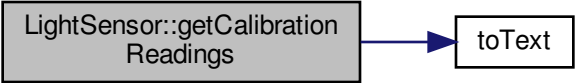


LightSensor::getCalibration  
Readings



```
graph LR; A[LightSensor::getCalibrationReadings] --> B[toText]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'LightSensor::getCalibrationReadings' in two lines. The right box is white with a black border and contains the text 'toText' in one line. A dark blue arrow points from the right side of the gray box to the left side of the white box.

toText