

NUC123 CMSIS BSP Directory

Directory Introduction for 32-bit NuMicro™ Family

Directory Information

Driver reference manual and revision history.	
Library	Driver header and source files.
SampleCode	Driver sample code.

The information described in this document is the exclusive intellectual property of Nuvoton Technology Corporation and shall not be reproduced without permission from Nuvoton.

Nuvoton is providing this document only for reference purposes of NuMicro microcontroller based system design.

Nuvoton assumes no responsibility for errors or omissions.

All data and specifications are subject to change without notice.

For additional information or questions, please contact: Nuvoton Technology Corporation.

www.nuvoton.com



TABLE OF CONTENTS

1	DOCUMENT INFORMATION	4
2	LIBRARY INFORMATION	5
3	SAMPLE CODE INFORMATION	6
4	SAMPLECODE\ISP	7
5	SAMPLECODE\REGBASED	8
	System Manager (SYS)	8
	Flash Memory Controller (FMC)	8
	General Purpose I/O (GPIO)	8
	PDMA Controller (PDMA)	8
	Timer Controller (TIMER)	8
	Watchdog Timer (WDT)	9
	Window Watchdog Timer (WWDT)	9
	PWM Generator and Capture Timer (PWM)	9
	UART Interface Controller (UART)	10
	Serial Peripheral Interface (SPI)	10
	I ² C Serial Interface Controller (I ² C)	11
	I ² S Controller (I ² S)	12
	CRC Controller (CRC)	12
	Analog-to-Digital Converter (ADC)	12
	PS/2 Controller (PS/2)	13
_	OAMBI FOODFIOTDDDIVED	
6	SAMPLECODE\STDDRIVER	
	System Manager (SYS)	
	Flash Memory Controller (FMC)	
	General Purpose I/O (GPIO)	
	Timer Controller (TIMER)	
	Watchdog Timer (WDT)	
	Window Watchdog Timer (WWDT)	
	UART Interface Controller (UART)	15



Serial Peripheral Interface (SPI)	16
I ² C Serial Interface Controller (I ² C)	17
I ² S Controller (I ² S)	17
CRC Controller (CRC)	18
Analog-to-Digital Converter (ADC)	18
PS/2 Controller (PS/2)	18



1 Document Information

Revision History	Show all the revision history about specific BSP.
NuMicro NUC123 Driver Reference Guide.chm	The usage of drivers in NUC123 Series BSP.



2 Library Information

CMSIS	CMSIS definitions by ARM® Corp.
Device	CMSIS compliant device header file.
StdDriver	All peripheral driver header and source files.



3 Sample Code Information

Hard_Fault_Sample	Show hard fault information when hard fault happened.
ISP	Sample codes for In-System-Programming.
Template	Software Development Template.
Semihost	A sample code to show how to debug with semihost message print.
RegBased	The sample codes which access control registers directly.
StdDriver	NUC123 Series Driver Samples



4 SampleCode\ISP

ISP_DFU	In-System-Programming Sample code through USB interface and following Device Firmware Upgrade Class Specification.
ISP_HID	In-System-Programming Sample code through USB HID interface.
ISP_I2C	In-System-Programming Sample code through I2C interface.
ISP_RS485	In-System-Programming Sample code through RS485 interface.
ISP_SPI	In-System-Programming Sample code through SPI interface.
ISP_UART	In-System-Programming Sample code through UART interface.



5 SampleCode\RegBased System Manager (SYS)

SYS	Demonstrate how to change system clock to different PLL frequency and output system clock from CLKO pin.
SYS_PowerDown_MinCurre	Demonstrate how to minimize power consumption when entering power down mode

Flash Memory Controller (FMC)

FIVIC. RVV	Demonstrate how to read/program embedded flash by ISP function.
_	TUNCTION.

General Purpose I/O (GPIO)

GPIO_EINT	Demonstrate how to use GPIO external interrupt function.
GPIO_INT	Demonstrate how to use GPIO interrupt function.
GPIO_OutputInput	Demonstrate how to set GPIO pin mode and use pin data input/output control.
GPIO_PowerDown	Demonstrate how to wake-up form Power-down mode by GPIO interrupt.
GPIO_SwDebounce	Demonstrate how to imeplement software debounce with GPIO interrupt and timer.

