

# M2U51 Series CMSIS BSP Guide

Directory Introduction for 32-bit NuMicro® Family

## Directory Information

<b>Document</b>	Driver reference guide and revision history.
<b>Library</b>	Driver header and source files.
<b>SampleCode</b>	Driver sample code.

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## 1 Document

<b>CMSIS.html</b>	Document of CMSIS version 6.1.0.
<b>NuMicro M2U51 Driver Reference Guide.chm</b>	This document describes the usage of drivers in M2U51 BSP.
<b>NuMicro M2U51 Series CMSIS BSP Revision History.pdf</b>	This document shows the revision history of M2U51 BSP.

## 2 Library

<b>CMSIS</b>	Cortex® Microcontroller Software Interface Standard (CMSIS) V6.1.0 definitions by Arm® Corp.
<b>Device</b>	CMSIS compliant device header file.
<b>StdDriver</b>	All peripheral driver header and source files.

### 3 SampleCode

<b>Hard_Fault_Sample</b>	<p>Show hard fault information when hard fault happened.</p> <p>The hard fault handler shows some information included program counter, which is the address where the processor was executing when the hard fault occurs. The listing file (or map file) can show what function and instruction that was.</p> <p>It also shows the Link Register (LR), which contains the return address of the last function call. It can show the status where CPU comes from to get to this point.</p>
<b>ISP</b>	Sample codes for In-System-Programming.
<b>PowerManagement</b>	Sample codes for power management.
<b>Semihost</b>	Show how to print and get character through IDE console window.
<b>StdDriver</b>	Sample code to demonstrate the usage of M2U51 series MCU peripheral driver APIs.
<b>Template</b>	A project template for M2U51 series MCU.

## **4 SampleCode\ISP**

<b>ISP_I2C</b>	In-System-Programming Sample code through I <sup>2</sup> C interface.
<b>ISP_RS485</b>	In-System-Programming Sample code through RS485 interface.
<b>ISP_SPI</b>	In-System-Programming Sample code through SPI interface.
<b>ISP_UART</b>	In-System-Programming Sample code through UART interface.

## 5 SampleCode\PowerManagement

<b>SYS_DPDMode_Wakeup</b>	Show how to wake up system from DPD Power-down mode by Wake-up pin 0 (PC.0) or Wake-up Timer or RTC Tick or RTC Alarm or RTC Tamper 0.
<b>SYS_PowerDownMode</b>	Show how to enter different Power-down mode and wake up by RTC.
<b>SYS_PowerMode</b>	Show how to set different core voltage.
<b>SYS_SPDMode_Wakeup</b>	Show how to wake up system from SPD Power-down mode by Wake-up pin (PC.0) or Wake-up Timer or Wake-up ACMP or RTC Tick or RTC Alarm or RTC Tamper 0 or BOD or LVR.
<b>SYS_SPDMode_WakeupVTOR</b>	Show how to continue executing code after wake-up from SPD Power-down mode by VTOR function.

## 6 SampleCode\StdDriver

### System Manager (SYS)

<b>SYS_BODWakeup</b>	Demonstrate how to wake up system from Power-down mode by brown-out detector interrupt.
<b>SYS_MIRCClockOutput</b>	Change system clock to different MIRC frequency and output system clock from CLKO pin.
<b>SYS_PowerDown_MinCurrent</b>	Demonstrate how to minimize power consumption when entering power down mode.
<b>SYS_TrimHIRC</b>	Demonstrate how to use LXT to trim HIRC.
<b>SYS_TrimMIRC</b>	Demonstrate how to use LXT to trim MIRC.

