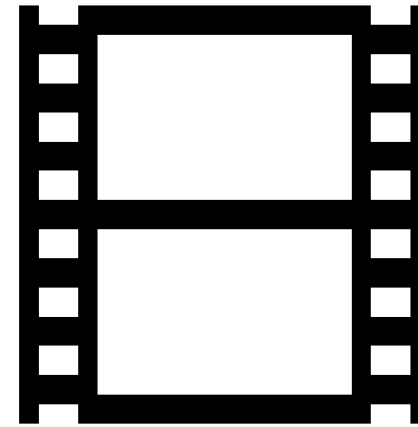
Other

React-Native, NativeScript, Sphero, ...

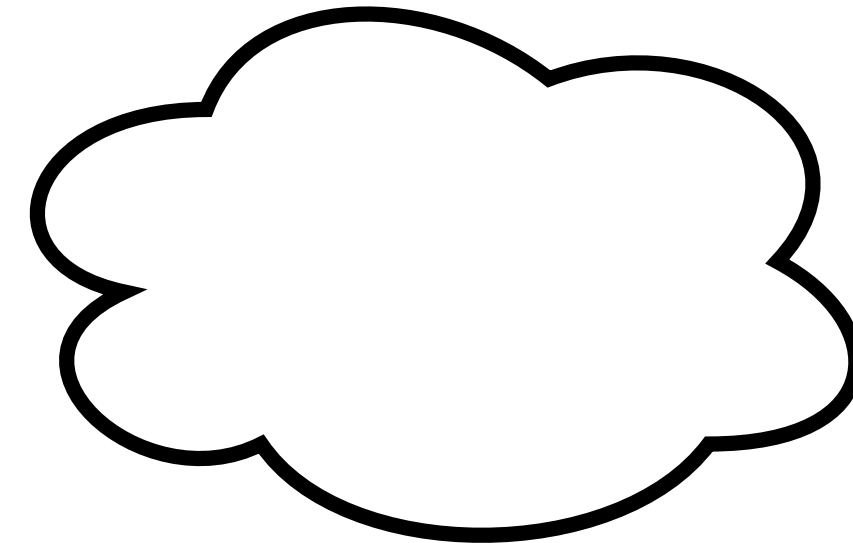
Data Processing



Knowledge

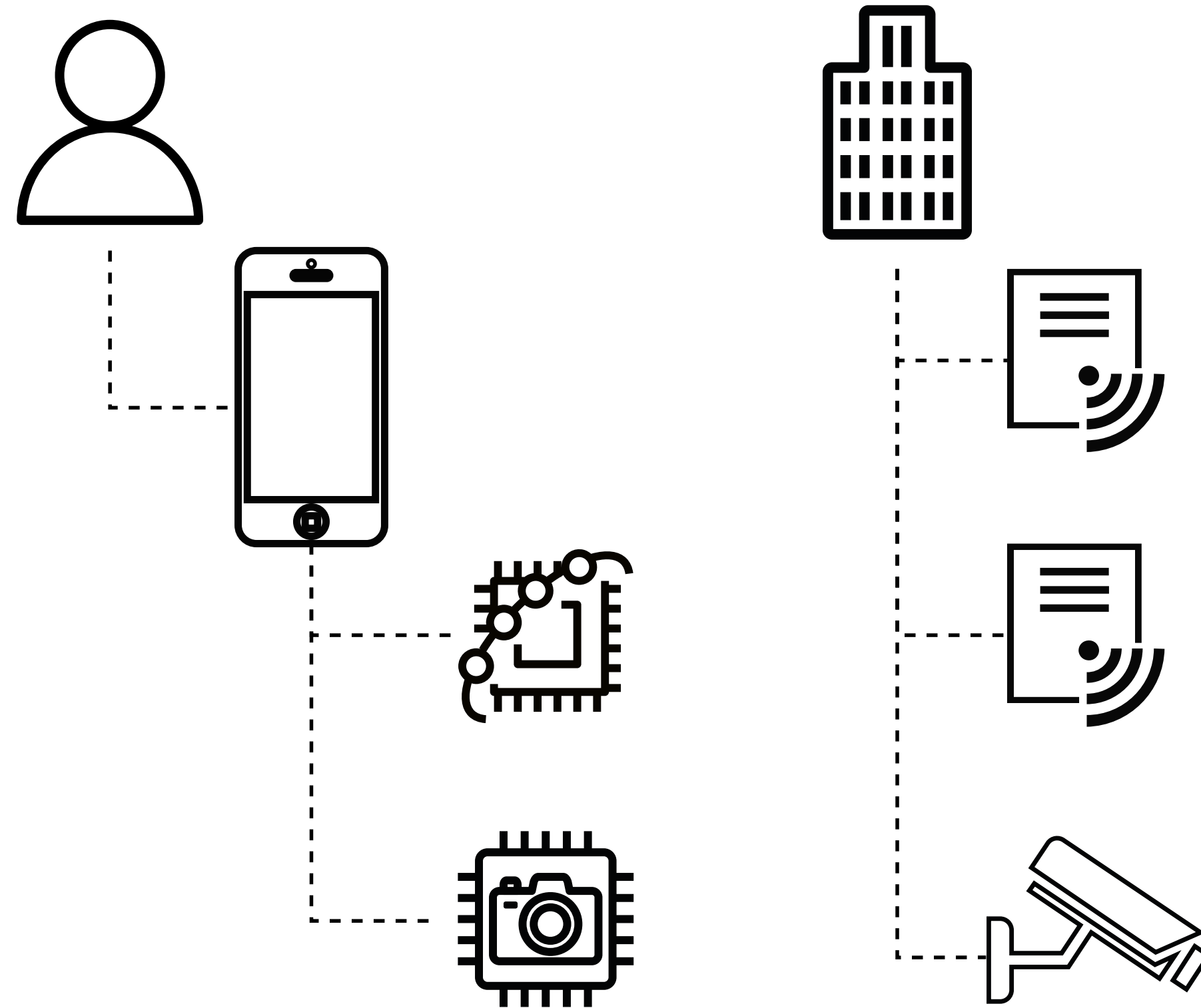


Raw Data



Processed Data

DataObject



Absolute and Relative Positions

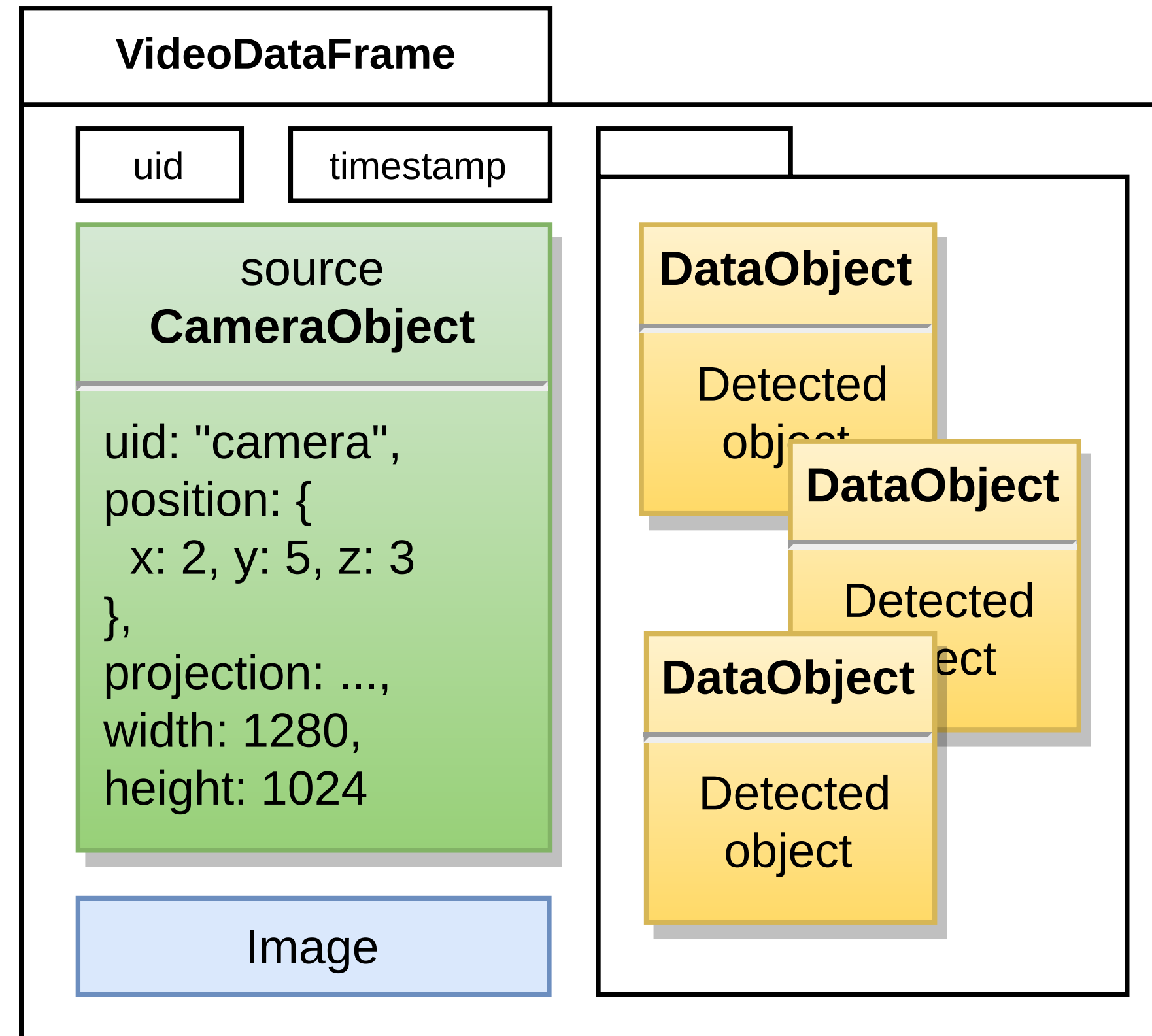
Absolute

- ▶ 2D, 3D, Geographical, ...

