

# Uboot 2014.04 启动流程分析

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## ➤ Uboot 目录结构

 api	文件夹	2016/3/16 22:15
 arch	文件夹	2016/2/17 11:30
 board	文件夹	2016/2/17 11:30
 common	文件夹	2016/3/16 22:15
 disk	文件夹	2016/3/16 22:15
 doc	文件夹	2016/3/16 22:15
 drivers	文件夹	2016/3/16 22:12
 dts	文件夹	2016/3/16 22:15
 examples	文件夹	2016/2/17 11:30
 fs	文件夹	2016/3/16 22:15
 include	文件夹	2016/3/16 22:15
 lib	文件夹	2016/3/16 22:15
 Licenses	文件夹	2016/3/16 22:15
 net	文件夹	2016/3/16 22:15
 post	文件夹	2016/2/17 11:30
 scripts	文件夹	2016/3/16 22:15
 test	文件夹	2016/3/16 22:15
 tools	文件夹	2016/3/16 22:15

## ➤ Uboot 目录结构

- ◎ api 此目录下存放u-boot向外提供的接口函数
- ◎ arch 与体系结构相关的代码。
- ◎ board 是根据不同的具体开发板而定制的代码。
- ◎ common 通用代码，涵盖各个方面，以命令行处理为主
- ◎ disk 磁盘分区相关代码
- ◎ doc 常见功能和问题的说明文档，一堆README开头的文件
- ◎ drivers 常用的设备驱动程序，每个类型的设备驱动占用一个子目录
- ◎ examples 示例程序
- ◎ fs 文件系统，支持嵌入式开发常见fs(cramfs, ext2, ext3, jffs2, etc)
- ◎ include 全局需要的头文件定义在这儿
- ◎ lib 通用库文件
- ◎ net 网络相关的代码，小型的协议栈
- ◎ post Power On Self Test, 上电自检 程序
- ◎ Tools 辅助程序，用于编译和检查uboot目标文件

## ➤ Uboot 目录结构

- ◎ boards.cfg : 所有支持的板子的基本信息
- ◎ config.mk , Makefile: 顶层目录下的Makefile文件
- ◎ mkconfig: shell 脚本文件

## ➤ Uboot 编译过程-make xxx\_config

- ⦿ make xxx\_config

- ✓ XXX : 开发板名字

- ✓ 匹配 Makefile 中的目标

```
%_config:: outputmakefile
```

```
    @$(MKCONFIG) -A $(@:_config =)
```

- ✓ 通过 mkconfig shell脚本 从boards.cfg 中获取开发板基本信息到 include/config.mk, 并生成 config.h

## ➤ Uboot 编译过程-make all

◎ make (all) CROSS\_COMPILE=

✓ CROSS\_COMPILE:设置交叉编译工具

✓ 匹配 Makefile 中的目标

all:\$(ALL-y)

## ➤ Uboot 编译过程-make all

```
# Always append ALL so that arch config.mk's can add custom or
ALL-y += u-boot.srec u-boot.bin System.map

ALL-$(CONFIG_NAND_U_BOOT) += u-boot-nand.bin
ALL-$(CONFIG_ONENAND_U_BOOT) += u-boot-onenand.bin
ALL-$(CONFIG_RAMBOOT_PBL) += u-boot.pbl
ALL-$(CONFIG_SPL) += spl/u-boot-spl.bin
ALL-$(CONFIG_SPL_FRAMEWORK) += u-boot.img
ALL-$(CONFIG_TPL) += tpl/u-boot-tpl.bin
ALL-$(CONFIG_OF_SEPARATE) += u-boot.dtb u-boot-dtb.bin
ALL-$(CONFIG_OF_HOSTFILE) += u-boot.dtb
ifneq ($(CONFIG_SPL_TARGET),)
ALL-$(CONFIG_SPL) += $(CONFIG_SPL_TARGET:"%"=%)
endif
ALL-$(CONFIG_REMAKE_ELF) += u-boot.elf

# enable combined SPL/u-boot/dtb rules for tegra
ifneq ($(CONFIG_TEGRA),)
ifeq ($(CONFIG_SPL),y)
ifeq ($(CONFIG_OF_SEPARATE),y)
ALL-y += u-boot-dtb-tegra.bin
else
ALL-y += u-boot-nodtb-tegra.bin
endif
endif
endif
```