PDMA Controller (PDMA)

PDMA	Demonstrate how to use PDMA channel 0 to transfer data from memory to memory.
------	---

Timer Controller (TIMER)

TIMER_Capture	Demonstrate how to use timer2 capture event to capture
TIMER_Capture	Demonstrate how to use timer2 capture event to capture



	timer2 counter value.	
TIMER_Counter	Demonstrate how to use timer1 counter input function to count the input event.	
TIMER_PeriodicINT	Demonstrate how to perform timer counting in periodic mode.	
TIMER_PowerDown	Demonstrate how to use timer0 toggle-output interrupt event to wake-up system.	

Watchdog Timer (WDT)

WDT_PowerDown	Demonstrate how to use WDT time-out interrupt event to wake-up system.
WDT_TimeoutINT	Select one WDT time-out interval period time to generate time-out interrupt event.
WDT_TimeoutReset	Demonstrate how to cause WDT time-out reset system event while WDT time-out reset delay period expired.

Window Watchdog Timer (WWDT)

WWWIII COMPARAINI	Select one WWDT window compare value to generate window compare match interrupt event.
-------------------	--

PWM Generator and Capture Timer (PWM)

PWM_Capture	Demonstrate how to use PWMB Channel 2 captures PWMB Channel 1 Waveform.
PWM_DeadZone	Demonstrate how to use PWM Dead Zone function.
PWM_DoubleBuffer	Use PWM Double Buffer function to change duty cycle and period of output waveform.



UART Interface Controller (UART)

UART_Autoflow_Master	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART Autoflow Slave .
UART_Autoflow_Slave	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART Autoflow Master .
UART_IrDA_Master	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART IrDA Slave.
UART_IrDA_Slave	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART IrDA Master.
UART_PDMA	Transmit and receive UART data with PDMA.
UART_RS485_Master	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART_RS485_Slave.
UART_RS485_Slave	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART RS485 Master.
UART_TxRx_Function	Demonstrate how UART transmit and receive data from PC terminal through RS232 interface.
UART_Wakeup	Show how to wake up system form Power-down mode by UART interrupt.

Serial Peripheral Interface (SPI)

SPI_Loopback	Implement SPI Master loop back transfer. This sample code needs to connect SPI0_MISO0 pin and SPI0_MOSI0 pin together. It will compare the received data with transmitted data.
SPI_MasterFifoMode	Demonstrate how to communicate with an off-chip SPI slave device with FIFO mode. This sample code needs to



	work with SPI_SlaveFifoMode sample code.
SPI_SlaveFifoMode	Demonstrate how to communicate with an off-chip SPI master device with FIFO mode. This sample code needs to work with SPI_MasterFifoMode sample code.
SPI_MasterDualIOMode	Demonstrate how to communicate with an off-chip SPI slave device with Dual I/O mode and FIFO mode. This sample code needs to work with SPI SlaveDualIOMode sample code.
SPI_SlaveDuallOMode	Demonstrate how to communicate with an off-chip SPI master device with Dual I/O mode and FIFO mode. This sample code needs to work with SPI_MasterDualIOMode sample code.

I²C Serial Interface Controller (I²C)

I2C_EEPROM	Demonstrate how to access EEPROM through a I2C interface
I2C_GCMode_Master	Demonstrate how a Master uses I2C address 0x0 to write data to I2C Slave. This sample code needs to work with I2C_GCMode_Slave.
I2C_GCMode_Slave	Demonstrate how to receive Master data in GC (General Call) mode. This sample code needs to work with I2C_GCMode_Master .
I2C_Loopback	Demonstrate how a Master accesses a Slave.
I2C_Master	Demonstrate how a Master accesses a Slave. This sample code needs to work with L2C_Slave .
I2C_Slave	Demonstrate how to set I2C in slave mode to receive data from a Master. This sample code needs to work with I2C Master .
I2C_Wakeup_Master	Demonstrate how to wake-up MCU from power-down. Needs to work with L2C Wakeup Slave sample code.