Relative

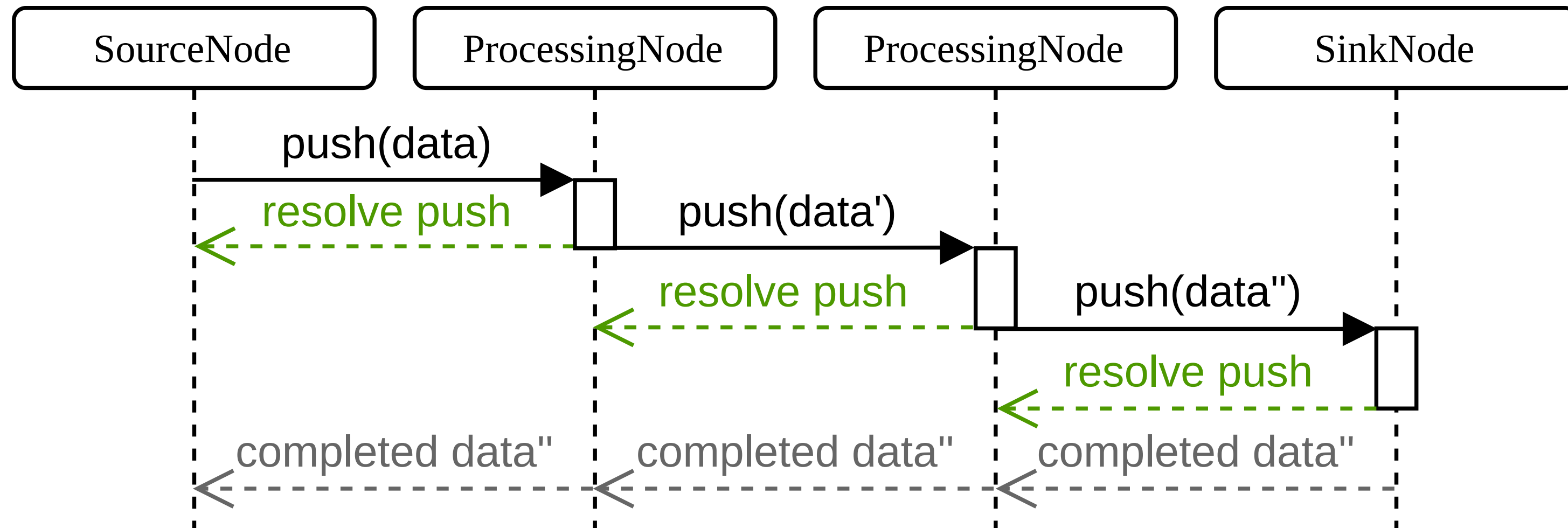
- ▶ Distance, angle, velocity, ...
- ▶ Relative to another *object*

DataFrame



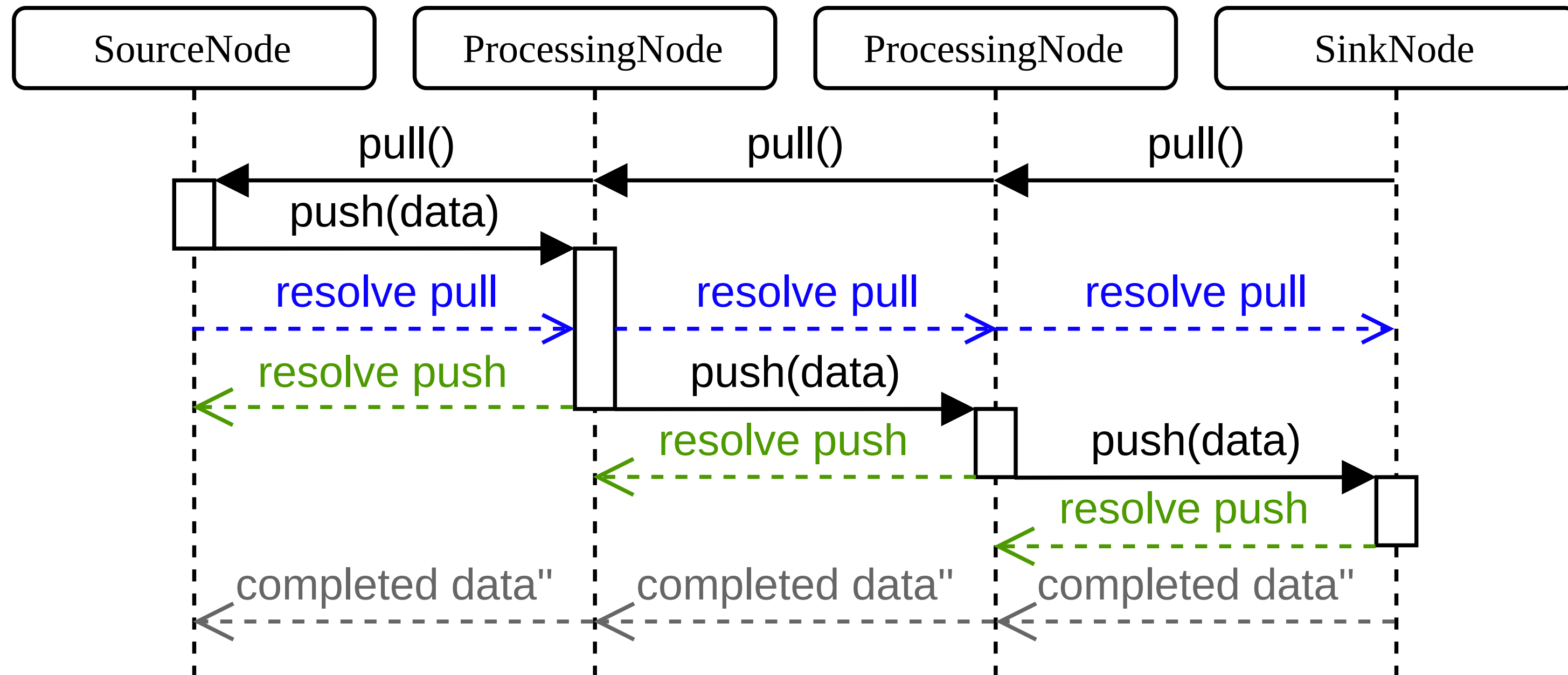
DataFrame ...

Pushing Data



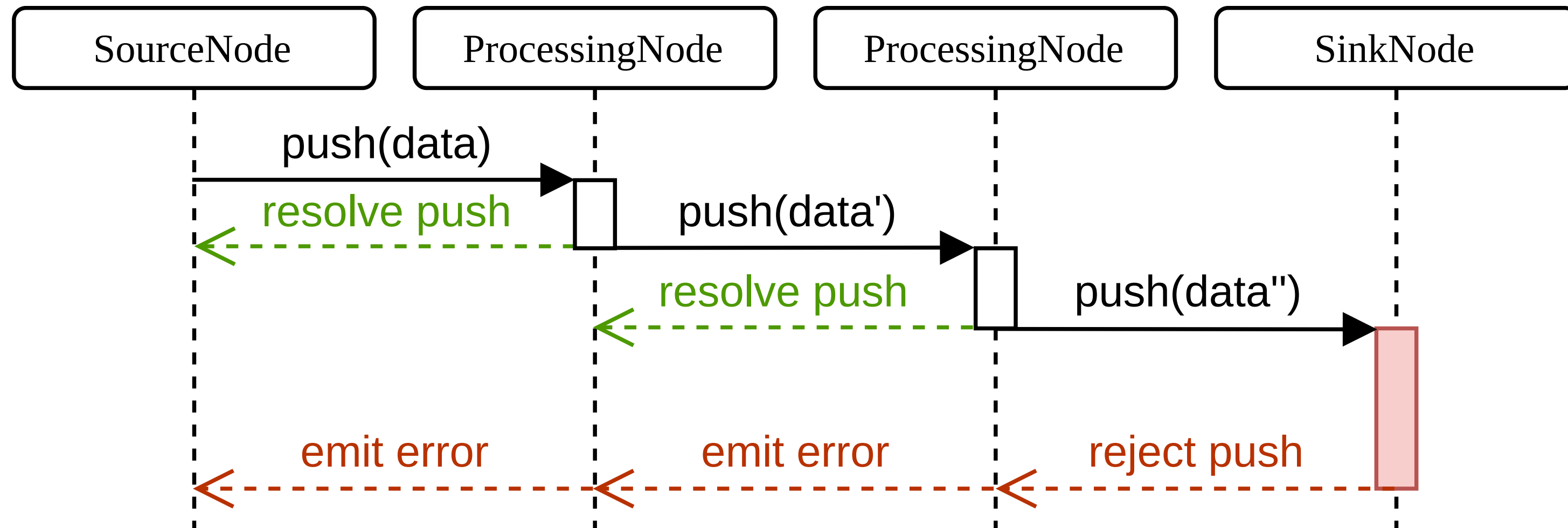
DataFrame ...

Pulling Data



DataFrame ...

