

M031 Series BSP Directory

Directory Introduction for 32-bit NuMicro® Family

Directory Information

Please extract the “M031 Series BSP_CMSIS_V3.02.000.zip” file firstly, and then put the “M031 Series BSP_CMSIS_V3.02.000” folder into the working folder (e.g. .\Nuvoton\BSP Library).

This BSP folder contents:

| | |
|--------------------|---|
| Document\ | Device driver reference manual and reversion history. |
| Library\ | Device driver header and source files. |
| SampleCode\ | Device driver sample code. |
| ThirdParty\ | Library from third party for emWin. |

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1 .\Document\

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| CMSIS.html | <p>Introduction of CMSIS version 4.5.0. CMSIS components included CMSIS-CORE, CMSIS-Driver, CMSIS-DSP, etc.</p> <ul style="list-style-type: none"> ● CMSIS-CORE: API for the Cortex®-M0 processor core and peripherals. ● CMSIS-Driver: Defines generic peripheral driver interfaces for middleware making it reusable across supported devices. ● CMSIS-DSP: DSP Library Collection with more than 60 functions for various data types: fix-point (fractional q7, q15, q31) and single precision floating-point (32-bit). |
| NuMicro M031 Series CMSIS BSP Revision History.pdf | <p>The revision history of M031 BSP.</p> |
| NuMicro M031 Series Driver Reference Guide.chm | <p>The usage of drivers in M031 BSP.</p> |

2 .\Library\

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| CMSIS\ | Cortex® Microcontroller Software Interface Standard (CMSIS) V4.5.0 definitions by ARM® Corp. |
| Device\ | CMSIS compliant device header file. |
| NuMaker\ | emWin library for NuMaker board. |
| StdDriver\ | All peripheral driver header and source files. |

3 .\Sample Code\

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| Hard_Fault_Sample\ | <p>Show hard fault information when hard fault happened.</p> <p>The hard fault handler shows some information included program counter, which is the address where the processor was executing when a hard fault occurred. The listing file (or map file) can show what function and instruction that was.</p> <p>It also shows the Link Register (LR), which contains the return address of the last function call. It can show the status where CPU comes from to get to this point.</p> |
| ISP | ISP firmware samples. |
| NuMaker | Sample codes for NuMaker board. |
| Semihost\ | Show how to print and get character through IDE console window. |
| RegBase\ | The sample codes that access control registers directly. |
| StdDriver\ | Demonstrate the usage of M031 series MCU peripheral driver APIs. |
| Template\ | A project template for M031 series MCU. |

4 .\SampleCode\ISP

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| ISP_DFU | Demonstrate how to use specific requests in DFU class to read data from Flash or write a firmware image file to Flash. |
| ISP_HID | Sample ISP firmware communicated with the ISP tool through a USB HID interface. |
| ISP_I2C | Sample ISP firmware communicated with the ISP tool through an I ² C interface. |
| ISP_RS485 | Sample ISP firmware communicated with the ISP tool through a RS485 interface. |
| ISP_SPI | Sample ISP firmware communicated with the ISP tool through a SPI interface. |
| ISP_UART | Sample ISP firmware communicated with the ISP tool through a UART interface. |

5 .\SampleCode\RegBase

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| ACMP_ComapreVBG | Demonstrate analog comparator (ACMP) comparison by comparing ACMP1_P1 input and VBG voltage and shows the result on UART console. |
| ACMP_Wakeup | Use ACMP to wake up system from Power-down mode while comparator output changes. |
| ACMP_WindowCompare | Show how to monitor ACMP input with window compare function. |
| ACMP_WindowLatch | Demonstrate how to use ACMP window latch mode. |
| ADC_2Msps_ContinuousScanMode | Demonstrate how to use PLL as ADC clock source to achieve 2 Msps ADC conversion rate. |
| ADC_1411ksps_ContinuousScanMode | Demonstrate how to use HIRC as ADC clock source to achieve 1411 ksps ADC conversion rate. |
| ADC_ADINT_Trigger | Use ADINT interrupt to do the ADC Single-cycle scan conversion. |
| ADC_BandGap | Convert band-gap (channel 29) and print a conversion result. |
| ADC_BandGapCalculateAVDD | Demonstrate how to calculate battery voltage (AV _{DD}) by using band-gap. |
| ADC_BurstMode | Perform A/D Conversion with ADC burst mode. |
| ADC_ContinuousScanMode | Perform A/D Conversion with ADC continuous scan mode. |
| ADC_PDMA_PWM_Trigger | Demonstrate how to trigger ADC by PWM and transfer conversion data by PDMA. |
| ADC_PWM_Trigger | Demonstrate how to trigger ADC by PWM. |
| ADC_ResultMonitor | Monitor the conversion result of channel 2 by the digital compare function. |
| ADC_SingleCycleScanMode | Perform A/D Conversion with ADC single cycle scan mode. |

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| ADC_SingleMode | Perform A/D Conversion with ADC single mode. |
| ADC_STADC_Trigger | Show how to trigger ADC by STADC pin. |
| ADC_SwTrg_Trigger | Trigger ADC by writing ADC software trigger register. |
| ADC_Timer_Trigger | Show how to trigger ADC by timer. |
| BPWM_Capture | Capture the BPWM1 Channel 0 waveform by BPWM0 Channel 0. |
| BPWM_DoubleBuffer | Change duty cycle and period of output waveform by BPWM Double Buffer function. |
| BPWM_DutySwitch | Change duty cycle of output waveform by a configured period. |
| BPWM_OutputWaveform | Demonstrate how to use BPWM counter output waveform. |
| BPWM_SyncStart | Demonstrate how to use BPWM counter synchronous start function. |
| CLK_ClockDetector | Demonstrate the usage of clock fail detector and clock frequency range detector function. |
| CRC_CCITT | Implement CRC in CRC-CCITT mode and get the CRC checksum result. |
| CRC_CRC8 | Implement CRC in CRC-8 mode and get the CRC checksum result. |
| CRC_CRC32_PDMA | Implement CRC in CRC-32 mode and get the CRC checksum result. |
| EBI_NOR | Configure EBI interface to access NOR Flash connected on EBI interface. |
| EBI_SRAM | Configure EBI interface to access SRAM connected on EBI interface. |
| FMC_IAP | Demonstrate FMC IAP boot mode and show how to use vector remap function. LDROM image is embedded in APROM image and programmed to LDROM Flash at run-time. This sample also shows how to branch between APROM and LDROM. |

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| FMC_RW | Show FMC read Flash IDs, erase, read, and write functions. |
| GPIO_EINTAndDebounce | Show the usage of GPIO external interrupt function and de-bounce function. |
| GPIO_INT | Show the usage of GPIO interrupt function. |
| GPIO_OutputInput | Show how to set GPIO pin mode and use pin data input/output control. |
| GPIO_PowerDown | Show how to wake up system from Power-down mode by GPIO interrupt. |
| HDIV | Demonstrate how to divide two signed integers by HDIV engine. |
| I2C_EEPROM | Show how to use I ² C interface to access EEPROM. |
| I2C_GCMode_Master | Show how a master uses I ² C address 0x0 to write data to a slave. This sample code needs to work with I2C_GCMode_Slave. |
| I2C_GCMode_Slave | Show how a Slave receives data from a master in GC (General Call) mode. This sample code needs to work with I2C_GCMode_Master. |
| I2C_Loopback | Demonstrate how to set I ² C Master mode and Slave Mode, and show how a master accesses a slave on a chip. |
| I2C_Master | Show how a master accesses a slave. This sample code needs to work with I2C_Slave. |
| I2C_MultiBytes_Master | Show how to set I ² C Multi bytes API Read and Write data to Slave. This sample code needs to work with I2C_Slave. |
| I2C_PDMA_TRX | Demonstrate I ² C PDMA mode. Need to connect I2C0 (master) and I2C1 (slave). |
| I2C_SingleByte_Master | Show how to use I ² C Single byte API Read and Write data to Slave. This sample code needs to work with I2C_Slave. |
| I2C_Slave | Demonstrate how to set I ² C in Slave mode to receive 256 bytes data from a master. This sample code needs |

