



Core Flight System Overview

OSK v3.1



Introduction



Objectives

Introduce flight software (FSW) concepts and core Flight System (cFS) architectural features

Intended audience

 Spacecraft technical managers, systems engineers, discipline engineers, and software engineers

Perquisites

- An interest in learning about FSW and the cFS
- No programming skills required

Slide outline

- 1. Introduction to flight software
- 2. cFS business context
- 3. cFS architecture overview
- 4. FSW engineering with the cFS

cFS Overview





Introduction to Flight Software

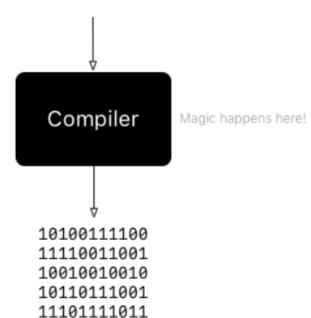


What is Software?



- Microcode are instructions and data processed by a microprocessor
- Programming languages are formal languages (i.e. grammatical rules) that are translated into microcode by a compiler

```
func greet() = {
    Console.println("Hello, World!")
}
```



 Interpreted languages such as Python, Ruby, and JavaScript run on a virtual machines (VMs) and the VM is ported to different processors



What is an Embedded Computer?



- An Embedded Computer is a computer that is integrated in a product
- Embedded Computers do not usually have a keyboard, mouse, or monitor interface



Embedded Software is software that that runs on an Embedded Computer in order to make a device or product work

"Embedded software is the opposing thumb of hardware"



Embedded Software Characteristics



Microcontroller

- Typically, limited resources: low power, small memory, and slower clock speeds
- Typically, no operating system
- For example, the processor embedded with reaction wheel assembly

Embedded Operating System

- Real-time preemptive multi-tasking
- Typically, much smaller than Windows or OS X
- Examples include VxWorks, RTEMS, and FreeRTOS

Embedded System

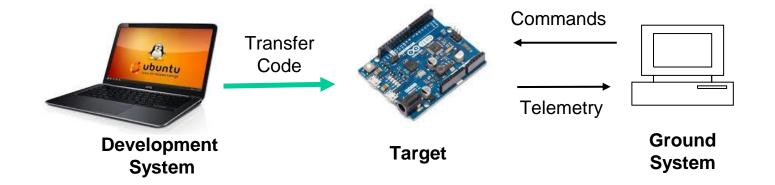
The combination of an Embedded Computer and Embedded Software



How do we Develop Embedded Software?



- Use a Windows, Mac, or Linux computer to write the code
 - Programming Languages used
 - For Flight Software: C, C++, Assembly Language, sometimes Ada
 - For Ground and test software: C, C++, Python, Java, Ruby, etc.
- Write code, cross-compile for target processor, transfer object code to embedded computer, control embedded system with a ground system
- This is known as Cross Development





Spacecraft Definitions



A few terms:

- Spacecraft Bus usually refers to the fundamental systems of a spacecraft, i.e.
 - Mechanical Structure
 - Electrical System
 - Power System
 - Command and Data Handling System (C&DH)
 - Attitude Control System/ Propulsion System
 - RF System
 - Thermal System
- Payloads refers to the instruments on board, i.e.
 - Cameras, Telescopes, Radars, etc
- Observatory Usually refers to the entire system, i.e. the combination of the Spacecraft Bus and the Payloads



FSW Challenges – Limited Resources



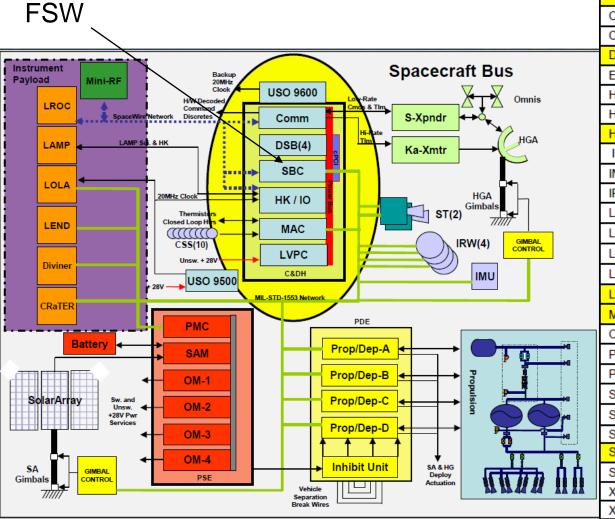
- Flight processor clock speeds are in the MHz range while our laptops are in the GHz range
 - NICER (6/12/17) 83Mhz Broad Reach 440 Power PC
- Non-volatile memory
 - GPM (2/27/14) 2MB banks of EEPROM for each FSW image
 - Compressed operating system and apps
- Flight RAM in MegaByte range while our laptops are in the GigaByte range
 - GPM (2/27/14) 36MB RAM



FSW Challenges – Large number of Custom Interfaces



More than 20 Interfaces controlled by FSW on this single string example



C&DH	Command & Data Handling	
Comm	Communication	
CRaTER	Cosmic Ray Telescope for the Effects of Radiation	
CSS	Coarse Sun Sensor	
DSB	Data Storage Board	
EVD	Engine Valve Driver	
HGA	High-Gain Antenna	
H/W	Hardware	
HK	Housekeeping	
Ю	Input/Output	
IMU	Inertial Measurement Unit	
IRW	Integrated Reaction Wheel	
LAMP	Lyman-Alpha Mapping Project	
LEND	Lunar Exploration Neutron Detector	
LOLA	Lunar Orbiter Laser Altimeter	
LROC	Lunar Reconnaissance Orbiter Camera	
LVPC	Low Voltage Power Converter	
MAC	Multi-Function Analog Card	
OM	Output Module	
PMC	Power Management Controller	
PSE	Power System Electronics	
SA	Solar Array	
SAM	Solar Array Module	
ST	Star Tracker	
SBC	Single Board Computer	
SSR	Solid State Recorder	
Xmtr	Transmitter	
Xpndr	Transponder	



FSW Challenges – Robustness & Remote Diagnostics



Curiosity Probe's Computer Reset (2/25/19)

 "Last week, its computer rebooted without warning. Now, NASA engineers are trying to figure out what caused the unprompted restart."



Israeli Lunar Lander Suffers Glitch on Way to the Moon (2/27/19)



- "During the pre-maneuver phase the spacecraft computer reset unexpectedly, causing the maneuver to be automatically cancelled,"
- "The engineering teams ... are examining the data and analyzing the situation. At this time, the spacecraft's systems are working well, except for the known problem in the star tracker."
- https://www.space.com/israel-moon-landersuffers-glitch.html



FSW Challenges – Manage & Protect Hardware



- Detect flight hardware anomalies and failures
 - Sensors, Actuators, Clocks, CPU, Memory, Power, Thermal, Communications
- Respond to onboard anomalies/failures pre-planned actions, e.g.,
 - Capture Diagnostic Data
 - Use "numerically safe" data for current control law cycle
 - Reconfigure onboard hardware and/or software minimize the problem
 - 'Safe' all Flight Hardware (Science Instruments, Spacecraft Hardware)
 - Ensure Sun is on the Solar Array Panels -- Maintain Power Positive State
 - Notify Ground of problems
- FSW can often compensate for hardware problems found during spacecraft I&T or post-launch



FSW Challenges – Serving Multiple Customers



- FSW "presents" the spacecraft to the end-user and there are multiple end users therefore a FSW expert should be involved from early formulation stages to
 - Participate in trades: ground-/flight, hardware/software, budget options, etc.
 - Champion requirements, design, and interface features with knowledge of all of the customers and spacecraft lifecycle needs

Who are FSW Customers?