I2C_Wakeup_Slave	Demonstrate how to set I ² C to wake-up MCU from power-down mode. Needs to work with I2C Wakeup Master sample code.
	•

I²S Controller (I²S)

I2S_Master	Demonstrate how I ² S works in master mode. This sample code needs to work with <u>I2S_Slave</u> sample code.
I2S_Slave	Demonstrate how I ² S works in slave mode. This sample code needs to work with <u>I2S Master</u> sample code.

CRC Controller (CRC)

CRC_CCITT	Implement CRC in CRC-CCITT mode and get CRC checksum results.
CRC_8	Implement CRC in CRC-8 mode and get CRC checksum results.

Analog-to-Digital Converter (ADC)

ADC_ContinuousScanMode	Demonstrate how to use continuous scan mode and finishes two cycles of conversion for the specified channels.
ADC_PwmTrigger	Demonstrate how to trigger ADC by PWM.
ADC_MeasureAVDD	Demonstrate how to measure AVDD voltage by ADC.
ADC_ResultMonitor	Demonstrate how to use the digital compare function to monitor the conversion result of channel 2.
ADC_SingleCycleScanMode	Demonstrate how to use single cycle scan mode and finishes one cycle of conversion for



	the specified channels.
ATTI SINGIPINAGE	Demonstrate how to use single mode and finishes the conversion of the specified channel.

PS/2 Controller (PS/2)

PS2 Demonstrate how to contro screen.	I PS/2 mouse movement on the
---------------------------------------	------------------------------



6 SampleCode\StdDriver

System Manager (SYS)

SYS	Demonstrate how to change system clock to different PLL frequency and output system clock from CLKO pin.
SYS_PowerDown_MinCurrent	Demonstrate how to minimize power consumption when entering power down mode

Flash Memory Controller (FMC)

FMC_RW ISP function.	FMC_RW	Demonstrate how to read/program embedded flash by ISP function.
----------------------	--------	---

General Purpose I/O (GPIO)

GPIO_EINT	Demonstrate how to use GPIO external interrupt function.
GPIO_INT	Demonstrate how to use GPIO interrupt function.
GPIO_OutputInput	Demonstrate how to set GPIO pin mode and use pin data input/output control.
GPIO_PowerDown	Demonstrate how to wake-up form Power-down mode by GPIO interrupt.
GPIO_SwDebounce	Demonstrate how to imeplement software debounce with GPIO interrupt and timer.

Timer Controller (TIMER)

TIMER_Capture	Demonstrate how to use timer2 capture event to capture timer2 counter value.
TIMER_Counter	Demonstrate how to use timer1 counter input function to count the input event.



TIMER_PeriodicINT	Demonstrate how to perform timer counting in periodic mode.
TIMER_PowerDown	Demonstrate how to use timer0 toggle-output interrupt event to wake-up system.

Watchdog Timer (WDT)

WDT_PowerDown	Demonstrate how to use WDT time-out interrupt event to wake-up system.
WDT_TimeoutINT	Select one WDT time-out interval period time to generate time-out interrupt event.
WDT_TimeoutReset	Demonstrate how to cause WDT time-out reset system event while WDT time-out reset delay period expired.

Window Watchdog Timer (WWDT)

WWDT_CompareINT Select one WWDT window compare value to generate window compare match interrupt event.	
--	--

UART Interface Controller (UART)

UART_Autoflow_Master	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Slave .
UART_Autoflow_Slave	Demonstrate how to transmit and receive data with auto flow control. The sample code needs to work with UART_Autoflow_Master .
UART_IrDA_Master	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with <u>UART IrDA Slave</u> .
UART_IrDA_Slave	Demonstrate how to transmit and receive data in UART IrDA mode. The sample code needs to work with UART IrDA Master.



UART_PDMA	Transmit and receive UART data with PDMA.
UART_RS485_Master	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with <u>UART RS485 Slave</u> .
UART_RS485_Slave	Demonstrate how to transmit and receive data in UART RS485 mode. The sample code needs to work with UART RS485 Master.
UART_TxRx_Function	Demonstrate how UART transmit and receive data from PC terminal through RS232 interface.
UART_Wakeup	Show how to wake up system form Power-down mode by UART interrupt.