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| | to work with I2C_Master. |
| I2C_Wakeup_Slave | Show how to wake up MCU from Power-down mode via the I ² C interface. This sample code needs to work with I2C_Master. |
| I2S_Master | Configure SPI in I ² S Master mode and demonstrate how I ² S works in Master mode. |
| I2S_PDMA_NAU8822 | An I ² S demo with PDMA function connected to audio codec NAU8822. |
| I2S_PDMA_Play | An I ² S demo for playing data and demonstrating how I ² S works with PDMA. |
| I2S_PDMA_PlayRecrod | An I ² S demo for playing and recording data with PDMA function. |
| I2S_PDMA_Record | An I ² S demo for recording data and demonstrating how I ² S works with PDMA. |
| I2S_Slave | Configure SPI as I ² S Slave mode and demonstrate how I ² S works in Slave mode. This sample code needs to work with I2S_Master. |
| PDMA_ADC_1882ksps_ContinousScanMode | Demonstrate how to transfer 1.822 Msps conversion data from ADC to SRAM by PDMA when ADC clock source is selected to HXT that is connected to 32 MHz crystal. |
| PDMA_BasicMode | Use PDMA channel 1 to transfer data from memory to memory. |
| PDMA_ScatterGather | Use PDMA channel 1 to transfer data from memory to memory by scatter-gather mode. |
| PDMA_ScatterGather_PingPongBuffer | Use PDMA to implement Ping-Pong buffer by scatter-gather mode (memory to memory). |
| PDMA_TimerCapture_CalculatePlusePeriod | Demonstrate timer capture function to measure the frequency of external signal through PDMA transfer. |
| PDMA_TimerTrigger_SRAM2GPIO | Demonstrate how to use PDMA channel 1 to transfer data from SRAM to GPIO based on 1 kHz timer trigger. |
| PWM_240KHz_DutySwitch | Demonstrate how to set PWM0 channel 0 output 240 kHz waveform and switch duty in each 0.5%. |

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| PWM_Capture | Capture the PWM0 Channel 0 waveform by PWM0 Channel 2. |
| PWM_DeadZone | Demonstrate how to use PWM Dead Time function. |
| PWM_DoubleBuffer_PeriodLoadingMode | Change duty cycle and period of output waveform by PWM Double Buffer function. |
| PWM_DutySwitch | Change duty cycle of output waveform by a configured period. |
| PWM_OutputWaveForm | Demonstrate how to use PWM counter output waveform. |
| PWM_PDMA_Capture | Capture the PWM0 Channel 0 waveform by PWM0 Channel 2, and use PDMA to transfer captured data. |
| PWM_PDMA_Capture_1MHzSignal | Capture the PWM0 Channel 0 waveform by PWM0 Channel 2, and use PDMA to transfer captured data. The frequency of PWM Channel 0 is 1 MHz, which is used to test the maximum input frequency for PWM Capture function. |
| PWM_SyncStart | Demonstrate how to use PWM0 counter synchronous start function. |
| QSPI_DualMode_Flash | Access SPI Flash using QSPI dual mode. |
| QSPI_QuadMode_Flash | Access SPI Flash using QSPI quad mode. |
| RTC_Alarm_Test | Demonstrate the RTC alarm function that sets an alarm 10 seconds after execution. |
| RTC_Alarm_Wakeup | Demonstrate how to wake up system periodically with RTC interrupt. |
| RTC_Time_Display | Demonstrate the RTC function and display the current time to the UART console. |
| SPI_LoopBack | SPI read/write demo connecting SPI MISO and MOSI pins. |
| SPI_MasterFIFOmode | Configure SPI as Master mode and demonstrate how to communicate with an off-chip SPI slave device with FIFO mode. This sample code needs to work with SPI_SlaveFIFOmode. |

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| SPI_PDMA_LoopTest | SPI read/write demo in PDMA mode. Connecting SPI MISO and MOSI pins. Both TX PDMA function and RX PDMA function will be enabled. |
| SPI_SlaveFIFOmode | Configure SPI as Slave mode and demonstrate how to communicate with an off-chip SPI master device with FIFO mode. This sample code needs to work with SPI_MasterFIFOmode. |
| SYS_BODWakeup | Demonstrate how to wake up system from Power-down mode by brown-out detector interrupt. |
| SYS_PLLClockOutput | Change system clock to different PLL frequency and output system clock from CLKO pin. |
| SYS_TrimHIRC | Demonstrate how to use LXT to trim HIRC. |
| TIMER_ACMPTrigger | Use ACMP to trigger timer reset mode. |
| TIMER_CaptureCounter | Show how to use the Timer capture function to capture Timer counter value. |
| TIMER_Delay | Demonstrate the usage of TIMER_Delay() API to generate a 1 second delay. |
| TIMER_EventCounter | Use TM0 pin to demonstrate timer event counter function. |
| TIMER_FreeCountingMode | Use the timer TM0_EXT pin to demonstrate timer free counting mode function, and display the measured input frequency to UART console. |
| TIMER_InterTimerTriggerMode | Use the timer TM0 pin to demonstrate inter timer trigger mode function, and display the measured input frequency to UART console. |
| TIMER_Periodic | Use the timer periodic mode to generate timer interrupt every 1 second. |
| TIMER_PeriodicINT | Implement timer counting in periodic mode. |
| TIMER_SW_RTC | Implement software RTC function by Timer0. |
| TIMER_TimeOutWakeup | Use timer to wake up system from Power-down mode periodically. |
| TIMER_ToggleOut | Demonstrate the timer 0 toggle out function on TM0 pin. |

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| UART_6Mbps_SingleWire | Demonstrate how to transfer 6 Mbps UART data through Single Wire. |
| UART_AutoBaudRate | Show how to use auto baud rate detection function. |
| UART_AutoFlow | Transmit and receive data using auto flow control. |
| UART_IrDA | Transmit and receive UART data in UART IrDA mode. |
| UART_PDMA | Demonstrate UART transmit and receive function with PDMA. |
| UART_RS485 | Transmit and receive data in UART RS485 mode. |
| UART_SingleWire | Transmit and receive data in UART single-wire mode. |
| UART_TxRxFunction | Transmit and receive data from PC terminal via the RS232 interface. |
| UART_Wakeup | Show how to wake up system from Power-down mode by UART interrupt. |
| USCI_I2C_EEPROM | Show how to use USCI_I2C interface to access EEPROM. |
| USCI_I2C_Loopback | Show how a master accesses 7-bit address Slave (loopback). |
| USCI_I2C_Loopback_10bit | Show how a master accesses 10-bit address Slave (loopback). |
| USCI_I2C_Master | Show how a master accesses a slave. This sample code needs to work with USCI_I2C_Slave. |
| USCI_I2C_Master_10bit | Show how a master accesses a 10-bit address slave. This sample code need works with USCI_I2C_Slave_10bit. |
| USCI_I2C_Monitor | Demonstrate USCI_I2C Monitor mode. |
| USCI_I2C_MultiBytes_Master | Show how to set USCI_I2C Multi bytes API Read and Write data to Slave. This sample code needs to work with USCI_I2C_Slave. |
| USCI_I2C_SingleByte_Master | Show how to use USCI_I2C Single byte API Read and Write data to Slave. This sample code needs to work with USCI_I2C_Slave. |

