**Nano103 CMSIS BSP Directory**

Directory Introduction for 32-bit NuMicro™ Family

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| **Directory Information** | |
| **Document** | Driver reference manual and revision history. |
| **Library** | Driver header and source files. |
| **SampleCode** | Driver sample code. |

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# Document Information

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| **NuMicro Nano103 CMSIS BSP Revision History.pdf** | This document shows the revision history of Nano103 BSP. |
| **NuMicro Nano103 Driver Reference Guide.chm** | This document describes the usage of drivers in Nano103 BSP. |

# Library Information

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| **CMSIS** | Cortex® Microcontroller Software Interface Standard (CMSIS) V3.01 definitions by ARM® Corp. |
| **Device** | CMSIS compliant device header file. |
| **SmartcardLib** | Library for accessing a smartcard. |
| **StdDriver** | All peripheral driver header and source files. |

# Sample Code Information

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| **Hard\_Fault\_Sample** | Show hard fault information when hard fault happened. |
| **NuTiny-EVB-NANO103** | Sample code for Nano103 Tiny Board |
| **PowerDown\_Chk** | Sample code which implements a function to test system state before entering power-down mode. If a system consumes more power than expected in power-down mode, this function can be used to check if there is any system setting that may cause power leakage. |
| **Semihost** | Show how to print and get character with IDE console window. |
| **StdDriver** | Demonstrate the usage of Nano103 MCU peripheral driver APIs. |
| **Template** | A project template for Nano103 MCU. |

# \SampleCode\NuTiny-EVB-NANO103

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| **LED** | Toggle PB.14 to turn on / off the board LED. |
| **RTC\_PowerDown** | Demonstrate how to wake up system periodically with RTC interrupt. |
| **SYS\_OperatingCurrent\_HIRC** | Demonstrate how to minimize operating current while HCLK is from HIRC. |
| **SYS\_OperatingCurrent\_MIRC** | Demonstrate how to minimize operating current while HCLK is from MIRC. |