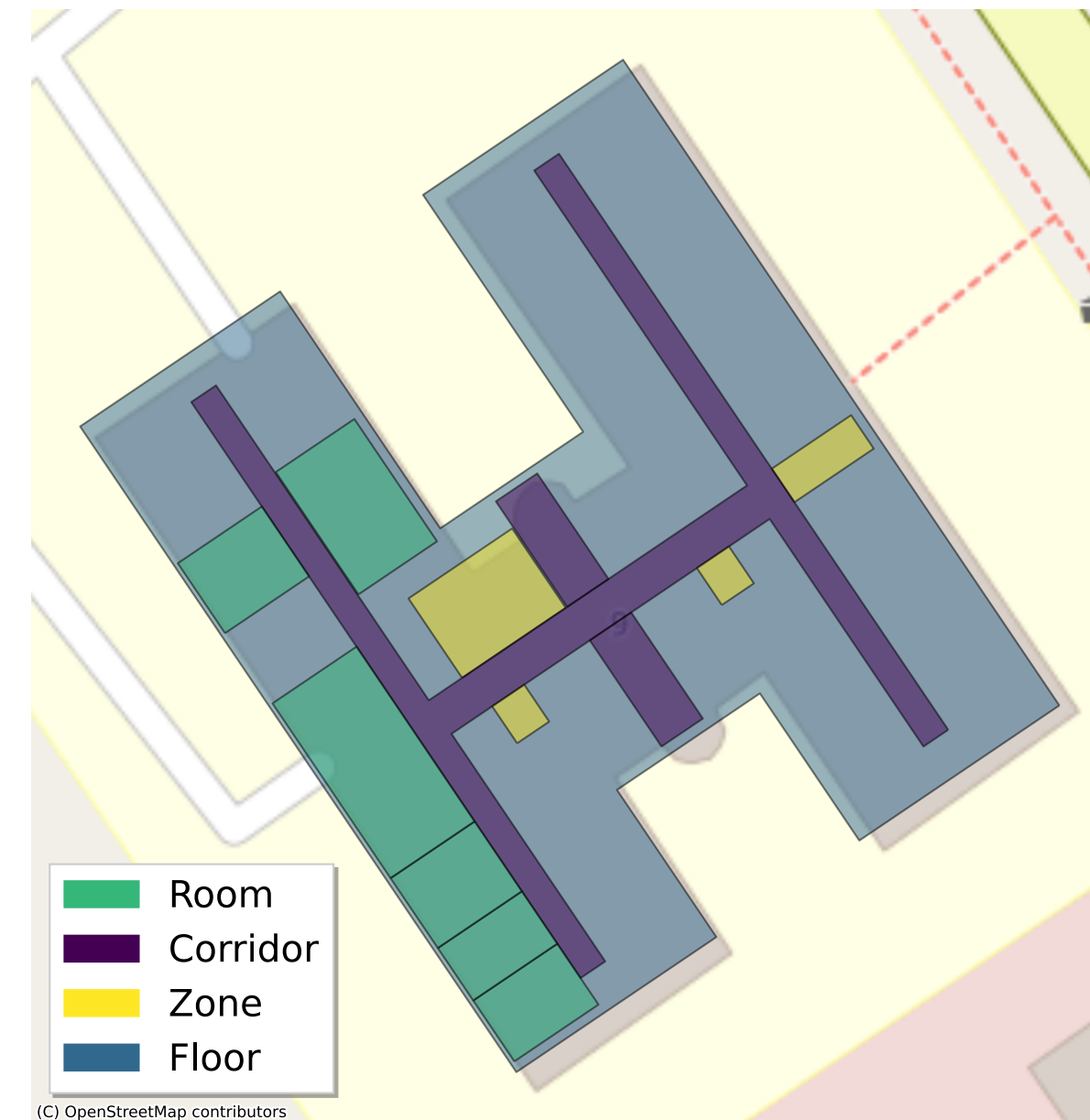
Pushing Error



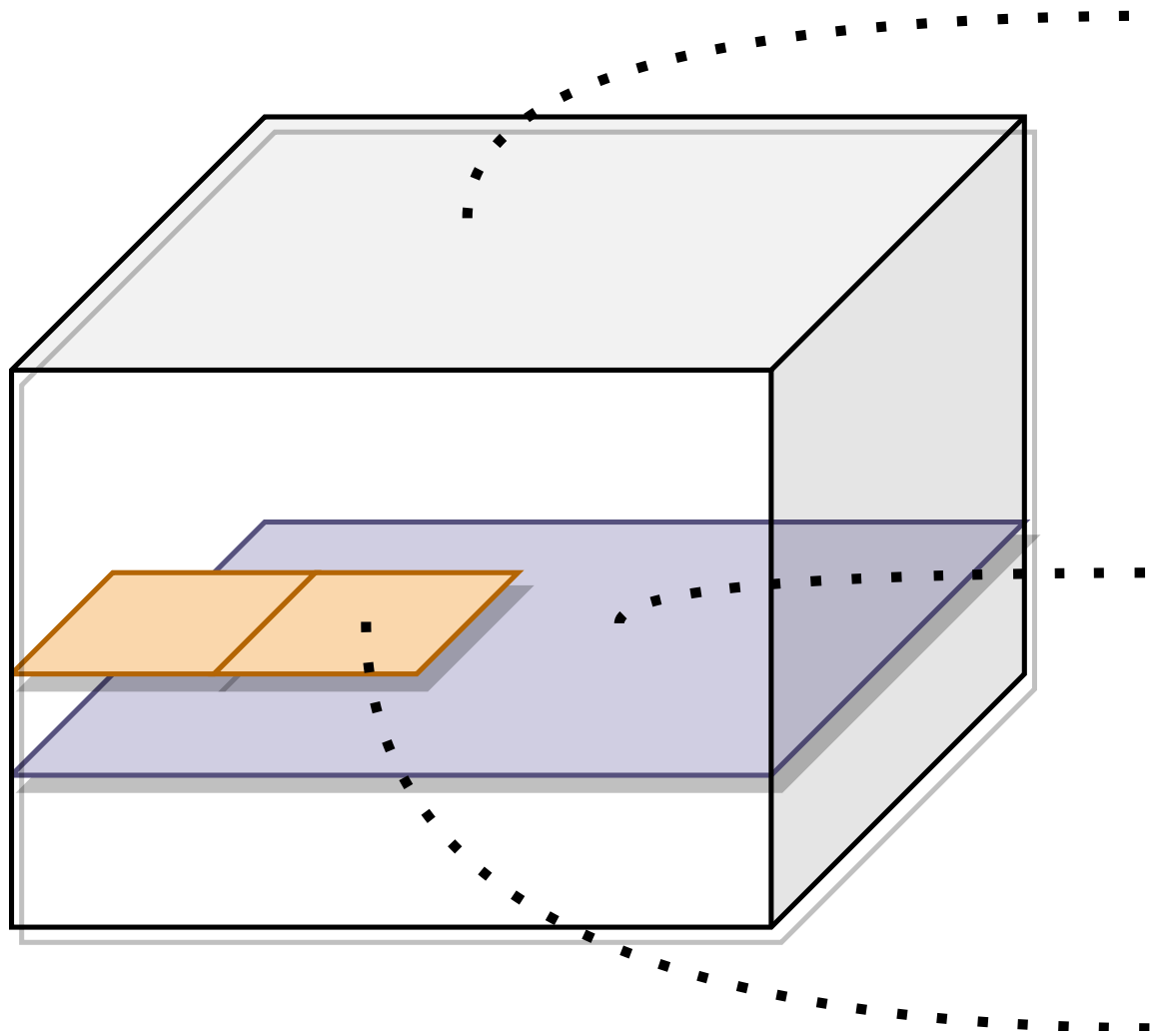
SymbolicSpace

An object that semantically defines a space

- ▶ Spatial hierarchy
- ▶ Graph connectivity with other spaces
- ▶ Geocoding
- ▶ GeoJSON compatibility
- ▶ Can be used as a location
- ▶ Can be extended ...



SymbolicSpace ...



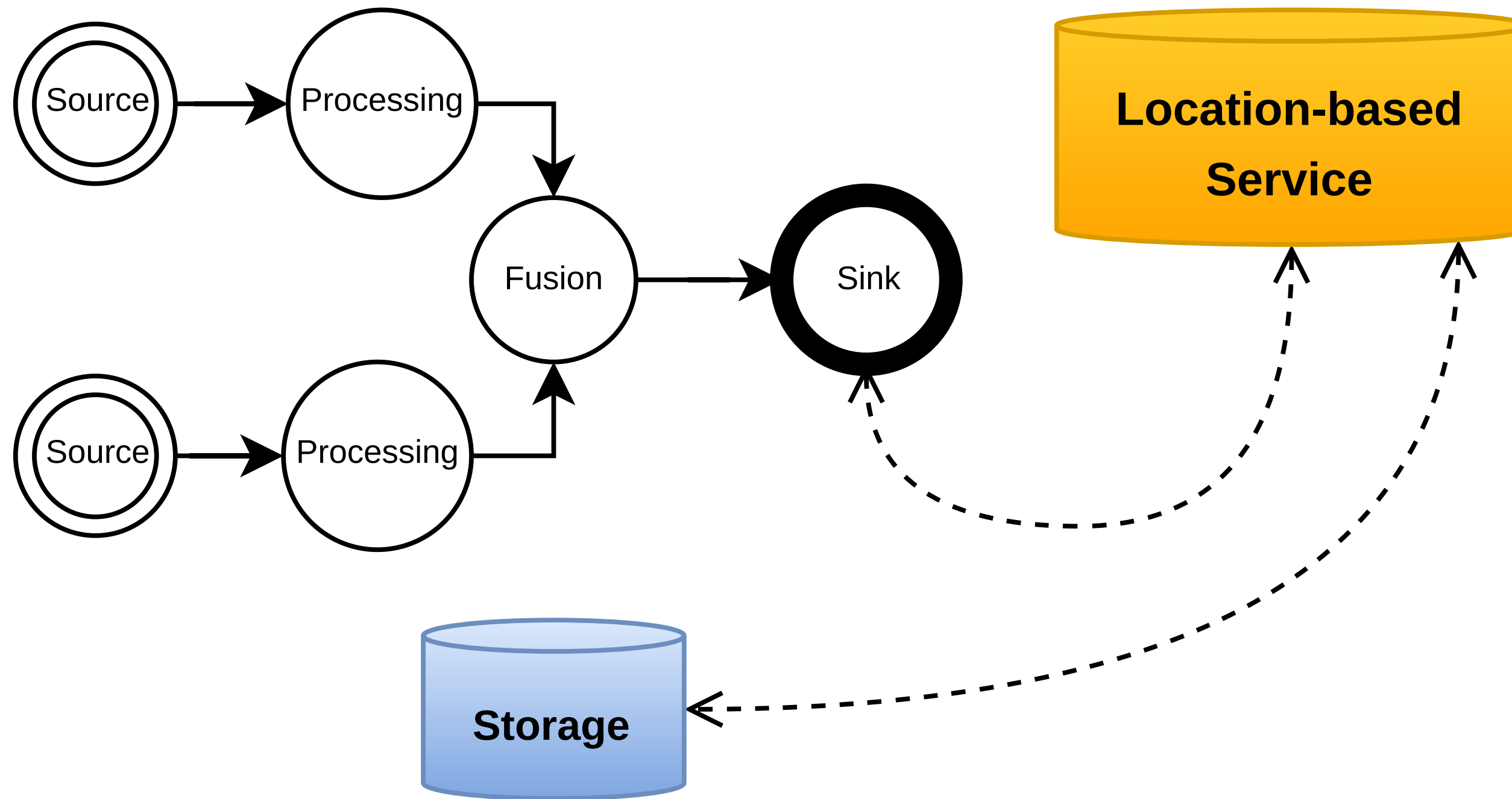
```
const building = new Building("PL9")
  .setBounds({
    topLeft: new GeographicalPosition(
      50.8203,
      4.3922),
    width: 46.275,
    height: 37.27,
    rotation: -34.04
  });

const floor = new Floor("PL9.3")
  .setBuilding(building)
  .setFloorNumber(3);

const office = new Room("PL9.3.58")
  .setFloor(floor)
  .setBounds([
    new Absolute2DPosition(4.75, 31.25),
    new Absolute2DPosition(8.35, 37.02),
  ]);
```