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| USCI_I2C_Slave | Show how a slave receives data from a master. This sample code needs to work with USCI_I2C_Master. |
| USCI_I2C_Slave_10bit | Show how a 10-bit address slave receives data from a master. This sample code need works with USCI_I2C_Master_10bit. |
| USCI_I2C_Wakeup_Slave | Show how to wake up USCI_I2C from Deep Sleep mode. This sample code needs to work with USCI_I2C_Master. |
| USCI_SPI_Loopback | Implement USCI_SPI0 Master loop back transfer. This sample code needs to connect USCI_SPI0_MISO pin and USCI_SPI0_MOSI pin together. It will compare the received data with transmitted data. |
| USCI_SPI_MasterMode | Configure USCI_SPI0 as Master mode and demonstrate how to communicate with an off-chip SPI slave device. This sample code needs to work with USCI_SPI_SlaveMode. |
| USCI_SPI_PDMA_LoopTest | Demonstrate USCI_SPI data transfer with PDMA. USCI_SPI0 will be configured as Master mode and USCI_SPI1 will be configured as Slave mode. Both TX PDMA function and RX PDMA function will be enabled. |
| USCI_SPI_SlaveMode | Configure USCI_SPI0 as Slave mode and demonstrate how to communicate with an off-chip SPI master device. This sample code needs to work with USCI_SPI_MasterMode. |
| USCI_UART_AutoBaudRate | Show how to use auto baud rate detection function. |
| USCI_UART_Autoflow_Master | Transmit and receive data with auto flow control. This sample code needs to work with USCI_UART_Autoflow_Slave. |
| USCI_UART_Autoflow_Slave | Transmit and receive data with auto flow control. This sample code needs to work with USCI_UART_Autoflow_Master. |
| USCI_UART_PDMA | This is a USCI_UART PDMA demo and needs to connect USCI_UART TX and RX. |
| USCI_UART_RS485_Master | Transmit and receive data in RS485 mode. This sample code needs to work with USCI_UART_RS485_Slave. |

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| USCI_UART_RS485_Slave | Transmit and receive data in RS485 mode. This sample code needs to work with USCI_UART_RS485_Master. |
| USCI_UART_TxRxFunction | Transmit and receive data from PC terminal via the RS232 interface. |
| USCI_UART_Wakeup | Show how to wake up system from Power-down mode by USCI interrupt in UART mode. |
| WDT_TimeoutWakeupAndReset | Implement WDT time-out interrupt event to wake up system and generate time-out reset system event while WDT time-out reset delay period expired. |
| WWDT_ReloadCounter | Show how to reload the WWDT counter value. |

| Category Type | Part Number | Note |
|---------------|--|------|
| Type-B | M031EB0AE, M031FB0AE, M031TB0AE | |
| Type-C | M031EC1AE, M031FC1AE, M031TC1AE | |
| Type-D | M031LD2AE, M031SD2AE, M031TD2AE, M031LC2AE, M031SC2AE | |
| Type-E | M031LE3AE, M031SE3AE, M032LE3AE, M032SE3AE | |
| Type-I | M031SIAAE, M031KIAAE, M032SIAAE, M032KIAAE | |
| Type-G | M031LG6AE, M031SG6AE, M031KG6AE, M031LG8AE, M031SG8AE, M031KG8AE, M032LG6AE, M032SG6AE, M032KG6AE, M032LG8AE, M032SG8AE, M032KG8AE | |

| Category Type | Type-B | Type-C | Type-D | Type-E | Type-I | Type-G |
|---------------------------|--------|--------|--------|--------|--------|--------|
| Sample Code | | | | | | |
| ACMP_ComapreVBG | - | - | √ | √ | √ | √ |
| ACMP_Wakeup | - | - | √ | √ | √ | √ |
| ACMP_WindowCompare | - | - | √ | √ | √ | √ |
| ACMP_WindowLatch | - | - | √ | √ | √ | √ |

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| ADC_2Msps_ContinuousScanMode | - | - | √ | √ | √ | √ |
| ADC_1411ksps_ContinuousScanMode | √ | √ | √ | √ | √ | √ |
| ADC_ADINT_Trigger | √ | √ | √ | √ | √ | √ |
| ADC_BandGap | √ | √ | √ | √ | √ | √ |
| ADC_BandGapCalculateAVDD | √ | √ | √ | √ | √ | √ |
| ADC_BurstMode | √ | √ | √ | √ | √ | √ |
| ADC_ContinuousScanMode | √ | √ | √ | √ | √ | √ |
| ADC_PDMA_PWM_Trigger | - | √ | √ | √ | √ | √ |
| ADC_PWM_Trigger | √ | √ | √ | √ | √ | √ |
| ADC_ResultMonitor | √ | √ | √ | √ | √ | √ |
| ADC_SingleCycleScanMode | √ | √ | √ | √ | √ | √ |
| ADC_SingleMode | √ | √ | √ | √ | √ | √ |
| ADC_STADC_Trigger | √ | √ | √ | √ | √ | √ |
| ADC_SwTrg_Trigger | √ | √ | √ | √ | √ | √ |
| ADC_Timer_Trigger | √ | √ | √ | √ | √ | √ |
| BPWM_Capture | - | - | - | - | √ | √ |
| BPWM_DoubleBuffer | - | - | - | - | √ | √ |
| BPWM_DutySwitch | - | - | - | - | √ | √ |
| BPWM_OutputWaveform | - | - | - | - | √ | √ |
| BPWM_SyncStart | - | - | - | - | √ | √ |
| CLK_ClockDetector | √ | √ | √ | √ | √ | √ |
| CRC_CCITT | √ | √ | √ | √ | √ | √ |
| CRC_CRC8 | √ | √ | √ | √ | √ | √ |
| CRC_CRC32_PDMA | - | √ | √ | √ | √ | √ |

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|--|---|---|---|---|---|---|
| EBI_NOR | - | - | - | √ | √ | √ |
| EBI_SRAM | - | - | - | √ | √ | √ |
| FMC_IAP | √ | √ | √ | √ | √ | √ |
| FMC_RW | √ | √ | √ | √ | √ | √ |
| GPIO_EINTAndDebounce | √ | √ | √ | √ | √ | √ |
| GPIO_INT | √ | √ | √ | √ | √ | √ |
| GPIO_OutputInput | √ | √ | √ | √ | √ | √ |
| GPIO_PowerDown | √ | √ | √ | √ | √ | √ |
| HDIV | √ | √ | √ | √ | √ | √ |
| I2C_EEPROM | √ | √ | √ | √ | √ | √ |
| I2C_GCMode_Master | √ | √ | √ | √ | √ | √ |
| I2C_GCMode_Slave | √ | √ | √ | √ | √ | √ |
| I2C_Loopback | √ | √ | √ | √ | √ | √ |
| I2C_Master | √ | √ | √ | √ | √ | √ |
| I2C_MultiBytes_Master | √ | √ | √ | √ | √ | √ |
| I2C_PDMA_TRX | - | - | √ | √ | √ | √ |
| I2C_SingleByte_Master | √ | √ | √ | √ | √ | √ |
| I2C_Slave | √ | √ | √ | √ | √ | √ |
| I2C_Wakeup_Slave | √ | √ | √ | √ | √ | √ |
| I2S_Master | √ | √ | √ | √ | √ | √ |
| I2S_PDMA_NAU8822 | - | √ | √ | √ | √ | √ |
| I2S_PDMA_Play | - | √ | √ | √ | √ | √ |
| I2S_PDMA_PlayRecrod | - | √ | √ | √ | √ | √ |
| I2S_PDMA_Record | - | √ | √ | √ | √ | √ |
| I2S_Slave | √ | √ | √ | √ | √ | √ |
| PDMA_ADC_1882ksps_ContinousScanMode | - | √ | √ | √ | √ | √ |
| PDMA_BasicMode | - | √ | √ | √ | √ | √ |