- Principle Investigator
 - "I want all my data and I want it now!"
- Spacecraft Operators (work under a management plan)
 - "Make my life simple and cheap"
- Other spacecraft subsystems
 - "It would be really nice if I could see X"
- FSW Test Team
 - "I want to see all of the data all of the time"
- Spacecraft Integration and Test team
 - "I want to see or at least log all of the data all of the time"
 - "I also need to test as we will fly"
- FSW Maintenance Team
 - "Can I access/view X and change Y?"

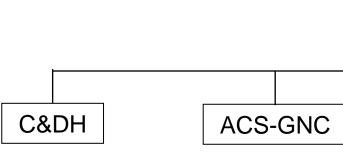
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Typical Spacecraft Flight Software Requirements

FSW





- Operational Environment
 - App Runtime Env
 - Command Ingest
 - Telemetry Output
 - Inter-processorComm
- Onboard Data Management
 - File Management
 - File Transfer
 - RecorderManagement
- Autonomy, Failure Detection & Correction
 - Stored Commanding
 - Hardware & Software Monitoring
 - Memory Integrity
 Support & Checks

- Attitude
 Determination
 and Control
- Orbit
 Determination
 and Control
- Models
 - Solar
 - Lunar
 - MagneticField

Mechanisms

- DeploymentsSolar Array Control
- Antenna Control

Thermal

- Auton Control
- Tlm & Cmd I/F
- Health & Safety

Power

- Auton Control
- Tlm & Cmd I/F
- Health& Safety

- Payload
- Auton Control
- Tlm & Cmd I/F
- Health& Safety

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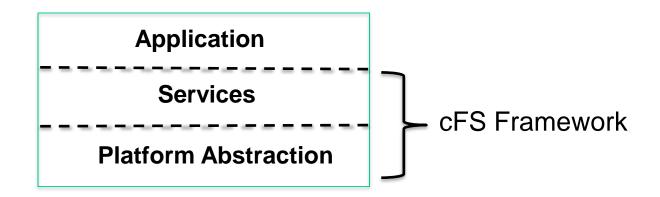
cFS Business Context



Core Flight System Overview



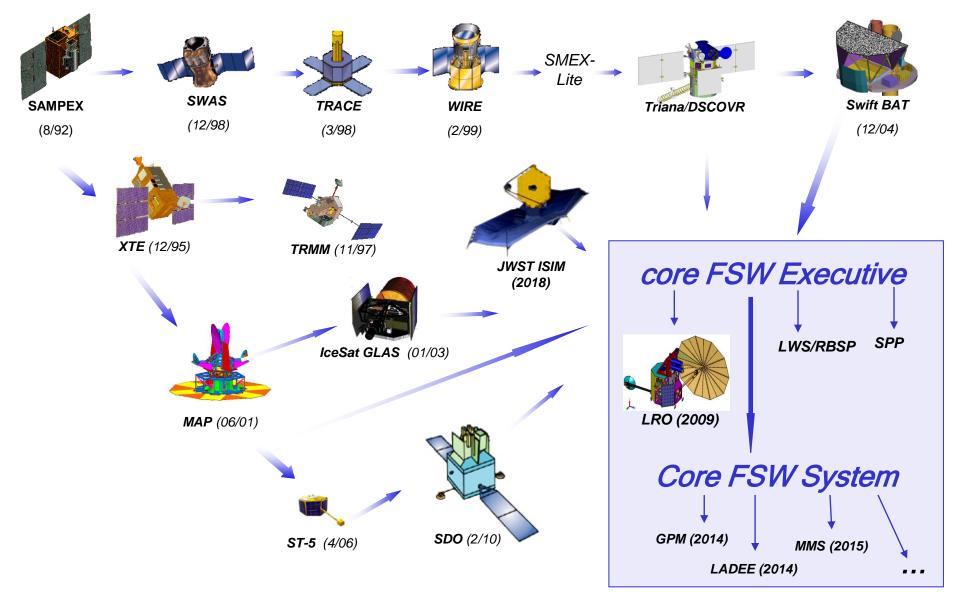
- The cFS uses a three-tiered software architecture that provides a <u>portable</u> and <u>extendable</u> framework with a <u>product</u> <u>line deployment model</u>
 - Platform Abstraction Layer supports portability
 - Applications provide mission functionality
 - Compile-time configuration parameters and run-time command/table parameters flexibility and scalability





cFS Architecture Heritage

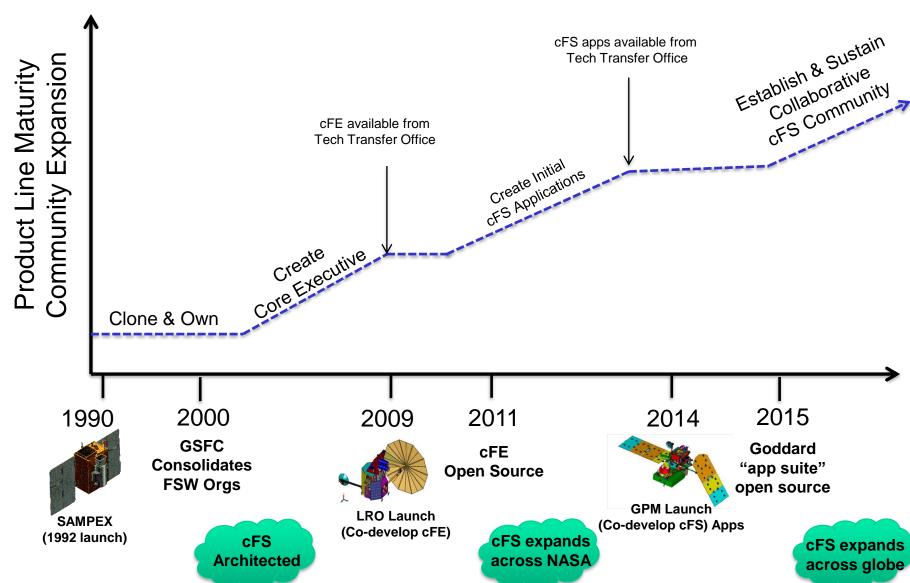






cFS History







What is the Core Flight System (cFS)?



