

Tap Command



Motion Home Position Set RTC. (MOTION-HOME-POSITION-SET)

↳ Execute RTC()

↳ Process Command Async

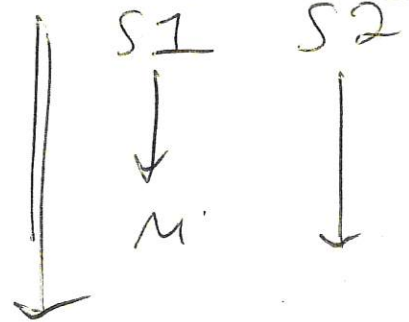
↳ Motion Home Position Set

↳ Servo Home Position Set()

↳ Servo Interface.

↳ Servo Home Position Set?

↳ pServoBase → SetHomePosition



↳ EcattMaster is only guy that inherits from ServoBase

EcattMaster::SetHomePosition()

OS(Wait For Single Object())

m-SetHomePos.h Done Event; // Set by Motion loop.

m-SetHomePos, b Pending RTC

↳ (m-dHome Origin Enc Canst)

EcattMaster::Check For Pending Set Home Position()