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|---|---|---|---|---|---|---|
| PDMA_ScatterGather | - | √ | √ | √ | √ | √ |
| PDMA_ScatterGather_PingPongBuffer | - | √ | √ | √ | √ | √ |
| PDMA_TimerCapture_CalculatePlusePeriod | - | √ | √ | √ | √ | √ |
| PDMA_TimerTrigger_SRAM2GPIO | - | √ | √ | √ | √ | √ |
| PWM_240KHz_DutySwitch | √ | √ | √ | √ | √ | √ |
| PWM_Capture | √ | √ | √ | √ | √ | √ |
| PWM_DeadZone | √ | √ | √ | √ | √ | √ |
| PWM_DoubleBuffer_PeriodLoadingMode | √ | √ | √ | √ | √ | √ |
| PWM_DutySwitch | √ | √ | √ | √ | √ | √ |
| PWM_OutputWaveForm | √ | √ | √ | √ | √ | √ |
| PWM_PDMA_Capture | - | √ | √ | √ | √ | √ |
| PWM_PDMA_Capture_1MHzSignal | - | √ | √ | √ | √ | √ |
| PWM_SyncStart | √ | √ | √ | √ | √ | √ |
| QSPI_DualMode_Flash | - | - | - | - | √ | √ |
| QSPI_QuadMode_Flash | - | - | - | - | √ | √ |
| RTC_Alarm_Test | - | - | - | - | √ | √ |
| RTC_Alarm_Wakeup | - | - | - | - | √ | √ |
| RTC_Time_Display | - | - | - | - | √ | √ |
| SPI_LoopBack | √ | √ | √ | √ | √ | √ |
| SPI_MasterFIFOmode | √ | √ | √ | √ | √ | √ |
| SPI_PDMA_LoopTest | - | √ | √ | √ | √ | √ |
| SPI_SlaveFIFOmode | √ | √ | √ | √ | √ | √ |
| SYS_BODWakeup | √ | √ | √ | √ | √ | √ |
| SYS_PLLClockOutput | - | - | √ | √ | √ | √ |

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|------------------------------------|---|---|---|---|---|---|
| SYS_PowerDon_MinCurrent | √ | √ | √ | √ | √ | √ |
| SYS_TrimHIRC | - | √ | √ | √ | √ | √ |
| TIMER_ACMPTTrigger | - | - | √ | √ | √ | √ |
| TIMER_CaptureCounter | - | √ | √ | √ | √ | √ |
| TIMER_Delay | √ | √ | √ | √ | √ | √ |
| TIMER_EventCounter | √ | √ | √ | √ | √ | √ |
| TIMER_FreeCountingMode | √ | √ | √ | √ | √ | √ |
| TIMER_InterTimerTriggerMode | √ | √ | √ | √ | √ | √ |
| TIMER_Periodic | √ | √ | √ | √ | √ | √ |
| TIMER_PeriodicINT | - | √ | √ | √ | √ | √ |
| TIMER_SW_RTC | - | √ | √ | √ | √ | √ |
| TIMER_TimeOutWakeup | √ | √ | √ | √ | √ | √ |
| TIMER_ToggleOut | √ | √ | √ | √ | √ | √ |
| UART_6Mbps_SingleWire | √ | √ | √ | √ | √ | √ |
| UART_AutoBaudRate | √ | √ | √ | √ | √ | √ |
| UART_AutoFlow | √ | √ | √ | √ | √ | √ |
| UART_IrDA | √ | √ | √ | √ | √ | √ |
| UART_PDMA | - | √ | √ | √ | √ | √ |
| UART_RS485 | √ | √ | √ | √ | √ | √ |
| UART_SingleWire | √ | √ | √ | √ | √ | √ |
| UART_TxRxFunction | √ | √ | √ | √ | √ | √ |
| UART_Wakeup | √ | √ | √ | √ | √ | √ |
| USCI_I2C_EEPROM | - | - | √ | √ | √ | √ |
| USCI_I2C_Loopback | - | - | - | - | √ | √ |
| USCI_I2C_Loopback_10bit | - | - | - | - | √ | √ |
| USCI_I2C_Master | - | - | √ | √ | √ | √ |

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|-----------------------------------|---|---|---|---|---|---|
| USCI_I2C_Master_10bit | - | - | √ | √ | √ | √ |
| USCI_I2C_Monitor | - | - | √ | √ | √ | √ |
| USCI_I2C_MultiBytes_Master | - | - | √ | √ | √ | √ |
| USCI_I2C_SingleByte_Master | - | - | √ | √ | √ | √ |
| USCI_I2C_Slave | - | - | √ | √ | √ | √ |
| USCI_I2C_Slave_10bit | - | - | √ | √ | √ | √ |
| USCI_I2C_Wakeup_Slave | - | - | √ | √ | √ | √ |
| USCI_SPI_Loopback | - | - | √ | √ | √ | √ |
| USCI_SPI_MasterMode | - | - | √ | √ | √ | √ |
| USCI_SPI_PDMA_LoopTest | - | - | - | - | √ | √ |
| USCI_SPI_SlaveMode | - | - | √ | √ | √ | √ |
| USCI_UART_AutoBaudRate | - | - | √ | √ | √ | √ |
| USCI_UART_Autoflow_Master | - | - | √ | √ | √ | √ |
| USCI_UART_Autoflow_Slave | - | - | √ | √ | √ | √ |
| USCI_UART_PDMA | - | - | √ | √ | √ | √ |
| USCI_UART_RS485_Master | - | - | √ | √ | √ | √ |
| USCI_UART_RS485_Slave | - | - | √ | √ | √ | √ |
| USCI_UART_TxRxFunction | - | - | √ | √ | √ | √ |
| USCI_UART_Wakeup | - | - | √ | √ | √ | √ |
| WDT_TimeoutWakeupAndReset | √ | √ | √ | √ | √ | √ |
| WWDT_ReloadCounter | √ | √ | √ | √ | √ | √ |

6 .\SampleCode\StdDriver

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| ACMP_ComapreVBG | Demonstrate analog comparator (ACMP) comparison by comparing ACMP1_P1 input and VBG voltage and shows the result on UART console. |
| ACMP_Wakeup | Use ACMP to wake up system from Power-down mode while comparator output changes. |
| ACMP_WindowCompare | Show how to monitor ACMP input with window compare function. |
| ACMP_WindowLatch | Demonstrate how to use ACMP window latch mode. |
| ADC_2Msps_ContinuousScanMode | Demonstrate how to use PLL as ADC clock source to achieve 2 Msps ADC conversion rate. |
| ADC_1411ksps_ContinuousScanMode | Demonstrate how to use HIRC as ADC clock source to achieve 1411 ksps ADC conversion rate. |
| ADC_ADINT_Trigger | Use ADINT interrupt to do the ADC Single-cycle scan conversion. |
| ADC_BandGap | Convert band-gap (channel 29) and print a conversion result. |
| ADC_BandGapCalculate AVDD | Demonstrate how to calculate battery voltage (AVDD) by using band-gap. |
| ADC_BurstMode | Perform A/D Conversion with ADC burst mode. |
| ADC_ContinuousScanMode | Perform A/D Conversion with ADC continuous scan mode. |
| ADC_PDMA_PWM_Trigger | Demonstrate how to trigger ADC by PWM and transfer conversion data by PDMA. |
| ADC_PWM_Trigger | Demonstrate how to trigger ADC by PWM. |
| ADC_ResultMonitor | Monitor the conversion result of channel 2 by the digital compare function. |
| ADC_SingleCycleScanMode | Perform A/D Conversion with ADC single cycle scan mode. |