 A NASA multi-center configuration controlled open source flight software <u>framework</u>

cFE Application Programmer Interface
Core Flight Executive Implementation
Platform Application Programmer Interface
Platform Implementation

- Layered architecture with international standards-based interfaces
- Provides development tools and runtime environment for user applications
- Reusable NASA Class A/B lifecycle artifacts: requirements, design, code, tests, and documents
- The framework is ported to a platform and augmented with applications to create Core Flight System (cFS) distributions

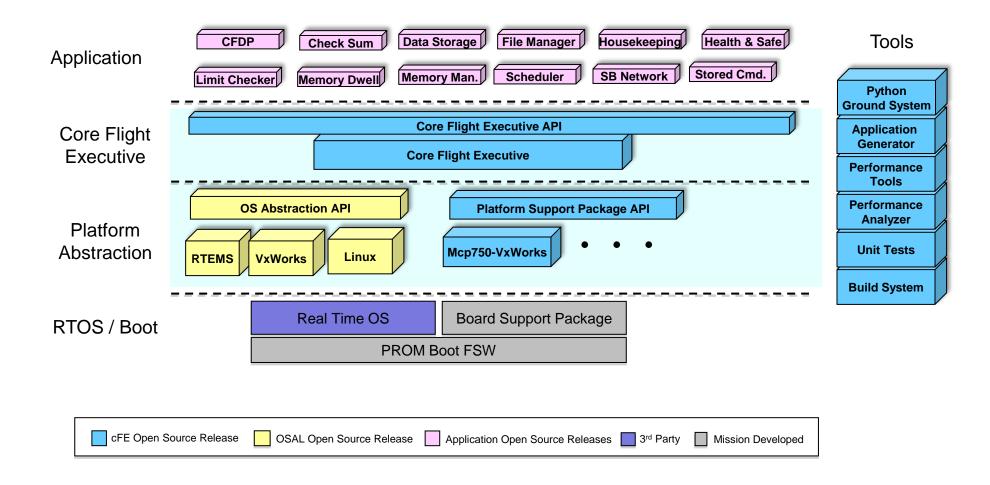


• A worldwide community from government, industry, and academia



cFS Architecture Layers

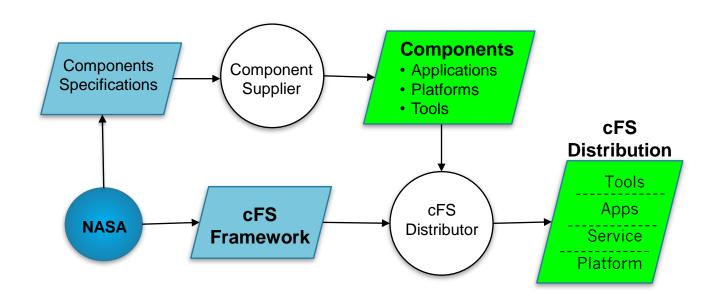






Community-based Product Model





- A NASA multi-center configuration control board (CCB) manages releases of the open source cFS Framework and component specifications
- Community members (regardless of affiliation)
 - Supply applications, platforms, and tools
 - Create cFS distributions



Community-based Product Model



Community component supplier value proposition

- As the number of supported platforms increases then apps become more valuable
- As the number of apps increases then supporting a cFS platform become more valuable
- In 2019 vendors starting to offer processor boards integrated with the cFS
 - Al Tech partnered with Embedded Flight Systems to offer the cFS integrated on the SP0-S Single Board Computer
 - Genesis Engineering developing an integrated GEN6000 (SpaceCube
 2.0) cFS product
 - Genesis pursuing a Space Act Agreement (SAA) that would include the creation of a platform certification test suite
- Community members release, maintain, and distribute (typically via git) their apps
 - No one has established an "app store"



User Responsibilities



- The cFS Framework is has a NASA NPR-7150.2C Class E classification
 - Class states Design Concept, Research,
 Technology and General-Purpose Software
 - The cFS Framework provides artifacts to support Class B missions and a subset of artifacts to support Class A missions
 - End-users are responsible for classifying the software system that uses the cFS Framework
 - This is consistent with the Apache license's "Disclaimer of Warranty" that states, "...provides the Work...on an "AS IS" BASIS, WITHOUT WARRANTIES OR CONDITIONS OF ANY KIND, either express or implied, including, without limitation, any warranties or conditions of ... FITNESS FOR A PARTICULAR PURPOSE."
- End-users are responsible for complying with International Traffic in arms Regulations (ITAR)



Obtaining cFS "Products"



cFS Bundle

- Contains the cFS Framework packaged with additional components to create a system that can easily be built, executed, and unit tested on a Linux platform
- http://github.com/nasa/cFS

User Components

Search https://github.com/nasa/ or do a general google on the cFS

Distributions

- Listed on the next slide
- Some distributions contain many of the common apps which give you a good starting point for apps

Engage with the Community

- Ask the community mailing list (See backup slides)
 - Especially useful when porting to a new platform
- Contact a cFS team member (See backup slides)



cFS Distributions



Name/Link	Intended Audience	Overview
cFS Framework-101	cFS Framework training package	This is a training tool for individuals to learn how to develop software with NASA-developed Core Flight software (CFS) framework. No agreement is necessary through this catalog. Software is available at open source site.
cFS Build	Initial cFS build for a developer or a project	This repository contains the core Flight Executive and a number of submodules including OSAL, example "lab" applications, and mission ready applications. This distribution has been compiled/linked but has not been verified as an operational system.
NASA Operational Simulator for Small Satellites (NOS3)	Initial cFS platform for a project	NOS3 provides a complete cFS system designed to support satellite flight software development throughout the project life cycle. It includes •42 Spacecraft dynamics and visualization, NASA GSFC • cFS – core Flight System, NASA GSFC • COSMOS – Ball Aerospace • ITC Common – Loggers and developer tools, NASA IV&V ITC • NOS Engine – Middleware bus simulator, NASA IV&V ITC
OpenSatKit (OSK)	cFS training platform for new cFS developers	OSK provides a complete cFS system to simplify the cFS learning curve, cFS deployment, and application development. The kit combines three open source tools to achieve these goals:
	Initial cFS platform for a project	 cFS – core Flight System, NASA GSFC COSMOS – command and control platform for embedded systems, Ball Aerospace 42 dynamic simulator, NASA GSFC



Community Operational Procedures





Version Control

- Master Branch
- Integration Candidates
- Release Candidates

User Contributions

 Community Contribution process and Contributor License Agreement (CLA)

Feature Deprecation

- Mark feature as deprecated on any release
- Provide tools/process that will warning applications when a feature is marked as deprecated
- Only deprecate on major versions



Consequences of cFS Evolution



- Some artifacts were developed for Goddard-specific environments and have not been transformed to a generalpurpose solution
 - Table Tools
 - Build test scripts
- Challenges with government run open-source programs
 - Project-centric funding
 - Cumbersome software licensing and release processes
- The product model and community infrastructure is immature
 - Lack of online component and distribution catalogs
 - cFS mailing list used as primary Q&A forum