### Flash Memory Controller (FMC)

<b>FMC_CRC32</b>	Demonstrate how to use FMC CRC32 ISP command to calculate the CRC32 checksum of APROM and LDROM.
<b>FMC_ExeInSRAM</b>	Implement a code and execute it in SRAM to program embedded Flash.
<b>FMC_IAP</b>	Demonstrate FMC IAP boot mode and show how to use vector remap function. LDROM image was embedded in APROM image and be programmed to LDROM Flash at run-time. This sample also shows how to branch between APROM and LDROM.
<b>FMC_MultiBoot</b>	Implement a multi-boot system to boot from different applications in APROM or LDROM by VECMAP.
<b>FMC_MultiWordProgram</b>	Show how to use FMC multi-word (word line) program flow to program APROM and LDROM.
<b>FMC_ReadAllOne</b>	Demonstrate how to use FMC Read-All-One ISP command to verify APROM or LDROM pages are all 0xFFFFFFFF or not.
<b>FMC_RW</b>	Show FMC read Flash IDs, erase, read, and write functions.



## General Purpose I/O (GPIO)

GPIO_EINTAndDebounce	Show the usage of GPIO external interrupt function and de-bounce function.
GPIO_INT	Show the usage of GPIO interrupt function.
GPIO_OutputInput	Show how to set GPIO pin mode and use pin data input and output control.
GPIO_PowerDown	Show how to wake up system from Power-down mode by GPIO interrupt.

## PDMA Controller (PDMA)

PDMA_BasicMode	Use PDMA0 channel 2 to transfer data from memory to memory.
PDMA_ScatterGather	Use PDMA0 channel 2 to transfer data from memory to memory by scatter-gather mode.
PDMA_ScatterGather_PingPongBuffer	Use PDMA0 to implement Ping-Pong buffer by scatter-gather mode (memory to memory).
PDMA_TimeOut	Demonstrate PDMA0 channel 0 get/clear timeout flag with UART1.

## Timer Controller (TIMER)

TIMER_ACMPTrigger	Use ACMP to trigger Timer0 counter reset mode.
TIMER_CaptureCounter	Show how to use the Timer capture function to capture Timer counter value.
TIMER_Delay	Demonstrate the usage of TIMER_Delay API to generate a 1 second delay.
TIMER_EventCounter	Use TM0 pin to demonstrate Timer event counter function.
TIMER_FreeCountingMode	Use the timer TM0_EXT pin to demonstrate timer free counting mode function. And displays the measured

	input frequency to UART console.
<b>TIMER_InterTimerMode</b>	Use the timer TM0 pin to demonstrate inter timer trigger mode function. Also display the measured input frequency to UART console.
<b>TIMER_Periodic</b>	Use the Timer periodic mode to generate Timer interrupt every 1 second.
<b>TIMER_PeriodicINT</b>	Implement Timer counting in periodic mode.
<b>TIMER_PWM_AccumulatorINTStopMode</b>	Demonstrate TIMER PWM accumulator interrupt to stop counting.
<b>TIMER_PWM_AccumulatorINTTriggerPDMA</b>	Demonstrate TIMER PWM accumulator interrupt to trigger PDMA transfer.
<b>TIMER_PWM_ChangeDuty</b>	Change duty cycle and period of output waveform in PWM up count type.
<b>TIMER_PWM_OutputWaveform</b>	Demonstrate output different duty waveform in Timer0~3 PWM.
<b>TIMER_TimeoutWakeup</b>	Use timer to wake up system from Power-down mode periodically.
<b>TIMER_ToggleOut</b>	Demonstrate the Timer0 toggle out function on TM0 pin.

## Watchdog Timer (WDT)

<b>WDT_TimeoutWakeupAndReset</b>	Implement WDT time-out interrupt event to wake up system and generate time-out reset system event while WDT time-out reset delay period expired.
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## Window Watchdog Timer (WWDT)

<b>WWDT_ReloadCounter</b>	Show how to reload the WWDT counter value.
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## Real Timer Clock (RTC)

<b>RTC_Alarm_Test</b>	Demonstrate the RTC alarm function. It sets an alarm 10 seconds after execution.
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<b>RTC_Alarm_Wakeup</b>	Use RTC alarm interrupt event to wake up system.
<b>RTC_Time_Display</b>	Demonstrate the RTC function and displays current time to the UART console.