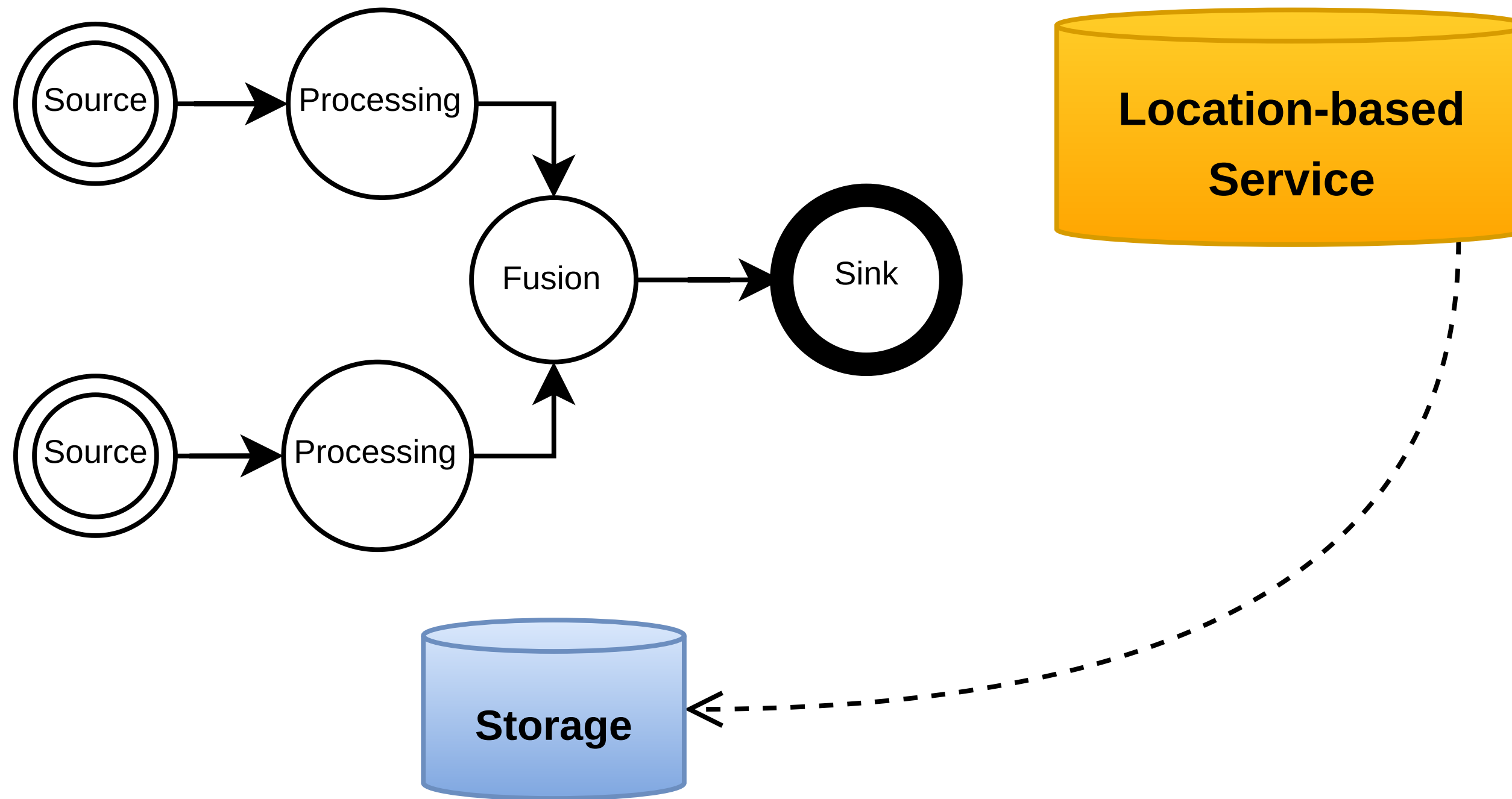
Location-based Service

`getCurrentPosition("me", ...)`



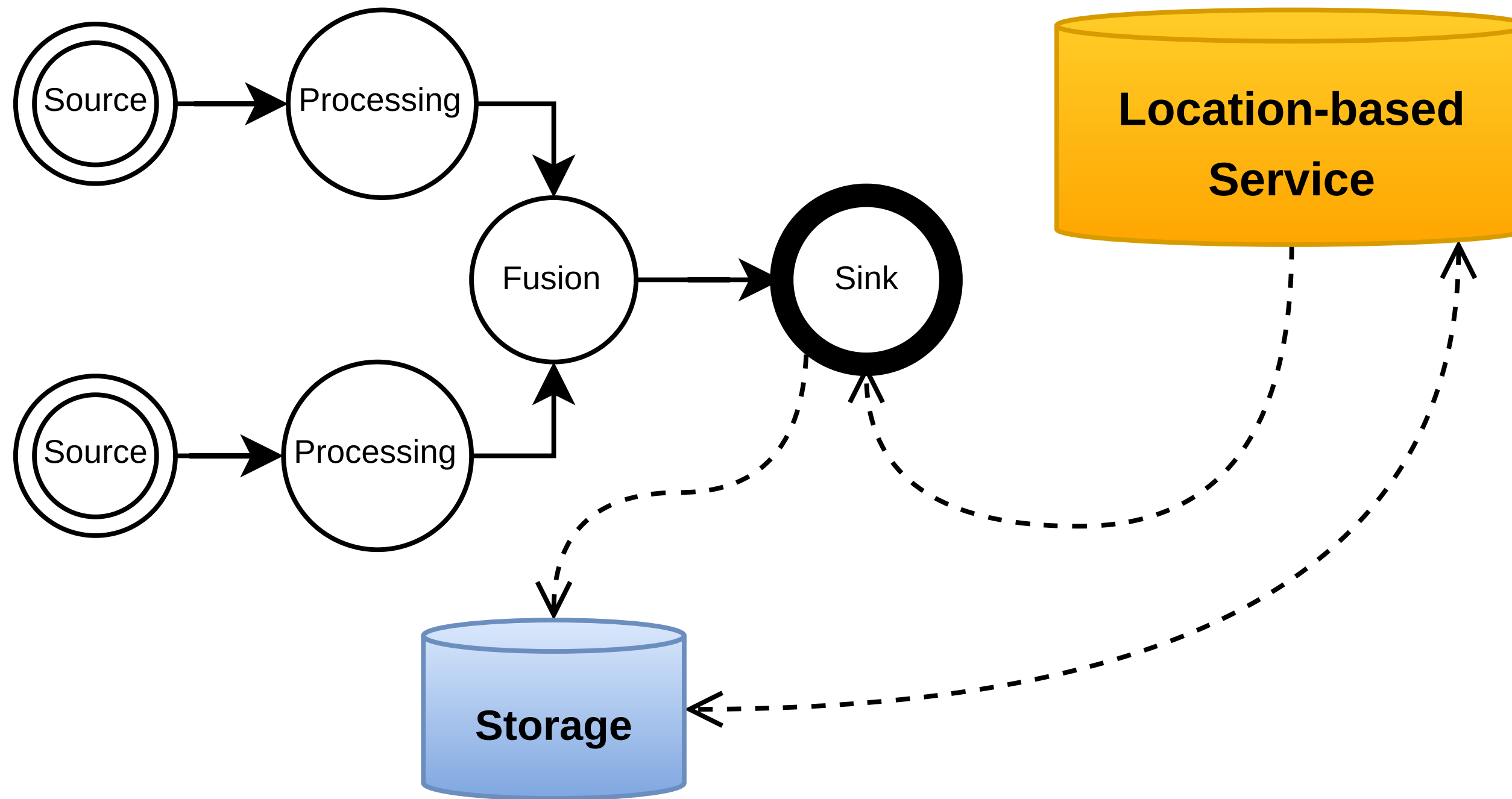
Location-based Service ...

`setCurrentPosition("me", ...)`



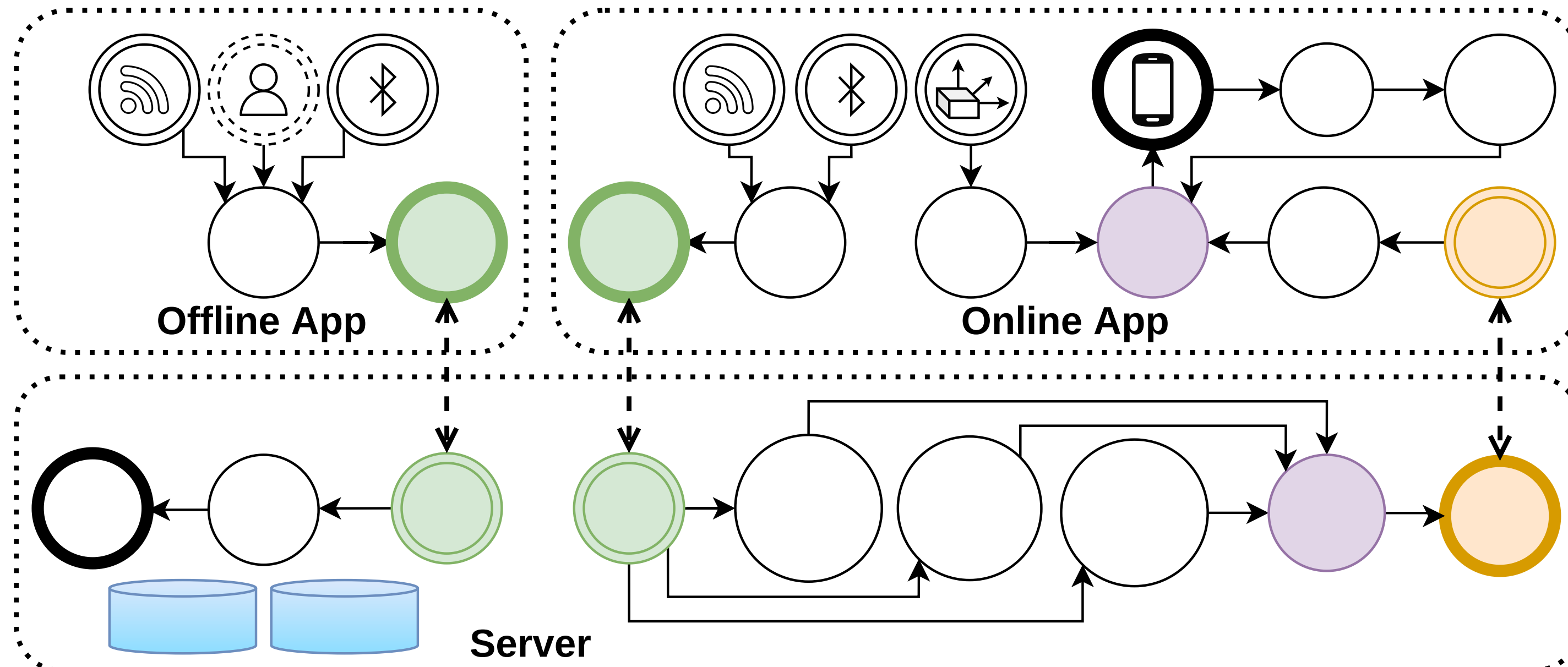
Location-based Service ...

