

Drop-off Locker

User Manual and Design Schematic



Soft Development

Open Source Projects

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About:

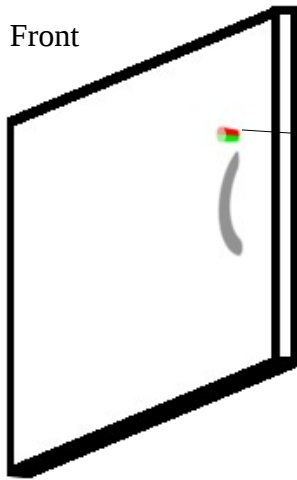
Drop-off Locker is designed to combat package theft. The cabinet is designed to allow delivery personnel to place packages in and lock it without the need of a key. Obtaining packages is accomplished with access to the administrator control box to unlock doors.



General Use:

Availability of the locker is indicated by the clear acrylic push button. When lit green, the locker is available and when red, occupied.

Front



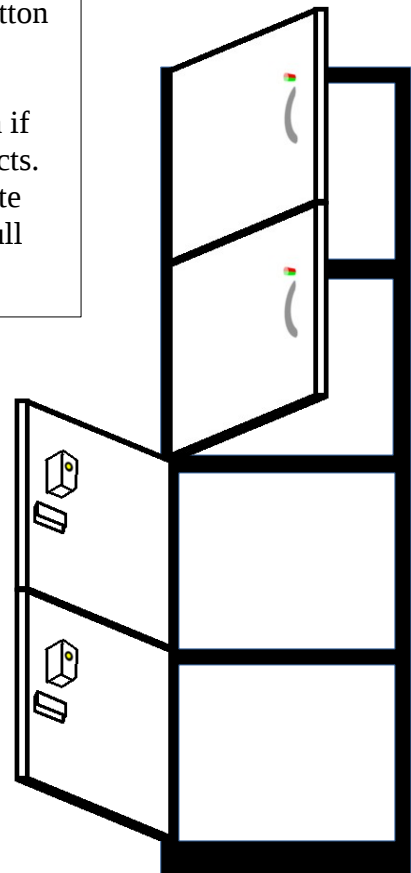
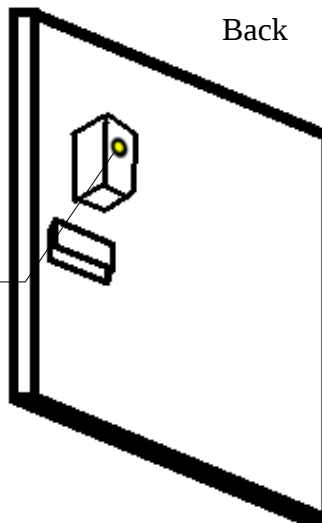
When available, pressing the button will release the lock.

NOTE: solenoid locks can jam if door is pulled before lock retracts. It's recommended to leave a note for delivery personnel to not pull until solenoid retracts.

The rear yellow button will lock the door when pressed. Upon locking the front button will light up red.