## ➤ Uboot 编译过程-make all

✓ u-boot.srec : u-boot

```
u-boot.hex u-boot.srec: u-boot FORCE  
$(call if_changed,objcopy)
```

✓ u-boot.bin : u-boot

```
u-boot.bin: u-boot FORCE  
$(call if_changed,objcopy)  
$(call DO_STATIC_RELA,$<,$@,$(CONFIG_SYS_TEXT_BASE))  
$(BOARD_SIZE_CHECK)
```

✓ System.map : u-boot

```
System.map: u-boot  
@$(call SYSTEM_MAP,$<) > $@
```



## ➤ Uboot 编译过程-make all

- ◎ u-boot: \$(u-boot-init) \$(u-boot-main) u-boot.lds

```
quiet_cmd_u-boot__?= LD      $@
cmd_u-boot__?= $(LD) $(LDFLAGS) $(LDFLAGS_u-boot) -o $@ \
-T u-boot.lds $(u-boot-init) \
--start-group $(u-boot-main) --end-group \
$(PLATFORM_LIBS) -Map u-boot.map

u-boot: $(u-boot-init) $(u-boot-main) u-boot.lds
$(call if_changed,u-boot__)
ifeq ($(CONFIG_KALLSYMS),y)
smap=`$(call SYSTEM_MAP,u-boot) | \
awk '$$2 ~ /[tTwW]/ {printf $$1 $$3 "\\000"}'` ; \
$(CC) $(c_flags) -DSYSTEM_MAP="\\"$${smap}\\"" \
-c $(srctree)/common/system_map.c -o common/system_map.o
$(call cmd,u-boot__) common/system_map.o
endif
```

## ➤ Uboot 编译过程-make all

- ✓ `u-boot-init := $(head-y)`
- ✓ `head-y := $(CPUDIR)/start.o`
- ✓ `u-boot-main := $(libs-y)`
- ✓ `u-boot.lds: $(LDSCRIPT) prepare FORCE`  
`$(call if_changed_dep, cpp_lds)`

