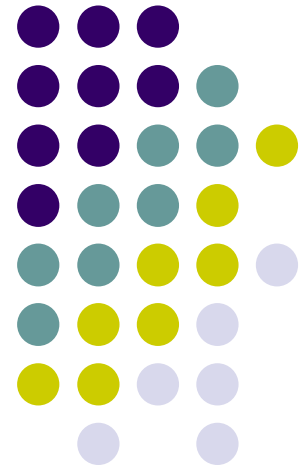
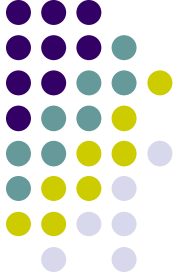


Machine Learning

Unsupervised Learning



Supervised learning vs. unsupervised learning

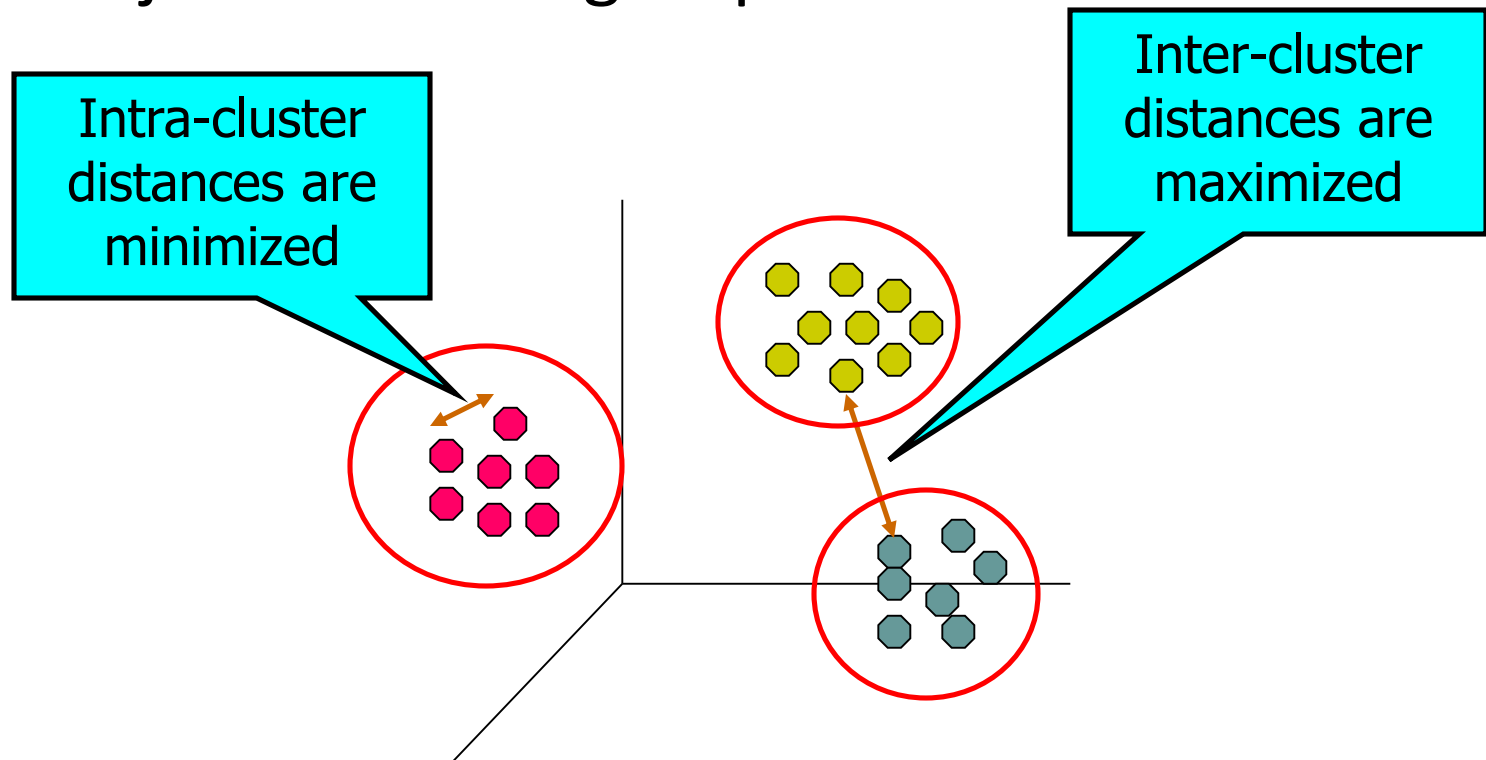


- **Supervised learning:** discover patterns in the data that relate data attributes with a target (class) attribute.
 - These patterns are then utilized to predict the values of the target attribute in future data instances
- **Unsupervised learning:** The data have no target attribute.
 - We want to explore the data to find some intrinsic structures in them.

What is Cluster Analysis?



- Finding groups of objects in data such that the objects in a group will be similar (or related) to one another and different from (or unrelated to) the objects in other groups



Applications of Cluster Analysis



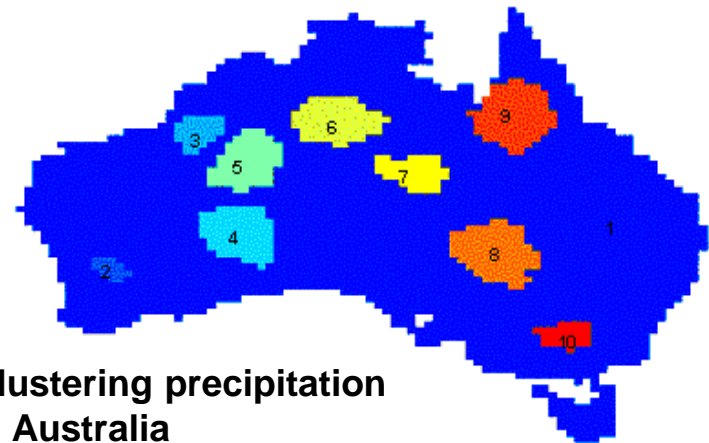
● Understanding

- Group related documents for browsing, group genes and proteins that have similar functionality, or group stocks with similar price fluctuations

	<i>Discovered Clusters</i>	<i>Industry Group</i>
1	Applied-Matl-DOWN,Bay-Network-Down,3-COM-DOWN,Cabletron-Sys-DOWN,CISCO-DOWN,HP-DOWN,DSC-Comm-DOWN,INTEL-DOWN,LSI-Logic-DOWN,Micron-Tech-DOWN,Texas-Inst-Down,Tellabs-Inc-Down,Natl-Semiconduct-DOWN,Oracl-DOWN,SGI-DOWN,Sun-DOWN	Technology1-DOWN
2	Apple-Comp-DOWN,Autodesk-DOWN,DEC-DOWN,ADV-Micro-Device-DOWN,Andrew-Corp-DOWN,Computer-Assoc-DOWN,Circuit-City-DOWN,Compaq-DOWN,EMC-Corp-DOWN,Gen-Inst-DOWN,Motorola-DOWN,Microsoft-DOWN,Scientific-Atl-DOWN	Technology2-DOWN
3	Fannie-Mae-DOWN,Fed-Home-Loan-DOWN,MBNA-Corp-DOWN,Morgan-Stanley-DOWN	Financial-DOWN
4	Baker-Hughes-UP,Dresser-Inds-UP,Halliburton-HLD-UP,Louisiana-Land-UP,Phillips-Petro-UP,Unocal-UP,Schlumberger-UP	Oil-UP

● Summarization

- Reduce the size of large data sets



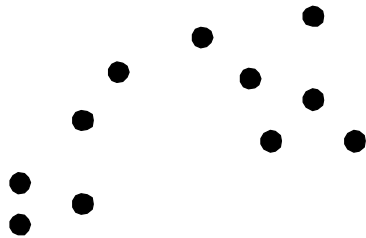
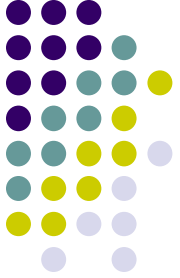
Clustering precipitation
in Australia

Types of Clusterings

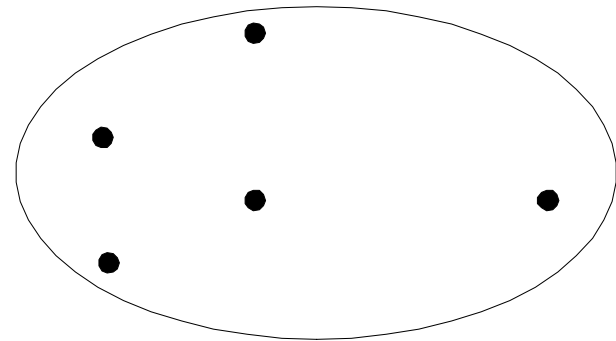
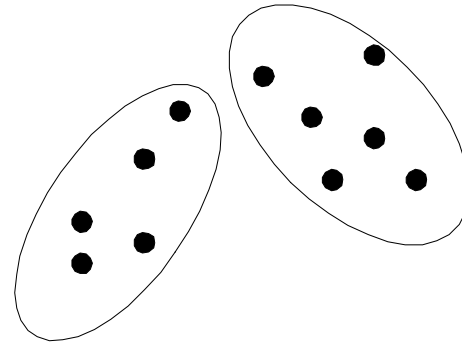


- A **clustering** is a set of clusters
- Important distinction between **hierarchical** and **partitional** sets of clusters
- Partitional Clustering
 - A division data objects into non-overlapping subsets (clusters) such that each data object is in exactly one subset
- Hierarchical clustering
 - A set of nested clusters organized as a hierarchical tree

Partitional Clustering

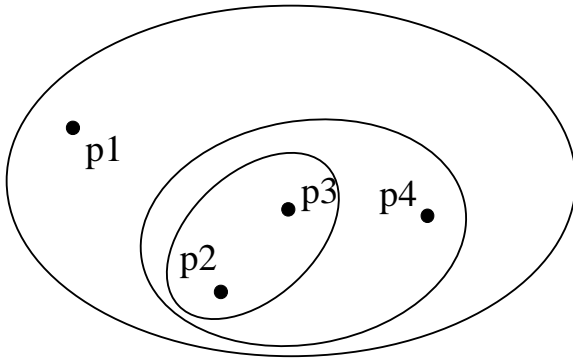
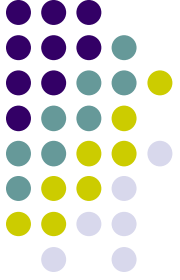


Original Points

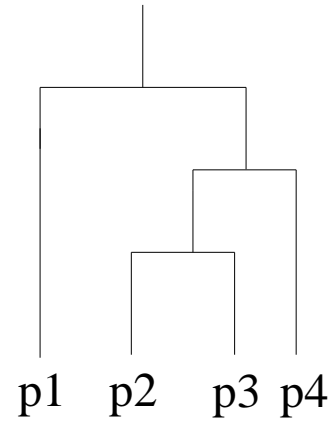


A Partitional Clustering

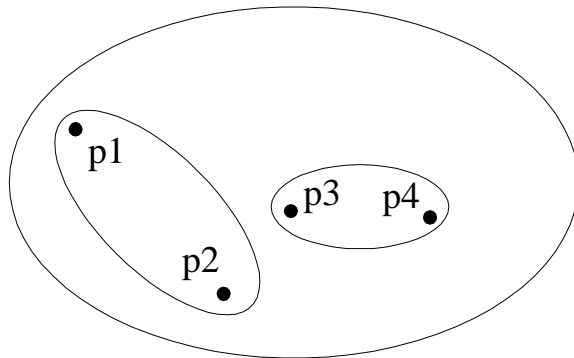
Hierarchical Clustering



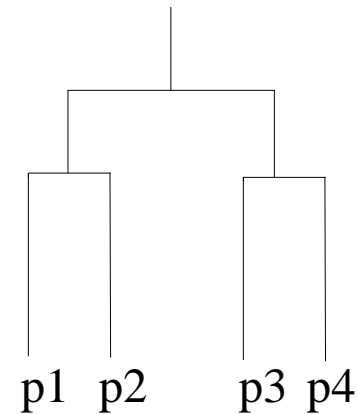
Traditional Hierarchical Clustering



Traditional Dendrogram



Non-traditional Hierarchical Clustering



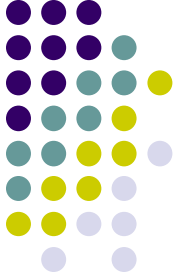
Non-traditional Dendrogram

Clustering Algorithms

- K-means and its variants
- Hierarchical clustering



K-means clustering



- K-means is a **partitional clustering** algorithm
- Let the set of data points (or instances) D be

$$\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\},$$

where $\mathbf{x}_i = (x_{i1}, x_{i2}, \dots, x_{ir})$ is a **vector** in a real-valued space $X \subseteq R^r$, and r is the number of attributes (dimensions) in the data.

- The k -means algorithm partitions the given data into k clusters.
 - Each cluster has a cluster **center**, called **centroid**.
 - k is specified by the user

K-means Clustering



- Basic algorithm

-
- 1: Select K points as the initial centroids.
 - 2: **repeat**
 - 3: Form K clusters by assigning all points to the closest centroid.
 - 4: Recompute the centroid of each cluster.
 - 5: **until** The centroids don't change
-

Stopping/convergence criterion



1. no (or minimum) re-assignments of data points to different clusters,
2. no (or minimum) change of centroids, or
3. minimum decrease in the **sum of squared error** (SSE),

$$SSE = \sum_{j=1}^k \sum_{\mathbf{x} \in C_j} \text{dist}(\mathbf{x}, \mathbf{m}_j)^2$$

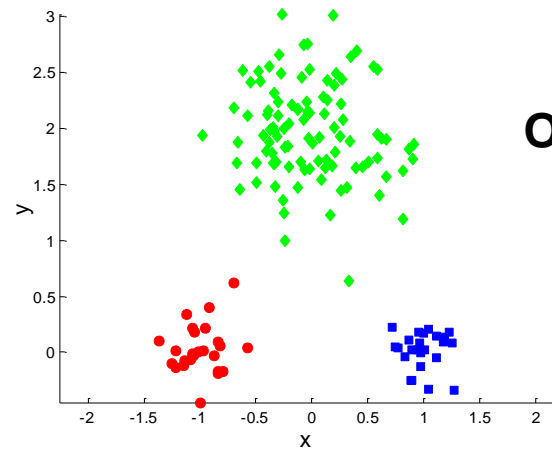
- C_j is the j th cluster, \mathbf{m}_j is the centroid of cluster C_j (the mean vector of all the data points in C_j), and $\text{dist}(\mathbf{x}, \mathbf{m}_j)$ is the distance between data point \mathbf{x} and centroid \mathbf{m}_j .

