

MATH50001/50017/50018 - Analysis II  
Complex Analysis

Lecture 4

## Section: Elementary functions.

### 1. Exponential function.

**Definition.** We define exponential  $e^z$  ( $z = x + iy \in \mathbb{C}$ ) as:

$$e^z = e^x \cos y + ie^x \sin y.$$

Properties:

- a) If  $y = 0$  then  $e^z = e^x$ .
- b)  $e^z$  is entire (holomorphic for any  $z \in \mathbb{C}$ )

Indeed, for that we check the C-R equations. Since  $u = \operatorname{Re} f = e^x \cos y$  and  $v = \operatorname{Im} f = e^x \sin y$ , we have

$$u'_x = e^x \cos y = v'_y \quad \text{and} \quad u'_y = e^x(-\sin y) = -v'_x.$$

c)

$$\frac{\partial}{\partial z} e^z = \frac{\partial}{\partial x} e^x \cos y + i \frac{\partial}{\partial x} e^x \sin y = e^z.$$

d) Let  $g(z)$  be holomorphic. Then

$$\frac{\partial}{\partial z} e^{g(z)} = e^{g(z)} g'(z).$$

e) Let  $z_1 = x_1 + iy_1$  and  $z_2 = x_2 + iy_2$ . Then

$$\begin{aligned} e^{z_1+z_2} &= e^{x_1+x_2} (\cos(y_1+y_2) + i \sin(y_1+y_2)) \\ &= e^{x_1+x_2} (\cos y_1 \cos y_2 - \sin y_1 \sin y_2 + i(\sin y_1 \cos y_2 + \cos y_1 \sin y_2)) \\ &= e^{x_1+x_2} (\cos y_1 + i \sin y_1)(\cos y_2 + i \sin y_2) = e^{z_1} e^{z_2}. \end{aligned}$$

f)  $|e^z| = |e^x| |e^{iy}| = e^x \sqrt{\cos^2 y + \sin^2 y} = e^x.$

The function  $e^z$  is  $2\pi$ -periodic with respect to  $y$ .

g) Applying the De Moivres formula

$$(\cos y + i \sin y)^n = \cos ny + i \sin ny$$

we obtain

$$(e^{iy})^n = e^{iny}.$$

h) Since  $\arg z = \arctan y/x$

$$\arg e^z = \arctan \frac{e^x \sin y}{e^x \cos y} = \arctan(\tan y) = y + 2\pi k, \quad k = 0, \pm 1, \pm 2, \dots$$

**Definition.** If  $f$  is holomorphic for all  $z \in \mathbb{C}$  then it calls *entire*.

Clearly the exponential function  $e^z$  is entire.

## 2. Trigonometric functions.

$$\begin{cases} e^{i\theta} = \cos \theta + i \sin \theta \\ e^{-i\theta} = \cos \theta - i \sin \theta \end{cases} \Rightarrow \begin{cases} \cos \theta = \frac{1}{2} (e^{i\theta} + e^{-i\theta}) \\ \sin \theta = \frac{1}{2i} (e^{i\theta} - e^{-i\theta}) \end{cases}$$

**Definition.** For any  $z \in \mathbb{C}$  we define

$$\sin z = \frac{1}{2i} (e^{iz} - e^{-iz}), \quad \cos z = \frac{1}{2} (e^{iz} + e^{-iz}).$$

Properties:

- a)  $\sin z$  and  $\cos z$  are entire functions
- b)  $\frac{\partial}{\partial z} \sin z = \cos z$  and  $\frac{\partial}{\partial z} \cos z = -\sin z$ .
- c)  $\sin^2 z + \cos^2 z = 1$ .

Indeed:

$$-\frac{1}{4} \left( e^{iz} - e^{-iz} \right)^2 + \frac{1}{4} \left( e^{iz} + e^{-iz} \right)^2 = \dots = 1.$$

d)

$$\sin(z_1 \pm z_2) = \sin z_1 \cos z_2 \pm \cos z_1 \sin z_2,$$

$$\cos(z_1 \pm z_2) = \cos z_1 \cos z_2 \mp \sin z_1 \sin z_2.$$

### 3. Logarithmic functions.

Let  $z = r(\cos \theta + i \sin \theta) = r e^{i\theta}$ .