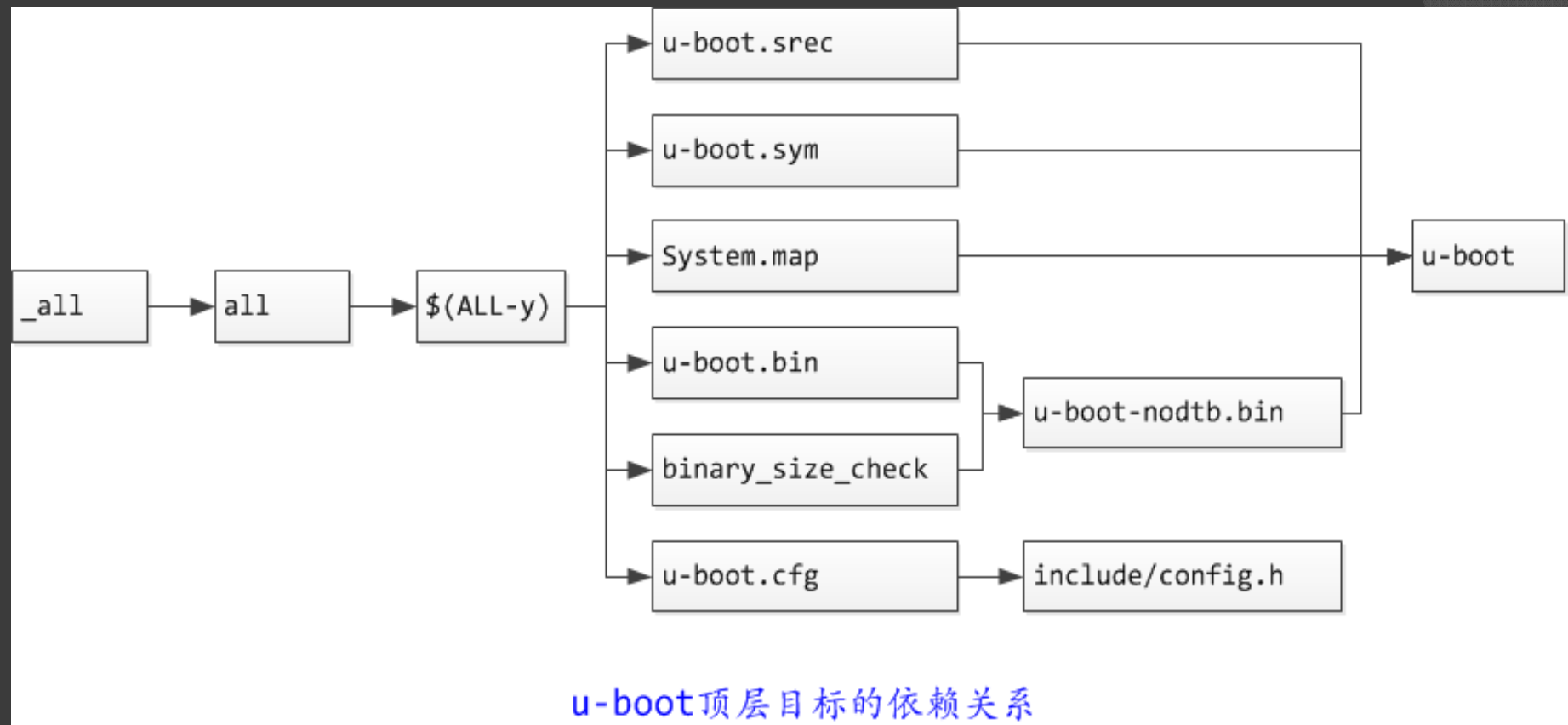
```
libs-y += lib/
libs-$(HAVE_VENDOR_COMMON_LIB) += board/$(VENDOR)/common/
libs-y += $(CPUDIR)/
ifdef SOC
libs-y += $(CPUDIR)/$(SOC)/
endif
libs-$(CONFIG_OF_EMBED) += dts/
libs-y += arch/$(ARCH)/lib/
libs-y += fs/
libs-y += net/
libs-y += disk/
libs-y += drivers/
libs-$(CONFIG_DM) += drivers/core/
libs-y += drivers/dma/
libs-y += drivers/gpio/
libs-y += drivers/i2c/
libs-y += drivers/input/
libs-y += drivers/mmc/
libs-y += drivers/mtd/
libs-$(CONFIG_CMD_NAND) += drivers/mtd/nand/
libs-y += drivers/mtd/onenand/
libs-$(CONFIG_CMD_UBI) += drivers/mtd/ubi/
libs-y += drivers/mtd/spi/
libs-y += drivers/net/
libs-y += drivers/net/phy/
libs-y += drivers/pci/
libs-y += drivers/power/ \
    drivers/power/fuel_gauge/ \
    drivers/power/mfd/ \
```

