

Q1.

$$\begin{aligned}f(x) &= \int_{-\infty}^x g(t) dt = \int_{-\infty}^{\infty} g(t) H(x-t) dt \\&= g(x) * H(x)\end{aligned}$$

Convolution theorem: $\mathcal{F}\{f(n)\} = \mathcal{F}\{g(n) * h(n)\} =$
 $\hat{g}(w) \hat{h}(w) \Rightarrow$

$$\begin{aligned}\mathcal{F}\{h(n)\} = \hat{h}(w) &= \frac{\hat{g}(w)}{iw} + \pi \hat{g}(0) \delta(w) = \\&\quad \frac{\hat{g}(w)}{iw} + \pi \hat{g}(0) \delta(w)\end{aligned}$$

$$\hat{g}(0) = \int_{-\infty}^{\infty} g(x) dx \Rightarrow \hat{g}(0) = 0 \Rightarrow$$

$$\hat{f}(w) = \frac{\hat{g}(w)}{iw}$$

Q2

$$\frac{d^2y}{dx^2} = \frac{1}{2} e^y$$

$$u = \frac{dy}{dx} \Rightarrow \frac{du}{dx} = \frac{du}{dy} \frac{dy}{dx} = \frac{1}{2} e^y$$

$$\frac{1}{2} u^2 = \frac{1}{2} e^y \Rightarrow \frac{u^2}{2} = \frac{1}{2} e^y + C_1$$

$$\begin{aligned} y(0) &= 0 \\ y'(0) &= u(0) = 1 \end{aligned} \quad \Rightarrow \quad C_1 = 0 \Rightarrow u^2 = e^y$$

$$u = \frac{dy}{dx} = e^{\frac{y}{2}} \Rightarrow \int e^{-\frac{y}{2}} dy = \int dx$$

$$(-2) e^{-\frac{y}{2}} = x + C_2 \Rightarrow$$

$$\text{using } y(0) = 0 \Rightarrow C_2 = -2 \Rightarrow$$

$$e^{-\frac{y}{2}} = 1 - \frac{x}{2} \Rightarrow$$

$$\frac{y}{2} = \ln \frac{2}{2-x} \Rightarrow y = \ln \left[\left(\frac{2}{2-x} \right)^2 \right]$$

$$\textcircled{Q} 3 \quad \frac{d^2x}{dt^2} + \frac{dx}{dt} + \frac{x}{4} = te^{-\frac{t}{2}} + 1$$

$$1) \text{ 1st step } \quad \mathcal{L}[x_{CF}] = 0$$

$$CF = e^{\lambda t} \Rightarrow 4\lambda^2 + 4\lambda + 1 = 0 \Rightarrow$$

$$\lambda = \lambda_2 = -\frac{1}{2} \Rightarrow x_{CF} = C_1 e^{-\frac{1}{2}t} + C_2 t e^{-\frac{1}{2}t}$$

$$2) \text{ 2nd step } \quad \mathcal{L}[x_{PI}] = te^{-\frac{t}{2}} + 1$$

$$\text{Ansatz } x_{PI} = At^3 e^{-\frac{t}{2}} + B$$

$$\Rightarrow A = \frac{1}{6}, B = 4 \Rightarrow$$

$$x_{GS} = C_1 e^{-\frac{1}{2}t} + C_2 t e^{-\frac{1}{2}t} + \frac{1}{6} t^3 e^{-\frac{t}{2}} + 4$$

$$b) \quad \frac{dx}{dt} = u \Rightarrow$$

$$\begin{cases} \frac{du}{dt} = -u - \frac{x}{4} + te^{-\frac{t}{2}} + 1 \\ \frac{dx}{dt} = u \end{cases}$$

$$u_{GS} = \frac{dx_{GS}}{dt} = -\frac{1}{2}C_1 e^{-\frac{1}{2}t} - \frac{1}{2}C_2 t e^{-\frac{1}{2}t} + C_2 e^{-\frac{1}{2}t} + \frac{1}{2}t^2 e^{-\frac{t}{2}} - \frac{1}{12}t e^{\frac{3}{2}t}$$

$$x_{GS} = \begin{pmatrix} x_{GS} \\ u_{GS} \end{pmatrix} = C_1 \begin{pmatrix} 1 \\ -\frac{1}{2} \end{pmatrix} e^{-\frac{1}{2}t} + C_2 \begin{pmatrix} t \\ -\frac{1}{2}t + 1 \end{pmatrix} e^{-\frac{1}{2}t} + \begin{pmatrix} \frac{1}{6}t^3 e^{-\frac{t}{2}} + 4 \\ \frac{1}{2}t^2 (1 - \frac{1}{6}t) e^{-\frac{t}{2}} \end{pmatrix}$$

$$x_{CF} \quad x_{PI}$$