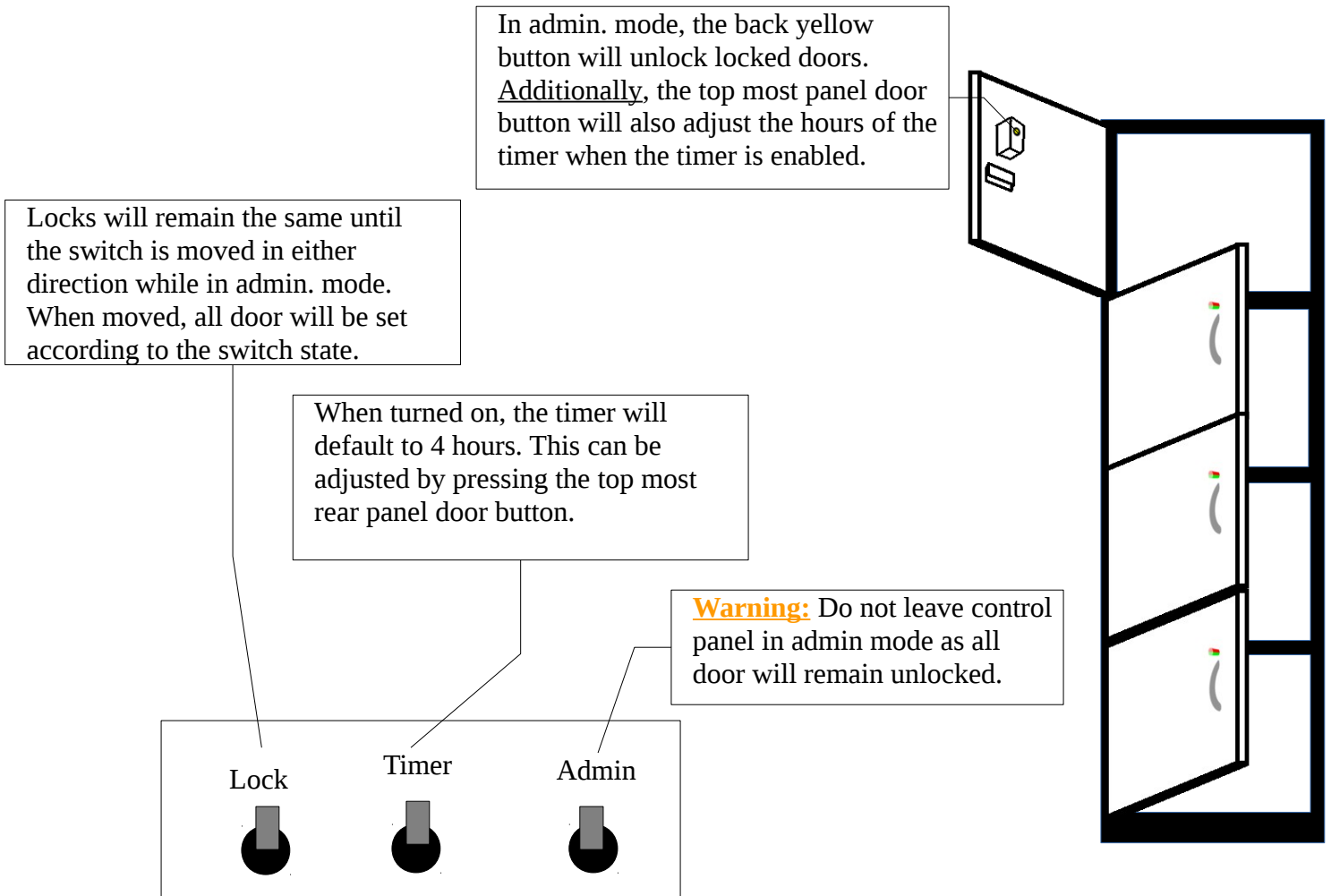
Recommendation: if possible provide a phone number in the event someone accidentally locks something in the cabinet by accident.

Back



Administrator Use:

As administrator, you will have the ability to lock and unlock all or individual doors as well as setup a timer until doors become locked. Within the control box are 3 switches: administrator mode, timer enable, and lock toggle. When in administrator mode, all doors are accessible and the lights will indicate the timer state instead of the lock state. When all red (no lights in control box) the timer is off, for each lit LED in the control box, an hour (or less) remains.



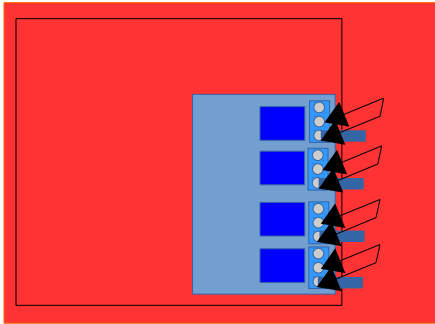
Troubleshoot and Repair:

- Unable to open door through normal procedure

- How to force open cabinet:

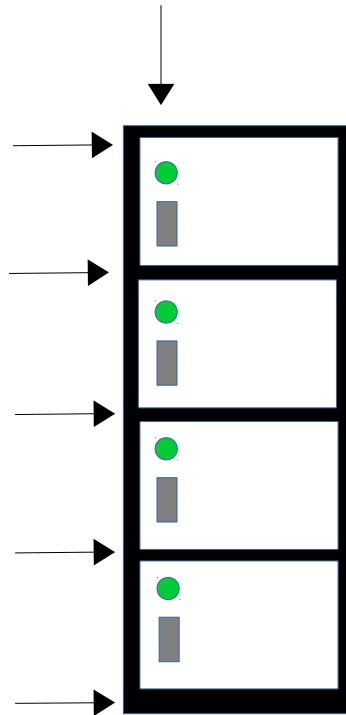
- Relay override:

Connect the center terminal to the wired terminal with a metal contact of the relay board contained in the control box. Make sure 12v power reaches the relay circuit.



- Cabinet dismantle:

With a hex key, dismantle the cabinet from the side nearest to the handle as to avoid impacting the wiring.