K-means Clustering – Details

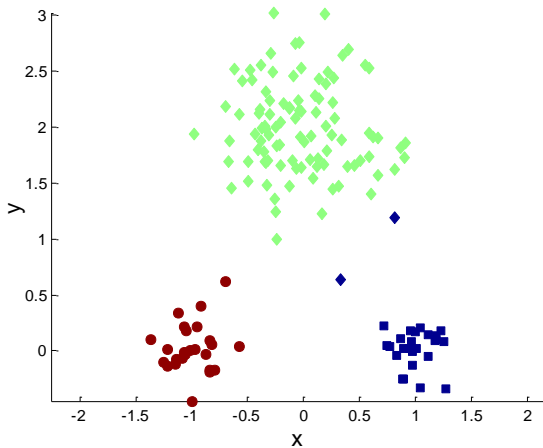


- Initial centroids are often chosen randomly.
 - Clusters produced vary from one run to another.
- The centroid is (typically) the mean of the points in the cluster.
- ‘Closeness’ is measured by Euclidean distance, cosine similarity, correlation, etc.
- K-means will converge for common similarity measures mentioned above.
- Most of the convergence happens in the first few iterations.
 - Often the stopping condition is changed to ‘Until relatively few points change clusters’
- Complexity is $O(n * K * l * d)$
 - n = number of points, K = number of clusters,
 l = number of iterations, d = number of attributes

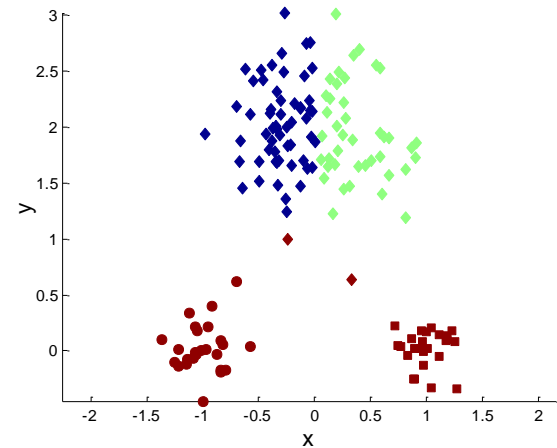
Two different K-means Clusterings



Original Points

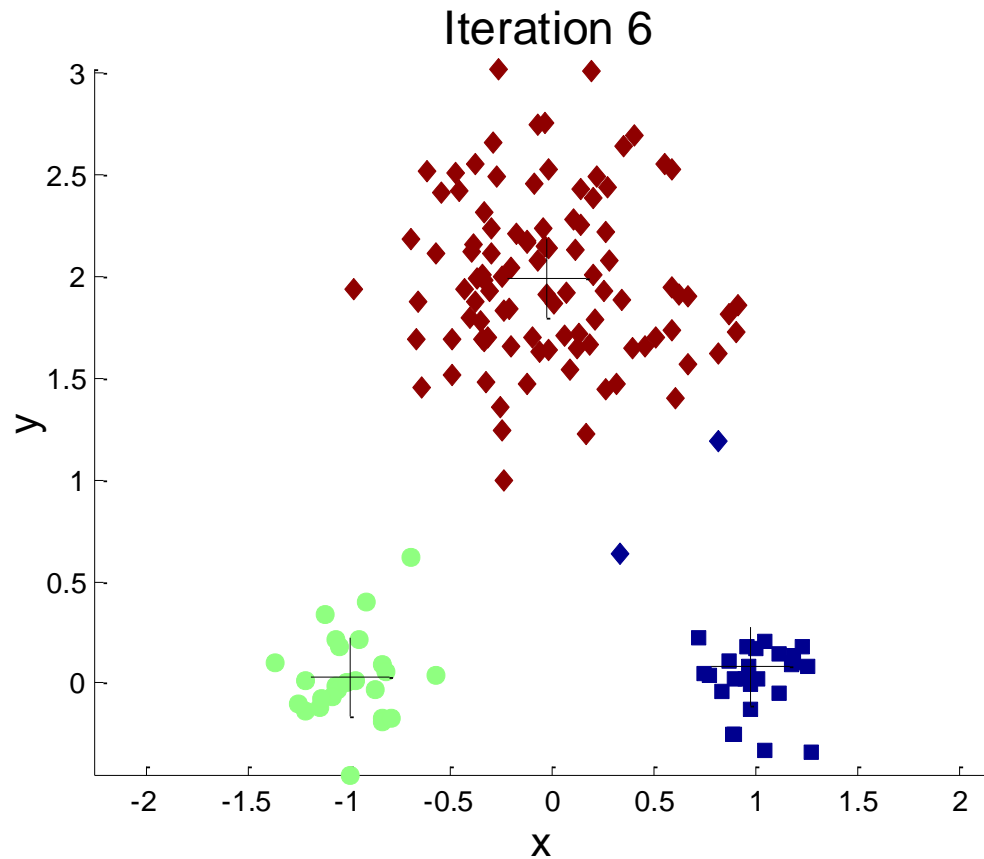
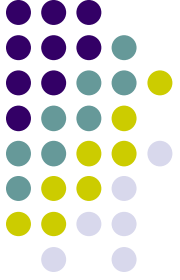


Optimal Clustering

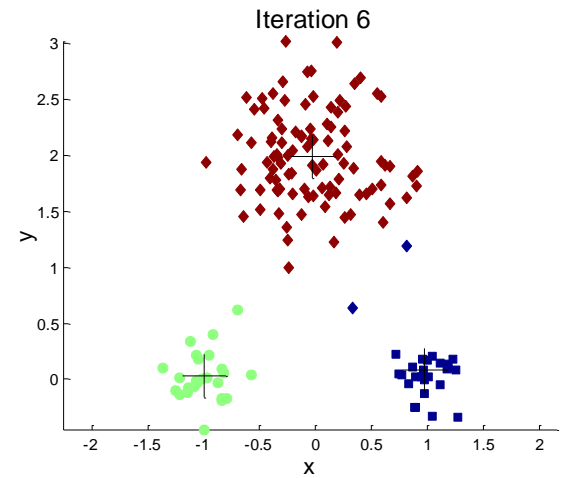
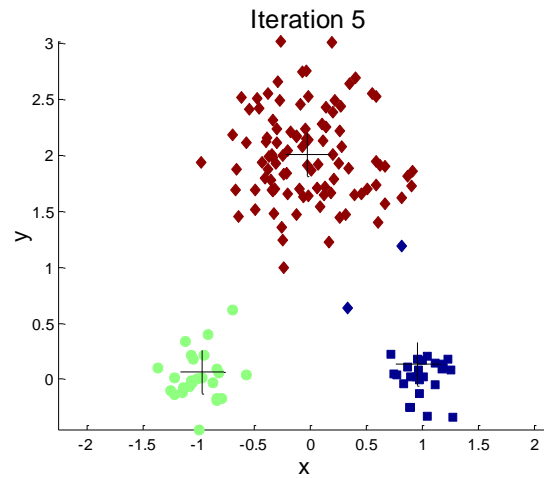
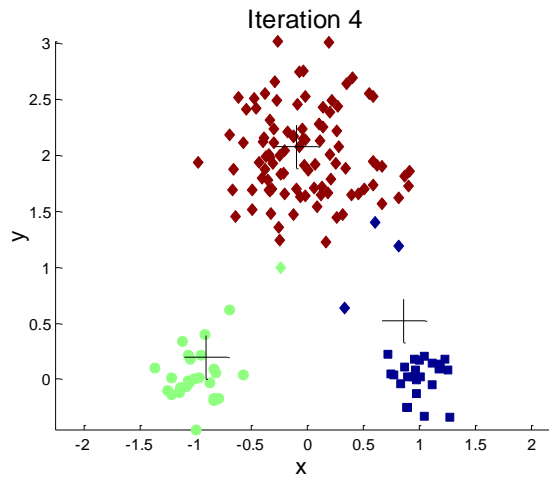
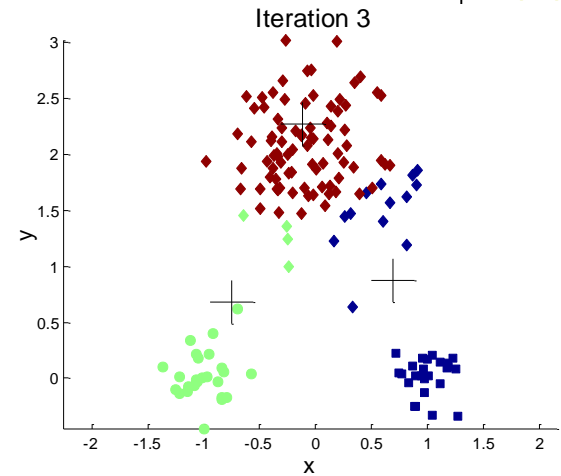
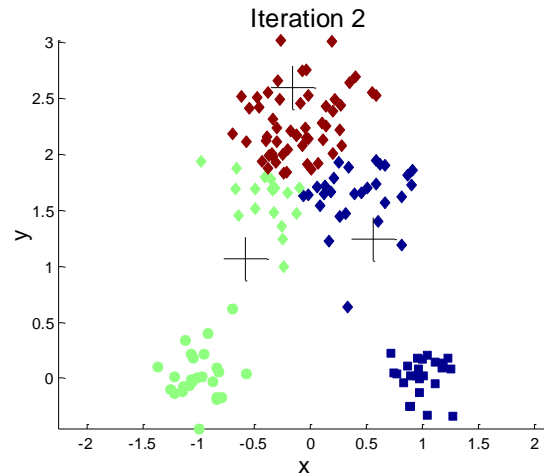
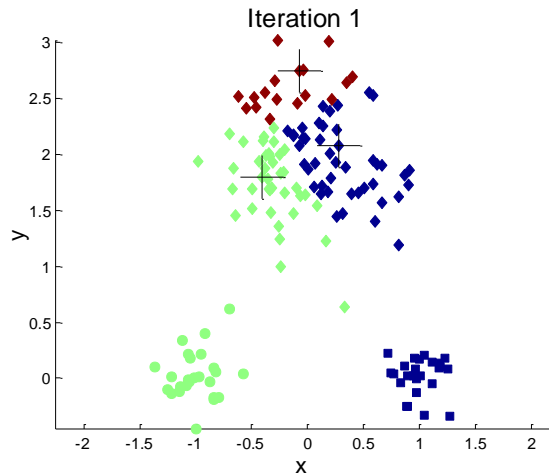


Sub-optimal Clustering

Importance of Choosing Initial Centroids



Importance of Choosing Initial Centroids



Evaluating K-means Clusters

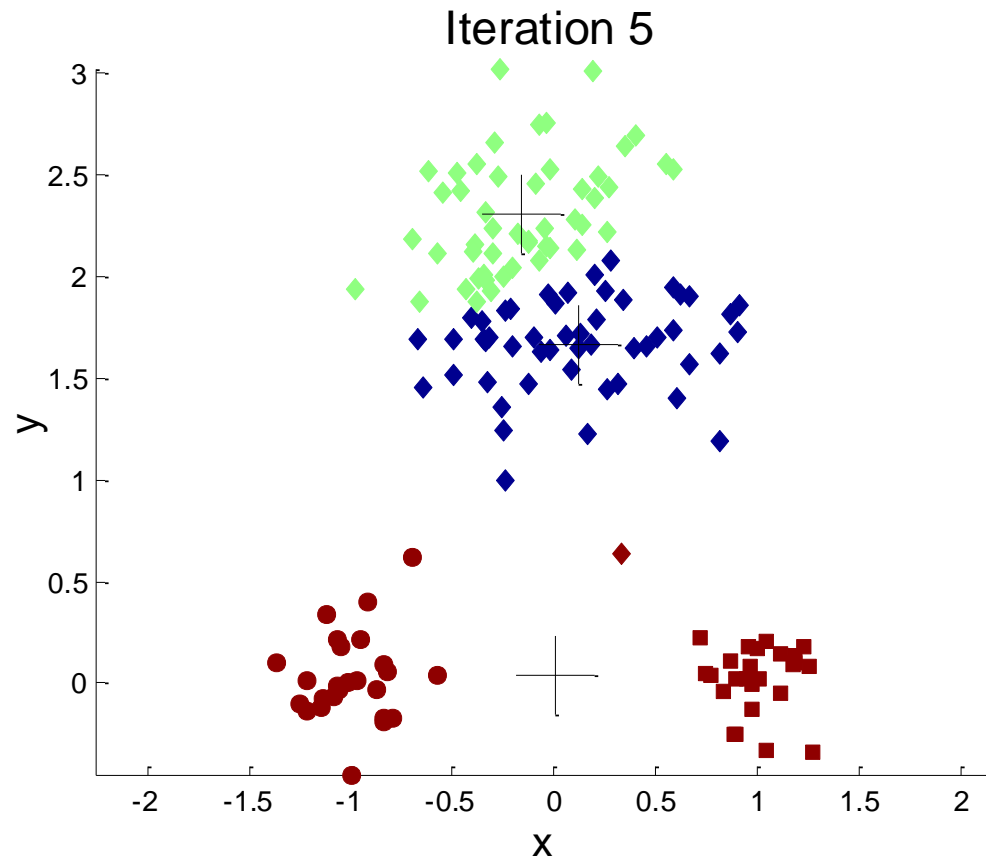


- Most common measure is Sum of Squared Error (SSE)
 - For each point, the error is the distance to the nearest cluster