Core Flight System Architectural Overview



cFS Overview

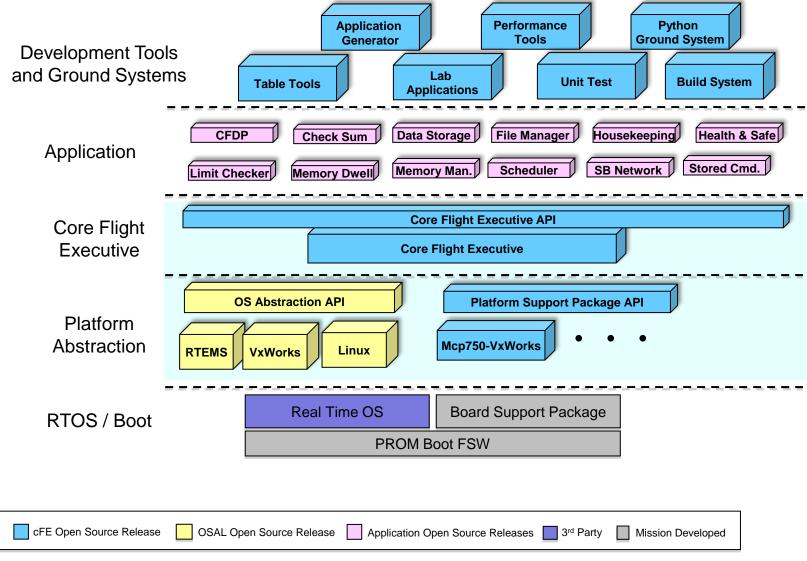


- A set of mission independent, re-usable, core flight software services, applications, and operating environment
 - Layered architecture
 - Supports a variety of hardware platforms
 - Provides standardized Application Programmer Interfaces (API)
 - Supports and hosts flight software applications
 - Applications can be added and removed at run-time (eases system integration and FSW maintenance)
 - Supports software development for on-board FSW, desktop FSW development and simulators
 - Contains platform and mission configuration parameters that are used to tailor to a specific platform and mission.



cFS Architecture Layers



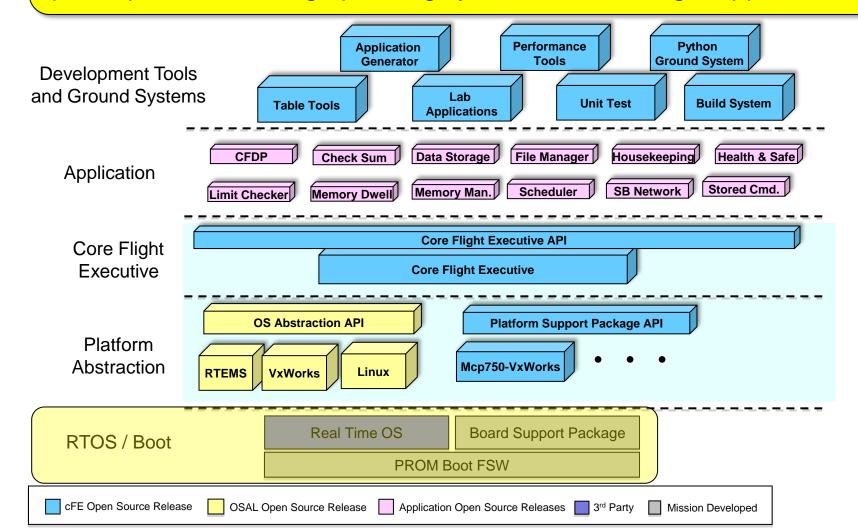




Operating System / Boot Layer



Provides the commercial, open-source, or custom software interface between the processor and the FSW. Real-time multi-tasking preemptive scheduling operating systems used for flight applications.

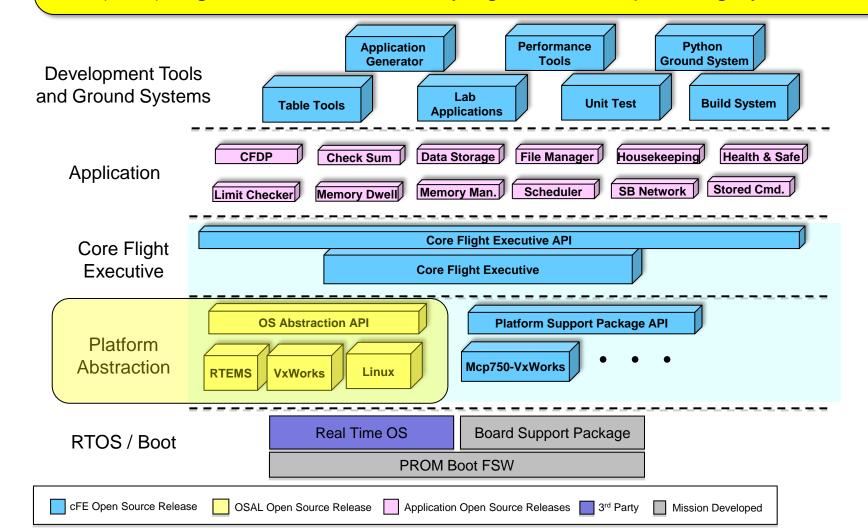




Platform Abstraction - OSAL



The OS Abstraction Layer (OSAL) is a software library that provides a single Application Program Interface (API) to the core Flight Executive (cFE) regardless of the underlying real-time operating system.

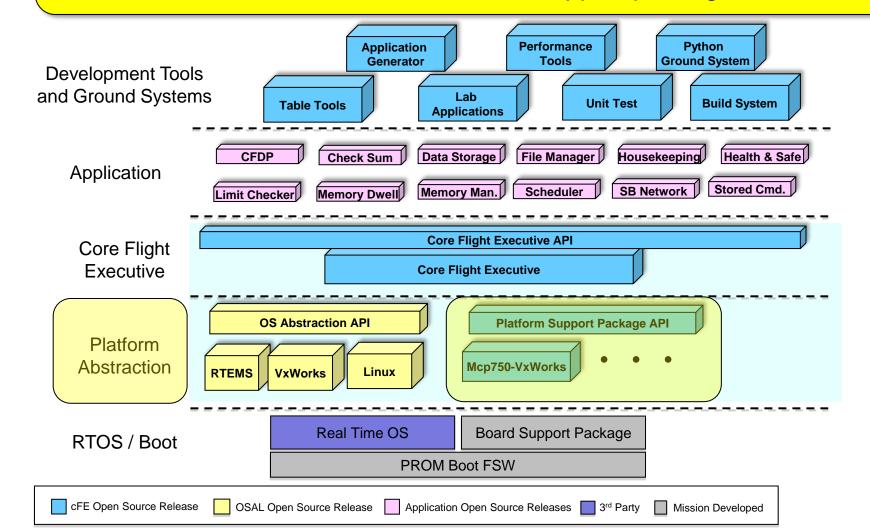




Platform Abstraction - PSP



The Platform Support Package (PSP) is a software library that provides a single Application Program Interface (API) to underlying avionics hardware and board support package.

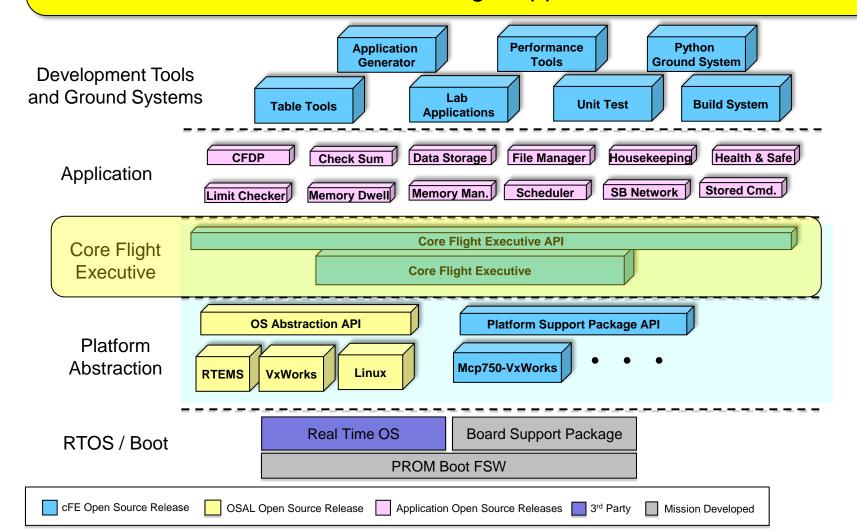




Core Flight Executive



The cFE is a portable, platform-independent framework that creates an application runtime environment by providing services that are common to most flight applications.