`watchPosition("me", ...)`

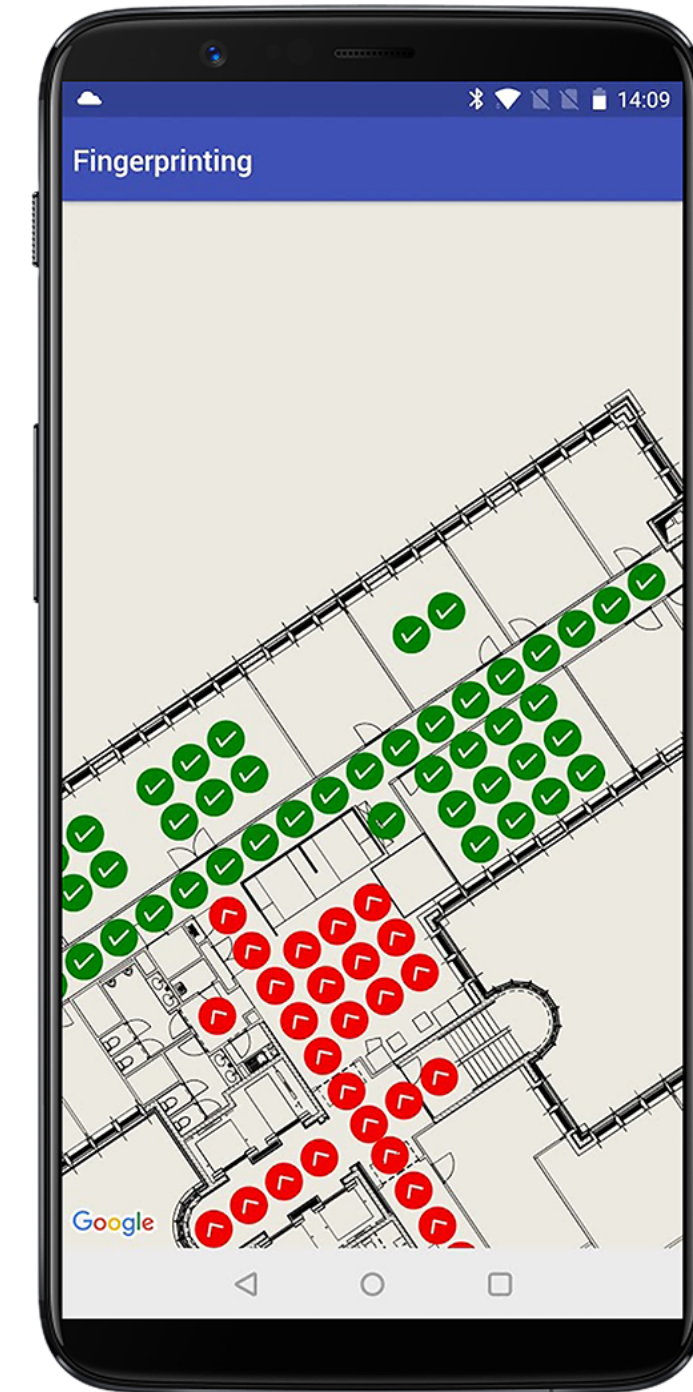
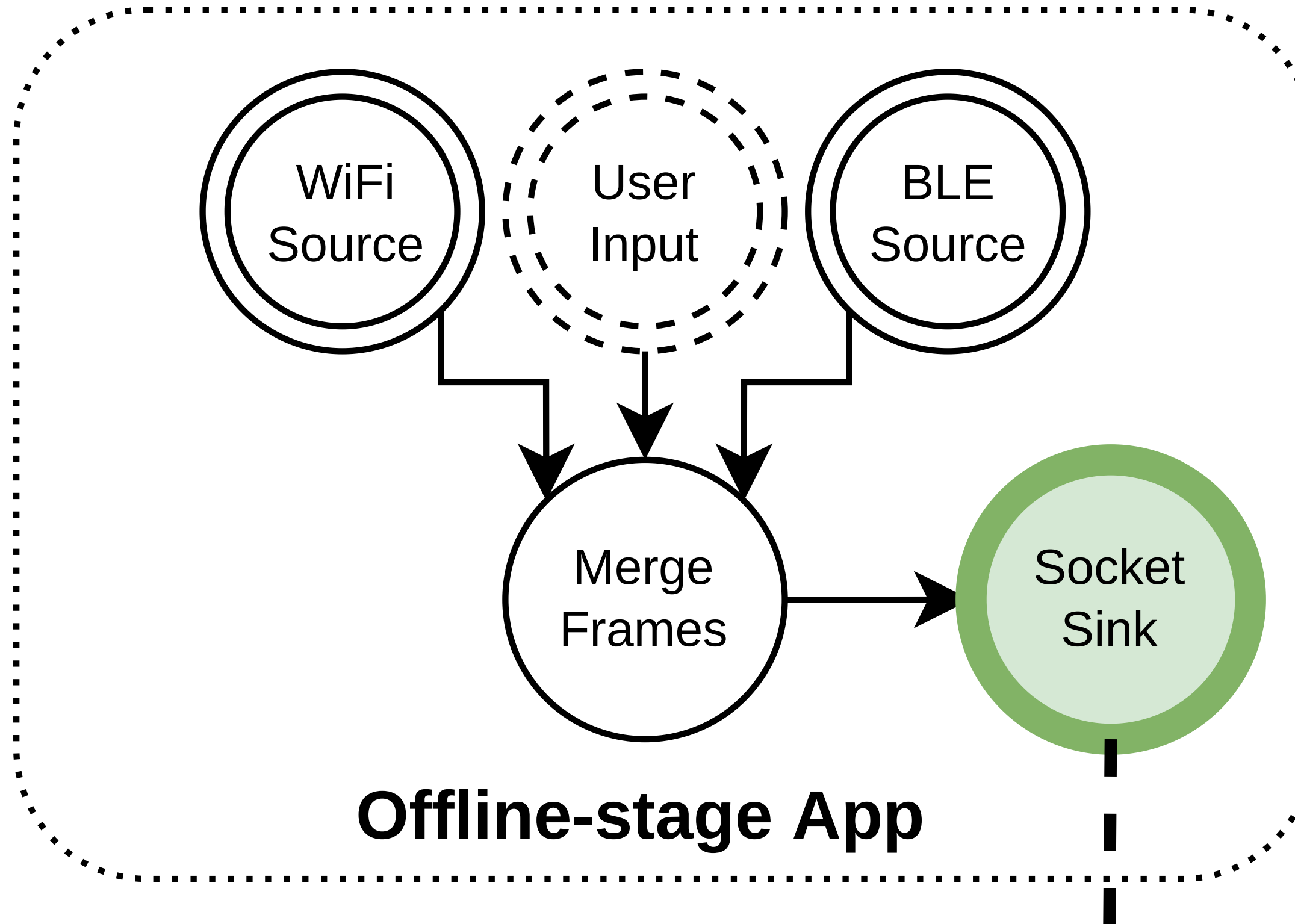


Demonstration

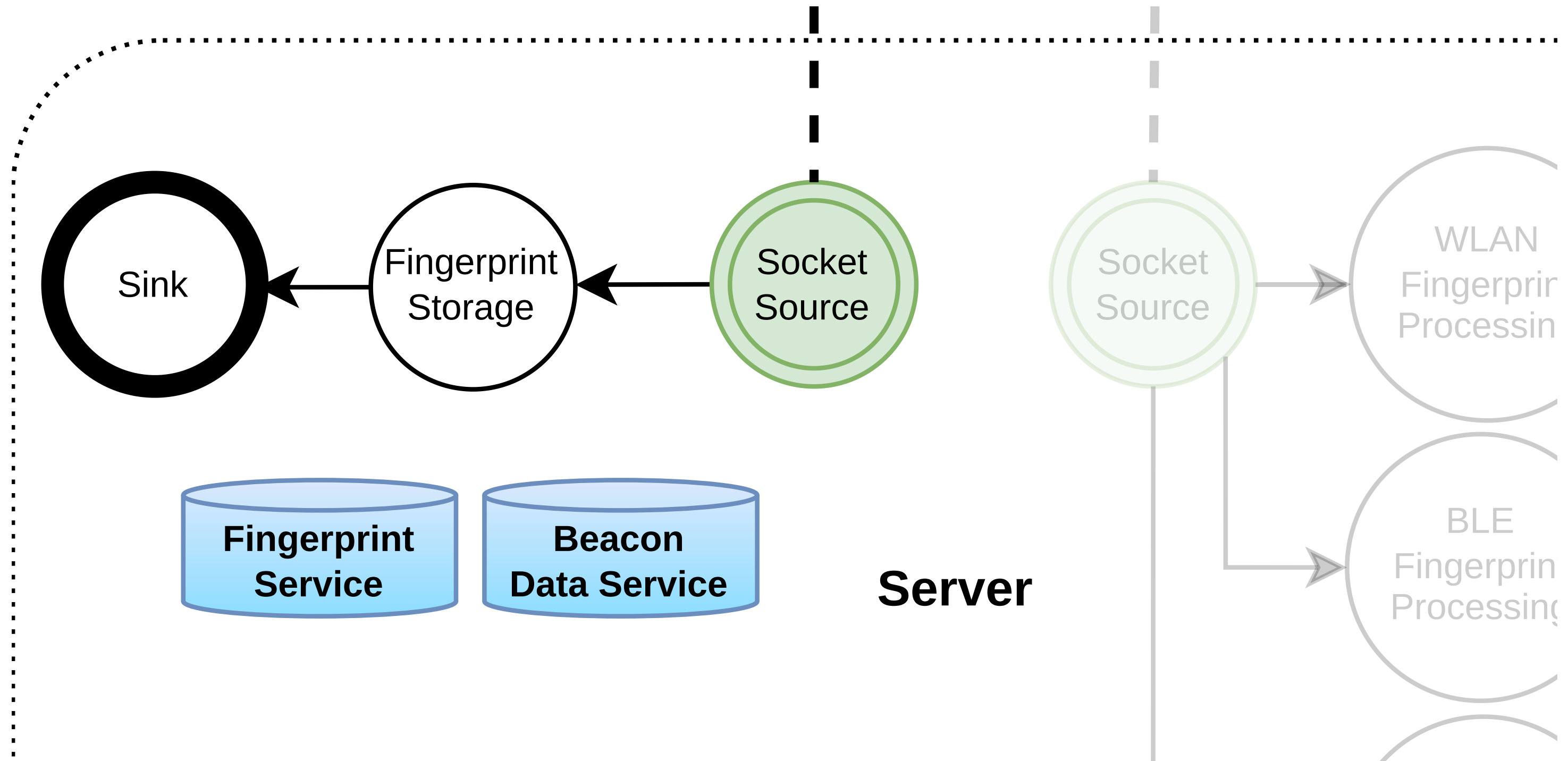
- ▶ Indoor positioning **use case**
- ▶ Use **existing techniques**
- ▶ Validation of **flexibility** and modularity