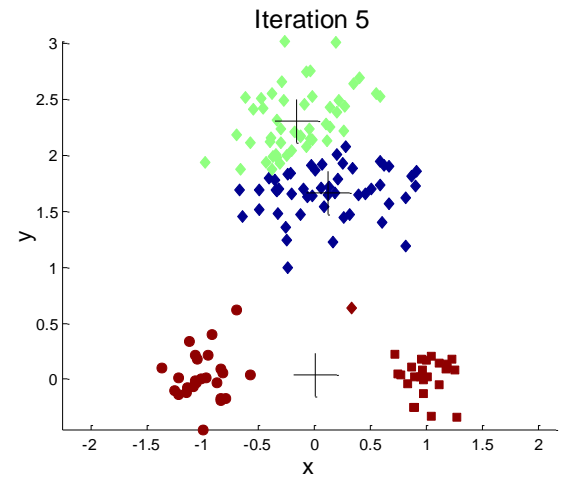
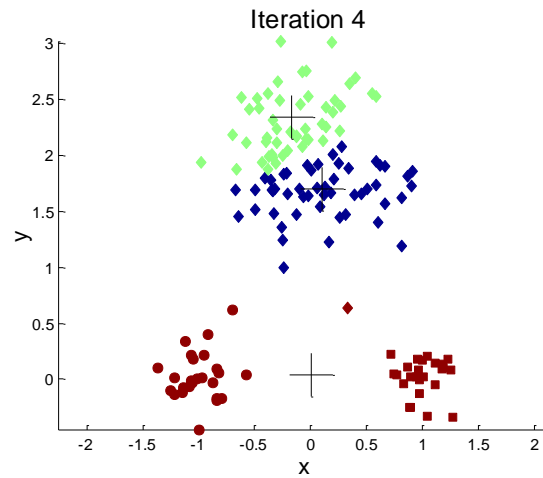
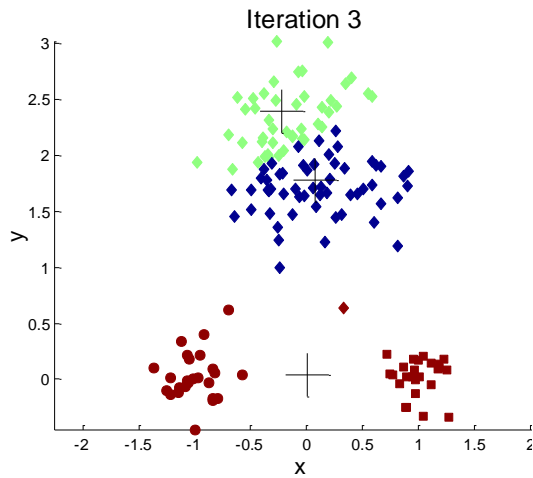
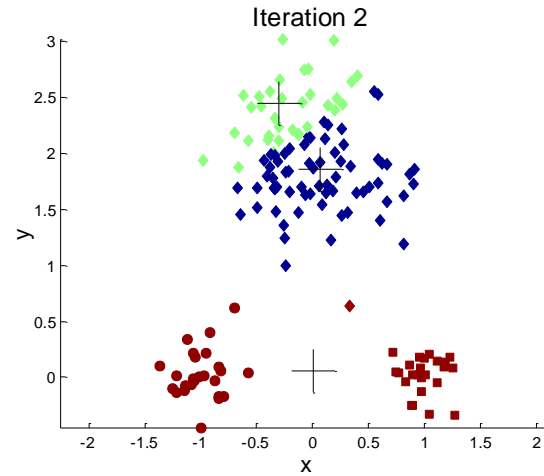
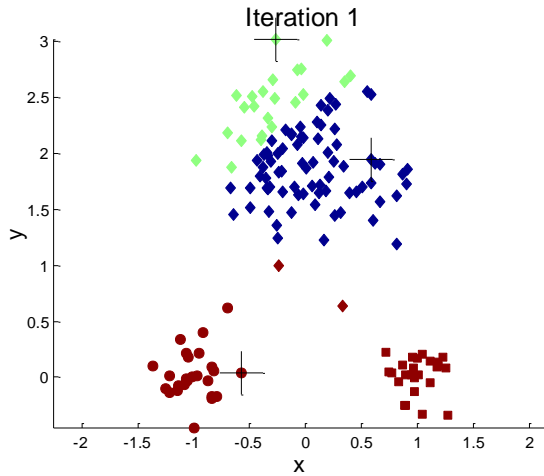
$$SSE = \sum_{j=1}^k \sum_{\mathbf{x} \in C_j} \text{dist}(\mathbf{x}, \mathbf{m}_j)^2$$

- Given two clusters, we can choose the one with the smallest error
- One easy way to reduce SSE is to increase K, the number of clusters
 - A good clustering with smaller K can have a lower SSE than a poor clustering with higher K

Importance of Choosing Initial Centroids



Importance of Choosing Initial Centroids



Problems with Selecting Initial Points



- If there are K 'real' clusters then the chance of selecting one centroid from each cluster is small.
 - Chance is relatively small when K is large
 - If clusters are the same size, n , then

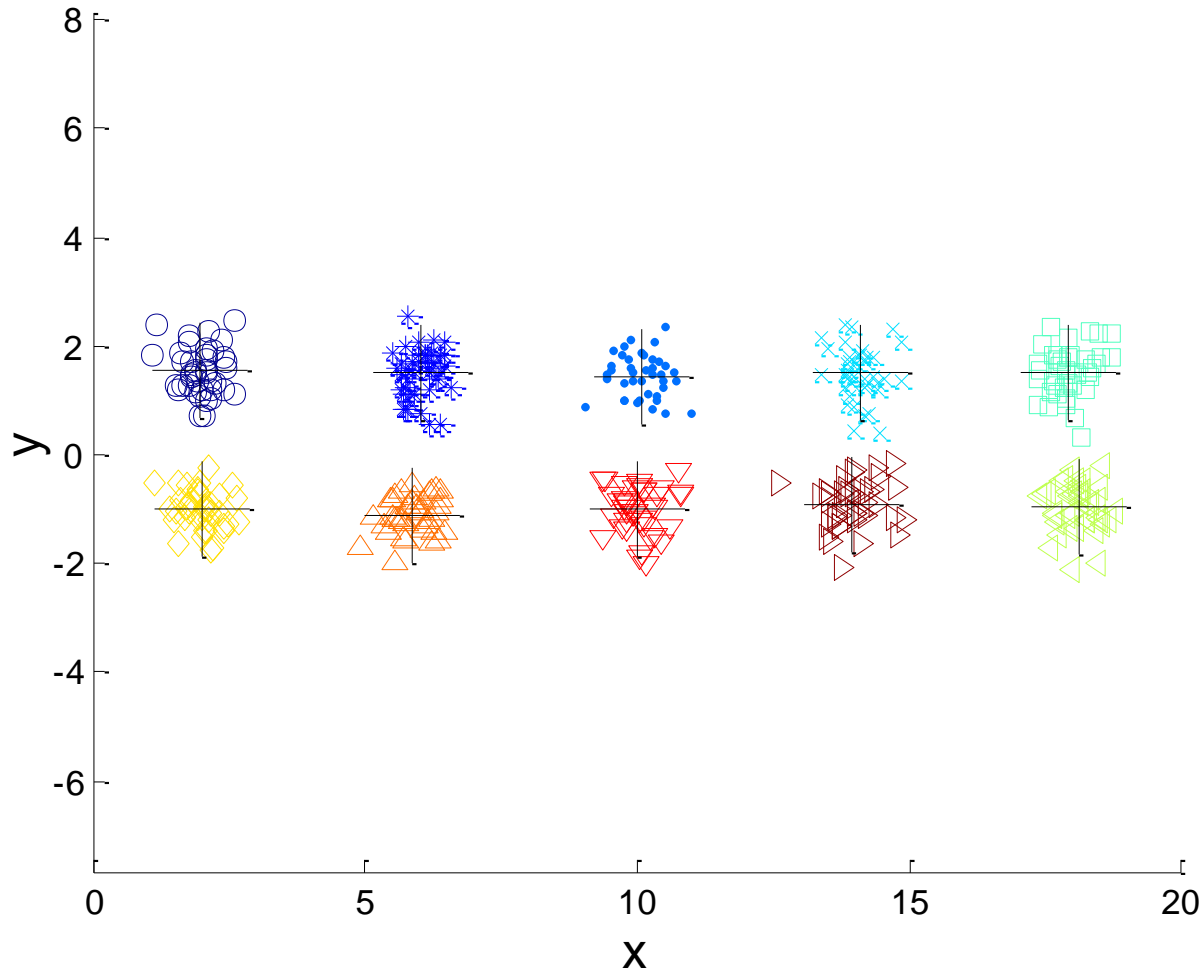
$$P = \frac{\text{number of ways to select one centroid from each cluster}}{\text{number of ways to select } K \text{ centroids}} = \frac{K!n^K}{(Kn)^K} = \frac{K!}{K^K}$$

- For example, if $K = 10$, then probability = $10!/10^{10} = 0.00036$
- Sometimes the initial centroids will readjust themselves in 'right' way, and sometimes they don't
- Consider an example of five pairs of clusters

10 Clusters Example

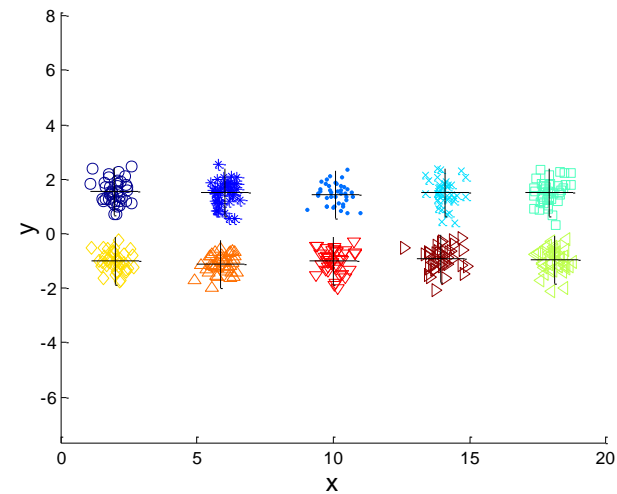
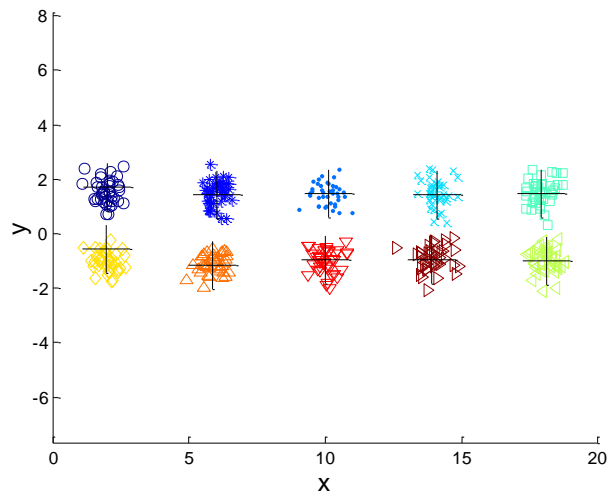
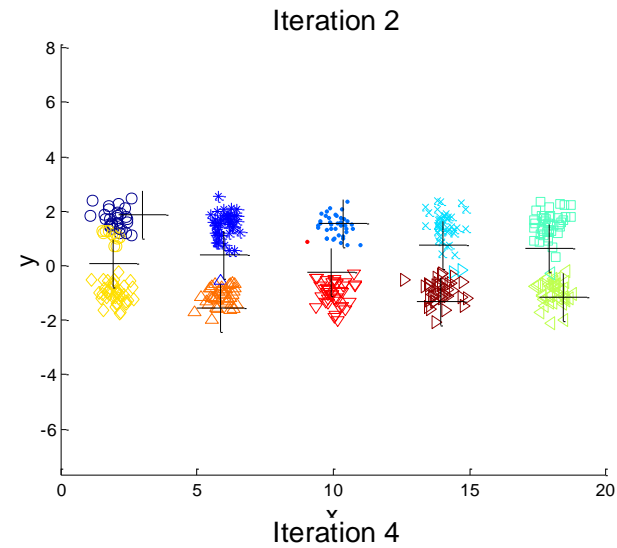
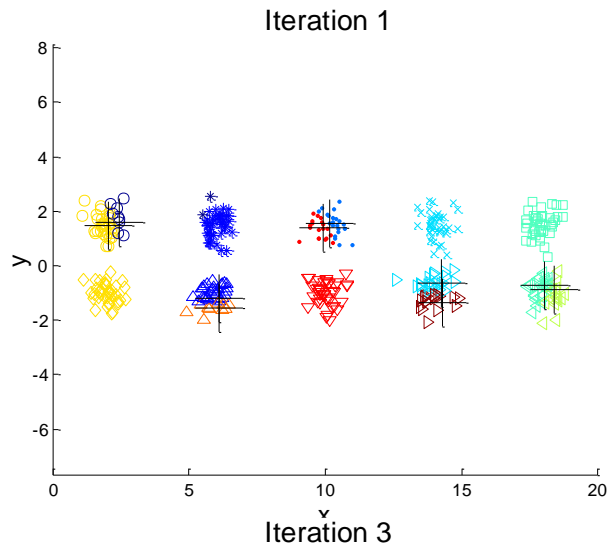


Iteration 4



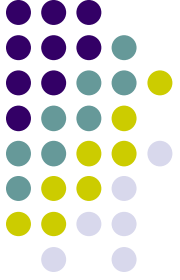
Starting with two initial centroids in one cluster of each pair of clusters

