

Indoor Positioning Using the OpenHPS Framework

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What is OpenHPS?



An Open Source Hybrid Positioning System

DOCSBLOGGITHUB

Documentation

Introduction

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Modules

Basic Concepts

Data Object

Data Frame

Creating data frames

Creating a custom data frame

Standard Units

Position and Orientation

Reference Space

Positioning Model

Source Node

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Sink Node

Services

Advanced Concepts

Remote Service

Threading

Miscellaneous

Examples

Data Frame

Data frames are envelopes that are transmitted and processed through a positioning model. These frames are created by source nodes (e.g. sensors) and contain one or more data objects needed to process the frame.

A frame should contain a single reading of a sensor (such as an image of a video stream or current acceleration) and not permanent or calculated information.

VideoDataFrame

uidtimestamp

source

CameraObject

uid: "camera",
position: {
 x: 2, y: 5, z: 3
},
projection: ...,
width: 1280,
height: 1024

Image

DataObject

Detected object

DataObject

Detected object

DataObject

Detected object

IMUDataFrame

uidtimestamp

source

DataObject

uid: "imusensor",
position: {
 x: 0, y: 0,
 linearVelocity: {
 x: 1, y: 0
 }
}

Acceleration

Sensor Frequency

No additional objects

RDFataFrame

uidtimestamp

source

RFRceiverObject

uid: "wifiscanner",
relativePositions: [
 {
 obj: "AP1",
 distance: 5
 }, {
 obj: "AP2",
 distance: 8
 }]

AP1 DataObject

uid: "AP1",
position: {
 x: 0, y:
}

AP2 DataObject

uid: "AP2",
position: {
 x: 15, y: 3
}

Creating data frames

OpenHPS is a framework that processes sensor information to retrieve a position for one or more data objects. These objects are contained within an envelope called a data frame.

```
import { DataObject, DataFrame } from '@openhps/core';

const myObject = new DataObject("bsigner", "Beat Signer");
const frame = new DataFrame();
frame.addObject(myObject);
```

(method) DataFrame.addObject(object: DataObject): void

A basic data frame supports the addition of objects. Extended versions of this basic data frame also add additional sensor data.

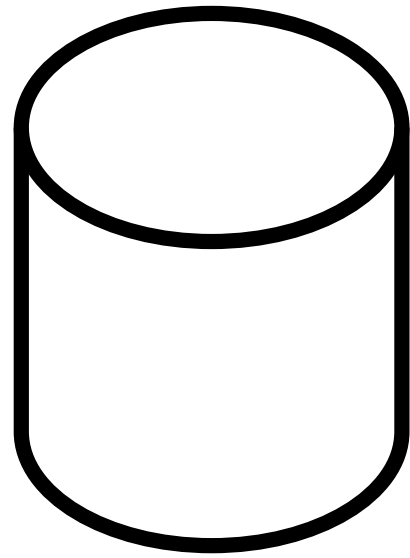
Creating a custom data frame

Similar to data objects, decorators have to be used to indicate a serializable data frame.

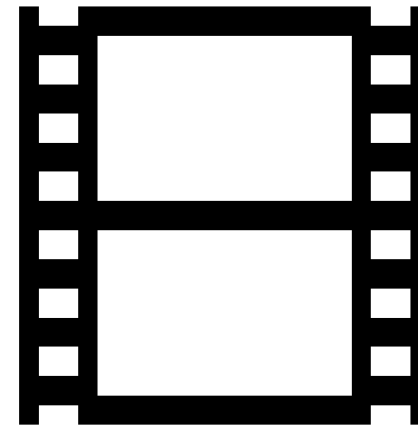
```
import {
  DataFrame,
  SerializableObject,
  SerializableMember
} from '@openhps/core';

@SerializableObject()
export class QRDataFrame extends DataFrame {
  public rawImage: any = undefined;
}
```