## ➤ Uboot 编译过程-make all

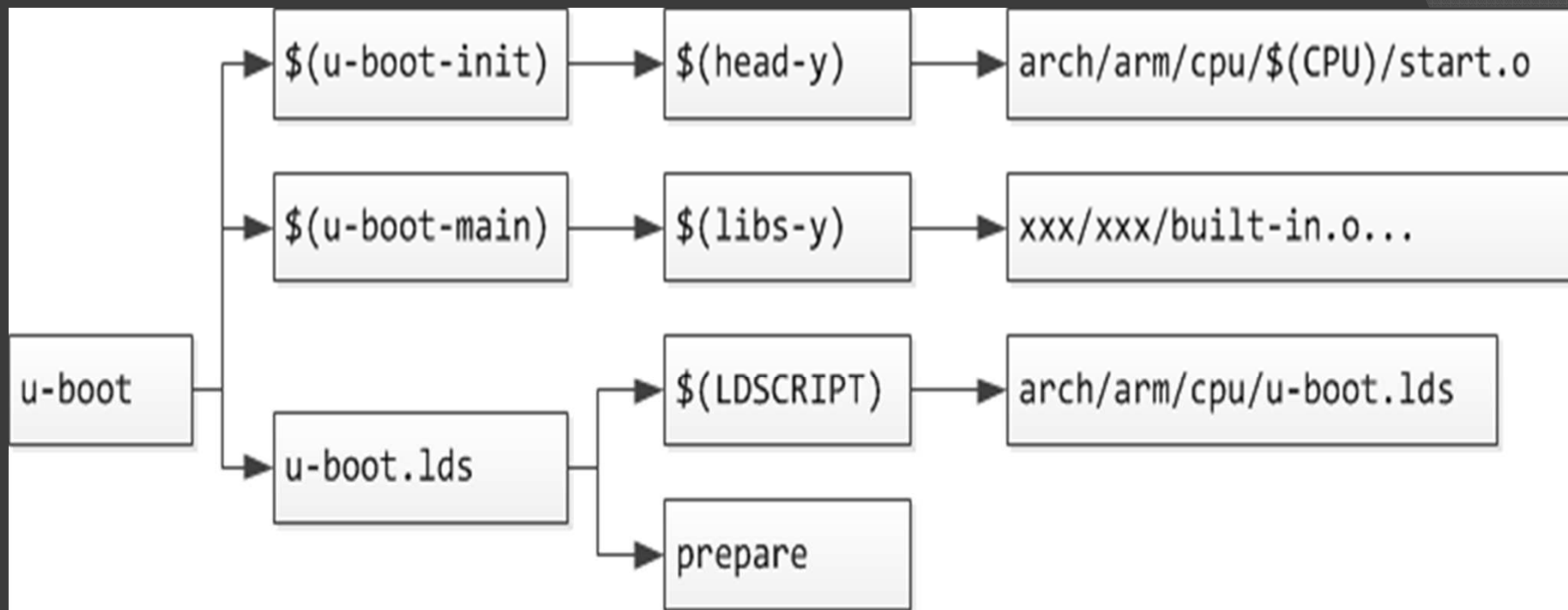
```
ifndef LDSCRIPT
    #LDSCRIPT := $(srctree)/board/$(BOARDDIR)/u-boot.lds.debug
    ifdef CONFIG_SYS_LDSCRIPT
        # need to strip off double quotes
        LDSCRIPT := $(srctree)/$(CONFIG_SYS_LDSCRIPT:"%"=%)
    endif
endif

# If there is no specified link script, we look in a number of places for it
ifndef LDSCRIPT
    ifeq [$(CONFIG_NAND_U_BOOT),y]
        LDSCRIPT := $(srctree)/board/$(BOARDDIR)/u-boot-nand.lds
        ifeq ($(wildcard $(LDSCRIPT)),)
            LDSCRIPT := $(srctree)/$(CPUDIR)/u-boot-nand.lds
        endif
    endif
    ifeq ($(wildcard $(LDSCRIPT)),)
        LDSCRIPT := $(srctree)/board/$(BOARDDIR)/u-boot.lds
    endif
    ifeq ($(wildcard $(LDSCRIPT)),)
        LDSCRIPT := $(srctree)/$(CPUDIR)/u-boot.lds
    endif
    ifeq ($(wildcard $(LDSCRIPT)),)
        LDSCRIPT := $(srctree)/arch/$(ARCH)/cpu/u-boot.lds
    endif
endif
```