- Troubleshoot Diagnoses:

- a) Issues:

- Lock will not release using the relay override technique.
 - See *cabinet wiring issues* and *control box wiring issues*.
 - Button lights up green and red.
 - See *cabinet wiring issues* and *control box wiring issues*.
 - Locker keeps power cycling (turns on and off continuously)
 - See *power issues*.
 - One or both colors do not show.
 - Light can be lit directly from door panel? (see *circuit design* and *assembly notes*)
 - Yes: See *cabinet wiring issues* and *control box wiring issues*.
 - No: See *circuit design* and *assembly notes* to replace lights.

- b) Checks & Fixes

- Cabinet wiring issues

A wire may be severed or the panel connector between the door and main frame may be disconnected. Inspect for any tampering or disconnected panel connections. To test for severed wires, use a multimeter's continuity tester feature to check for connections between control box and panels. (see *circuit design* and *assembly notes*)

- Control box issues

Unscrew nuts and check no connectors were disconnected. NOTE: some wires have little slack; remove top cover gently. (see *circuit design* and *assembly notes*)

- Power Issues

Two particular things can cause this. 1) If the solenoid lock is replaced/damaged and a diode is not connected between the voltage line and ground lines (see circuit diagram). 2) . An exposed wire/connector is shorting cause the board to restart.

Circuit Design:

TBD

Source Code:

```
#define LED_D 13 //bottom
#define LED_C 12
#define LED_B 11
#define LED_A 10 //top
#define B_EN_D 9
#define B_EN_C 8 //back button
#define B_EN_B 7 //front button
#define B_EN_A 6 //priority set(control panel)

#define LCK_D 5 //bottom
#define LCK_C 4
#define LCK_B 3
#define LCK_A 2 //top
#define B_IN_D 3
#define B_IN_C 2
#define B_IN_B 1
#define B_IN_A 0
#define LOCKED 0
#define UNLOCKED 1
#define TAKEN 1
#define OPEN 0
#define LOOPS_TO_HR 36000
#define WATHCHDOG_LIMIT 50 //5 seconds limit

#define ACTIVE_LOW_RELAY

struct QuadState
{
    bool s[4];
};
struct QuadCount
{
    int c[4];
};

//lock access (TAKEN/OPEN)
QuadState gLockLed;
//current state of lock(LOCKED/UNLOCKED)
QuadState gLock;
//button state (per poll per set)
QuadState gBtn;

//avoid holding solenoid lock if button jams in
QuadState gWatchDogHit;
QuadCount gWatchDogCnt;
```

```

//how many hours till locking
unsigned short gLkTmr;
//no available pins to allow for interrupt based timer.
//keep track of hours by counting loops
unsigned int gHrTmr;
//perserve last state of button/switch to trigger event on changed state
bool gLastTToggle; //for changing time
bool gLastLToggle; //for locking/unlocking all in admin mode
bool gLastAMode; //check if admin mode was just entered

//TODO: add watchdog timer for held lock buttons

void setup()
{
    // Initialize the digital pin as an output.
    for(int i = 6; i < 14; i++)
    {
        pinMode(i, OUTPUT);
        digitalWrite(i, 0);
    }
    for(int i = 0; i < 4; i++)
    {
        pinMode(i+LCK_A, OUTPUT);
#ifdef ACTIVE_LOW_RELAY
        digitalWrite(i+LCK_A, 1);
#else
        digitalWrite(i+LCK_A, 0);
#endif
    }

    Serial.begin(9600);
    Serial.println("LOCKER STARTING UP....");

    /*  Debug code
    //startup debug blink
    for(int d = 0; d < 4; d++)
    {
        for(int t = 0; t < 4; t++)
        {
            delay(500);
            for(int i = LED_A; i <= LED_D; i++) { digitalWrite(i, LOCKED); }
            delay(500);
            debugBtnShow(d);
            //for(int i = LED_A; i <= LED_D; i++) { digitalWrite(i, UNLOCKED); }
        }
    }
    */

```

```

//set default values
for(int i = 0; i < 4; i++)
{
    gLock.s[i] = LOCKED;
    gLockLed.s[i] = TAKEN;
}

gLkTmr = 4;

gLastTToggle = false;
gLastLToggle = false;
gLastAMode = false;

gHrTmr = LOOPS_TO_HR;

//start watchdog with clean slate (no open locks)
watchdogTick();

showLockState();
Serial.println("SYSTEM INITIALIZED....");
}

void loop()
{
    bool adminMode = false;
    bool activeTimer = false;
    bool toggleLock = false;

//button routines=====
//admin setup-----
delay(25);
readBtn(0);
adminMode = gBtn.s[0];
activeTimer = gBtn.s[1];
toggleLock = gBtn.s[2];

if(activeTimer && adminMode && (gLkTmr == 0))
{
    gLkTmr = 4;
}
else if(!activeTimer)
{
    gLkTmr = 0;
}

if((adminMode) && (toggleLock != gLastLToggle) && gLastAMode)
{
    setAllState(toggleLock ? TAKEN : OPEN);
}
gLastLToggle = toggleLock;
gLastAMode = adminMode;