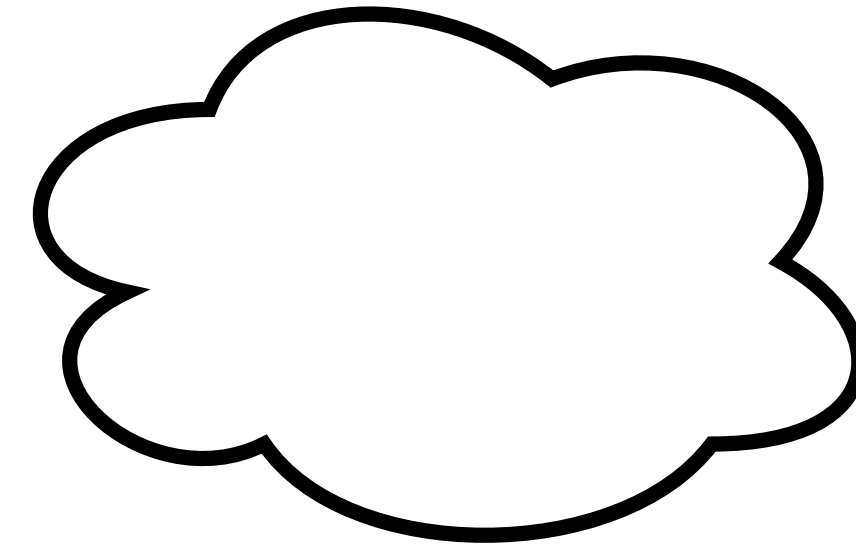
Data Processing



Knowledge



Raw Data

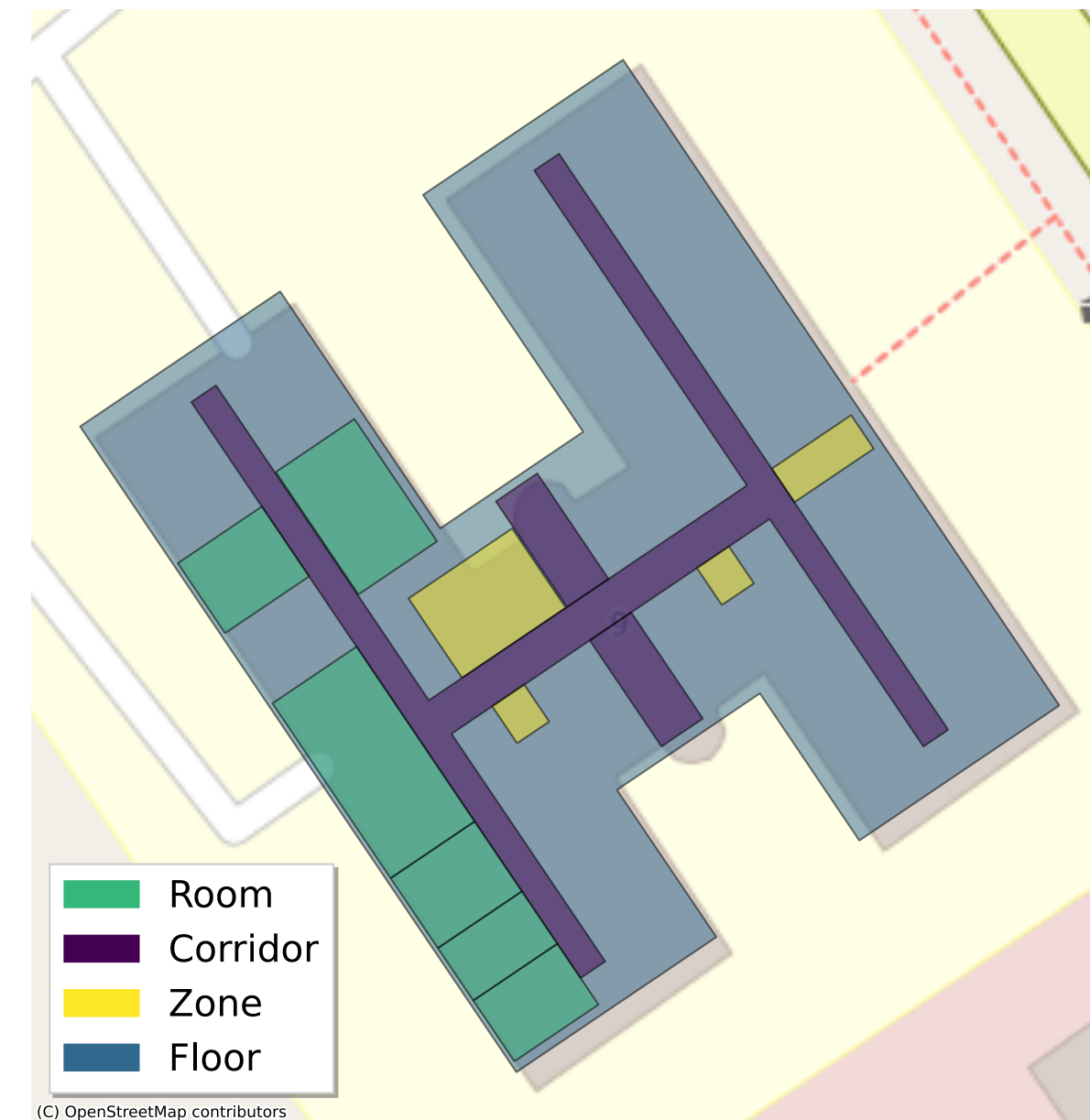


Processed Data

SymbolicSpace

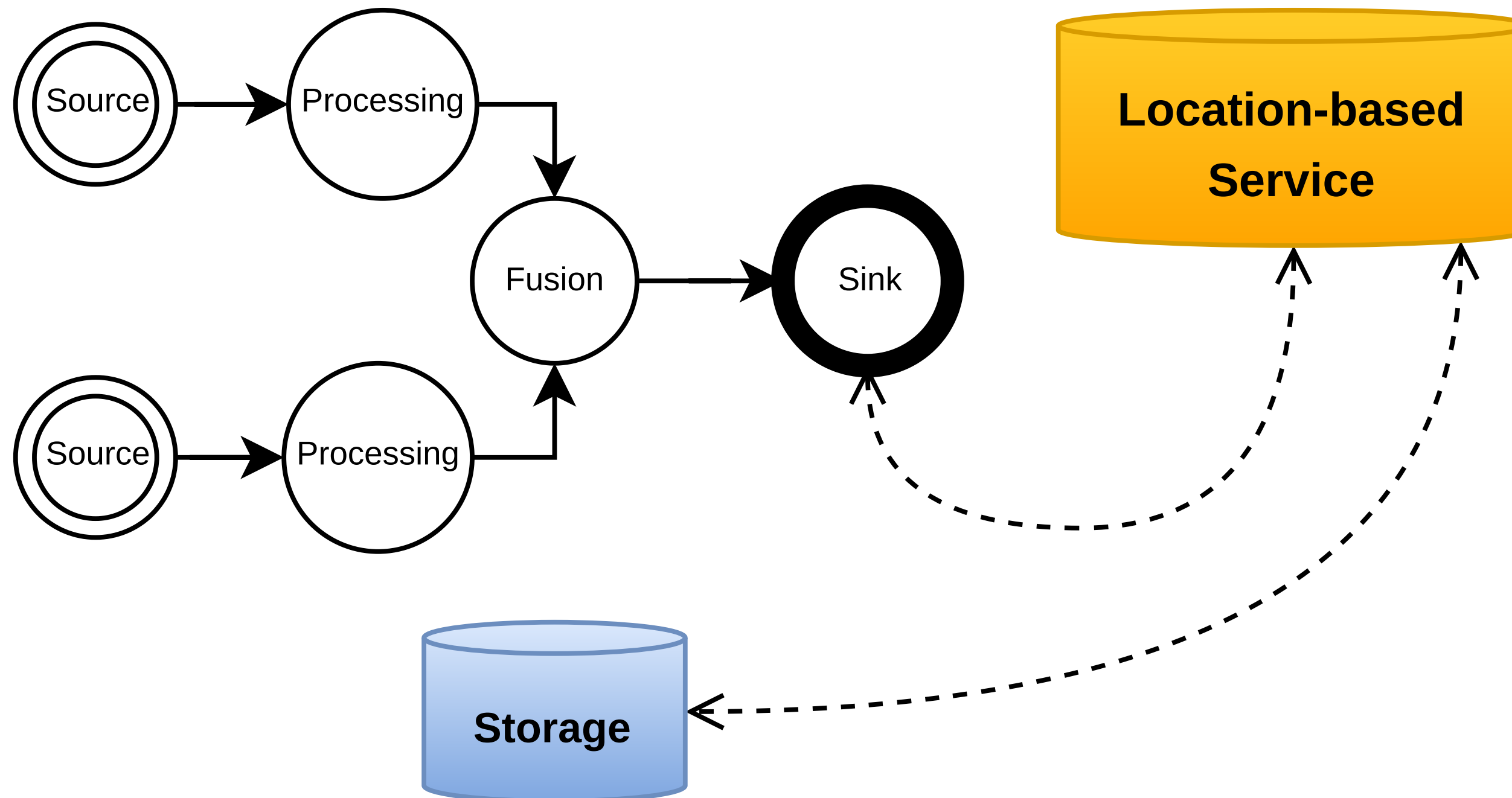
An object that semantically defines a space

- ▶ Spatial hierarchy
- ▶ Graph connectivity with other spaces
- ▶ Geocoding
- ▶ GeoJSON compatibility
- ▶ Can be used as a location
- ▶ Can be extended ...