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| ADC_SingleMode | Perform A/D Conversion with ADC single mode. |
| ADC_STADC_Trigger | Show how to trigger ADC by STADC pin. |
| ADC_SwTrg_Trigger | Trigger ADC by writing ADC software trigger register. |
| ADC_Timer_Trigger | Show how to trigger ADC by timer. |
| BPWM_Capture | Capture the BPWM1 Channel 0 waveform by BPWM0 Channel 0. |
| BPWM_DoubleBuffer | Change duty cycle and period of output waveform by BPWM Double Buffer function. |
| BPWM_DutySwitch | Change duty cycle of output waveform by a configured period. |
| BPWM_OutputWaveform | Demonstrate how to use BPWM counter output waveform. |
| BPWM_SyncStart | Demonstrate how to use BPWM counter synchronous start function. |
| CLK_ClockDetector | Demonstrate the usage of clock fail detector and clock frequency range detector function. |
| CRC_CCITT | Implement CRC in CRC-CCITT mode and get the CRC checksum result. |
| CRC_CRC8 | Implement CRC in CRC-8 mode and get the CRC checksum result. |
| CRC_CRC32_PDMA | Implement CRC in CRC-32 mode and get the CRC checksum result. |
| EBI_NOR | Configure EBI interface to access NOR Flash connected on EBI interface. |
| EBI_SRAM | Configure EBI interface to access SRAM connected on EBI interface. |
| FMC_CRC32 | Demonstrate how to use FMC CRC32 ISP command to calculate the CRC32 checksum of APROM, LDROM, and SPROM. |
| FMC_ExecInSRAM | Implement a code and execute in SRAM to program embedded Flash. |

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| FMC_IAP | Demonstrate FMC IAP boot mode and show how to use vector remap function. LDROM image is embedded in APROM image and programmed to LDROM Flash at run-time. This sample also shows how to branch between APROM and LDROM. |
| FMC_MultiBoot | Implement a multi-boot system to boot from different applications in APROM. A LDROM code and 4 APROM code are implemented in this sample code. |
| FMC_MultiWordProgram | Show FMC multi-word program ISP command to program APROM 0x10000~0x20000 area. |
| FMC_ReadAllOne | Demonstrate how to use FMC Read-All-One ISP command to verify if APROM/LDROM pages are all 0xFFFFFFFF. |
| FMC_RW | Show FMC read Flash IDs, erase, read, and write functions. |
| GPIO_EINTAndDebounce | Show the usage of GPIO external interrupt function and de-bounce function. |
| GPIO_INT | Show the usage of GPIO interrupt function. |
| GPIO_OutputInput | Show how to set GPIO pin mode and use pin data input/output control. |
| GPIO_PowerDown | Show how to wake up system from Power-down mode by GPIO interrupt. |
| HDIV | Demonstrate how to divide two signed integers by HDIV engine. |
| I2C_EEPROM | Show how to use I ² C interface to access EEPROM. |
| I2C_GCMode_Master | Show how a master uses I ² C address 0x0 to write data to a slave. This sample code needs to work with I2C_GCMode_Slave. |
| I2C_GCMode_Slave | Show how a slave receives data from a master in GC (General Call) mode. This sample code needs to work with I2C_GCMode_Master. |
| I2C_Loopback | Demonstrate how to set I ² C Master mode and Slave Mode, and show how a master accesses a slave on a chip. |

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| I2C_Master | Show how a master accesses a slave. This sample code needs to work with I2C_Slave. |
| I2C_MultiBytes_Master | Show how to set I ² C Multi bytes API Read and Write data to Slave. This sample code needs to work with I2C_Slave. |
| I2C_PDMA_TRX | Demonstrate I ² C PDMA mode. Need to connect I2C0 (master) and I2C1 (slave). |
| I2C_SingleByte_Master | Show how to use I ² C Single byte API Read and Write data to Slave. This sample code needs to work with I2C_Slave. |
| I2C_Slave | Demonstrate how to set I ² C in Slave mode to receive 256 bytes data from a master. This sample code needs to work with I2C_Master. |
| I2C_Wakeup_Slave | Show how to wake up MCU from Power-down mode via the I ² C interface. This sample code needs to work with I2C_Master. |
| I2S_Master | Configure SPI in I ² S Master mode and demonstrate how I ² S works in Master mode. |
| I2S_PDMA_NAU8822 | An I ² S demo with PDMA function connected to audio codec NAU8822. |
| I2S_PDMA_Play | An I ² S demo for playing data and demonstrating how I ² S works with PDMA. |
| I2S_PDMA_PlayRecrod | An I ² S demo for playing and recording data with PDMA function. |
| I2S_PDMA_Record | An I ² S demo for recording data and demonstrating how I ² S works with PDMA. |
| I2S_Slave | Configure SPI as I ² S Slave mode and demonstrate how I ² S works in Slave mode. This sample code needs to work with I2S_Master. |
| PDMA_ADC_1882ksps_ContinuousScanMode | Demonstrate how to transfer 1.822 Msps conversion data from ADC to SRAM by PDMA when ADC clock source is selected to HXT that is connected to 32 MHz crystal. |
| PDMA_BasicMode | Use PDMA channel 1 to transfer data from memory to memory. |

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| PDMA_ScatterGather | Use PDMA channel 1 to transfer data from memory to memory by scatter-gather mode. |
| PDMA_ScatterGather_PingPongBuffer | Use PDMA to implement Ping-Pong buffer by scatter-gather mode (memory to memory). |
| PDMA_TimerCapture_CalculatePlusePeriod | Demonstrate timer capture function to measure the frequency of external signal through PDMA transfer. |
| PDMA_TimerTrigger_SRAM2GPIO | Demonstrate how to use PDMA channel 1 to transfer data from SRAM to GPIO based on 1 kHz timer trigger. |
| PWM_240KHz_DutySwitch | Demonstrate how to set PWM0 channel 0 output 240 kHz waveform and switch duty in each 0.5%. |
| PWM_Capture | Capture the PWM0 Channel 0 waveform by PWM0 Channel 2. |
| PWM_DeadZone | Demonstrate how to use PWM Dead Time function. |
| PWM_DoubleBuffer_PeriodLoadingMode | Change duty cycle and period of output waveform by PWM Double Buffer function. |
| PWM_DutySwitch | Change duty cycle of output waveform by a configured period. |
| PWM_OutputWaveForm | Demonstrate how to use PWM counter output waveform. |
| PWM_PDMA_Capture | Capture the PWM0 Channel 0 waveform by PWM0 Channel 2, and use PDMA to transfer captured data. |
| PWM_PDMA_Capture_1MHzSignal | Capture the PWM0 Channel 0 waveform by PWM0 Channel 2, and use PDMA to transfer captured data. The frequency of PWM Channel 0 is 1 MHz, which is used to test the maximum input frequency for PWM Capture function. |
| PWM_SyncStart | Demonstrate how to use PWM0 counter synchronous start function. |
| QSPI_DualMode_Flash | Access SPI Flash using QSPI dual mode. |
| QSPI_QuadMode_Flash | Access SPI Flash using QSPI quad mode. |
| RTC_Alarm_Test | Demonstrate the RTC alarm function that sets an alarm 10 seconds after execution. |

