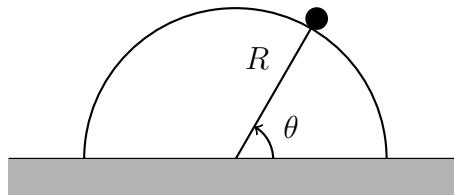


**Test 1**

1. The motion of a particle of mass  $m$  in the  $(x - y)$ -plane is governed by the Lagrangian

$$L = \frac{m}{2} (\dot{x}^2 + \dot{y}^2) - mgy.$$

- (a) i. Identify the kinetic energy and the potential energy of the particle.  
ii. What is the force acting on the particle? Is it a conservative force?  
[4 marks]
- (b) i. Obtain the equations of motion.  
ii. Write the Lagrangian in polar coordinates,  $(x, y) = (r \cos \theta, r \sin \theta)$ , and obtain the Euler-Lagrange equations for this Lagrangian.  
iii. Explicitly show that the equations obtained in parts i. and ii. are equivalent.  
*Hint: Compute  $\ddot{x}$  and  $\ddot{y}$  in polar coordinates and use the result from (b)ii.*  
[9 marks]
- (c) Now assume that the particle sits on a hemisphere of radius  $R$ , and that there are no frictional forces.



- i. Derive the equation of motion for  $\theta$  which governs the dynamics of the particle whilst it remains on the hemisphere.  
ii. Derive the normal constraint force imparted on the particle by the hemisphere, in terms of  $\theta$ .  
iii. Discuss the relationship between Newton's second law and the answers to parts i. and ii..

[12 marks]

[Total: 25 marks]

## Answers to Test 1

1. (a) i.

$$T = \frac{m}{2} (\dot{x}^2 + \dot{y}^2), \quad \text{and} \quad V = mgy.$$

[2 marks]

ii. The force is calculated as  $\mathbf{F} = -\nabla V$ , to give

$$\mathbf{F} = -mg\mathbf{j},$$

where  $\mathbf{j}$  is the unit vector in the  $y$ -direction. This is a conservative force since it has the form  $\mathbf{F} = -\nabla V$ .

[2 marks]

[1(a): 4 marks in total]

(b) i. The Euler-Lagrange equations give

$$\frac{d}{dt} (m\dot{x}) = 0, \quad \text{and} \quad \frac{d}{dt} (m\dot{y}) = -mg.$$

The equation of motion is therefore a particle in free fall

$$\ddot{x} = 0, \quad \text{and} \quad \ddot{y} = -g.$$

[2 marks]

ii. The Lagrangian in polar coordinates is

$$L = \frac{m}{2} \left( \dot{r}^2 + r^2 \dot{\theta}^2 \right) - mgr \sin \theta.$$

The corresponding Euler-Lagrange equations are, for  $r$  and  $\theta$  respectively, given by

$$\frac{d}{dt} (mr\dot{r}) = mr\dot{\theta}^2 - mg \sin \theta, \quad \text{and} \quad \frac{d}{dt} (mr^2\dot{\theta}) = -mgr \cos \theta.$$

Simplifying gives

$$\ddot{r} = r\dot{\theta}^2 - g \sin \theta, \quad \text{and} \quad r\ddot{\theta} + 2r\dot{\theta}\dot{\theta} = -g \cos \theta.$$

[3 marks]

iii. Since we have  $(x, y) = (r \cos \theta, r \sin \theta)$ , it follows that

$$\begin{aligned} \ddot{x} &= \ddot{r} \cos \theta - 2r\dot{\theta}\dot{\theta} \sin \theta - r\ddot{\theta} \sin \theta - r\dot{\theta}^2 \cos \theta, \\ \ddot{y} &= \ddot{r} \sin \theta + 2r\dot{\theta}\dot{\theta} \cos \theta + r\ddot{\theta} \cos \theta - r\dot{\theta}^2 \sin \theta. \end{aligned}$$

Now, using the Euler-Lagrange equation,  $\ddot{r} = r\dot{\theta}^2 - g \sin \theta$ , in each of the above equations gives

$$\begin{aligned} \ddot{x} &= -g \sin \theta \cos \theta - 2r\dot{\theta}\dot{\theta} \sin \theta - r\ddot{\theta} \sin \theta, \\ \ddot{y} &= -g \sin^2 \theta + 2r\dot{\theta}\dot{\theta} \cos \theta + r\ddot{\theta} \cos \theta. \end{aligned}$$

Now using the Euler-Lagrange equation  $r\ddot{\theta} + 2r\dot{\theta}^2 = -g \cos \theta$  in these equations gives

$$\begin{aligned}\ddot{x} &= 0, \\ \ddot{y} &= -g(\cos^2 \theta + \sin^2 \theta) = -g,\end{aligned}$$

as required.

[4 marks]

[1(b): 9 marks in total]

- (c) i. METHOD 1: Take the Lagrangian from (b) ii. and substitute in  $r = R$  to give

$$L = \frac{mR^2}{2}\dot{\theta}^2 - mgR \sin \theta.$$

The Euler-Lagrange equation for  $\theta$  is

$$\frac{d}{dt} \left( mR^2\dot{\theta} \right) = -mgR \cos \theta, \quad \text{or} \quad \ddot{\theta} = -\frac{g}{R} \cos \theta.$$

METHOD 2: Form a constrained Lagrangian as

$$L = \frac{m}{2} \left( \dot{r}^2 + r^2\dot{\theta}^2 \right) - mgr \sin \theta + \lambda(r - R).$$

The Euler-Lagrange equation for  $\theta$  is

$$\frac{d}{dt} \left( mr^2\dot{\theta} \right) = -mgr \cos \theta.$$

Using the variation in  $\lambda$  to conclude that  $r = R$ , the result follows. It is also valid to use the constraint  $r^2 - R^2 = 0$ .

[4 marks]

- ii. Determining the full Euler-Lagrange equations from the constrained Lagrangian above gives

$$\begin{aligned}\frac{d}{dt} (mr) &= mr\dot{\theta}^2 - mg \sin \theta + \lambda, \\ \frac{d}{dt} \left( mr^2\dot{\theta} \right) &= -mgr \cos \theta, \\ r &= R.\end{aligned}$$

The constraint force is then given by evaluating the first of these at  $r = R$  as

$$\lambda = -mR\dot{\theta}^2 + mg \sin \theta.$$

[6 marks]

- iii. The answer to part i. is Newton's second law tangentially to the hemisphere, and the radial Euler-Lagrange equation computed in part ii. is Newton's law understood in the radial direction.

[2 marks]

[1(c): 12 marks in total]