10 Clusters Example

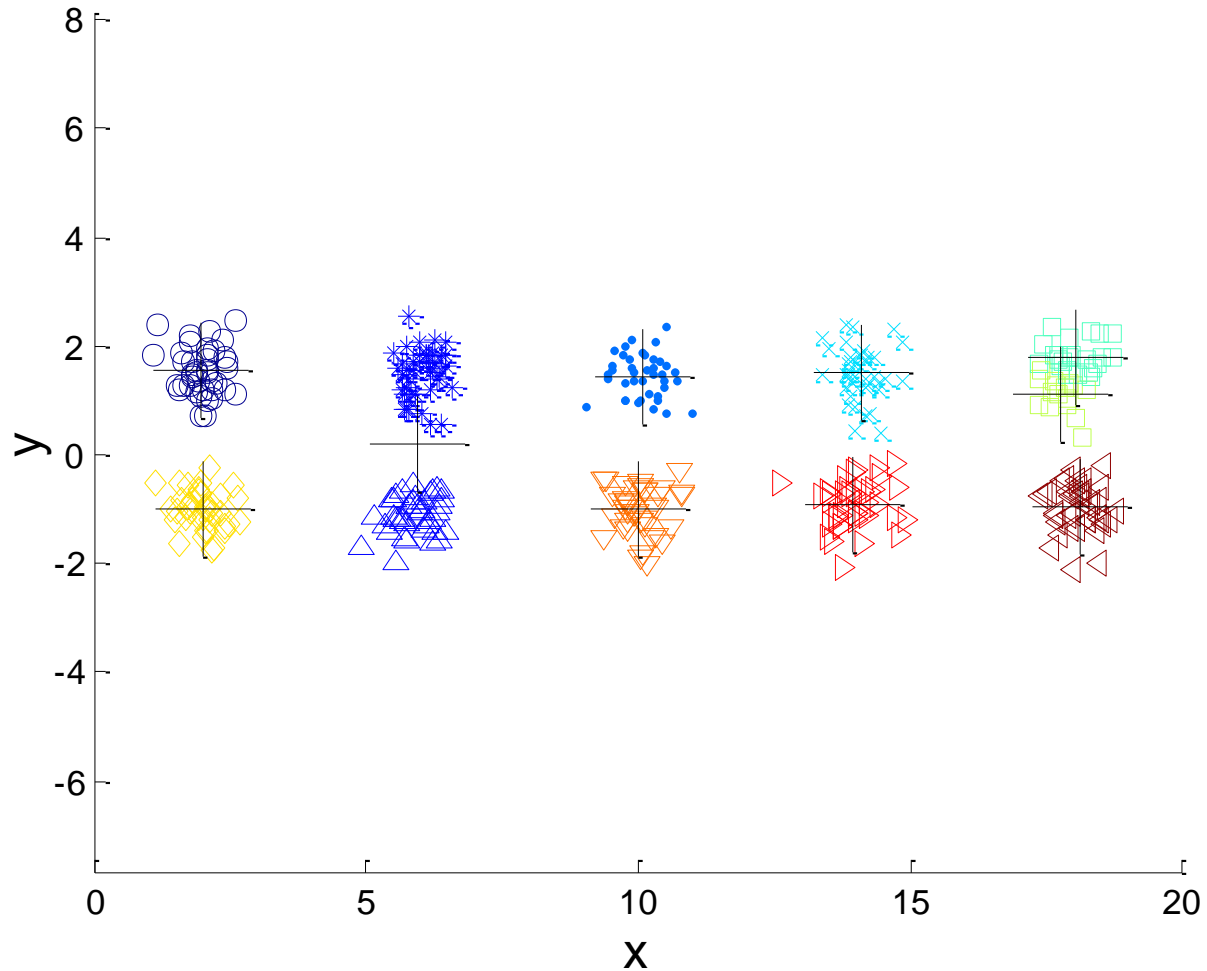


Starting with two initial centroids in one cluster of each pair of clusters

10 Clusters Example

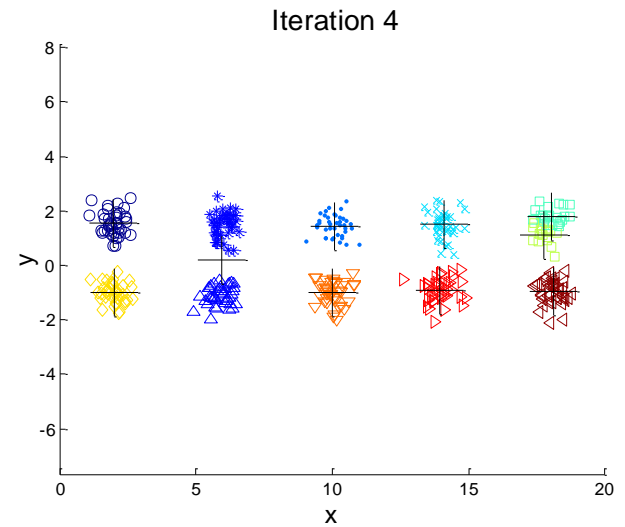
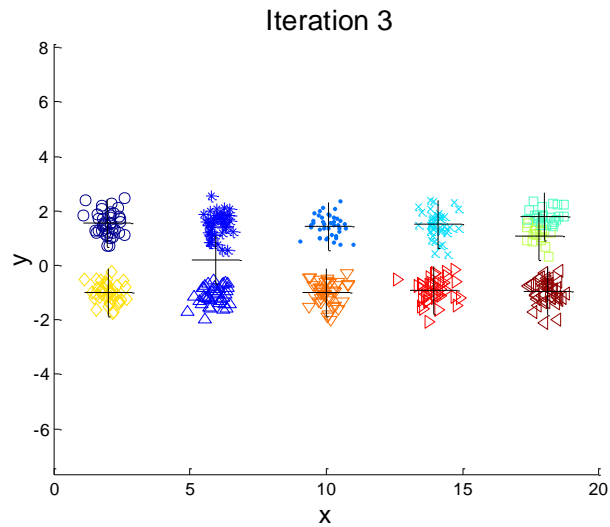
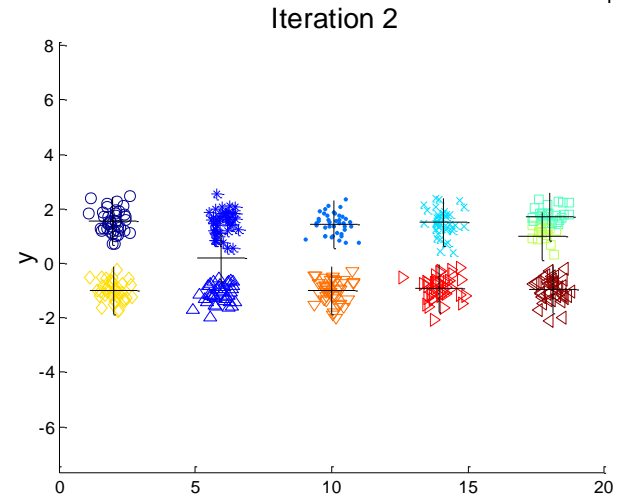
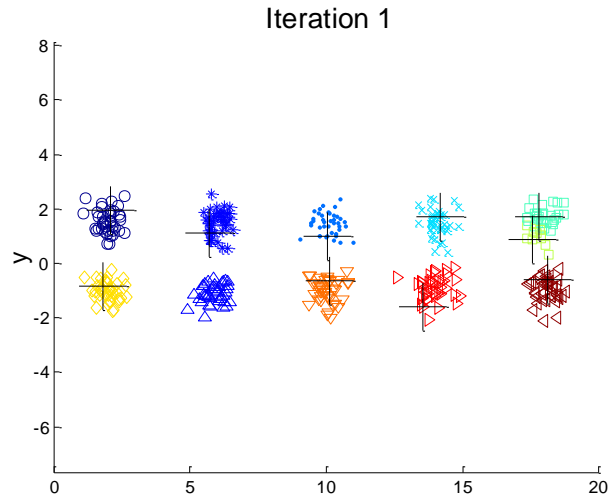


Iteration 4



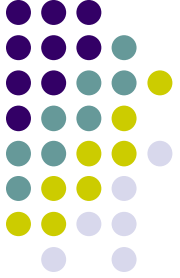
Starting with some pairs of clusters having three initial centroids, while other have only one.

10 Clusters Example



Starting with some pairs of clusters having three initial centroids, while other have only one.

Solutions to Initial Centroids Problem



- Multiple runs
 - Helps, but probability is not on your side
- Sample and use hierarchical clustering to determine initial centroids
- Select more than k initial centroids and then select among these initial centroids
 - Select most widely separated
- Postprocessing
- Bisecting K-means

Pre-processing and Post-processing



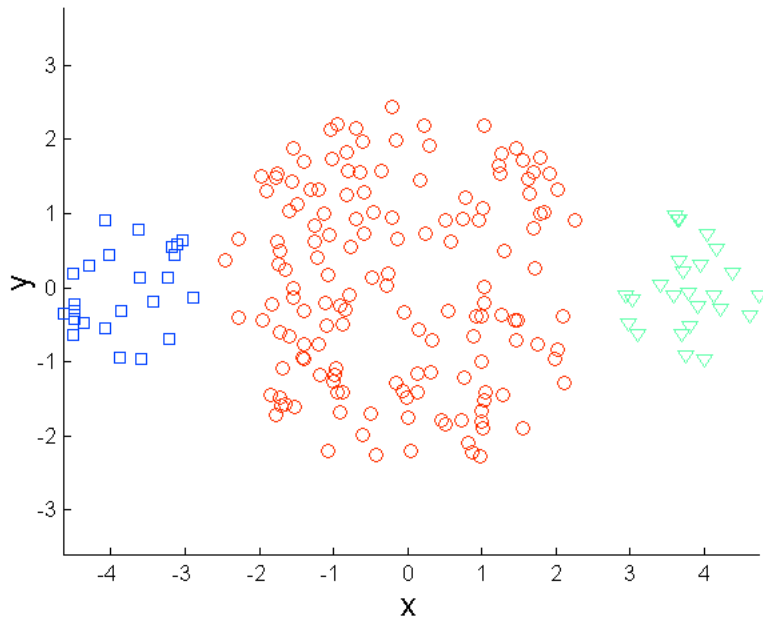
- Pre-processing
 - Normalize the data
 - Eliminate outliers
- Post-processing
 - Eliminate small clusters that may represent outliers
 - Split 'loose' clusters, i.e., clusters with relatively high SSE
 - Merge clusters that are 'close' and that have relatively low SSE
 - Can use these steps during the clustering process
 - ISODATA

Limitations of K-means

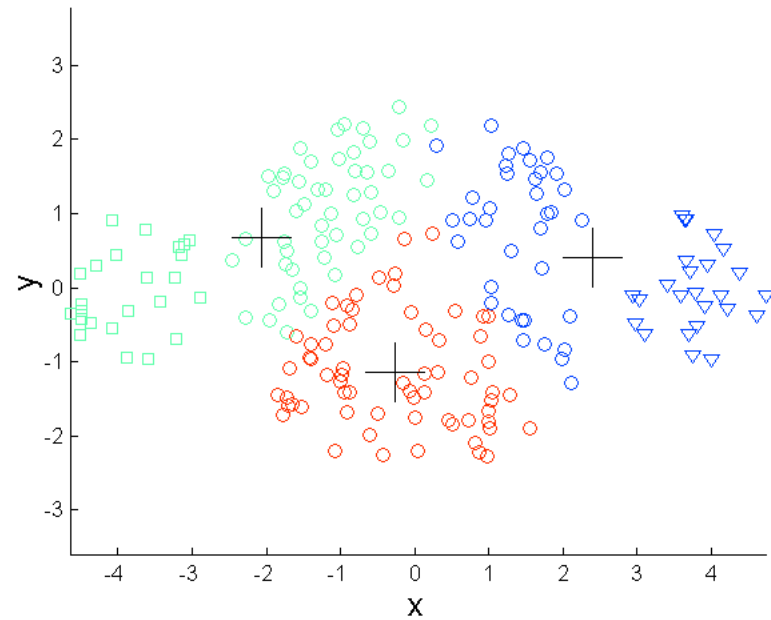


- K-means has problems when clusters are of differing
 - Sizes
 - Densities
 - Non-globular shapes
- K-means has problems when the data contains outliers.

Limitations of K-means: Differing Sizes

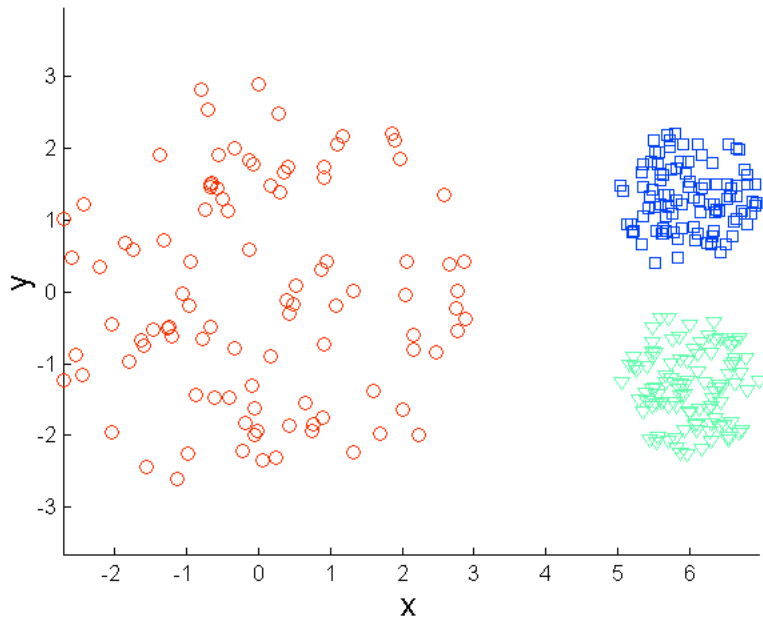


Original Points

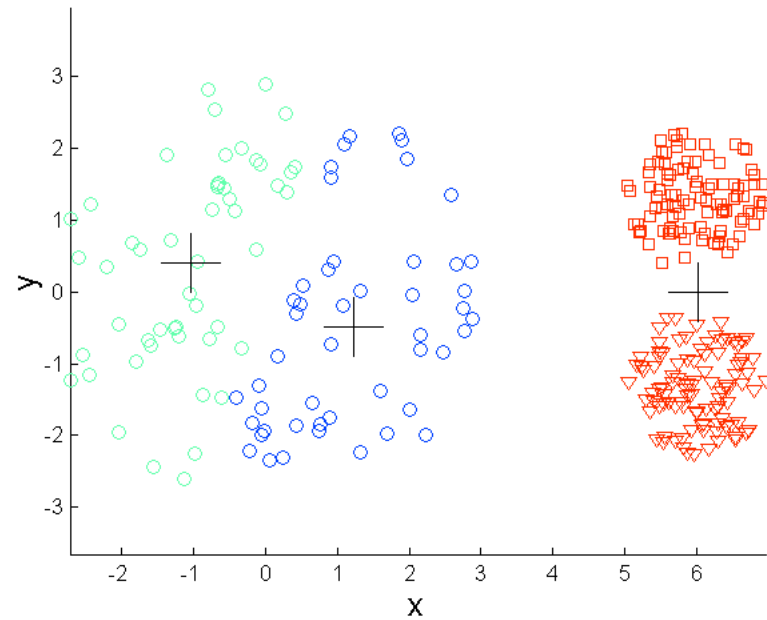


K-means (3 Clusters)

