

## M251/M252/M254/M256/M258 Series CMSIS BSP Guide

Directory Introduction for 32-bit NuMicro® Family

#### **Directory Information**

| Document   | Driver reference guide and revision history. |
|------------|--|
| Library    | Driver header and source files.              |
| SampleCode | Driver sample code.                          |
| ThirdParty | Libraries from third parties.                |
| Tool       | Utility programs.                            |

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#### 1 Document

| CMSIS.html  | Document of CMSIS version 6.1.0.  |
|---|---|
| NuMicro<br>M251_252_254_256_258<br>Series CMSIS BSP Driver<br>Reference Guide.chm | This document describes the usage of drivers in M251/M252/M254/M256/M258 BSP. |
| NuMicro<br>M251_252_254_256_258<br>Series CMSIS BSP Revision<br>History.pdf       | This document shows the revision history of M251/M252/M254/M256/M258 BSP.     |



## 2 Library

| CMSIS        | Cortex <sup>®</sup> Microcontroller Software Interface Standard (CMSIS) V6.1.0 definitions by Arm <sup>®</sup> Corp. |
|--------------|--|
| Device       | CMSIS compliant device header file.  |
| LCDLib       | Library for controlling LCD module.  |
| SmartcardLib | Smart card library binary and header file.   |
| StdDriver    | All peripheral driver header and source file.  |
| TKLib        | Library for controlling touch key module.  |



# 3 SampleCode

| CardReader        | USB CCID smart card reader sample code.  |
|-------------------|--|
| CortexM23         | ·  |
| Cortexiviza       | Cortex®-M23 sample code.   |
| FreeRTOS          | Simple FreeRTOS™ demo code.  |
|                   | Show hard fault information when hard fault happened.  |
| Hard_Fault_Sample | The hard fault handler shows some information including program counter, which is the address where the processor is executed when the hard fault occurs. The listing file (or map file) can show what function and instruction that is. |
|                   | It also shows the Link Register (LR), which contains the return address of the last function call. It can show the status where CPU comes from to get to this point.   |
| ISP               | Sample codes for In-System-Programming.  |
| NuMaker-M258KE    | Sample codes for NuMaker-M258KE board.   |
| PowerManagement   | Power management sample code.  |
|                   | For more information about M251/M252/M254/M256/M258 series power management, please refer to the <u>application</u> note.  |
| Semihost          | Show how to print and get character through IDE console window.  |
| StdDriver         | Sample code to demonstrate the usage of M251/M252/M254/M256/M258 series MCU peripheral driver APIs.  |
| Template          | A project template for M251/M252/M254/M256/M258 series MCU.  |
| XOM               | Demonstrate how to create XOM library and use it.  |
|                   | For more information about M251/M252/M254/M256/M258 series XOM, please refer to the application note.  |



# 4 ThirdParty

| FreeRTOS | A real time operating system available for free download. Its                          |
|----------|--|
|          | official website is: <a href="http://www.freertos.org/">http://www.freertos.org/</a> . |



## 5 Tool

| тк   | Touch key tools for calibration and mass production. |
|------|--|
| I IX | Touch key look for calibration and mass production.  |



# 6 SampleCode\CardReader

| BD_CCID | USB CCID smart card reader sample code. |
|---------|---|
|---------|---|



# 7 SampleCode\CortexM23

| MPU | Demonstrate the usage of Cortex®-M23 MPU. |
|-----|---|
|-----|---|



# 8 SampleCode\FreeRTOS

| This project provides two demo apblinky style project, and a more codemo application. |
|---|
|---|



# 9 SampleCode\ISP

| ISP_DFU   | In-System-Programming Sample code through USB interface and following Device Firmware Upgrade Class Specification. |
|-----------|--|
| ISP_HID   | In-System-Programming Sample code through USB HID interface.   |
| ISP_I2C   | In-System-Programming Sample code through I <sup>2</sup> C interface.  |
| ISP_MSC   | In-System-Programming Sample code through USB interface and following Mass Storage Class Specification.            |
| ISP_RS485 | In-System-Programming Sample code through RS485 interface.   |
| ISP_SPI   | In-System-Programming Sample code through SPI interface.   |
| ISP_UART  | In-System-Programming Sample code through UART interface.  |



# 10 SampleCode\Level1\_Training

| Level1_EADC_BandGapCalculat eAVDD       | Demonstrate how to calculate battery voltage( AVdd ) by using band-gap.                        |
|---|--|
| Level1_GPIO_Ctrl                        | Show the usage of GPIO control LED function.   |
| Level1_I2C_EEPROM                       | Show how to use I <sup>2</sup> C interface to access EEPROM.                                   |
| Level1_PWM_LED_Breathing                | Change duty cycle of output waveform to show breathing effect of Red LED.                      |
| Level1_PWM_LED_Duty                     | Change duty cycle of output waveform to show different brightness of Red LED.                  |
| Level1_SPI_Flash                        | Access SPI Flash through SPI interface.  |
| Level1_Timer_Ctrl                       | TIMER function for level1 training course.   |
| Level1_UART_ReceiveUnknowD ataLengthPkg | Show how to use the UART Rx timeout function for receiving unknown data length package.        |
| Level1_WDT                              | WDT function for level 1 training course. MCU will be woken-up by WDT 10 times and then reset. |



# 11 SampleCode\NuMaker-M256SD

| LCD_Blinking     | Demonstrate the LCD blinking function by using RHE6616TP01 (8-COM, 40-SEG, 1/4 Bias) LCD.  |
|------------------|--|
| LCD_Pixel_OnOff  | Show how to set pixel on and off on RHE6616TP01 (8-COM, 40-SEG, 1/4 Bias) LCD.   |
| LCD_Print_Text   | Show how to print text on RHE6616TP01 (8-COM, 40-SEG, 1/4 Bias) LCD.   |
| NK_M256SD_LCD_TK | Demonstrate how to calibrate TK1 in the NuMaker-M256SD board. After the calibration completes, LCD displays M256SD temperature, firmware version, and TK1 press information. |



## 12 SampleCode\NuMaker-M258KE



## 13 SampleCode\NuMaker-M258KG

| NK_M258KG_LCD_TK | Demonstrate how to calibrate TK14 in the NuMaker-M258KG board. After the calibration completes, LCD displays M258KG temperature, firmware version, and TK14 press information. |
|------------------|--|
|                  |  |



### 14 SampleCode\PowerManagement

The M251/M252/M254/M256/M258 series MCU provides some power modes with different power consumption level and wake-up time. For more information, please refer to the <u>application note</u>.

| LCD_PowerConsumption     | Demonstrate the LCD run in low power consumption.  |
|--------------------------|--|
| RTC_Alarm_Wakeup         | Demonstrate the RTC Wake-up in Power-down mode.  |
| SYS_DPDMode_Wakeup       | Demonstrate how to wake up system from Deep Powerdown mode by Wake-up pin (PA.0), Wake-up Timer, RTC Tick, RTC Alarm, or RTC Tamper 0. |
| SYS_PowerDownMode        | Show how to enter a different Power-down mode and wake up by RTC.  |
| SYS_PowerDown_MinCurrent | Demonstrate how to minimize power consumption when entering Power-down mode.   |
| SYS_PowerMode            | Show how to set different core voltage and main voltage regulator type.  |
| TK_PowerDownMode         | Demonstrate how to TK14 in the NPD Mode to Wake Up for NuMaker-M258KE / M258KG board;TK1 for NuMaker-M256SD board.                     |



#### 15 SampleCode\XOM

In the M251/M252/M254/M256/M258 series MCU, XOM (Execute-Only Memory) is a secure ROM region which forbids any data access. However, the code stored in the XOM region could still be executed by CPU since it is accessed by instruction fetch. For more information, please refer to the application note.

| XOMLib     | Demonstrate how to create XOM library. |
|------------|--|
| XOMLibDemo | Demonstrate how to use XOMLib.         |



