

Mini55 Series CMSIS BSP Directory

Directory Introduction for 32-bit NuMicro® Family

Directory Information

Document	Driver reference manual and revision history.
Library	Driver header and source files.
SampleCode	Driver sample code.

The information described in this document is the exclusive intellectual property of Nuvoton Technology Corporation and shall not be reproduced without permission from Nuvoton.

Nuvoton is providing this document only for reference purposes of NuMicro microcontroller based system design.

Nuvoton assumes no responsibility for errors or omissions.

All data and specifications are subject to change without notice.

For additional information or questions, please contact: Nuvoton Technology Corporation.

www.nuvoton.com



1 Document Information

CMSIS.html	Document of CMSIS version 4.5.0
NuMicro Mini55 Series CMSIS BSP Revision History.pdf	This document shows the revision history of Mini55 BSP.
NuMicro Mini55 Driver Reference Guide.chm	This document describes the usage of drivers in Mini55 BSP.



2 Library Information

CMSIS	Cortex [®] Microcontroller Software Interface Standard (CMSIS) V4.5 definitions by ARM [®] Corp.
Device	CMSIS compliant device header file.
StdDriver	All peripheral driver header and source files.



3 Sample Code Information

Hard_Fault_Sample	Show hard fault information when hard fault happened.
NuTiny-SDK-MINI55	Same codefor Mini51DE Tiny Board
RegBased	Sample code implemented without access standard library but access registers directly.
Semihost	Show how to print and get character with IDE console window.
StdDriver	Demonstrate the usage of Mini55 MCU peripheral driver APIs.
Template	A project template for Mini55 MCU.



4 \SampleCode\NuTiny-SDK-MINI55

LED_Toggle	This sample toggles P1.5 to turn on board LED on and off.
LLD_1 oggie	off.



\SampleCode\RegBased

ACMP	Demonstrate Analog comparator (ACMP) comparison by comparing CPP0 (P1.5) with Band-gap voltage and shows the result on UART console.
ACMP_TriggerTimerCapture	Show how to use Analog comparator (ACMP) state change to trigger timer capture function. P1.5 is used as comparator positive input and Band-gap voltage as negative input.
ADC_Compare	Demonstrate ADC conversion and comparison function by monitoring the conversion result of channel 0.
ADC_Convert	Demonstrate ADC function by repeatedly convert the input of ADC channel 0 (P5.3) and shows the result on UART console.
CLK_SwitchHCLK	Demonstrate how to switch HCLK between HIRC and HXT.
FMC_RW	Show FMC read flash IDs, erase, read, and write functions.
GPIO	Use GPIO driver to control the GPIO pin direction, control their high/low state, and how to use GPIO interrupts.
HDIV	Show how to use hardware divider.
I2C_FIFO_EEPROM	Read/write EEPROM via I ² C interface using FIFO mode.
I2C_Interrupt_EEPROM	Read/write EEPROM via I ² C interface using interrupt mode.
PWM_DeadZone	Demonstrate the dead-zone feature with PWM.
PWM_DoubleBuffer	Demonstrate the PWM double buffer feature.
SPI_FIFO_FLASH	Access SPI Flash using FIFO mode.
SPI_LoopBack	Demonstrate SPI function by connect MOSI (P0.5) with MISO (P0.6).
Timer_EventCounter	Use pin P3.4 to demonstrates timer event counter



	function.
Timer_FreeCountingMode	Use the timer pin P3.2 to demonstrate timer free counting mode function. Also display the measured input frequency to UART console.
Timer_Periodic	Use the timer periodic mode to generate timer interrupt every 1 second.
Timer_ToggleOut	Demonstrate the timer 0 toggle out function on pin P3.4.
Timer_TriggerCountingMode	Use the timer pin P3.2 to demonstrate timer trigger counting mode function. And displays the measured input frequency to UART console.
Timer_Wakeup	Use Timer to wake up system from Power-down mode periodically.
UART_AutoFlow	Show how to transmit and receive data using auto flow control.
UART_IrDA	Show how to transmit and receive UART data in UART IrDA mode.
UART_RS485	Transmit and receive data in UART RS485 mode.
UART_TxRx_Function	Transmit and receive data from PC terminal through RS232 interface.
WDT_Polling	Use polling mode to check WDT time-out state and reset WDT after time out occurs.
WDT_Wakeup	Use WDT to wake up system from Power-down mode periodically.