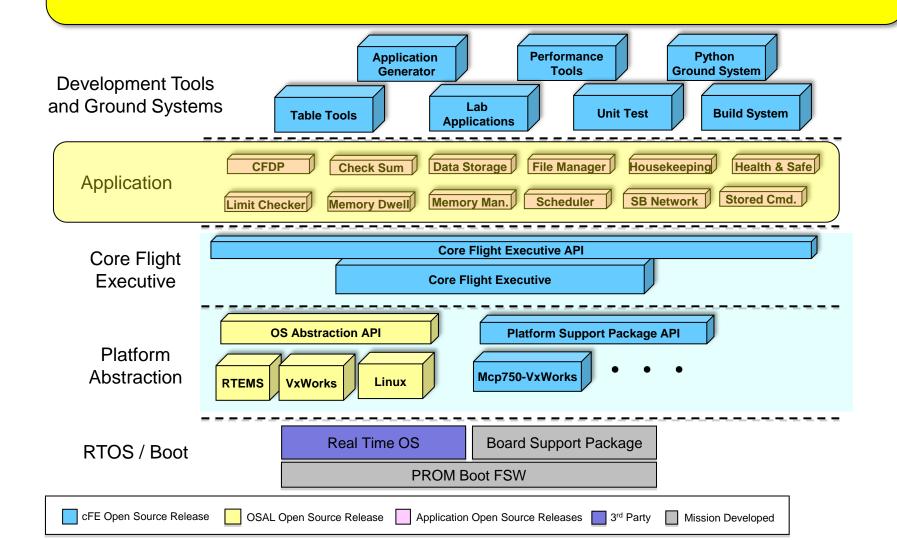




Applications



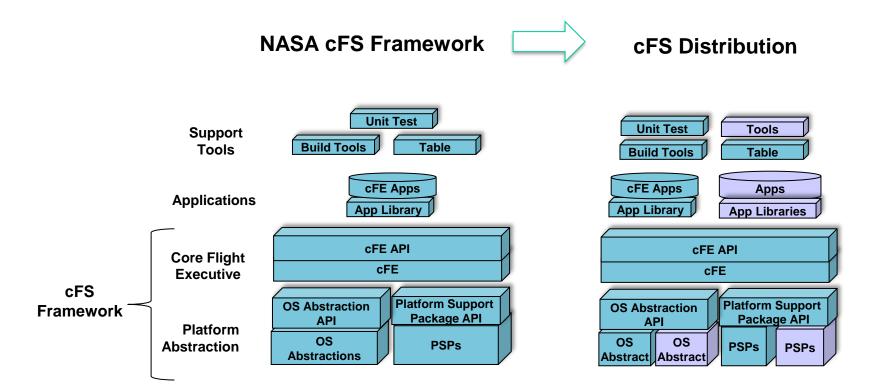
Applications provide mission functionality using a combination of cFS community apps and mission-specific apps.





cFS Product Model





- The NASA Configuration Control Board (CCB) manages the "cFS Framework"
- "cFS Distribution" created by augmenting the NASA cFS Framework with components (platforms, apps, and tools) to create an operational system



Applications



- Write once run anywhere the cFS framework has been deployed
- Framework has been ported to many popular hardware platform/operating system platforms including MUSTANG and Spacecube
- Goddard has released 15 applications that provide common command and data handling functionality such as
 - Stored command management and execution
 - Onboard data storage file management
- Reduce project cost and schedule risks
 - High quality flight heritage applications
 - Focus resources on mission-specific functionality
- Framework provides seamless application transition from technology efforts to flight projects



Initial GSFC Open Source Apps

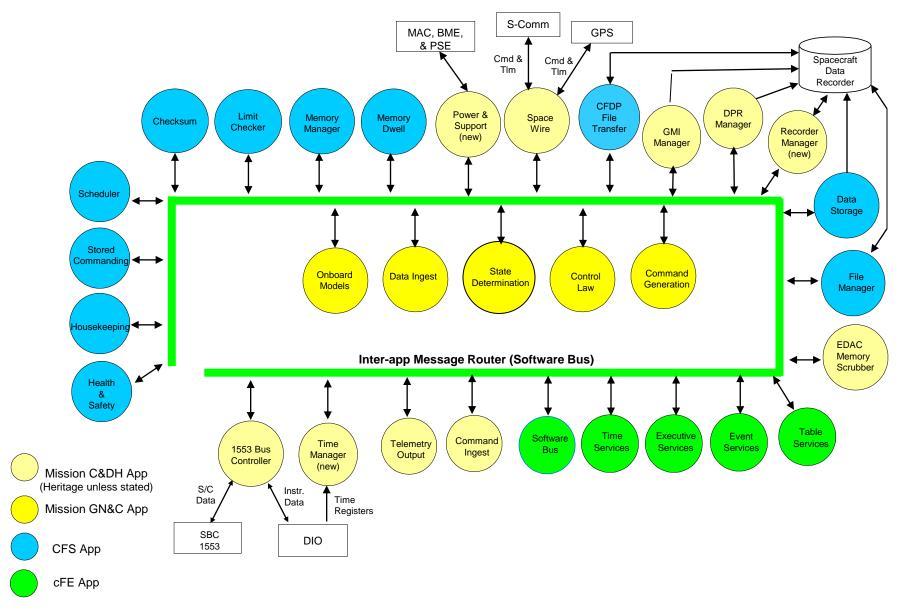


Application	Function		
CFDP	Transfers/receives file data to/from the ground		
Checksum	Performs data integrity checking of memory, tables and files		
Command Ingest Lab	Accepts CCSDS telecommand packets over a UDP/IP port		
Data Storage	Records housekeeping, engineering and science data onboard for downlink		
File Manager	Interfaces to the ground for managing files		
Housekeeping	Collects and re-packages telemetry from other applications.		
Health and Safety	Ensures that critical tasks check-in, services watchdog, detects CPU hogging, and calculates CPU utilization		
Limit Checker	Provides the capability to monitor values and take action when exceed threshold		
Memory Dwell	Allows ground to telemeter the contents of memory locations. Useful for debugging		
Memory Manager	Provides the ability to load and dump memory		
Software Bus Network	Passes Software Bus messages over various "plug-in" network protocols		
Scheduler	Schedules onboard activities via (e.g. HK requests)		
Scheduler Lab	Simple activity scheduler with a one second resolution		
Stored Command	Onboard Commands Sequencer (absolute and relative)		
Telemetry Output Lab	Sends CCSDS telemetry packets over a UDP/IP port		



