

Cypress CyAPI Programmer's Reference

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Table of Contents

Part I Overview	9
Part II Library Class Hierarchy	10
Part III USB3.0 Support Overview	11
Part IV CCyBulkEndPoint	12
1 BeginDataXfer().....	13
2 CCyBulkEndPoint().....	14
3 CCyBulkEndPoint().....	15
Part V CCyControlEndPoint	16
1 BeginDataXfer().....	17
2 CCyControlEndPoint().....	19
3 CCyControlEndPoint().....	20
4 Direction.....	21
5 Index.....	22
6 Read().....	23
7 ReqCode.....	24
8 ReqType.....	25
9 Target.....	26
10 Value	27
11 Write().....	28
Part VI CCyInterruptEndPoint	29
1 BeginDataXfer().....	30
2 CCyInterruptEndPoint().....	31
3 CCyInterruptEndPoint().....	32
Part VII CCylsocEndPoint	33
1 BeginDataXfer().....	34
2 CCylsocEndPoint().....	36
3 CCylsocEndPoint().....	37
4 CreatePktInfos().....	38
Part VIII CCylsoPktInfo	40

Part IX CCyFX3Device 42

- 1 DownloadFw()..... 43
- 2 IsBootLoaderRunning()..... 45

Part X CCyUSBDevice 46

- 1 AltIntfc()..... 47
- 2 AltIntfcCount()..... 48
- 3 bHighSpeed..... 49
- 4 bSuperSpeed..... 50
- 5 BcdDevice..... 51
- 6 BcdUSB..... 52
- 7 BulkInEndPt..... 53
- 8 BulkOutEndPt..... 54
- 9 CCyUSBDevice()..... 55
- 10 ~CCyUSBDevice()..... 58
- 11 Close()..... 59
- 12 Config()..... 60
- 13 ConfigAttrib..... 61
- 14 ConfigCount()..... 62
- 15 ConfigValue..... 63
- 16 ControlEndPt..... 64
- 17 DevClass..... 65
- 18 DeviceCount()..... 66
- 19 DeviceHandle()..... 67
- 20 DeviceName..... 68
- 21 DevProtocol..... 69
- 22 DevSubClass..... 70
- 23 DriverGUID()..... 71
- 24 DriverVersion..... 72
- 25 EndPointCount()..... 73
- 26 EndPointOf()..... 74
- 27 EndPoints..... 75
- 28 FriendlyName..... 76
- 29 GetDeviceDescriptor()..... 77
- 30 GetBosDescriptor()..... 78
- 31 GetBosUSB20DeviceExtensionDescriptor()..... 79
- 32 GetBosContainerIDDescriptor()..... 80
- 33 GetBosSSCapabilityDescriptor()..... 81
- 34 GetConfigDescriptor()..... 82

35	GetIntfcDescriptor().....	83
36	GetUSBConfig().....	84
37	Interface().....	87
38	InterruptInEndPt.....	88
39	InterruptOutEndPt.....	89
40	IntfcClass.....	90
41	IntfcCount().....	91
42	IntfcProtocol.....	92
43	IntfcSubClass.....	93
44	IsocInEndPt.....	94
45	IsocOutEndPt.....	95
46	IsOpen().....	96
47	Manufacturer.....	97
48	MaxPacketSize.....	98
49	MaxPower.....	99
50	NtStatus.....	100
51	Open().....	101
52	PowerState().....	102
53	Product.....	103
54	ProductID.....	104
55	ReConnect().....	105
56	Reset().....	106
57	Resume().....	107
58	SerialNumber.....	108
59	SetConfig().....	109
60	SetAltIntfc().....	110
61	StrLangID.....	111
62	Suspend().....	112
63	USBAddress.....	113
64	USBDIVersion.....	114
65	UsbdStatus.....	115
66	UsbdStatusString().....	116
67	VendorID.....	117
Part XI CCyUSBConfig		118
1	AltInterfaces.....	121
2	bConfigurationValue.....	122
3	bDescriptorType.....	123
4	bLength.....	124
5	bmAttributes.....	125

6	bNumInterfaces.....	126
7	CCyUSBConfig().....	127
8	CCyUSBConfig().....	128
9	CCyUSBConfig().....	129
10	~CCyUSBConfig.....	130
11	iConfiguration.....	131
12	Interfaces.....	132
13	wTotalLength.....	135

Part XII CCyUSBEndPoint 136

1	Abort().....	137
2	Address.....	138
3	Attributes.....	139
4	BeginDataXfer().....	140
5	bln	142
6	CCyUSBEndPoint().....	143
7	CCyUSBEndPoint().....	144
8	CCyUSBEndPoint().....	145
9	DscLen.....	146
10	DscType.....	147
11	GetXferSize().....	148
12	FinishDataXfer().....	149
13	hDevice.....	151
14	Interval.....	152
15	MaxPktSize.....	153
16	NtStatus.....	154
17	Reset().....	155
18	SetXferSize().....	156
19	TimeOut.....	157
20	UsbdStatus.....	158
21	WaitForXfer().....	159
22	XferData().....	160
23	ssdscLen.....	161
24	ssdscType.....	162
25	ssmaxburst.....	163
26	ssbmAttribute	164
27	ssbytesperinterval	165

Part XIII CCyUSBInterface 166

1	bAlternateSetting.....	169
---	------------------------	-----

2	bAltSettings.....	170
3	bDescriptorType.....	171
4	CCyUSBInterface().....	172
5	CCyUSBInterface().....	173
6	bInterfaceClass.....	174
7	bInterfaceNumber.....	175
8	bInterfaceProtocol.....	176
9	bInterfaceSubClass.....	177
10	bLength.....	178
11	bNumEndpoints.....	179
12	EndPoints.....	180
13	iInterface.....	183
Part XIV CCyUSBBOS		184
1	pContainer_ID.....	187
2	pUSB20_DeviceExt.....	188
3	pSS_DeviceCap.....	189
4	bLength.....	190
5	bDescriptorType.....	191
6	wTotalLength.....	192
7	bNumDeviceCaps.....	193
Part XV CCyBOSUSB20Extesnion		194
1	bLength.....	195
2	bDescriptorType.....	196
3	bDevCapabilityType.....	197
4	bmAttribute.....	198
Part XVI CCyBOSSuperSpeedCapability		199
1	bLength.....	201
2	bDescriptorType.....	202
3	bDevCapabilityType.....	203
4	bmAttribute.....	204
5	SpeedsSuported.....	205
6	bFunctionalitySupport.....	206
7	bU1DevExitLat.....	207
8	bU2DevExitLat.....	208
Part XVII CCyBOSContainerID		209
1	bLength.....	210
2	bDescriptorType.....	211

3	bDevCapabilityType.....	212
4	bReserved.....	213
5	ContainerID.....	214
Part XVIII	USB_BOS_USB20_DEVICE_EXTENSION	215
Part XIX	USB_BOS_SS_DEVICE_CAPABILITY	216
Part XX	USB_BOS_CONTAINER_ID	217
Part XXI	USB_BOS_DESCRIPTOR	218
Part XXII	FX3_FWDWNLOAD_MEDIA_TYPE	219
Part XXIII	FX3_FWDWNLOAD_ERROR_CODE	220
Part XXIV	How to Link with CyAPI.lib	221
Part XXV	Features Not Supported	222
	Index	223

1 Overview

Library Overview

[Top](#) [Next](#)

CyAPI.lib provides a simple, powerful C++ programming interface to USB devices. More specifically, it is a C++ class library that provides a high-level programming interface to the **CyUsb3.sys** device driver. The library is only able to communicate with USB devices that are served by (i.e. bound to) this driver.

Rather than communicate with the driver via Windows API calls such as *SetupDiXxxx* and *DeviceIoControl*, applications can call simpler CyAPI methods such as [Open](#), [Close](#), and [XferData](#) to communicate with these USB devices.

To use the library, you need to include the header file, **CyAPI.h**, in files that access the **CCyUSBDevice** class. In addition, the statically linked **CyAPI.lib** file must be linked to your project. Versions of the .lib files are available for use with Microsoft Visual Studio 2008.

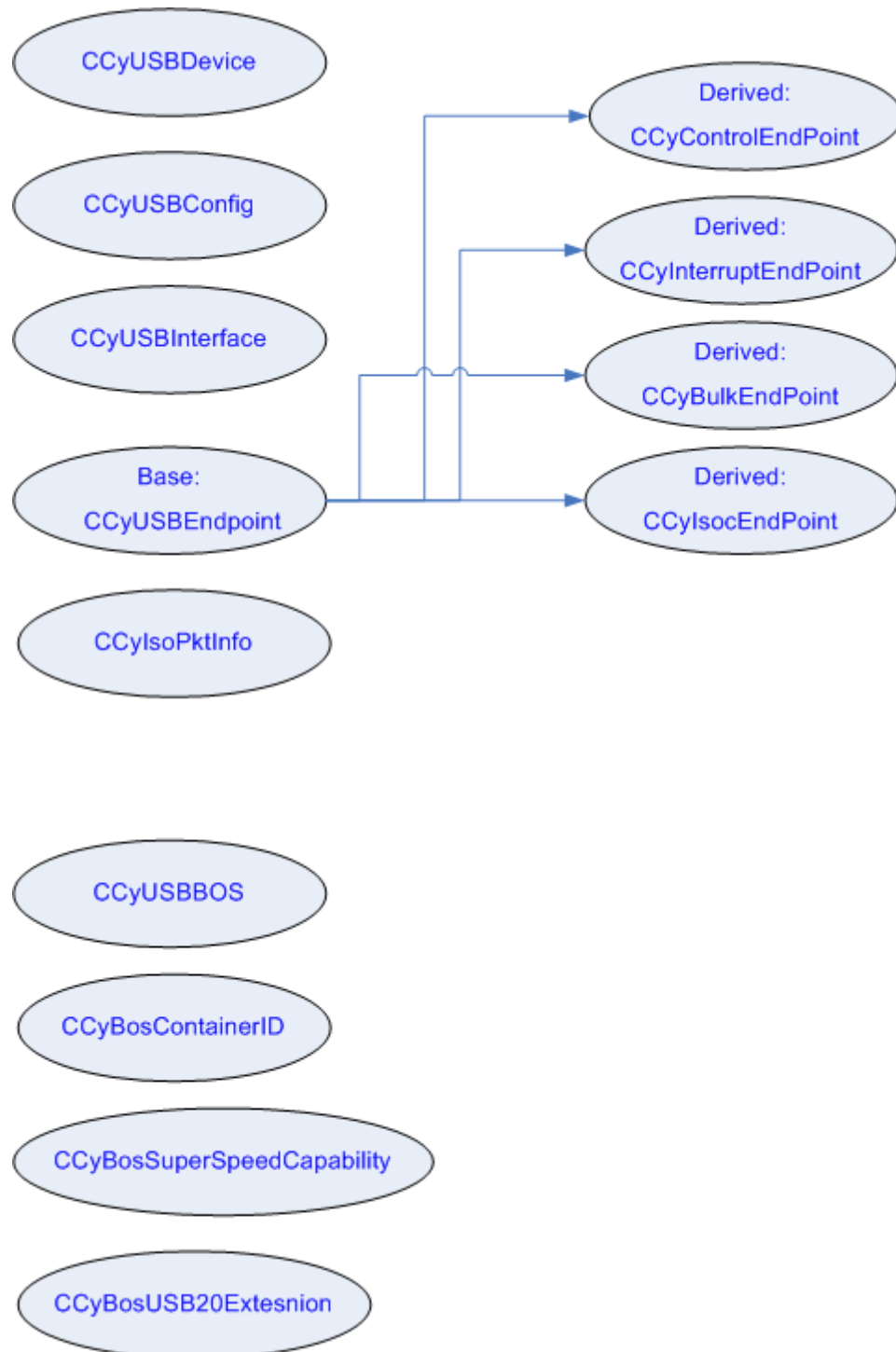
The library employs a **Device and EndPoints** use model. To use the library you must [create an instance](#) of the **CCyUSBDevice** class using the **new** keyword. A **CCyUSBDevice** object knows [how many USB devices](#) are attached to the **CyUsb3.sys** driver and can be made to abstract any one of those devices at a time by using the [Open](#) method. An instance of **CCyUSBDevice** exposes several methods and data members that are device-specific, such as [DeviceName](#), [DevClass](#), [VendorID](#), [ProductID](#), and [SetAltIntfc](#).

When a **CCyUSBDevice** object is open to an attached USB device, its [endpoint](#) members provide an interface for performing data transfers to and from the device's endpoints. Endpoint-specific data members and methods such as [MaxPktSize](#), [TimeOut](#), [bIn](#), [Reset](#) and [XferData](#) are only accessible through endpoint members of a **CCyUSBDevice** object.

In addition to its simplicity, the class library facilitates creation of sophisticated applications as well. The **CCyUSBDevice** [constructor](#) automatically registers the application for Windows USB Plug and Play event notification. This allows your application to support "hot plugging" of devices. Also, the asynchronous [BeginDataXfer/WaitForXfer/FinishDataXfer](#) methods allow queuing of multiple data transfer requests on a single endpoint, thus enabling high performance data streaming from the application level.

2 Library Class Hierarchy

The class hierarchy diagram shown below illustrates the C++ CyAPI library interface classes.



3 USB3.0 Support Overview

USB3.0 Support Overview

[Top](#) [Previous](#) [Next](#)

Description

The Binary Device Object Store(BOS) descriptor defines a root descriptor that is similar to the configuration descriptor and a base descriptor for accessing a family of related descriptors. A host can read the wTotalLength field of the BOS descriptor to find the length of the device level descriptor set.

API

All BOS support APIs are incorporated in the [CCyUSBDevice](#) class.

[GetBosDescriptor\(\)](#)

[GetBosContainerIDDescriptor\(\)](#)

[GetBosSSCapabilityDescriptor\(\)](#)

[GetBosUSB20DeviceExtensionDesc\(\)](#)

Data Structure

All BOS data structure definitions are defined in the USB30_def.h header file.

[USB_BOS_DESCRIPTOR](#)

[USB_BOS_CONTAINER_ID](#)

[USB_BOS_SS_DEVICE_CAPABILITY](#)

[USB_BOS_USB20_DEVICE_EXTENSION](#)

Classes

All BOS class definitions are defined in the CyAPI.h header file.

[CCyUSBBOS](#)

[CCyBOSContainerID](#)

[CCyBOSSuperSpeedCapability](#)

[CCyBOSUSB20Extension](#)

Device Speed

Super speed variable is defined in the [CCyUSBDevice](#) class.

[bSuperSpeed](#)

SuperSpeed Endpoint Companion descriptor

All Superspeed endpoint companion descriptor data variable definition is incorporated in the [CCyUSBEndPoint](#). The following variables will be initialized with zero if device is USB2.0, and will be set to the the SuperSpeed endpoint companion descriptor values, for USB3.0 devices.

[ssdscLen](#)

[ssdscType](#)

[ssbytesperinterval](#)

[ssbmAttribute](#)

[ssmaxburst](#)

Firmware Download

CyUSB library provides APIs to download a firmware binary to the FX3 device RAM or EEPROM connected to the FX3 device.

[CCyFX3Device](#)

NOTE : Please note that this library does not support USB3.0 bulk streams and power management.

4 CCyBulkEndPoint

CCyBulkEndPoint Class

[Previous](#) [Top](#) [Next](#)

Header

CyUSB.h

Description

CCyBulkEndPoint is a subclass of the CCyUSBEndPoint abstract class. CCyBulkEndPoint exists to implement a bulk-specific [BeginDataXfer\(\)](#) function.

Normally, you should not need to construct any of your own instances of this class. Rather, when an instance of [CCyUSBDevice](#) is created, instances of this class are automatically created for all bulk endpoints as members of that class. Two such members of CCyUSBDevice are [BulkInEndPt](#) and [BulkOutEndPt](#).

Example

```
// Find bulk endpoints in the EndPoints[] array
CCyBulkEndPoint *BulkInEpt = NULL;
CCyBulkEndPoint *BulkOutEpt = NULL;

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
int eptCount = USBDevice->EndPointCount();

for (int i=1; i<eptCount; i++) {
    bool bIn = (( USBDevice->EndPoints[i]->Address & 0x80) == 0x80);
    bool bBulk = ( USBDevice->EndPoints[i]->Attributes == 2);

    if ( bBulk && bIn)
        BulkInEpt = ( CCyBulkEndPoint *) USBDevice->EndPoints[i];
    if ( bBulk && !bIn)
        BulkOutEpt = ( CCyBulkEndPoint *) USBDevice->EndPoints[i];
}
```

4.1 BeginDataXfer()

PCHAR CCyBulkEndPoint::BeginDataXfer(
PCHAR buf, LONG len, OVERLAPPED *ov)

[Previous](#) [Top](#) [Next](#)

Description

BeginDataXfer is an advanced method for performing asynchronous IO. This method sets-up all the parameters for a data transfer, initiates the transfer, and immediately returns, not waiting for the transfer to complete.

BeginDataXfer allocates a complex data structure and returns a pointer to that structure. [FinishDataXfer](#) de-allocates the structure. Therefore, it is imperative that each BeginDataXfer call have exactly one matching FinishDataXfer call.

You will usually want to use the synchronous [XferData](#) method rather than the asynchronous BeginDataXfer/WaitForXfer/FinishDataXfer approach.

Example

```
// This example assumes that the device automatically sends back,
// over its bulk-IN endpoint, any bytes that were received over its
// bulk-OUT endpoint (commonly referred to as a loopback function)

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
OVERLAPPED outOvLap, inOvLap;

outOvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_OUT" );
inOvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_IN" );

unsigned char inBuf[ 128 ];
ZeroMemory( inBuf, 128 );

unsigned char buffer[ 128 ];
LONG length = 128;

// Request the return data before initiating the loopback
UCHAR *inContext = USBDevice->BulkInEndPt->BeginDataXfer( inBuf, length,
&inOvLap );
UCHAR *outContext = USBDevice->BulkOutEndPt->BeginDataXfer( buffer, length,
&outOvLap );

USBDevice->BulkOutEndPt->WaitForXfer( &outOvLap, 100 );
USBDevice->BulkInEndPt->WaitForXfer( &inOvLap, 100 );

USBDevice->BulkOutEndPt->FinishDataXfer( buffer, length, &outOvLap,
outContext );
USBDevice->BulkInEndPt->FinishDataXfer( inBuf, length, &inOvLap, inContext );

CloseHandle( outOvLap.hEvent );
CloseHandle( inOvLap.hEvent );
```

4.2 CCyBulkEndPoint()

CCyBulkEndPoint::CCyBulkEndPoint (void)

[Previous](#) [Top](#) [Next](#)

Description

This is the default constructor for the CCyBulkEndPoint class.

The resulting instance has most of its member variables initialized to zero. The two exceptions are [hDevice](#), which gets set to INVALID_HANDLE_VALUE and [TimeOut](#) which is set to 10,000 (10 seconds).

4.3 CCyBulkEndPoint()

CCyBulkEndPoint::CCyBulkEndPoint (HANDLE
h, PUSB_ENDPOINT_DESCRIPTOR
pEndPointDescriptor)

[Previous](#) [Top](#) [Next](#)

Description

This constructor creates a legitimate CCyBulkEndPoint object through which bulk transactions can be performed on the endpoint.

The constructor is called by the library, itself, in the process of performing the [Open](#)() method of the CCyUSBDevice.

You should never need to invoke this constructor. Instead, you should use the CCyBulkEndPoint objects created for you by the CCyUSBDevice class and accessed via its [EndPoints](#), [BulkInEndPt](#) and [BulkOutEndPt](#) members.

5 CCyControlEndPoint

CCyControlEndPoint Class

[Previous](#) [Top](#) [Next](#)

Header

CyUSB.h

Description

CCyControlEndPoint is a subclass of the CCyUSBEndPoint abstract class.

Instances of this class can be used to perform control transfers to the device.

