Drop-off Locker User Manual and Design Schematic





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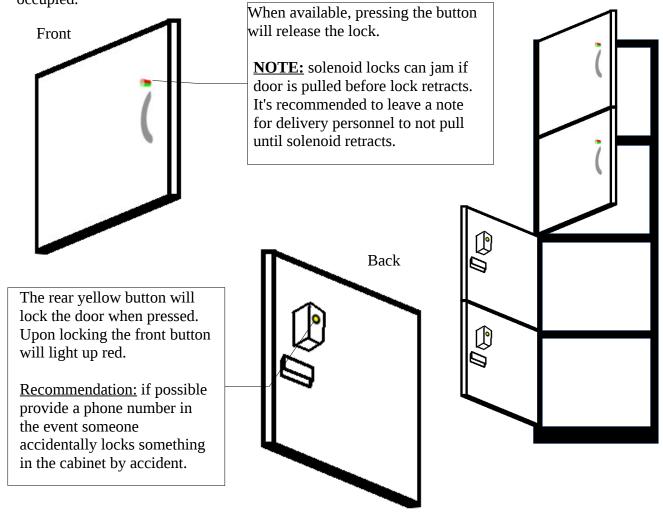
About:

Drop-off Locker is designed to combat package theft. The cabinet is designed to allow delivery personnel to place packages in and lock it without the need of a key. Obtaining packages is accomplished with access to the administrator control box to unlock doors.



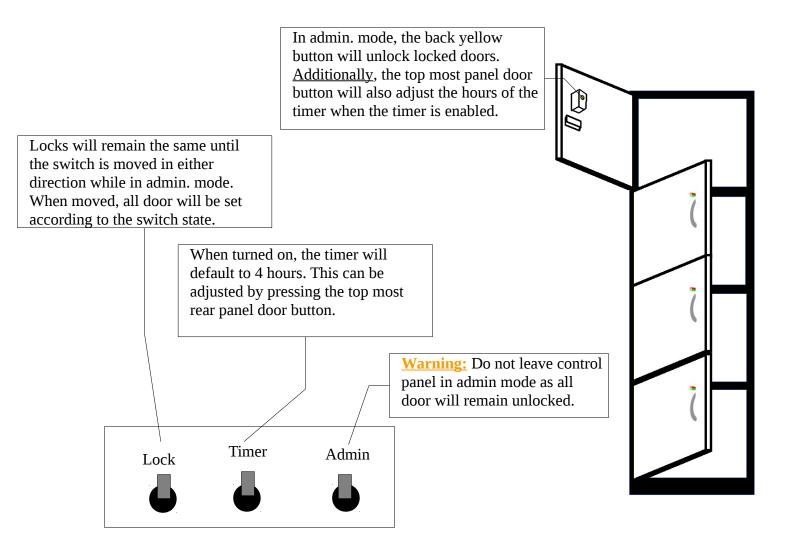
General Use:

Availability of the locker is indicated by the clear acrylic push button. When lit green, the locker is available and when red, occupied.



Administrator Use:

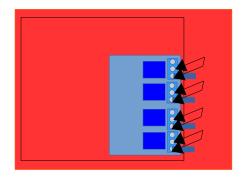
As administrator, you will have the ability to lock and unlock all or individual doors as well as setup a timer until doors become locked. Within the control box are 3 switches: administrator mode, timer enable, and lock toggle. When in administrator mode, all doors are accessible and the lights will indicate the timer state instead of the lock state. When all red (no lights in control box) the timer is off, for each lit LED in the control box, an hour (or less) remains.



Troubleshoot and Repair:

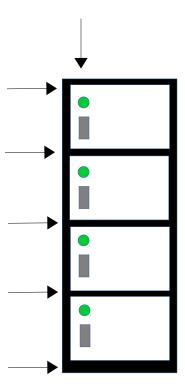
- Unable to open door through normal procedure
 - How to force open cabinet:
 - Relay override:

Connect the center terminal to the wired terminal with a metal contact of the relay board contained in the control box. Make sure 12v power reaches the relay circuit.



Cabinet dismantle:

With a hex key, dismantle the cabinet from the side nearest to the handle as to avoid impacting the wiring.