Limitations of K-means: Differing Density

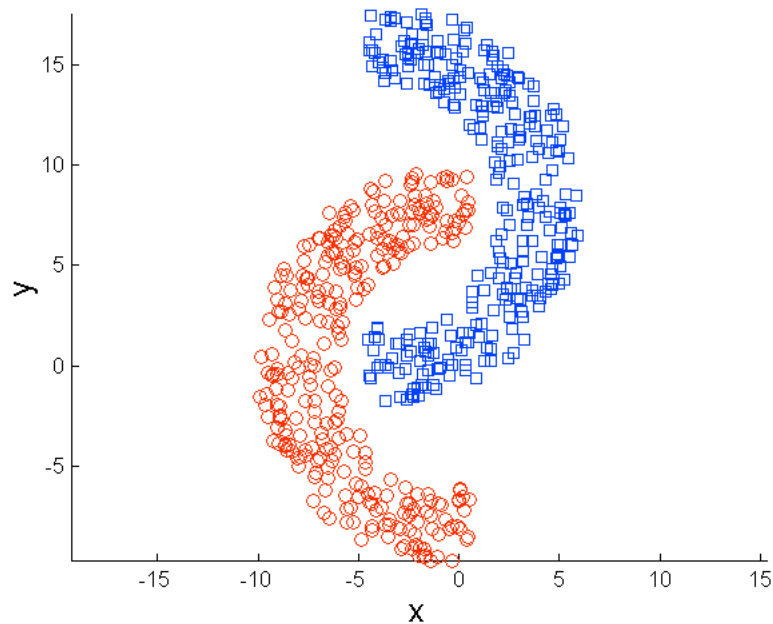


Original Points

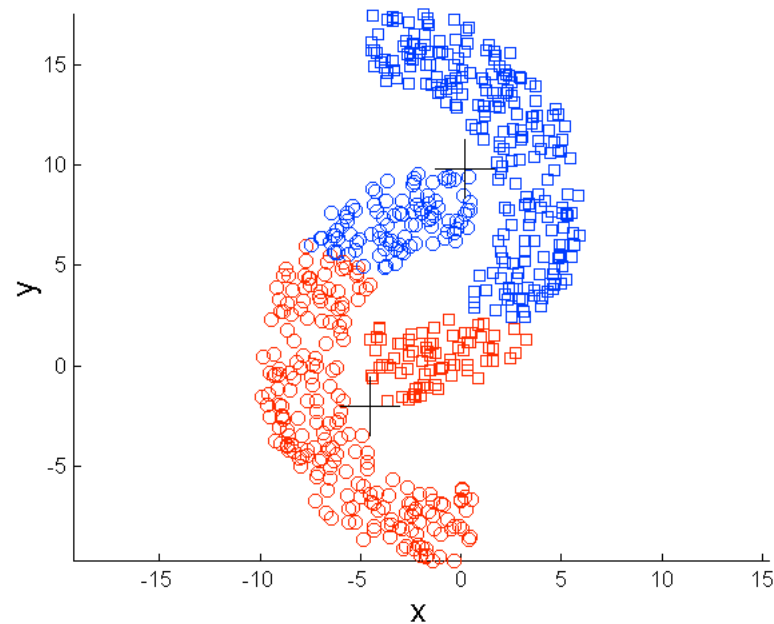


K-means (3 Clusters)

Limitations of K-means: Non-globular Shapes

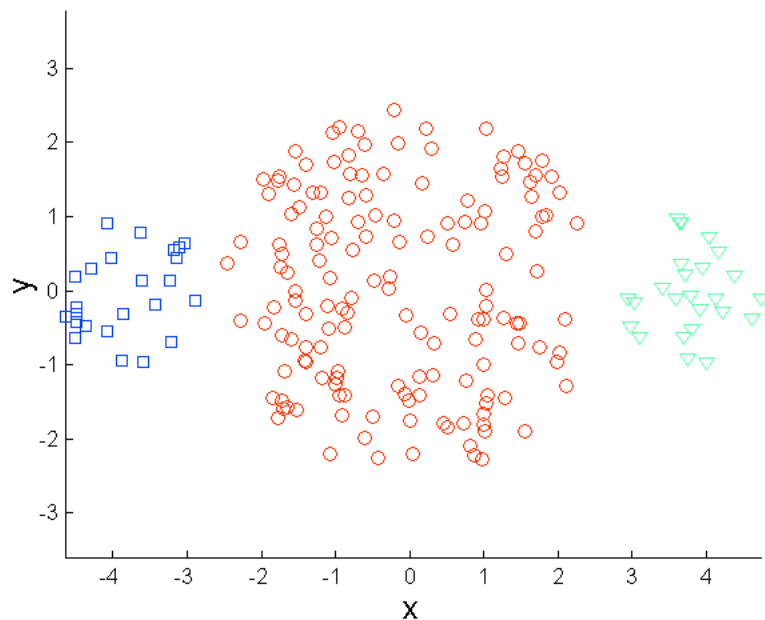


Original Points

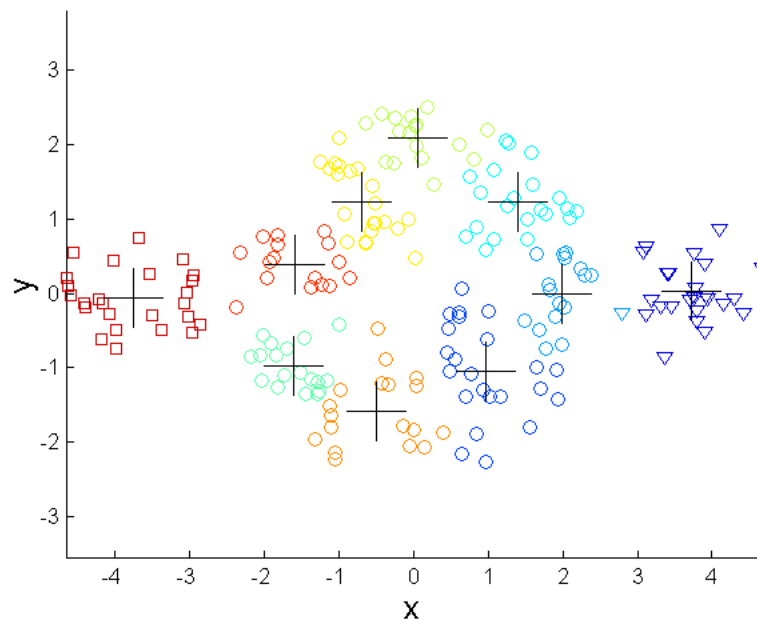


K-means (2 Clusters)

Overcoming K-means Limitations



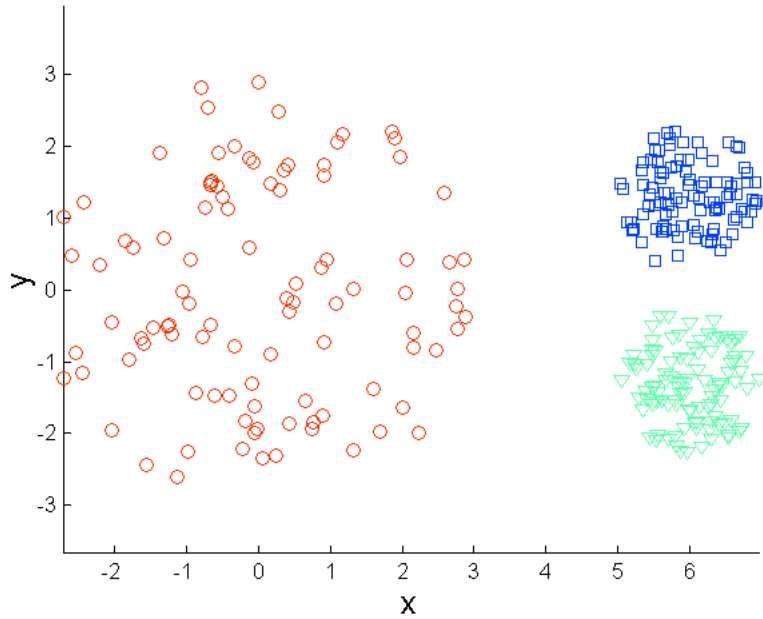
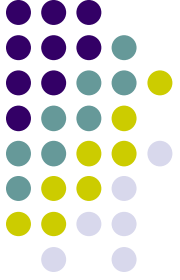
Original Points



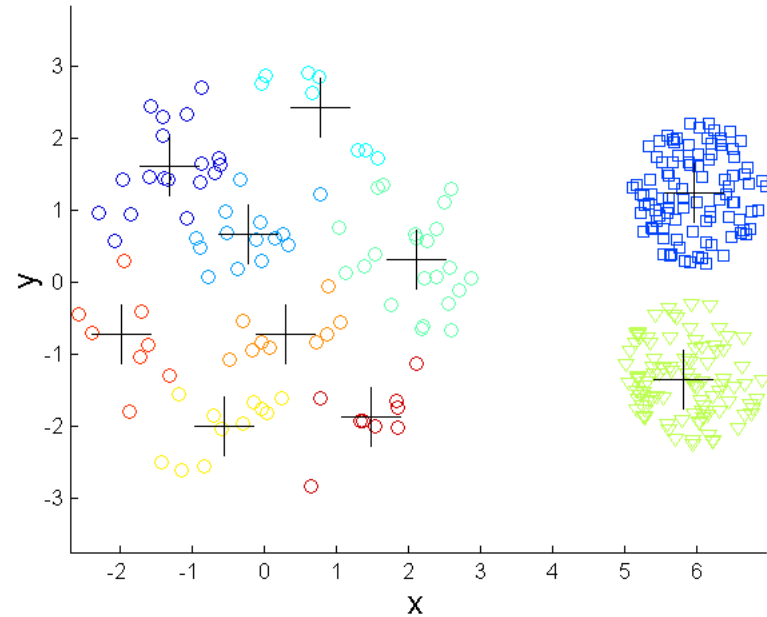
K-means Clusters

One solution is to use many clusters.
Find parts of clusters, but need to put together.

Overcoming K-means Limitations

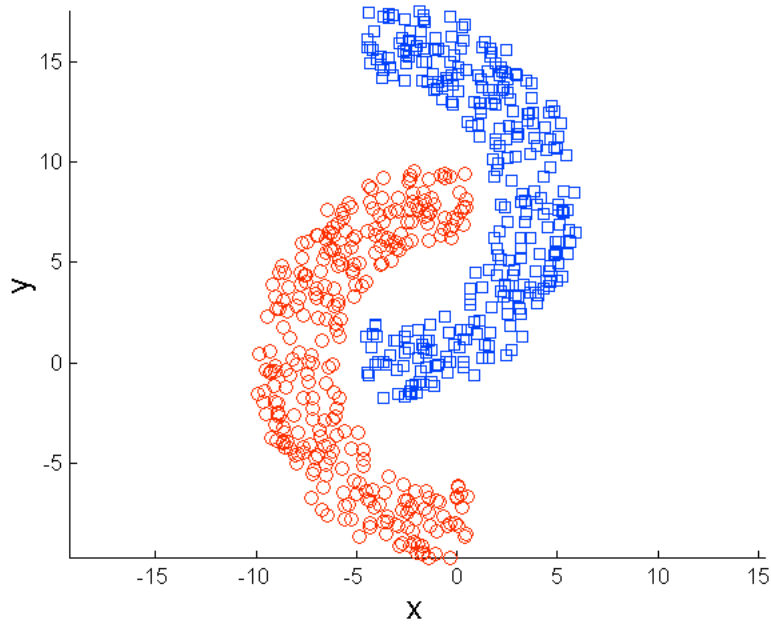
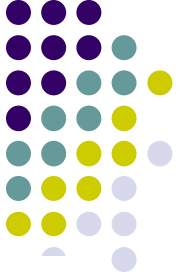


Original Points

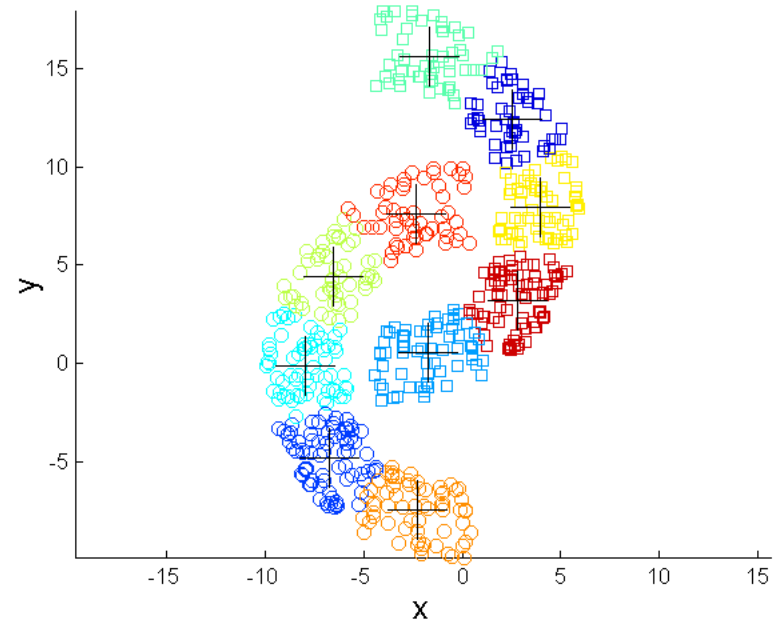


K-means Clusters

Overcoming K-means Limitations



Original Points

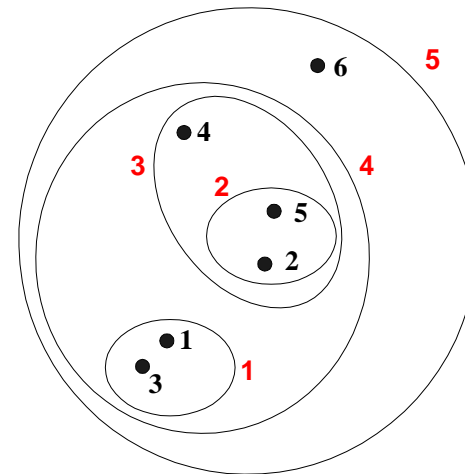
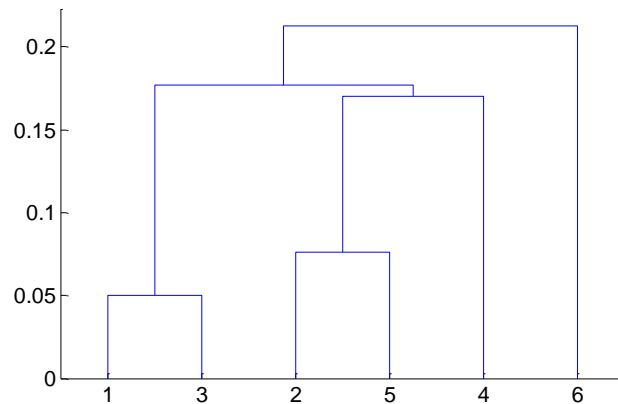


K-means Clusters

Hierarchical Clustering



- Produces a set of nested clusters organized as a hierarchical tree
- Can be visualized as a dendrogram
 - A tree like diagram that records the sequences of merges or splits



Strengths of Hierarchical Clustering



- Do not have to assume any particular number of clusters
 - Any desired number of clusters can be obtained by ‘cutting’ the dendrogram at the proper level
- They may correspond to meaningful taxonomies
 - Example in biological sciences (e.g., animal kingdom, phylogeny reconstruction, ...)