5 \SampleCode\StdDriver

ACMP	Demonstrate Analog comparator (ACMP) comparison by comparing CPP0 (P1.5) with Band-gap voltage and shows the result on UART console.
ADC_Compare	Demonstrate ADC conversion and comparison function by monitoring the conversion result of channel 0.
ADC_Convert	Demonstrate ADC function by repeatedly convert the input of ADC channel 0 (P5.3) and shows the result on UART console.
CLK_SwitchHCLK	Demonstrate how to switch HCLK between HIRC and HXT.
FMC IAP	This sample code includes LDROM image (fmc_ld_iap) and APROM image (fmc_ap_main).
TIVIO_IAF	It shows how to branch between APROM and LDROM. To run this sample code, the boot mode must be "Boot from APROM with IAP".
FMC_RW	Show FMC read flash IDs, erase, read, and write functions.
GPIO	Use GPIO driver to control the GPIO pin direction, control their high/low state, and how to use GPIO interrupts.
HDIV	Show how to use hardware divider.
I2C_FIFO_EEPROM	Read/write EEPROM via I ² C interface using FIFO mode.
I2C_Interrupt_EEPROM	Read/write EEPROM via I ² C interface using interrupt mode.
PWM_DeadZone	Demonstrate the dead-zone feature with PWM.
PWM_DoubleBuffer	Demonstrate the PWM double buffer feature.
SPI_FIFO_FLASH	Access SPI Flash using FIFO mode.
SPI_LoopBack	Demonstrate SPI function by connect MOSI (P0.5) with MISO (P0.6).



Demonstrate how to get PDID, get and clear reset source, configure BOD, and output system clock to CKO pin with the system clock / 4 frequency.
Demonstrate how to use LXT to trim HIRC.
Use pin P3.4 to demonstrates timer event counter function.
Use the timer pin P3.2 to demonstrate timer free counting mode function. Also display the measured input frequency to UART console.
Use the timer periodic mode to generate timer interrupt every 1 second.
Demonstrate the timer 0 toggle out function on pin P3.4.
Use the timer pin P3.2 to demonstrate timer trigger counting mode function. And displays the measured input frequency to UART console.
Use Timer to wake up system from Power-down mode periodically.
Show how to transmit and receive data using auto flow control.
Show how to transmit and receive UART data in UART IrDA mode.
Transmit and receive data in UART RS485 mode.
Transmit and receive data from PC terminal through RS232 interface.
Use polling mode to check WDT time-out state and reset WDT after time out occurs.
Use WDT to wake up system from Power-down mode periodically.



Important Notice

Nuvoton Products are neither intended nor warranted for usage in systems or equipment, any malfunction or failure of which may cause loss of human life, bodily injury or severe property damage. Such applications are deemed, "Insecure Usage".

Insecure usage includes, but is not limited to: equipment for surgical implementation, atomic energy control instruments, airplane or spaceship instruments, the control or operation of dynamic, brake or safety systems designed for vehicular use, traffic signal instruments, all types of safety devices, and other applications intended to support or sustain life.

All Insecure Usage shall be made at customer's risk, and in the event that third parties lay claims to Nuvoton as a result of customer's Insecure Usage, customer shall indemnify the damages and liabilities thus incurred by Nuvoton.

Please note that all data and specifications are subject to change without notice.

All the trademarks of products and companies mentioned in this datasheet belong to their respective owners.