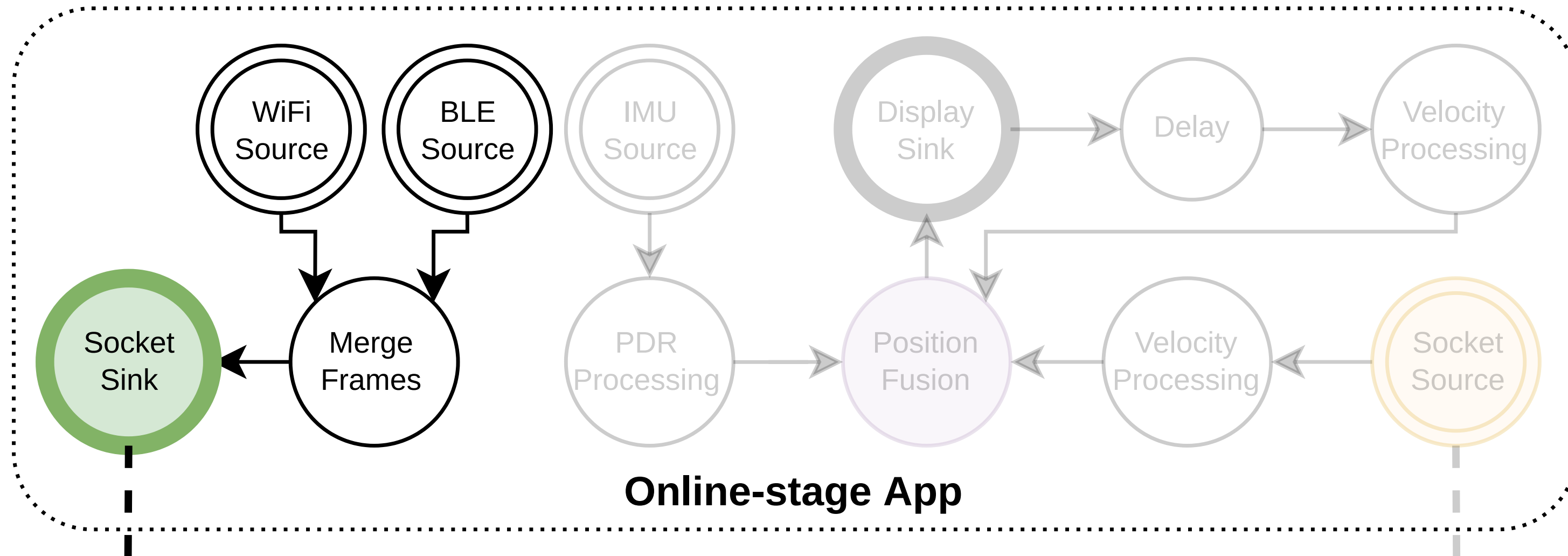
Positioning Model



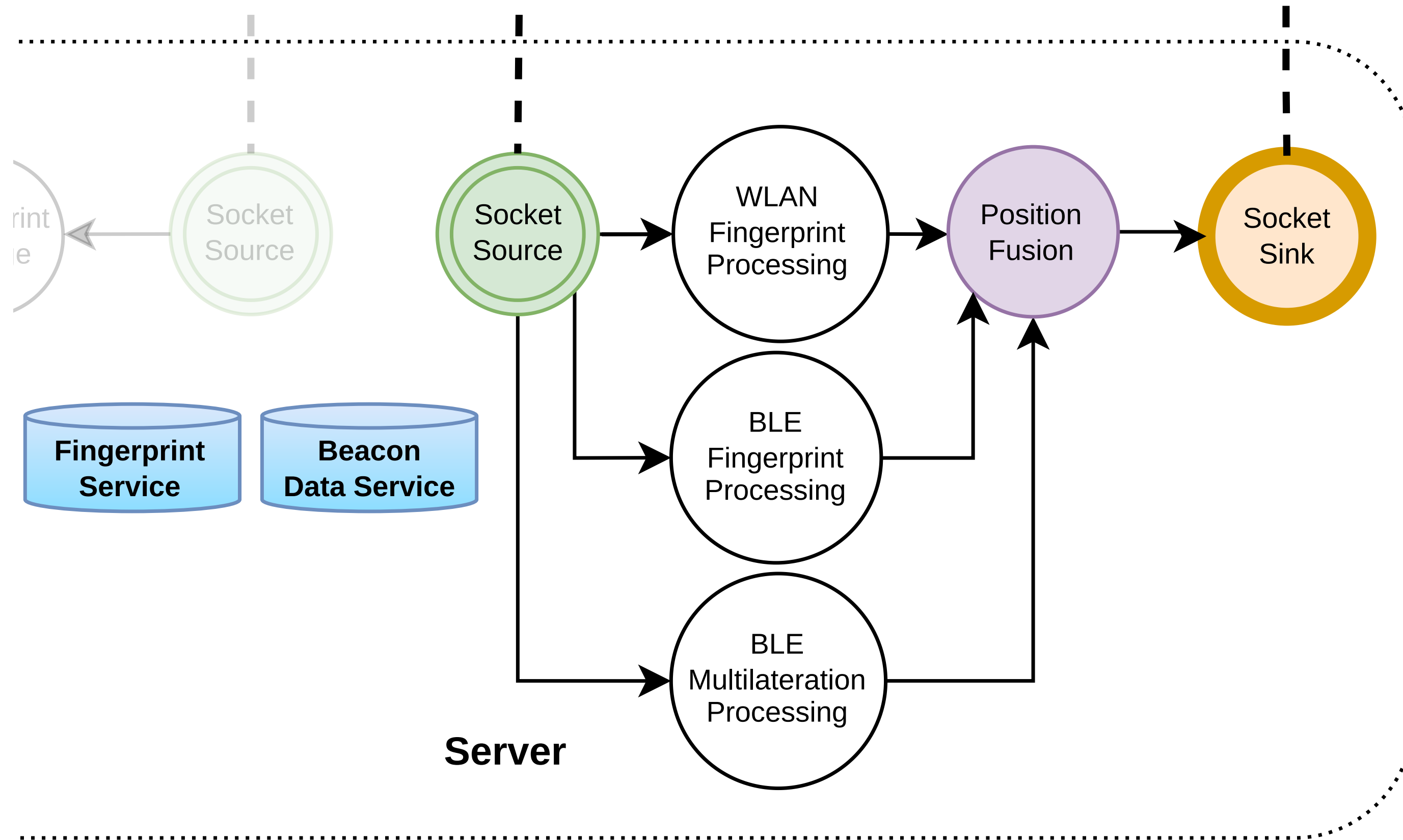
Positioning Model ...



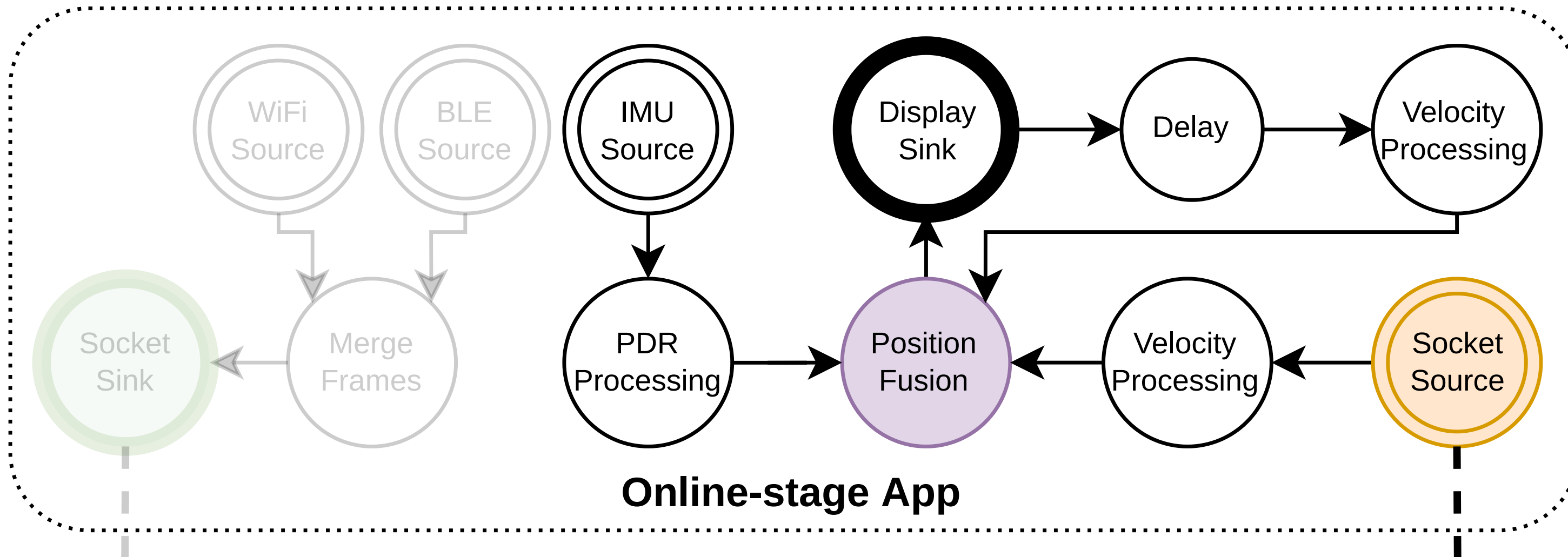
Positioning Model ...



Positioning Model ...