## 16 SampleCode\StdDriver

### **System Manager (SYS)**

| SYS_BODWakeup      | Demonstrate how to wake up system from Power-down mode by brown-out detector interrupt. |
|--------------------|---|
| SYS_PLLClockOutput | Change system clock to different PLL frequency and output system clock from CLKO pin.   |
| SYS_TrimHIRC       | Demonstrate how to use LXT to trim HIRC.  |
| SYS_TrimMIRC       | Demonstrate how to use Timer to trim MIRC.  |

### **Clock Controller (CLK)**

| C.I.K. C.IOCKI JETECTOR | Demonstrate the usage of clock fail detector and clock frequency range detector function. |
|-------------------------|---|
|                         | moquemey ramge detector rameticin   |

#### Flash Memory Controller (FMC)

| FMC_CRC32            | Demonstrate how to use FMC CRC32 ISP command to calculate the CRC32 checksum of APROM and LDROM.   |
|----------------------|--|
| FMC_ExeInSRAM        | Implement a code and execute it in SRAM to program embedded Flash.   |
| FMC_IAP              | Demonstrate FMC IAP boot mode and show how to use vector remap function. LDROM image has been embedded in APROM image and programmed to LDROM Flash at run-time. This sample also shows how to branch between APROM and LDROM. |
| FMC_MultiBoot        | Implement a multi-boot system to boot from different applications in APROM or LDROM by VECMAP.   |
| FMC_MultiWordProgram | Show how to use FMC multi-word program ISP command to program APROM 0x18000~0x20000 area.  |
| FMC_ReadAllOne       | Demonstrate how to use FMC Read-All-One ISP command to verify APROM or LDROM pages are all 0xFFFFFFF or not.   |



| FMC_RW  | Show FMC read Flash IDs, erase, read, and write functions.                 |
|---------|--|
| FMC_XOM | Show how to configure and set up an XOM region then perform XOM function.  |
|         | For more information, please refer to the <u>application</u> <u>note</u> . |

#### **General Purpose I/O (GPIO)**

The M254/M256/M258 series MCU support 5V tolerance I/O except PF2, PF3, PF4 and PF5 pins.

| GPIO_EINTAndDebounce | Show the usage of GPIO external interrupt function and de-bounce function. |
|----------------------|--|
| GPIO_INT             | Show the usage of GPIO interrupt function.                                 |
| GPIO_OutputInput     | Show how to set GPIO pin mode and use pin data input and output control.   |
| GPIO_PowerDown       | Show how to wake up system from Power-down mode by GPIO interrupt.         |
| GPIO_SingleCycleIO   | Show GPIO single cycle IO bus performance.                                 |

#### **PDMA Controller (PDMA)**

| PDMA_BasicMode                     | Use PDMA channel 2 to transfer data from memory to memory.                        |
|------------------------------------|---|
| PDMA_ScatterGather                 | Use PDMA channel 4 to transfer data from memory to memory by scatter-gather mode. |
| PDMA_ScatterGather_ PingPongBuffer | Use PDMA to implement Ping-Pong buffer by scattergather mode (memory to memory).  |

### **Timer Controller (TIMER)**



| TIMER_CaptureCounter        | Show how to use the Timer2 capture function to capture Timer2 counter value.  |
|-----------------------------|---|
| TIMER_Delay                 | Demonstrate the usage of TIMER_Delay API to generate a 1 second delay.  |
| TIMER_EventCounter          | Use pin PB.4 to demonstrate Timer event counter function.   |
| TIMER_FreeCountingMode      | Use the Timer pin to demonstrate Timer free counting mode function, and display the measured input frequency to UART console. |
| TIMER_InterTimerTriggerMode | Use the Timer pin to demonstrate inter-timer trigger mode function, and display the measured input frequency to UART console. |
| TIMER_Periodic              | Use the Timer periodic mode to generate Timer interrupt every 1 second.   |
| TIMER_PeriodicINT           | Implement Timer counting in periodic mode.  |
| TIMER_PWM_ChangeDuty        | Change duty cycle and period of output waveform in PWM down count type.   |
| TIMER_PWM_OutputWaveform    | Demonstrate output different duty waveform in Timer0~3 PWM.   |
| TIMER_TimeoutWakeup         | Use Timer0 periodic time-out interrupt event to wake up system.   |
| TIMER_ToggleOut             | Demonstrate the Timer0 toggle out function on pin PB.5.   |

### Watchdog Timer (WDT)

| WDT_TimeoutWakeupAndReset Implement WDT time-out interrupt event to wake us system and generate time-out reset system event WDT time-out reset delay period expired. | • |
|--|---|
|--|---|

### **Window Watchdog Timer (WWDT)**

| WWDT_CompareINT | Show how to reload the WWDT counter value. |
|-----------------|--|
|-----------------|--|



### **Real Timer Clock (RTC)**

| RTC_Alarm_Test    | Demonstrate the RTC alarm function. It sets an alarm 10 seconds after execution. |
|-------------------|--|
| RTC_Spare_Access  | Show how to access RTC spare registers in supported chip.                        |
| RTC_Static_Tamper | Show how to use RTC static tamper function in supported chip.                    |
| RTC_Time_Display  | Demonstrate the RTC function and display current time to the UART console.       |

### **Basic PWM Generator and Capture Timer (BPWM)**

| BPWM_Capture        | Use BPWM0 channel 0 to capture the Timer0 waveform.                             |
|---------------------|---|
| BPWM_DoubleBuffer   | Change duty cycle and period of output waveform by BPWM double buffer function. |
| BPWM_OutputWaveform | Demonstrate how to use BPWM counter output waveform.                            |
| BPWM_SwitchDuty     | Change duty cycle of output waveform by configured period.                      |
| BPWM_SyncStart      | Demonstrate how to use BPWM counter synchronous start function.                 |

#### **PWM Generator and Capture Timer (PWM)**

| PWM_Brake        | Demonstrate how to use PWM brake function.                                     |
|------------------|--|
| PWM_Capture      | Capture the PWM1 channel 0 waveform by PWM1 channel 2.                         |
| PWM_DeadTime     | Demonstrate how to use PWM dead-time insertion function.                       |
| PWM_DoubleBuffer | Change duty cycle and period of output waveform by PWM double buffer function. |



| PWM_OutputWaveform | Demonstrate how to use PWM output waveform.  |
|--------------------|--|
| PWM_PDMA_Capture   | Capture the PWM1 channel 0 waveform by PWM1 channel 2, and use PDMA to transfer captured data. |
| PWM_SwitchDuty     | Change duty cycle of PWM output waveform by configured period.                                 |
| PWM_SyncStart      | Demonstrate how to use PWM counter synchronous start function.                                 |

### **UART Interface Controller (UART)**

| UART_AutoBaudRate | Show how to use auto baud rate detection function.                  |
|-------------------|---|
| UART_AutoFlow     | Transmit and receive data using auto flow control.                  |
| UART_IrDA         | Transmit and receive UART data in UART IrDA mode.                   |
| UART_LIN          | Demonstrate how to send data to LIN bus.                            |
| UART_PDMA         | Demonstrate UART transmit and receive function with PDMA.           |
| UART_RS485        | Transmit and receive data in UART RS485 mode.                       |
| UART_SingleWire   | Transmit and receive data in UART single-wire mode.                 |
| UART_TxRxFunction | Transmit and receive data from PC terminal through RS232 interface. |
| UART_Wakeup       | Show how to wake up system from Power-down mode by UART interrupt.  |

## **Smart Card Host Interface (SC)**

| SC_ReadATR          | Read the smartcard ATR from Smartcard interface.                |
|---------------------|---|
| SC_ReadSimPhoneBook | Demonstrate how to read phone book information in the SIM card. |
| SC_Timer            | Demonstrate how to use SC embedded timer.                       |



| SCUART_TxRx | Demonstrate Smartcard UART mode by connecting PB.4 and PB.5 pins. |
|-------------|---|
|-------------|---|