Control transfers require 6 parameters that are not needed for bulk, isochronous or interrupt transfers. These are:

[Target](#)

[ReqType](#)

[Direction](#)

[ReqCode](#)

[Value](#)

[Index](#)

All USB devices have at least one Control endpoint, endpoint zero. Whenever an instance of CCyUSBDevice successfully performs its [Open\(\)](#) function, an instance of CCyControlEndPoint called [ControlEndPt](#) is created. Normally, you will use this [ControlEndPt](#) member of CCyUSBDevice to perform all your Control endpoint data transfers.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);

// Obtain the control endpoint pointer
CCyControlEndPoint *ept = USBDevice->ControlEndPt;
unsigned char buf[ 512];
LONG buflen = 512;

// Send a vendor request ( bRequest = 0x05) to the device
ept->Target      = TGT_DEVICE;
ept->ReqType     = REQ_VENDOR;
ept->Direction   = DIR_TO_DEVICE;
ept->ReqCode     = 0x05;
ept->Value       = 1;
ept->Index       = 0;

ZeroMemory( buf, 512);
ept->XferData( buf,  buflen);
```


5.1 BeginDataXfer()

PUCHAR CCyControlEndPoint::BeginDataXfer (
PCHAR buf, LONG len, OVERLAPPED *ov)

[Previous](#) [Top](#) [Next](#)

Description

BeginDataXfer is an advanced method for performing asynchronous IO.

This method sets-up all the parameters for a data transfer, initiates the transfer, and immediately returns, not waiting for the transfer to complete.

BeginDataXfer allocates a complex data structure and returns a pointer to that structure. [FinishDataXfer](#) de-allocates the structure. Therefore, it is imperative that each BeginDataXfer call have exactly one matching FinishDataXfer call.

You will usually want to use the synchronous [XferData](#) method rather than the asynchronous BeginDataXfer/WaitForXfer/FinishDataXfer approach.

Control transfers require six parameters that are not needed for bulk, isochronous or interrupt transfers. These are:

[Target](#)
[ReqType](#)
[Direction](#)
[ReqCode](#)
[Value](#)
[Index](#)

Be sure to set the value of these CCyControlEndPoint members before invoking the BeginDataXfer or [XferData](#) methods.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);

// Get a handle to the control endpoint
CCyControlEndPoint *ept = USBDevice->ControlEndPt;

OVERLAPPED OvLap;
OvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_CTL");

unsigned char buffer[128];
LONG length = 128;
ept->Target = TGT_DEVICE;
ept->ReqType = REQ_VENDOR;
ept->Direction = DIR_TO_DEVICE;
ept->ReqCode = 0x05;
ept->Value = 1;
ept->Index = 0;

// Begin the transfer and wait for it to complete
PUCHAR Context = ept->BeginDataXfer( buffer, length, &OvLap);
```

```
ept->WaitForXfer( &OvLap, 100);  
ept->FinishDataXfer( buffer,  length,  &OvLap, Context);  
  
CloseHandle( OvLap. hEvent);
```

5.2 CCyControlEndPoint()

CCyControlEndPoint::CCyControlEndPoint(void)

[Previous](#) [Top](#) [Next](#)

Description

This is the default constructor for the CCyControlEndPoint class.

It sets the class' data members to:

```
Target      = TGT_DEVICE
ReqType     = REQ_VENDOR
Direction   = DIR_TO_DEVICE
ReqCode     = 0
Value       = 0
Index       = 0
```

5.3 CCyControlEndPoint()

```
CCyControlEndPoint::CCyControlEndPoint(  
HANDLE h, USB_ENDPOINT_DESCRIPTOR  
pEndPointDescriptor)
```

[Previous](#) [Top](#) [Next](#)

Description

This is the primary constructor for the CCyControlEndPoint class.

It sets the class' data members to:

```
Target      = TGT_DEVICE  
ReqType     = REQ_VENDOR  
Direction   = DIR_TO_DEVICE  
ReqCode     = 0  
Value       = 0  
Index       = 0
```

5.4 Direction

CTL_XFER_DIR_TYPE CCyControlEndPoint::
Direction

[Previous](#) [Top](#) [Next](#)

Description

Direction is one of the essential parameters for a Control transfer and a data member of the CCyControlEndPoint class.

Legitimate values for the Direction member are DIR_TO_DEVICE and DIR_FROM_DEVICE.

Unlike Bulk, Interrupt and Isochronous endpoints which are uni-directional (either IN or OUT), the Control endpoint is bi-directional. It can be used to send data to the device or read data from the device. So, the direction of the transaction is one of the fundamental parameters required for each Control transfer.

Direction is automatically set to DIR_TO_DEVICE by the [Write\(\)](#) method. It is automatically set to DIR_FROM_DEVICE by the [Read\(\)](#) method.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

// Get a handle to the control endpoint
CCyControlEndPoint *ept = USBDevice->ControlEndPt;

ept->Target      = TGT_DEVICE;
ept->ReqType     = REQ_VENDOR;
ept->Direction = DIR_TO_DEVICE;
ept->ReqCode     = 0x05;
ept->Value       = 1;
ept->Index       = 0;

unsigned char  buf[ 512 ];
ZeroMemory( buf, 512 );
LONG buflen = 512;

ept->XferData( buf, buflen );
```

5.5 Index

WORD CCyControlEndPoint::Index

[Previous](#) [Top](#) [Next](#)

Description

Index is one of the essential parameters for a Control transfer and a data member of the CCyControlEndPoint class.

Index values typically depend on the specific ReqCode that is being sent in the Control transfer.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

// Get a handle to the control endpoint
CCyControlEndPoint *ept = USBDevice->ControlEndPt;

ept->Target      = TGT_DEVICE;
ept->ReqType     = REQ_VENDOR;
ept->Direction   = DIR_TO_DEVICE;
ept->ReqCode     = 0x05;
ept->Value       = 1;
ept->Index      = 0;

unsigned char  buf[ 512 ];
ZeroMemory( buf, 512 );
LONG buflen = 512;

ept->XferData( buf, buflen );
```

5.6 Read()

```
bool CCyControlEndPoint::Read( PCHAR buf,  
LONG &len)
```

[Previous](#) [Top](#) [Next](#)

Description

Read() sets the CyControlEndPoint [Direction](#) member to DIR_FROM_DEVICE and then calls [CCyUSBEndPoint::XferData](#)().

The **buf** parameter points to a memory buffer where the read bytes will be placed.

The **len** parameter specifies how many bytes are to be read.

Returns **true** if the read operation was successful.

Passes-back the actual number of bytes transferred in the **len** parameter.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);  
  
// Get a handle to the control endpoint  
CCyControlEndPoint *ept = USBDevice->ControlEndPt;  
  
ept->Target = TGT_DEVICE;  
ept->ReqType = REQ_VENDOR;  
ept->ReqCode = 0x07;  
ept->Value = 1;  
ept->Index = 0;  
  
unsigned char buf[ 512];  
LONG bytesToRead = 64;  
  
ept->Read( buf, bytesToRead);
```

5.7 ReqCode

UCHAR CCyControlEndPoint::ReqCode[Previous](#) [Top](#) [Next](#)

Description

ReqCode is one of the essential parameters for a Control transfer and a data member of the CCyControlEndPoint class.

ReqCode values indicate, to the USB chip, a particular function or command that the chip should perform. They are usually documented by the USB chip manufacturer.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

// Get a handle to the control endpoint
CCyControlEndPoint *ept = USBDevice->ControlEndPt;

ept->Target      = TGT_DEVICE;
ept->ReqType     = REQ_VENDOR;
ept->Direction   = DIR_TO_DEVICE;
ept->ReqCode    = 0x05;
ept->Value       = 1;
ept->Index       = 0;

unsigned char  buf[ 512 ];
ZeroMemory( buf, 512 );
LONG buflen = 512;

ept->XferData( buf, buflen );
```


5.8 ReqType

CTL_XFER_REQ_TYPE CCyControlEndPoint::
ReqType

[Previous](#) [Top](#) [Next](#)

Description

ReqType is one of the essential parameters for a Control transfer and a data member of the CCyControlEndPoint class.

Legitimate values for the ReqType member are **REQ_STD**, **REQ_CLASS** and **REQ_VENDOR**.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);

// Get a handle to the control endpoint
CCyControlEndPoint *ept = USBDevice->ControlEndPt;

ept->Target      = TGT_DEVICE;
ept->ReqType    = REQ_VENDOR;
ept->Direction  = DIR_TO_DEVICE;
ept->ReqCode     = 0x05;
ept->Value       = 1;
ept->Index       = 0;

unsigned char  buf[ 512];
ZeroMemory( buf, 512);
LONG buflen = 512;

ept->XferData( buf, buflen);
```

5.9 Target

CTL_XFER_TGT_TYPE CCyControlEndPoint::
Target

[Previous](#) [Top](#) [Next](#)

Description

Target is one of the essential parameters for a Control transfer and a data member of the CCyControlEndPoint class.

Legitimate values for the Target member are **TGT_DEVICE**, **TGT_INTFC**, **TGT_ENDPT** and **TGT_OTHER**.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

// Get a handle to the control endpoint
CCyControlEndPoint *ept = USBDevice->ControlEndPt;

ept->Target      = TGT_DEVICE;
ept->ReqType     = REQ_VENDOR;
ept->Direction   = DIR_TO_DEVICE;
ept->ReqCode     = 0x05;
ept->Value       = 1;
ept->Index       = 0;

unsigned char  buf[ 512 ];
ZeroMemory( buf, 512 );
LONG buflen = 512;

ept->XferData( buf, buflen );
```

5.10 Value

WORD CCyControlEndPoint::Value

[Previous](#) [Top](#) [Next](#)

Description

Value is one of the essential parameters for a Control transfer and a data member of the CCyControlEndPoint class.

Values typically depend on the specific ReqCode that is being sent in the Control transfer.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

// Get a handle to the control endpoint
CCyControlEndPoint *ept = USBDevice->ControlEndPt;

ept->Target      = TGT_DEVICE;
ept->ReqType     = REQ_VENDOR;
ept->Direction   = DIR_TO_DEVICE;
ept->ReqCode     = 0x05;
ept->Value      = 1;
ept->Index       = 0;

unsigned char  buf[ 512 ];
ZeroMemory( buf, 512 );
LONG buflen = 512;

ept->XferData( buf, buflen );
```

5.11 Write()

```
bool CCyControlEndPoint::Write(PCHAR buf,  
LONG &len)
```

[Previous](#) [Top](#) [Next](#)

Description

Write() sets the CyControlEndPoint [Direction](#) member to DIR_TO_DEVICE and then calls [CCyUSBEndPoint::XferData\(\)](#).

The **buf** parameter points to a memory buffer where the read bytes will be placed.

The **len** parameter tells how many bytes are to be read.

Returns **true** if the write operation was successful.

Passes-back the actual number of bytes transferred in the **len** parameter.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );  
  
// Get a handle to the control endpoint  
CCyControlEndPoint *ept = USBDevice->ControlEndPt;  
  
ept->Target    = TGT_DEVICE;  
ept->ReqType   = REQ_VENDOR;  
ept->ReqCode   = 0x07;  
ept->Value     = 1;  
ept->Index     = 0;  
  
unsigned char  buf[ 512];  
ZeroMemory( buf, 512);  
LONG bytesToSend = 128;  
  
// Call the write method to perform the control write transfer  
ept->Write( buf,  bytesToSend);
```

6 CCyInterruptEndPoint

CCyInterruptEndPoint Class

[Previous](#) [Top](#) [Next](#)

Header

CyUSB.h

Description

CCyInterruptEndPoint is a subclass of the [CCyUSBEndPoint](#) abstract class.

CCyInterruptEndPoint exists to implement a interrupt-specific [BeginDataXfer\(\)](#) function.

Normally, you should not need to construct any of your own instances of this class. Rather, when an instance of [CCyUSBDevice](#) is created, instances of this class are automatically created as members of that class. Two such members of CCyUSBDevice are [InterruptInEndPt](#) and [InterruptOutEndPt](#).

Example

```
// Find interrupt endpoints in the EndPoints[] array
CCyInterruptEndPoint *IntInEpt = NULL;
CCyInterruptEndPoint *IntOutEpt = NULL;

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
int eptCount = USBDevice->EndPointCount();

// Check all endpoints and get handles to any interrupt endpoints
for (int i=1; i<eptCount; i++) {
    bool bIn = ((USBDevice->EndPoints[i]->Address & 0x80)==0x80);
    bool bInt = (USBDevice->EndPoints[i]->Attributes == 3);

    if (bInt && bIn)
        IntInEpt = (CCyInterruptEndPoint *) USBDevice->EndPoints[i];
    if (bInt && !bIn)
        IntOutEpt = (CCyInterruptEndPoint *) USBDevice->EndPoints[i];
}
```

6.1 BeginDataXfer()

PUCHAR CCyInterruptEndPoint::BeginDataXfer
(PCHAR buf, LONG len, OVERLAPPED *ov)

[Previous](#) [Top](#) [Next](#)

Description

BeginDataXfer is an advanced method for performing asynchronous IO. This method sets-up all the parameters for a data transfer, initiates the transfer, and immediately returns, not waiting for the transfer to complete.

BeginDataXfer allocates a complex data structure and returns a pointer to that structure. [FinishDataXfer](#) de-allocates the structure. Therefore, it is imperative that each BeginDataXfer call have exactly one matching FinishDataXfer call.

You will usually want to use the synchronous [XferData](#) method rather than the asynchronous BeginDataXfer/WaitForXfer/FinishDataXfer approach.

Example

```
// This example assumes that the device automatically sends back
// over its bulk-IN endpoint, any bytes that were received over its
// bulk-OUT endpoint (commonly referred to as a loopback function)

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
OVERLAPPED outOvLap, inOvLap;

outOvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_OUT" );
inOvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_IN" );

unsigned char inBuf[ 128 ];
ZeroMemory( inBuf, 128 );

unsigned char buffer[ 128 ];
LONG length = 128;

// Request the return data before initiating the loopback
UCHAR *inContext = USBDevice->InterruptInEndPt->BeginDataXfer( inBuf,
length, &inOvLap );
UCHAR *outContext = USBDevice->InterruptOutEndPt->BeginDataXfer( buffer,
length, &outOvLap );

USBDevice->InterruptOutEndPt->WaitForXfer( &outOvLap, 100 );
USBDevice->InterruptInEndPt->WaitForXfer( &inOvLap, 100 );

USBDevice->InterruptOutEndPt->FinishDataXfer( buffer, length, &outOvLap,
outContext );
USBDevice->InterruptInEndPt->FinishDataXfer( inBuf, length, &inOvLap,
inContext );

CloseHandle( outOvLap.hEvent );
CloseHandle( inOvLap.hEvent );
```

6.2 CCyInterruptEndPoint()

```
CCyInterruptEndPoint::CCyInterruptEndPoint (  
void)
```

[Previous](#) [Top](#) [Next](#)

Description

This is the default constructor for the CCyInterruptEndPoint class.

The resulting instance has most of its member variables initialized to zero. The two exceptions are [hDevice](#), which gets set to INVALID_HANDLE_VALUE and [TimeOut](#) which is set to 10,000 (10 seconds).

6.3 CCyInterruptEndPoint()

```
CCyInterruptEndPoint::CCyInterruptEndPoint(  
HANDLE h, PUSB_ENDPOINT_DESCRIPTOR  
pEndPtDescriptor)
```

[Previous](#) [Top](#) [Next](#)

Description

This constructor creates a legitimate CCyInterruptEndPoint object through which interrupt transactions can be performed on the endpoint.

The constructor may be called by the library itself in the process of performing the [Open\(\)](#) method of the CCyUSBDevice.

You should never need to invoke this constructor. Instead, you should use the CCyInterruptEndPoint objects created for you by the CCyUSBDevice class and accessed via its [EndPoints](#), [InterruptInEndPt](#) and [InterruptOutEndPt](#) members.

7 CCyIsocEndPoint

CCyIsocEndPoint Class

[Previous](#) [Top](#) [Next](#)

Header

CyUSB.h

Description

CCyIsocEndPoint is a subclass of the [CCyUSBEndPoint](#) abstract class.

CCyIsocEndPoint exists to implement an isochronous-specific [BeginDataXfer\(\)](#) function.

Normally, you should not need to construct any of your own instances of this class. Rather, when an instance of [CCyUSBDevice](#) is created, instances of this class are automatically created as members of that class. Two such members of CCyUSBDevice are [IsocInEndPt](#) and [IsocOutEndPt](#).

NOTE: For ISOC transfers, the buffer length and the endpoint's transfers size (see SetXferSize) must be a multiple of 8 times the endpoint's MaxPktSize.

Example

```
// Find isoc endpoints in the EndPoints[] array
CCyIsocEndPoint *IsocInEpt = NULL;
CCyIsocEndPoint *IsocOutEpt = NULL;

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
int eptCount = USBDevice->EndPointCount();

// Iterate through all endpoints and pick handles for ISOC endpoints
for (int i=1; i<eptCount; i++) {
    bool bIn = (( USBDevice->EndPoints[i]->Address & 0x80)==0x80);
    bool bInt = ( USBDevice->EndPoints[i]->Attributes == 1);
    if (bInt && bIn)
        IsocInEpt = (CCyIsocEndPoint *) USBDevice->EndPoints[i];
    if (bInt && !bIn)
        IsocOutEpt = (CCyIsocEndPoint *) USBDevice->EndPoints[i];
}
```

7.1 BeginDataXfer()

PUCHAR CCyIsocEndPoint::BeginDataXfer (
PCHAR buf, LONG len, OVERLAPPED *ov)

[Previous](#) [Top](#) [Next](#)

Description

BeginDataXfer is an advanced method for performing asynchronous IO. This method sets-up all the parameters for a data transfer, initiates the transfer, and immediately returns, not waiting for the transfer to complete.

BeginDataXfer allocates a complex data structure and returns a pointer to that structure. [FinishDataXfer](#) de-allocates the structure. Therefore, it is imperative that each BeginDataXfer call have exactly one matching FinishDataXfer call.

You will usually want to use the synchronous [XferData](#) method rather than the asynchronous BeginDataXfer/WaitForXfer/FinishDataXfer approach.

NOTE: For ISOC transfers, the buffer length and the endpoint's transfers size (see SetXferSize) must be a multiple of 8 times the endpoint's MaxPktSize.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
CCyIsocEndPoint *IsoIn = USBDevice->IsocInEndPt;

if (IsoIn) {
    int pkts = 16;
    LONG bufSize = IsoIn->MaxPktSize * pkts;

    PCHAR          context;
    OVERLAPPED      inOvLap;
    PCHAR          buffer      = new UCHAR[ bufSize];
    CCyIsoPktInfo *isoPktInfos = new CCyIsoPktInfo[ pkts];

    IsoIn->SetXferSize( bufSize);
    inOvLap.hEvent = CreateEvent( NULL, false, false, NULL);

    // Begin the data transfer
    context = IsoIn->BeginDataXfer( buffer, bufSize, &inOvLap);

    // Wait for the xfer to complete.
    if (!IsoIn->WaitForXfer( &inOvLap, 1500)) {
        IsoIn->Abort();
        // Wait for the stalled command to complete
        WaitForSingleObject( inOvLap.hEvent, INFINITE);
    }

    int complete = 0;
    int partial = 0;

    // Must always call FinishDataXfer to release memory of contexts[i]
    if (IsoIn->FinishDataXfer( buffer, bufSize, &inOvLap, context,
```

```
isoPktInfos)) {  
  
    // For each packet, check whether the transfer was completed  
    for (int i=0; i< pkts; i++)  
        if (isoPktInfos[i].Status)  
            partial++;  
        else  
            complete++;  
    }  
    else {  
        partial++;  
    }  
  
    delete buffer;  
    delete [] isoPktInfos;  
}
```

7.2 CCylsocEndPoint()

CCylsocEndPoint::CCylsocEndPoint (void)

[Previous](#) [Top](#) [Next](#)

Description

This is the default constructor for the CCylsocEndPoint class.

The resulting instance has most of its member variables initialized to zero. The two exceptions are [hDevice](#), which gets set to INVALID_HANDLE_VALUE and [TimeOut](#) which is set to 10,000 (10 seconds).

7.3 CCylsocEndPoint()

```
CCylsocEndPoint::CCylsocEndPoint(HANDLE h,  
PUSB_ENDPOINT_DESCRIPTOR  
pEndPtDescriptor)
```

[Previous](#) [Top](#) [Next](#)

Description

This constructor creates a legitimate CCylsocEndPoint object through which isochronous transactions can be performed on the endpoint.

The constructor is called by the library itself in the process of performing the [Open\(\)](#) method of the CCyUSBDevice.

You should never need to invoke this constructor. Instead, you should use the CCylsocEndPoint objects created for you by the CCyUSBDevice class and accessed via its [EndPoints](#), [IsocInEndPt](#) and [IsocOutEndPt](#) members.

7.4 CreatePktInfos()

**CCyIsoPktInfo* CCyIsoEndPoint::
CreatePktInfos**(LONG bufLen, int &packets)

[Previous](#) [Top](#) [Next](#)

Description

The **CreatePktInfos** method is provided for convenience.

It creates an array of [CCyIsoPktInfo](#) objects to be used in calls to [XferData](#) and [FinishDataXfer](#) for Isoc endpoints.

CreatePktInfos calculates the number of isoc packets that the driver will use to transfer a data buffer of **bufLen** bytes. This number is returned in the **packets** parameter.

CreatePktInfos also dynamically constructs an array of [CCyIsoPktInfo](#) objects and returns a pointer to the first element of that array. There are **packets** elements in the array.

After using the array of CCyPktInfo objects you must delete the array of objects yourself by calling **delete []**.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice();
CCyIsoEndPoint *IsoIn = USBDevice->IsocInEndPt;

if (IsoIn) {

    LONG    bufSize = 4096;
    UCHAR  buffer = new UCHAR[ bufSize];

    CCyIsoPktInfo *isoPktInfos;
    int  pkts;

    // Allocate the IsoPktInfo objects, and find-out how many were
    allocated
    isoPktInfos = IsoIn->CreatePktInfos( bufSize, pkts);

    // Request the transfer and identify how much data got transferred
    if (IsoIn->XferData( buffer, bufSize, isoPktInfos)) {

        LONG recvdBytes = 0;

        for (int i=0; i<pkts; i++) {
            if (isoPktInfos[ i].Status == 0) {
                recvdBytes += isoPktInfos[ i].Length;
            }
        }

        // Free the buffer and IsoPktInfo array
        delete [ ] buffer;
        delete [ ] isoPktInfos;
    }
}
```

}

8 CCyIsoPktInfo

CCyIsoPktInfo

[Previous](#) [Top](#) [Next](#)

The **CCyIsoPktInfo** class is defined as:

```
class CCyIsoPktInfo {
public:
    LONG Status;
    LONG Length;
};
```

When an Isochronous data transfer is performed, the data buffer passed to [XferData](#) or [BeginDataXfer](#) is logically partitioned by the driver into multiple packets of data. The driver returns status and length information for each of those packets.