Mission Application Example











The Distribution Starts with the **Platform Layer** (bottom), which is specific to a processor card and operating system. The Platform layer is everything needed to allow the cFS to run on a Cubesat/Smallsat

Mission Cubesat/Smallsat Specific Apps and Components Specific Layer Reusable Core Flight Executive and Reusable cFS Applications cFS Layer **Operating System Abstraction Layer** Platform Support Package **Platform** Real Time Operating System (Linux, Real Time OS Board Support Package Layer VxWorks, etc) Boot Software - Usually Vendor Provided (u-boot, etc)

Cubesat/SmallSat Hardware

OSK - Making Space for Apps

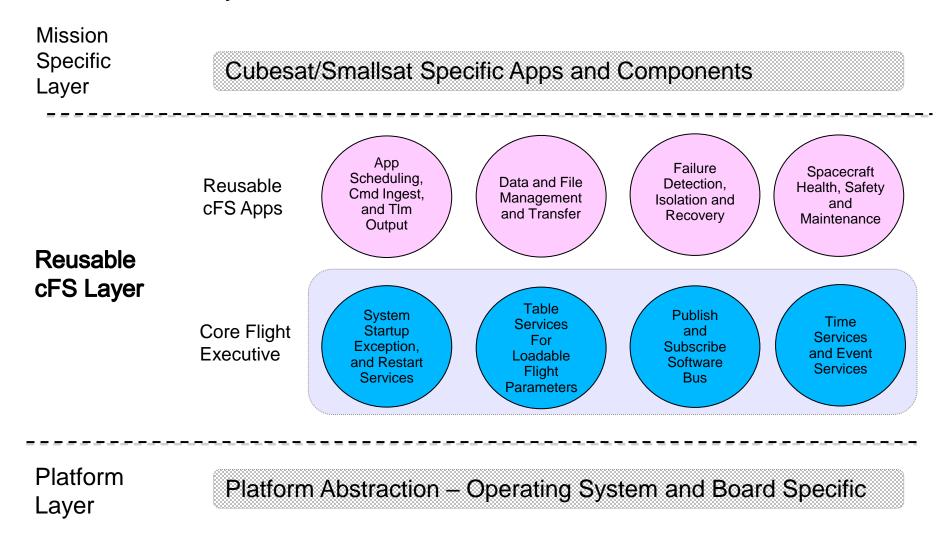
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ext format



Next, the **Reusable cFS Layer** provides the core functionality that is common to every mission



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Finally, the **Mission Specific Layer** adds support for commonly used components, and mission specific functionality

Mission Specific Layer Radio Interface Apps (L3 Cadet) (Innoflight) Attitude Control Components (Sun Sensors, Star Trackers, etc)

Spacecraft
Bus and
Power
Control Apps

Instrument and Payload Apps

Reusable cFS Layer

Core Flight Executive and Reusable cFS Applications

Platform Layer

Platform Abstraction - Operating System and Board Specific

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cFS Metrics



cFE/	Logical	Config.	EEPROM
Арр	Lines of Code (non-table)	Parameters	(bytes)
cFE 6.4.0	12,930	General: 17 Executive Service: 46 Event Service: 5 Software Bus: 29 Table Service: 10 Time Service: 32	341,561
CFDP	8,559	33	85,812
Checksum	2,873	15	35,242
Data Storage	2,429	27	40,523
File Manager	1,853	22	16,272
Health & Safety	1,531	45	15071
House-Keeping	575	8	8.059
Limit Checker	2,074	13	31,026
Memory Dwell	1,035	8	8,617
Memory Manager	1,958	25	15,840
Scheduler	1,164	19	35,809
Stored Command (124 command sequences)	2,314	26	104,960



Example Mission Code Metrics Goddard Class B Mission



Noteworthy items

- + cFE was very reliable and stable
- + Easy rapid prototyping with heritage code that was cFE compliant
- + Layered architecture has allowed COTS lab to be maintained through all builds
- Addition of PSP changed build infrastructure midstream

Lines of Code Percentages:

Source	Percentage		
BAE	0.3		
EEFS	1.7		
OSAL	2.1		
PSP	1.0		
cFE	12.4		
GNC Library	1.6		
CFS Applications	23.5		
Heritage Clone & Own	38.9		
New Source	18.5		



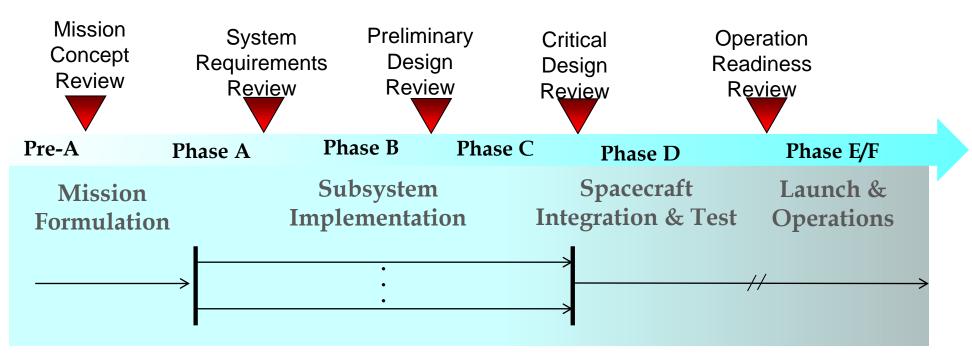


Flight Software • Engineering with the cFS



FSW Perspective of Mission Lifecycele





- Estimate Costs
- Define Ops Concept
- Define System Requirements
- Perform Trades
- Identify Risks

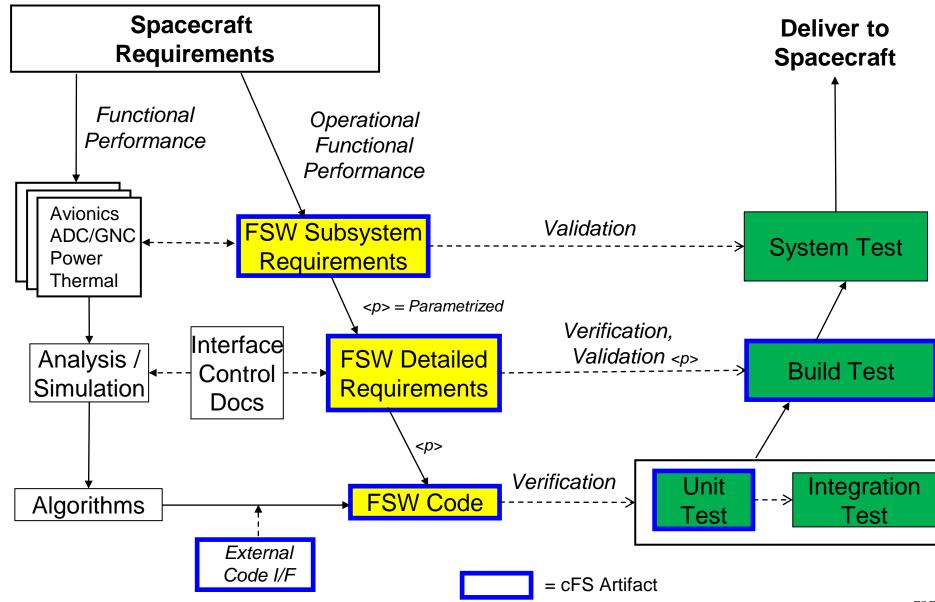
- Establish Development & Test Facility
- Refine FSW Requirements
- Develop & Test
 FSW in builds
- Support I&T test development, runs, and results verification
- FSW consultation and tool support

- Support initial checkout
- Support Ops
 - Troubleshoot
 - Update FSW



FSW Engineering "V"







Flight Software Engineering



- Describe spacecraft mission lifecycle from a FSW perspective
- Identify NASA standards and procedures
- So I was thinking we could frame the compliance as:
- The open source cFS Framework provides the framework to support certification for use by a project. The verification, software classification and quality assurance activities for a specific project use are all the responsibility of the project.
- Then I could mark up the verification matrix/traceability with all the artifacts we supply, what is a project responsibility, etc. So I wouldn't say "we don't comply with" or require any tailoring, but mark the things we don't do or don't quite meet as "Flight project responsibility"?
- With 7150.2C on the verge of coming out it seems like a good time to refresh...



