

# **NUC029xDE Board Supporting Package Directory Introduction**

Rev.3.00.001

## Directory Information

<b>Document</b>	Driver reference manual and revision history.
<b>Library</b>	Driver header and source files.
<b>SampleCode</b>	Driver sample code.

## Document Information

BSP Revision History	Show all the revision history about specific BSP.
Driver Reference Guide	Describe the definition, input and output of each API.

## Library Information

CMSIS	CMSIS definitions by ARM® Corp.
Device	CMSIS compliant device header file.
StdDriver	All peripheral driver header and source files.

## Sample Code Information

\SampleCode\Template	Software Development Template.
\SampleCode\Semihost	Show how to debug with semi-host message print.
\SampleCode\RegBased	The sample code able to access control registers directly.
\SampleCode\StdDriver	Driver Samples

## \SampleCode\RegBased

<b>ADC_ContinuousScanMode</b>	Perform A/D Conversion with ADC continuous scan mode.
<b>ADC_MeasureAVDD</b>	Measure AVDD voltage by ADC.
<b>ADC_PwmTrigger</b>	Demonstrate how to trigger ADC by PWM.
<b>ADC_ResultMonitor</b>	Monitor the conversion result of channel 2 by the digital compare function.
<b>ADC_SingleCycleScanMode</b>	Perform A/D Conversion with ADC single cycle scan mode.
<b>ADC_SingleMode</b>	Perform A/D Conversion with ADC single mode.
<b>BPWM_Capture</b>	Capture the BPWM1 Channel 0 waveform by BPWM0 Channel 0.
<b>BPWM_DoubleBuffer</b>	Change duty cycle and period of output waveform by BPWM Double Buffer function.
<b>FMC_IAP</b>	Show how to call LDROM functions from APROM. The code in APROM will look up the table at 0x100E00 to get the address of function of LDROM and call the function.
<b>FMC_MultiBoot</b>	Implement a multi-boot system to boot from different applications in APROM. A LDROM code and 4 APROM code are implemented in this sample code.
<b>FMC_RW</b>	Show how to read/program embedded flash by ISP function.
<b>GPIO_EINTAndDebounce</b>	Show the usage of GPIO external interrupt function and debounce function.
<b>GPIO_INT</b>	Show the usage of GPIO interrupt function.
<b>GPIO_OutputInput</b>	Show how to set GPIO pin mode and use pin data input/output control.
<b>GPIO_PowerDown</b>	Show how to wake up system from Power-down mode by GPIO interrupt.

<b>I2C_EEPROM</b>	Show how to use I <sup>2</sup> C interface to access EEPROM.
<b>I2C_GCMode_Master</b>	Show how a Master uses I <sup>2</sup> C address 0x0 to write data to Slave. This sample code needs to work with I2C_GCMode_Slave.
<b>I2C_GCMode_Slave</b>	Show a Slave how to receive data from Master in GC (General Call) mode. This sample code needs to work with I2C_GCMode_Master.
<b>I2C_Master</b>	Show a Master how to access Slave. This sample code needs to work with I2C_Slave.
<b>I2C_Slave</b>	Show how to set I <sup>2</sup> C in Slave mode and receive the data from Master. This sample code needs to work with I2C_Master.
<b>I2C_Wakeup_Master</b>	Show how to wake up MCU from Power-down. This sample code needs to work with I2C_Wakeup_Slave.
<b>I2C_Wakeup_Slave</b>	Show how to wake up MCU from Power-down mode through I <sup>2</sup> C interface. This sample code needs to work with I2C_Wakeup_Master.
<b>PWM_Capture</b>	Capture the PWM1 Channel 0 waveform by PWM0 Channel 0.
<b>PWM_DeadZone</b>	Demonstrate how to use PWM Dead Zone function.
<b>PWM_DoubleBuffer</b>	Change duty cycle and period of output waveform by PWM Double Buffer function.
<b>SPI_Loopback</b>	Implement SPI Master loop back transfer. This sample code needs to connect SPI0_MISO0 pin and SPI0_MOSI0 pin together. It will compare the received data with transmitted data.
<b>SPI_MasterFifoMode</b>	Configure SPI0 as Master mode and demonstrate how to communicate with an off-chip SPI Slave device. This sample code needs to work with SPI_SlaveFifoMode sample code.
<b>SPI_SlaveFifoMode</b>	Configure SPI0 as Slave mode and demonstrate how to