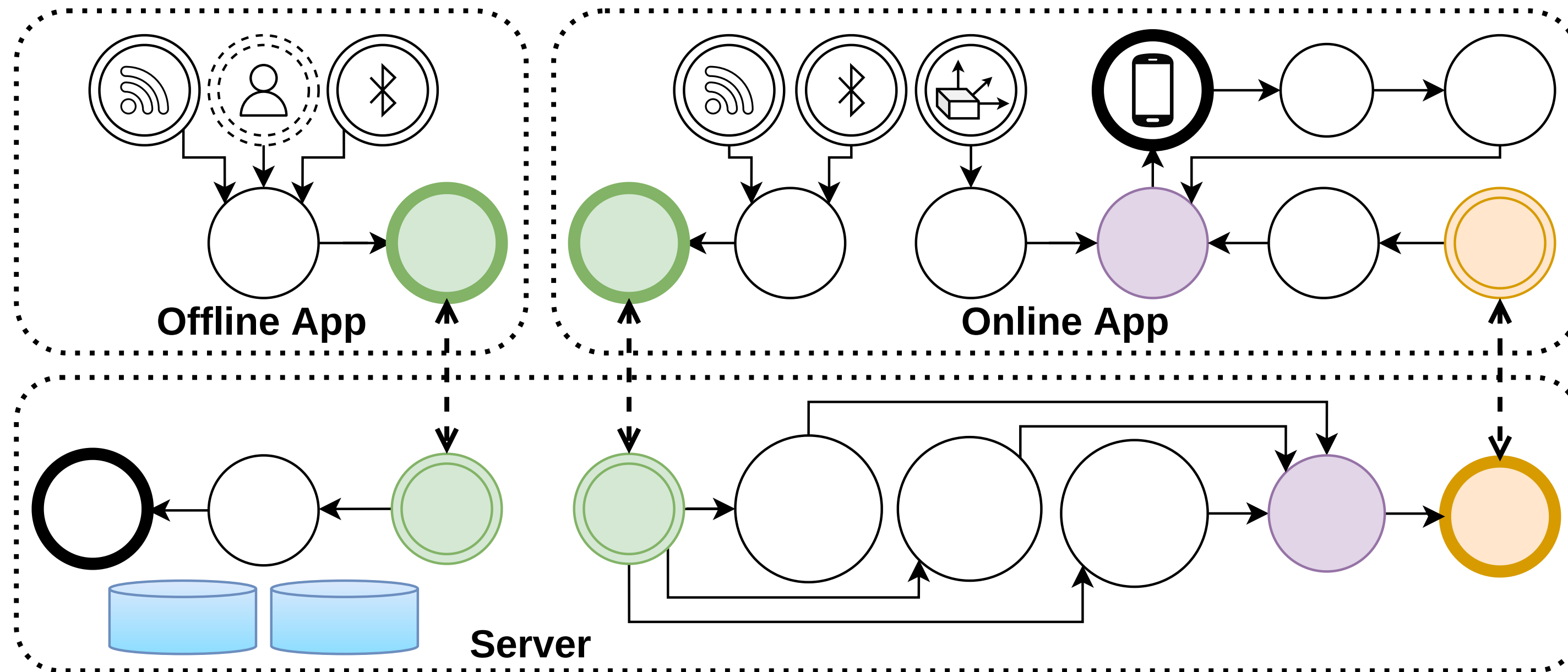
Location-based Service

`getCurrentPosition("me", ...)`

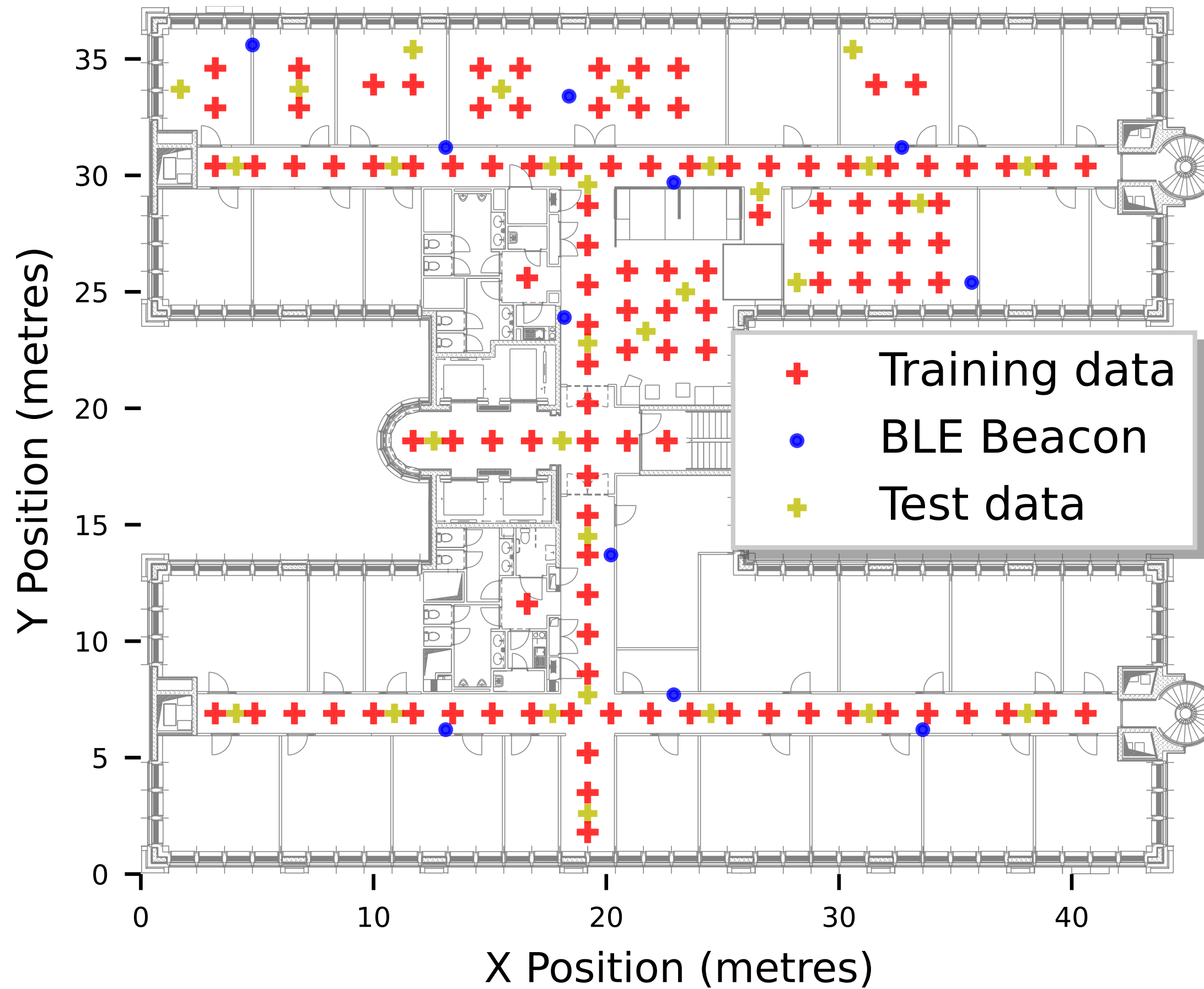


Demonstration

- ▶ Indoor positioning **use case**
- ▶ Use **existing techniques**
- ▶ Validation of **flexibility** and modularity



Dataset



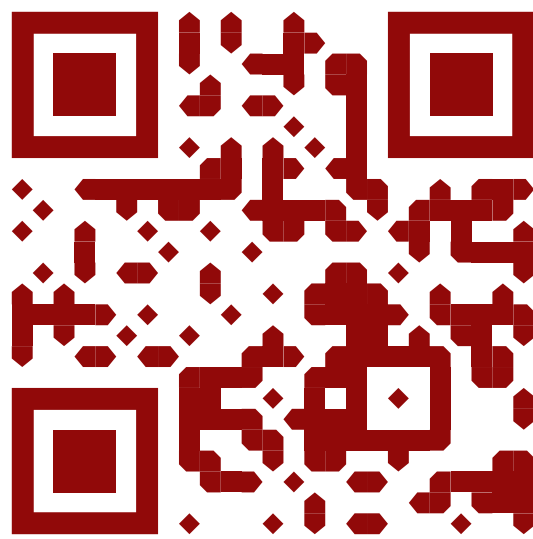
Validation Results

Static Positioning

	WLAN	BLE	BLE	Fusion
	fingerprinting	fingerprinting	multilateration	
<i>failed points</i>	0	6	12	0
<i>average error</i>	1.23 m	3.23 m	4.92 m	1.37 m
<i>minimum error</i>	0.01 m	0.17 m	0.74 m	0.01 m
<i>maximum error</i>	4.77 m	15.39 m	19.26 m	9.75 m
<i>hit rate</i>	95.82 %	80.83 %	52.50 %	96.67 %

Contributions and Conclusions

- ▶ OpenHPS: **open source** framework for hybrid positioning
 - Aimed towards **developers** and **researchers**
- ▶ **Abstractions** such as location-based services and spaces
- ▶ Validation of an indoor positioning use case
- ▶ Configurable and interchangeable **nodes** and **services**
- ▶ **Public dataset** with multiple orientations



Visit <https://openhps.org> for additional resources, documentation, source code and more!