

Q1.

$$f(x) = \int_{-\infty}^x g(t) dt = \int_{-\infty}^{\infty} g(t) H(x-t) dt \\ = g(x) * H(x)$$

Convolution theorem: $\mathcal{F}\{f(x)\} = \mathcal{F}\{g(x) * H(x)\} =$
 $\hat{g}(\omega) \cdot \hat{H}(\omega) \Rightarrow$

$$\mathcal{F}\{f(x)\} = \hat{f}(\omega) = \frac{\hat{g}(\omega)}{i\omega} + \pi \hat{g}(\omega) \delta(\omega) =$$
$$\frac{\hat{g}(\omega)}{i\omega} + \pi \hat{g}(0) \delta(\omega)$$

$$\hat{g}(0) = \int_{-\infty}^{\infty} g(x) dx \Rightarrow \hat{g}(0) = 0 \Rightarrow$$

$$\underline{\underline{\hat{f}(\omega) = \frac{\hat{g}(\omega)}{i\omega}}}$$

Q2

$$\frac{d^2 y}{dx^2} = \frac{1}{2} e^y$$

$$u = \frac{dy}{dx} \Rightarrow \frac{du}{dx} = \frac{du}{dy} \frac{dy}{dx} = \frac{d}{dy} \left(\frac{1}{2} u^2 \right)$$

$$\frac{d}{dy} \left(\frac{1}{2} u^2 \right) = \frac{1}{2} e^y \Rightarrow \frac{u^2}{2} = \frac{1}{2} e^y + C_1$$

$$\left. \begin{array}{l} y(0) = 0 \\ y'(0) = u(0) = 1 \end{array} \right\} \Rightarrow C_1 = 0 \Rightarrow u^2 = e^y$$

$$u = \frac{dy}{dx} = e^{y/2} \Rightarrow \int e^{-y/2} dy = \int dx$$

$$(-2) e^{-y/2} = x + C_2 \Rightarrow$$

$$\text{using } y(0) = 0 \Rightarrow C_2 = -2 \Rightarrow$$

$$e^{-y/2} = 1 - \frac{x}{2} \Rightarrow$$

$$\frac{y}{2} = \ln \frac{2}{2-x} \Rightarrow y = \ln \left[\left(\frac{2}{2-x} \right)^2 \right]$$

③ $\frac{d^2 x}{dt^2} + \frac{dx}{dt} + \frac{x}{4} = te^{-\frac{t}{2}} + 1$

a) 1st step $\mathcal{L}[x_{CF}] = 0$

$$CF = e^{\lambda t} \Rightarrow 4\lambda^2 + 4\lambda + \lambda = 0 \Rightarrow$$

$$\lambda_1 = \lambda_2 = -\frac{1}{2} \Rightarrow x_{CF} = c_1 e^{-\frac{1}{2}t} + c_2 t e^{-\frac{1}{2}t}$$

2nd step $\mathcal{L}[x_{PI}] = te^{-\frac{t}{2}} + 1$

Ansatz $x_{PI} = At^3 e^{-\frac{t}{2}} + B$

$$\Rightarrow A = \frac{1}{6}, B = 4 \Rightarrow$$

$$x_{GS} = c_1 e^{-\frac{1}{2}t} + c_2 t e^{-\frac{1}{2}t} + \frac{1}{6} t^3 e^{-\frac{t}{2}} + 4$$

b) $\frac{dx}{dt} = u \Rightarrow$

$$\begin{cases} \frac{du}{dt} = -u - \frac{x}{4} + te^{-\frac{t}{2}} + 1 \\ \frac{dx}{dt} = u \end{cases}$$

$$u_{GS} = \frac{dx_{GS}}{dt} = -\frac{1}{2}c_1 e^{-\frac{1}{2}t} - \frac{1}{2}c_2 t e^{-\frac{1}{2}t} + c_2 e^{-\frac{1}{2}t} + \frac{1}{2}t e^{-\frac{t}{2}} - \frac{1}{12}t^2 e^{-\frac{t}{2}}$$

$$\vec{x} = \begin{pmatrix} x_{GS} \\ u_{GS} \end{pmatrix} = c_1 \underbrace{\begin{pmatrix} 1 \\ -\frac{1}{2} \end{pmatrix} e^{-\frac{1}{2}t}}_{\vec{x}_{CF}} + c_2 \underbrace{\begin{pmatrix} t \\ -\frac{1}{2}t + 1 \end{pmatrix} e^{-\frac{1}{2}t}}_{\vec{x}_{CF}} + \underbrace{\begin{pmatrix} \frac{1}{6}t^3 e^{-\frac{t}{2}} + 4 \\ \frac{1}{2}t^2 (1 - \frac{1}{6}t) e^{-\frac{t}{2}} \end{pmatrix}}_{\vec{x}_{PI}}$$