The [XferData](#) and [FinishDataXfer](#) methods of [CCyUSBEndPoint](#) accept an optional parameter that is a pointer to an array of **CCyIsoPktInfo** objects. If this parameter is not NULL, the array will be filled with the packet status and length information returned by the driver.

If the value returned in the **Status** field is zero (USB_D_STATUS_SUCCESS) all the data in the packet is valid. Other non-zero values for the Status field can be found in the Windows Driver Development Kit (DDK) include file, USBDI.H.

The value returned in the **Length** field indicates the number of bytes transferred in the packet. Under ideal conditions, this number will be `bufferLength / numPackets` (which is the maximum capacity of each packet). However, it is possible that fewer bytes could be transferred in any or all of the packets.

An array of **CCyIsoPktInfo** objects can be easily created by invoking the [CCyUSBIsocEndPoint::CreatePktInfos](#) method.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice();
CCyIsocEndPoint *IsoIn = USBDevice->IsocInEndPt;

if (IsoIn) {

    LONG    bufSize = 4096;
    PCHAR buffer = new UCHAR[ bufSize];

    CCyIsoPktInfo *isoPktInfos;
    int pkts;

    // Allocate the IsoPktInfo objects, and find-out how many were
    allocated
    isoPktInfos = IsoIn->CreatePktInfos(bufSize, pkts);

    // Request the transfer and identify how much data got transferred
    if (IsoIn->XferData(buffer, bufSize, isoPktInfos)) {
```



```
    LONG recvdBytes = 0;

    for (int i=0; i<pkts; i++) {
        if (isoPktInfos[i].Status == 0) {
            recvdBytes += isoPktInfos[i].Length;
        }
    }

    // Free the buffer and IsoPktInfo array
    delete [] buffer;
    delete [] isoPktInfos;
}
```

9 CCyFX3Device

CCyFX3Device

[Top](#) [Previous](#) [Next](#)

Description

API defined for this class will work with the FX3 boot devices only. The behaviour of each API is undefined for non-boot FX3 devices.

CCyFX3Device extends the functionality of [CCyUSBDevice](#) by adding methods to download firmware to the Cypress FX3 boot devices.

Note that any [CCyUSBDevice](#) class object can be cast into a CCyFX3Device object. However, only those that represent actual FX3 boot devices will function properly when the [DownloadFw](#) method of CCyFX3Device is invoked.

Please use the [CCyUSBDevice](#) class instead of CCyFX3Device class for non-boot devices.

Example

Example#1 Get instance for FX3-boot device and download a firmware binary to the device RAM.

```
CCyFX3Device *m_usbDevice = new CCyFX3Device();
FX3_FWDWNLOAD_ERROR_CODE dwld_status = FAILED;

// Open first USB device
if( m_usbDevice->Open(0))
{
    //Check if boot loader is running.
    status = m_usbDevice->IsBootLoaderRunning();
    if(status)
    {
        // Download the file C:\Bulkloop.img file to FX3 device RAM
        dwld_status = m_usbDevice->DownloadFw( "C:\Bulkloop.img", RAM)
    }
}
```

Example#2 Get instance for FX3 non-boot device.

Refer to the example code on page [CCyUSBDevice](#)

9.1 DownloadFw()

FX3_FWDWNLOAD_ERROR_CODE CCyFX3Device::

[Top](#) [Previous](#) [Next](#)

DownloadFw (char *fileName, FX3_FWDWNLOAD_MEDIA_TYPE enMediaType)

Description

The DownloadFw method of CCyFX3Device allows the user to download firmware to various media (RAM, I2C E2PROM and SPI FLASH) associated with a FX3 device.

The file name of the firmware file (*.img file format file only) is passed as the first parameter to the API.

The second parameter defines the Media Type using members of [FX3_FWDWNLOAD_MEDIA_TYPE](#)

The API returns a [FX3_FWDWNLOAD_ERROR_CODE](#) return code.

Examples:

NOTE : The sample example code provided is only a guideline and is not ready to compile code.

Example#1 Sample code for downloading FX3 firmware to RAM

```
CCyFX3Device *m_usbDevice = new CCyFX3Device();
FX3_FWDWNLOAD_ERROR_CODE dwld_status = FAILED;

if( m_usbDevice->Open(0))
{
    //Check if boot loader is running.
    status = m_usbDevice->IsBootLoaderRunning();
    if( status)
    {
        // Download the file C:\Bulkloop.img to FX3 device RAM
        dwld_status = m_usbDevice->DownloadFw( "C:\Bulkloop.img", RAM);
    }
}
```

Example#2 Sample code for downloading FX3 firmware to I2C E2PROM

Step 1 First Download the Boot Programmer IMG file to RAM. The CyBootProgrammer.img file is available in the Cypress SS USBSuite installation directory: \Cypress USBSuite\bin\CyBootProgrammer.img

```
CCyFX3Device *m_usbDevice = new CCyFX3Device();
FX3_FWDWNLOAD_ERROR_CODE dwld_status = FAILED;

if( m_usbDevice->Open(0))
{
    //Check if boot loader is running.
    status = m_usbDevice->IsBootLoaderRunning();
    if( status)
    {
        // Download the boot programmer IMG file to RAM first
        dwld_status = m_usbDevice->DownloadFw( "\Cypress
```

```

USBSuite\bin\CyBootProgrammer.img", RAM);
    }
}

```

Step 2 Download actual IMG file to the I2C E2PROM.

Note: After downloading the boot programmer firmware, the device will be re-enumerated with different VID/PID. First time users will need to install the driver from the Cypress USBSuite\driver\bin\ directory for the boot programmer.

```

CCyFX3Device *m_usbDevice = new CCyFX3Device();
FX3_FWDNLOAD_ERROR_CODE dwld_status = FAILED;

if(m_usbDevice->Open(0))
{
    // Download the Bulkloop IMG file to I2C E2PROM first
    dwld_status = m_usbDevice->DownloadFw("C:\Bulkloop.IMG", I2CE2PROM);
}

```

Example#3 Sample code for downloading FX3 firmware to SPI FLASH

Step 1 First Download the Boot Programmer IMG file to RAM. The CyBootProgrammer.img file is available in the Cypress SS USBSuite installation directory \Cypress USBSuite\bin\CyBootProgrammer.img

```

CCyFX3Device *m_usbDevice = new CCyFX3Device();
FX3_FWDNLOAD_ERROR_CODE dwld_status = FAILED;

if(m_usbDevice->Open(0))
{
    //Check if boot loader is running.
    status = m_usbDevice->IsBootLoaderRunning();
    if(status)
    {
        // Download the boot programmer IMG file to RAM first
        dwld_status = m_usbDevice->DownloadFw("\Cypress
USBSuite\bin\CyBootProgrammer.img", RAM);
    }
}

```

Step 2 Download actual IMG file to SPI FLASH.

Note: After downloading the boot programmer firmware, the device will be re-enumerated with different VID/PID. First time users will need to install the driver from the Cypress USBSuite\driver\bin\ directory for the boot programmer.

```

CCyFX3Device *m_usbDevice = new CCyFX3Device();
FX3_FWDNLOAD_ERROR_CODE dwld_status = FAILED;

if(m_usbDevice->Open(0))
{
    // Download the Bulkloop IMG file to I2C E2PROM first
    dwld_status = m_usbDevice->DownloadFw("C:\Bulkloop.IMG", SPIFLASH);
}

```

9.2 IsBootLoaderRunning()

bool IsBootLoaderRunning (void)

[Top](#) [Previous](#) [Next](#)

Description

The IsBootLoaderRunning function sends a vendor command to check the FX3 boot loader status. If boot loader is running, then it will return true; otherwise false.

Example

```
CCyFX3Device *m_usbDevice = new CCyFX3Device();
FX3_FWDLNLOAD_ERROR_CODE dwld_status = FAILED;

if( m_usbDevice->Open(0))
{
    //Check if boot loader is running.
    status = m_usbDevice->IsBootLoaderRunning();
    if( status)
    {
        // Download the file C:\Bulkloop.img to FX3 device RAM
        dwld_status = m_usbDevice->DownloadFw( "C:\Bulkloop.img", RAM);
    }
}
```

10 CCyUSBDevice

CCyUSBDevice Class

[Previous](#) [Top](#) [Next](#)

Header

CyUSB.h

Description

The CCyUSBDevice class is the primary entry point into the CyAPI library. All the functionality of the library should be accessed via an instance of CCyUSBDevice.

Create an instance of CCyUSBDevice using the **new** keyword.

An instance of CCyUSBDevice is aware of all the USB devices that are attached to the USB driver and can selectively communicate with any ONE of them by using the [Open\(\)](#) method.

Example

```
// Create an instance of CCyUSBDevice
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);

// Look for a device having VID = 04b4, PID = 00f1
int devices = USBDevice->DeviceCount();
int vID, pID;
int d = 0;

do {
    // Open() automatically calls Close() if necessary
    USBDevice->Open( d);
    vID = USBDevice->VendorID;
    pID = USBDevice->ProductID;
    d++;
} while ((d < devices) && (vID != 0x04b4) && (pID != 0x00f1));
```

10.1 AltIntfc()

UCHAR CCyUSBDevice::AltIntfc(void)

[Previous](#) [Top](#) [Next](#)

Description

This function returns the current alternate interface setting for the device. A return value of 255 (0xFF) indicates that the driver failed to return the current alternate interface setting.

Note:

As Windows represents each USB device interface as a separate device, the interface number need not be specified.

Call [SetAltIntfc\(\)](#) to select a different alternate interface (changing the AltSetting).

Call [AltIntfcCount\(\)](#) to find-out how many alternate interfaces are exposed by the device.

10.2 AltIntfcCount()

UCHAR CCyUSBDevice::AltIntfcCount(void)

[Previous](#) [Top](#) [Next](#)

Description

This function returns the number of alternate interfaces exposed by the device.

The primary interface setting (AltSetting == 0) is not counted as an alternate interface.

Example

A return value of 2 means that there are 2 alternate interfaces, in addition to the primary interface. Legitimate parameter values for calls to [SetAltIntfc\(\)](#) would then be 0, 1 and 2.

10.3 bHighSpeed

bool CCyUSBDevice::bHighSpeed

[Previous](#) [Top](#) [Next](#)

Description

bHighSpeed indicates whether or not the device is a high speed USB device.

If the USB device represented is a high speed device, **bHighSpeed** will be **true**. Otherwise, **bHighSpeed** will be **false**.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );  
if ( USBDevice->bHighSpeed) {  
    // Do something  
}
```

10.4 bSuperSpeed

bool CCyUSBDevice::bSuperSpeed

[Previous](#) [Top](#) [Next](#)

Description

bSuperSpeed indicates whether or not the device is a USB Super Speed (USB 3.0) device.

If the USB device represented is a Super Speed device, **bSuperSpeed** will be **true**. Otherwise, **bSuperSpeed** will be **false**.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);  
if ( USBDevice->bSuperSpeed) {  
    // Do something  
}
```

10.5 BcdDevice

USHORT CCyUSBDevice::BcdDevice

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of the **bcdDevice** member from the device's USB device descriptor structure.

10.6 BcdUSB

USHORT CCyUSBDevice::BcdUSB

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of the **bcdUSB** member from the device's USB device descriptor structure.

10.7 BulkInEndPt

**CCyBulkEndPoint* CCyUSBDevice::
BulkInEndPt**

[Previous](#) [Top](#) [Next](#)

Description

BulkInEndPt is a pointer to an object representing the first BULK IN endpoint enumerated for the selected interface.

The selected interface might expose additional BULK IN endpoints. To discern this, one would need to traverse the [EndPoints](#) array, checking the [Attributes](#) and [Address](#) members of each [CCyUSBEndPoint](#) object referenced in the array.

If no BULK IN endpoints were enumerated by the device, BulkInEndPt will be set to NULL.

Example

```
// Find a second bulk IN endpoint in the EndPoints[] array
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
CCyBulkEndPoint *BulkIn2 = NULL;
int eptCount = USBDevice->EndPointCount();

for (int i=1; i<eptCount; i++) {
    bool bIn = USBDevice->EndPoints[ i]->bIn;
    bool bBulk = ( USBDevice->EndPoints[ i]->Attributes == 2);

    if ( bBulk && bIn) {
        BulkIn2 = ( CCyBulkEndPoint *) USBDevice->EndPoints[ i];
        if ( BulkIn2 == USBDevice->BulkInEndPt)
            BulkIn2 = NULL;
    }
}
```

10.8 BulkOutEndPt

**CCyBulkEndPoint* CCyUSBDevice::
BulkOutEndPt**

[Previous](#) [Top](#) [Next](#)

Description

BulkOutEndPt is a pointer to an object representing the first BULK OUT endpoint enumerated for the selected interface.

The selected interface might expose additional BULK OUT endpoints. To discern this, one would need to traverse the [EndPoints](#) array, checking the [Attributes](#) and [Address](#) members of each [CCyUSBEndPoint](#) object referenced in the array.

If no BULK OUT endpoints were enumerated by the device, BulkOutEndPt will be set to NULL.

Example

```
// Find a second bulk OUT endpoint in the EndPoints[] array
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
CCyBulkEndPoint *BulkOut2 = NULL;
int eptCount = USBDevice->EndPointCount();

for (int i=1; i<eptCount; i++) {
    bool bIn = (( USBDevice->EndPoints[ i]->Address & 0x80)==0x80);
    bool bBulk = ( USBDevice->EndPoints[ i]->Attributes == 2);

    if ( bBulk && !bIn) {
        BulkOut2 = ( CCyBulkEndPoint *) USBDevice->EndPoints[ i];
        if ( BulkOut2 == USBDevice->BulkOutEndPt)
            BulkOut2 = NULL;
    }
}
```

10.9 CCyUSBDevice()

```
CCyUSBDevice::CCyUSBDevice(HANDLE hnd =  
NULL, GUID guid = CYUSBDRV_GUID)
```

[Previous](#) [Top](#) [Next](#)

Description

This is the constructor for the CCyUSBDevice class.

It registers the Windows handle *hnd* to receive USB Plug and Play (PnP) messages when devices are connected or disconnected to/from the driver.

The object created serves as the programming interface to the driver whose GUID is passed in the *guid* parameter.

The constructor initializes the class members and then calls the [Open](#)(0) method to open the first device that is attached to the driver.

Parameters

hnd

hnd is a handle to the application's main window (the window whose WndProc function will process USB PnP events).

If you are building a console application or do not want your window to receive PnP events, you may omit the *hnd* parameter.

guid

guid is the GUID defined in the [Strings] section of the CyUsb.inf file (or your own named copy). If this parameter is omitted, *guid* defaults to CYUSBDRV_GUID.

If you do not want to register for PnP events, but want to pass your own driver GUID to the constructor, you will need to pass NULL as the *hnd* parameter.

Example #1

```
void MainForm::FormCreate(  
    Object *Sender)  
{  
    USBDevice = new CCyUSBDevice( Handle);  
    CurrentEndPt = USBDevice->ControlEndPt;  
}  
  
// Overload MainForm's WndProc method to watch for PnP messages  
// Requires #include <dbt.h>  
void MainForm::WndProc (  
    Message &Message)  
{  
    if ( Message.Msg == WM_DEVICECHANGE) {  
  
        // Tracks DBT_DEVICEARRIVAL followed by DBT_DEVNODES_CHANGED
```

```

    if (Message.WParam == DBT_DEVICEARRIVAL) {
        bPnP_Arrival = true;
        bPnP_DevNodeChange = false;
    }

    // Tracks DBT_DEVNODES_CHANGED followed by DBT_DEVICEREMOVECOMPLETE
    if (Message.WParam == DBT_DEVNODES_CHANGED) {
        bPnP_DevNodeChange = true;
        bPnP_Removal = false;
    }

    if (Message.WParam == DBT_DEVICEREMOVECOMPLETE) {
        bPnP_Removal = true;

        PDEV_BROADCAST_HDR bcastHdr = (PDEV_BROADCAST_HDR) Message.LParam;
        if (bcastHdr->dbch_devicetype == DBT_DEVTYP_HANDLE) {
            PDEV_BROADCAST_HANDLE pDev = (PDEV_BROADCAST_HANDLE) Message.
LParam;
            if (pDev->dbch_handle == USBDevice->DeviceHandle())
                USBDevice->Close();
        }
    }

    // If DBT_DEVNODES_CHANGED followed by DBT_DEVICEREMOVECOMPLETE
    if (bPnP_Removal && bPnP_DevNodeChange) {
        Sleep(10);
        DisplayDevices();
        bPnP_Removal = false;
        bPnP_DevNodeChange = false;
    }

    // If DBT_DEVICEARRIVAL followed by DBT_DEVNODES_CHANGED
    if (bPnP_DevNodeChange && bPnP_Arrival) {
        DisplayDevices();
        bPnP_Arrival = false;
        bPnP_DevNodeChange = false;
    }
}

Form: : WndProc( Message);
}

```

Example 2

In the CyUSB.inf file :

[Strings]

CyUSB.GUID="{BE18AA60-7F6A-11d4-97DD-00010229B959}"

In some application source (.cpp) file:

```

GUID guid = {0xBE18AA60, 0x7F6A, 0x11D4, 0x97, 0xDD, 0x00, 0x01, 0x02,
0x29, 0xB9, 0x59};
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL, guid); // Does not
register for PnP events

```


10.10 ~CCyUSBDevice()

CCyUSBDevice::~~CCyUSBDevice(void)

[Previous](#) [Top](#) [Next](#)

Description

This is the destructor for the CCyUSBDevice class. It calls the [Close\(\)](#) method in order to properly close any open handle to the driver and to deallocate dynamically allocated members of the class.

10.11 Close()

void CCyUSBDevice:: Close(void)

[Previous](#) [Top](#) [Next](#)

Description

The Close method closes the handle to the CyUSB driver, if one is open.

Dynamically allocated members of the CCyUSBDevice class are de-allocated. All "shortcut" pointers to elements of the [EndPoints](#) array (ControlEndPt, IsoIn/OutEndPt, BulkIn/OutEndPt, InterruptIn/OutEndPt) are reset to NULL.

Close() is called automatically by the [~CCyUSBDevice\(\)](#) destructor. It is also called automatically by the [Open\(\)](#) method, if a handle to the driver is already open.

Therefore, it is rare that you would ever need to call Close() explicitly (though doing so would not cause any problems).

10.12 Config()

UCHAR CCyUSBDevice::Config(void)

[Previous](#) [Top](#) [Next](#)

Description

This method returns the current configuration index for the device.

Most devices only expose a single configuration. So, this method should almost always return zero.

10.13 ConfigAttrib

UCHAR CCyUSBDevice::ConfigAttrib

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of the **bmAttributes** field from the device's current configuration descriptor.

10.14 ConfigCount()

UCHAR CCyUSBDevice::ConfigCount(void)

[Previous](#) [Top](#) [Next](#)

Description

This function returns the number of configurations reported by the device in the **bNumConfigurations** field of its device descriptor.

10.15 ConfigValue

UCHAR CCyUSBDevice::ConfigValue

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of the **bConfigurationValue** field from the device's current configuration descriptor.

10.16 ControlEndPoint

**CCyControlEndPoint* CCyUSBDevice::
ControlEndPoint**

[Previous](#) [Top](#) [Next](#)

Description

ControlEndPoint points to an object representing the primary control endpoint, endpoint 0.

ControlEndPoint should always be the same value as [EndPoints](#)[0].

Before calling the [XferData](#)() method for ControlEndPoint, you should set the object's control properties.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

// Get a handle to the control endpoint
CCyControlEndPoint *ept = USBDevice->ControlEndPoint;

ept->Target      = TGT_DEVICE;
ept->ReqType     = REQ_VENDOR;
ept->Direction   = DIR_TO_DEVICE;
ept->ReqCode     = 0x05;
ept->Value       = 1;
ept->Index       = 0;

unsigned char  buf[ 512 ];
ZeroMemory( buf, 512 );
LONG buflen = 512;

ept->XferData( buf, buflen );
```


10.17 DevClass

UCHAR CCyUSBDevice::DevClass

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of the **bDeviceClass** field from the open device's Device Descriptor.