Serial Peripheral Interface (SPI)

SPI_Loopback	Implement SPI Master loop back transfer. This sample code needs to connect SPI0_MISO0 pin and SPI0_MOSI0 pin together. It will compare the received data with transmitted data.
SPI_MasterFIFOMode	Configure SPI0 as Master mode and demonstrate how to communicate with an off-chip SPI Slave device with FIFO mode. This sample code needs to work with SPI SlaveFifoMode sample code.
SPI_SlaveFIFOMode	Configure SPI0 as Slave mode and demonstrate how to communicate with an off-chip SPI Master device with FIFO mode. This sample code needs to work with SPI_MasterFifoMode sample code.
SPI_MasterDualIOMode	Demonstrate how to communicate with an off-chip SPI slave device with Dual I/O mode and FIFO mode. This sample code needs to work with SPI SlaveDuallOMode sample code.
SPI_SlaveDuallOMode	Demonstrate how to communicate with an off-chip SPI master device with Dual I/O mode and FIFO mode. This sample code needs to work with SPI_MasterDualIOMode sample code.



I²C Serial Interface Controller (I²C)

I2C_EEPROM	Demonstrate how to access EEPROM by I ² C interface.
I2C_GCMode_Master	Demonstrate how a Master uses I ² C address 0x0 to write data to I ² C Slave. Needs to work with I2C GCMode SLAVE sample code.
I2C_GCMode_Slave	Demonstrate how to receive Master data in GC (General Call) mode. Needs to work with l2C_GCMode_MASTER sample code.
I2C_Loopback	Demonstrate how to set I2C Master and Slave mode, and show how a Master access Slave.
I2C_Master	Demonstrate how a Master access Slave. Needs to work with I2C SLAVE sample code.
I2C_Slave	Demonstrate how to set I ² C in slave mode to receive the data of a Master. Needs to work with I2C MASTER sample code.
I2C_MultiBytes_Master	Demonstrate how a Master access Slave use multi bytes write and multi-bytes read. Needs to work with I2C_SLAVE sample code.
I2C_SingleByte_Master	Demonstrate how a Master access Slave use single byte write and single byte read. Needs to work with I2C SLAVE sample code.
I2C_Wakeup_Master	Demonstrate how to wake-up MCU from power-down. Needs to work with l2C_Wakeup_Slave sample code.
I2C_Wakeup_Slave	Demonstrate how to set I ² C to wake-up MCU from power-down mode. Needs to work with I2C Wakeup Master sample code.

I²S Controller (I²S)



I2S_Slave	Demonstrate how I ² S works in slave mode. This sample code needs to work with I2S Master sample code.
	oumple odde.

CRC Controller (CRC)

CRC_CCITT	Implement CRC in CRC-CCITT mode and get CRC checksum results.
CRC_8	Implement CRC in CRC-8 mode and get CRC checksum results.

Analog-to-Digital Converter (ADC)

ADC_ContinuousScanMode	Demonstrate how to use continuous scan mode and finishes two cycles of conversion for the specified channels.
ADC_PwmTrigger	Demonstrate how to trigger ADC by PWM.
ADC_MeasureAVDD	Demonstrate how to measure AVDD voltage by ADC.
ADC_ResultMonitor	Demonstrate how to use the digital compare function to monitor the conversion result of channel 2.
ADC_SingleCycleScanMode	Demonstrate how to use single cycle scan mode and finishes one cycle of conversion for the specified channels.
ADC_SingleMode	Demonstrate how to use single mode and finishes the conversion of the specified channel.

PS/2 Controller (PS/2)

PS2	Demonstrate how to control PS/2 mouse movement on the screen.
-----	---



Important Notice

Nuvoton Products are neither intended nor warranted for usage in systems or equipment, any malfunction or failure of which may cause loss of human life, bodily injury or severe property damage. Such applications are deemed, "Insecure Usage".

Insecure usage includes, but is not limited to: equipment for surgical implementation, atomic energy control instruments, airplane or spaceship instruments, the control or operation of dynamic, brake or safety systems designed for vehicular use, traffic signal instruments, all types of safety devices, and other applications intended to support or sustain life.

All Insecure Usage shall be made at customer's risk, and in the event that third parties lay claims to Nuvoton as a result of customer's Insecure Usage, customer shall indemnify the damages and liabilities thus incurred by Nuvoton.

Please note that all data and specifications are subject to change without notice.

All the trademarks of products and companies mentioned in this datasheet belong to their respective owners