Provide guidelines for different mission classes



Requirements





Describe parameters, requirements, and test approach

 Combine next 2 slides and make a good cFS systems top-down story and what cFS does and doesn't provide

Add IVV chart and relationship to V



Concept of Operations





Key mission events and their timelines

- Tracking and navigation
- Detailed operational performance requirements
- Mission data management
 - What needs to be stored



A Complete Engineering Solution



Includes reusable:

- Requirements
- Source Code
- Design Documentation
- Development Standards
- Test Artifacts
- Tools
 - Unit Test Framework
 - Software Timing Analyzer
- User's Guides
 - Application Developers Guide
 - API Reference Guides
 - Deployment Guides
 - Flight Operations Guides
- Simple Ground system

The cFS architecture reduces Non-Recurring Engineering (NRE) up to 90%



NASA Standards



NASA Procedural Requirements (NPRs)

- A set of documents that define procedural and process requirements
- Compliance is mandatory
- Defined in NASA Online Directive Information System



https://nodis3.gsfc.nasa.gov/main_lib.html

Lifecycle phases defined in

NPR 7120.5E NASA Space Flight Program and Project Management



Also referenced in the NASA Systems Engineering Handbook

https://www.nasa.gov/feature/release-of-revision-to-the-nasa-systems-engineering-handbook-sp-2016-6105-rev-2



FSW Process Requirements (1 of 2)



NPR 7150.2C – NASA Software Engineering Requirements

- Defines software "classes"
 - A Human Rated Space Software Systems
 - B Non-human Space Rated Software Systems or Large Scale Aeronautics Vehicles
 - C Mission Support Software or Aeronautic Vehicles, or Major Engineering/research Facility Software
 - D Basic Science/Engineering Design and Research and Technology Software
 - E Design Concept, Research, Technology and General Purpose Software

Capability Maturity Model CMMI

- Process level improvement training and appraisal program
- NASA Goddard FSW appraised at CMMI Level 2 ("Managed")



FSW Process Requirements (2 of 2)



Goddard Open Learning Design (GOLD) Rules

- Specify sound engineering principles and practices, which have evolved in the Goddard community
- Intended to describe foundational principles that "work," without being overly prescriptive of an implementation "philosophy

Global Precipitation Measurement (GPM) Critical Design Review

For this chart, Margin = (Available - Estimate) / Available

Resource	Amount Available	Current Estimate	Current Margin	GOLD Rule Margin Guidance @ CDR
CPU	100%	40.00%	60%	40%
EEPROM(kB)	2048	1311	36%	40%
uP RAM(kB)	24576	8424	66%	40%
PCI Bus	100%	2.00%	98%	60%
1553 S/C Bus (kbps)	300000	110890	63%	20%
1553 Instr. Bus (kbps)	300000	227000	24%	20%





Appendix A

Acronyms





API Application Programmer Interface

APL Applied Physics Lab

ASIST Advanced Spacecraft Integration and System Testing

ATS Absolute Time Sequence

BC Bus Controller
BT Build Test

bps bits-per seconds
Bps Bytes-per seconds

BSP Board Support Package

C&DH Command and Data Handling

CCSDS Consultative Committee for Space Data Systems

CDS Critical Data Store

CESE Center for Experimental Software Engineering

CFDP CCSDS File Delivery Protocol

cFE Core Flight Executive

cFS Core Flight Software SystemCM Configuration Management

CMD Command

COTS Commercial Off The Shelf

cPCI Compact PCI

CRC Cyclic Redundancy Check

CS Checksum

DMA Direct Memory Access

DS Data Storage

EEPROM Electrically Erasable Programmable Read-Only Memory

EOF End of File

ES Executive Services
EVS Event Services

FDC Failure Detection and Correction

FDIR Failure Detection, Isolation, and Recovery
FM File Management, Fault Management

FSW Flight Software





GNC Guidance Navigation and Control
GSFC Goddard Space Flight Center

GOTS Government Off The Shelf

GPM Global Precipitation Measurement

GPS Global Positioning System
Hi-Fi High-Fidelity Simulation

HK Housekeeping HS Health & Safety

HW Hardware Hz Hertz

I&T Integration and Test

ICD Interface Control Document

IPP Innovative Partnership Program Office IRAD Internal Research and Development

ITAR International Traffic in Arms Regulations

ISR Interrupt Service Routine

ITOS Integration Test and Operations System IV&V Independent Verification and Validation

JHU Johns Hopkins University

KORI Korean Aerospace Research Institute

LADEE Lunar Atmosphere and Dust Environment Explorer

LC Limit Checker

LDS Local Data Storage

LRO Lunar Reconnaissance Orbiter

Mbps Megabits-per seconds

MD Memory Dwell

MET Mission Elapsed Timer

MM Memory Manager
MS Memory Scrub

NASA

NACK Negative-acknowledgement

National Aeronautics Space Agency





NESC NASA Engineering and Safety Center

NOOP No Operation
OS Operating System

OSAL Operating System Abstraction Layer
PCI Peripheral Component Interconnect

PSP Platform Support Package RAM Random-Access Memory

RM Recorder Manager ROM Read-Only Memory RT Remote Terminal

R/T Real-time

RTOS Real-Time Operating System
RTS Relative Time Sequence

SARB Software Architecture Review Board

S/C Spacecraft
SB Software Bus

SBC Single-Board Computer

SC Stored Command

SCH Scheduler

S-COMM S-Band Communication Card SDO Solar Dynamic Observatory SDR Spacecraft Data Recorder SIL Simulink Interface Layer