**Definition.**  $\log z = \ln |z| + i \arg z = \log r + i(\theta + 2\pi k), \quad z \neq 0,$

where  $k = 0, \pm 1, \pm 2, \dots$

Clearly:

$$e^{\log z} = e^{\ln r + i(\theta + 2\pi k)} = r e^{i(\theta + 2\pi k)} = r (\cos \theta + i \sin \theta) = x + iy = z.$$

**Remark.** The function  $\log$  is a multi-valued function.

**Definition.** We define  $\text{Log } z$  as the single-valued function:

$$\text{Log } z = \ln |z| + i \arg z,$$

where  $\arg z$  is the principal value of the argument, namely,  $-\pi < \arg z \leq \pi$ .

**Remark.** The function  $\text{Log}$  is a single-valued function.

**Examples.**

$$\text{Log}(-1) = i\pi,$$

$$\text{Log}(2i) = \ln 2 + i\pi/2,$$

$$\text{Log}(1-i) = \ln \sqrt{2} - i\pi/4.$$

Properties:

a)  $\log(z_1 \cdot z_2) = \log(z_1) + \log(z_2)$ . Indeed

$$\begin{aligned}\log(z_1 \cdot z_2) &= \ln |z_1 z_2| + i \arg(z_1 \cdot z_2) \\ &= \ln |z_1| + \ln |z_2| + i \arg z_1 + i \arg z_2 = \log z_1 + \log z_2.\end{aligned}$$

**Remark.**  $\text{Log}(z_1 \cdot z_2) \neq \text{Log} z_1 + \text{Log} z_2$ , because  $\text{Arg}(z_1 \cdot z_2) \neq \text{Arg} z_1 + \text{Arg} z_2$ .

b) The function  $\text{Log } z$  is holomorphic in  $\mathbb{C} \setminus \{(-\infty, 0]\}$ .

Indeed, we have already checked that the C-R equations are satisfied:

$$\text{Log } z = \ln r + i\theta = u + iv, \quad -\pi < \theta \leq \pi.$$

Therefore we have

$$\frac{\partial u}{\partial r} = \frac{1}{r} \cdot 1 = \frac{1}{r} \frac{\partial v}{\partial \theta}, \quad \frac{\partial v}{\partial r} = 0 = -\frac{1}{r} \frac{\partial u}{\partial \theta}.$$

**Exercise.** Compute  $(\text{Log } z)'$ .

#### 4. Powers.

**Definition.** For any  $\alpha \in \mathbb{C}$ , we define  $z^\alpha = e^{\alpha \log z}$  as a multi-valued function.

**Example.**  $i^i = e^{i \log i} = e^{i(i\pi/2 + i2\pi k)} = e^{-\pi/2} e^{-2\pi k}$ ,  $k = 0, \pm 1, \pm 2, \dots$

**Definition.** We define the principal value of  $z^\alpha$ ,  $\alpha \in \mathbb{C}$ , as

$$z^\alpha = e^{\alpha \operatorname{Log} z}.$$

Property:

a)  $z^{\alpha_1} \cdot z^{\alpha_2} = e^{\alpha_1 \operatorname{Log} z} e^{\alpha_2 \operatorname{Log} z} = e^{(\alpha_1 + \alpha_2) \operatorname{Log} z} = z^{\alpha_1 + \alpha_2}.$

## Section: Parametrised curve.

**Definition.** A *parametrised curve* is a function  $z(t)$  which maps a closed interval  $[a, b] \subset \mathbb{R}$  to the complex plane. We say that the parametrised curve is smooth if  $z'(t)$  exists and is continuous on  $[a, b]$ , and  $z'(t) \neq 0$  for  $t \in [a, b]$ . At the points  $t = a$  and  $t = b$ , the quantities  $z'(a)$  and  $z'(b)$  are interpreted as the one-sided limits

$$z'(a) = \lim_{h \rightarrow 0, h > 0} \frac{z(a + h) - z(a)}{h}, \quad z'(b) = \lim_{h \rightarrow 0, h < 0} \frac{z(b + h) - z(b)}{h}.$$

Similarly we say that the parametrised curve is piecewise - smooth if  $z$  is continuous on  $[a, b]$  and if there exist a finite number of points  $a = a_0 < a_1 < \dots < a_n = b$ , where  $z(t)$  is smooth in the intervals  $[a_k, a_{k+1}]$ . In particular, the righthand derivative at  $a_k$  may differ from the left-hand derivative at  $a_k$  for  $k = 1, 2, \dots, n - 1$ .