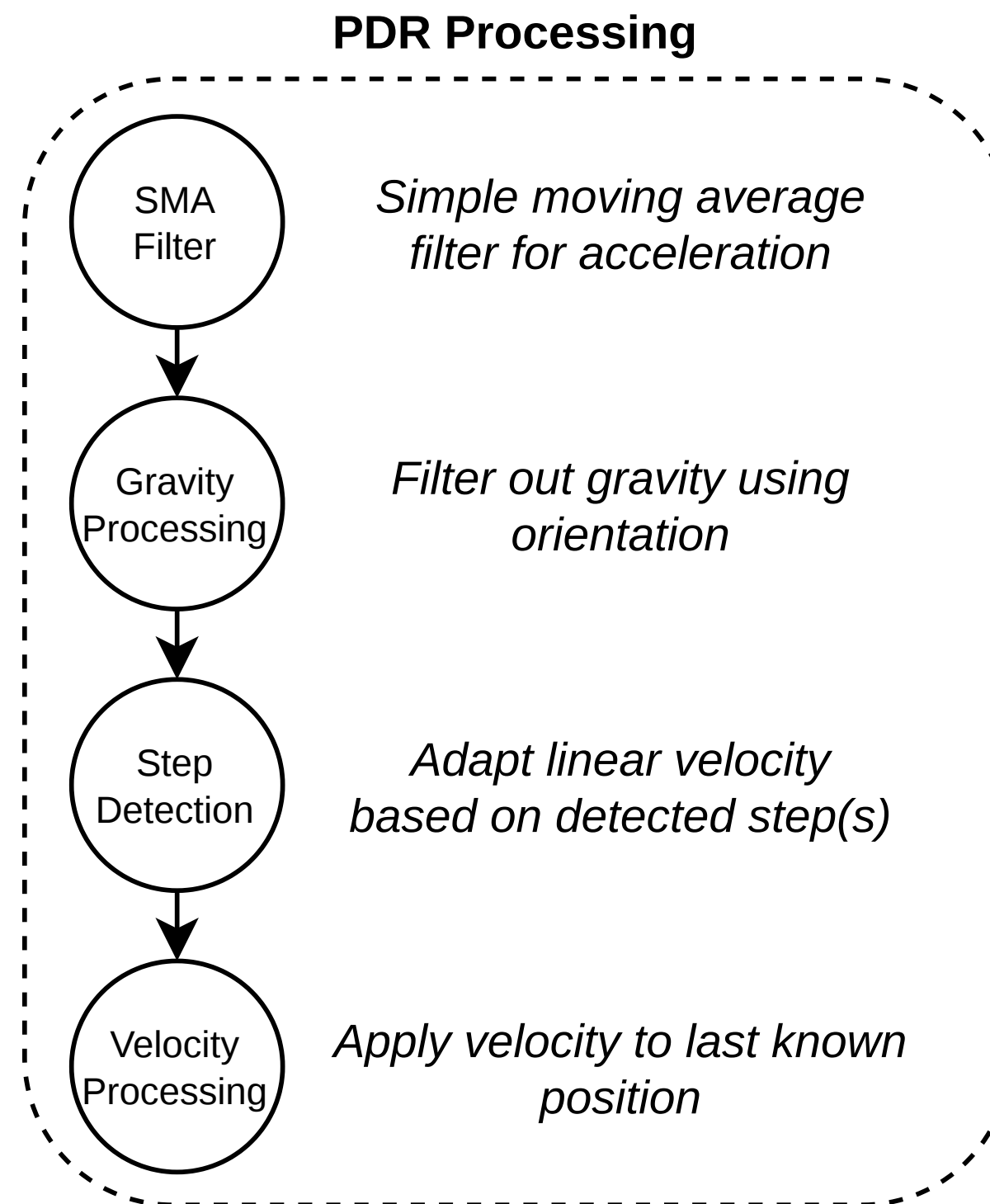


Positioning Model ...



Positioning Model

Online App

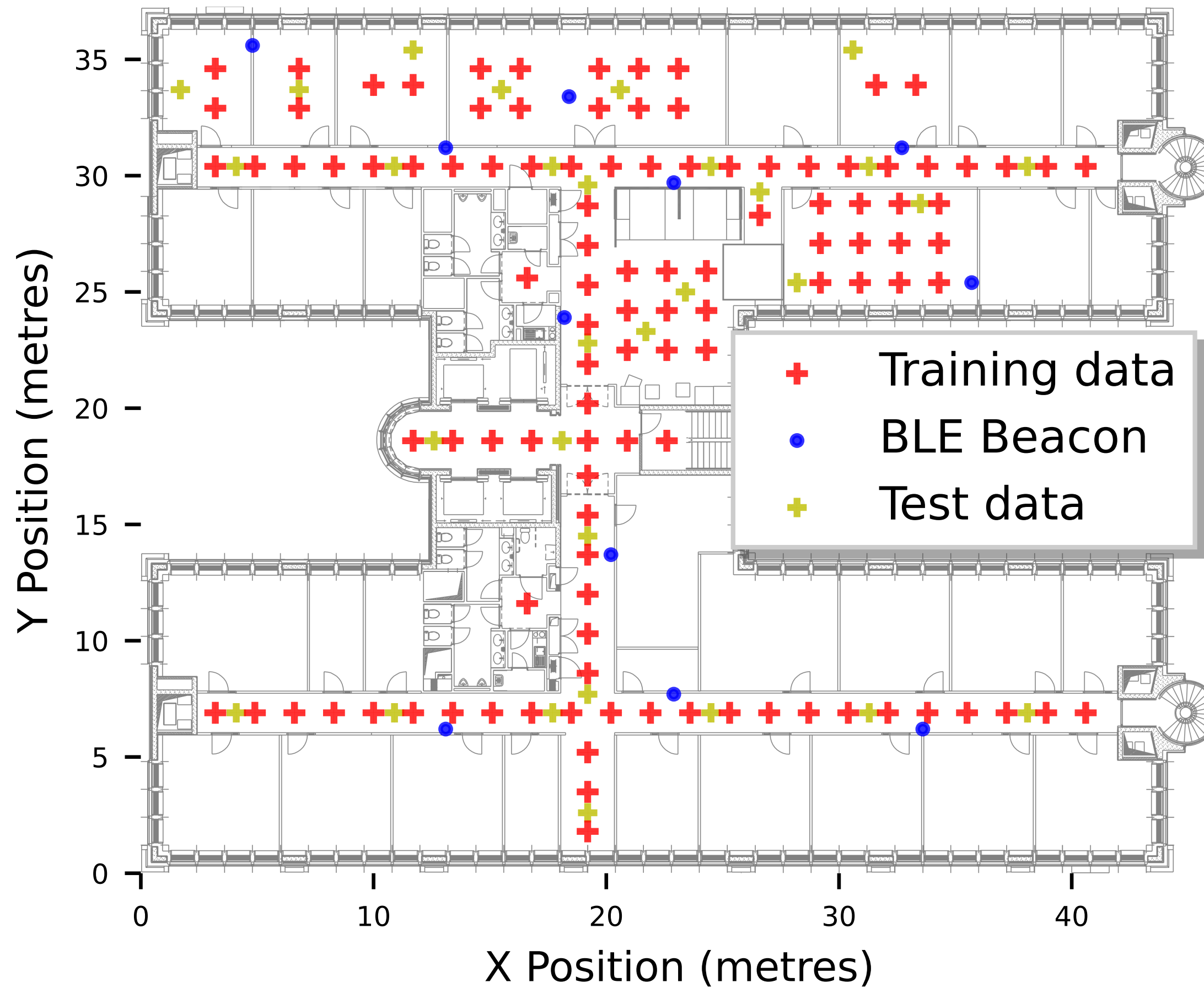


Positioning Model

Online App

```
ModelBuilder.create()  
  .addShape(GraphBuilder.create()  
    .from(new IMUSourceNode({  
      source: new DataObject(phoneUID),  
      interval: 20,  
      sensors: [  
        SensorType.ACCELEROMETER,  
        SensorType.ORIENTATION  
      ]  
    })))  
  .via(new SMAFilterNode(  
    frame => [frame, "acceleration"],  
    { taps: 10 }  
  ))  
  .via(new GravityProcessingNode({  
    method: GravityProcessingMethod.ABSOLUTE_ORIENTATION  
  })))
```

Dataset



Dataset ...

Total BLE Beacons: 11

Total detected WLAN access points: 220

Total stable WLAN access points: 199

	Training	Test
Datapoints	110	30
Total fingerprints	440	120
Duration (per orientation)	20s	20s
Avg. WLAN Scans (per fingerprint)	6	6
Avg. BLE Advertisements (per fingerprint)	16	15

