

#### **Mini55 Series CMSIS BSP Directory**

Directory Introduction for 32-bit NuMicro® Family

#### **Directory Information**

| Document   | Driver reference manual and revision history. |
|------------|---|
| Library    | Driver header and source files.               |
| SampleCode | Driver sample code.                           |

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#### 1 Document Information

| NuMicro Mini55 Series<br>CMSIS BSP Revision<br>History.pdf |  | This document shows the revision history of Mini55 BSP.     |
|--|--|---|
|  | NuMicro Mini55 Driver<br>Reference Guide.chm | This document describes the usage of drivers in Mini55 BSP. |



# 2 Library Information

| CMSIS     | Cortex <sup>®</sup> Microcontroller Software Interface Standard (CMSIS) V3.01 definitions by ARM <sup>®</sup> Corp. |
|-----------|---|
| Device    | CMSIS compliant device header file.   |
| StdDriver | All peripheral driver header and source files.  |



## **3 Sample Code Information**

| Hard_Fault_Sample | Show hard fault information when hard fault happened.                                  |
|-------------------|--|
| RegBased          | Sample code implemented without access standard library but access registers directly. |
| Semihost          | Show how to print and get character with IDE console window.                           |
| StdDriver         | Demonstrate the usage of Mini55 MCU peripheral driver APIs.                            |
| Template          | A project template for Mini55 MCU.   |



## 4 \SampleCode\RegBased

| ACMP                     | Demonstrate Analog comparator (ACMP) comparison by comparing CPP0 (P1.5) with Band-gap voltage and shows the result on UART console.                                       |
|--------------------------|--|
| ACMP_TriggerTimerCapture | Show how to use Analog comparator (ACMP) state change to trigger timer capture function. P1.5 is used as comparator positive input and Band-gap voltage as negative input. |
| ADC_Compare              | Demonstrate ADC conversion and comparison function by monitoring the conversion result of channel 0.   |
| ADC_Convert              | Demonstrate ADC function by repeatedly convert the input of ADC channel 0 (P5.3) and shows the result on UART console.   |
| CLK_SwitchHCLK           | Demonstrate how to switch HCLK between HIRC and HXT.   |
| FMC_RW                   | Show FMC read flash IDs, erase, read, and write functions.   |
| GPIO                     | Use GPIO driver to control the GPIO pin direction, control their high/low state, and how to use GPIO interrupts.   |
| HDIV                     | Show how to use hardware divider.  |
| I2C_FIFO_EEPROM          | Read/write EEPROM via I <sup>2</sup> C interface using FIFO mode.  |
| I2C_Interrupt_EEPROM     | Read/write EEPROM via I <sup>2</sup> C interface using interrupt mode.   |
| PWM_DeadZone             | Demonstrate the dead-zone feature with PWM.  |
| PWM_DoubleBuffer         | Demonstrate the PWM double buffer feature.   |
| SPI_FIFO_FLASH           | Access SPI Flash using FIFO mode.  |
| SPI_LoopBack             | Demonstrate SPI function by connect MOSI (P0.5) with MISO (P0.6).  |
| Timer_EventCounter       | Use pin P3.4 to demonstrates timer event counter   |



|                           | function.  |
|---------------------------|--|
| Timer_FreeCountingMode    | Use the timer pin P3.2 to demonstrate timer free counting mode function. Also display the measured input frequency to UART console.    |
| Timer_Periodic            | Use the timer periodic mode to generate timer interrupt every 1 second.  |
| Timer_ToggleOut           | Demonstrate the timer 0 toggle out function on pin P3.4.   |
| Timer_TriggerCountingMode | Use the timer pin P3.2 to demonstrate timer trigger counting mode function. And displays the measured input frequency to UART console. |
| Timer_Wakeup              | Use Timer to wake up system from Power-down mode periodically.   |
| UART_AutoFlow             | Show how to transmit and receive data using auto flow control.   |
| UART_IrDA                 | Show how to transmit and receive UART data in UART IrDA mode.  |
| UART_RS485                | Transmit and receive data in UART RS485 mode.  |
| UART_TxRx_Function        | Transmit and receive data from PC terminal through RS232 interface.  |
| WDT_Polling               | Use polling mode to check WDT time-out state and reset WDT after time out occurs.  |
| WDT_Wakeup                | Use WDT to wake up system from Power-down mode periodically.   |



## 5 \SampleCode\StdDriver

| ACMP                 | Demonstrate Analog comparator (ACMP) comparison by comparing CPP0 (P1.5) with Band-gap voltage and shows the result on UART console. |
|----------------------|--|
| ADC_Compare          | Demonstrate ADC conversion and comparison function by monitoring the conversion result of channel 0.                                 |
| ADC_Convert          | Demonstrate ADC function by repeatedly convert the input of ADC channel 0 (P5.3) and shows the result on UART console.               |
| CLK_SwitchHCLK       | Demonstrate how to switch HCLK between HIRC and HXT.   |
| FMC IAP              | This sample code includes LDROM image (fmc_ld_iap) and APROM image (fmc_ap_main).  |
| T MO_IAI             | It shows how to branch between APROM and LDROM. To run this sample code, the boot mode must be "Boot from APROM with IAP".           |
| FMC_RW               | Show FMC read flash IDs, erase, read, and write functions.   |
| GPIO                 | Use GPIO driver to control the GPIO pin direction, control their high/low state, and how to use GPIO interrupts.                     |
| HDIV                 | Show how to use hardware divider.  |
| I2C_FIFO_EEPROM      | Read/write EEPROM via I <sup>2</sup> C interface using FIFO mode.  |
| I2C_Interrupt_EEPROM | Read/write EEPROM via I <sup>2</sup> C interface using interrupt mode.   |
| PWM_DeadZone         | Demonstrate the dead-zone feature with PWM.  |
| PWM_DoubleBuffer     | Demonstrate the PWM double buffer feature.   |
| SPI_FIFO_FLASH       | Access SPI Flash using FIFO mode.  |
| SPI_LoopBack         | Demonstrate SPI function by connect MOSI (P0.5) with MISO (P0.6).  |



| Demonstrate how to get PDID, get and clear reset source, configure BOD, and output system clock to CKO pin with the system clock / 4 frequency. |
|---|
| Demonstrate how to use LXT to trim HIRC.  |
| Use pin P3.4 to demonstrates timer event counter function.  |
| Use the timer pin P3.2 to demonstrate timer free counting mode function. Also display the measured input frequency to UART console.             |
| Use the timer periodic mode to generate timer interrupt every 1 second.   |
| Demonstrate the timer 0 toggle out function on pin P3.4.  |
| Use the timer pin P3.2 to demonstrate timer trigger counting mode function. And displays the measured input frequency to UART console.          |
| Use Timer to wake up system from Power-down mode periodically.  |
| Show how to transmit and receive data using auto flow control.  |
| Show how to transmit and receive UART data in UART IrDA mode.   |
| Transmit and receive data in UART RS485 mode.   |
| Transmit and receive data from PC terminal through RS232 interface.   |
| Use polling mode to check WDT time-out state and reset WDT after time out occurs.   |
| Use WDT to wake up system from Power-down mode periodically.  |
|   |



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