Two parametrisations,

$$z: [a, b] \rightarrow \mathbb{C} \quad \text{and} \quad \tilde{z}: [c, d] \rightarrow \mathbb{C},$$

are equivalent if there exists a continuously differentiable bijection  $s \rightarrow t(s)$  from  $[c, d]$  to  $[a, b]$  so that  $t'(s) > 0$  and

$$\tilde{z}(s) = z(t(s)).$$

The condition  $t'(s) > 0$  says precisely that the orientation is preserved: as  $s$  travels from  $c$  to  $d$ , then  $t(s)$  travels from  $a$  to  $b$ .

Given a smooth curve  $\gamma$  in  $\mathbb{C}$  parametrised by  $z : [a, b] \rightarrow \mathbb{C}$ , and  $f$  a continuous function on  $\gamma$  we define the integral of  $f$  along  $\gamma$  by

$$\int_{\gamma} f(z) dz = \int_a^b f(z(t)) z'(t) dt.$$

In order for this definition to be meaningful, we must show that the right-hand integral is independent of the parametrisation chosen for  $\gamma$ . Say that  $\tilde{z}$  is an equivalent parametrisation as above. Then the change of variables formula and the chain rule imply that

$$\begin{aligned} \int_a^b f(z(t)) z'(t) dt &= \int_c^d f(z(t(s))) z'(t(s)) t'(s) ds \\ &= \int_c^d f(\tilde{z}(s)) \tilde{z}'(s) ds. \end{aligned}$$

This proves that the integral of  $f$  over  $\gamma$  is well defined.

If  $\gamma$  is piecewise smooth, then the integral of  $f$  over  $\gamma$  is the sum of the integrals of  $f$  over the smooth parts of  $\gamma$ , so if  $z(t)$  is a piecewise-smooth parametrisation as before, then

$$\int_{\gamma} f(z) dz = \sum_{k=0}^{n-1} \int_{a_k}^{a_{k+1}} f(z(t)) z'(t) dt.$$

We can define a curve  $\gamma^-$  obtained from the curve  $\gamma$  by reversing the orientation (so that  $\gamma$  and  $\gamma^-$  consist of the same points in the plane). As a particular parametrisation for  $\gamma^-$  we can take  $z^- : [a, b] \rightarrow \mathbb{C}$  defined by

$$z^-(t) = z(b + a - t).$$

A smooth or piecewise-smooth curve is closed if  $z(a) = z(b)$  for any of its parametrisations. A smooth or piecewise-smooth curve is simple if it is not self-intersecting, that is,  $z(t) \neq z(s)$  unless  $s = t$ , or  $s = a$  and  $t = b$ .

A basic example consists of a circle. Consider the circle  $C_r(z_0)$  centred at  $z_0$  and of radius  $r$ , which by definition is the set

$$C_r(z_0) = \{z \in \mathbb{C} : |z - z_0| = r\}.$$

The positive orientation (counterclockwise) is the one that is given by the standard parametrisation

$$z(t) = z_0 + r e^{it}, \quad \text{where } t \in [0, 2\pi],$$

while the negative orientation (clockwise) is given by

$$z(t) = z_0 + r e^{-it}, \quad \text{where } t \in [0, 2\pi].$$

## Section: Integration along curves.

By definition, the length of the smooth curve  $\gamma$  is

$$\text{length}(\gamma) = \int_a^b |z'(t)| dt = \int_a^b \sqrt{(x'(t))^2 + (y'(t))^2} dt.$$

# Quizzes

Question 1: Let  $f(z) = e^{iz^2}$ . What is true?

Answers:

- A.  $|f(z)| = 1$
- B. There is  $C > 0$  such that  $|f(z)| < C$
- C.  $f(z)$  is unbounded

Question 2: Which of the following functions are multivalued on the complex plane?

Answers:

A.  $e^z$

B.  $\log z$

C.  $z^{1/3}$

D.  $z^2$

Thank you