10.18 DeviceCount()

UCHAR CCyUSBDevice::DeviceCount(void)[Previous](#) [Top](#) [Next](#)

Description

Returns the number of devices attached to the USB driver.

The value returned can be used to discern legitimate parameters for the [Open\(\)](#) method.

Example

```
// Create an instance of CCyUSBDevice
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

// Look for a device having VID = 04b4, PID = 00f1
int devices = USBDevice->DeviceCount();
int vID, pID;
int d = 0;

do {
    // Open() automatically calls Close() if necessary
    USBDevice->Open( d );
    vID = USBDevice->VendorID;
    pID = USBDevice->ProductID;
    d++;
} while ( (d < devices ) && ( vID != 0x04b4 ) && ( pID != 0x00f1 ) );
```

10.19 DeviceHandle()

HANDLE CCyUSBDevice::DeviceHandle(void)

[Previous](#) [Top](#) [Next](#)

Description

Returns the handle to the driver if the CCyUSBDevice is opened to a connected USB device.
If no device is currently open, DeviceHandle() returns INVALID_HANDLE_VALUE.

10.20 DeviceName

```
char CCyUSBDevice::DeviceName  
[USB_STRING_MAXLEN]
```

[Previous](#) [Top](#) [Next](#)

Description

DeviceName is an array of characters containing the product string indicated by the device descriptor's iProduct field.

10.21 DevProtocol

UCHAR CCyUSBDevice::DevProtocol

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of the **bDeviceProtocol** field from the open device's Device Descriptor.

10.22 DevSubClass

UCHAR CCyUSBDevice::DevSubClass

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of the **bDeviceSubClass** field from the open device's Device Descriptor.

10.23 DriverGUID()

GUID CCyUSBDevice::DriverGUID(void)

[Previous](#) [Top](#) [Next](#)

Description

Returns the Global Unique Identifier of the USB driver attached to the CCyUSBDevice.

See also: [CCyUSBDevice\(\)](#)

10.24 DriverVersion

ULONG CCyUSBDevice::DriverVersion

[Previous](#) [Top](#) [Next](#)

Description

DriverVersion contains 4 bytes representing the version of the driver that is attached to the CCyUSBDevice.

10.25 EndPointCount()

UCHAR CCyUSBDevice::EndPointCount(void)

[Previous](#) [Top](#) [Next](#)

Description

Returns the number of endpoints exposed by the currently selected interface (or Alternate Interface) plus 1.

The default Control endpoint (endpoint 0) is included in the count.

Example

```
// Find bulk endpoints in the EndPoints[] array
CCyBulkEndPoint *BulkInEpt = NULL;
CCyBulkEndPoint *BulkOutEpt = NULL;

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
int eptCount = USBDevice->EndPointCount();

// Skip EndPoints[0], which we know is the control endpoint
for (int i=1; i<eptCount; i++) {
    bool bIn = ((USBDevice->EndPoints[i]->Address & 0x80)==0x80);
    bool bBulk = (USBDevice->EndPoints[i]->Attributes == 2);

    if (bBulk && bIn)
        BulkInEpt = (CCyBulkEndPoint *) USBDevice->EndPoints[i];
    if (bBulk && !bIn)
        BulkOutEpt = (CCyBulkEndPoint *) USBDevice->EndPoints[i];
}
```

10.26 EndPointOf()

CCyUSBEndPoint* CCyUSBDevice::EndPointOf(
UCHAR addr)

[Previous](#) [Top](#) [Next](#)

Description

Returns a pointer to the endpoint object in the EndPoints array whose [Address](#) property is equal to **addr** .

Returns NULL If no endpoint with Address = **addr** is found.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL) ;

// Look for Endpoint 0x82 (2-IN)
UCHAR eptAddr = 0x82;
CCyUSBEndPoint *EndPt = USBDevice->EndPointOf( eptAddr) ;

// Reset the endpoint, if found
if ( EndPt)
    EndPt->Reset() ;
```

10.27 EndPoints

CCyUSBEndPoint CCyUSBDevice::EndPoints**

[Previous](#) [Top](#) [Next](#)

Description

EndPoints is a list of up to MAX_ENDPTS (16) pointers to endpoint objects.

The objects pointed to represent all the USB endpoints reported for the current USB interface / alternate interface of the device.

EndPoints[0] always contains a pointer to a [CCyControlEndPoint](#) representing the primary Control Endpoint (endpoint 0) of the device.

Unused entries in EndPoints are set to NULL.

Use [EndPointCount\(\)](#) to find-out how many entries in EndPoints are valid.

EndPoints is re-initialized each time [Open\(\)](#) or [SetAltIntfc\(\)](#) is called.

NOTE:

CCyUSBEndPoint is an abstract class, having a pure virtual function BeginDataXfer(). The objects pointed to by EndPoints** are therefore, actually instances of CCyControlEndPoint, CCyBulkEndPoint, CCyIsocEndPoint or CCyInterruptEndPoint. Calling EndPoints[n]->XferData() automatically results in the correct XferData() function being invoked.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);

int epCnt = USBDevice->EndPointCount();
bool bBulk, bIn;
int blkInCnt = 0;

// Count the bulk-in endpoints
for (int e=0; e<epCnt; e++) {
    bBulk = ( USBDevice->EndPoints[ e]->Attributes  == 2);
    bIn    = (( USBDevice->EndPoints[ e]->Address & 0x80)==0x80);
    if ( bBulk && bIn)
        blkInCnt++;
}
```

10.28 FriendlyName

```
char CCyUSBDevice::FriendlyName  
[USB_STRING_MAXLEN]
```

[Previous](#) [Top](#) [Next](#)

Description

FriendlyName is an array of characters containing the device description string for the open device which was provided by the driver's .inf file.

10.29 GetDeviceDescriptor()

```
void CCyUSBDevice::GetDeviceDescriptor(  
PUSB_DEVICE_DESCRIPTOR descr)
```

[Previous](#) [Top](#) [Next](#)

Description

This function copies the current device's device descriptor into the memory pointed to by **descr**.

10.30 GetBosDescriptor()

```
bool CCyUSBDevice::GetBosDescriptor(  
PUSB_BOS_DESCRIPTOR descr)
```

[Top](#) [Previous](#) [Next](#)

Description

This function copies the device's Binary device Object Store (BOS) descriptor into memory pointed to by ***descr***. This function will return BOS descriptor only for USB 3.0 devices.

Return Value

True Operation successful.

False Operation failed (Not a USB 3.0 device)

10.31 GetBosUSB20DeviceExtensionDescriptor()

```
bool CCyUSBDevice::  
GetBosUSB20DeviceExtensionDescriptor(  
PUSB_BOS_USB20_DEVICE_EXTENSION descr)
```

[Previous](#) [Top](#) [Next](#)

Description

This function copies the device's USB 2.0 device extension descriptor into the **descr** buffer. This function will return the USB 2.0 Device extension descriptor only for USB 3.0 devices.

Return Value

True Operation successful.

False Operation failed (Not a USB 3.0 device)

10.32 GetBosContainerIDDescriptor()

```
bool CCyUSBDevice::  
GetBosContainerIDDescriptor(  
PUSB_BOS_CONTAINER_ID descr)
```

[Previous](#) [Top](#) [Next](#)

Description

This function copies the device's Container ID descriptor into the **descr** buffer. This function will return Container ID only for USB 3.0 devices, otherwise it will return false as a return value.

Return Value

True Operation successful.

False Operation failed (Not a USB 3.0 device)

10.33 GetBosSSCapabilityDescriptor()

```
bool CCyUSBDevice::  
GetBosSSCapabilityDescriptor(  
PUSB_BOS_SS_DEVICE_CAPABILITY descr)
```

[Previous](#) [Top](#) [Next](#)

Description

This function copies the device's Super Speed capability descriptor into the **descr** buffer. This function will return Super Speed capability descriptor only for USB 3.0 devices.

Return Value

True Operation successful.
False Operation failed (Not a USB 3.0 device)

10.34 GetConfigDescriptor()

```
void CCyUSBDevice::GetConfigDescriptor(  
PUSB_CONFIGURATION_DESCRIPTOR descr)
```

[Previous](#) [Top](#) [Next](#)

Description

This function copies the current device's configuration descriptor into the memory pointed to by **descr**.

10.35 GetIntfcDescriptor()

```
void CCyUSBDevice::GetIntfcDescriptor(  
PUSB_INTERFACE_DESCRIPTOR descr)
```

[Previous](#) [Top](#) [Next](#)

Description

This function copies the currently selected interface descriptor into the memory pointed to by **descr** .

10.36 GetUSBConfig()

CCyUSBConfig CCyUSBDevice::GetUSBConfig(
int index)

[Previous](#) [Top](#) [Next](#)

Description

This function returns a copy of the [CCyUSBConfig](#) object indicated by **index** .

The **index** parameter must be less than [CCyUSBDevice::ConfigCount\(\)](#).

Example

```
// This code snippet lists all the endpoints reported
// by the device under all interfaces and configurations.

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

char buf[ 512 ];
string s;

for ( int c=0; c<USBDevice->ConfigCount(); c++)
{
    CCyUSBConfig cfg = USBDevice->GetUSBConfig( c );

    // Print all configuration descriptor fields
    sprintf_s( buf, "bLength: 0x%x\n", cfg. bLength );
    s. append( buf );

    sprintf_s( buf, "bDescriptorType: %d\n", cfg. bDescriptorType );
    s. append( buf );

    sprintf_s( buf, "wTotalLength: %d ( 0x%x )\n", cfg. wTotalLength, cfg.
wTotalLength );
    s. append( buf );

    sprintf_s( buf, "bNumInterfaces: %d\n", cfg. bNumInterfaces );
    s. append( buf );

    sprintf_s( buf, "bConfigurationValue: %d\n", cfg. bConfigurationValue );
    s. append( buf );

    sprintf_s( buf, "iConfiguration: %d\n", cfg. iConfiguration );
    s. append( buf );

    sprintf_s( buf, "bmAttributes: 0x%x\n", cfg. bmAttributes );
    s. append( buf );

    sprintf_s( buf, "MaxPower: %d\n", cfg. MaxPower );
    s. append( buf );
    s. append( "*****\n" );
}
```

```

cout<<s;
s.clear();

for (int i=0; i<cfg.AltInterfaces; i++)
{
    // Print all interface descriptor fields
    CCyUSBInterface *ifc = cfg.Interfaces[i];
    sprintf_s(buf, "Interface Descriptor: %d\n", (i+1));
    s.append(buf);

    sprintf_s(buf, "-----\n");
    s.append(buf);

    sprintf_s(buf, "bLength: 0x%x\n", ifc->bLength);
    s.append(buf);

    sprintf_s(buf, "bDescriptorType: %d\n", ifc->bDescriptorType);
    s.append(buf);

    sprintf_s(buf, "bInterfaceNumber: %d\n", ifc->bInterfaceNumber);
    s.append(buf);

    sprintf_s(buf, "bAlternateSetting: %d\n", ifc->bAlternateSetting);
    s.append(buf);

    sprintf_s(buf, "bNumEndpoints: %d\n", ifc->bNumEndpoints);
    s.append(buf);

    sprintf_s(buf, "bInterfaceClass: %d\n", ifc->bInterfaceClass);
    s.append(buf);
    sprintf_s(buf, "*****\n"); s.append(buf);

    cout<<s;
    s.clear();

    for (int e=0; e<ifc->bNumEndpoints; e++)
    {
        // Print all endpoint descriptor fields
        CCyUSBEndPoint *ept = ifc->EndPoints[e+1];
        sprintf_s(buf, "EndPoint Descriptor: %d\n", (e+1));
        s.append(buf);

        sprintf_s(buf, "-----\n");
        s.append(buf);

        sprintf_s(buf, "bLength: 0x%x\n", ept->DscLen);
        s.append(buf);

        sprintf_s(buf, "bDescriptorType: %d\n", ept->DscType);
        s.append(buf);

        sprintf_s(buf, "bEndpointAddress: 0x%x\n", ept->Address);
        s.append(buf);
    }
}

```

```
    sprintf_s(buf, "bmAttributes: 0x%x\n", ept->Attributes);  
    s.append(buf);  
  
    sprintf_s(buf, "wMaxPacketSize: %d\n", ept->MaxPktSize);  
    s.append(buf);  
  
    sprintf_s(buf, "bInterval: %d\n", ept->Interval);  
    s.append(buf);  
    s.append("*****\n");  
  
    cout<<s;  
    s.clear();  
}  
}  
}
```

10.37 Interface()

UCHAR CCyUSBDevice::Interface(void)

[Previous](#) [Top](#) [Next](#)

Description

Interface returns the index of the currently selected device interface.

Because Windows always represents different reported interfaces as separate devices, the CyUSB driver is only shown devices that have a single interface. This causes the Interface() method to always return zero.

10.38 InterruptInEndPt

CCyInterruptEndPoint* CCyUSBDevice::
InterruptInEndPt

[Previous](#) [Top](#) [Next](#)

Description

InterruptInEndPt is a pointer to an object representing the first INTERRUPT IN endpoint enumerated for the selected interface.

The selected interface might expose additional INTERRUPT IN endpoints. To discern this, one would need to traverse the [EndPoints](#) array, checking the [Attributes](#) and [Address](#) members of each [CCyUSBEndPoint](#) object referenced in the array.

If no INTERRUPT IN endpoints were enumerated by the device, InterruptInEndPt will be set to NULL.

Example

```
// Find a second Interrupt IN endpoint in the EndPoints[] array
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
CCyInterruptEndPoint *IntIn2 = NULL;
int eptCount = USBDevice->EndPointCount();

for (int i=1; i<eptCount; i++) {
    bool bIn = (( USBDevice->EndPoints[ i ]->Address & 0x80) == 0x80);
    bool bInt = ( USBDevice->EndPoints[ i ]->Attributes == 3);

    if ( bInt && bIn ) {
        IntIn2 = ( CCyInterruptEndPoint *) USBDevice->EndPoints[ i ];
        if ( IntIn2 == USBDevice->InterruptInEndPt )
            IntIn2 = NULL;
    }
}
```


10.39 InterruptOutEndPt

CCyInterruptEndPoint* CCyUSBDevice::
InterruptOutEndPt

[Previous](#) [Top](#) [Next](#)

Description

InterruptOutEndPt is a pointer to an object representing the first INTERRUPT OUT endpoint enumerated for the selected interface.

The selected interface might expose additional INTERRUPT OUT endpoints. To discern this, one would need to traverse the [EndPoints](#) array, checking the [Attributes](#) and [Address](#) members of each [CCyUSBEndPoint](#) object referenced in the array.

If no INTERRUPT OUT endpoints were enumerated by the device, InterruptOutEndPt will be set to NULL.

Example

```
// Find a second Interrupt OUT endpoint in the EndPoints[] array
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
CCyInterruptEndPoint *IntOut2 = NULL;
int eptCount = USBDevice->EndPointCount();

for (int i=1; i<eptCount; i++) {
    bool bIn = (( USBDevice->EndPoints[ i]->Address & 0x80) == 0x80);
    bool bInt = ( USBDevice->EndPoints[ i]->Attributes == 3);

    if (bInt && !bIn) {
        IntOut2 = (CCyInterruptEndPoint *) USBDevice->EndPoints[ i];
        if (IntOut2 == USBDevice->InterruptInEndPt)
            IntOut2 = NULL;
    }
}
```

10.40 IntfcClass

UCHAR CCyUSBDevice::IntfcClass[Previous](#) [Top](#) [Next](#)

Description

This data member contains the bInterfaceClass field from the currently selected interface's interface descriptor.

10.41 IntfcCount()

UCHAR CCyUSBDevice::IntfcCount(void)

[Previous](#) [Top](#) [Next](#)

Description

Returns the bNumInterfaces field of the current device's configuration descriptor.

This number does not include alternate interfaces that might be part of the configuration. Because Windows always represents different reported interfaces as separate devices, the CyUSB3 driver is only shown devices that have a single interface. This causes the IntfcCount() method to always return 1.

10.42 IntfcProtocol

UCHAR CCyUSBDevice::IntfcProtocol

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the **blInterfaceProtocol** field from the currently selected interface's interface descriptor.

10.43 IntfcSubClass

UCHAR CCyUSBDevice::IntfcSubClass

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the **bInterfaceSubClass** field from the currently selected interface's interface descriptor.

10.44 IsocInEndPt

CCyIsocEndPoint* CCyUSBDevice::IsocInEndPt[Previous](#) [Top](#) [Next](#)

Description

IsocInEndPt is a pointer to an object representing the first ISOCHRONOUS IN endpoint enumerated for the selected interface.

The selected interface might expose additional ISOCHRONOUS IN endpoints. To discern this, one would need to traverse the [EndPoints](#) array, checking the [Attributes](#) and [Address](#) members of each [CCyUSBEndPoint](#) object referenced in the array.

If no ISOCHRONOUS IN endpoints were enumerated by the device, IsocInEndPt will be set to NULL.

Example

```
// Find a second Isoc IN endpoint in the EndPoints[] array
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
CCyIsocEndPoint *IsocIn2 = NULL;
int eptCount = USBDevice->EndPointCount();

for (int i=1; i<eptCount; i++) {
    bool bIn = (( USBDevice->EndPoints[ i ]->Address & 0x80) == 0x80);
    bool bIsoc = ( USBDevice->EndPoints[ i ]->Attributes == 1);

    if ( bIsoc && bIn) {
        IsocIn2 = ( CCyIsocEndPoint *) USBDevice->EndPoints[ i ];
        if ( IsocIn2 == USBDevice->IsocInEndPt)
            IsocIn2 = NULL;
    }
}
```

10.45 IsocOutEndPt

CCyIsocEndPoint* CCyUSBDevice::
IsocOutEndPt

[Previous](#) [Top](#) [Next](#)

Description

IsocOutEndPt is a pointer to an object representing the first ISOCHRONOUS OUT endpoint enumerated for the selected interface.

The selected interface might expose additional ISOCHRONOUS OUT endpoints. To discern this, one would need to traverse the [EndPoints](#) array, checking the [Attributes](#) and [Address](#) members of each [CCyUSBEndPoint](#) object referenced in the array.

If no ISOCHRONOUS OUT endpoints were enumerated by the device, IsocOutEndPt will be set to NULL.

Example

```
// Find a second Isoc OUT endpoint in the EndPoints[] array
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
CCyIsocEndPoint *IsocOut2 = NULL;
int eptCount = USBDevice->EndPointCount();

for (int i=1; i<eptCount; i++) {
    bool bIn = (( USBDevice->EndPoints[ i ]->Address & 0x80) == 0x80);
    bool bIsoc = ( USBDevice->EndPoints[ i ]->Attributes == 1);

    if ( bIsoc && !bIn) {
        IsocOut2 = ( CCyIsocEndPoint *) USBDevice->EndPoints[ i ];
        if ( IsocOut2 == USBDevice->IsocOutEndPt)
            IsocOut2 = NULL;
    }
}
```

10.46 IsOpen()

bool CCyUSBDevice::IsOpen(void)

[Previous](#) [Top](#) [Next](#)

Description

IsOpen() returns **true** if CCyUSBDevice object has a valid handle to a device attached to the CyUSB driver.

When IsOpen() is **true**, the CCyUSBDevice object is ready to perform IO operations via its [EndPoints](#) members.

10.47 Manufacturer

```
wchar_t CCyUSBDevice::Manufacturer  
[USB_STRING_MAXLEN]
```

[Previous](#) [Top](#) [Next](#)

Description

Manufacturer is an array of wide characters containing the manufacturer string indicated by the device descriptor's **iManufacturer** field.