# \SampleCode\StdDriver

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| **ACMP** | Demonstrate Analog comparator (ACMP) comparison by  comparing CMP0\_P with Band-gap voltage and  shows the result on UART console. |
| **ADC\_Compare** | Demonstrate ADC conversion and comparison function by monitoring the conversion result of channel 0. |
| **ADC\_ContinuousScan** | Convert ADC channel 0, 1, 2 in Continuous Scan mode and print conversion results. |
| **ADC\_PDMA** | Use PDMA channel 1 to move ADC channel 0, 1, 2 converted data to SRAM |
| **ADC\_PWMTrigger** | Configure PWM0 channel 0 to trigger ADC. |
| **ADC\_Single** | Convert ADC channel 0 in Single mode and print conversion results. |
| **ADC\_Single\_BandGap** | Convert the band-gap voltage using an internal ADC channel. |
| **ADC\_Single\_TempSensor** | Convert temperature sensor voltage using an internal ADC channel. |
| **ADC\_Single\_VBat** | Convert the VBAT voltage using an internal ADC channel. |
| **ADC\_SingleCycleScan** | Convert ADC channel 0, 1, 2 in Single Cycle Scan mode and print conversion results. |
| **ADC\_TimerTrigger** | Configure Timer0 to trigger ADC and move converted data to SRAM using PDMA. |
| **CRC\_CCITT** | Calculate the CRC-CCITT checksum value by CRC DMA mode. |
| **FMC\_CRC32** | Show FMC CRC32 calculating capability. |
| **FMC\_IAP** | Demonstrate IAP (In-Application Programming) function. To run this sample, the boot mode must be “Boot from APROM with IAP”. |
| **FMC\_ReadAllOne** | Show FMC flash Read-All-One function. |
| **FMC\_RW** | Show FMC read Flash IDs, erase, read, and write function. |
| **FMC\_SecurityKey** | Show FMC security key function. |
| **GPIO\_IOTest** | Use GPIO driver to control the GPIO pin direction and the high/low state, and show how to use GPIO interrupts. |
| **GPIO\_PowerDown** | Demonstrate how to wake up system form Power-down mode by GPIO interrupt. |
| **I2C\_EEPROM** | Read/write EEPROM via an I²C interface. |
| **I2C\_Loopback** | An I²C master/slave demo by connecting I²C0 and I²C1 interface. |
| **I2C\_Wakeup** | Demonstrate how to wake up system form Power-down mode by I²C interrupt. |
| **PDMA\_Memory** | Use PDMA channel 2 to demonstrate memory to memory transfer. |
| **PWM\_Capture** | Demonstrate PWM Capture function by using PWM0 channel 2 to capture the output of PWM0 channel 0. |
| **PWM\_CapturePDMA** | Demonstrate PWM Capture function by using PWM0 channel 2 to capture the output of PWM0 channel 0 and move captured data to SRAM with PDMA. |
| **PWM\_DeadZone** | Demonstrate the dead-zone feature with PWM0. |
| **RTC\_Alarm\_Test** | Demonstrate the RTC alarm function which sets an alarm 10 seconds after execution. |
| **RTC\_Snoop\_Detection** | Show how to use RTC snoop detect function. |
| **RTC\_Time\_Display** | Demonstrate the RTC function and display the current time to the UART console. |
| **SC\_ReadATR** | Read the smartcard ATR from smartcard 0 interface. |
| **SC\_ReadSimPhoneBook** | Demonstrate how to read phone book information in the SIM card. |
| **SCUART\_TxRx** | Demonstrate smartcard UART mode by connecting PC.4 and PC.6 pins. |
| **SPI\_FIFO\_Flash** | Access SPI Flash using FIFO mode. |
| **SPI\_LoopBack** | Demonstrate SPI loop back transfer |
| **SPI\_TxRxLoopback\_PDMA** | Demonstrate SPI loop back transfer with PDMA. |
| **SYS\_CLKO** | Demonstrate how to output different clocks one after another to the same CLKO (PB.2) pin. |
| **SYS\_Control** | Demonstrate how to change different PLL settings for the system clock source, and output system clock to CLKO (PB.2) pin with the system clock / 4 frequency. |
| **SYS\_ScalableLDO** | Demonstrate maximum system operating frequency with different LDO settings. |
| **SYS\_PLLClockOutput** | Change system clock to different PLL frequency and output system clock from CLKO pin. |
| **SYS\_TrimIRC** | Demonstrate how to use LXT to trim HIRC. |
| **Timer\_Delay** | Demonstrate the usage of TIMER\_Delay() API to generate a 1 second delay. |
| **Timer\_EventCounter** | Use the pin PB.8 to demonstrate timer event counter function. |
| **Timer\_FreeCountingMode** | Use the timer pin PD.11 to demonstrate timer free counting mode function. Also display the measured input frequency to UART console. |
| **Timer\_InterTimerTriggerMode** | Use the timer pin PB.8 to demonstrate inter timer trigger mode function. Also display the measured input frequency to UART console. |
| **Timer\_Periodic** | Use the timer periodic mode to generate timer interrupt every 1 second. |
| **Timer\_ToggleOut** | Demonstrate the timer 0 toggle out function on pin PB.8. |
| **Timer\_TriggerCountingMode** | Use the timer pin PD.11 to demonstrate timer trigger counting mode function. And displays the measured input frequency to UART console. |
| **Timer\_Wakeup** | Use timer to wake up system from Power-down mode periodically. |
| **UART\_AutoBaudRate** | Demonstrate how to use auto baud rate detection function. |
| **UART\_FlowCtrl** | Transmit and receive data using auto flow control. |
| **UART\_IrDA** | Show how to transmit and receive UART data in UART IrDA mode. |
| **UART\_LIN** | Demonstrate how to transmit LIN header and response. |
| **UART\_PDMA** | Demonstrate UART transmit and receive function with PDMA. |
| **UART\_RS485\_Receive** | Demonstrate how to receive data in UART RS485 mode. |
| **UART\_RS485\_Transmit** | Demonstrate how to transmit data in UART RS485 mode. |
| **UART\_Rx\_Wakeup** | Demonstrate how to wake up system form Power-down mode by UART interrupt. |
| **UART\_TxRx\_Function** | Transmit and receive data from PC terminal through RS232 interface. |
| **WDT\_Polling** | Use Polling mode to check WDT time-out state and reset WDT after time-out occurs. |
| **WDT\_Wakeup** | Use WDT to wake up system from Power-down mode periodically. |
| **WWDT\_Reload** | Demonstrate the WWDT counter reload function. |

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