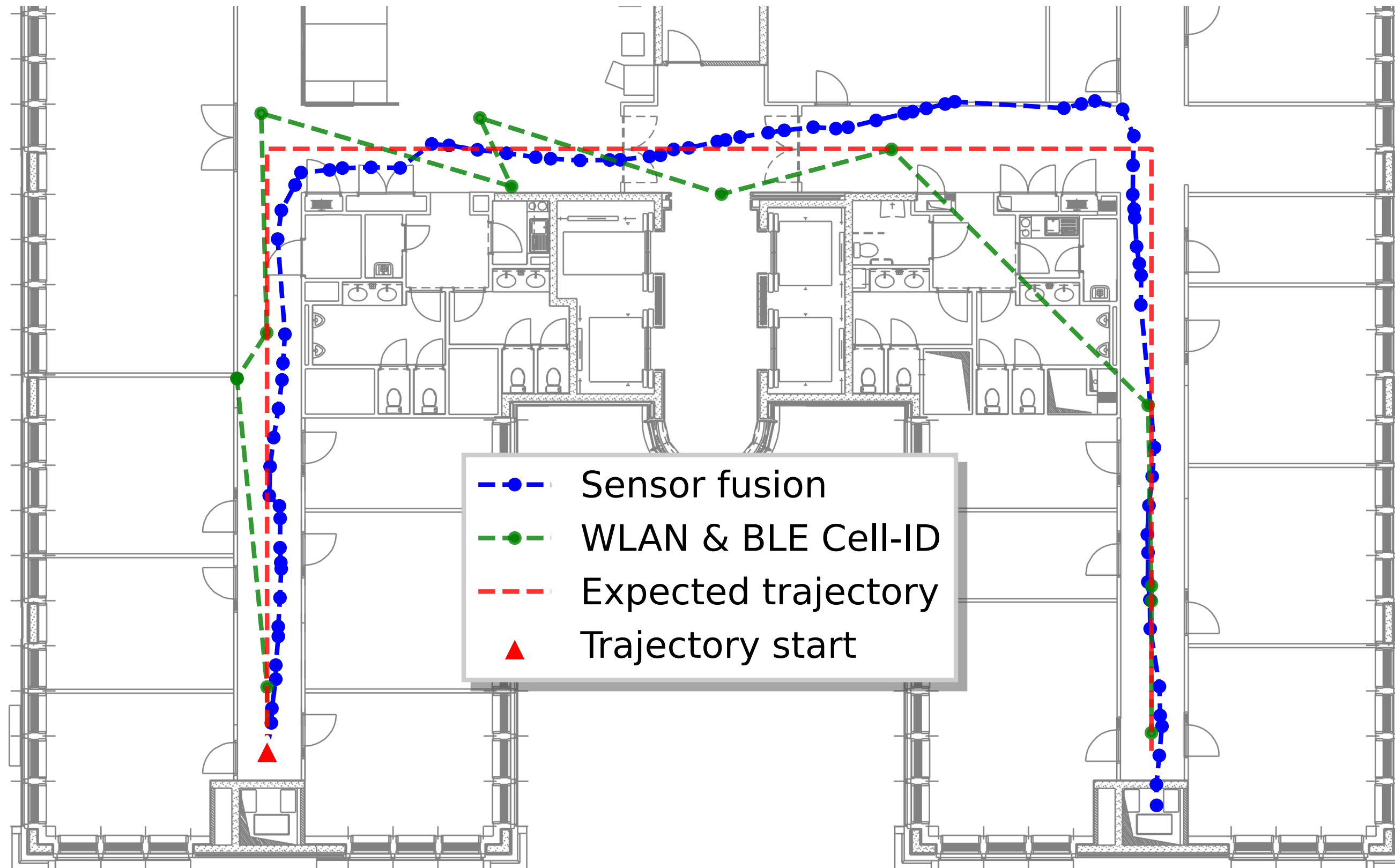
Validation Results

Static Positioning

	WLAN	BLE	BLE	Fusion
	fingerprinting	fingerprinting	multilateration	
<i>failed points</i>	0	6	12	0
<i>average error</i>	1.23 m	3.23 m	4.92 m	1.37 m
<i>minimum error</i>	0.01 m	0.17 m	0.74 m	0.01 m
<i>maximum error</i>	4.77 m	15.39 m	19.26 m	9.75 m
<i>hit rate</i>	95.82 %	80.83 %	52.50 %	96.67 %

Validation Results ...

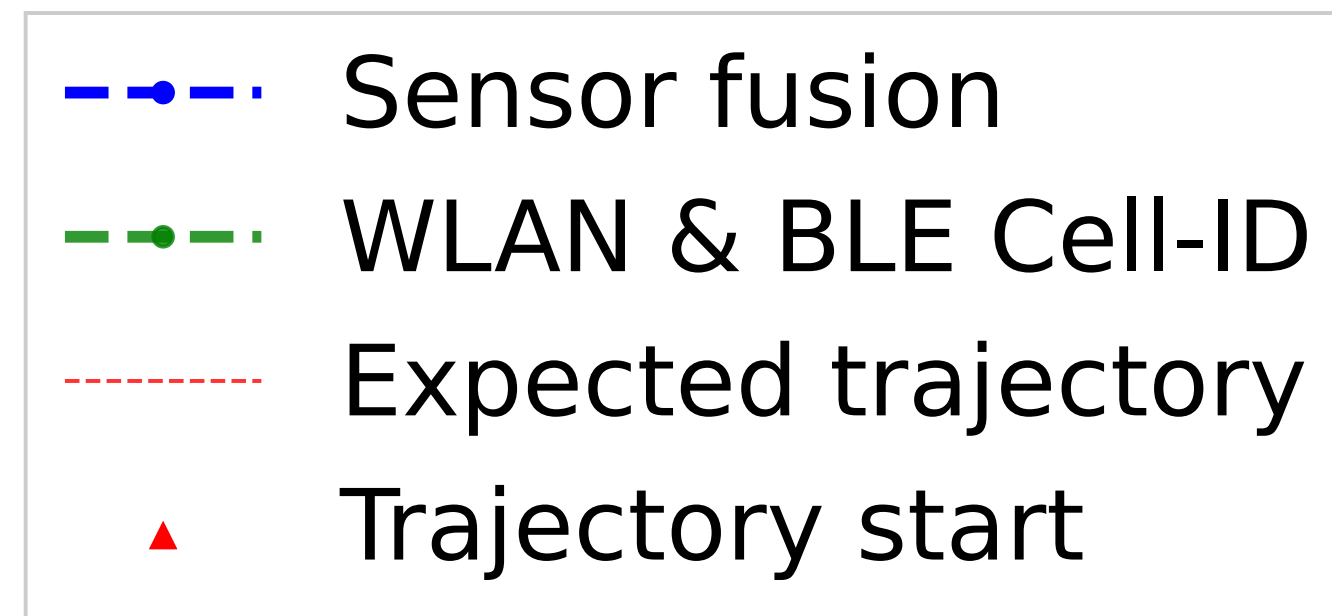
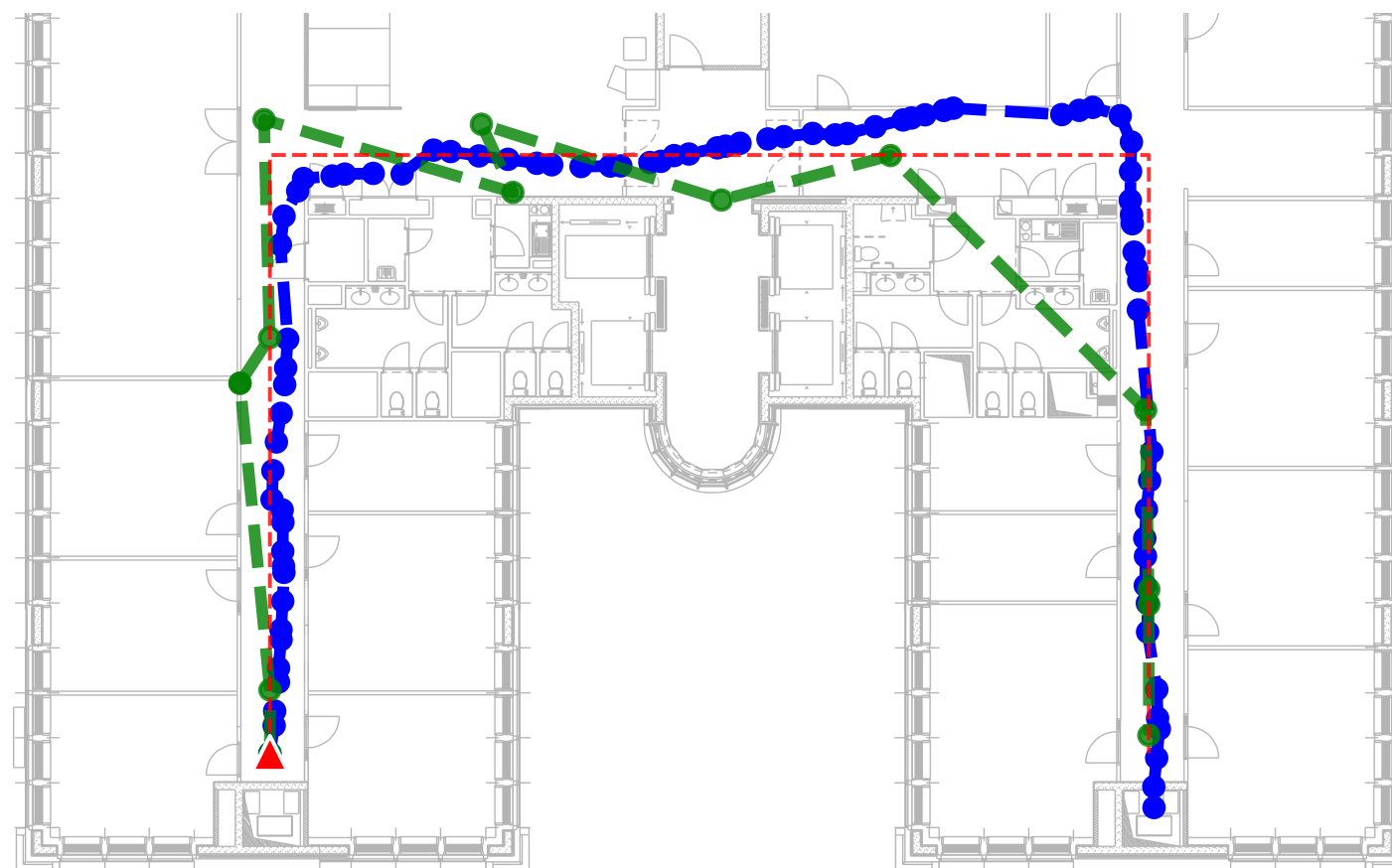
Trajectories



Validation Results ...

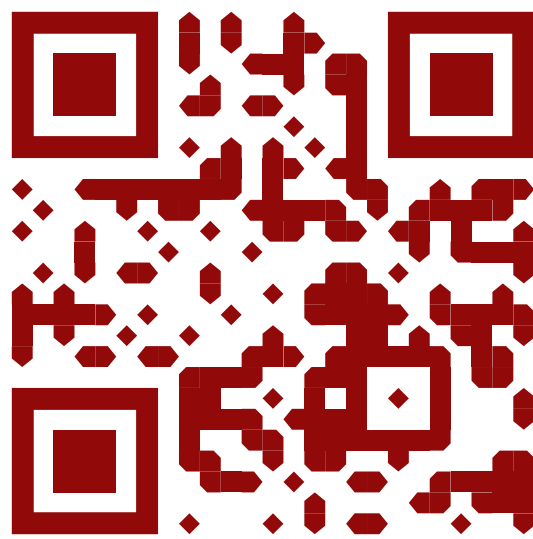
Trajectories

	WLAN + BLE	WLAN + BLE + IMU
<i>average error</i>	3.28 m	1.26 m
<i>maximum error</i>	9.60 m	3.10 m
<i>average update frequency</i>	3.04 s	0.52 s



Contributions and Conclusions

- ▶ OpenHPS: **open source** framework for hybrid positioning
 - Aimed towards **developers** and **researchers**
- ▶ **Abstractions** such as location-based services and spaces
- ▶ Validation of an indoor positioning use case
- ▶ Configurable and interchangeable **nodes** and **services**
- ▶ **Public dataset** with multiple orientations



Visit <https://openhps.org> for additional resources, documentation, source code and more!