### **Serial Peripheral Interface (SPI)**

| SPI_Flash            | Access SPI Flash through SPI interface.  |
|----------------------|--|
| SPI_HalfDuplex       | Demonstrate SPI half-duplex mode. Configure USPI0 as master mode and SPI0 as slave mode. Both USPI0 and SPI0 are half-duplex mode.   |
| SPI_Loopback         | A SPI read/write demo connecting SPI0 MISO and MOSI pins.  |
| SPI_MasterFIFOMode   | Configure SPI0 as master mode and demonstrate how to communicate with an off-chip SPI slave device with FIFO mode. This sample code could work with SPI SlaveFIFOMode sample code.   |
| SPI_PDMA_LoopTest    | Demonstrate SPI data transfer with PDMA. SPI0 will be configured as slave mode and USPI0 will be configured as master mode. Both Tx PDMA function and Rx PDMA function will be enabled.  |
| SPI_SlaveFIFOMode    | Configure SPI0 as slave mode and demonstrate how to communicate with an off-chip SPI master device with FIFO mode. This sample code needs to work with SPI MasterFIFOMode sample code.   |
| SPI_SlaveFIFOModelNT | Configure SPI0 as slave mode and demonstrate how to use FIFO mode to communicate with an off-chip SPI master device, and transmit and receive data in the interrupt handler. This sample code needs to work with SPI MasterFIFOMode sample code. |
| SPII2S_Master        | Configure SPI0 as I <sup>2</sup> S master mode and demonstrate how I <sup>2</sup> S works in master mode. This sample code needs to work with <u>SPII2S Slave</u> sample code.   |
| SPII2S_PDMA_Codec    | An I <sup>2</sup> S demo with PDMA function connected with audio codec.  |
| SPII2S_PDMA_Play     | An I <sup>2</sup> S demo for playing data and demonstrating how I <sup>2</sup> S   |



|                        | works with PDMA.   |
|------------------------|--|
| SPII2S_PDMA_PlayRecord | An I <sup>2</sup> S demo for playing and recording data with PDMA function.  |
| SPII2S_PDMA_Record     | An I <sup>2</sup> S demo for recording data and demonstrating how I <sup>2</sup> S works with PDMA.  |
| SPII2S_Slave           | Configure SPI0 as I <sup>2</sup> S slave mode and demonstrate how I <sup>2</sup> S works in slave mode. This sample code needs to work with SPII2S Master sample code. |

### **Quad Serial Peripheral Interface (QSPI)**

| QSPI_DualMode_Flash | Access SPI Flash using QSPI dual mode.   |
|---------------------|--|
| QSPI_QuadMode_Flash | Access SPI Flash using QSPI quad mode.   |
| QSPI_Slave3Wire     | Configure QSPI0 as Slave 3-wire mode and demonstrate how to communicate with an off-chip SPI Master device with FIFO mode. This sample code needs to work with SPI MasterFIFOMode sample code. |

### I<sup>2</sup>C Serial Interface Controller (I<sup>2</sup>C)

| I2C_EEPROM            | Read and write EEPROM via I <sup>2</sup> C interface.   |
|-----------------------|---|
| I2C_GCMode_Master     | Demonstrate how a master uses I <sup>2</sup> C address 0x0 to write data to I <sup>2</sup> C slave. This sample code needs to work with I2C_GCMode_Slave sample code. |
| I2C_GCMode_Slave      | Demonstrate how to receive master data in GC (General Call) mode. This sample code needs to work with <a href="I2C_GCMode_Master">I2C_GCMode_Master</a> sample code.  |
| I2C_Loopback          | Show how a I <sup>2</sup> C master accesses a slave via loopback of 2 I <sup>2</sup> C ports.   |
| I2C_Master            | Show how a I <sup>2</sup> C master accesses a slave. This sample code needs to work with I2C Slave sample code.   |
| I2C_MultiBytes_Master | Demonstrate how to use multi-bytes API to access slave. This sample code needs to work with <a href="L2C_Slave">L2C_Slave</a>   |



|                       | sample code.  |
|-----------------------|---|
| I2C_PDMA_TRX          | Demonstrate I <sup>2</sup> C PDMA mode, which need to connect I <sup>2</sup> C0 (master) and I <sup>2</sup> C1 (slave).                           |
| I2C_SingleByte_Master | Demonstrate how to use single byte API to access slave. This sample code needs to work with <a href="mailto:I2C_Slave">I2C_Slave</a> sample code. |
| I2C_Slave             | Show how a I <sup>2</sup> C slave receives data from a master. This sample code needs to work with I2C Master sample code.                        |
| I2C_SMBus             | Show how to control SMBus interface and use SMBus protocol between host and slave.  |
| I2C_Wakeup_Slave      | Demonstrate how to set I <sup>2</sup> C to wake up MCU from Power-down mode. This sample code could work with I2C Master sample code.             |

### **Universal Serial Control Interface Controller - UART Mode (USCI-UART)**

| USCI_UART_AutoBaudRate    | Show how to use auto baud rate detection function.   |
|---------------------------|--|
| USCI_UART_Autoflow_Master | Transmit and receive data with auto flow control. This sample code needs to work with <a href="USCI_UART_Autoflow_Slave">USCI_UART_Autoflow_Slave</a> sample code.   |
| USCI_UART_Autoflow_Slave  | Transmit and receive data with auto flow control. This sample code needs to work with <a href="USCI_UART_Autoflow_Master">USCI_UART_Autoflow_Master</a> sample code. |
| USCI_UART_PDMA            | This is a USCI_UART PDMA demo and needs to connect USCI_UART Tx and Rx.  |
| USCI_UART_RS485_Master    | Transmit and receive data in RS485 mode. This sample code needs to work with <u>USCI_UART_RS485_Slave</u> sample code.   |
| USCI_UART_RS485_Slave     | Transmit and receive data in RS485 mode. This sample code needs to work with <u>USCI_UART_RS485_Master</u> sample code.  |
| USCI_UART_TxRxFunction    | Transmit and receive data from PC terminal through   |



|                  | RS232 interface.  |
|------------------|---|
| USCI_UART_Wakeup | Show how to wake up system from Power-down mode by USCI interrupt in UART mode. |

## **Universal Serial Control Interface Controller - SPI Mode (USCI-SPI)**

| USCI_SPI_Loopback      | Implement USCI_SPI0 master loop back transfer. This sample code needs to connect USCI_SPI0_MISO pin and USCI_SPI0_MOSI pin together. It will compare the received data with transmitted data.   |
|------------------------|---|
| USCI_SPI_MasterMode    | Configure USCI_SPI0 as master mode and demonstrate how to communicate with an off-chip SPI Slave device. This sample code needs to work with <a href="USCI_SPI_SlaveMode">USCI_SPI_SlaveMode</a> sample code.   |
| USCI_SPI_PDMA_LoopTest | Demonstrate SPI data transfer with PDMA. USCI_SPI0 will be configured as master mode and USCI_SPI1 will be configured as slave mode. Both Tx PDMA function and Rx PDMA function will be enabled.  |
| USCI_SPI_SlaveMode     | Configure USCI_SPI0 as slave mode and demonstrate how to communicate with an off-chip SPI master device. This sample code needs to work with <a href="USCI_SPI_MasterMode">USCI_SPI_MasterMode</a> sample code.   |
| USCI_SPI_SlaveModeINT  | Configure USCI_SPI0 as slave mode and demonstrate how to communicate with an off-chip SPI master device, and transmit and receive data in the interrupt handler. This sample code needs to work with <a href="USCI_SPI_MasterMode">USCI_SPI_MasterMode</a> sample code. |

