Simulation Requirements – MagNanoBridge (Updated with Expert Feedback)

1. Introduction

This document outlines the strict and detailed requirements for the development of a realistic magnetic nanoparticle simulation intended to model the temporary bridging of a bone fracture using magnetically guided particles. The simulation must be physically plausible, modular, clearly documented, and allow both interactive and pre-configured operation modes.

2. Project Folder Structure

The project must follow a modular, well-organized folder structure, suitable for collaborative scientific development and future expansion. The structure must separate core simulation logic, visualization, and documentation, with clear entry points and file responsibilities. A single monolithic file is explicitly not allowed.

The required structure (or a functionally equivalent layout) is as follows:

```
MagNanoBridge/
                     # Core Python code for the simulation
    -src/
                        # Main simulation entry point (minimal logic)
   ├── main.py
                        # Modules: magnetism, drag, dipole forces, collisions
   ⊢— physics/
                        # PID/AI-based control of field dynamics
   ├── control/
      utils/
                      # Math helpers, constants, tools
      config/
                       # YAML/JSON configs for full reproducibility
    -visualization/
                        # Web interface (Three.js/HTML) synced with simulation state
   ⊢—index.html
     —threejs/
                       # Modular IS components
                      # Icons, stylesheets, shaders
       -static/
                        # Jupyter/Colab exploration, analysis, optimization
   notebooks/
   -data/
                     # Simulation results: raw, processed, export
                     # Unit + integration tests for physics/logic (required)
├── tests/
   -doc/
                     # User/dev documentation, architecture, manuals
   requirements.txt
                          # Dependencies for Colab and offline use
Additional requirements:
```

- Python source code must be modular. No single-file architecture is allowed.
- The Python code must run in Google Colab with necessary installation cells.
- Three.js visualization must reflect the actual simulation state (not animations).
- Code must follow PEP-8 or equivalent standards and be documented.
- • Offline and online usage must be supported.
- README.md must describe usage, setup, structure, and contribution notes.

3. Core Functional Requirements

The simulation must:

- Allow the definition of a 3D FOCUS FIGURE (e.g., narrow cylinder or STL mesh) as target volume.
- • Support manual or file-based (CSV/JSON) configuration of this focus zone.
- Simulate the movement of magnetic nanoparticles influenced by multiple external coil fields
- Each nanoparticle must have: realistic mass, volume, dipole, and plastic shell.
- Dipole-dipole interaction between particles must be implemented (not approximated).
- Dipole logic must scale to >1000 particles. If needed, Fast Multipole Method or approximation must be discussed.
- Plastic shell must have adjustable thickness, separately visualized and physically present.
- Collisions must follow a Lennard-Jones or equivalent soft-sphere model.
- Brownian motion must be optionally included for nanoscale realism (via Langevin dynamics).
- Motion integration should use a stable method (e.g., Velocity Verlet or RK4).
- Field sources (coils) must be real (e.g., Biot-Savart) and not ideal dipoles unless justified.
- PID or AI-based control system must guide particles into focus zone in 'focus mode'.
- The objective function (e.g., density, volume coverage) for bridging success must be clearly defined.
- Real-time 3D rendering (Three.js) of full particle system with trails, shell, size.
- Allow slow-motion visual playback of movement, with toggle.
- Enable ID-based tracking and highlighting of individual particles.
- • Allow switch between 3D and 2D (cross-section) debug views.
- Export CSV or JSON of position, velocity, forces over time.
- Batch mode for non-visual, AI-optimized or multi-run experiments must be included.

4. Grounds for Rejection

The project will be rejected and payment withheld if any of the following conditions are met:

- Any single core requirement is missing or only partially implemented.
- • 3D focus zone is not functioning, controllable, or is not volumetric.
- Particles behave unrealistically (e.g., teleport, ignore forces).
- No mutual dipole-dipole force simulation or poorly implemented version.
- Collision logic missing or unphysical.
- • Simulation logic and rendering not aligned (e.g., faked visuals).
- Missing or incomplete modular structure.
- No data export, test suite, or config-based reproducibility.
- Time-varying or induced fields implemented against specifications.

• No PID/AI logic or no defined objective for 'focus mode'.

Note: Partial delivery, 'work in progress', or placeholder elements will not be accepted unless explicitly agreed upon in advance and in writing.

6. Ownership and Legal Enforcement

1. Exclusive Ownership:

Upon acceptance of this project, all intellectual property rights, source code, simulations, documentation, visualizations, and derivative works become the sole and exclusive property of the commissioning party (Oscar van Maarseveen). The developer or contractor waives any and all rights to reuse, resell, republish, or relicense any portion of the work, unless explicitly authorized in writing by the commissioning party.

2. Non-Disclosure and Exclusivity:

The contractor agrees not to share, discuss, or demonstrate any part of the developed codebase, logic, data, or visualization techniques with any third party, under any circumstances.

3. Breach and Penalty Clause:

In the event of unauthorized reuse, reproduction, publication, or distribution of the code, concepts, or simulation system, a contractual penalty of €100,000 per day will be due, plus €2,500 per additional calendar day, without prejudice to any further claims for actual damages.

4. Jurisdiction:

This agreement shall be governed by Dutch law. In the event of any legal dispute, the competent court shall be the **Rechtbank Midden-Nederland, location Utrecht**, unless otherwise mandated by law.