Troubleshoot Diagnoses:

- a) Issues:
 - Lock will not release using the relay override technique.
 - See *cabinet wiring issues* and *control box wiring issues*.
 - Button lights up green and red.
 - See *cabinet wiring issues* and *control box wiring issues*.
 - Locker keeps power cycling (turns on and off continuously)
 - See *power issues*.
 - One or both colors do not show.
 - Light can be lit directly from door panel? (see *circuit design* and *assembly notes*)
 - Yes: See *cabinet wiring issues* and *control box wiring issues*.
 - No: See *circuit design* and *assembly notes* to replace lights.

b) Checks & Fixes

Cabinet wiring issues

A wire may be severed or the panel connector between the door and main frame may be disconnected. Inspect for any tampering or disconnected panel connections. To test for severed wires, use a multimeter's continuity tester feature to check for connections between control box and panels. (see *circuit design* and *assembly notes*)

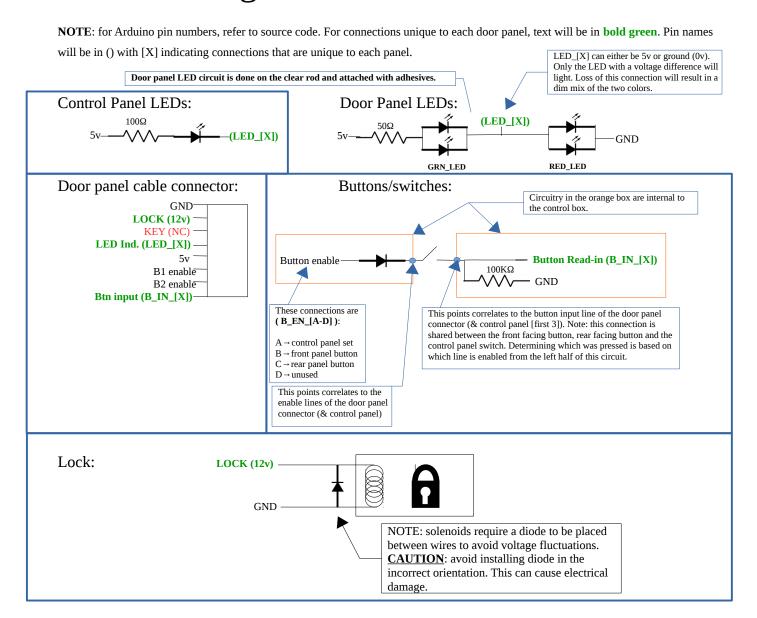
Control box issues

Unscrew nuts and check no connectors were disconnected. NOTE: some wires have little slack; remove top cover gently. (see *circuit design* and *assembly notes*)

Power Issues

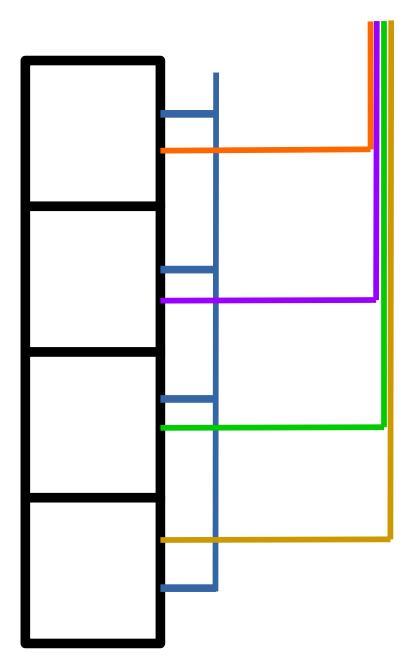
Two particular things can cause this. 1) If the solenoid lock is replaced/damaged and a diode is not connected between the voltage line and ground lines (see circuit diagram). 2) . An exposed wire/connector is shorting cause the board to restart.

Circuit Design:



Relay circuitry: refer to source code to determine connections between the relay control board and Arduino micro-controller. NOTE: make sure to properly connect 12v and the solenoid lines to the correct terminals. Also check to see if the relay board used is active low or active high and adjust source code accordingly (see ACTIVE_LOW_RELAY in code).

Wiring: wiring is done in two bundles. The first are the common lines shared with all the panels and the second to each individual panel.



