

Check installation

Nobuhiko Miyamoto

National Institute of Advanced Industrial Science
and Technology

Industrial Cyber-Physical Systems Research Center



Check installation(Windows)

- OpenRTM-aist
 - OpenRTM-aist-1.2.2-RELEASE_x86_64.msi
- Python
 - python-3.7.5-amd64.msi
- CMake
 - cmake-3.15.4-win64-x64.msi
- Doxygen
 - doxygen-1.8.14-setup.exe
- Visual Studio
 - Visual Studio 2019

Check installation(Ubuntu)

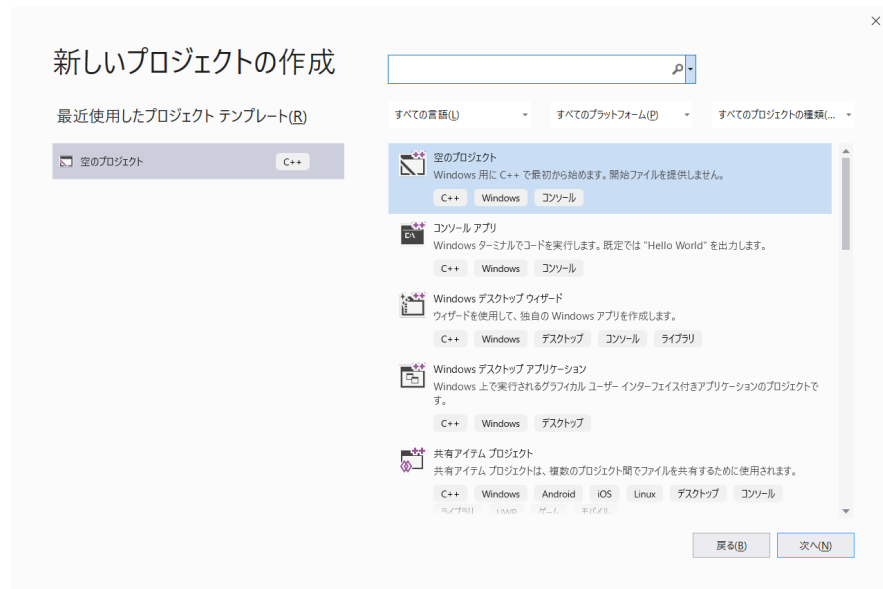
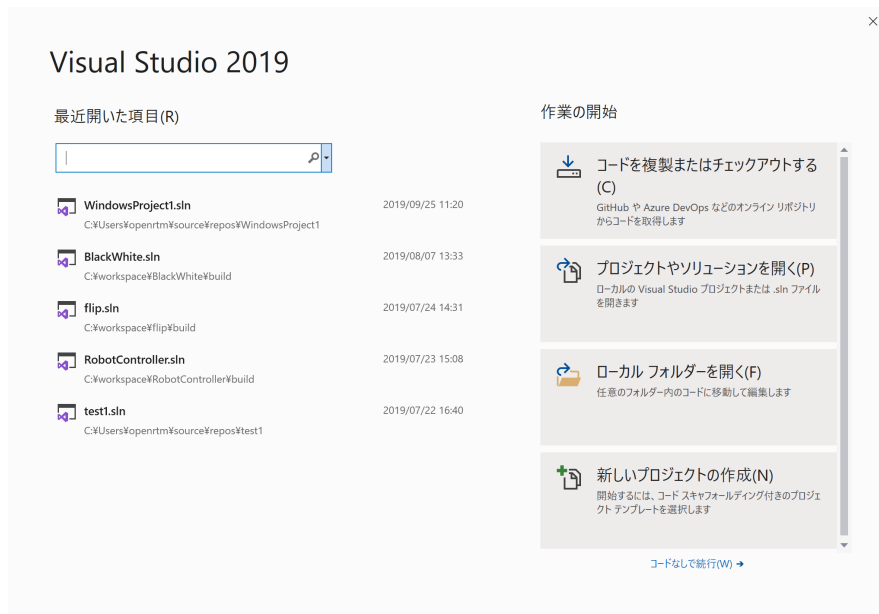
- OpenRTM-aist
 - \$ wget https://raw.githubusercontent.com/OpenRTM/OpenRTM-aist/master/scripts/pkg_install_ubuntu.sh
 - \$ sudo sh pkg_install_ubuntu.sh -l all --yes
- CMake
 - \$ sudo apt-get install cmake cmake-gui
- Doxygen
 - \$ sudo apt-get install doxygen
- Java
 - \$ sudo apt-get install openjdk-8-jdk
- Code::Blocks
 - \$ sudo apt-get install codeblocks
- RaspberryPiMouseSimulatorComp
 - sudo apt install git premake4 freeglut3-dev
 - \$ wget https://raw.githubusercontent.com/OpenRTM/RTM_Tutorial/master/script/install_raspimouse_simulator.sh
 - sh install_raspimouse_simulator.sh

Download materials

- Download and unzip RTM_Tutorial.zip
 - https://github.com/OpenRTM/RTM_Tutorial/releases/download/20220930/RTM_Tutorial.zip
- Contents of the extracted RTM_Tutorial.zip
 - ppt
 - Part 2 slides
 - RTMTutorial_2_online.pdf
 - WEBpage
 - Part 2(Windows)
 - Part 2(Ubuntu)
 - script
 - Simulator installation script(Ubuntu)
 - EXE
 - RaspberryPiMouseSimulatorComp.exe(Simulator)
 - sample
 - RobotController(Sample code)

If you have not installed or downloaded the materials

- Please install software during breaks.
 - <https://openrtm.org/openrtm/ja/node/7041#toc7>
 - https://github.com/OpenRTM/RTM_Tutorial/releases/download/20220930/RTM_Tutorial.zip
 - Make sure you have Visual C ++ installed.



If you have any questions

- Ask a question in Zoom's chat.

Display the Zoom Group Chat screen



Please set the destination to everyone.



- If the problem is not solved by chat, we will provide individual support.