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| RTC_Alarm_Wakeup | Demonstrate how to wake up system periodically with RTC interrupt. |
| RTC_Time_Display | Demonstrate the RTC function and display the current time to the UART console. |
| SPI_LoopBack | SPI read/write demo connecting SPI MISO and MOSI pins. |
| SPI_MasterFIFOmode | Configure SPI as Master mode and demonstrate how to communicate with an off-chip SPI slave device with FIFO mode. This sample code needs to work with SPI_SlaveFIFOmode. |
| SPI_PDMA_LoopTest | SPI read/write demo in PDMA mode. Connecting SPI MISO and MOSI pins. Both TX PDMA function and RX PDMA function will be enabled. |
| SPI_SlaveFIFOmode | Configure SPI as Slave mode and demonstrate how to communicate with an off-chip SPI master device with FIFO mode. This sample code needs to work with SPI_MasterFIFOmode. |
| SYS_BODWakeup | Demonstrate how to wake up system from Power-down mode by brown-out detector interrupt. |
| SYS_PLLClockOutput | Change system clock to different PLL frequency and output system clock from CLKO pin. |
| SYS_PowerDown_MinCurrent | Demonstrate how to minimize power consumption when entering Power-down mode. |
| SYS_TrimHIRC | Demonstrate how to use LXT to trim HIRC. |
| TIMER_ACMPTrigger | Use ACMP to trigger timer reset mode. |
| TIMER_CaptureCounter | Show how to use the Timer capture function to capture Timer counter value. |
| TIMER_Delay | Demonstrate the usage of TIMER_Delay() API to generate a 1 second delay. |
| TIMER_EventCounter | Use TM0 pin to demonstrate timer event counter function. |
| TIMER_FreeCountingMode | Use the timer TM0_EXT pin to demonstrate timer free counting mode function, and display the measured input |

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| | frequency to UART console. |
| TIMER_InterTimerTrigger Mode | Use the timer TM0 pin to demonstrate inter timer trigger mode function, and display the measured input frequency to UART console. |
| TIMER_Periodic | Use the timer periodic mode to generate timer interrupt every 1 second. |
| TIMER_PeriodicINT | Implement timer counting in periodic mode. |
| TIMER_SW_RTC | Implement software RTC function by Timer0. |
| TIMER_TimeOutWakeup | Use timer to wake up system from Power-down mode periodically. |
| TIMER_ToggleOut | Demonstrate the timer 0 toggle out function on TM0 pin. |
| UART_6Mbps_SingleWire | Demonstrate how to transfer 6 Mbps UART data through Single Wire. |
| UART_115200bps_SingleWire_ISP | The UART ISP LDROM firmware used to update APROM through Single Wire (PB.12). The UART must be set to "baud-rate 115200 bps" and "8-N-1". Boot option must be set to "boot in LDROM". |
| UART_AutoBaudRate | Show how to use auto baud rate detection function. |
| UART_AutoFlow | Transmit and receive data using auto flow control. |
| UART_IrDA | Transmit and receive UART data in UART IrDA mode. |
| UART_PDMA | Demonstrate UART transmit and receive function with PDMA. |
| UART_RS485 | Transmit and receive data in UART RS485 mode. |
| UART_SingleWire | Transmit and receive data in UART single-wire mode. |
| UART_TxRxFunction | Transmit and receive data from PC terminal via the RS232 interface. |
| UART_Wakeup | Show how to wake up system from Power-down mode by UART interrupt. |
| USBDAudio_NAU8822_Headset | Demonstrate how to implement a USB audio class device (Headset) with HID key (MediaKey/JoyStick). NAU8822 is used in this sample code to play the audio data from |

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| | Host. It also supports to record data from NAU8822 to Host. |
| USBD_Audio_NAU8822_Microphone | Demonstrate how to implement a USB audio class device (Microphone) with HID key (MediaKey/JoyStick). NAU8822 is used in this sample code to record data from NAU8822 to Host. |
| USBD_Audio_NAU8822_Speaker | Demonstrate how to implement a USB audio class device (Speaker) with HID key (MediaKey/JoyStick). NAU8822 is used in this sample code to play the audio data from Host. |
| USBD_HID_Keyboard | Demonstrate how to implement a USB keyboard device. This sample code supports to use GPIO to simulate key input. |
| USBD_HID_Mouse | Simulate a USB mouse and draw circles on the screen. |
| USBD_HID_MouseKeyboard | Simulate a USB HID mouse and HID keyboard. Mouse draws circles on the screen and Keyboard uses GPIO to simulate key input. |
| USBD_HID_RemoteWakeup | Simulate how a HID mouse supports USB suspend and remote wakeup. |
| USBD_HID_Touch | Demonstrate how to implement a USB touch digitizer device. Two lines demo in Paint. |
| USBD_HID_Transfer | Demonstrate how to transfer data between a USB device and PC through a USB HID interface. A windows tool is also included in this sample code to connect with a USB device. |
| USBD_HID_Transfer_And_Keyboard | Demonstrate how to implement a composite device (HID Transfer and keyboard). Transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with a USB device. |
| USBD_HID_Transfer_And_MSC | Demonstrate how to implement a composite device (HID Transfer and Mass storage). Transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with a USB device. |
| USBD_HID_Transfer_CTRL | Use USB Host core driver and HID driver. It shows how to submit HID class request and how to read data from |

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| | control pipe. A windows tool is also included in this sample code to connect with a USB device. |
| USBD_Mass_Storage_CDROM | Demonstrate the emulation of USB Mass Storage Device CD-ROM. |
| USBD_Mass_Storage_Flash | Use internal Flash as back end storage media to simulate a USB pen drive. |
| USBD_Micro_Printer | Demonstrate how to implement a USB micro printer device. |
| USBD_Printer_And_HID_Transfer | Demonstrate how to implement a composite device (USB micro printer device and HID Transfer). Transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with a USB device. |
| USBD_VCOM_And_HID_Keyboard | Demonstrate how to implement a composite device.(VCOM and HID keyboard) |
| USBD_VCOM_And_HID_Transfer | Demonstrate how to implement a composite device. (VCOM and HID Transfer) Transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with a USB device. |
| USBD_VCOM_And_Mass_Storage | Demonstrate how to implement a composite device.(Virtual COM port and Mass storage device) |
| USBD_VCOM_DualPort | Demonstrate how to implement a USB dual virtual COM port device. |
| USBD_VCOM_Serial_Emulator | Demonstrate how to implement a USB virtual COM port device. |
| USCI_I2C_EEPROM | Show how to use USCI_I2C interface to access EEPROM. |
| USCI_I2C_Loopback | Show how a master accesses 7-bit address Slave (loopback). |
| USCI_I2C_Loopback_10bit | Show how a master accesses 10-bit address Slave (loopback). |
| USCI_I2C_Master | Show how a master accesses a slave. This sample code needs to work with USCI_I2C_Slave. |

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| USCI_I2C_Master_10bit | Show how a master accesses a 10-bit address slave. This sample code need works with USCI_I2C_Slave_10bit. |
| USCI_I2C_Monitor | Demonstrate USCI_I2C Monitor mode. |
| USCI_I2C_MultiBytes_Master | Show how to set USCI_I2C use Multi bytes API Read and Write data to Slave. This sample code needs to work with USCI_I2C_Slave. |
| USCI_I2C_SingleByte_Master | Show how to use USCI_I2C Single byte API Read and Write data to Slave. This sample code needs to work with USCI_I2C_Slave. |
| USCI_I2C_Slave | Show how a slave receives data from a master. This sample code needs to work with USCI_I2C_Master. |
| USCI_I2C_Slave_10bit | Show how a 10-bit address slave receives data from a master. This sample code needs to work with USCI_I2C_Master_10bit. |
| USCI_I2C_Wakeup_Slave | Show how to wake up USCI_I2C from Deep Sleep mode. This sample code needs to work with USCI_I2C_Master. |
| USCI_SPI_Loopback | Implement USCI_SPI0 Master loop back transfer. This sample code needs to connect USCI_SPI0_MISO pin and USCI_SPI0_MOSI pin together. It will compare the received data with transmitted data. |
| USCI_SPI_MasterMode | Configure USCI_SPI0 as Master mode and demonstrate how to communicate with an off-chip SPI slave device. This sample code needs to work with USCI_SPI_SlaveMode. |
| USCI_SPI_PDMA_LoopTest | Demonstrate USCI_SPI data transfer with PDMA. USCI_SPI0 will be configured as Master mode and USCI_SPI1 will be configured as Slave mode. Both TX PDMA function and RX PDMA function will be enabled. |
| USCI_SPI_SlaveMode | Configure USCI_SPI0 as Slave mode and demonstrate how to communicate with an off-chip SPI master device. This sample code needs to work with USCI_SPI_MasterMode. |
| USCI_UART_AutoBaudRate | Show how to use auto baud rate detection function. |
| USCI_UART_Autoflow_ | Transmit and receive data with auto flow control. This |