## Universal Serial Control Interface Controller - I<sup>2</sup>C Mode (USCI-I2C)

| USCI_I2C_EEPROM         | Show how to use USCI_I2C interface to access EEPROM.   |
|-------------------------|--|
| USCI_I2C_Lookback       | Show how an I <sup>2</sup> C master accesses 7-bit address slave via loopback of 2 USCI ports. |
| USCI_I2C_Loopback_10bit | Show how an I <sup>2</sup> C master accesses 10-bit address slave                              |



|                            | 2-1  |
|----------------------------|--|
|                            | via loopback of 2 USCI ports.  |
| USCI_I2C_Master            | Show how an I <sup>2</sup> C master accesses 7-bit address slave. This sample code needs to work with <u>USCI_I2C_Slave</u> sample code.             |
| USCI_I2C_Master_10bit      | Show how an I <sup>2</sup> C master accesses 10-bit address slave. This sample code needs to work with USCI I2C Slave 10bit sample code.             |
| USCI_I2C_Monitor           | Use USCI_I2C to monitor and log I2C bus traffic.   |
| USCI_I2C_MultiBytes_Master | Use UI2C multiple-byte functions to read and write data to slave. Need to work with the USCI I2C Slave sample code.                                  |
| USCI_I2C_SingleByte_Master | Use UI2C single-byte functions to read and write data to slave. Need to work with the <u>USCI_I2C_Slave</u> sample code.                             |
| USCI_I2C_Slave             | Show how an I <sup>2</sup> C 7-bit address slave receives data from master.  |
| USCI_I2C_Slave_10bit       | Show how an I <sup>2</sup> C 10-bit address slave receives data from master. This sample code needs to work with USCI_I2C_Master_10bit sample code.  |
| USCI_I2C_Wakeup_Slave      | Demonstrate how to set I <sup>2</sup> C to wake up MCU from Power-down mode. This sample code needs to work with <u>USCI_I2C_Master</u> sample code. |

## Programmable Serial I/O (PSIO)

| PSIO_1Wire  | Use PSIO to access MAXIM DS18B20 digital thermometer.   |
|-------------|---|
| PSIO_DMX512 | Use PSIO to implement DMX512 protocol.  |
| PSIO_HDQ    | Use PSIO to access TI BQ2028 EEPROM.  For more information, please refer to the application note. |
| PSIO_IR     | Use PSIO to implement NEC IR protocol.  |



| PSIO_LED        | Use PSIO to control Worldsemi WS2812 LED.   |
|-----------------|---|
| PSIO_Microwire  | Use PSIO to access Atmel T93C46D EEPROM.  For more information, please refer to the application note. |
| PSIO_PS2_Device | Use PSIO to implement PS/2 device.  |
| PSIO_PS2_Host   | Use PSIO to implement PS/2 host.  |
| PSIO_Wiegand    | Use PSIO to access HZ1050 RFID reader.  |

### **External Bus Interface (EBI)**

| EBI_NOR  | Configure EBI interface to access NOR Flash connected on EBI interface. |
|----------|---|
| EBI_SRAM | Configure EBI interface to access SRAM connected on EBI interface.      |

## **USB 1.1 Device Controller (USBD)**

| USBD_Audio_Codec    | Demonstrate how to implement a USB audio class device.   |
|---------------------|--|
| USBD_Audio_Headset  | Demonstrate how to implement a USB audio class device. Codec is used in this sample code to play the audio data from Host. It also supports to record data from codec to Host.   |
| USBD_BC12_HID_Mouse | Demonstrate how to implement a USB mouse device with BC1.2 (Battery Charging). This sample code shows different type of charging port after connected USB port. The mouse cursor will move automatically when this mouse device is connected to PC by USB. |
| USBD_HID_Keyboard   | Demonstrate how to implement a USB keyboard device. This sample code supports to use GPIO to simulate key input.   |
| USBD_HID_Mouse      | Simulate a USB mouse and draws circle on the screen.   |



| USBD_HID_MouseKeyboard             | Simulate an USB HID mouse and HID keyboard. Mouse draws circle on the screen and Keyboard uses GPIO to simulate key input.   |
|------------------------------------|--|
| USBD_HID_RemoteWakeup              | Simulate a HID mouse supporting USB suspend and remote wakeup.   |
| USBD_HID_Transfer                  | Demonstrate how to transfer data between a USB device and PC through a USB HID interface. A windows tool is also included in this sample code to connect with a USB device.  |
| USBD_HID_Transfer_And_<br>Keyboard | Demonstrate how to implement a composite device of HID transfer and keyboard. Transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with a USB device.     |
| USBD_HID_Transfer_And_<br>MSC      | Demonstrate how to implement a composite device of HID transfer and mass storage. Transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with a USB device. |
| USBD_HID_Transfer_CTRL             | Use USB host core driver and HID driver. It shows how to submit HID class request and how to read data from control pipe. A windows tool is also included in this sample code to connect with a USB device.                            |
| USBD_Mass_Storage_CDROM            | Demonstrate the emulation of USB mass storage device, CD-ROM.  |
| USBD_Mass_Storage_Flash            | Use internal Flash as backend storage media to simulate a USB pen drive.   |
| USBD_Mass_Storage_SRAM             | Use internal SRAM as backend storage media to simulate a USB pen drive.  |
| USBD_Micro_Printer                 | Demonstrate how to implement a USB micro printer device.   |
| USBD_Printer_And_HID_<br>Transfer  | Demonstrate how to implement a composite device of USB micro printer and HID transfer. Transfer data between USB device and PC through USB HID   |



|                                | interface. A windows tool is also included in this sample code to connect with a USB device.   |
|--------------------------------|--|
| USBD_VCOM_And_HID_<br>Keyboard | Demonstrate how to implement a composite device of VCOM and HID keyboard.  |
| USBD_VCOM_And_HID_<br>Transfer | Demonstrate how to implement a composite device of VCOM and HID transfer. Transfer data between USB device and PC through USB HID interface. A windows tool is also included in this sample code to connect with a USB device. |
| USBD_VCOM_And_Mass_<br>Storage | Demonstrate how to implement a composite device of VCOM and mass storage.  |
| USBD_VCOM_DualPort             | Demonstrate how to implement a USB dual virtual COM port device.   |
| USBD_VCOM_SerialEmulator       | Demonstrate how to implement a USB virtual COM port device.  |
| CRC Controller (CRC)           |  |

#### **CRC Controller (CRC)**

| CRC_CCITT | Implement CRC in CRC-CCITT mode and get the CRC checksum result. |
|-----------|--|
| CRC_CRC32 | Implement CRC in CRC-32 mode and get the CRC checksum result.    |
| CRC_CRC8  | Implement CRC in CRC-8 mode and get the CRC checksum result.     |

## **Cryptographic Accelerator (CRYPTO)**

| CRYPTO_AES  Show Crypto IP AES-128 ECB mode encrypt/ function. | /decrypt |
|--|----------|
|--|----------|

#### **LCD Controller (LCD)**



| LCD_Pixel_OnOff | Show how to set pixel on and off on RHE6616TP01 (8-COM, 40-SEG, 1/4 Bias) LCD. |
|-----------------|--|
| LCD_Print_Text  | Show how to print text on RHE6616TP01 (8-COM, 40-SEG, 1/4 Bias) LCD.           |

### **Enhanced 12-bit Analog-to-Digital Converter (EADC)**

| EADC_Accumulate           | Demonstrate how to get accumulated conversion result.   |
|---------------------------|---|
| EADC_ADINT_Trigger        | Use ADINT interrupt to trigger the EADC conversion.   |
| EADC_Average              | Demonstrate how to get average conversion result.   |
| EADC_BandGap              | Convert band-gap (Sample module 16) and print conversion result.                                    |
| EADC_BandGapCalculateAVDD | Demonstrate how to calculate battery voltage (AVDD) by using band-gap.                              |
| EADC_BPWM_Trigger         | Demonstrate how to trigger EADC by BPWM.  |
| EADC_PDMA_BPWM_Trigger    | Demonstrate how to trigger EADC by BPWM and transfer conversion data by PDMA.                       |
| EADC_PDMA_PWM_Trigger     | Demonstrate how to trigger EADC by PWM and transfer conversion data by PDMA.                        |
| EADC_Pending_Priority     | Demonstrate how to trigger multiple sample modules and got conversion results in order of priority. |
| EADC_PWM_Trigger          | Demonstrate how to trigger EADC by PWM.   |
| EADC_ResultMonitor        | Monitor the conversion result of channel 2 by the digital compare function.                         |
| EADC_SWTRG_Trigger        | Trigger EADC by writing EADC_SWTRG register.  |
| EADC_TempSensor           | Convert temperature sensor (Sample module 17) and print conversion result.                          |
| EADC_Timer_Trigger        | Show how to trigger EADC by Timer.  |



| EADC_VBat | Convert VBAT/4 (Sample module 18) and print conversion result. |
|-----------|--|
|-----------|--|