10.48 MaxPacketSize

UCHAR CCyUSBDevice::MaxPacketSize

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of the **bMaxPacketSize0** field from the open device's Device Descriptor structure.

10.49 MaxPower

UCHAR CCyUSBDevice::MaxPower

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of the **MaxPower** field of the open device's selected configuration descriptor.

10.50 NtStatus

ULONG CCyUSBDevice::NtStatus

[Previous](#) [Top](#) [Next](#)

Description

The NtStatus member contains the NTSTATUS returned by the driver for the most recent call to a non-endpoint IO method (SetAltIntfc, Open, Reset, etc.).

More often, you will want to access the [NtStatus](#) member of the [CCyUSBEndPoint](#) objects.

10.51 Open()

bool CCyUSBDevice::Open(UCHAR dev)

[Previous](#) [Top](#) [Next](#)

Description

The Open() method is one of the main workhorses of the library.

When Open() is called, it first checks to see if the CCyUSBDevice object is already opened to one of the attached devices. If so, it calls [Close\(\)](#), then proceeds.

Open() calls [DeviceCount\(\)](#) to determine how many devices are attached to the USB driver.

Open() creates a valid handle to the device driver, through which all future access is accomplished by the library methods.

Open() calls the driver to gather the device, interface, endpoint and string descriptors.

Open() results in the [EndPoints](#) array getting properly initialized to pointers of the default interface's endpoints.

Open() initializes the [ControlEndPt](#) member to point to an instance of [CCyControlEndPoint](#) that represents the device's endpoint zero.

Open() initializes the [BulkInEndPt](#) member to point to an instance of CCyBulkEndPoint representing the first Bulk-IN endpoint that was found. Similarly, the [BulkOutEndPt](#), [InterruptInEndPt](#), [InterruptOutEndPt](#), [IsocInEndPt](#) and [IsocOutEndPt](#) members are initialized to point to instances of their respective endpoint classes if such endpoints were found.

After Open() returns **true**, all the properties and methods of CCyUSBDevice are legitimate.

Open() returns **false** if it is unsuccessful in accomplishing the above activities. However, if Open() was able to obtain a valid handle to the driver, the handle will remain valid even after Open() returns **false**. (When open fails, it does not automatically call Close().) This allows the programmer to call the [Reset\(\)](#) or [ReConnect\(\)](#) methods and then call Open() again. Sometimes, this will allow a device to open properly.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

// Attempt to open device #0
if ( USBDevice->DeviceCount() && !USBDevice->Open( 0 ) ) {
    // If Open() failed, retry Open() after resetting the device
    USBDevice->Reset();
    USBDevice->Open( 0 );
}

if ( !USBDevice->IsOpen() )
    return false;
```

10.52 PowerState()

UCHAR CCyUSBDevice::PowerState(void)

[Previous](#) [Top](#) [Next](#)

This function is no longer supported. It is available to keep backward compatibility with legacy library and application.

10.53 Product

```
wchar_t CCyUSBDevice::Product  
[USB_STRING_MAXLEN]
```

[Previous](#) [Top](#) [Next](#)

Description

Product is an array of wide characters containing the product string indicated by the device descriptor's **iProduct** field.

10.54 ProductID

USHORT CCyUSBDevice::ProductID[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of idProduct from the open device's Device Descriptor structure.

Example

```
// Look for a device having VID = 04b4, PID = 00f0
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
int devices = USBDevice->DeviceCount();
int vID, pID;
int d = 0;

do {
    // Open automatically calls Close() if necessary
    USBDevice->Open( d );
    vID = USBDevice->VendorID;
    pID = USBDevice->ProductID;
    d++;
} while ((d < devices) && (vID != 0x04b4) && (pID != 0x00f0));
```


10.55 ReConnect()

```
bool CCyUSBDevice::ReConnect(void)
```

[Previous](#) [Top](#) [Next](#)

Description

ReConnect() calls the USB device driver to cause the currently open USB device to be logically disconnected from the USB bus and re-enumerated.

10.56 Reset()

```
bool CCyUSBDevice::Reset( void)
```

[Previous](#) [Top](#) [Next](#)

Description

Reset() calls the USB device driver to cause the currently open USB device to be reset.

This call causes the device to return to its initial power-on configuration.

10.57 Resume()

```
bool CCyUSBDevice::Resume(void)
```

[Previous](#) [Top](#) [Next](#)

The Resume() method sets the device power state to D0 (Full on).

The method returns true if successful, and false if the command failed.

10.58 SerialNumber

```
wchar_t CCyUSBDevice::SerialNumber  
[USB_STRING_MAXLEN]
```

[Previous](#) [Top](#) [Next](#)

Description

SerialNumber is an array of wide characters containing the serial number string indicated by the device descriptor's **iSerialNumber** field.

10.59 SetConfig()

```
void CCyUSBDevice::SetConfig( UCHAR cfg)
```

[Previous](#) [Top](#) [Next](#)

Description

This method will set the current device configuration to **cfg**, if **cfg** represents an existing configuration.

In general, devices only expose a single configuration. So, while this method exists for completeness; it should not need to be invoked with a **cfg** value other than 0.

10.60 SetAltIntfc()

bool CCyUSBDevice::SetAltIntfc(UCHAR alt)

[Previous](#) [Top](#) [Next](#)

Description

SetAltIntfc() calls the driver to set the active interface of the device to **alt**.

If **alt** is not a valid alt interface setting, the method does nothing.

Legitimate values for **alt** are 0 to [AltIntfcCount](#)().

Calling SetAltIntfc() causes all the [EndPoints](#) members of CCyUSBDevice to be re-assigned to objects reflecting the endpoints of the new alternate interface.

Returns **true** if the alternate interface was successfully set to **alt** .

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
int lastIntfc = USBDevice->AltIntfcCount();

// Select the last Alternate Interface
USBDevice->SetAltIntfc( lastIntfc );
```

10.61 StrLangID

USHORT CCyUSBDevice::StrLangID

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of **bString** field from the open device's first String Descriptor.

This value indicates the language of the other string descriptors.

If multiple languages are supported in the string descriptors and English is one of the supported languages, StrLangID is set to the value for English (0x0409).

10.62 Suspend()

```
bool CCyUSBDevice::Suspend(void)
```

[Previous](#) [Top](#) [Next](#)

The Suspend() method sets the device power state to D3 (Full asleep).

The method returns true if successful, and false if the command failed.

10.63 USBAddress

UCHAR CCyUSBDevice::USBAddress

[Previous](#) [Top](#) [Next](#)

Description

USBAddress contains the bus address of the currently open USB device.

This is the address value used by the Windows USBDI stack. It is not particularly useful at the application level.

10.64 USBDIVersion

ULONG CCyUSBDevice::USBDIVersion

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the version of the USB Host Controller Driver in BCD format.

10.65 UsbdStatus

ULONG CCyUSBDevice::UsbdStatus

[Previous](#) [Top](#) [Next](#)

Description

The UsbdStatus member contains the USB_D_STATUS returned by the driver for the most recent call to a non-endpoint IO method (SetAltIntfc, Open, Reset, etc.)

More often, you will want to access the [UsbdStatus](#) member of the [CCyUSBEndPoint](#) objects.

10.66 UsbdStatusString()

```
void CCyUSBDevice::UsbdStatusString(ULONG  
stat, PCHAR s)
```

[Previous](#) [Top](#) [Next](#)

Description

The UsbdStatusString method returns a string of characters in **s** that represents the UsbdStatus error code contained in **stat**.

The **stat** parameter should be the [UsbdStatus](#) member or a CCyUSBEndPoint::UsbdStatus member.

The format of the returned string, **s**, is:

"[state=SSSSSS status=TTTTTTT]"

where SSSSSS can be "SUCCESS", "PENDING", "STALLED", or "ERROR".

Note:

There is no endpoint equivalent for this method. To interpret the UsbdStatus member of an endpoint object, call this method (CCyUSBDevice::UsbdStatusString) passing the UsbdStatus member of the endpoint.

10.67 VendorID

USHORT CCyUSBDevice::VendorID[Previous](#) [Top](#) [Next](#)

Description

This data member contains the value of idVendor from the open device's Device Descriptor structure.

Example

```
// Look for a device having VID = 04b4, PID = 00f0
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
int devices = USBDevice->DeviceCount();
int vID, pID;
int d = 0;

do {
    // Open automatically calls Close() if necessary
    USBDevice->Open( d );
    vID = USBDevice->VendorID;
    pID = USBDevice->ProductID;
    d++;
} while ((d < devices) && (vID != 0x04b4) && (pID != 0x00f0));
```

11 CCyUSBConfig

CCyUSBConfig Class

[Previous](#) [Top](#) [Next](#)

Header

CyUSB.h

Description

CCyUSBConfig represents a USB device configuration. Such configurations have one or more interfaces each of which exposes one or more endpoints.

When [CCyUSBDevice::Open\(\)](#) is called, an instance of CCyUSBConfig is constructed for each configuration reported by the open device's device descriptor. (Normally, each device has only one configuration.)

In the process of construction, CCyUSBConfig creates instances of [CCyUSBInterface](#) for each interface exposed in the device's configuration descriptor. In turn, the CCyUSBInterface class creates instances of [CCyUSBEndPoint](#) for each endpoint descriptor contained in the interface descriptor. In this iterative fashion, the entire structure of Configurations->Interfaces->EndPoints gets populated from a single construction of the CCyUSBConfig class.

The following example code shows the use of the CCyUSBConfig class in an application.

Example

```
// This code snippet lists all the endpoints reported
// by the device under all interfaces and configurations.

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

char buf[ 512 ];
string s;

for ( int c=0; c<USBDevice->ConfigCount(); c++)
{
    CCyUSBConfig cfg = USBDevice->GetUSBConfig( c );

    // Print all configuration descriptor fields
    sprintf_s( buf, "bLength: 0x%x\n", cfg.bLength );
    s.append( buf );

    sprintf_s( buf, "bDescriptorType: %d\n", cfg.bDescriptorType );
    s.append( buf );

    sprintf_s( buf, "wTotalLength: %d (0x%x)\n", cfg.wTotalLength, cfg.
wTotalLength );
    s.append( buf );

    sprintf_s( buf, "bNumInterfaces: %d\n", cfg.bNumInterfaces );
    s.append( buf );
}
```

```
    sprintf_s(buf, "bConfigurationValue: %d\n", cfg.bConfigurationValue);
    s.append(buf);

    sprintf_s(buf, "iConfiguration: %d\n", cfg.iConfiguration);
    s.append(buf);

    sprintf_s(buf, "bmAttributes: 0x%x\n", cfg.bmAttributes);
    s.append(buf);

    sprintf_s(buf, "MaxPower: %d\n", cfg.MaxPower);
    s.append(buf);
    s.append("*****\n");

    cout<<s;
    s.clear();

    for (int i=0; i<cfg.AltInterfaces; i++)
    {
        // Print all interface descriptor fields
        CCyUSBInterface *ifc = cfg.Interfaces[i];
        sprintf_s(buf, "Interface Descriptor: %d\n", (i+1));
        s.append(buf);

        sprintf_s(buf, "-----\n");
        s.append(buf);

        sprintf_s(buf, "bLength: 0x%x\n", ifc->bLength);
        s.append(buf);

        sprintf_s(buf, "bDescriptorType: %d\n", ifc->bDescriptorType);
        s.append(buf);

        sprintf_s(buf, "bInterfaceNumber: %d\n", ifc->bInterfaceNumber);
        s.append(buf);

        sprintf_s(buf, "bAlternateSetting: %d\n", ifc->bAlternateSetting);
        s.append(buf);

        sprintf_s(buf, "bNumEndpoints: %d\n", ifc->bNumEndpoints);
        s.append(buf);

        sprintf_s(buf, "bInterfaceClass: %d\n", ifc->bInterfaceClass);
        s.append(buf);
        sprintf_s(buf, "*****\n"); s.append(buf);

        cout<<s;
        s.clear();

        for (int e=0; e<ifc->bNumEndpoints; e++)
        {
            // Print all endpoint descriptor fields
            CCyUSBEndPoint *ept = ifc->EndPoints[e+1];
            sprintf_s(buf, "EndPoint Descriptor: %d\n", (e+1));
```

```
s.append( buf );

sprintf_s( buf, "-----\n" );
s.append( buf );

sprintf_s( buf, "bLength: 0x%x\n", ept->DscLen );
s.append( buf );

sprintf_s( buf, "bDescriptorType: %d\n", ept->DscType );
s.append( buf );

sprintf_s( buf, "bEndpointAddress: 0x%x\n", ept->Address );
s.append( buf );

sprintf_s( buf, "bmAttributes: 0x%x\n", ept->Attributes );
s.append( buf );

sprintf_s( buf, "wMaxPacketSize: %d\n", ept->MaxPktSize );
s.append( buf );

sprintf_s( buf, "bInterval: %d\n", ept->Interval );
s.append( buf );
s.append( "*****\n" );

cout<<s;
s.clear();
}
}
}
```


11.1 AltInterfaces

CCyUSBConfig::AltInterfaces

[Previous](#) [Top](#) [Next](#)

Description

AltInterfaces contains the total number of interfaces exposed by the configuration (including the default interface). This value is the number of interface descriptors contained in the current configuration descriptor.

Because the [CCyUSBDevice::AltIntfcCount](#)() method does not count the primary interface, it returns CCyUSBConfig::AltInterfaces - 1.

11.2 bConfigurationValue

UCHAR CCyUSBConfig::bConfigurationValue

[Previous](#) [Top](#) [Next](#)

Description

bConfigurationValue contains value of the **bConfigurationValue** field from the selected configuration descriptor.

11.3 bDescriptorType

UCHAR CCyUSBConfig::bDescriptorType

[Previous](#) [Top](#) [Next](#)

Description

bDescriptorType contains value of the **bDescriptorType** field from the selected configuration descriptor.

11.4 bLength

UCHAR CCyUSBConfig::bLength

[Previous](#) [Top](#) [Next](#)

Description

bLength contains value of the **bLength** field from the selected configuration descriptor.

11.5 bmAttributes

UCHAR CCyUSBConfig::bmAttributes

[Previous](#) [Top](#) [Next](#)

Description

bmAttributes contains value of the **bmAttributes** field from the selected configuration descriptor.

11.6 bNumInterfaces

UCHAR CCyUSBConfig::bNumInterfaces

[Previous](#) [Top](#) [Next](#)

Description

bNumInterfaces contains value of the **bNumInterfaces** field from the selected configuration descriptor.

11.7 CCyUSBConfig()

CCyUSBConfig::CCyUSBConfig(void)

[Previous](#) [Top](#) [Next](#)

Description

This is the default constructor for the CCyUSBConfig class.

This constructor simply sets all its data members to zero.

11.8 CCyUSBConfig()

```
CCyUSBConfig::CCyUSBConfig(HANDLE handle,  
PUSB_CONFIGURATION_DESCRIPTOR  
pConfigDescr)
```

[Previous](#) [Top](#) [Next](#)

Description

This constructor creates a functional CCyUSBConfig object, complete with a populated Interfaces[] array.

During construction, the pConfigDescr structure is traversed and all interface descriptors are read, creating CCyUSBInterface objects.

This constructor is called automatically as part of the [CCyUSBDevice::Open](#)() method. You should never need to call this constructor yourself.

11.9 CCyUSBConfig()

CCyUSBConfig::CCyUSBConfig(CCyUSBConfig& cfg)

[Previous](#) [Top](#) [Next](#)

Description

This is the *copy* constructor for the CCyUSBConfig class.

This constructor copies all of the simple data members of **cfg**. Then, it walks through **cfg**'s list of [CCyUSBInterface](#) objects and makes copies of them, storing pointers to the new interface objects in a private, internal data array. (This is accomplished by calling the [copy constructor](#) for CCyUSBInterface.)

You should usually not call the copy constructor explicitly. Instead, use the [GetUSBConfig\(\)](#) method of the CCyUSBDevice class.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );  
CCyUSBConfig cfg = USBDevice->GetUSBConfig( 0 );
```

11.10 ~CCyUSBConfig

CCyUSBConfig::~~CCyUSBConfig(void)

[Previous](#) [Top](#) [Next](#)

Description

This is the destructor for the CCyUSBConfig class.

The destructor deletes all the dynamically constructed [CCyUSBInterface](#) objects that were created during construction of the object.

11.11 iConfiguration

UCHAR CCyUSBConfig::iConfiguration

[Previous](#) [Top](#) [Next](#)

Description

iConfiguration contains value of the **iConfiguration** field from the selected configuration descriptor.

11.12 Interfaces

**CCyUSBInterface* CCyUSBConfig::Interfaces
[MAX_INTERFACES]**

[Previous](#) [Top](#) [Next](#)

Description

Interfaces are an array of pointers to [CCyUSBInterface](#) objects. One valid pointer exists in Interfaces[] for each alternate interface exposed by the configuration (including alt setting 0).

The [AltInterfaces](#) member tells how many valid entries are held in Interfaces.

Use [CCyUSBDevice::AltIntfcCount\(\)](#) and [CCyUSBDevice::SetAltIntfc\(\)](#) to access a configuration's alternate interfaces.

Example

```
// This code snippet lists all the endpoints reported
// by the device under all interfaces and configurations.

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

char buf[ 512 ];
string s;

for ( int c=0; c<USBDevice->ConfigCount(); c++)
{
    CCyUSBConfig cfg = USBDevice->GetUSBConfig( c );

    // Print all configuration descriptor fields
    sprintf_s( buf, "bLength: 0x%x\n", cfg. bLength );
    s. append( buf );

    sprintf_s( buf, "bDescriptorType: %d\n", cfg. bDescriptorType );
    s. append( buf );

    sprintf_s( buf, "wTotalLength: %d ( 0x%x )\n", cfg. wTotalLength, cfg.
wTotalLength );
    s. append( buf );

    sprintf_s( buf, "bNumInterfaces: %d\n", cfg. bNumInterfaces );
    s. append( buf );

    sprintf_s( buf, "bConfigurationValue: %d\n", cfg. bConfigurationValue );
    s. append( buf );

    sprintf_s( buf, "iConfiguration: %d\n", cfg. iConfiguration );
    s. append( buf );

    sprintf_s( buf, "bmAttributes: 0x%x\n", cfg. bmAttributes );
    s. append( buf );
}
```

```
printf_s(buf, "MaxPower: %d\n", cfg.MaxPower);
s.append(buf);
s.append("*****\n");

cout<<s;
s.clear();

for (int i=0; i<cfg.AltInterfaces; i++)
{
    // Print all interface descriptor fields
    CCyUSBInterface *ifc = cfg.Interfaces[i];
    printf_s(buf, "Interface Descriptor: %d\n", (i+1));
    s.append(buf);

    printf_s(buf, "-----\n");
    s.append(buf);

    printf_s(buf, "bLength: 0x%x\n", ifc->bLength);
    s.append(buf);

    printf_s(buf, "bDescriptorType: %d\n", ifc->bDescriptorType);
    s.append(buf);

    printf_s(buf, "bInterfaceNumber: %d\n", ifc->bInterfaceNumber);
    s.append(buf);

    printf_s(buf, "bAlternateSetting: %d\n", ifc->bAlternateSetting);
    s.append(buf);

    printf_s(buf, "bNumEndpoints: %d\n", ifc->bNumEndpoints);
    s.append(buf);

    printf_s(buf, "bInterfaceClass: %d\n", ifc->bInterfaceClass);
    s.append(buf);
    printf_s(buf, "*****\n"); s.append(buf);

    cout<<s;
    s.clear();

    for (int e=0; e<ifc->bNumEndpoints; e++)
    {
        // Print all endpoint descriptor fields
        CCyUSBEndPoint *ept = ifc->Endpoints[e+1];
        printf_s(buf, "EndPoint Descriptor: %d\n", (e+1));
        s.append(buf);

        printf_s(buf, "-----\n");
        s.append(buf);

        printf_s(buf, "bLength: 0x%x\n", ept->DscLen);
        s.append(buf);

        printf_s(buf, "bDescriptorType: %d\n", ept->DscType);
```

```
s.append( buf );

sprintf_s( buf, "bEndpointAddress: 0x%x\n", ept->Address );
s.append( buf );

sprintf_s( buf, "bmAttributes: 0x%x\n", ept->Attributes );
s.append( buf );

sprintf_s( buf, "wMaxPacketSize: %d\n", ept->MaxPktSize );
s.append( buf );

sprintf_s( buf, "bInterval: %d\n", ept->Interval );
s.append( buf );
s.append( "*****\n" );

cout<<s;
s.clear();
}
}
}
```

11.13 wTotalLength

USHORT CCyUSBConfig::wTotalLength

[Previous](#) [Top](#) [Next](#)

Description

wTotalLength contains value of the **wTotalLength** field from the selected configuration descriptor.

12 CCyUSBEndPoint

CCyUSBEndPoint Class

[Previous](#) [Top](#) [Next](#)

Header

CyUSB.h

Description

CCyUSBEndPoint is an abstract class, having a pure virtual method, [BeginDataXfer\(\)](#). Therefore, instances of CCyUSBEndPoint cannot be constructed. [CCyControlEndPoint](#), [CCyBulkEndPoint](#), [CCyIsocEndPoint](#), and [CCyInterruptEndPoint](#) are all classes derived from CCyUSBEndPoint.

All USB data traffic is accomplished by using instances of the endpoint classes.

When a CCyUSBDevice is opened, a list of all the [EndPoints](#) for the current alternate interface is generated. This list is populated with viable CCyUSBEndPoint objects, instantiated for the appropriate type of endpoint. Data access is then accomplished via one of these CCyUSBEndPoint objects.

12.1 Abort()

```
void CCyUSBEndPoint::Abort(void)
```

[Previous](#) [Top](#) [Next](#)

Description

Abort sends an IOCTL_ADAPT_ABORT_PIPE command to the USB device, with the endpoint address as a parameter. This causes an abort of pending IO transactions on the endpoint.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );  
USBDevice->ControlEndPt->Abort( );
```

12.2 Address

UCHAR CCyUSBEndPoint::Address[Previous](#) [Top](#) [Next](#)

Description

Address contains the value of the **bEndpointAddress** field of the endpoint descriptor returned by the device.