Hierarchical Clustering



- Two main types of hierarchical clustering
 - Agglomerative:
 - Start with the points as individual clusters
 - At each step, merge the closest pair of clusters until only one cluster (or k clusters) left
 - Divisive:
 - Start with one, all-inclusive cluster
 - At each step, split a cluster until each cluster contains a point (or there are k clusters)
- Traditional hierarchical algorithms use a similarity or distance matrix
 - Merge or split one cluster at a time

Agglomerative Clustering Algorithm

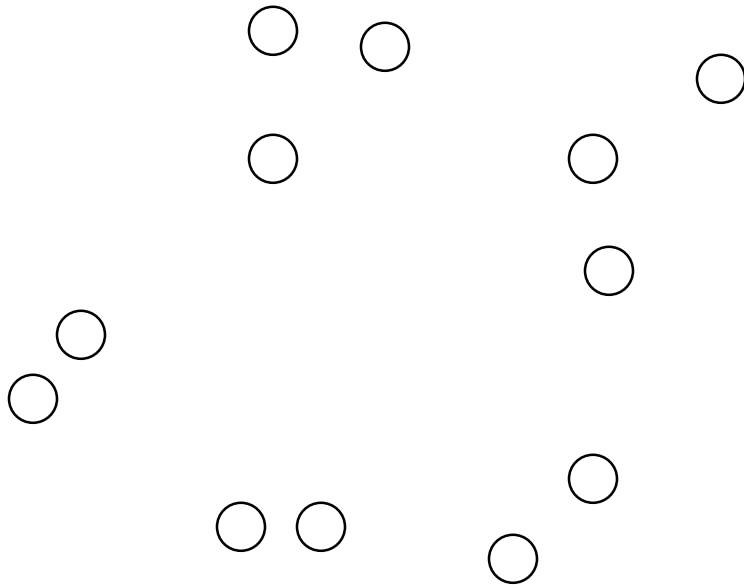


- More popular hierarchical clustering technique
- Basic algorithm is straightforward
 1. Compute the proximity matrix
 2. Let each data point be a cluster
 3. **Repeat**
 4. Merge the two closest clusters
 5. Update the proximity matrix
 6. **Until** only a single cluster remains
- Key operation is the computation of the proximity of two clusters
 - Different approaches to defining the distance between clusters distinguish the different algorithms

Starting Situation



- Start with clusters of individual points and a proximity matrix

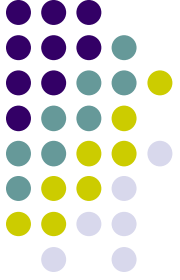


	p1	p2	p3	p4	p5	...
p1						
p2						
p3						
p4						
p5						
.						
.						
.						

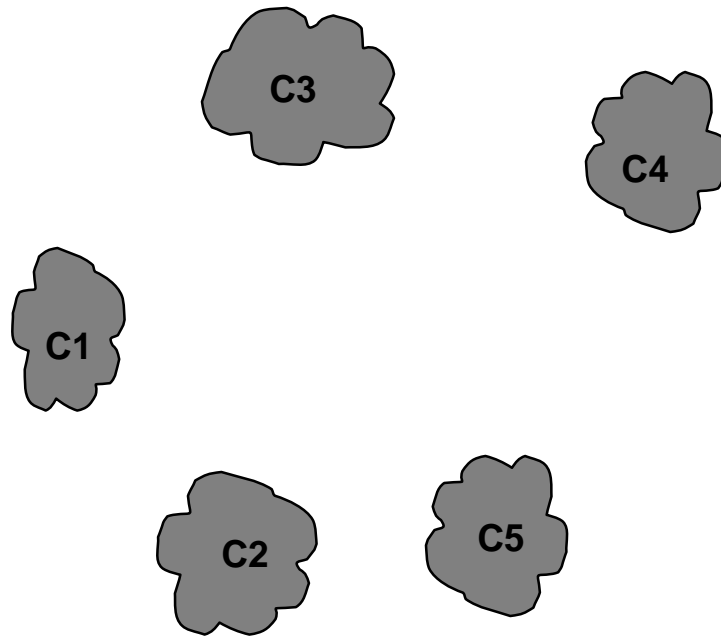
Proximity Matrix



Intermediate Situation

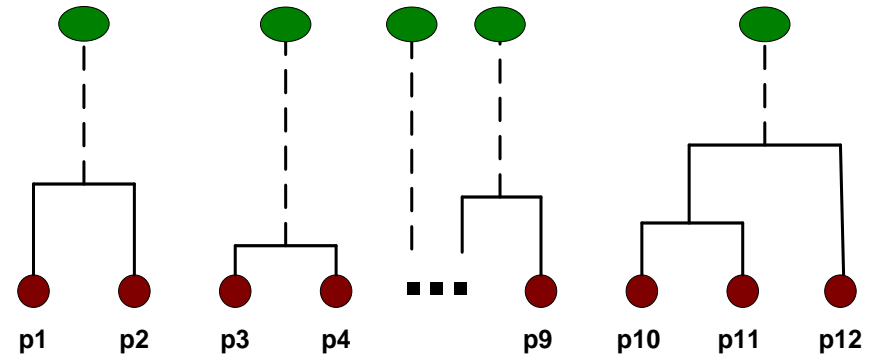


- After some merging steps, we have some clusters



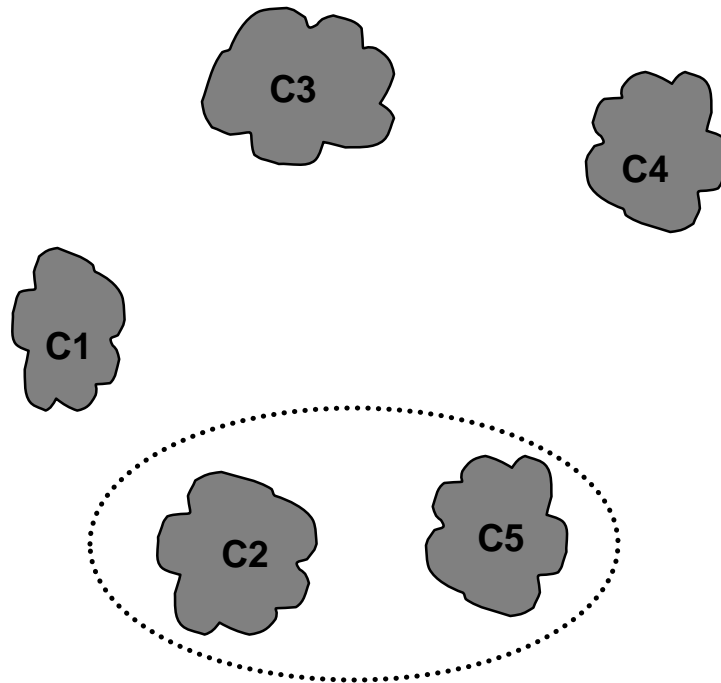
	C1	C2	C3	C4	C5
C1					
C2					
C3					
C4					
C5					

Proximity Matrix



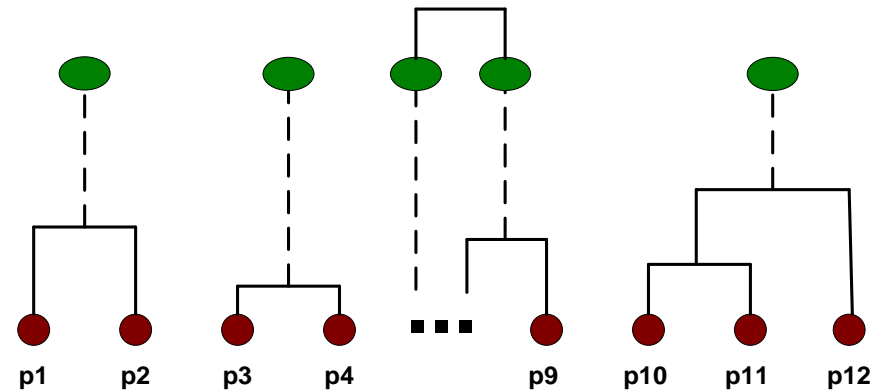
Intermediate Situation

- We want to merge the two closest clusters (C2 and C5) and update the proximity matrix.



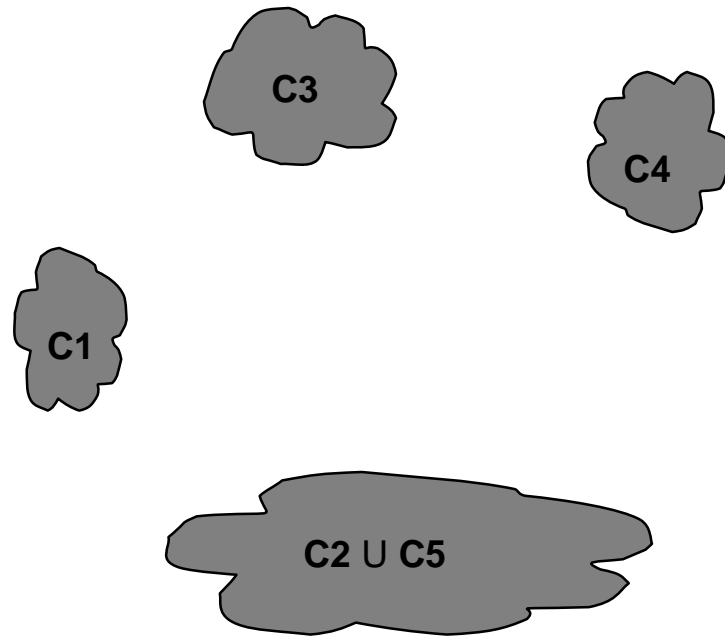
	C1	C2	C3	C4	C5
C1					
C2					
C3					
C4					
C5					

Proximity Matrix



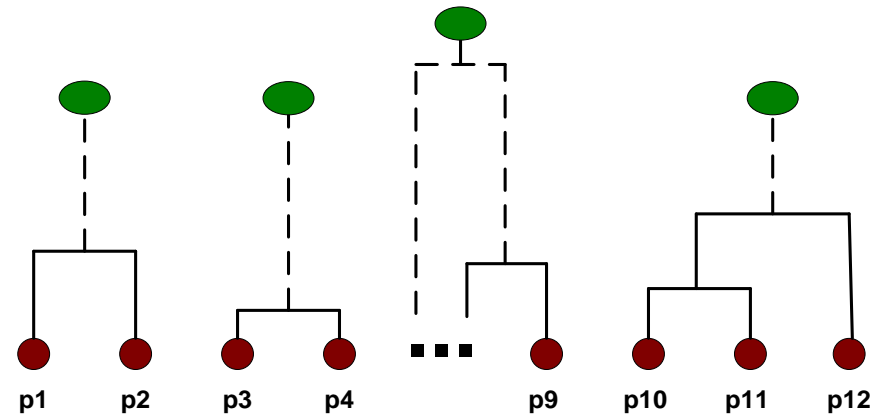
After Merging

- The question is “How do we update the proximity matrix?”

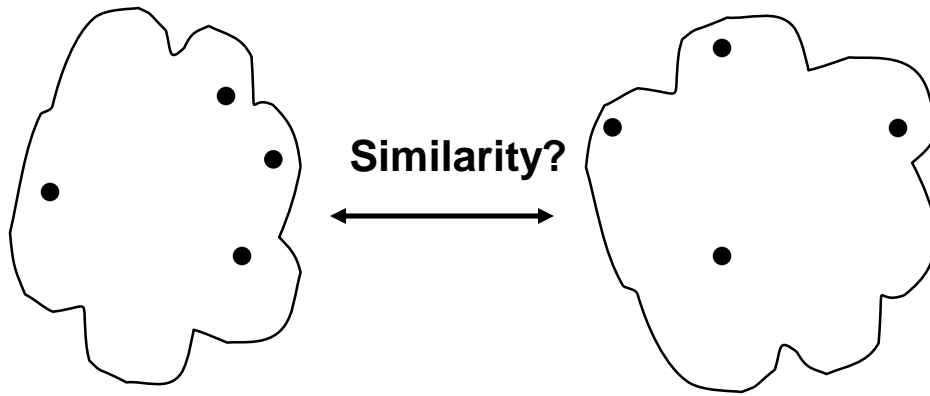
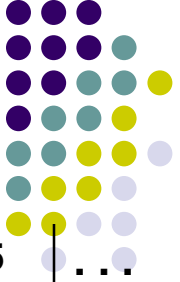


		$C2$ \cup $C5$			
		C1		C3	C4
$C2 \cup C5$	C1		?		
		?	?	?	?
	C3		?		
	C4		?		