### **Digital-to-Analog Converter (DAC)**

| DAC_ExtPinTrigger     | Demonstrate external pin trigger DAC to convert sine wave outputs.            |
|-----------------------|---|
| DAC_GroupMode         | Demonstrate DAC0 and DAC1 work in group mode.                                 |
| DAC_PDMA_TimerTrigger | Show Timer trigger DAC to fetch data with PDMA and convert sine wave outputs. |
| DAC_SoftwareTrigger   | Demonstrate software trigger DAC to convert sine wave outputs.                |
| DAC_TimerTrigger      | Demonstrate Timer trigger DAC to convert sine wave outputs.                   |

#### **Analog Comparator Controller (ACMP)**

| ACMP_ComapreDAC    | Demonstrate ACMP comparison by comparing ACMP0_P0 input and DAC voltage and shows the result on UART console. |
|--------------------|---|
| ACMP_ComapreVBG    | Demonstrate ACMP comparison by comparing ACMP0_P0 input and VBG voltage and shows the result on UART console. |
| ACMP_Wakeup        | Use ACMP to wake up system from Power-down mode while comparator output changes.                              |
| ACMP_WindowCompare | Show how to monitor ACMP input with window compare function.  |
| ACMP_WindowLatch   | Demonstrate how to use ACMP window latch mode.  |

#### **OP Amplifier (OPA)**

| OPA_Control | Show how to control OPA. |
|-------------|--------------------------|
|-------------|--------------------------|



# 17 Sample Code Compatibility List

| Part Number Sample Code        | M254xG<br>M256xG<br>M258xG | M254xE<br>M256xE<br>M258xE | M254xD<br>M256xD | M251xG<br>M252xG | M251xE<br>M252xE | M251LC<br>M251SC<br>M251xD<br>M252LC<br>M252SC<br>M252xD | M251EC<br>M251FC<br>M251ZC<br>M252EC<br>M252FC<br>M252ZC |
|--------------------------------|----------------------------|----------------------------|------------------|------------------|------------------|--|--|
| ACMP_ComapreDAC                | √                          | -                          | -                | √                | -                | -  | -  |
| ACMP_ComapreVBG                | V                          | V                          | V                | V                | V                | √  | -  |
| ACMP_Wakeup                    | V                          | √                          | <b>V</b>         | √                | √                | √  | -  |
| ACMP_WindowCompare             | V                          | V                          | V                | V                | $\sqrt{}$        | <b>V</b>   | -  |
| ACMP_WindowLatch               | V                          | V                          | <b>V</b>         | V                | <b>V</b>         | <b>V</b>   | -  |
| BPWM_Capture                   | √                          | V                          | √                | <b>V</b>         | √                | √  | -  |
| BPWM_DoubleBuffer              | V                          | √                          | V                | √                | √                | √  |  |
| BPWM_OutputWaveform            | V                          | V                          | V                | <b>V</b>         | √                | √  | -  |
| BPWM_SwitchDuty                | V                          | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | -  |
| BPWM_SyncStart <sup>1</sup>    | $\sqrt{}$                  | -                          | -                | $\sqrt{}$        | $\checkmark$     | $\checkmark$   | -  |
| CLK_ClockDetector <sup>2</sup> | V                          | V                          | V                | √                | √                | √  | <b>√</b>   |
| CRC_CCITT                      | V                          | V                          | V                | $\sqrt{}$        | √                | √  | <b>V</b>   |
| CRC_CRC8                       | V                          | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | <b>V</b>   | $\checkmark$   |
| CRC_CRC32                      | √                          | √                          | √                | √                | √                | √  | V  |
| CRYPTO_AES                     | √                          | -                          | -                | -                | -                | -  | -  |
| DAC_ExtPinTrigger              | V                          | -                          | -                | √                | -                | -  | -  |
| DAC_GroupMode                  | V                          | -                          | -                | -                | -                | -  | -  |

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 $<sup>^{1}\ \</sup>mbox{\footnotesize BPWM\_SyncStart}$  requires two BPWM ports.

 $<sup>^2\,\</sup>mbox{CLK\_ClockDetector}$  requires HXT.



| Part Number Sample Code | M254xG<br>M256xG<br>M258xG | M254xE<br>M256xE<br>M258xE | M254xD<br>M256xD | M251xG<br>M252xG | M251xE<br>M252xE | M251LC<br>M251SC<br>M251xD<br>M252LC<br>M252SC<br>M252xD | M251EC<br>M251FC<br>M251ZC<br>M252EC<br>M252FC<br>M252ZC |
|-------------------------|----------------------------|----------------------------|------------------|------------------|------------------|--|--|
| DAC_PDMA_TimerTrigger   | √                          | -                          | -                | √                | -                | -  | -  |
| DAC_SoftwareTrigger     | V                          | -                          | -                | √                | -                | -  | -  |
| DAC_TimerTrigger        | √                          | -                          | -                | √                | -                | -  | -  |
| EADC_Accumulate         | V                          | √                          | √                | √                | √                | √  | √  |
| EADC_ADINT_Trigger      | V                          | <b>√</b>                   | V                | V                | √                | V  | <b>√</b>   |
| EADC_Average            | √                          | √                          | √                | √                | √                | √  | <b>√</b>   |
| EADC_BandGap            | V                          | √                          | V                | √                | <b>V</b>         | V  | √  |
| EADC_BPWM_Trigger       | V                          | V                          | V                | V                | V                | V  | -  |
| EADC_PDMA_BPWM_Trigger  | V                          | <b>√</b>                   | V                | <b>V</b>         | V                | V  | -  |
| EADC_PDMA_PWM_Trigger   | -                          | -                          | -                | <b>V</b>         | V                | V  | <b>V</b>   |
| EADC_Pending_Priority   | V                          | <b>V</b>                   | <b>V</b>         | <b>V</b>         | <b>V</b>         | <b>V</b>   | <b>V</b>   |
| EADC_PWM_Trigger        | -                          | -                          | -                | √                | V                | <b>√</b>   | <b>V</b>   |
| EADC_ResultMonitor      | √                          | √                          | √                | √                | √                | √  | <b>V</b>   |
| EADC_SWTRG_Trigger      | V                          | √                          | V                | √                | $\sqrt{}$        | V  | <b>V</b>   |
| EADC_TempSensor         | V                          | √                          | V                | √                | $\sqrt{}$        | V  | <b>V</b>   |
| EADC_Timer_Trigger      | V                          | √                          | V                | √                | <b>V</b>         | V  | <b>V</b>   |
| EADC_VBat               | V                          | √                          | V                | √                | $\sqrt{}$        | -  | -  |
| EBI_NOR                 | -                          | -                          | -                | √                | √                | -  | -  |
| EBI_SRAM                | -                          | -                          | -                | √                | √                | -  | -  |
| FMC_CRC32               | <b>V</b>                   | √                          | √                | √                | √                | √  | <b>√</b>   |
| FMC_ExeInSRAM           | V                          | √                          | √                | √                | √                | √  | √  |
| FMC_IAP                 | V                          | <b>V</b>                   | √                | √                | <b>√</b>         | √  | <b>V</b>   |



