ndvar Documentation

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Chapter 1

Optimum interpolation

$$\left(\overrightarrow{H} \stackrel{\longleftrightarrow}{B}\right)_{i,j} = \sum_{k=1}^{M} \stackrel{\longleftrightarrow}{H}_{i,k} \stackrel{\longleftrightarrow}{B}_{k,j}. \tag{1.1}$$

In the special case, where \overrightarrow{B} has diagonal form, this reduces to

$$\left(\overrightarrow{H} \stackrel{\longleftrightarrow}{B}\right)_{i,j} = \sum_{k=1}^{M} \stackrel{\longleftrightarrow}{H}_{i,k} \stackrel{\longleftrightarrow}{B}_{k,j} \delta_{k,j} = \sum_{k=1}^{M} \stackrel{\longleftrightarrow}{H}_{i,k} \stackrel{\longleftrightarrow}{B}_{j,j} \delta_{k,j} = \stackrel{\longleftrightarrow}{H}_{i,j} \stackrel{\longleftrightarrow}{B}_{j,j}.$$
(1.2)

For $\overleftrightarrow{H} \overleftrightarrow{B} \overleftrightarrow{H}^T$, one obtains

$$\left(\overrightarrow{H} \overset{\longleftrightarrow}{B} \overset{\longleftrightarrow}{H}^T \right)_{i,j} = \left[\left(\overset{\longleftrightarrow}{H} \overset{\longleftrightarrow}{B} \right) \overset{\longleftrightarrow}{H}^T \right]_{i,j} = \sum_{k=1}^{M} \left(\overset{\longleftrightarrow}{H} \overset{\longleftrightarrow}{B} \right)_{i,k} \overset{\longleftrightarrow}{H}_{k,j} = \sum_{k=1}^{M} \left(\overset{\longleftrightarrow}{H} \overset{\longleftrightarrow}{B} \right)_{i,k} \overset{\longleftrightarrow}{H}_{j,k} \overset{\longleftrightarrow}{H}_{j,k} = \sum_{k=1}^{M} \left(\overset{\longleftrightarrow}{H} \overset{\longleftrightarrow$$

In the special case, where \overrightarrow{B} has diagonal form, this reduces to

$$\left(\overrightarrow{H} \stackrel{\longleftrightarrow}{B} \stackrel{\longleftrightarrow}{H}^{T}\right)_{i,j} = \sum_{k=1}^{M} \stackrel{\longleftrightarrow}{H}_{i,k} \stackrel{\longleftrightarrow}{B}_{k,k} \stackrel{\longleftrightarrow}{H}_{j,k} = \sum_{k=1}^{M} \stackrel{\longleftrightarrow}{B}_{k,k} \left(\stackrel{\longleftrightarrow}{H}_{i,k} \stackrel{\longleftrightarrow}{H}_{j,k}\right). \tag{1.4}$$

For the final result, we obtain

$$x_{i} = x_{B,i} + \sum_{j=1}^{N} \left[\overrightarrow{B} \overrightarrow{H}^{T} \left(\overrightarrow{H} \overrightarrow{B} \overrightarrow{H}^{T} + \overrightarrow{R} \right) \right]_{i,j} (y_{j} - h_{j}) = x_{B,i} + \sum_{j=1}^{N} \left[\sum_{k=1}^{N} \left(\overrightarrow{B} \overrightarrow{H}^{T} \right)_{i,k} \left(\overrightarrow{H} \overrightarrow{B} \overrightarrow{H}^{T} + \overrightarrow{R} \right)_{k,j} \right] (y_{j} - h_{j})$$

$$= x_{B,i} + \sum_{j=1}^{N} \left[\sum_{k=1}^{N} \left(\overrightarrow{H} \overrightarrow{B} \overrightarrow{H}^{T} + \overrightarrow{R} \right)_{k,j} \left(\overrightarrow{B} \overrightarrow{H}^{T} \right)_{i,k} \right] (y_{j} - h_{j}) = x_{B,i} + \sum_{j=1}^{N} \left[\sum_{k=1}^{N} \left(\overrightarrow{H} \overrightarrow{B} \overrightarrow{H}^{T} + \overrightarrow{R} \right)_{k,j} \left(\sum_{l=1}^{M} \overrightarrow{B} \overrightarrow{H}^{T} \right) \right] (y_{j} - h_{j})$$

$$= x_{B,i} + \sum_{j=1}^{N} \left[\sum_{k=1}^{N} \left(\overrightarrow{H} \overrightarrow{B} \overrightarrow{H}^{T} + \overrightarrow{R} \right)_{k,j} \left(\sum_{l=1}^{M} \overrightarrow{B} \overrightarrow{H}^{T} + \overrightarrow{R} \right)_{k,l} \left(\sum_{l=1}^{M} \overrightarrow{B} \overrightarrow{H}^{T} + \overrightarrow{A} \right)_{k,l} \left($$

In the special case, where \overrightarrow{B} has diagonal form, this reduces to

$$x_{i} = x_{B,i} + \sum_{j=1}^{N} \left[\sum_{k=1}^{N} \left(\overrightarrow{H} \stackrel{\leftrightarrow}{B} \stackrel{\leftrightarrow}{H}^{T} + \stackrel{\leftrightarrow}{R} \right)_{k,j} \left(\overrightarrow{B}_{i,i} \stackrel{\leftrightarrow}{H}_{k,i} \right) \right] \left(y_{j} - h_{j} \right) = x_{B,i} + \sum_{j=1}^{N} \left[\sum_{k=1}^{N} \left(\overrightarrow{H} \stackrel{\leftrightarrow}{B} \stackrel{\leftrightarrow}{H}^{T} + \stackrel{\leftrightarrow}{R} \right)_{k,j} \stackrel{\leftrightarrow}{B}_{i,i} \stackrel{\leftrightarrow}{H}_{k,i} \right] \left(y_{j} - h_{j} \right). \tag{1.6}$$

1.1 Inclusion of moisture

So far, moisture is taken into account in a separate assimilation process for efficiency.

Chapter 2

3D-Var

2.1 Technicalities

The observations used come from a time window $\left[-\frac{T}{2},\frac{T}{2}\right]$ around the analysis time and are all taken to be valid at the analysis time. T=3 h is a typical value..

Chapter 3

4D-Var

3.1 Technicalities

The observations used come from a time window $\left[-\frac{T}{2},\frac{T}{2}\right]$ around the analysis time and are taken to be valid at individual time steps $n\Delta t$. T=6 h and $\Delta t=15$ min are typical values.