


PressureSensor::readPressure



```
graph LR; A[PressureSensor::readPressure] --> B[RollingAverage::updateAverage]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'PressureSensor::readPressure'. The right box is white and contains the text 'RollingAverage::updateAverage'. A blue arrow points from the right side of the gray box to the left side of the white box.

RollingAverage::updateAverage