| Part Number Sample Code   | M254xG<br>M256xG<br>M258xG | M254xE<br>M256xE<br>M258xE | M254xD<br>M256xD | M251xG<br>M252xG | M251xE<br>M252xE | M251LC<br>M251SC<br>M251xD<br>M252LC<br>M252SC<br>M252SC | M251EC<br>M251FC<br>M251ZC<br>M252EC<br>M252FC<br>M252ZC |
|---------------------------|----------------------------|----------------------------|------------------|------------------|------------------|--|--|
| FMC_MultiBoot             | $\sqrt{}$                  | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | V  |
| FMC_MultiWordProgram      | $\sqrt{}$                  | $\sqrt{}$                  | √                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | V  |
| FMC_ReadAllOne            | $\sqrt{}$                  | $\sqrt{}$                  | √                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | V  |
| FMC_RW                    | $\sqrt{}$                  | $\sqrt{}$                  | √                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | V  |
| FMC_XOM                   | V                          | $\sqrt{}$                  | √                | √                | √                | V  | V  |
| GPIO_EINTAndDebounce      | √                          | √                          | √                | √                | √                | √  | V  |
| GPIO_INT                  | V                          | √                          | √                | √                | √                | √  | V  |
| GPIO_OutputInput          | V                          | √                          | √                | √                | √                | √  | V  |
| GPIO_PowerDown            | √                          | $\sqrt{}$                  | √                | $\checkmark$     | $\checkmark$     | $\sqrt{}$  | V  |
| GPIO_SingleCycleIO        | √                          | √                          | √                | √                | √                | √  | V  |
| I2C_EEPROM                | √                          | $\sqrt{}$                  | √                | $\checkmark$     | $\checkmark$     | $\sqrt{}$  | V  |
| I2C_GCMode_Master         | √                          | √                          | √                | √                | √                | √  | V  |
| I2C_GCMode_Slave          | √                          | √                          | √                | √                | √                | V  | <b>V</b>   |
| I2C_Loopback <sup>3</sup> | V                          | -                          | -                | <b>V</b>         | <b>V</b>         | V  | V  |
| I2C_Master                | V                          | V                          | √                | V                | V                | V  | V  |
| I2C_MultiBytes_Master     | V                          | <b>V</b>                   | √                | <b>V</b>         | <b>V</b>         | V  | V  |
| I2C_PDMA_TRX              | √                          | -                          | -                | √                | √                | V  | <b>V</b>   |
| I2C_SingleByte_Master     | V                          | √                          | √                | √                | √                | √  | V  |
| I2C_Slave                 | V                          | √                          | √                | √                | √                | √  | √  |

 $^3$  I2C\_Loopback, I2C\_PDMA\_TRX, and I2C\_SMBus require two  $\mbox{I}^2\mbox{C}$  ports.



| Part Number Sample Code           | M254xG<br>M256xG<br>M258xG | M254xE<br>M256xE<br>M258xE | M254xD<br>M256xD | M251xG<br>M252xG | M251xE<br>M252xE | M251LC<br>M251SC<br>M251xD<br>M252LC<br>M252SC<br>M252SC | M251EC<br>M251FC<br>M251ZC<br>M252EC<br>M252FC<br>M252ZC |
|-----------------------------------|----------------------------|----------------------------|------------------|------------------|------------------|--|--|
| I2C_SMBus                         | √                          | -                          | -                | V                | √                | √  | -  |
| I2C_Wakeup_Slave                  | V                          | $\checkmark$               | $\sqrt{}$        | V                | $\sqrt{}$        | $\sqrt{}$  | <b>V</b>   |
| LCD_Blinking                      | V                          | <b>√</b>                   | √                | •                | -                | -  | -  |
| LCD_Pixel_OnOff                   | V                          | <b>√</b>                   | √                | •                | -                | -  | -  |
| LCD_PowerConsumption              | $\sqrt{}$                  | $\checkmark$               | $\sqrt{}$        | ı                | ı                | -  | -  |
| LCD_Print_Text                    | V                          | <b>√</b>                   | √                | •                | -                | -  | -  |
| OPA_Control                       | -                          | -                          | -                | V                | -                | -  | -  |
| PDMA_BasicMode                    | V                          | $\sqrt{}$                  | <b>√</b>         | V                | $\sqrt{}$        | $\sqrt{}$  | <b>V</b>   |
| PDMA_ScatterGather                | $\sqrt{}$                  | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | √  |
| PDMA_ScatterGather_PingPongBuffer | V                          | <b>√</b>                   | <b>√</b>         | V                | √                | V  | <b>√</b>   |
| PSIO_1Wire                        | -                          | -                          | -                | V                | $\sqrt{}$        | $\sqrt{}$  | -  |
| PSIO_DMX512                       | •                          | •                          | -                | V                | √                | V  | -  |
| PSIO_HDQ                          | ı                          | ı                          | -                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | -  |
| PSIO_IR                           | ı                          | ı                          | -                | $\sqrt{}$        | $\sqrt{}$        | V  | -  |
| PSIO_LED                          | ı                          | ı                          | -                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | -  |
| PSIO_Microwire                    | ı                          | ı                          | -                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | -  |
| PSIO_PS2_Device                   | -                          | -                          | -                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | -  |
| PSIO_PS2_Host                     | -                          | -                          | -                | V                | $\sqrt{}$        | V  | -  |
| PSIO_Wiegand                      | -                          | -                          | -                | <b>V</b>         | $\sqrt{}$        | √  | -  |
| PWM_Brake                         | -                          | -                          | -                | V                | $\sqrt{}$        | √  | <b>√</b>   |
| PWM_Capture                       | -                          | -                          | -                | V                | $\sqrt{}$        | √  | <b>√</b>   |
| PWM_DeadTime                      | -                          | -                          | -                | V                | <b>V</b>         | √  | <b>√</b>   |



| Part Number Sample Code | M254xG<br>M256xG<br>M258xG | M254xE<br>M256xE<br>M258xE | M254xD<br>M256xD | M251xG<br>M252xG | M251xE<br>M252xE | M251LC<br>M251SC<br>M251xD<br>M252LC<br>M252SC<br>M252XD | M251EC<br>M251FC<br>M251ZC<br>M252EC<br>M252FC<br>M252ZC |
|-------------------------|----------------------------|----------------------------|------------------|------------------|------------------|--|--|
| PWM_DoubleBuffer        | -                          | -                          | ı                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | $\sqrt{}$  |
| PWM_OutputWaveform      | -                          | -                          | -                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | <b>V</b>   |
| PWM_PDMA_Capture        | -                          | -                          | -                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | <b>V</b>   |
| PWM_SwitchDuty          | -                          | -                          | -                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | <b>V</b>   |
| PWM_SyncStart           | -                          | -                          | -                | √                | <b>V</b>         | √  | √  |
| QSPI_DualMode_Flash     | -                          | -                          | -                | √                | $\sqrt{}$        | V  | $\checkmark$   |
| QSPI_QuadMode_Flash     | -                          | -                          | -                | √                | $\sqrt{}$        | V  | <b>√</b>   |
| QSPI_Slave3Wire         | -                          | -                          | -                | √                | √                | √  | <b>√</b>   |
| RTC_Alarm_Test          | $\sqrt{}$                  | $\sqrt{}$                  | $\sqrt{}$        | $\checkmark$     | $\sqrt{}$        | $\sqrt{}$  | <b>V</b>   |
| RTC_Alarm_Wakeup        | V                          | <b>√</b>                   | V                | √                | <b>√</b>         | √  | <b>V</b>   |
| RTC_Spare_Access        | -                          | -                          | -                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | -  |
| RTC_Static_Tamper       | -                          | -                          | -                | √                | <b>√</b>         | √  | -  |
| RTC_Time_Display        | V                          | $\sqrt{}$                  | V                | √                | $\sqrt{}$        | V  | <b>√</b>   |
| SC_ReadATR              | $\sqrt{}$                  | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | <b>V</b>   |
| SC_ReadSimPhoneBook     | √                          | √                          | √                | √                | √                | √  | <b>√</b>   |
| SC_Timer                | √                          | √                          | V                | √                | √                | √  | <b>V</b>   |
| SCUART_TxRx             | √                          | √                          | <b>V</b>         | √                | $\sqrt{}$        | √  | <b>V</b>   |
| SPI_Flash               | V                          | √                          | V                | √                | $\sqrt{}$        | √  | -  |
| SPI_HalfDuplex          | V                          | <b>V</b>                   | V                | <b>V</b>         | <b>V</b>         | √  | -  |
| SPI_Loopback            | V                          | V                          | V                | <b>V</b>         | <b>√</b>         | V  | -  |
| SPI_MasterFIFOMode      | V                          | V                          | V                | <b>V</b>         | <b>√</b>         | V  | -  |
| SPI_PDMA_LoopTest       | V                          | $\sqrt{}$                  | V                | $\sqrt{}$        | V                | V  | -  |



