



Figure 5: Examples of the 3 multi-view datasets and their prediction results. The 3D density maps of PETS2009, DukeMTMC and CityStreet are thresholded by $5e-3$, $1e-3$ and $1e-3$, respectively. See the supplemental for more visualizations.

Compared to DukeMTMC and CityStreet, the best performance of PETS2009 is achieved at $h=40\text{cm}$. The people occlusion in PETS2009 is more severe and many people’s lower bodies are totally occluded from all views (e.g., the people in the middle). Thus, increasing the height resolution does not provide additional information of the body, but may introduce more noises (other people’s features) along the z -dim, thus leading to worse performance.

5 Conclusion and Discussion

In this paper, a DNN-based 3D multi-view counting method is proposed, which fuses camera-views to predict the 3D scene-level density map. 3D projection and fusion are used, which can handle the situation when people are not all located at the same height (e.g., people standing on a staircase), and provides a chance to solve the scale variation issue in the 3D space without a scale selection operation. The projection consistency measure between the 3D prediction and 2D density map ground-truth is studied and then utilized in the loss function to refine the 3D prediction further. Compared to other state-of-art multi-view counting methods, the proposed method achieves better or comparable counting performance as well as a more informative scene-level crowd representation.

In addition to counting humans, the proposed 3D multi-view counting method can also be applied to counting birds in the sky or the fish in the aquarium, where both the bird or the fish count can be obtained as well as their 3D location distributions – of course, this requires collecting more multi-view scenes. Except for object counting, since the 3D Gaussian kernels are used as ground-truth, the 3D prediction provides a vivid visualization for the scenes, as well as the potentials for other applications like observing the scene in

arbitrary view angles, which may contribute to better scene understanding, generation or visualization.

6 Acknowledgements

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