## ➤ Uboot 编译过程-文件依赖关系



## ➤ Uboot 编译过程-文件依赖关系



u-boot文件目标的依赖关系

## ➤ Uboot 启动流程分析

- ◎ `_start,`
- ◎ `_main,`
- ◎ `board_init_f,`
- ◎ `relocate_code,`
- ◎ `board_init_r`

## ➤ Uboot 启动流程分析-\_start

### ✓ 定义异常向量入口

```
.globl _start
_start: b reset
    ldr pc, _undefined_instruction
    ldr pc, _software_interrupt
    ldr pc, _prefetch_abort
    ldr pc, _data_abort
    ldr pc, _not_used
    ldr pc, _irq
    ldr pc, _fiq
#ifdef CONFIG_SPL_BUILD
_undefined_instruction: .word _undefined_instruction
_software_interrupt:    .word _software_interrupt
_prefetch_abort:       .word _prefetch_abort
_data_abort:           .word _data_abort
_not_used:             .word _not_used
_irq:                  .word _irq
_fiq:                  .word _fiq
_pad:                  .word 0x12345678 /* now 16*4=64 */
#else
.globl _undefined_instruction
_undefined_instruction: .word _undefined_instruction
.globl _software_interrupt
_software_interrupt:    .word _software_interrupt
.globl _prefetch_abort
_prefetch_abort:       .word _prefetch_abort
.globl _data_abort
_data_abort:           .word _data_abort
.globl _not_used
_not_used:             .word _not_used
```

### ✓ reset向量 执行 b reset



## ➤ Uboot 启动流程分析-reset

```
reset:
    bl  save_boot_params
    /*
     * disable interrupts (FIQ and IRQ), also set the cpu to SVC32 mode,
     * except if in HYP mode already
     */
    mrs r0, cpsr
    and r1, r0, #0x1f          @ mask mode bits
    teq r1, #0x1a             @ test for HYP mode
    bicne r0, r0, #0x1f        @ clear all mode bits
    orrne r0, r0, #0x13        @ set SVC mode
    orr r0, r0, #0xc0          @ disable FIQ and IRQ
    msr cpsr,r0
- /*
 * Setup vector:
 * (OMAP4 spl TEXT_BASE is not 32 byte aligned.
 * Continue to use ROM code vector only in OMAP4 spl)
 */
- #if !(defined(CONFIG_OMAP44XX) && defined(CONFIG_SPL_BUILD))
    /* Set V=0 in CP15 SCTRL register - for VBAR to point to vector */
    mrc p15, 0, r0, c1, c0, 0 @ Read CP15 SCTRL Register
    bic r0, #CR_V             @ V = 0
-    mcr p15, 0, r0, c1, c0, 0 @ Write CP15 SCTRL Register
    /* Set vector address in CP15 VBAR register */
    ldr r0, =_start
    mcr p15, 0, r0, c12, c0, 0 @Set VBAR
- #endif
    /* the mask ROM code should have PLL and others stable */
- #ifndef CONFIG_SKIP_LOWLEVEL_INIT
    bl  cpu_init_cp15
    bl  cpu_init_crit
- #endif
    bl  _main
```