Source Code:

```
#define LED D 13 //bottom
#define LED C 12
#define LED B 11
#define LED A 10 //top
#define B EN D 9
#define B EN C 8 //back button
#define B EN B 7 //front button
#define B_EN_A 6 //priority set(control panel)
#define LCK_D 5 //bottom
#define LCK C 4
#define LCK B 3
#define LCK A 2 //top
#define B_IN_D 3
#define B IN C 2
#define B IN B 1
#define B IN A 0
#define LOCKED 0
#define UNLOCKED 1
#define TAKEN 1
#define OPEN 0
#define LOOPS TO HR 36000
#define WATHCHDOG LIMIT 50 //5 seconds limit
#define ACTIVE LOW RELAY
struct QuadState
 bool s[4];
};
struct QuadCount
  int c[4];
};
//lock access (TAKEN/OPEN)
QuadState gLockLed;
//current state of lock(LOCKED/UNLOCKED)
QuadState gLock;
//button state (per poll per set)
QuadState gBtn;
//avoid holding solenoid lock if button jams in
QuadState gWatchDogHit;
QuadCount gWatchDogCnt;
```

```
//how many hours till locking
unsigned short gLkTmr;
//no available pins to allow for interupt based timer.
//keep track of hours by counting loops
unsigned int gHrTmr;
//perserve last state of button/switch to trigger event on changed state
bool gLastTToggle; //for changing time
bool gLastLToggle; //for locking/unlocking all in admin mode
bool gLastAMode; //check if admin mode was just entered
//TODO: add watchdog timer for held lock buttons
void setup()
  // Initialize the digital pin as an output.
  for(int i = 6; i < 14; i++)
    pinMode(i, OUTPUT);
    digitalWrite(i, 0);
  for(int i = 0; i < 4; i++)
    pinMode(i+LCK A, OUTPUT);
#ifdef ACTIVE_LOW_RELAY
    digitalWrite(i+LCK A, 1);
#else
    digitalWrite(i+LCK A, 0);
#endif
  }
  Serial.begin(9600);
  Serial.println("LOCKER STARTING UP....");
/* Debug code
  //startup debug blink
  for(int d = 0; d < 4; d++)
   for(int t = 0; t < 4; t++)
      delay(500);
      for(int i = LED A; i <= LED D; i++) { digitalWrite(i, LOCKED); }</pre>
      delay(500);
      debugBtnShow(d);
      //for(int i = LED A; i <= LED D; i++) { digitalWrite(i, UNLOCKED); }</pre>
   }
 }
```

```
//set default values
 for(int i = 0; i < 4; i++)
   gLock.s[i] = LOCKED;
   gLockLed.s[i] = TAKEN;
 gLkTmr = 4;
 gLastTToggle = false;
 gLastLToggle = false;
 gLastAMode = false;
 gHrTmr = LOOPS_TO_HR;
 //start watchdog with clean slate (no open locks)
 watchdogTick();
 showLockState();
 Serial.println("SYSTEM INITIALIZED....");
}
void loop()
 bool adminMode = false;
 bool activeTimer = false;
 bool toggleLock = false;
delay(25);
 readBtn(0);
 adminMode = gBtn.s[0];
 activeTimer = gBtn.s[1];
 toggleLock = gBtn.s[2];
 if(activeTimer && adminMode && (gLkTmr == 0))
 {
   gLkTmr = 4;
 else if(!activeTimer)
   gLkTmr = 0;
 }
 if((adminMode) && (toggleLock != gLastLToggle) && gLastAMode)
   setAllState(toggleLock ? TAKEN : OPEN);
 gLastLToggle = toggleLock;
 gLastAMode = adminMode;
```

```
//front button------
 delay(25);
 readBtn(1);
 if(adminMode)
 {
  for(int i = 0; i < 4; i++)
    gLock.s[i] = gBtn.s[i];
  }
 }
 else
  for(int i = 0; i < 4; i++)
    gLock.s[i] = gBtn.s[i] && (gLockLed.s[i] == OPEN);
  }
 }
 //rear button------
 delay(25);
 readBtn(2);
 for(int i = 0; i < 4; i++)
  if(adminMode) { gLockLed.s[i] &= !gBtn.s[i]; }
  else { gLockLed.s[i] |= gBtn.s[i]; }
 if(adminMode)
  if(activeTimer && !gLastTToggle && gBtn.s[0])
    toggleTimer();
  gLastTToggle = gBtn.s[0];
 }
 else { gLastTToggle = false; }
 //for future improvements/debug ------
 delay(25);
 readBtn(3);
 //add code as needed
//display state
 if(adminMode)
 {
  showTimerState();
 else
 {
  showLockState();
 watchdogTick();
```

```
triggerLock();
  //check for timer event (reaching an hour)
  gHrTmr--;
  if(!gHrTmr)
    hrHit();
}
void watchdogTick()
  for(int i = 0; i < 4; i++)
    if(gWatchDogHit.s[i])
      if(!gLock.s[i]) { gWatchDogCnt.c[i] = 0; }
    }
    else
    {
      gWatchDogCnt.c[i] = gLock.s[i] ? gWatchDogCnt.c[i]+1 : 0;
    gWatchDogHit.s[i] = (gWatchDogCnt.c[i] >= WATHCHDOG LIMIT);
  }
}
void showTimerState()
  for(int i = 0; i < 4; i++)
    digitalWrite(i+LED A, gLkTmr > i ? LOW : HIGH);
  }
}
void showLockState()
  for(int i = 0; i < 4; i++)
    digitalWrite(i+LED A, gLockLed.s[i]);
  }
}
void debugBtnShow(unsigned int set)
  readBtn(set);
 gLockLed = gBtn;
  showLockState();
}
```

```
void triggerLock()
 for(int i = 0; i < 4; i++)
#ifdef ACTIVE LOW RELAY
    digitalWrite(i+LCK A, !(gLock.s[i] && !gWatchDogHit.s[i]));
    digitalWrite(i+LCK_A, (gLock.s[i] && !gWatchDogHit.s[i]));
#endif
 }
}
void readBtn(unsigned int set)
  //disable all sets and reset state
  for(int i = 0; i < 4; i++)
   digitalWrite(B_EN_A+i, 0);
   gBtn.s[i] = false;
  //if valid set, read in buttons
  if(set < 4)
   digitalWrite(B EN A+set, 1);
    for(int i = 0; i < 4; i++) { gBtn.s[i] = analogRead(i+B IN A) > 111; }
  }
}
void toggleTimer()
  gLkTmr = (gLkTmr + 4) % 5;
void enableTimer(bool en)
  if(en)
    gLkTmr = 4;
  }
  else
  {
    gLkTmr = 0;
  }
}
void setAllState(bool takenState)
  for(int i = 0; i < 4; i++)
    gLockLed.s[i] = takenState;
  }
}
```

```
void hrHit()
{
   gHrTmr = LOOPS_TO_HR;

   if(gLkTmr)
   {
      gLkTmr--;
      if(!gLkTmr)
      {
        setAllState(TAKEN);
      }
   }
}
```