	communicate with an off-chip SPI Master device. This sample code needs to work with SPI_MasterFifoMode sample code.
<b>SYS_PLLClockOutput</b>	Change system clock to different PLL frequency and output system clock from CLKO pin.
<b>TIMER_Capture</b>	Show how to use the timer0 capture function to capture timer0 counter value
<b>TIMER_Counter</b>	Implement timer0 event counter function to count the external input event.
<b>TIMER_PeriodicINT</b>	Implement timer counting in periodic mode.
<b>TIMER_PowerDown</b>	Use timer0 periodic time-out interrupt event to wake up system.
<b>UART_Autoflow_Master</b>	Transmit and receive data with auto flow control. This sample code needs to work with UART_Autoflow_Slave.
<b>UART_Autoflow_Slave</b>	Transmit and receive data with auto flow control. This sample code needs to work with UART_Autoflow_Master.
<b>UART_IrDA_Master</b>	Transmit and receive data in UART IrDA mode. This sample code needs to work with UART_IrDA_Slave.
<b>UART_IrDA_Slave</b>	Transmit and receive data in UART IrDA mode. This sample code needs to work with UART_IrDA_Master.
<b>UART_LIN</b>	Transmit LIN header and response.
<b>UART_RS485_Master</b>	Transmit and receive data in UART RS485 mode. This sample code needs to work with UART_RS485_Slave.
<b>UART_RS485_Slave</b>	Transmit and receive data in UART RS485 mode. This sample code needs to work with UART_RS485_Master.
<b>UART_TxRx_Function</b>	Transmit and receive data from PC terminal through RS232 interface.
<b>WDT_PowerDown</b>	Use WDT time-out interrupt event to wake-up system.

<b>WDT_TimeoutINT</b>	Implement periodic WDT time-out interrupt event.
<b>WDT_TimeoutReset</b>	Show how to generate time-out reset system event while WDT time-out reset delay period expired.
<b>WWDT_CompareINT</b>	Show how to reload the WWDT counter value.

## \SampleCode\StdDriver

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<b>ADC_MeasureAVDD</b>	Measure AVDD voltage by ADC.
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<b>ADC_ResultMonitor</b>	Monitor the conversion result of channel 2 by the digital compare function.
<b>ADC_SingleCycleScanMode</b>	Perform A/D Conversion with ADC single cycle scan mode.
<b>ADC_SingleMode</b>	Perform A/D Conversion with ADC single mode.
<b>BPWM_Capture</b>	Capture the BPWM1 Channel 0 waveform by BPWM0 Channel 0.
<b>BPWM_DoubleBuffer</b>	Change duty cycle and period of output waveform by BPWM Double Buffer function.
<b>DAC_PWMTrigger</b>	Demonstrate how to trigger DAC by PWM.
<b>DAC_SoftwareTrigger</b>	Demonstrate how to trigger DAC conversion by software method.
<b>DAC_TimerTrigger</b>	Demonstrate how to trigger DAC by timer.
<b>FMC_IAP</b>	Show how to reboot to LDROM functions from APROM. This sample code set VECMAP to LDROM and reset to re-boot to LDROM.
<b>FMC_RW</b>	Show how to read/program embedded flash by ISP function.

<b>GPIO_EINTAndDebounce</b>	Show the usage of GPIO external interrupt function and debounce function.
<b>GPIO_INT</b>	Show the usage of GPIO interrupt function.
<b>GPIO_OutputInput</b>	Show how to set GPIO pin mode and use pin data input/output control.
<b>GPIO_PowerDown</b>	Show how to wake up system from Power-down mode by GPIO interrupt.
<b>I2C EEPROM</b>	Show how to use I <sup>2</sup> C interface to access EEPROM.
<b>I2C_GCMode_Master</b>	Show how a Master uses I <sup>2</sup> C address 0x0 to write data to Slave. This sample code needs to work with I2C_GCMode_Slave.
<b>I2C_GCMode_Slave</b>	Show a Slave how to receive data from Master in GC (General Call) mode. This sample code needs to work with I2C_GCMode_Master.
<b>I2C_Master</b>	Show a Master how to access Slave. This sample code needs to work with I2C_Slave.
<b>I2C_Slave</b>	Show how to set I <sup>2</sup> C in Slave mode and receive the data from Master. This sample code needs to work with I2C_Master.
<b>I2C_Wakeup_Master</b>	Show how to wake up MCU from Power-down. This sample code needs to work with I2C_Wakeup_Slave.
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<b>TIMER_Capture</b>	Show how to use the timer0 capture function to capture timer0 counter value.
<b>TIMER_Counter</b>	Implement timer0 event counter function to count the external input event
<b>TIMER_Delay</b>	Show how to use timer0 to create various delay time.
<b>TIMER_PeriodicINT</b>	Implement timer counting in periodic mode.
<b>TIMER_PowerDown</b>	Use timer0 periodic time-out interrupt event to wake up system.
<b>UART_Autoflow_Master</b>	Transmit and receive data with auto flow control. This sample code needs to work with UART_Autoflow_Slave.
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<b>WWDT_CompareINT</b>	Show how to reload the WWDT counter value.

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