Addresses with the high-order bit set (0x8Y) are IN endpoints.

Addresses with the high-order bit cleared (0x0Y) are OUT endpoints.

The default endpoint ([ControlEndPt](#)) has Address = 0.

Example

```
// Find a second bulk IN endpoint in the EndPoints[] array
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
CCyBulkEndPoint *BulkIn2 = NULL;
int eptCount = USBDevice->EndPointCount();

for (int i=1; i<eptCount; i++) {
    bool bIn = (( USBDevice->EndPoints[ i ]->Address & 0x80) == 0x80);
    bool bBulk = ( USBDevice->EndPoints[ i ]->Attributes == 2);

    if ( bBulk && bIn) {
        BulkIn2 = ( CCyBulkEndPoint *) USBDevice->EndPoints[ i ];
        if ( BulkIn2 == USBDevice->BulkInEndPt)
            BulkIn2 = NULL;
    }
}
```

12.3 Attributes

UCHAR CCyUSBEndPoint::Attributes

[Previous](#) [Top](#) [Next](#)

Description

Attributes contains the value of the **bmAttributes** field of the endpoint's descriptor.

The Attributes member indicates the type of endpoint per the following list.

- 0: Control
- 1: Isochronous
- 2: Bulk
- 3: Interrupt

Example

```
// Find a second bulk IN endpoint in the EndPoints[] array
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
CCyBulkEndPoint *BulkIn2 = NULL;
int eptCount = USBDevice->EndPointCount();

for ( int i=1; i<eptCount; i++) {
    bool bIn = ( ( USBDevice->EndPoints[ i ]->Address & 0x80) == 0x80 );
    bool bBulk = ( USBDevice->EndPoints[ i ]->Attributes == 2 );

    if ( bBulk && bIn ) {
        BulkIn2 = ( CCyBulkEndPoint *) USBDevice->EndPoints[ i ];
        if ( BulkIn2 == USBDevice->BulkInEndPt )
            BulkIn2 = NULL;
    }
}
```

12.4 BeginDataXfer()

```
virtual PCHAR CCyUSBEndPoint::
BeginDataXfer(PCHAR buf, LONG len,
OVERLAPPED *ov) = 0
```

[Previous](#) [Top](#) [Next](#)

Description

Note that the CCyUSBEndPoint version of this method is a pure virtual function. There is no implementation body for this function in the CCyUSBEndPoint class. Rather, all the classes derived from CCyUSBEndPoint provide their own special implementation of this method.

BeginDataXfer is an advanced method for performing asynchronous IO. This method sets-up all the parameters for a data transfer, initiates the transfer, and immediately returns, not waiting for the transfer to complete.

BeginDataXfer allocates a complex data structure and returns a pointer to that structure. [FinishDataXfer](#) de-allocates the structure. Therefore, it is imperative that each BeginDataXfer call have exactly one matching FinishDataXfer call.

You will usually want to use the synchronous [XferData](#) method rather than the asynchronous BeginDataXfer/WaitForXfer/FinishDataXfer approach.

Example

```
// This example assumes that the device automatically sends back
// over its bulk-IN endpoint, any bytes that were received over its
// bulk-OUT endpoint (commonly referred to as a loopback function)
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
OVERLAPPED outOvLap, inOvLap;

outOvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_OUT");
inOvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_IN");

unsigned char inBuf[128];
ZeroMemory(inBuf, 128);

unsigned char buffer[128];
LONG length = 128;

// Request the return data before initiating the loopback
UCHAR *inContext = USBDevice->BulkInEndPt->BeginDataXfer(inBuf, length,
&inOvLap);
UCHAR *outContext = USBDevice->BulkOutEndPt->BeginDataXfer(buffer,
length, &outOvLap);

USBDevice->BulkOutEndPt->WaitForXfer(&outOvLap, 100);
USBDevice->BulkInEndPt->WaitForXfer(&inOvLap, 100);

USBDevice->BulkOutEndPt->FinishDataXfer(buffer, length, &outOvLap,
outContext);
USBDevice->BulkInEndPt->FinishDataXfer(inBuf, length, &inOvLap,
inContext);
```

```
CloseHandle( outOvLap. hEvent );  
CloseHandle( inOvLap. hEvent );
```

12.5 bIn

bool CCyUSBEndPoint::bIn[Previous](#) [Top](#) [Next](#)

Description

bIn indicates whether or not the endpoint is an IN endpoint.

IN endpoints transfer data from the USB device to the Host (PC).

Endpoint addresses with the high-order bit set (0x8_) are IN endpoints. Endpoint addresses with the high-order bit cleared (0x0_) are OUT endpoints.

bIn is not valid for [CCyControlEndPoint](#) objects (such as CCyUSBDevice->ControlEndPt).

Example

```
// Find a second bulk IN endpoint in the EndPoints[] array
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );
CCyBulkEndPoint *BulkIn2 = NULL;
int eptCount = USBDevice->EndPointCount();

for ( int i=1; i<eptCount; i++) {
    bool bIn = ( ( USBDevice->EndPoints[ i ]->Address & 0x80 ) == 0x80 );
    bool bBulk = ( USBDevice->EndPoints[ i ]->Attributes == 2 );

    if ( bBulk && bIn ) {
        BulkIn2 = ( CCyBulkEndPoint *) USBDevice->EndPoints[ i ];
        if ( BulkIn2 == USBDevice->BulkInEndPt )
            BulkIn2 = NULL;
    }
}
```

12.6 CCyUSBEndPoint()

CCyUSBEndPoint::CCyUSBEndPoint(void)

[Previous](#) [Top](#) [Next](#)

Description

This is the default constructor for the CCyUSBEndPoint class.

Because CCyUSBEndPoint is an abstract class, you cannot instantiate an object of CCyUSBEndPoint. That is, the statement:

```
new CCyUSBEndPoint( );
```

would result in a compiler error.

The default constructor initializes most of its data members to zero. It sets the default endpoint Timeout to 10 seconds. It sets bln to false, and sets hDevice to INVALID_HANDLE_VALUE.

12.7 CCyUSBEndPoint()

```
CCyUSBEndPoint::CCyUSBEndPoint(HANDLE h,  
PUSB_ENDPOINT_DESCRIPTOR  
pEndPtDescriptor)
```

[Previous](#) [Top](#) [Next](#)

Description

This is the primary constructor for the CCyUSBEndPoint class.

Because CCyUSBEndPoint is an abstract class, you cannot instantiate an object of CCyUSBEndPoint. That is, the statement:

```
new CCyUSBEndPoint( h, pEndPtDesc );
```

would result in a compiler error.

However, the constructor does get called (automatically) in the process of constructing derived endpoint classes.

This constructor sets most of its data members to their corresponding fields in the **pEndPtDescriptor** structure. It sets the default endpoint Timeout to 10 seconds. It sets its hDevice member to **h**.

12.8 CCyUSBEndPoint()

**CCyUSBEndPoint::CCyUSBEndPoint(
CCyUSBEndPoint& ept)**

[Previous](#) [Top](#) [Next](#)

Description

This is the *copy* constructor for the CCyUSBEndPoint class.

This constructor copies all of the simple data members of ept.

Because CCyUSBEndPoint is an abstract class, you cannot invoke this constructor explicitly. Instead, it gets called as a side effect of invoking the copy constructors for [CCyControlEndPoint](#), [CCyBulkEndPoint](#), [CCyIsocEndPoint](#) and [CCyInterruptEndPoint](#).

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );  
CCyControlEndPoint *ctlEpt = new CCyControlEndPoint( *USBDevice->  
ControlEndPt );
```

12.9 DscLen

UCHAR CCyUSBEndPoint::DscLen

[Previous](#) [Top](#) [Next](#)

Description

DscLen contains the length of the endpoint descriptor as reported in the **bLength** field of the `USB_ENDPOINT_DESCRIPTOR` structure that was passed to the endpoint object's constructor.

Because the passed descriptor was an endpoint descriptor, this value should always be 0x07. This data member exists for completeness and debugging purposes. You should normally never need to access this data member.

12.10 DscType

UCHAR CCyUSBEndPoint::DscType

[Previous](#) [Top](#) [Next](#)

Description

DscType contains the type of the endpoint descriptor as reported in the **bDescriptorType** field of the USB_ENDPOINT_DESCRIPTOR structure that was passed to the endpoint object's constructor.

Because the passed descriptor was an endpoint descriptor, this value should always be 0x05. This data member exists for completeness and debugging purposes. You should normally never need to access this data member.

12.11 GetXferSize()

ULONG CCyUSBEndPoint::GetXferSize(void)

[Previous](#) [Top](#) [Next](#)

Description

This function is no longer supported. It is available in the library to keep backward compatibility with legacy library and application.

For more information on USB transfer size please refer to the following link from Microsoft : <http://msdn.microsoft.com/en-us/library/ff538112.aspx>

Following is the maximum transfer size limit set into the CyUSB3.sys driver for various transfer types:

Bulk Transfers	4 MBytes
Interrupt Transfers	4 MBytes
Full Speed Isochronous Transfers	256 frames of data
High Speed and Super Speed Isochronous Transfers	1024 frames

12.12 FinishDataXfer()

```
bool CCyUSBEndPoint::FinishDataXfer(PCHAR
buf, LONG &len, OVERLAPPED *ov, PCHAR
pXmitBuf, CCyIsoPktInfo* pktInfos = NULL)
```

[Previous](#) [Top](#) [Next](#)

Description

FinishDataXfer is an advanced method for performing asynchronous IO.

FinishDataXfer transfers any received bytes into **buf**. It sets the **len** parameter to the actual number of bytes transferred. Finally, **FinishDataXfer** frees the memory associated with the **pXmitBuf** pointer. This pointer would have been returned by a previous corresponding call to [BeginDataXfer](#).

The pointer to the OVERLAPPED structure, passed in the **ov** parameter, should be the same one that was passed to the corresponding **BeginDataXfer** method.

The **pktInfos** parameter is optional and points to an array of [CCyIsoPktInfo](#) objects when present. It should only be used for Isochronous endpoint transfers.

You will usually want to use the synchronous [XferData](#) method rather than the asynchronous **BeginDataXfer/WaitForXfer/FinishDataXfer** approach.

Example

```
// This example assumes that the device automatically sends back
// over its bulk-IN endpoint, any bytes that were received over its
// bulk-OUT endpoint (commonly referred to as a loopback function)
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
OVERLAPPED outOvLap, inOvLap;

outOvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_OUT");
inOvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_IN");

unsigned char inBuf[128];
ZeroMemory(inBuf, 128);

unsigned char buffer[128];
LONG length = 128;

// Request the return data before initiating the loopback
UCHAR *inContext = USBDevice->BulkInEndPt->BeginDataXfer(inBuf, length,
&inOvLap);
UCHAR *outContext = USBDevice->BulkOutEndPt->BeginDataXfer(buffer,
length, &outOvLap);

USBDevice->BulkOutEndPt->WaitForXfer( &outOvLap, 100);
USBDevice->BulkInEndPt->WaitForXfer( &inOvLap, 100);

USBDevice->BulkOutEndPt->FinishDataXfer(buffer, length, &outOvLap,
outContext);
USBDevice->BulkInEndPt->FinishDataXfer(inBuf, length, &inOvLap,
inContext);
```

```
CloseHandle( outOvLap. hEvent );  
CloseHandle( inOvLap. hEvent );
```

12.13 hDevice

HANDLE CCyUSBEndPoint::hDevice

[Previous](#) [Top](#) [Next](#)

Description

hDevice contains a handle to the USB device driver, through which all the IO is carried-out. The handle is created by the [Open\(\)](#) method of a [CCyUSBDevice](#) object.

The only reason to access this data member would be to call the device driver explicitly, bypassing the API library methods. ***This is not recommended.***

You should never call CloseHandle(hDevice) directly. Instead, call the [Close\(\)](#) method of a CCyUSBDevice object.

Note that an instance of CCyUSBDevice will contain several [CCyUSBEndPoint](#) objects. Each of those will have the same value for their hDevice member. Also, the endpoint's hDevice member will be identical to its container CCyUSBDevice object's private hDevice member (accessed via the [DeviceHandle\(\)](#) method).

12.14 Interval

UCHAR CCyUSBEndPoint::Interval

[Previous](#) [Top](#) [Next](#)

Description

Interval contains the value reported in the **Interval** field of the USB_ENDPOINT_DESCRIPTOR structure that was passed to the endpoint object's constructor.

12.15 MaxPktSize

UCHAR CCyUSBEndPoint::MaxPktSize

[Previous](#) [Top](#) [Next](#)

Description

MaxPktSize contains the value indicated by the **wMaxPacketSize** field of the USB_ENDPOINT_DESCRIPTOR structure that was passed to the endpoint object's constructor.

For High Speed High Bandwidth endpoints, **MaxPktSize** is calculated by multiplying the low-order 11 bits of **wMaxPacketSize** by the value represented by 1 + the next 2 bits (bits 11 and 12).

For USB 3.0 Bulk and Interrupt Endpoints, the **MaxPktSize** contains the value indicated by **wMaxPacketSize** field of the USB_ENDPOINT_DESCRIPTOR structure multiplied by the (1 + bMaxBurst) field of the Super Speed Companion descriptor.

For USB 3.0 Isochronous Endpoints, the **MaxPktSize** contains the value indicated by **wMaxPacketSize** field of the USB_ENDPOINT_DESCRIPTOR structure multiplied by the (1 + bMaxBurst) and (1 + bmAttributes) fields of the Super Speed Companion descriptor

NOTE: For ISOC transfers, the buffer length and the endpoint's transfers size (see [SetXferSize](#)) must be a multiple of 8 times the endpoint's [MaxPktSize](#).

Example

Full Speed Device	
wMaxPacketSize = 0x03FF	1023 bytes
wMaxPacketSize = 0x0040	64 bytes
High Speed Device	
wMaxPacketSize = 0x0200	512 bytes
wMaxPacketSize = 0x0880	$128 * (1 + 1) = 256$ bytes
wMaxPacketSize = 0x1400	$1024 * (1 + 2) = 3072$ bytes
Super Speed Device	
Bulk, wMaxPacketSize = 0x0400, bMaxBurst = 0	$1024 * (1 + 0) = 1024$ bytes
Bulk, wMaxPacketSize = 0x0400, bMaxBurst = 0x07	$1024 * (1 + 7) = 8192$ bytes
Interrupt, wMaxPacketSize = 0x0400, bMaxBurst = 0x02	$1024 * (1 + 2) = 3072$ bytes
Isochronous, wMaxPacketSize = 0x0400, bMaxBurst = 0x03, bmAttributes = 0x02	$1024 * (1 + 3) * (1 + 2) = 12288$ bytes

12.16 NtStatus

ULONG CCyUSBEndPoint::NtStatus[Previous](#) [Top](#) [Next](#)

Description

NtStatus member contains the error code returned by the driver from the last call to the [XferData](#), [BeginDataXfer](#), [FinishDataXfer](#) or [Abort](#) methods.

This member has the same functionality as Windows System Error Code mapper, otherwise known by Win32 API name "GetLastError()". In a swiftly changing system environment, keeping a separate tracker to distinguish endpoint specific system errors from global system error is very helpful. So, this member capture endpoint specific NT status errors (if any exist).

This member will automatically be cleared by those library function calls which will in turn use windows driver API's for its intended functionality. So, it is recommended to refer to the NtStatus and UsbdStatus values to understand any failure returned by XferData or BeginDataXfer function calls.

NTStatus is a 32 bit numerical status defined by Microsoft. Please see the [MSDN documentation for NTStatus](#) for a description of each NTStatus value.

Please refer to the [UsbdStatus](#) member for more information on the USB related errors.

12.17 Reset()

```
bool CCyUSBEndPoint::Reset(void)
```

[Previous](#) [Top](#) [Next](#)

Description

The Reset method resets the endpoint, clearing any error or stall conditions on that endpoint.

Pending data transfers are not cancelled by the Reset method.

Call [Abort](#)() for the endpoint in order to force completion of any transfers in-process.

12.18 SetXferSize()

```
void CCyUSBEndPoint::SetXferSize(ULONG xfer  
)
```

[Previous](#) [Top](#) [Next](#)

Description

This function is no longer supported. It is available to keep backward compatibility with legacy library and application.

For more information on USB transfer size, please refer to the following link from Microsoft: <http://msdn.microsoft.com/en-us/library/ff538112.aspx>

Following is the maximum transfer size limit set into the CyUSB3.sys driver for various transfer types:

Bulk Transfers	4 MBytes
Interrupt Transfers	4 MBytes
Full Speed Isochronous Transfers	256 frames of data
High Speed and Super Speed Isochronous Transfers	1024 frames

12.19 TimeOut

ULONG CCyUSBEndPoint::TimeOut

[Previous](#) [Top](#) [Next](#)

Description

TimeOut limits the length of time that a [XferData](#)() call will wait for the transfer to complete.

The unit of **TimeOut** is milliseconds.

NOTE: For [CCyControlEndPoint](#), the **TimeOut** is rounded down to the nearest 1000 ms, except for values between 0 and 1000 which are rounded up to 1000.

Set the TimeOut values to 0xFFFFFFFF(INFINITE), to wait for infinite time on any transfer (Bulk, Isochronous, Interrupt or Control).

When TimeOut is set to 0 for bulk, interrupt or isochronous transfers; XferData does not wait for read/write operation to complete and will return immediately.

The TimeOut value 0 for control transfer is rounded up to 1000ms.

The default TimeOut for Bulk, Interrupt, Control, and Isochronous transfer is 10 seconds. User can override this value depending upon their application needs.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);

if ( USBDevice->BulkOutEndPt) {
    unsigned char buf[ 128];
    LONG length = 128;

    // Set the timeout to 1 second
    USBDevice->BulkOutEndPt->TimeOut = 1000;
    USBDevice->BulkOutEndPt->XferData( buf, length);
}
```

12.20 UsbdStatus

ULONG CCyUSBEndPoint::UsbdStatus

[Previous](#) [Top](#) [Next](#)

Description

UsbdStatus member contains an error code returned from the last call to the `XferData` or `BeginDataXfer` methods.

`UsbdStatus` can be decoded by passing the value to the [CCyUSBDevice::UsbdStatusString\(\)](#) method.

Any failure in library function calls that will end-up performing an active USB transaction, will set this member to a value returned by Microsoft USB D Stack. This member will carry information about the USB failure occurred from the USB Host perspective. This member together with [NtStatus](#) provides detailed description about any functionality failure coming from the library APIs such as `XferData`, `BeginDataXfer`, `FinishDataXfer` etc.

This member will be cleared by any library APIs which initiate a new USB transaction.

12.21 WaitForXfer()

```
bool CCyUSBEndPoint::WaitForXfer(
OVERLAPPED *ov, ULONG tOut)
```

[Previous](#) [Top](#) [Next](#)

Description

This method is used in conjunction with [BeginDataXfer](#) and [FinishDataXfer](#) to perform asynchronous IO.

The **ov** parameter points to the OVERLAPPED object that was passed in the preceding BeginDataXfer call.

tOut limits the time, in milliseconds, that the library will wait for the transaction to complete.

You will usually want to use the synchronous [XferData](#) method rather than the asynchronous BeginDataXfer/WaitForXfer/FinishDataXfer approach.