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| Master | sample code needs to work with USCI_UART_Autoflow_Slave. |
| USCI_UART_Autoflow_Slave | Transmit and receive data with auto flow control. This sample code needs to work with USCI_UART_Autoflow_Master. |
| USCI_UART_PDMA | This is a USCI_UART PDMA demo and needs to connect USCI_UART TX and RX. |
| USCI_UART_RS485_Master | Transmit and receive data in RS485 mode. This sample code needs to work with USCI_UART_RS485_Slave. |
| USCI_UART_RS485_Slave | Transmit and receive data in RS485 mode. This sample code needs to work with USCI_UART_RS485_Master. |
| USCI_UART_TxRxFunction | Transmit and receive data from PC terminal via the RS232 interface. |
| USCI_UART_Wakeup | Show how to wake up system from Power-down mode by USCI interrupt in UART mode. |
| WDT_TimeoutWakeupAndReset | Implement WDT time-out interrupt event to wake up system and generate time-out reset system event while WDT time-out reset delay period expired. |
| WWDT_ReloadCounter | Show how to reload the WWDT counter value. |

7 .\SampleCode\NuMaker

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| emWin_GUIDemo | Utilize emWin library to demonstrate widgets feature. |
| emWin_SimpleDemo | Utilize emWin library to demonstrate interactive feature. |

| Category Type | Type-B | Type-C | Type-D | Type-E | Type-I | Type-G |
|--|--------|--------|--------|--------|--------|--------|
| Sample Code | | | | | | |
| ACMP_ComapreVBG | - | - | √ | √ | √ | √ |
| ACMP_Wakeup | - | - | √ | √ | √ | √ |
| ACMP_WindowCompare | - | - | √ | √ | √ | √ |
| ACMP_WindowLatch | - | - | √ | √ | √ | √ |
| ADC_2Msps_ContinuousScanMode | - | - | √ | √ | √ | √ |
| ADC_1411ksps_ContinuousScanMode | √ | √ | √ | √ | √ | √ |
| ADC_ADINT_Trigger | √ | √ | √ | √ | √ | √ |
| ADC_BandGap | √ | √ | √ | √ | √ | √ |
| ADC_BandGapCalculate AVDD | √ | √ | √ | √ | √ | √ |
| ADC_BurstMode | √ | √ | √ | √ | √ | √ |
| ADC_Continuous ScanMode | √ | √ | √ | √ | √ | √ |
| ADC_PDMA_PWM_Trigger | - | √ | √ | √ | √ | √ |
| ADC_PWM_Trigger | √ | √ | √ | √ | √ | √ |
| ADC_ResultMonitor | √ | √ | √ | √ | √ | √ |

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|-------------------------------------|---|---|---|---|---|---|
| ADC_SingleCycle ScanMode | √ | √ | √ | √ | √ | √ |
| ADC_SingleMode | √ | √ | √ | √ | √ | √ |
| ADC_STADC_Trigger | √ | √ | √ | √ | √ | √ |
| ADC_SwTrg_Trigger | √ | √ | √ | √ | √ | √ |
| ADC_Timer_Trigger | √ | √ | √ | √ | √ | √ |
| BPWM_Capture | - | - | - | - | √ | √ |
| BPWM_DoubleBuffer | - | - | - | - | √ | √ |
| BPWM_DutySwitch | - | - | - | - | √ | √ |
| BPWM_OutputWaveform | - | - | - | - | √ | √ |
| BPWM_SyncStart | - | - | - | - | √ | √ |
| CLK_ClockDetector | √ | √ | √ | √ | √ | √ |
| CRC_CCITT | √ | √ | √ | √ | √ | √ |
| CRC_CRC8 | √ | √ | √ | √ | √ | √ |
| CRC_CRC32_PDMA | - | √ | √ | √ | √ | √ |
| EBI_NOR | - | - | - | √ | √ | √ |
| EBI_SRAM | - | - | - | √ | √ | √ |
| FMC_CRC32 | √ | √ | √ | √ | √ | √ |
| FMC_ExecInSRAM | √ | √ | √ | √ | √ | √ |
| FMC_IAP | √ | √ | √ | √ | √ | √ |
| FMC_MultiBoot | √ | √ | √ | √ | √ | √ |
| FMC_MultiWordProgram | - | - | - | - | √ | √ |
| FMC_ReadAllOne | - | - | - | - | √ | √ |
| FMC_RW | √ | √ | √ | √ | √ | √ |
| GPIO_EINTAndDebounce | √ | √ | √ | √ | √ | √ |
| GPIO_INT | √ | √ | √ | √ | √ | √ |
| GPIO_OutputInput | √ | √ | √ | √ | √ | √ |
| GPIO_PowerDown | √ | √ | √ | √ | √ | √ |

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| HDIV | √ | √ | √ | √ | √ | √ |
| I2C_EEPROM | √ | √ | √ | √ | √ | √ |
| I2C_GCMode_Master | √ | √ | √ | √ | √ | √ |
| I2C_GCMode_Slave | √ | √ | √ | √ | √ | √ |
| I2C_Loopback | √ | √ | √ | √ | √ | √ |
| I2C_Master | √ | √ | √ | √ | √ | √ |
| I2C_MultiBytes_Master | √ | √ | √ | √ | √ | √ |
| I2C_PDMA_TRX | - | - | √ | √ | √ | √ |
| I2C_SingleByte_Master | √ | √ | √ | √ | √ | √ |
| I2C_Slave | √ | √ | √ | √ | √ | √ |
| I2C_Wakeup_Slave | √ | √ | √ | √ | √ | √ |
| I2S_Master | √ | √ | √ | √ | √ | √ |
| I2S_PDMA_NAU8822 | - | √ | √ | √ | √ | √ |
| I2S_PDMA_Play | - | √ | √ | √ | √ | √ |
| I2S_PDMA_PlayRecrod | - | √ | √ | √ | √ | √ |
| I2S_PDMA_Record | - | √ | √ | √ | √ | √ |
| I2S_Slave | √ | √ | √ | √ | √ | √ |
| PDMA_ADC_1882ksps_ContinousScanMode | - | √ | √ | √ | √ | √ |
| PDMA_BasicMode | - | √ | √ | √ | √ | √ |
| PDMA_ScatterGather | - | √ | √ | √ | √ | √ |
| PDMA_ScatterGather_PingPongBuffer | - | √ | √ | √ | √ | √ |
| PDMA_TimerCapture_CalculatePlusePeriod | - | √ | √ | √ | √ | √ |
| PDMA_TimerTrigger_SRAM 2GPIO | - | √ | √ | √ | √ | √ |
| PWM_240KHz_DutySwitch | √ | √ | √ | √ | √ | √ |
| PWM_Capture | √ | √ | √ | √ | √ | √ |