## ➤ Uboot 启动流程分析-reset

- ◎ 设置cpu进入svc32模式

- ◎ 关闭中断

- ◎ cpu\_init\_cp15

设置cp15相关寄存器来设置处理器的MMU, cache以及tlb

- ◎ cpu\_init\_crit

lowlevel\_init: 初始化 pll, memory

## ➤ Uboot 启动流程分析-main

```
- ENTRY(_main)
/*
 * Set up initial C runtime environment and call board_init_f(0).
 */
- #if defined(CONFIG_SPL_BUILD) && defined(CONFIG_SPL_STACK)
    ldr sp, =(CONFIG_SPL_STACK)
- #else
    ldr sp, =(CONFIG_SYS_INIT_SP_ADDR)
- #endif
    bic sp, sp, #7 /* 8-byte alignment for ABI compliance */
    sub sp, sp, #GD_SIZE /* allocate one GD above SP */
    bic sp, sp, #7 /* 8-byte alignment for ABI compliance */
    mov r9, sp /* GD is above SP */
    mov r0, #0
    bl board_init_f
- #if ! defined(CONFIG_SPL_BUILD)
/*
 * Set up intermediate environment (new sp and gd) and call
 * relocate_code(addr_moni). Trick here is that we'll return
 * 'here' but relocated.
 */
-    ldr sp, [r9, #GD_START_ADDR_SP] /* sp = gd->start_addr_sp */
    bic sp, sp, #7 /* 8-byte alignment for ABI compliance */
    ldr r9, [r9, #GD_BD] /* r9 = gd->bd */
    sub r9, r9, #GD_SIZE /* new GD is below bd */

    adr lr, here
    ldr r0, [r9, #GD_RELOC_OFF] /* r0 = gd->reloc_off */
    add lr, lr, r0
    ldr r0, [r9, #GD_RELOCADDR] /* r0 = gd->relocaddr */
    b relocate_code
- here:
/* Set up final (full) environment */
```

## ➤ Uboot 启动流程分析-main

```
here:
/* Set up final (full) environment */

bl c_runtime_cpu_setup /* we still call old routine here */
ldr r0, =_bss_start /* this is auto-relocated! */
ldr r1, =_bss_end /* this is auto-relocated! */
mov r2, #0x00000000 /* prepare zero to clear BSS */
clbss_l: cmp r0, r1 /* while not at end of BSS */
        strlo r2, [r0] /* clear 32-bit BSS word */
        addlo r0, r0, #4 /* move to next */
        blo clbss_l
bl coloured_LED_init
bl red_led_on
/* call board_init_r(gd_t *id, ulong dest_addr) */
mov r0, r9 /* gd_t */
ldr r1, [r9, #GD_RELOCADDR] /* dest_addr */
/* call board_init_r */
ldr pc, =board_init_r /* this is auto-relocated! */
/* we should not return here. */
#endif
ENDPROC(_main)
```

## ➤ Uboot 启动流程分析-main

- ◎ 设置栈指针sp
- ◎ board\_init\_f : init\_sequence\_f
- ◎ relocate\_code
- ◎ board\_init\_r : init\_sequence\_r