Example

```
// This example assumes that the device automatically sends back
// over its bulk-IN endpoint, any bytes that were received over its
// bulk-OUT endpoint (commonly referred to as a loopback function)
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
OVERLAPPED outOvLap, inOvLap;

outOvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_OUT");
inOvLap.hEvent = CreateEvent( NULL, false, false, L"CYUSB_IN");

unsigned char inBuf[128];
ZeroMemory(inBuf, 128);

unsigned char buffer[128];
LONG length = 128;

// Request the return data before initiating the loopback
UCHAR *inContext = USBDevice->BulkInEndPt->BeginDataXfer(inBuf, length,
&inOvLap);
UCHAR *outContext = USBDevice->BulkOutEndPt->BeginDataXfer(buffer,
length, &outOvLap);

USBDevice->BulkOutEndPt->WaitForXfer(&outOvLap, 100);
USBDevice->BulkInEndPt->WaitForXfer(&inOvLap, 100);

USBDevice->BulkOutEndPt->FinishDataXfer(buffer, length, &outOvLap,
outContext);
USBDevice->BulkInEndPt->FinishDataXfer(inBuf, length, &inOvLap,
inContext);

CloseHandle(outOvLap.hEvent);
CloseHandle(inOvLap.hEvent);
```

12.22 XferData()

```
bool CCyUSBEndPoint::XferData(PUCHAR buf,
LONG &bufLen, CCyIsoPktInfo* pktInfos)
```

[Previous](#) [Top](#) [Next](#)

Description

XferData sends or receives **len** bytes of data from / into **buf**.

This is the primary IO method of the library for transferring data. Most data transfers should occur by invoking the **XferData** method of an instantiated endpoint object.

XferData calls the appropriate [BeginDataXfer](#) method for the instantiated class (one of [CCyBulkEndPoint](#), [CCyControlEndPoint](#), [CCyInterruptEndPoint](#), or [CCyIsocEndPoint](#)). It then waits for the transaction to complete (or until the endpoint's [TimeOut](#) expires), and finally calls the [FinishDataXfer](#) method to complete the transaction. It calls [Abort\(\)](#) method internally if the operation fails.

For all non-control endpoints, the direction of the transfer is implied by the endpoint itself (each such endpoint will either be an IN or an OUT endpoint).

For control endpoints, the [Direction](#) must be specified, along with the other control-specific parameters.

XferData performs synchronous (i.e. blocking) IO operations. It does not return until the transaction completes or the endpoint's [TimeOut](#) has elapsed.

Returns **true** if the transaction successfully completes before [TimeOut](#) has elapsed.

Note that the **len** parameter is a reference, meaning that the method can modify its value. The number of bytes actually transferred is passed back in **len**.

The **pktInfos** parameter is optional and points to an array of [CCyIsoPktInfo](#) objects. It should only be used for Isochronous endpoint transfers.

NOTE: For ISOC transfers, the buffer length and the endpoint's transfers size (see [SetXferSize](#)) must be a multiple of 8 times the endpoint's [MaxPktSize](#).

Please refer [XferData for Isochronous transfer](#) for the usage of the **XferData** for isochronous transfers.

The code sample below demonstrates the usage of **XferData()** api for bulk and interrupt transfers.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

if ( USBDevice->BulkOutEndPt ) {
    unsigned char buf[ 128 ];
    LONG length = 128;

    USBDevice->BulkOutEndPt->XferData( buf, length );
}
```


12.23 ssdscLen

UCHAR CCyUSBEndPoint::ssdscLen

[Top](#) [Previous](#) [Next](#)

Description

ssdscLen contains the length of the superspeed endpoint companion descriptor as reported in the *bLength* field of the USB_SUPERPEED_ENDPOINT_COMPANION_DESCRIPTOR structure that was passed to the endpoint object's constructor.

Because the passed descriptor was an endpoint descriptor, this value should always be 0x06. This data member exists for completeness and debugging purposes. You should normally never need to access this data member.

12.24 ssdscType

UCHAR CCyUSBEndPoint::ssdsType[Top](#) [Previous](#) [Next](#)**Description**

ssdscType contains the type of the superspeed endpoint companion descriptor as reported in the bDescriptorType field of the USB_SUPERPEED_ENDPOINT_COMPANION_DESCRIPTOR structure that was passed to the endpoint object's constructor.

Because the passed descriptor was an endpoint descriptor, this value should always be 0x30. This data member exists for completeness and debugging purposes. You should normally never need to access this data member.

12.25 ssmaxburst

UCHAR CCyUSBEndPoint::ssmaxburst

[Top](#) [Previous](#) [Next](#)

Description

ssmaxburst contains the value indicated by the bMaxBurst field of the USB_SUPER SPEED_ENDPOINT_COMPANION_DESCRIPTOR structure that was passed to the endpoint object's constructor.

The ssmaxburst represent the maximum number of packets the endpoint can send or receive as part of a burst. Valid values are from 0 to 15. A value of 0 indicates that the endpoint can only burst one packet at a time and a value of 16 indicates that the endpoint can burst up to 16 packets at a time.

For endpoint of type control, this shall be set to 0.

12.26 ssbmAttribute

UCHAR CCyUSBEndPoint::ssbmAttribute

[Top](#) [Previous](#) [Next](#)

Description

ssbmAttribute contains the value indicated by the bmAttributes field of the USB_SUPER SPEED_ENDPOINT_COMPANION_DESCRIPTOR structure that was passed to the endpoint object's constructor.

ssbmAttribute represent different information based on the type of endpoint.

Bulk Endpoint

Bits 4:0

MaxStream, the maximum number of streams supported by the endpoint. Valid values are from 0 to 15, where 0 indicates that the endpoint does not support Streams. For other values, the number of streams supported will be power (2, MaxStream).

Note: The CyUsb3.sys driver and the CyAPI library do not support data transfers from/to stream enabled bulk endpoints.

Reserved. Shall be set to 0.

Bits 7:5

Control and Interrupt Endpoints

Bits 7:0

Reserved. Shall be set to 0.

Isochronous Endpoints

Bits 1:0

Mult. A zero based value that determines the number of burst transfers that the endpoint can support within a service interval.

Bits 7:2

Reserved. Shall be set to 0.

12.27 ssbytesperinterval

USHORT CCyUSBEndPoint::ssbyteperinterval

[Top](#) [Previous](#) [Next](#)

Description

ssbyteperinterval contains the value indicated by the wBytesPerInterval field of the USB_SUPER SPEED_ENDPOINT_COMPANION_DESCRIPTOR structure that was passed to the endpoint object's constructor.

For periodic (Isochronous or Interrupt) endpoints, this value represents the total number of bytes the endpoint will transfer every service interval.

For an Isochronous endpoint, this value is used to reserve the bus time in the schedule, required for the frame data payloads per 125us. The pipe may on an ongoing basis, actually use less bandwidth than that was reserved. If necessary, the device can report the actual bandwidth used via a non-USB defined mechanism.

13 CCyUSBInterface

CCyUSBInterface Class

[Previous](#) [Top](#) [Next](#)

Header

CyUSB.h

Description

CCyUSBInterface represents a USB device interface. Such interfaces can have one or more endpoints.

When [CCyUSBDevice::Open\(\)](#) is called, an instance of [CCyUSBConfig](#) is constructed for each configuration reported by the open device's device descriptor. (In most cases, there is just one configuration per device.)

In the process of construction, CCyUSBConfig creates instances of CCyUSBInterface for each interface exposed in the device's configuration descriptor. In turn, the CCyUSBInterface class creates instances of [CCyUSBEndPoint](#) for each endpoint descriptor contained in the interface descriptor. In this iterative fashion, the entire structure of Configs->Interfaces->Endpoints gets populated from a single construction of the CCyUSBConfig class.

The below example code shows the usage of the CCyUSBInterface class in an application.

Example

```
// This code snippet lists all the endpoints reported
// by the device under all interfaces and configurations.

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

char buf[ 512 ];
string s;

for ( int c=0; c<USBDevice->ConfigCount(); c++)
{
    CCyUSBConfig cfg = USBDevice->GetUSBConfig( c );

    // Print all configuration descriptor fields
    sprintf_s( buf, "bLength: 0x%x\n", cfg.bLength );
    s.append( buf );

    sprintf_s( buf, "bDescriptorType: %d\n", cfg.bDescriptorType );
    s.append( buf );

    sprintf_s( buf, "wTotalLength: %d (0x%x)\n", cfg.wTotalLength, cfg.
wTotalLength );
    s.append( buf );

    sprintf_s( buf, "bNumInterfaces: %d\n", cfg.bNumInterfaces );
    s.append( buf );
}
```

```
    sprintf_s(buf, "bConfigurationValue: %d\n", cfg.bConfigurationValue);
    s.append(buf);

    sprintf_s(buf, "iConfiguration: %d\n", cfg.iConfiguration);
    s.append(buf);

    sprintf_s(buf, "bmAttributes: 0x%x\n", cfg.bmAttributes);
    s.append(buf);

    sprintf_s(buf, "MaxPower: %d\n", cfg.MaxPower);
    s.append(buf);
    s.append("*****\n");

    cout<<s;
    s.clear();

    for (int i=0; i<cfg.AltInterfaces; i++)
    {
        // Print all interface descriptor fields
        CCyUSBInterface *ifc = cfg.Interfaces[i];
        sprintf_s(buf, "Interface Descriptor: %d\n", (i+1));
        s.append(buf);

        sprintf_s(buf, "-----\n");
        s.append(buf);

        sprintf_s(buf, "bLength: 0x%x\n", ifc->bLength);
        s.append(buf);

        sprintf_s(buf, "bDescriptorType: %d\n", ifc->bDescriptorType);
        s.append(buf);

        sprintf_s(buf, "bInterfaceNumber: %d\n", ifc->bInterfaceNumber);
        s.append(buf);

        sprintf_s(buf, "bAlternateSetting: %d\n", ifc->bAlternateSetting);
        s.append(buf);

        sprintf_s(buf, "bNumEndpoints: %d\n", ifc->bNumEndpoints);
        s.append(buf);

        sprintf_s(buf, "bInterfaceClass: %d\n", ifc->bInterfaceClass);
        s.append(buf);
        sprintf_s(buf, "*****\n"); s.append(buf);

        cout<<s;
        s.clear();

        for (int e=0; e<ifc->bNumEndpoints; e++)
        {
            // Print all endpoint descriptor fields
            CCyUSBEndPoint *ept = ifc->EndPoints[e+1];
            sprintf_s(buf, "EndPoint Descriptor: %d\n", (e+1));
```

```
s.append( buf );

sprintf_s( buf, "-----\n" );
s.append( buf );

sprintf_s( buf, "bLength: 0x%x\n", ept->DscLen );
s.append( buf );

sprintf_s( buf, "bDescriptorType: %d\n", ept->DscType );
s.append( buf );

sprintf_s( buf, "bEndpointAddress: 0x%x\n", ept->Address );
s.append( buf );

sprintf_s( buf, "bmAttributes: 0x%x\n", ept->Attributes );
s.append( buf );

sprintf_s( buf, "wMaxPacketSize: %d\n", ept->MaxPktSize );
s.append( buf );

sprintf_s( buf, "bInterval: %d\n", ept->Interval );
s.append( buf );
s.append( "*****\n" );

cout<<s;
s.clear();
}
}
}
```


13.1 bAlternateSetting

UCHAR CCyUSBInterface::bAlternateSetting

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the **bAlternateSetting** field from the currently selected interface's interface descriptor.

13.2 bAltSettings

UCHAR CCyUSBInterface::bAltSettings

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the number of valid alternate interface settings exposed by this interface.

For an interface that exposes a primary interface and two alternate interfaces, this value would be 3.

See [CCyUSBDevice::AltIntfcCount\(\)](#).

13.3 bDescriptorType

UCHAR CCyUSBInterface::bDescriptorType

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the **bDescriptorType** field of the USB_INTERFACE_DESCRIPTOR structure that was passed to the interface object's constructor.

Because the passed descriptor was an interface descriptor, this value should always be 0x04. This data member exists for completeness and debugging purposes. You should normally never need to access this data member.

13.4 CCyUSBInterface()

```
CCyUSBInterface::CCyUSBInterface:(HANDLE  
h, PUSB_INTERFACE_DESCRIPTOR  
pIntfcDescriptor)
```

[Previous](#) [Top](#) [Next](#)

Description

This is the constructor for the [CCyUSBInterface](#) class.

It reads [bNumEndpoint](#) endpoint descriptors and creates the appropriate type of endpoint object for each one, saving a pointer to each new endpoint in the class' [EndPoints](#) array.

13.5 CCyUSBInterface()

```
CCyUSBInterface::CCyUSBInterface:(  
    CCyUSBInterface& intfc)
```

[Previous](#) [Top](#) [Next](#)

Description

This is the *copy* constructor for the [CCyUSBInterface](#) class.

This constructor copies all of the simple data members of **intfc**. It then walks through **intfc**'s [EndPoints](#) array, making copies of every endpoint referenced there and storing pointers to the new copies in its own EndPoints array.

You should usually not call the copy constructor explicitly. It is called by the copy constructor for [CCyUSBConfig](#) when [CCyUSBDevice::GetUSBConfig\(\)](#) is called.

The below example shows how you could create a copy of the first interface exposed by a device.

Example

```
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );  
CCyUSBConfig cfg = USBDevice->GetUSBConfig( 0 );  
CCyUSBInterface *iface = new CCyUSBInterface( *cfg.Interfaces[ 0 ] );
```

13.6 bInterfaceClass

UCHAR CCyUSBInterface::bInterfaceClass

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the **bInterfaceClass** field from the currently selected interface's interface descriptor.

13.7 bInterfaceNumber

UCHAR CCyUSBInterface::bInterfaceNumber

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the **bInterfaceNumber** field from the currently selected interface's interface descriptor.

13.8 bInterfaceProtocol

UCHAR CCyUSBInterface::bInterfaceProtocol

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the **bInterfaceProtocol** field from the currently selected interface's interface descriptor.

13.9 bInterfaceSubClass

UCHAR CCyUSBInterface::bInterfaceSubClass

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the **bInterfaceSubClass** field from the currently selected interface's interface descriptor.

13.10 bLength

UCHAR CCyUSBInterface::bLength

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the **bLength** field from the currently selected interface's interface descriptor. It indicates the length of the interface descriptor.

Because the descriptor is an interface descriptor, this value should always be 0x09.

13.11 bNumEndpoints

UCHAR CCyUSBInterface::bNumEndpoints

[Previous](#) [Top](#) [Next](#)

Description

This data member contains the **bNumEndpoints** field from the currently selected interface's interface descriptor. It indicates how many endpoint descriptors are returned for the selected interface.

13.12 EndPoints

**CCyUSBEndPoint* CCyUSBInterfac::EndPoints[
MAX_ENDPTS]**

[Previous](#) [Top](#) [Next](#)

Description

This is the key data member of the CCyUSBInterface class. It is an array of pointers to CCyUSBEndPoint objects that represent the endpoint descriptors returned, by the device, for the interface.

The [CCyUSBDevice::EndPoints](#) member is actually a pointer to the currently selected interface's EndPoints array.

Example

```
// This code snippet lists all the endpoints reported
// by the device under all interfaces and configurations.

CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL );

char buf[ 512 ];
string s;

for ( int c=0; c<USBDevice->ConfigCount(); c++)
{
    CCyUSBConfig cfg = USBDevice->GetUSBConfig( c );

    // Print all configuration descriptor fields
    sprintf_s( buf, "bLength: 0x%x\n", cfg. bLength );
    s. append( buf );

    sprintf_s( buf, "bDescriptorType: %d\n", cfg. bDescriptorType );
    s. append( buf );

    sprintf_s( buf, "wTotalLength: %d (0x%x)\n", cfg. wTotalLength, cfg.
wTotalLength );
    s. append( buf );

    sprintf_s( buf, "bNumInterfaces: %d\n", cfg. bNumInterfaces );
    s. append( buf );

    sprintf_s( buf, "bConfigurationValue: %d\n", cfg. bConfigurationValue );
    s. append( buf );

    sprintf_s( buf, "iConfiguration: %d\n", cfg. iConfiguration );
    s. append( buf );

    sprintf_s( buf, "bmAttributes: 0x%x\n", cfg. bmAttributes );
    s. append( buf );

    sprintf_s( buf, "MaxPower: %d\n", cfg. MaxPower );
    s. append( buf );
}
```

```
s.append("*****\n");

cout<<s;
s.clear();

for (int i=0; i<cfg.AltInterfaces; i++)
{
    // Print all interface descriptor fields
    CCyUSBInterface *ifc = cfg.Interfaces[i];
    sprintf_s(buf, "Interface Descriptor: %d\n", (i+1));
    s.append(buf);

    sprintf_s(buf, "-----\n");
    s.append(buf);

    sprintf_s(buf, "bLength: 0x%x\n", ifc->bLength);
    s.append(buf);

    sprintf_s(buf, "bDescriptorType: %d\n", ifc->bDescriptorType);
    s.append(buf);

    sprintf_s(buf, "bInterfaceNumber: %d\n", ifc->bInterfaceNumber);
    s.append(buf);

    sprintf_s(buf, "bAlternateSetting: %d\n", ifc->bAlternateSetting);
    s.append(buf);

    sprintf_s(buf, "bNumEndpoints: %d\n", ifc->bNumEndpoints);
    s.append(buf);

    sprintf_s(buf, "bInterfaceClass: %d\n", ifc->bInterfaceClass);
    s.append(buf);
    sprintf_s(buf, "*****\n"); s.append(buf);

    cout<<s;
    s.clear();

    for (int e=0; e<ifc->bNumEndpoints; e++)
    {
        // Print all endpoint descriptor fields
        CCyUSBEndPoint *ept = ifc->Endpoints[e+1];
        sprintf_s(buf, "EndPoint Descriptor: %d\n", (e+1));
        s.append(buf);

        sprintf_s(buf, "-----\n");
        s.append(buf);

        sprintf_s(buf, "bLength: 0x%x\n", ept->DscLen);
        s.append(buf);

        sprintf_s(buf, "bDescriptorType: %d\n", ept->DscType);
        s.append(buf);
    }
}
```

```
    sprintf_s(buf, "bEndpointAddress: 0x%x\n", ept->Address);  
    s.append(buf);  
  
    sprintf_s(buf, "bmAttributes: 0x%x\n", ept->Attributes);  
    s.append(buf);  
  
    sprintf_s(buf, "wMaxPacketSize: %d\n", ept->MaxPktSize);  
    s.append(buf);  
  
    sprintf_s(buf, "bInterval: %d\n", ept->Interval);  
    s.append(buf);  
    s.append("*****\n");  
  
    cout<<s;  
    s.clear();  
}  
}  
}
```

13.13 iInterface

UCHAR CCyUSBInterface::iInterface

[Previous Top](#)

Description

This data member contains the **iInterface** field from the currently selected interface's interface descriptor.

This data member exists for completeness and debugging purposes. You should normally never need to access this data member.

14 CCyUSBBOS

CCyUSBBOS class

[Top](#) [Previous](#) [Next](#)

Header

CyAPI.h

Description

CCyUSBBOS represents a USB 3.0 device BOS descriptor.

When [CCyUSBDevice::Open\(\)](#) is called, an instance of CCyUSBBOS is constructed if the current device is a USB 3.0 device.

In the process of construction, CCyUSBBOS creates instances for each capability. If device does not define specific capability in the BOS descriptor, then the value of the instance will be NULL.

The capability types supported are: [CCyBOS_USB20_DEVICE_EXT](#), [CCyBOS_SS_DEVICE_CAPABILITY](#) and [CCyBOS_CONTAINER_ID](#).

The following example code shows how you can use the CCyUSBBOS class in an application.

Example

```
// This code lists the BOS device capability descriptor
char buf[512];
string s;
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
CCyUSBBOS *bos = USBDevice->UsbBos;

sprintf_s( buf, "BOS  Descriptor");
s.append( buf);
sprintf_s( buf, "-----");
s.append( buf);
sprintf_s( buf, "bLength:  0x%x", bos->bLength);
s.append( buf);
sprintf_s( buf, "bDescriptorType:  %d", bos->bDescriptorType);
s.append( buf);
sprintf_s( buf, "wTotalLength:  %d", bos->wTotalLength);
s.append( buf);
sprintf_s( buf, "bNumDeviceCaps:  %d", bos->bNumDeviceCaps);
s.append( buf);
sprintf_s( buf, "*****");
s.append( buf);

cout<<s;
s.clear();

// Print the USB 2.0 Device Extension descriptor if found
if( bos->pUSB20_DeviceExt)
{
```