```

```

//front button-----
delay(25);
readBtn(1);
if(adminMode)
{
    for(int i = 0; i < 4; i++)
    {
        gLock.s[i] = gBtn.s[i];
    }
}
else
{
    for(int i = 0; i < 4; i++)
    {
        gLock.s[i] = gBtn.s[i] && (gLockLed.s[i] == OPEN);
    }
}

//rear button-----
delay(25);
readBtn(2);
for(int i = 0; i < 4; i++)
{
    if(adminMode) { gLockLed.s[i] &= !gBtn.s[i]; }
    else { gLockLed.s[i] |= gBtn.s[i]; }
}
if(adminMode)
{
    if(activeTimer && !gLastTToggle && gBtn.s[0])
    {
        toggleTimer();
    }
    gLastTToggle = gBtn.s[0];
}
else { gLastTToggle = false; }

//for future improvements/debug -----
delay(25);
readBtn(3);
//add code as needed

//show results =====
//display state
if(adminMode)
{
    showTimerState();
}
else
{
    showLockState();
}

watchdogTick();

```

```

triggerLock();

//check for timer event (reaching an hour)
gHrTmr--;
if(!gHrTmr)
{
    hrHit();
}
}

void watchdogTick()
{
    for(int i = 0; i < 4; i++)
    {
        if(gWatchDogHit.s[i])
        {
            if(!gLock.s[i]) { gWatchDogCnt.c[i] = 0; }
        }
        else
        {
            gWatchDogCnt.c[i] = gLock.s[i] ? gWatchDogCnt.c[i]+1 : 0;
        }

        gWatchDogHit.s[i] = (gWatchDogCnt.c[i] >= WATHCHDOG_LIMIT);
    }
}

void showTimerState()
{
    for(int i = 0; i < 4; i++)
    {
        digitalWrite(i+LED_A, gLkTmr > i ? LOW : HIGH);
    }
}

void showLockState()
{
    for(int i = 0; i < 4; i++)
    {
        digitalWrite(i+LED_A, gLockLed.s[i]);
    }
}

void debugBtnShow(unsigned int set)
{
    readBtn(set);
    gLockLed = gBtn;
    showLockState();
}

```

```

void triggerLock()
{
    for(int i = 0; i < 4; i++)
    {
#ifdef ACTIVE_LOW_RELAY
        digitalWrite(i+LCK_A, !(gLock.s[i] && !gWatchDogHit.s[i]));
#else
        digitalWrite(i+LCK_A, (gLock.s[i] && !gWatchDogHit.s[i]));
#endif
    }
}

void readBtn(unsigned int set)
{
    //disable all sets and reset state
    for(int i = 0; i < 4; i++)
    {
        digitalWrite(B_EN_A+i, 0);
        gBtn.s[i] = false;
    }

    //if valid set, read in buttons
    if(set < 4)
    {
        digitalWrite(B_EN_A+set, 1);
        for(int i = 0; i < 4; i++) { gBtn.s[i] = analogRead(i+B_IN_A) > 111; }
    }
}

void toggleTimer()
{
    gLkTmr = (gLkTmr + 4) % 5;
}

void enableTimer(bool en)
{
    if(en)
    {
        gLkTmr = 4;
    }
    else
    {
        gLkTmr = 0;
    }
}

void setAllState(bool takenState)
{
    for(int i = 0; i < 4; i++)
    {
        gLockLed.s[i] = takenState;
    }
}

```

```
void hrHit()
{
    gHrTmr = LOOPS_TO_HR;

    if(gLkTmr)
    {
        gLkTmr--;
        if(!gLkTmr)
        {
            setAllState(TAKEN);
        }
    }
}
```


Fabrication Notes:

Upgrade Notes:

Currently a breadboard is used to connect all components between the micro-controller and hardware. Producing a PCB with the necessary pull down resistors for the button read in as well as the diode circuitry for the button enable lines and slots for connecting wires.

Contact Info:

Developer: Jerry Z.

Email: open_help@zsoftdevelopment.com