| Part Number                    | M254xG<br>M256xG<br>M258xG | M254xE<br>M256xE<br>M258xE | M254xD<br>M256xD | M251xG<br>M252xG | M251xE<br>M252xE | M251LC<br>M251SC<br>M251xD<br>M252LC<br>M252SC<br>M252XD | M251EC<br>M251FC<br>M251ZC<br>M252EC<br>M252FC<br>M252ZC |
|--------------------------------|----------------------------|----------------------------|------------------|------------------|------------------|--|--|
| Sample Code  SPI_SlaveFIFOMode | V                          | √                          | √                | √                | √                | WIZ5ZXD<br>√   | -  |
| SPI_SlaveFIFOModeINT           | ·<br>√                     | · √                        | ,<br>√           | ,<br>√           | ·<br>√           | √<br>√   | -  |
| SPII2S_Master                  | √                          | √                          | √                | √                | √                | √  | -  |
| SPII2S_PDMA_Codec              | V                          | V                          | √                | √                | √                | V  | -  |
| SPII2S_PDMA_Play               | √                          | √                          | √                | √                | √                | √  | -  |
| SPII2S_PDMA_PlayRecord         | V                          | V                          | $\sqrt{}$        | $\sqrt{}$        | V                | V  | -  |
| SPII2S_PDMA_Record             | V                          | $\sqrt{}$                  | √                | √                | $\sqrt{}$        | V  | -  |
| SPII2S_Slave                   | V                          | V                          | V                | V                | V                | V  | -  |
| SYS_BODWakeup                  | V                          | V                          | <b>V</b>         | <b>V</b>         | V                | V  | <b>V</b>   |
| SYS_DPDMode_Wakeup             | V                          | V                          | <b>V</b>         | <b>V</b>         | V                | V  | <b>V</b>   |
| SYS_PLLClockOutput             | -                          | -                          | -                | <b>V</b>         | <b>V</b>         | <b>V</b>   | -  |
| SYS_PowerDownMode              | V                          | V                          | √                | √                | $\sqrt{}$        | √  | <b>V</b>   |
| SYS_PowerMode                  | √                          | √                          | √                | √                | √                | √  | √  |
| SYS_TrimHIRC                   | V                          | V                          | √                | √                | $\sqrt{}$        | V  | <b>V</b>   |
| SYS_TrimMIRC                   | V                          | $\sqrt{}$                  | <b>V</b>         | <b>V</b>         | $\sqrt{}$        | V  | $\sqrt{}$  |
| TIMER_ACMPTrigger              | V                          | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | -  |
| TIMER_CaptureCounter           | V                          | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | <b>V</b>   |
| TIMER_Delay                    | V                          | V                          | V                | V                | $\sqrt{}$        | V  | V  |
| TIMER_EventCounter             | V                          | V                          | √                | √                | $\sqrt{}$        | $\sqrt{}$  | V  |
| TIMER_FreeCountingMode         | √                          | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | <b>V</b>   |
| TIMER_InterTimerTriggerMode    | V                          | $\sqrt{}$                  | √                | √                | $\sqrt{}$        | V  | √  |
| TIMER_Periodic                 | V                          | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | V  |



| Part Number Sample Code        | M254xG<br>M256xG<br>M258xG | M254xE<br>M256xE<br>M258xE | M254xD<br>M256xD | M251xG<br>M252xG | M251xE<br>M252xE | M251LC<br>M251SC<br>M251xD<br>M252LC<br>M252SC<br>M252XD | M251EC<br>M251FC<br>M251ZC<br>M252EC<br>M252FC<br>M252ZC |
|--------------------------------|----------------------------|----------------------------|------------------|------------------|------------------|--|--|
| TIMER_PeriodicINT              | V                          | $\sqrt{}$                  | V                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | √  |
| TIMER_PWM_ChangeDuty           | V                          | $\sqrt{}$                  | V                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | <b>V</b>   |
| TIMER_PWM_OutputWaveform       | V                          | $\sqrt{}$                  | V                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | √  |
| TIMER_TimeoutWakeup            | V                          | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | <b>√</b>   |
| TIMER_ToggleOut                | V                          | $\sqrt{}$                  | V                | √                | V                | V  | <b>V</b>   |
| TK_PowerDownMode <sup>5</sup>  | V                          | $\checkmark$               | V                | -                | -                | -  | -  |
| UART_AutoBaudRate              | V                          | $\sqrt{}$                  | V                | √                | $\sqrt{}$        | V  | <b>V</b>   |
| UART_AutoFlow                  | V                          | $\sqrt{}$                  | V                | √                | V                | V  | <b>V</b>   |
| UART_IrDA                      | V                          | <b>√</b>                   | V                | √                | V                | V  | <b>V</b>   |
| UART_LIN                       | V                          | $\sqrt{}$                  | V                | √                | V                | V  | <b>V</b>   |
| UART_PDMA                      | V                          | $\sqrt{}$                  | V                | √                | V                | V  | <b>V</b>   |
| UART_RS485                     | V                          | $\sqrt{}$                  | V                | √                | $\sqrt{}$        | V  | <b>V</b>   |
| UART_SingleWire                | V                          | <b>V</b>                   | V                | √                | <b>V</b>         | √  | <b>V</b>   |
| UART_TxRxFunction              | <b>V</b>                   | <b>√</b>                   | √                | √                | $\sqrt{}$        | √  | <b>V</b>   |
| UART_Wakeup                    | <b>V</b>                   | <b>√</b>                   | √                | √                | $\sqrt{}$        | √  | <b>V</b>   |
| USBD_Audio_Codec <sup>67</sup> | <b>√</b>                   | <b>V</b>                   | -                | V                | V                | V  | -  |

 $<sup>^{5}</sup>$  Only M256 and M258 series support TK samples.

 $<sup>^{6}\,\</sup>mbox{Only}$  M252 and M258 series support USBD samples.