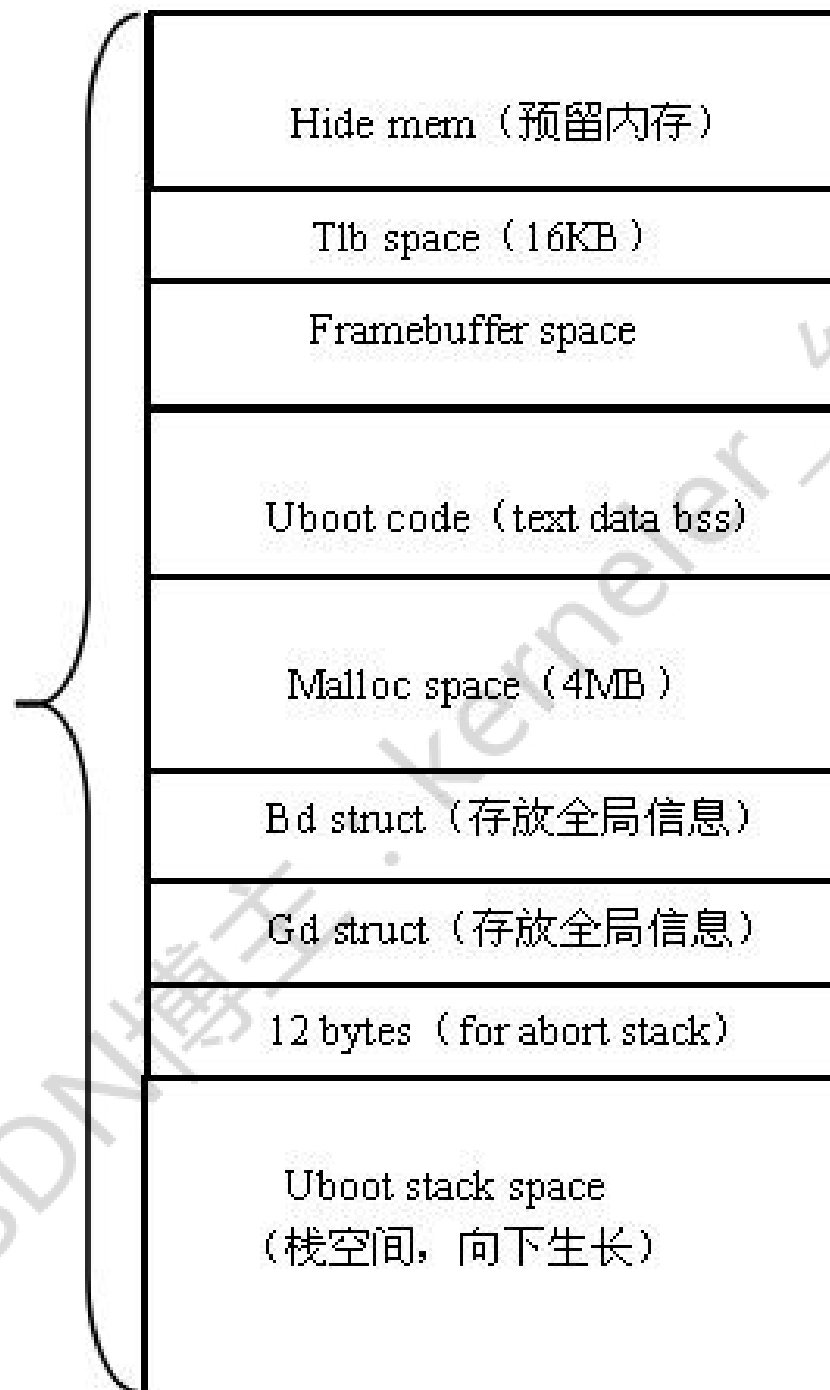
## ➤ Uboot 启动流程分析- board\_init\_f

- ◎ setup\_mon\_len: 获取uboot code长度 (初始化gd->mon\_len)
- ◎ setup\_fdt : 获取fdt地址 (初始化gd->fdt\_blob)
- ◎ mark\_bootstage : 记录启动阶段
- ◎ env\_init : 初始化环境来源 (gd->env\_addr, gd->env\_valid)
- ◎ init\_baud\_rate: 从环境变量中获取baudrate (gd->baudrate)
- ◎ serial\_init : 串口初始化
- ◎ console\_init\_f: (gd->have\_console=1)
- ◎ display\_options: 打印uboot版本信息
- ◎ display\_text\_info: 打印调试信息  
(CONFIG\_SYS\_TEXT\_BASE, bss\_start, bss\_end)
- ◎ print\_cpuinfo: 打印cpu相关信息
- ◎ dram\_init : dram初始化 (gd->ram\_size)