## Pulse Width Modulation Controller (PWM)

<b>PWM_240KHz_SwitchDuty</b>	Demonstrate how to set PWM0 channel 0 output 240 kHz waveform and switch duty in each 0.5%.
<b>PWM_Brake</b>	Demonstrate how to use PWM brake function.
<b>PWM_Capture</b>	Capture the PWM Channel 2 waveform by PWM Channel 0.
<b>PWM_DeadTime</b>	Demonstrate how to use PWM Dead Time function.
<b>PWM_DoubleBuffer</b>	Change duty cycle and period of output waveform by PWM double buffer function.
<b>PWM_OutputWaveform</b>	Demonstrate how to use PWM counter output waveform.
<b>PWM_PDMA_Capture</b>	Capture the PWM0 Channel 0 waveform by PWM0 Channel 2, and use PDMA to transfer captured data.
<b>PWM_PDMA_Capture_1MHzSingal</b>	Capture the PWM0 Channel 0 waveform by PWM0 Channel 2, and use PDMA to transfer captured data. The frequency of PWM Channel 0 is 1 MHz, which is used to test the maximum input frequency for PWM Capture function.
<b>PWM_SwitchDuty</b>	Change duty cycle of output waveform by configured period.
<b>PWM_SyncStart</b>	Demonstrate how to use PWM counter synchronous start function.

## Basic Pulse Width Modulation Controller (BPWM)

<b>BPWM_Capture</b>	Capture the BPWM1 Channel 0 waveform by BPWM1 Channel 2.
<b>BPWM_DoubleBuffer</b>	Change duty cycle and period of output waveform by

	BPWM Double Buffer function.
<b>BPWM_OutputWaveform</b>	Demonstrate how to use BPWM counter output waveform.
<b>BPWM_SwitchDuty</b>	Change duty cycle of output waveform by configured period.
<b>BPWM_SyncStart</b>	Demonstrate how to use BPWM counter synchronous start function.

## UART Interface Controller (UART)

<b>UART_AutoBaudRate</b>	Show how to use auto baud rate detection function.
<b>UART_AutoFlow</b>	Transmit and receive data using auto flow control.
<b>UART_AutoOperation</b>	Demonstrate how to enable UART Auto-operation mode to transmit and receive data when chip enters Power-down mode.
<b>UART_IrDA</b>	Transmit and receive UART data in UART IrDA mode.
<b>UART_PDMA</b>	Demonstrate UART transmit and receive function with PDMA.
<b>UART_RS485</b>	Transmit and receive data in UART RS485 mode.
<b>UART_SingleWire</b>	Transmit and receive data in UART single-wire mode.
<b>UART_TxRxFunction</b>	Transmit and receive data from PC terminal through RS232 interface.
<b>UART_Wakeup</b>	Show how to wake up system from Power-down mode by UART interrupt.

## Serial Peripheral Interface (SPI)

<b>SPI_AutoOperation</b>	Demonstrate how to do SPI loopback test in Auto-operation mode when chip enters power-down mode.
<b>SPI_Loopback</b>	SPI read/write demo connecting SPI MISO and MOSI pins.

<b>SPI_MasterFIFOmode</b>	Configure SPI as Master mode and demonstrate how to communicate with an off-chip SPI slave device with FIFO mode. This sample code needs to work with SPI_SlaveFIFOmode.
<b>SPI_PDMA_LoopTest</b>	SPI read/write demo in PDMA mode. Connecting SPI MISO and MOSI pins. Both TX PDMA function and RX PDMA function will be enabled.
<b>SPI_SlaveFIFOmode</b>	Configure SPI as Slave mode and demonstrate how to communicate with an off-chip SPI master device with FIFO mode. This sample code needs to work with SPI_MasterFIFOmode.