 $<sup>^{7}\, \</sup>rm USBD\_Audio\_Codec$  requires I^2S. The audio quality depends on system performance and PCM buffer size.



| Part Number Sample Code                 | M254xG<br>M256xG<br>M258xG | M254xE<br>M256xE<br>M258xE | M254xD<br>M256xD | M251xG<br>M252xG | M251xE<br>M252xE | M251LC<br>M251SC<br>M251xD<br>M252LC<br>M252SC<br>M252XD | M251EC<br>M251FC<br>M251ZC<br>M252EC<br>M252FC<br>M252ZC |
|---|----------------------------|----------------------------|------------------|------------------|------------------|--|--|
| USBD_Audio_Headset <sup>8</sup>         | -                          | -                          | -                | $\sqrt{}$        | -                | -  | -  |
| USBD_BC12_HID_Mouse <sup>9</sup>        | <b>V</b>                   | $\sqrt{}$                  | -                | -                | -                | -  | ,  |
| USBD_HID_Keyboard                       | V                          | √                          | -                | √                | √                | √  | <b>V</b>   |
| USBD_HID_Mouse                          | V                          | √                          | -                | √                | <b>V</b>         | V  | V  |
| USBD_HID_MouseKeyboard                  | $\sqrt{}$                  | $\sqrt{}$                  | -                | <b>V</b>         | $\sqrt{}$        | $\sqrt{}$  | $\checkmark$   |
| USBD_HID_RemoteWakeup                   | $\sqrt{}$                  | $\sqrt{}$                  | -                | <b>V</b>         | $\sqrt{}$        | $\sqrt{}$  | $\checkmark$   |
| USBD_HID_Transfer                       | $\sqrt{}$                  | $\sqrt{}$                  | -                | <b>V</b>         | $\sqrt{}$        | $\sqrt{}$  | $\checkmark$   |
| USBD_HID_Transfer_And_Keyboard          | $\sqrt{}$                  | $\sqrt{}$                  | -                | <b>V</b>         | $\sqrt{}$        | $\sqrt{}$  | $\checkmark$   |
| USBD_HID_Transfer_And_MSC <sup>11</sup> | <b>√</b>                   | $\checkmark$               | -                | <b>V</b>         | $\checkmark$     | V  | ı  |
| USBD_HID_Transfer_CTRL                  | $\sqrt{}$                  | $\sqrt{}$                  | -                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | V  |
| USBD_Mass_Storage_CDROM                 | $\sqrt{}$                  | $\sqrt{}$                  | -                | <b>V</b>         | $\sqrt{}$        | $\sqrt{}$  | V  |
| USBD_Mass_Storage_Flash                 | V                          | $\sqrt{}$                  | -                | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | -  |
| USBD_Mass_Storage_SRAM                  | $\sqrt{}$                  | -                          | -                | <b>V</b>         | ı                | -  | ı  |
| USBD_Micro_Printer                      | V                          | <b>V</b>                   | -                | <b>V</b>         | $\sqrt{}$        | V  | V  |
| USBD_Printer_And_HID_Transfer           | V                          | <b>V</b>                   | -                | <b>V</b>         | $\sqrt{}$        | V  | V  |
| USBD_VCOM_And_HID_Keyboard              | V                          | √                          | -                | √                | √                | √  | V  |
| USBD_VCOM_And_HID_Transfer              | V                          | $\checkmark$               | -                | √                | $\sqrt{}$        | $\sqrt{}$  | V  |

<sup>8</sup> USBD\_Audio\_Headset requires enough SRAM.

<sup>&</sup>lt;sup>9</sup> Only M258 series supports BC1.2.

<sup>11</sup> Mass storage function of USBD samples requires enough storage size for distinct file systems of operation systems.



| Part Number Sample Code         | M254xG<br>M256xG<br>M258xG | M254xE<br>M256xE<br>M258xE | M254xD<br>M256xD | M251xG<br>M252xG | M251xE<br>M252xE | M251LC<br>M251SC<br>M251xD<br>M252LC<br>M252SC<br>M252XD | M251EC<br>M251FC<br>M251ZC<br>M252EC<br>M252FC<br>M252ZC |
|---------------------------------|----------------------------|----------------------------|------------------|------------------|------------------|--|--|
| USBD_VCOM_And_Mass_Storage      | V                          | √                          | -                | √                | <b>√</b>         | √  | -  |
| USBD_VCOM_DualPort              | V                          | V                          | -                | √                | <b>V</b>         | V  | <b>V</b>   |
| USBD_VCOM_SerialEmulator        | V                          | V                          | -                | √                | V                | V  | V  |
| USCI_I2C_EEPROM                 | V                          | V                          | <b>V</b>         | <b>V</b>         | <b>V</b>         | √  | V  |
| USCI_I2C_Lookback <sup>12</sup> | V                          | -                          | -                | √                | V                | V  | -  |
| USCI_I2C_Loopback_10bit         | V                          | -                          | -                | <b>V</b>         | V                | V  | -  |
| USCI_I2C_Master                 | V                          | V                          | <b>V</b>         | <b>V</b>         | V                | <b>V</b>   | V  |
| USCI_I2C_Master_10bit           | V                          | V                          | √                | √                | $\sqrt{}$        | √  | V  |
| USCI_I2C_Monitor                | √                          | V                          | √                | √                | √                | √  | √  |
| USCI_I2C_MultiBytes_Master      | V                          | $\sqrt{}$                  | <b>V</b>         | √                | $\sqrt{}$        | V  | V  |
| USCI_I2C_SingleByte_Master      | V                          | V                          | <b>V</b>         | √                | <b>V</b>         | V  | V  |
| USCI_I2C_Slave                  | V                          | $\sqrt{}$                  | $\sqrt{}$        | √                | $\sqrt{}$        | $\sqrt{}$  | V  |
| USCI_I2C_Slave_10bit            | V                          | V                          | $\sqrt{}$        | √                | $\sqrt{}$        | V  | V  |
| USCI_I2C_Wakeup_Slave           | V                          | V                          | $\sqrt{}$        | √                | $\sqrt{}$        | V  | V  |
| USCI_SPI_Loopback               | V                          | V                          | √                | √                | $\sqrt{}$        | V  | V  |
| USCI_SPI_MasterMode             | V                          | V                          | V                | √                | $\sqrt{}$        | V  | V  |
| USCI_SPI_PDMA_LoopTest13        | $\sqrt{}$                  | -                          | -                | √                | $\sqrt{}$        | $\sqrt{}$  | -  |
| USCI_SPI_SlaveMode              | V                          | V                          | √                | √                | <b>V</b>         | √  | √  |

 $^{12}$  USCI\_I2C\_Lookback and USCI\_I2C\_Loopback\_10bit require two USCI ports.

<sup>13</sup> USCI\_SPI\_PDMA\_LoopTest requires two USCI ports.



| Part Number Sample Code        | M254xG<br>M256xG<br>M258xG | M254xE<br>M256xE<br>M258xE | M254xD<br>M256xD | M251xG<br>M252xG | M251xE<br>M252xE | M251LC<br>M251SC<br>M251xD<br>M252LC<br>M252SC<br>M252XD | M251EC<br>M251FC<br>M251ZC<br>M252EC<br>M252EC<br>M252FC<br>M252ZC |
|--------------------------------|----------------------------|----------------------------|------------------|------------------|------------------|--|--|
| USCI_SPI_SlaveModeINT          | $\sqrt{}$                  | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | $\sqrt{}$  |
| USCI_UART_AutoBaudRate         | $\sqrt{}$                  | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | $\sqrt{}$  |
| USCI_UART_Autoflow_Master      | $\sqrt{}$                  | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | $\sqrt{}$  |
| USCI_UART_Autoflow_Slave       | $\sqrt{}$                  | $\sqrt{}$                  | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$        | $\sqrt{}$  | $\sqrt{}$  |
| USCI_UART_PDMA                 | $\sqrt{}$                  | $\sqrt{}$                  | √                | √                | $\sqrt{}$        | √  | √  |
| USCI_UART_RS485_Master         | $\sqrt{}$                  | $\sqrt{}$                  | √                | √                | $\sqrt{}$        | √  | √  |
| USCI_UART_RS485_Slave          | $\sqrt{}$                  | $\sqrt{}$                  | √                | √                | $\sqrt{}$        | √  | √  |
| USCI_UART_TxRxFunction         | V                          | V                          | <b>√</b>         | <b>√</b>         | √                | <b>√</b>   | V  |
| USCI_UART_Wakeup <sup>14</sup> | V                          | V                          | V                | √                | V                | √  | √  |
| WDT_TimeoutWakeupAndReset      | √                          | √                          | √                | √                | <b>V</b>         | √  | √  |
| WWDT_CompareINT                | √                          | √                          | √                | √                | √                | √  | √  |

 $^{14}\, {\rm USCI\_UART\_Wakeup}$  nCTS wakeup function requires USCI\_CTL0 pin.



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