Fabrication Notes:

Product Links:

- Cabinet: https://www.amazon.com/gp/product/B00DQQQOGY/ref=oh-aui-search_detailpage?
 ie=UTF8&psc=1
- Arduino Board: https://www.amazon.com/Arduino-Uno-R3-Microcontroller-A000066/dp/B008GRTSV6/ref=sr 1 1?ie=UTF8&qid=1490608822&sr=8-1&keywords=arduino+uno
- Relay Board: http://www.ebay.com/itm/321869298037

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Fabrication supplies and services:

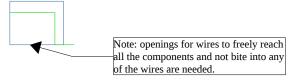
- Welding (in Redmond, WA): STA Weld https://www.yelp.com/biz/sta-weld-redmond
- Acrylic tube & sheets: Tap Plastics https://tapplastics.com/

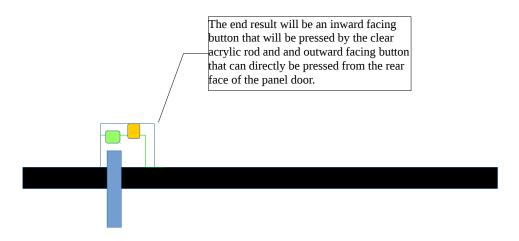
Assembling button enclosure:

Using 2 inch wide sheet metal strips (1/16 thick), bend to the following patterns:



Drill 2 large holes (in red) to fit buttons into and 2 small holes for wood tapping screws (in blue) to hold the enclosure to the door panel. Then weld the two strips together in the arrangement below.





Upgrade Notes:

Currently a breadboard is used to connect all components between the micro-controller and hardware. Producing a PCB with the necessary pull down resistors for the button read in as well as the diode circuitry for the button enable lines and slots for connecting wires would provided a needed level of convenience for maintenance and repair.

Contact Info:

Developer: Jerry Z.

Email: open_help@zsoftdevelopment.com