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|---|---|---|---|---|---|---|
| PWM_DeadZone | √ | √ | √ | √ | √ | √ |
| PWM_DoubleBuffer_PeriodLoadingMode | √ | √ | √ | √ | √ | √ |
| PWM_DutySwitch | √ | √ | √ | √ | √ | √ |
| PWM_OutputWaveForm | √ | √ | √ | √ | √ | √ |
| PWM_PDMA_Capture | - | √ | √ | √ | √ | √ |
| PWM_PDMA_Capture_1MHzSignal | - | √ | √ | √ | √ | √ |
| PWM_SyncStart | √ | √ | √ | √ | √ | √ |
| QSPI_DualMode_Flash | - | - | - | - | √ | √ |
| QSPI_QuadMode_Flash | - | - | - | - | √ | √ |
| RTC_Alarm_Test | - | - | - | - | √ | √ |
| RTC_Alarm_Wakeup | - | - | - | - | √ | √ |
| RTC_Time_Display | - | - | - | - | √ | √ |
| SPI_LoopBack | √ | √ | √ | √ | √ | √ |
| SPI_MasterFIFOmode | √ | √ | √ | √ | √ | √ |
| SPI_PDMA_LoopTest | - | √ | √ | √ | √ | √ |
| SPI_SlaveFIFOmode | √ | √ | √ | √ | √ | √ |
| SYS_BODWakeup | √ | √ | √ | √ | √ | √ |
| SYS_PLLClockOutput | - | - | √ | √ | √ | √ |
| SYS_PowerDon_MinCurrent | √ | √ | √ | √ | √ | √ |
| SYS_TrimHIRC | - | √ | √ | √ | √ | √ |
| TIMER_ACMPTrigger | - | - | √ | √ | √ | √ |
| TIMER_CaptureCounter | - | √ | √ | √ | √ | √ |
| TIMER_Delay | √ | √ | √ | √ | √ | √ |
| TIMER_EventCounter | √ | √ | √ | √ | √ | √ |
| TIMER_FreeCountingMode | √ | √ | √ | √ | √ | √ |

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| TIMER_InterTimerTrigger Mode | √ | √ | √ | √ | √ | √ |
| TIMER_Periodic | √ | √ | √ | √ | √ | √ |
| TIMER_PeriodicINT | - | √ | √ | √ | √ | √ |
| TIMER_SW_RTC | - | √ | √ | √ | √ | √ |
| TIMER_TimeOutWakeup | √ | √ | √ | √ | √ | √ |
| TIMER_ToggleOut | √ | √ | √ | √ | √ | √ |
| UART_6Mbps_SingleWire | √ | √ | √ | √ | √ | √ |
| UART_115200bps_SingleWire_ISP[*1] | √ | √ | √ | √ | √ | √ |
| UART_AutoBaudRate | √ | √ | √ | √ | √ | √ |
| UART_AutoFlow | √ | √ | √ | √ | √ | √ |
| UART_IrDA | √ | √ | √ | √ | √ | √ |
| UART_PDMA | - | √ | √ | √ | √ | √ |
| UART_RS485 | √ | √ | √ | √ | √ | √ |
| UART_SingleWire | √ | √ | √ | √ | √ | √ |
| UART_TxRxFunction | √ | √ | √ | √ | √ | √ |
| UART_Wakeup | √ | √ | √ | √ | √ | √ |
| USBDAudio_NAU8822_Headset | - | - | - | √ | √ | √ |
| USBDAudio_NAU8822_Microphone | - | - | - | √ | √ | √ |
| USBDAudio_NAU8822_Speaker | - | - | - | √ | √ | √ |
| USBDAudio_KEYBOARD | - | - | - | √ | √ | √ |
| USBDAudio_MOUSE | - | - | - | √ | √ | √ |
| USBDAudio_MOUSE_KEYBOARD | - | - | - | √ | √ | √ |
| USBDAudio_REMOTEWAKEUP | - | - | - | √ | √ | √ |

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|--------------------------------|---|---|---|---|---|---|
| USBD_HID_Touch | - | - | - | √ | √ | √ |
| USBD_HID_Transfer | - | - | - | √ | √ | √ |
| USBD_HID_Transfer_And_Keyboard | - | - | - | √ | √ | √ |
| USBD_HID_Transfer_And_MSC | - | - | - | √ | √ | √ |
| USBD_HID_Transfer_CTRL | - | - | - | √ | √ | √ |
| USBD_Mass_Storage_CDROM | - | - | - | √ | √ | √ |
| USBD_Mass_Storage_Flash | - | - | - | √ | √ | √ |
| USBD_Micro_Printer | - | - | - | √ | √ | √ |
| USBD_Printer_And_HID_Transfer | - | - | - | √ | √ | √ |
| USBD_VCOM_And_HID_Keyboard | - | - | - | √ | √ | √ |
| USBD_VCOM_And_HID_Transfer | - | - | - | √ | √ | √ |
| USBD_VCOM_And_Mass_Storage | - | - | - | √ | √ | √ |
| USBD_VCOM_DualPort | - | - | - | √ | √ | √ |
| USBD_VCOM_Serial Emulator | - | - | - | √ | √ | √ |
| USCI_I2C_EEPROM | - | - | √ | √ | √ | √ |
| USCI_I2C_Loopback | - | - | - | - | √ | √ |
| USCI_I2C_Loopback_10bit | - | - | - | - | √ | √ |
| USCI_I2C_Master | - | - | √ | √ | √ | √ |
| USCI_I2C_Master_10bit | - | - | √ | √ | √ | √ |
| USCI_I2C_Monitor | - | - | √ | √ | √ | √ |

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|----------------------------|---|---|---|---|---|---|
| USCI_I2C_MultiBytes_Master | - | - | √ | √ | √ | √ |
| USCI_I2C_SingleByte_Master | - | - | √ | √ | √ | √ |
| USCI_I2C_Slave | - | - | √ | √ | √ | √ |
| USCI_I2C_Slave_10bit | - | - | √ | √ | √ | √ |
| USCI_I2C_Wakeup_Slave | - | - | √ | √ | √ | √ |
| USCI_SPI_Loopback | - | - | √ | √ | √ | √ |
| USCI_SPI_MasterMode | - | - | √ | √ | √ | √ |
| USCI_SPI_PDMA_LoopTest | - | - | - | - | √ | √ |
| USCI_SPI_SlaveMode | - | - | √ | √ | √ | √ |
| USCI_UART_AutoBaudRate | - | - | √ | √ | √ | √ |
| USCI_UART_Autoflow_Master | - | - | √ | √ | √ | √ |
| USCI_UART_Autoflow_Slave | - | - | √ | √ | √ | √ |
| USCI_UART_PDMA | - | - | √ | √ | √ | √ |
| USCI_UART_RS485_Master | - | - | √ | √ | √ | √ |
| USCI_UART_RS485_Slave | - | - | √ | √ | √ | √ |
| USCI_UART_TxRxFunction | - | - | √ | √ | √ | √ |
| USCI_UART_Wakeup | - | - | √ | √ | √ | √ |
| WDT_TimeoutWakeup AndReset | √ | √ | √ | √ | √ | √ |
| WWDT_ReloadCounter | √ | √ | √ | √ | √ | √ |
| emWin_GUIDemo | - | - | - | - | √ | √ |
| emWin_SimpleDemo | - | - | - | - | √ | √ |

Note 1: This GCC sample code size exceeds 2KB.

Note 2: USB samples are only supported in M032LE3AE, M032SE3AE, M032LG6AE, M032SG6AE, M032KG6AE, M032LG8AE, M032SG8AE, M032KG8AE, M032SIAAE, and M032KIAAE.

8 .\ThirdParty\

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| emWin | emWin is designed to provide an efficient, processor- and display controller-independent graphical user interface for any application that operates with a graphical display. |
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