```

CCyBosUSB20Extesnion *Usb20Ext = bos->pUSB20_DeviceExt;

sprintf_s(buf, "USB20 Device Extension Descriptor");
s.append(buf);
sprintf_s(buf, "-----");
s.append(buf);
sprintf_s(buf, "bLength: 0x%x", Usb20Ext->bLength);
s.append(buf);
sprintf_s(buf, "bDescriptorType: %d", Usb20Ext->bDescriptorType);
s.append(buf);
sprintf_s(buf, "bDevCapabilityType: %d", Usb20Ext->bDevCapabilityType);
s.append(buf);
sprintf_s(buf, "bmAttribute: %d", Usb20Ext->bmAttribute);
s.append(buf);
sprintf_s(buf, "*****");
s.append(buf);

cout<<s;
s.clear();
}

// Print the SuperSpeed Device Capability descriptor if found
if(bos->pSS_DeviceCap)
{
    CCyBosSuperSpeedCapability *ssCap = bos->pSS_DeviceCap;

    sprintf_s(buf, "Super Speed Device capability Descriptor");
    s.append(buf);
    sprintf_s(buf, "-----");
    s.append(buf);
    sprintf_s(buf, "bLength: 0x%x", ssCap->bLength);
    s.append(buf);
    sprintf_s(buf, "bDescriptorType: %d", ssCap->bDescriptorType);
    s.append(buf);
    sprintf_s(buf, "bDevCapabilityType: %d", ssCap->bDevCapabilityType);
    s.append(buf);
    sprintf_s(buf, "bmAttribute: %d", ssCap->bmAttribute);
    s.append(buf);
    sprintf_s(buf, "SpeedsSuported: %d", ssCap->SpeedsSuported);
    s.append(buf);
    sprintf_s(buf, "bFunctionalitySupported: %d", ssCap->
>bFunctionalitySupporte);
    s.append(buf);
    sprintf_s(buf, "bU1DevExitLat: %d", ssCap->bU1DevExitLat);
    s.append(buf);
    sprintf_s(buf, "bU2DevExitLat: %d", ssCap->bU2DevExitLat);
    s.append(buf);
    sprintf_s(buf, "*****");
    s.append(buf);

    cout<<s;
    s.clear();
}

```

```
// Print the Container ID descriptor if found
if( bos->pContainer_ID)
{
    CCyBosContainerID *ContID = bos->pContainer_ID;

    sprintf_s( buf, "Container ID Descriptor");
    s.append( buf);
    sprintf_s( buf, "-----");
    s.append( buf);
    sprintf_s( buf, "bLength: 0x%x", ContID->bLength);
    s.append( buf);
    sprintf_s( buf, "bDescriptorType: %d", ContID->bDescriptorType);
    s.append( buf);
    sprintf_s( buf, "bDevCapabilityType: %d", ContID->bDevCapabilityType);
    s.append( buf);
    sprintf_s( buf, "bReserved: %d", ContID->bReserved);
    s.append( buf);
    sprintf_s( buf, "ContainerID: %s", ContID->ContainerID);
    s.append( buf);
    sprintf_s( buf, "*****");
    s.append( buf);

    cout<<s;
    s.clear();
}
```

14.1 pContainer_ID

CCyBosContainerID *pContainer_ID

[Top](#) [Previous](#) [Next](#)

Description

pContainer ID is a [CCyBOSContainerID](#) object representing the USB 3.0 device container ID of BOS. It can be NULL if the device does not define this capability, or if the device is a USB 2.0 device.

14.2 pUSB20_DeviceExt

CCyBosUSB20Extesnion *pUSB20_DeviceExt

[Top](#) [Previous](#) [Next](#)

Description

pUSB20_DeviceExt is a [CCyBosUSB20Extesnion](#) object that represents the USB 2.0 device extension capability of BOS. It can be null, if the device does not define this capability or if the device is a USB 2.0 device.

14.3 pSS_DeviceCap

CCyBosSuperSpeedCapability
*pSS_DeviceCap

[Top](#) [Previous](#) [Next](#)

Description

pSS_DeviceCap is a [CCyBosSuperSpeedCapability](#) object representing the USB3.0 device Super Speed capability of BOS. It can be NULL, if the device does not define this capability, or if the device is a USB 2.0 device.

14.4 bLength

UCHAR bLength[Top](#) [Previous](#) [Next](#)**Description**

This property returns the length of BOS descriptor.

14.5 bDescriptorType

UCHAR bDescriptorType

[Top](#) [Previous](#) [Next](#)

Description

bDescriptorType contains value of the **bDescriptorType** field from the selected BOS descriptor.

14.6 wTotalLength

USHORT wTotalLength[Top](#) [Previous](#) [Next](#)**Description**

wTotalLength contains value of the wTotalLength field from the selected BOS descriptor.

14.7 bNumDeviceCaps

UCHAR bNumDeviceCaps

[Top](#) [Previous](#) [Next](#)

Description

bNumDeviceCaps contains value of the **bNumberOfDeviceCapability** field from the selected BOS descriptor.

15 CCyBOSUSB20Extesnion

CCyBOSUSB20Extesnion class

[Top](#) [Previous](#) [Next](#)

Header

CyAPI.h

Description

CCyBOSUSB20Extesnion represents the USB 2.0 device extension capability descriptor of a USB 3.0 device

If the device defines the USB 2.0 device extension capability, then an instance of this class will be instantiated by the CCyUSBBOS class.

The following example code shows usage of the CCyUSBBOS class and CCyBOSUSB20Extesnion class in an application.

Example

```
// This code lists the BOS device capability descriptor
char buf[ 512];
string s;
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
CCyUSBBOS *bos = USBDevice->UsbBos;

// Print the USB 2.0 Device Extension descriptor if found
if( bos->pUSB20_DeviceExt)
{
    CCyBosUSB20Extesnion *Usb20Ext = bos->pUSB20_DeviceExt;

    sprintf_s( buf, "USB20 Device Extension Descriptor");
    s.append( buf);
    sprintf_s( buf, "-----");
    s.append( buf);
    sprintf_s( buf, "bLength: 0x%x", Usb20Ext->bLength);
    s.append( buf);
    sprintf_s( buf, "bDescriptorType: %d", Usb20Ext->bDescriptorType);
    s.append( buf);
    sprintf_s( buf, "bDevCapabilityType: %d", Usb20Ext->bDevCapabilityType);
    s.append( buf);
    sprintf_s( buf, "bmAttribute: %d", Usb20Ext->bmAttribute);
    s.append( buf);
    sprintf_s( buf, "*****");
    s.append( buf);

    cout<<s;
    s.clear();
}
```

15.1 bLength

UCHAR bLength

[Top](#) [Previous](#) [Next](#)

Description

bLength contains the value of bLength field of USB 2.0 Device extension descriptor.

15.2 bDescriptorType

UCHAR bDescriptorType

[Top](#) [Previous](#) [Next](#)

Description

bDescriptorType contains the value of bDescriptorType field of USB 2.0 Device extension descriptor.

15.3 bDevCapabilityType

UCHAR bDevCapabilityType

[Top](#) [Previous](#) [Next](#)

Description

bDevCapabilityType contains the value of bDevCapabilityType field of USB 2.0 Device extension descriptor.

15.4 bmAttribute

UINT bmAttribute[Top](#) [Previous](#) [Next](#)**Description**

bmAttribute contains the value of bmAttribute field of USB 2.0 Device extension descriptor.

16 CCyBOSSuperSpeedCapability

CCyBOSSuperSpeedCapability class

[Top](#) [Previous](#) [Next](#)

Header

CyAPI.h

Description

CCyBosSuperSpeedCapability represents the Super Speed device capability descriptor of a USB 3.0 device

If the device defines the SS device capability, then it will be instantiated by the [CCyUSBBOS](#) class.

The following example code shows the usage of the CCyBOSSuperSpeedCapability class in an application.

Examples

```
// This code lists the BOS device capability descriptor
char buf[ 512];
string s;
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
CCyUSBBOS *bos = USBDevice->UsbBos;

// Print the SuperSpeed Device Capability descriptor if found
if( bos->pSS_DeviceCap)
{
    CCyBosSuperSpeedCapability *ssCap = bos->pSS_DeviceCap;

    sprintf_s( buf, "Super Speed Device capability Descriptor");
    s.append( buf);
    sprintf_s( buf, "-----");
    s.append( buf);
    sprintf_s( buf, "bLength: 0x%x", ssCap->bLength);
    s.append( buf);
    sprintf_s( buf, "bDescriptorType: %d", ssCap->bDescriptorType);
    s.append( buf);
    sprintf_s( buf, "bDevCapabilityType: %d", ssCap->bDevCapabilityType);
    s.append( buf);
    sprintf_s( buf, "bmAttribute: %d", ssCap->bmAttribute);
    s.append( buf);
    sprintf_s( buf, "SpeedsSupported: %d", ssCap->SpeedsSupported);
    s.append( buf);
    sprintf_s( buf, "bFunctionalitySupported: %d", ssCap->
    bFunctionalitySupported);
    s.append( buf);
    sprintf_s( buf, "bU1DevExitLat: %d", ssCap->bU1DevExitLat);
    s.append( buf);
    sprintf_s( buf, "bU2DevExitLat: %d", ssCap->bU2DevExitLat);
    s.append( buf);
    sprintf_s( buf, "*****");
}
```

```
s.append( buf );  
  
cout<<s;  
s.clear();  
}
```


16.1 bLength

UCHAR bLength

[Top](#) [Previous](#) [Next](#)

Description

Length contains the value of bLength field of SS Device capability descriptor.

16.2 bDescriptorType

UCHAR bDescriptorType

[Top](#) [Previous](#) [Next](#)

Description

bDescriptorType contains the value of bDescriptorType field of SS Device capability descriptor.

16.3 bDevCapabilityType

UCHAR bDevCapabilityType

[Top](#) [Previous](#) [Next](#)

Description

bDevCapabilityType contains the value of bDevCapabilityType field of SS Device capability descriptor.

16.4 bmAttribute

UCHAR bmAttribute[Top](#) [Previous](#) [Next](#)**Description**

bmAttribute contains the value of bmAttribute field of SS Device capability descriptor.

16.5 SpeedsSupported

USHORT SpeedsSupported[Top](#) [Previous](#) [Next](#)

Description

SpeedsSupported contains the value of wSpeedsSupported field of SS Device capability descriptor.

16.6 bFunctionalitySupport

UCHAR bFunctionalitySupport[Top](#) [Previous](#) [Next](#)**Description**

bFunctionalitySupport contains the value of bFunctionalitySupport field of SS Device capability descriptor.

16.7 bU1DevExitLat

UCHAR bU1DevExitLat

[Top](#) [Previous](#) [Next](#)

Description

U1DevExitLat contains the value of U1DevExitLat field of SS Device capability descriptor.

16.8 bU2DevExitLat

USHORT bU2DevExitLat[Top](#) [Previous](#) [Next](#)**Description**

bU2DevExit contains the value of bU2DevExit field of SS Device capability descriptor.

17 CCyBOSContainerID

CCyBOSContainerID class

[Top](#) [Previous](#) [Next](#)

Header

CyAPI.h

Description

CCyBOSContainerID represents a USB 3.0 device container id descriptor.

If the device defines the SS device capability, then it will be instantiated by the [CCyUSBBOS](#) class.

The following example code shows how you might use the CCyBOSContainerID class in an application.

Examples

```
// This code lists the BOS device capability descriptor
char buf[ 512];
string s;
CCyUSBDevice *USBDevice = new CCyUSBDevice( NULL);
CCyUSBBOS *bos = USBDevice->UsbBos;

// Print the Container ID descriptor if found
if( bos->pContainer_ID)
{
    CCyBosContainerID *ContID = bos->pContainer_ID;

    sprintf_s( buf, "Container ID Descriptor");
    s.append( buf);
    sprintf_s( buf, "-----");
    s.append( buf);
    sprintf_s( buf, "bLength: 0x%x", ContID->bLength);
    s.append( buf);
    sprintf_s( buf, "bDescriptorType: %d", ContID->bDescriptorType);
    s.append( buf);
    sprintf_s( buf, "bDevCapabilityType: %d", ContID->bDevCapabilityType);
    s.append( buf);
    sprintf_s( buf, "bReserved: %d", ContID->bReserved);
    s.append( buf);
    sprintf_s( buf, "ContainerID: %s", ContID->ContainerID);
    s.append( buf);
    sprintf_s( buf, "*****");
    s.append( buf);

    cout<<s;
    s.clear();
}
```

17.1 bLength

UCHAR bLength[Top](#) [Previous](#) [Next](#)**Description**

bLength contains the value of bLength field of Container ID descriptor.

17.2 bDescriptorType

UCHAR bDescriptorType

[Top](#) [Previous](#) [Next](#)

Description

bDescriptorType contains the value of bDescriptorType field of Container ID descriptor.

17.3 bDevCapabilityType

UCHAR bDevCapabilityType

[Top](#) [Previous](#) [Next](#)

Description

bDevCapabilityType contains the value of bDevCapabilityType field of Container ID descriptor.

17.4 bReserved

UCHAR bReserved

[Top](#) [Previous](#) [Next](#)

Description

Reserved field of Container ID descriptor.

17.5 ContainerID

UCHAR [] ContainerID

[Top](#) [Previous](#) [Next](#)

Description

ContainerID contains the value of ContainerID field of Container ID descriptor.

18 USB_BOS_USB20_DEVICE_EXTENSION

struct _USB_BOS_USB20_DEVICE_EXTENSION
defined in CyUSB30_def.h

[Top](#) [Previous](#) [Next](#)

Description

The USB_BOS_USB20_DEVICE_EXTENSION structure is filled-in by the [GetBosUSB20DeviceExtensionDesc](#) method of [CCyUSBDevice](#). The structure is defined as:

```
typedef struct _USB_BOS_USB20_DEVICE_EXTENSION
{
    UCHAR bLength;
    UCHAR bDescriptorType;
    UCHAR bDevCapabilityType;
    UINT bmAttribute;
} USB_BOS_USB20_DEVICE_EXTENSION, *PUSB_BOS_USB20_DEVICE_EXTENSION;
```

Please refer to USB 3.0 specification section 9.6.2.1 for detailed description of each parameter.

19 USB_BOS_SS_DEVICE_CAPABILITY

struct _USB_BOS_SS_DEVICE_CAPABILITY
defined in CyUSB30_def.h

[Top](#) [Previous](#) [Next](#)

Description

The USB_BOS_SS_DEVICE_CAPABILITY structure is filled-in by the [GetBosSSCapabilityDescriptor](#) method of [CCyUSBDevice](#).

The structure is defined as:

```
typedef struct _USB_BOS_SS_DEVICE_CAPABILITY
{
    UCHAR bLength;
    UCHAR bDescriptorType;
    UCHAR bDevCapabilityType;
    UCHAR bmAttribute;
    USHORT wSpeedsSupported;
    UCHAR bFunctionalitySupported;
    UCHAR bU1DevExitLat;
    USHORT bU2DevExitLat;
} USB_BOS_SS_DEVICE_CAPABILITY, *PUSB_BOS_SS_DEVICE_CAPABILITY;
```

Please refer to USB 3.0 specification section 9.6.2.2 for detailed description of each parameter.

20 USB_BOS_CONTAINER_ID

struct _USB_BOS_CONTAINER_ID
defined in CyUSB30_def.h

[Top](#) [Previous](#) [Next](#)

Description

The USB_BOS_CONTAINER_ID structure is filled-in by the [GetBosContainedIDDescriptor](#) method of [CCyUSBDevice](#).

The structure is defined as:

```
typedef struct _USB_BOS_CONTAINER_ID
{
    UCHAR bLength;
    UCHAR bDescriptorType;
    UCHAR bDevCapabilityType;
    UCHAR bReserved;
    UCHAR ContainerID[ USB_BOS_CAPABILITY_TYPE_CONTAINER_ID_SIZE ];
} USB_BOS_CONTAINER_ID, *PUSB_BOS_CONTAINER_ID;
```

Please refer to USB 3.0 specification section 9.6.2.3 for detailed description of each parameter.

21 USB_BOS_DESCRIPTOR

struct _USB_BOS_DESCRIPTOR
defined in CyUSB30_def.h

[Top](#) [Previous](#) [Next](#)

Description

The USB_BOS_DESCRIPTOR structure is filled-in by the [GetBosDescriptor](#) method of [CCyUSBDevice](#).

The structure is defined as:

```
typedef struct _USB_BOS_DESCRIPTOR
{
    UCHAR bLength;
    UCHAR bDescriptorType;
    USHORT wTotalLength;
    UCHAR bNumDeviceCaps;
} USB_BOS_DESCRIPTOR, *PUSB_BOS_DESCRIPTOR;
```

Please refer to USB 3.0 specification section 9.6.2 for detailed description of each parameter.

22 FX3_FWDOWNLOAD_MEDIA_TYPE

enum FX3_FWDOWNLOAD_MEDIA_TYPE

[Top](#) [Previous](#) [Next](#)

Description

This enum defines the types of media to which FX3 firmware can be downloaded through the USB link. The following media types are defined:

RAM	- Download firmware to Ram.
I2CE2PROM	- Download firmware to I2C E2PROM.
SPIFLASH	- Download firmware to SPI FLASH.

23 FX3_FWDOWNLOAD_ERROR_CODE

enum FX3_FWDOWNLOAD_ERROR_CODE

[Top](#) [Previous](#) [Next](#)

Description

This type defines status codes that can be returned by the [DownloadFw](#) method of the [CCyFX3Device](#) class.

Status Code

SUCCESS

FAILED

INVALID_FILE

INVALID_MEDIA_TYPE

INVALID_FWSIGNATURE

DEVICE_CREATE_FAILED

INCORRECT_IMAGE_LENGTH

SPILASH_ERASE_FAILED

I2CE2PROM_UNKNOWN_I2C_SIZE

CORRUPT_FIRMWARE_IMAGE_FILE

Description

Firmware download successful

Firmware download failed

Invalid file

Given Input Media type is not supported

Invalid Firmware Signature

Device Open failed

Firmware image length is incorrect

SPI FLASH erase operation failed

Unknown I2CE2PROM size: unknown value parsed from 2nd byte of IMG file

Corrupt Firmware image file

24 How to Link with CyAPI.lib

Please follow the below steps to add CyAPI.lib to your project:

- 1 Adding CyAPI.h header file path to your project
 - 1.1 Select Project properties
 - 1.2 Select the "General" node under "C/C++"
 - 1.3 Add the path to the header files (for example, "C:\Program Files (x86)\Cypress\EZ-USB FX3 SDK\1.3\library\cpp\inc") under "Additional Include Directories".
- 2 Linking CyAPI.lib
 - 2.1 Select Project properties.
 - 2.2 Select 'Linker' node under the 'Configuration Properties'.
 - 2.3 Select the 'Input' node under the 'Linker'.
 - 2.4 Add lib path (including the lib name, for example, "C:\Program Files (x86)\Cypress\EZ-USB FX3 SDK\1.3\library\cpp\lib\x86\cyapi.lib") in the 'Additional Dependencies' edit box. Libraries for 32/64 bit available in the CySuiteUSB installation directory "library\cpp\lib". The directory 'x64' is for 64-bit library and the 'x86' directory is for 32-bit library.
- 3 Linking setupapi.lib in your project
 - 3.1 Select Project properties.
 - 3.2 Select 'Linker' node under the 'Configuration Properties'.
 - 3.3 Select the 'Input' node under the 'Linker'.
 - 3.4 Add lib 'setupapi.lib' in the 'Additional Dependencies' edit box. The setupapi.lib is a standard library and is available in the Microsoft SDK.

25 Features Not Supported

The Following features are not supported by CyAPI.lib

1. SET ADDRESS Feature

The SET ADDRESS Request cannot be implemented through Control Endpoint.

2. SYNC FRAME

The SYNC FRAME Request cannot be implemented through Control Endpoint.

3. USB 3.0 Bulk Streaming

Data transfer on stream enabled BULK endpoints is not supported.

4. Set/Get Transfer size

The [XferSize](#) variable to get/set the transfer size of endpoint is no longer supported. Please refer [XferSize](#) for more information.

Index

- D -

Data Transfers

Asynchronous Transfers 140

Synchronous Transfers 160

Descriptors

Configuration 82

Device 77

Endpoint 136

Interface 166

Listing Descriptor Contents 118

Devices

Finding USB Devices 46

Manufacturer 97

Product 103

Serial Number 108

- E -

Endpoints 75

Bulk Endpoints 54

Control Endpoints 64

Interrupt Endpoints 89

Isochronous Endpoints 95

- I -

Interfaces

Alternate Interfaces 110

- U -

uint 215