Proximity Matrix



How to Define Inter-Cluster Similarity

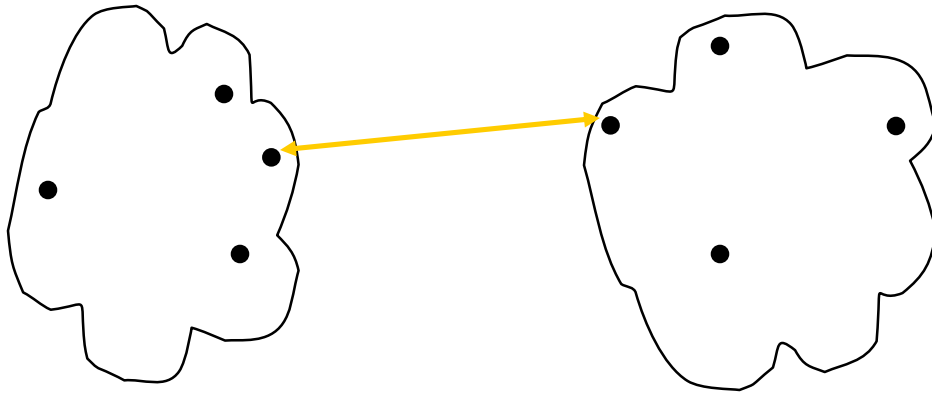


- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
 - Ward's Method uses squared error

	p1	p2	p3	p4	p5	...
p1						
p2						
p3						
p4						
p5						
.						
.						
.						

Proximity Matrix

How to Define Inter-Cluster Similarity

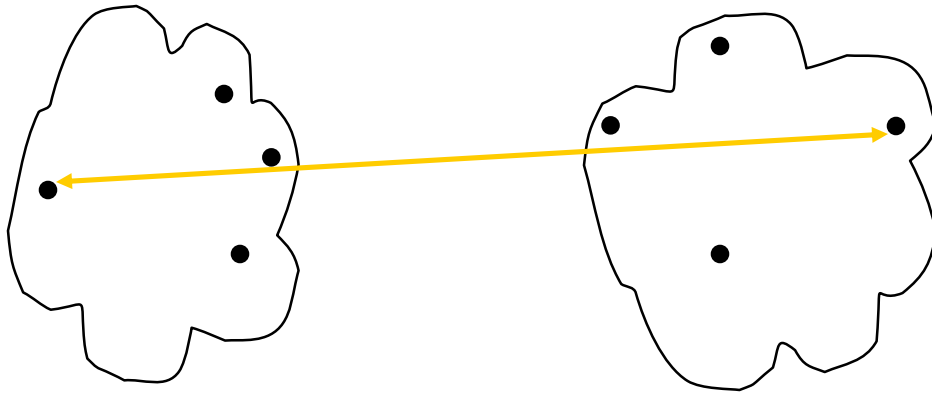
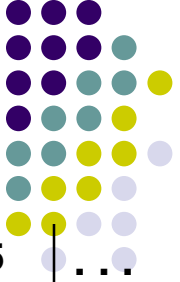


- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
 - Ward's Method uses squared error

	p1	p2	p3	p4	p5	...
p1						
p2						
p3						
p4						
p5						
.						
.						
.						

· **Proximity Matrix**

How to Define Inter-Cluster Similarity

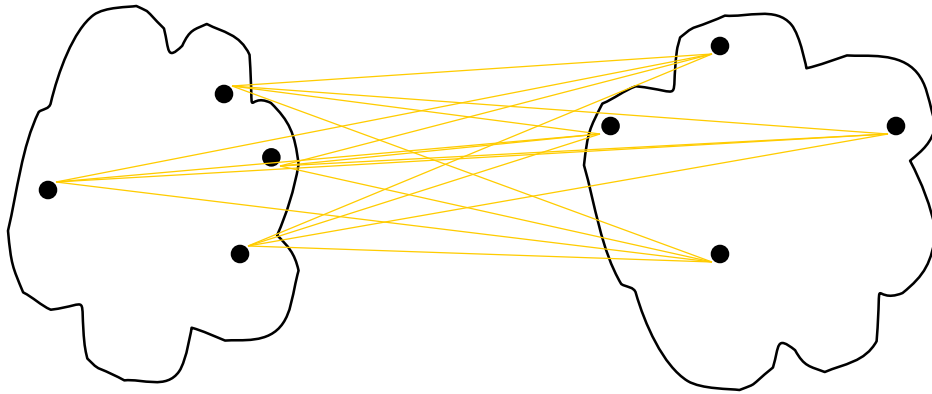


- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
 - Ward's Method uses squared error

	p1	p2	p3	p4	p5	...
p1						
p2						
p3						
p4						
p5						
.						
.						
.						

Proximity Matrix

How to Define Inter-Cluster Similarity

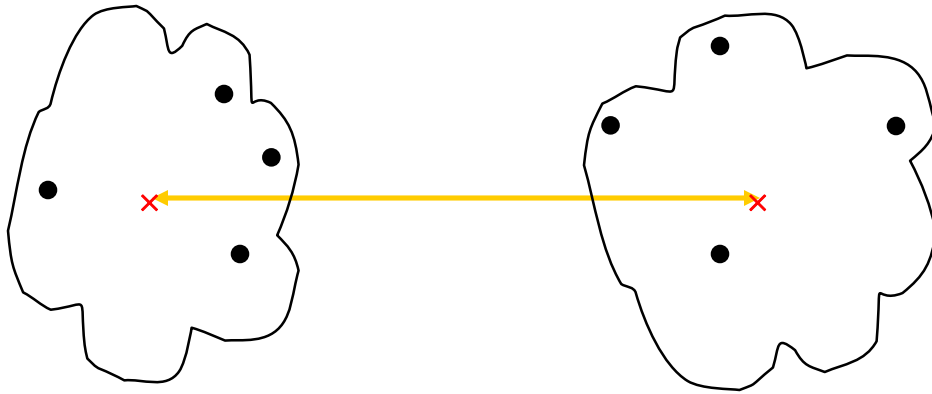
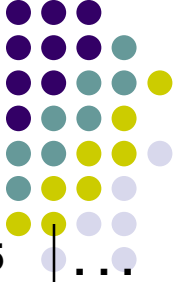


- MIN
- MAX
- **Group Average**
- Distance Between Centroids
- Other methods driven by an objective function
 - Ward's Method uses squared error

	p1	p2	p3	p4	p5	...
p1						
p2						
p3						
p4						
p5						
.						
.						
.						

Proximity Matrix

How to Define Inter-Cluster Similarity

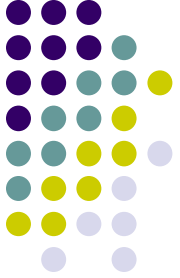


- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
 - Ward's Method uses squared error

	p1	p2	p3	p4	p5	...
p1						
p2						
p3						
p4						
p5						
.						
.						

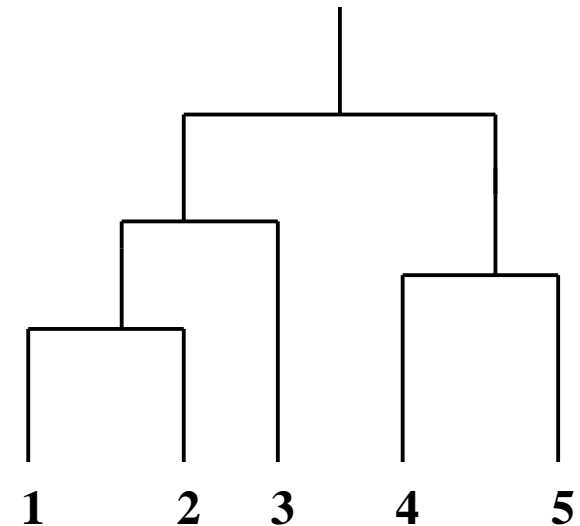
· **Proximity Matrix**

Cluster Similarity: MIN or Single Link

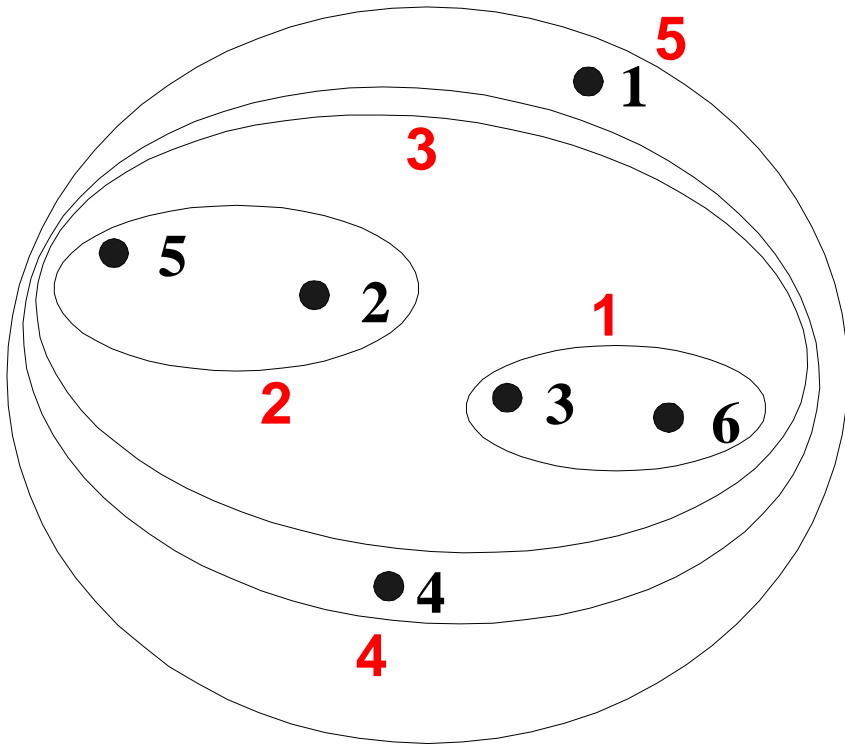
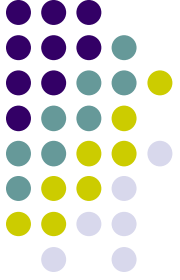


- Similarity of two clusters is based on the two most similar (closest) points in the different clusters
 - Determined by one pair of points, i.e., by one link in the proximity graph.

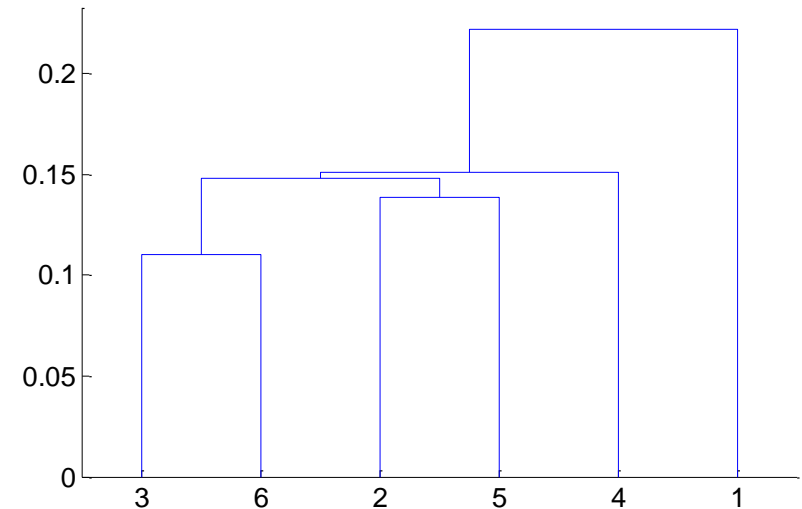
	I1	I2	I3	I4	I5
I1	1.00	0.90	0.10	0.65	0.20
I2	0.90	1.00	0.70	0.60	0.50
I3	0.10	0.70	1.00	0.40	0.30
I4	0.65	0.60	0.40	1.00	0.80
I5	0.20	0.50	0.30	0.80	1.00



Hierarchical Clustering: MIN

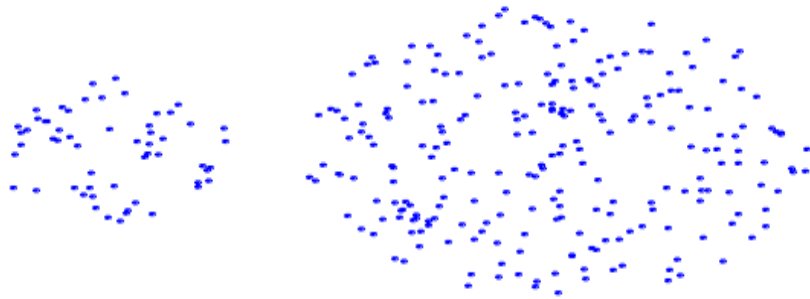
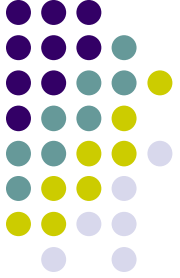


Nested Clusters

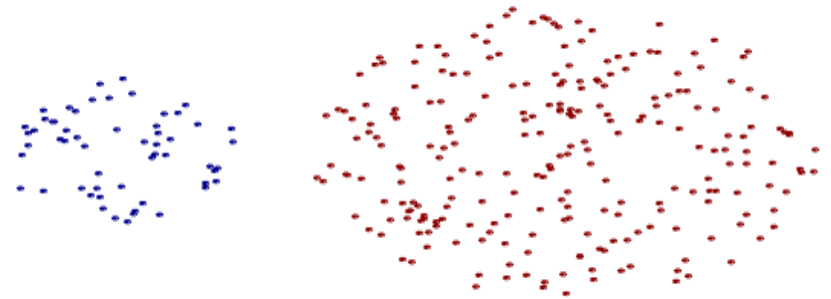


Dendrogram

Strength of MIN



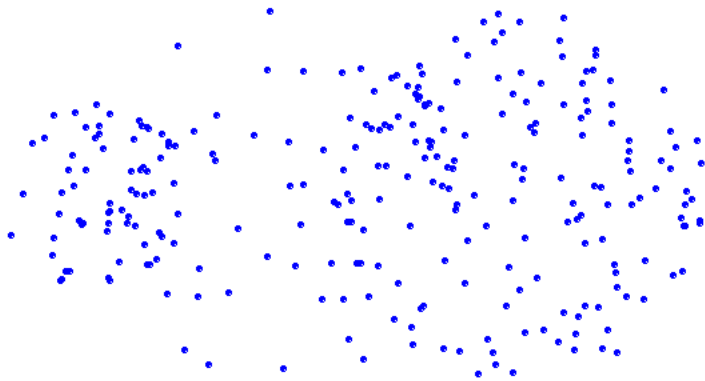
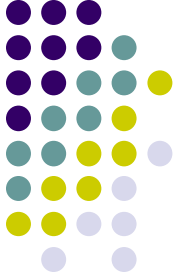
Original Points