SpW Spacewire SRAM Static RAM

SSR Solid State Recorder

STCF Spacecraft Time Correlation Factor

SUROM Start-Up Read-Only Memory

SW Software, Spacewire

TAI International Atomic Time

TBD To be determined





TBL Table Services

TLM Telemetry

TDRS Tracking Data Relay Satellite

TM Time Manager
TO Telemetry Output

TRMM Tropical Rainfall Measuring System

UART Universal Asynchronous Receiver/Transmitter

UDP User Datagram Protocol UMD University of Maryland

UT Unit Test

UTC Coordinated Universal Time
VCDU Virtual Channel Data Unit

XB External Bus

XBI Instrument 1553 External Bus
XBS Spacecraft 1553 External Bus





Appendix B

cFS & OSK Online Resources



cFS Resources



- cFE Framework, http://github.com/nasa/cFE
 - Contains the OSALs, PSPs and cFE that are managed and released by the NASA CCB
- cFS Bundle (cFE Framework), http://github.com/nasa/cFS
 - Contains the cFE Framework packaged with additional components to create a system that can be built, run and unit tested on a Linux platform
 - Website also contains a list of apps, tools and distributions
 - Other components may exist
- cFS Apps, https://github.com/nasa/**
 - "**" is the app abbreviation such as FM for File Manager
- cFS External Code Interface (ECI) library, https://github.com/nasa/ECI



OSK Resources



- OpenSatKit (OSK) A cFS distribution for learning the cFS, developing and integrating apps
 - Wiki and download, https://github.com/OpenSatKit/OpenSatKit/wiki
 - YouTube Channel, https://www.youtube.com/channel/UC2wfvAlkrrgyC4ITwL3zokg/
 - Pi-Sat Repo, https://github.com/OpenSatKit/pi-sat

NASA 42 Simulator, https://github.com/ericstoneking/42

Ball Aerospace COSMOS, https://cosmosrb.com/





Appendix C

Supplemental Architectural Material



Architecture Goals



- 1. Reduce time to deploy high quality flight software
- 2. Reduce project schedule and cost uncertainty
- 3. Directly facilitate formalized software reuse
- 4. Enable collaboration across organizations
- 5. Simplify sustaining engineering (AKA. On Orbit FSW maintenance) Missions last 10 years or more
- 6. Scale from small instruments to Hubble class missions
- 7. Build a platform for advanced concepts and prototyping
- 8. Create common standards and tools across the center



Quality Analysis - 1



Operability

The architecture must enable the flight system to operate in an efficient and understandable way

Reliability

- The architecture implementation must be known to behave correctly in nominal and expected off-nominal situations

Robustness

The architecture implementation must be predictable and safe in the presence of unexpected conditions

Performance

- The architecture implementation must efficient in runtime resources given the targeted processing environments

Testability

The architecture implementation must be easily and comprehensively testable in situ in flight like scenarios

Maintainability

The architecture implementation must be maintainable in the operational environment



Quality Analysis - 2



Effective Reuse

The architecture must support an effective reuse approach. This includes the software and artifacts. Requirements, design, code, review presentations, test, operations guides, command and telemetry databases. The goal is to achieve 100% reuse of a software component with no code changes

Composability

- Properties established at the component level, such as interfaces, timeliness or testability, also hold at the system level. For an application or node to be composable the architecture and process must support:
 - Independent development of nodes
 - Integration of the node into a system should not invalidate services in the value and temporal domains
 - Integration of an additional node into a functioning system should not disturb the correct operation of the existing nodes
 - Replica determinism identical copies of nodes must produce identical results in an identical order, within a specified time interval

Predicable Development Schedule

Development estimates provided by the FSW team should be reliable



Quality Analysis - 3



Scalability

 The FSW must scale with mission requirements. (Example: instruments or subsystem processor may only need a small amount of message buffer space. This should be configurable to avoid wasting memory resources)

Adaptability

The FSW must be capable of supporting a range of platforms and missions

Minimized Development Cost

 Costs for mission functions should be as low as possible. The teams must consider the difference between NRE and costs for a given mission

Technology infusion

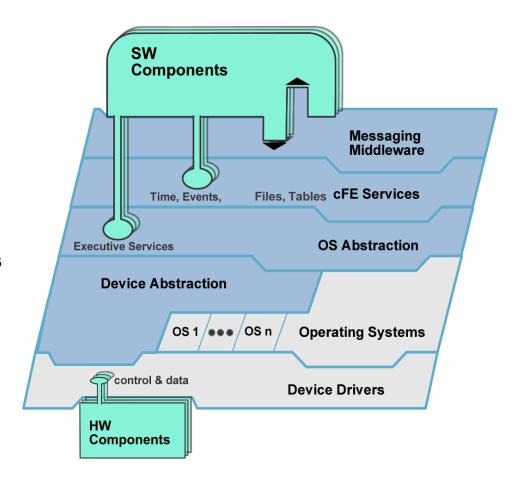
 The FSW should support the infusion of new hardware and software technologies with minimal side effects



Layered Service Architecture



- Each layer and service has a standard API
- Each layer "hides" its implementation and technology details.
- Internals of a layer can be changed -without affecting other layers' internals and components.
- Provides Middleware, OS and HW platform-independence.





Plug and Play

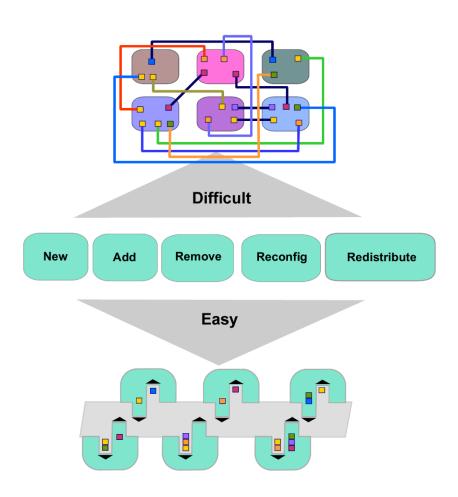


Plug and Play

- cFE API's support add and remove functions
- SW components can be switched in and out at runtime, without rebooting or rebuilding the system SW.
- Qualified Hardware and cFS-compatible software both "plug and play."

Impact:

- Changes can be made dynamically during development, test and on-orbit even as part of contingency management
- Technology evolution/change can be taken advantage of later in the development cycle.
- Testing flexibility (GSE, test apps, simulators)



This powerful paradigm allows SW components to be switched in and out at runtime, without rebooting or rebuilding the system SW.



Reusable Components

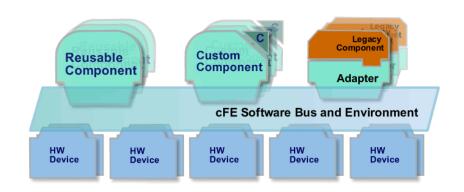


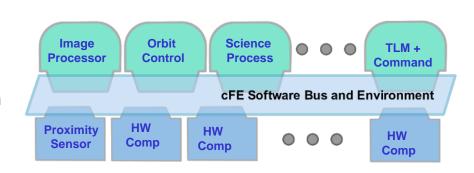
Reusable Components

- Common FSW functionality has been abstracted into a library of reusable components and services.
- Tested, Certified, Documented
- A system is built from:
 - Core services
 - Reusable components
 - Custom mission specific components
 - Adapted legacy components

Impact:

- Reuse of tested, certified components supplies savings in each phase of the software development cycle
- Reduces risk
- Teams focus on the custom aspects of their project and don't "reinvent the wheel."





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Component Example



- Interface only through core API's.
- A components contains all data needed to define it's operation.
- Components register for services
 - Register exception handlers
 - Register Event counters and filter
 - Register Tables
 - Publish messages
 - Subscribe to messages
- Component may be added and removed at runtime. (Allows rapid prototyping during development)
- Configuration Parameters