## I<sup>2</sup>C Serial Interface Controller (I<sup>2</sup>C)

<b>I2C_AutoOperation</b>	Demonstrate I <sup>2</sup> C Auto-operation mode when chip enters Power-down mode. This sample code needs to work with I2C_Slave.
<b>I2C_Double_Buffer_Slave</b>	Demonstrate how to set I <sup>2</sup> C two-level buffer in Slave mode to receive 256 bytes data from a master. This sample code needs to work with I2C_MultiBytes_Master.
<b>I2C_EEPROM</b>	Show how to use I <sup>2</sup> C interface to access EEPROM.
<b>I2C_Loopback</b>	Demonstrate how to set I <sup>2</sup> C Master mode and Slave Mode, and show how a master accesses a slave on a chip.
<b>I2C_Master</b>	Show how a master accesses a slave. This sample code needs to work with I2C_Slave.
<b>I2C_MultiBytes_Master</b>	Show how to set I <sup>2</sup> C Multi bytes API Read and Write data to Slave. This sample code needs to work with I2C_Slave.
<b>I2C_PDMA_TRX</b>	Demonstrate I <sup>2</sup> C PDMA mode and need to connect I2C0 (master) and I2C1 (slave).
<b>I2C_SingleByte_Master</b>	Show how to use I <sup>2</sup> C Single byte API Read and Write data to Slave. This sample code needs to work with I2C_Slave.

<b>I2C_Slave</b>	Demonstrate how to set I <sup>2</sup> C in Slave mode to receive 256 bytes data from a master. This sample code needs to work with I2C_Master.
<b>I2C_SMBus</b>	Demonstrate how to control SMBus interface and use SMBus protocol between Host and Slave.
<b>I2C_Wakeup_Slave</b>	Show how to wake up MCU from Power-down mode via the I <sup>2</sup> C interface. This sample code needs to work with I2C_Master.

### Universal Serial Control Interface Controller – UART Mode (USCI-UART)

<b>USCI_UART_AutoBaudRate</b>	Show how to use auto baud rate detection function.
<b>USCI_UART_Autoflow</b>	Transmit and receive data using auto flow control.
<b>USCI_UART_PDMA</b>	Transmit and receive UART data with PDMA.
<b>USCI_UART_RS485</b>	Transmit and receive data in RS485 mode.
<b>USCI_UART_TxRxFunction</b>	Transmit and receive data from PC terminal through a RS232 interface.
<b>USCI_UART_Wakeup</b>	Show how to wake up system from Power-down mode by USCI interrupt in UART mode.

### Universal Serial Control Interface Controller – SPI Mode (USCI-SPI)

<b>USCI_SPI_Loopback</b>	Implement USCI_SPI0 Master loop back transfer. This sample code needs to connect USCI_SPI0_MISO pin and USCI_SPI0_MOSI pin together. It will compare the received data with transmitted data.
<b>USCI_SPI_MasterMode</b>	Configure USCI_SPI0 as Master mode and demonstrate how to communicate with an off-chip SPI Slave device. This sample code needs to work with USCI_SPI_SlaveMode sample code.
<b>USCI_SPI_PDMA_LoopTest</b>	Demonstrate USCI_SPI data transfer with PDMA. USCI_SPI0 will be configured as Master mode. Both TX PDMA function and RX PDMA function will be enabled.

<b>USCI_SPI_SlaveMode</b>	Configure USCI_SPI0 as Slave mode and demonstrate how to communicate with an off-chip SPI Master device. This sample code needs to work with USCI_SPI_MasterMode sample code.
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## Universal Serial Control Interface Controller – I<sup>2</sup>C Mode (USCI-I2C)