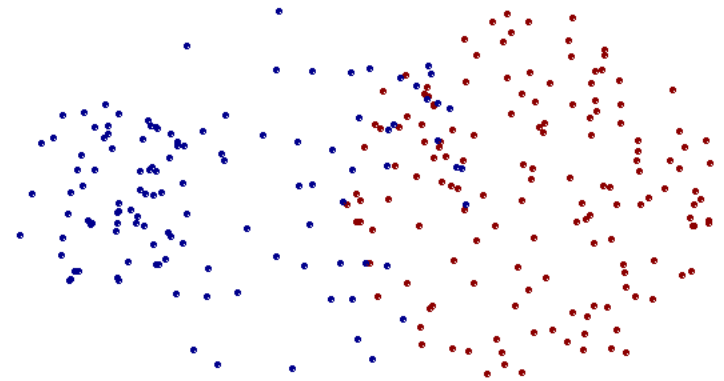
Two Clusters

- Can handle non-elliptical shapes

Limitations of MIN



Original Points



Two Clusters

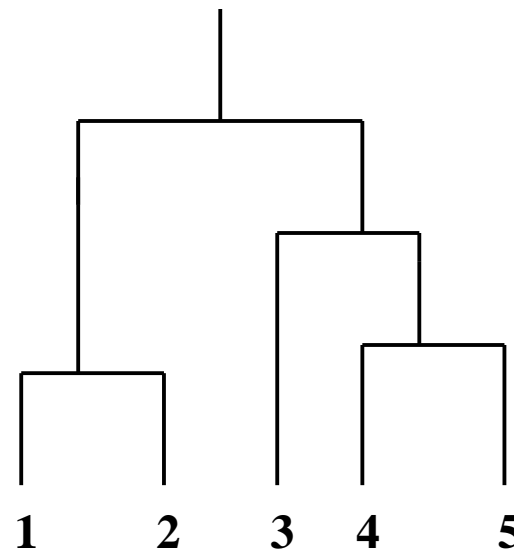
- **Sensitive to noise and outliers**

Cluster Similarity: MAX or Complete Linkage

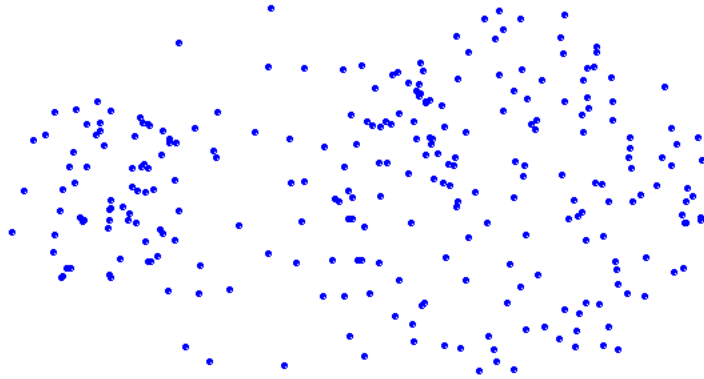
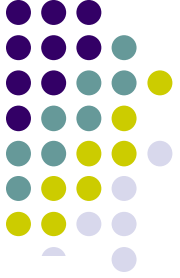


- Similarity of two clusters is based on the two least similar (most distant) points in the different clusters
 - Determined by all pairs of points in the two clusters

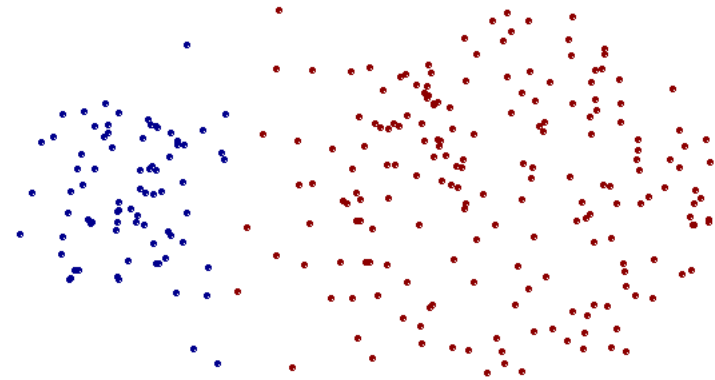
	I1	I2	I3	I4	I5
I1	1.00	0.90	0.10	0.65	0.20
I2	0.90	1.00	0.70	0.60	0.50
I3	0.10	0.70	1.00	0.40	0.30
I4	0.65	0.60	0.40	1.00	0.80
I5	0.20	0.50	0.30	0.80	1.00



Strength of MAX



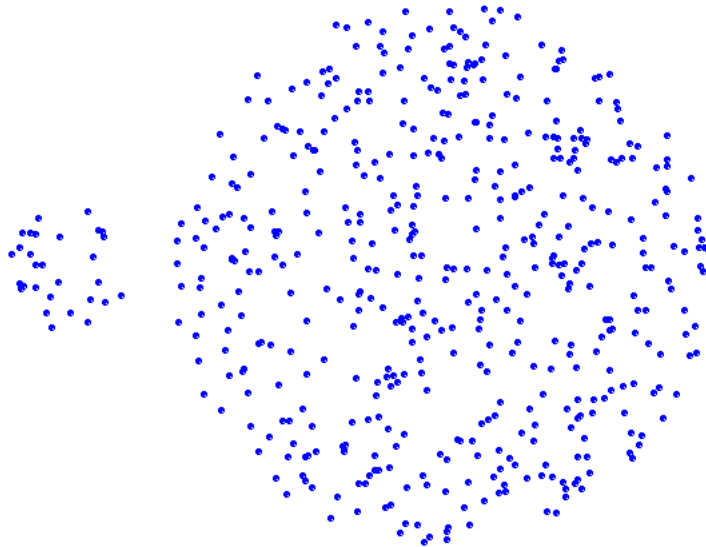
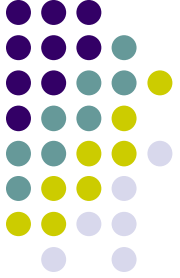
Original Points



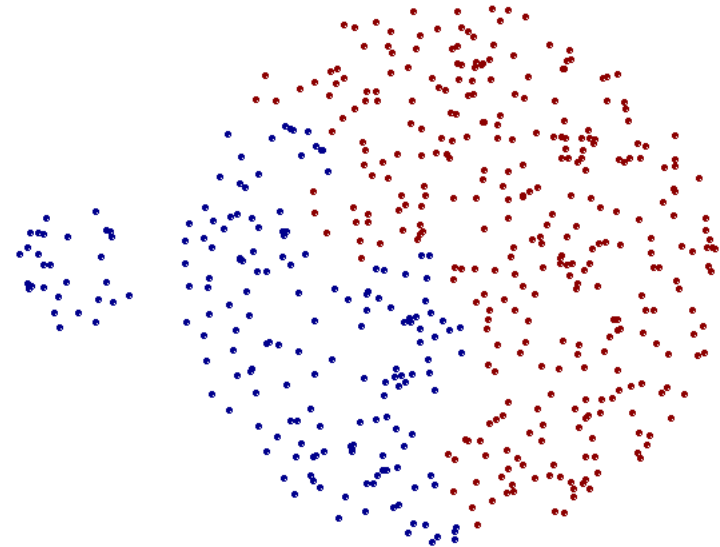
Two Clusters

- **Less susceptible to noise and outliers**

Limitations of MAX



Original Points



Two Clusters

- Tends to break large clusters
- Biased towards globular clusters (globular -- küresel)

Cluster Similarity: Group Average

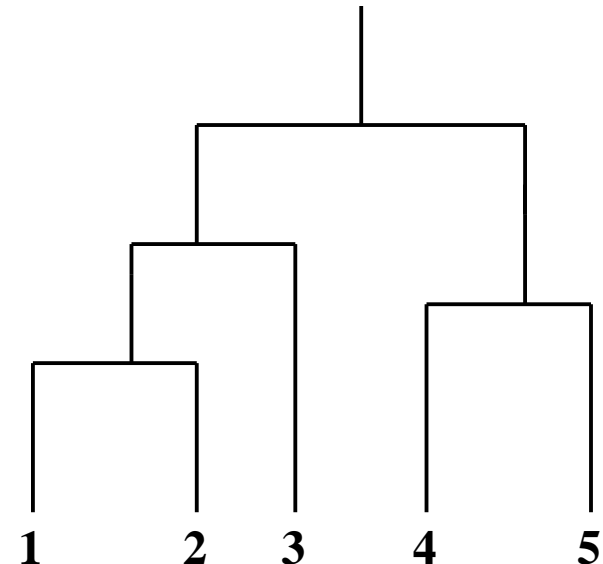


- Proximity of two clusters is the average of pairwise proximity between points in the two clusters.

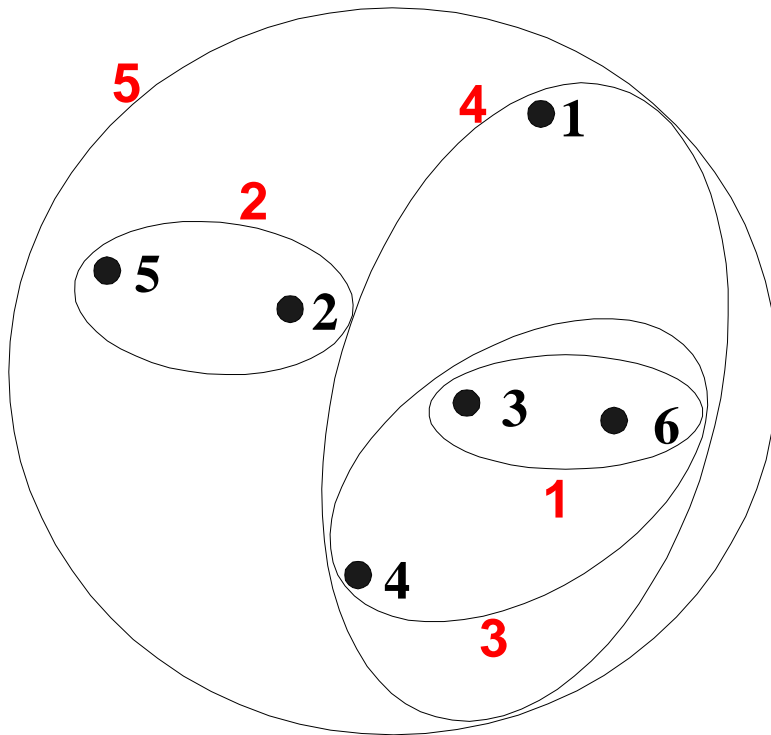
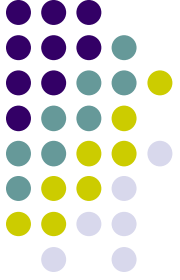
$$\text{proximity}(\text{Cluster}_i, \text{Cluster}_j) = \frac{\sum_{\substack{p_i \in \text{Cluster}_i \\ p_j \in \text{Cluster}_j}} \text{proximity}(p_i, p_j)}{|\text{Cluster}_i| * |\text{Cluster}_j|}$$

- Need to use average connectivity for scalability since total proximity favors large clusters

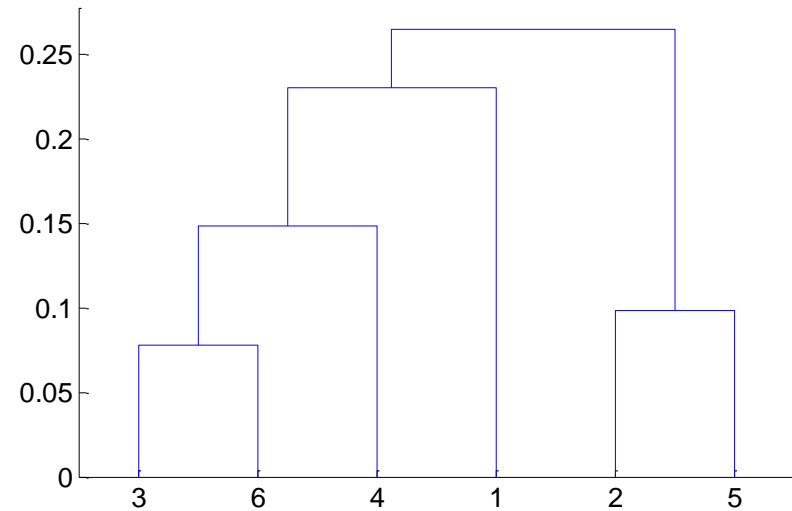
	I1	I2	I3	I4	I5
I1	1.00	0.90	0.10	0.65	0.20
I2	0.90	1.00	0.70	0.60	0.50
I3	0.10	0.70	1.00	0.40	0.30
I4	0.65	0.60	0.40	1.00	0.80
I5	0.20	0.50	0.30	0.80	1.00



Hierarchical Clustering: Group Average

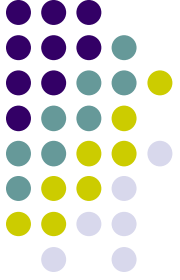


Nested Clusters



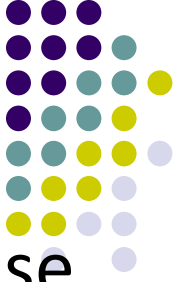
Dendrogram

Hierarchical Clustering: Group Average



- Compromise between Single and Complete Link
- Strengths
 - Less susceptible to noise and outliers
- Limitations
 - Biased towards globular (küresel) clusters

Cluster Similarity: Ward's Method



- Similarity of two clusters is based on the increase in squared error when two clusters are merged
 - Similar to group average if distance between points is distance squared
- Less susceptible to noise and outliers
- Biased towards globular clusters
- Hierarchical analogue of K-means
 - Can be used to initialize K-means