## ➤ Uboot 启动流程分析- board\_init\_f

```
#if defined(CONFIG_VIDEO) && (!defined(CONFIG_PPC) || defined(CONFIG_8xx)) \
    && !defined(CONFIG_ARM) && !defined(CONFIG_X86)
    reserve_video,
#endif
    reserve_uboot,
#ifdef CONFIG_SPL_BUILD
    reserve_malloc,
    reserve_board,
#endif
    setup_machine,
    reserve_global_data,
    reserve_fdt,
    reserve_stacks,
    setup_dram_config,
    show_dram_config,
#ifdef CONFIG_PPC
    setup_board_part1,
    INIT_FUNC_WATCHDOG_RESET
    setup_board_part2,
#endif
    setup_baud_rate,
    display_new_sp,
#ifdef CONFIG_SYS_EXTBDINFO
    setup_board_extra,
#endif
    INIT_FUNC_WATCHDOG_RESET
    reloc_fdt,
    setup_reloc,
#if !defined(CONFIG_ARM) && !defined(CONFIG_SANDBOX)
    jump_to_copy,
#endif
    NULL,
};
```

整个 sdram  
地址空间



Sdram 起始地址, 如 0x80000000



## ➤ Uboot 启动流程分析- relocate\_code

```
bl board_init_f

#if ! defined(CONFIG_SPL_BUILD)

/*
 * Set up intermediate environment (new sp and gd) and call
 * relocate_code(addr_moni). Trick here is that we'll return
 * 'here' but relocated.
 */

ldr sp, [r9, #GD_START_ADDR_SP] /* sp = gd->start_addr_sp */
bic sp, sp, #7 /* 8-byte alignment for ABI compliance */
ldr r9, [r9, #GD_BD] /* r9 = gd->bd */
sub r9, r9, #GD_SIZE /* new GD is below bd */

adr lr, here
ldr r0, [r9, #GD_RELOC_OFF] /* r0 = gd->reloc_off */
add lr, lr, r0
ldr r0, [r9, #GD_RELOCADDR] /* r0 = gd->relocaddr */
b relocate_code

here:

/* Set up final (full) environment */

bl c_runtime_cpu_setup /* we still call old routine here */

ldr r0, =__bss_start /* this is auto-relocated! */
ldr r1, =__bss_end /* this is auto-relocated! */

mov r2, #0x00000000 /* prepare zero to clear BSS */
```

## ➤ Uboot 启动流程分析- relocate\_code

- ◎ 更新栈指针sp
- ◎ 更新全局结构体gd地址
- ◎ 保存here搬移后在ram中的位置
- ◎ relocate\_code
- ◎ relocate\_code后进入ram空间

## ➤ Uboot 启动流程分析- board\_init\_r

here:

```
/* Set up final (full) environment */

bl c_runtime_cpu_setup /* we still call old routine here */

ldr r0, =__bss_start    /* this is auto-relocated! */
ldr r1, =__bss_end      /* this is auto-relocated! */

mov r2, #0x00000000     /* prepare zero to clear BSS */

clbss_l:cmp r0, r1      /* while not at end of BSS */
strlo r2, [r0]          /* clear 32-bit BSS word */
addlo r0, r0, #4        /* move to next */
blo clbss_l

bl coloured_LED_init
bl red_led_on

/* call board_init_r(gd_t *id, ulong dest_addr) */
mov r0, r9              /* gd_t */
ldr r1, [r9, #GD_RELOCADDR] /* dest_addr */
/* call board_init_r */
ldr pc, =board_init_r  /* this is auto-relocated! */

/* we should not return here. */

#endif

ENDPROC(_main)
```

## ➤ Uboot 启动流程分析- board\_init\_r

- ◎ initr\_reloc: 设置gd->flag, 记录启动阶段
- ◎ set\_cpu\_clk\_info: 设置时钟相关的操作
- ◎ initr\_serial: 注册当前串口设备到全局串口链表中 (将串口更新到ram)
- ◎ initr\_malloc: 初始化 malloc 区域 (清零)
- ◎ set\_cpu\_clk\_info: 设置cpu时钟信息
- ◎ stdio\_init: 将所有串口注册到stdio设备中
- ◎ initr\_jumptable : 设置gd->jt
- ◎ console\_init\_r: 设置标准输入输出和出错设备
- ◎ run\_main\_loop: 进入uboot命令模式

谢谢观赏！