<b>USCI_I2C_EEPROM</b>	Demonstrate how to access EEPROM through a USCI_I2C interface.
<b>USCI_I2C_Master</b>	Demonstrate how a Master accesses Slave. This sample code needs to work with USCI_I2C_Slave sample code.
<b>USCI_I2C_Master_10bit</b>	Demonstrate how a Master uses 10-bit addressing access Slave. This sample code needs to work with USCI_I2C_Slave_10bit sample code.
<b>USCI_I2C_Monitor</b>	Demonstrate how USCI_I2C monitors transmission between I2C Master and I2C Slave.
<b>USCI_I2C_MultiBytes_Master</b>	Demonstrate how to use multi-bytes API to access slave. This sample code needs to work with USCI_I2C_Slave sample code.
<b>USCI_I2C_SingleByte_Master</b>	Demonstrate how to use single byte API to access slave. This sample code needs to work with USCI_I2C_Slave sample code.
<b>USCI_I2C_Slave</b>	Demonstrate how to set USCI_I2C in slave mode to receive the data from a Master. This sample code needs to work with USCI_I2C_Master sample code.
<b>USCI_I2C_Slave_10bit</b>	Demonstrate how to set USCI_I2C in 10-bit addressing slave mode to receive the data from a Master. This sample code needs to work with USCI_I2C_Master_10bit sample code.
<b>USCI_I2C_Wakeup_Slave</b>	Demonstrate how to set USCI_I2C to wake up MCU from Power-down mode. This sample code needs to work with USCI_I2C_Master sample code.

## CRC Controller (CRC)

CRC_CCITT	Implement CRC in CRC-CCITT mode and get the CRC checksum result.
CRC_CRC32_PDMA	Implement CRC in CRC-32 mode and get the CRC checksum result.
CRC_CRC8	Implement CRC in CRC-8 mode and get the CRC checksum result.

## Cryptographic Accelerator (CRYPTO)

CRYPTO_AES	Show Crypto IP AES-128 ECB mode encrypt/decrypt function.
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## Analog-to-Digital Converter (ADC)

ADC_ADINT_Trigger	Use ADINT interrupt to do the ADC continuous scan conversion.
ADC_BandGap	Convert Band-gap and print conversion result.
ADC_BandGapCalculateAVDD	Demonstrate how to calculate battery voltage( AVdd ) by using band-gap.
ADC_BPWM_Trigger	Demonstrate how to trigger ADC by BPWM.
ADC_BurstMode	Perform A/D Conversion with ADC burst mode.
ADC_ContinuousScanMode	Perform A/D Conversion with ADC continuous scan mode.
ADC_MaxSPS	Demonstrate how to use HIRC as ADC clock source to achieve maximum SPS ADC conversion rate.
ADC_PDMA_BPWM_Trigger	Demonstrate how to trigger ADC by BPWM and transfer conversion data by PDMA.
ADC_PDMA_PWM_Trigger	Demonstrate how to trigger ADC by PWM and transfer conversion data by PDMA.
ADC_PWM_Trigger	Demonstrate how to trigger ADC by PWM.



<b>ADC_ResultMonitor</b>	Monitor the conversion result of channel 2 by the digital compare function.
<b>ADC_SingleCycleScanMode</b>	Perform A/D Conversion with ADC single cycle scan mode.
<b>ADC_SingleCycleScanMode2</b>	Perform A/D Conversion with ADC single mode to simulate single cycle scan mode.
<b>ADC_SingleMode</b>	Perform A/D Conversion with ADC single mode.
<b>ADC_STADC_Trigger</b>	Show how to trigger ADC by STADC pin.
<b>ADC_SwTrg_Trigger</b>	Trigger ADC by writing ADC software trigger register.
<b>ADC_TempSensor</b>	Convert temperature sensor and print conversion result.
<b>ADC_Timer_Trigger</b>	Show how to trigger ADC by Timer.

### **Analog Comparator Converter (ACMP)**

<b>ACMP_CompareVBG</b>	Demonstrate analog comparator (ACMP) comparison by comparing ACMP1_P1 input and VBG voltage and shows the result on UART console.
<b>ACMP_Wakeup</b>	Use ACMP to wake up system from Power-down mode while comparator output changes.
<b>ACMP_WindowCompare</b>	Show how to monitor ACMP input with window compare function.
<b>ACMP_WindowLatch</b>	Demonstrate how to use ACMP window latch mode.

### **Liquid Crystal Display (LCD)**

<b>LCD_Blinking</b>	The LCD displays the text with a blinking effect.
<b>LCD_Pixel_OnOff</b>	Configure the specified pixels to be either ON or OFF.
<b>LCD_Print_Text</b>	Display the specified text on the LCD screen.

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