

population $k \in \{1, 2, 3\}$

Objective:

$$J^k(g, \Gamma, \alpha) = \mathbb{E} \left[\int_0^{T_2} \frac{3}{2} g_t^2 + \frac{\gamma^k}{2} \Gamma_t^2 + \frac{\beta^k}{2} \alpha_t^2 + S_t \Gamma_t dt \right]$$

$$+ (R - X_{T_1})_+ + (R - X_{T_2} + X_{T_1} - (X_{T_1} - R)_+)_+$$

$X_{T_2} - X_{T_1}$
 $+ (X_{T_1} - R)_+$ is the
amt leftover after period 1 quota.

$S = (S_k)_{t \geq 0}$ market price of goods.

Equilibrium clearing condition:

$$\lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \Gamma_t^i = 0$$

where here Γ^i denotes
that we draw at random
a population $k \in \{1, 2, 3\}$ according
to their size and then a
copy of Γ from that population.

Here: $dX_t = (h + g_t + \Gamma_t + C_t)dt + \sigma dW_t$, $X_0 \sim \xi$

$$dC_t = a_t dt, \quad C_0 = 0$$

"Differentiating" X w.r.t. g and Γ in the direction n :

$$\partial_g X_t = \int_0^t n_s ds, \quad \partial_\Gamma X_t = \int_0^t n_s ds. \quad n \text{ adapted}$$

If we differentiate w.r.t. a :

$$\partial_a C_t = \int_0^t n_s ds, \quad \partial_a X_t = \int_0^t \partial_a C_s ds = \int_0^t \int_s n_u du ds.$$

"Differentiating" J^k w.r.t. g in the direction n :

$$\begin{aligned} \partial_g J^k(g, \Gamma, \alpha; n) &= \mathbb{E} \left[\int_0^{T_2} \frac{3}{2} g_t + \Gamma_t dt - \mathbb{1}_{X_{T_1} < R} \partial_g X_{T_1} \right. \\ &\quad \left. - \mathbb{1}_{X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} \partial_g X_{T_2} + \mathbb{1}_{X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ \leq R} \partial_g X_{T_1} \right] \end{aligned}$$

$$\begin{aligned}
&= \mathbb{E} \left[\mathbb{1}_{X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} \frac{1}{X_{T_1} > R} \partial_g X_{T_1} \right] \\
&= \mathbb{E} \left[\int_0^{T_2} 3^k g_t r_t dt - \int_0^{T_1} \mathbb{1}_{X_{T_1} < R} r_t dt \right. \\
&\quad \left. - \int_{T_1}^{T_2} \mathbb{1}_{X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} r_t dt \right. \\
&\quad \left. - \int_0^{T_1} \mathbb{1}_{X_{T_1} > R, X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} \frac{r_t}{X_{T_1}} dt \right] \\
&= \mathbb{E} \left[\int_0^{T_1} \left[3^k g_t - \mathbb{1}_{X_{T_1} < R} - \mathbb{1}_{X_{T_1} > R, X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} \right] r_t dt \right. \\
&\quad \left. + \int_{T_1}^{T_2} \left[3^k g_t - \mathbb{1}_{X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} \right] r_t dt \right]
\end{aligned}$$

Iterating expectations:

$$\partial_g J^k = \mathbb{E} \left[\int_0^{T_1} \left[3^k g_t - V_t - U_t \right] r_t dt + \int_{T_1}^{T_2} \left[3^k g_t - Y_t \right] r_t dt \right]$$

where:

$$V_t = \mathbb{E} \left[\mathbb{1}_{X_t < R} | \mathcal{F}_t \right] = P(X_{T_1} < R | \mathcal{F}_t) \quad \text{← Prob. of non-compliance in period 1}$$

$$\begin{aligned}
U_t &= \mathbb{E} \left[\mathbb{1}_{X_{T_1} > R, X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} | \mathcal{F}_t \right] \\
&\Rightarrow P(X_{T_1} > R, X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R | \mathcal{F}_t) \quad \text{← Prob. of compliance in period 1 and non-compliance in period 2.}
\end{aligned}$$

$$\begin{aligned}
Y_t &= \mathbb{E} \left[\mathbb{1}_{X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} | \mathcal{F}_t \right] \\
&= P(X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R | \mathcal{F}_t) \quad \text{← Prob. of non-compliance in period 2.}
\end{aligned}$$

$$\mathbb{E}[(X_{T_2} - X_{T_1} + (X_{T_1} - K)_+)^{\alpha}] \sim \text{normal}$$

remove \leftarrow

Similarly:

$$\partial_R J^k = \mathbb{E} \left[\int_0^{T_1} [g^k P_t + S_t - V_t - U_t] \eta_t dt + \int_{T_1}^{T_2} [g^k P_t + S_t - Y_t] \eta_t dt \right]$$

Lastly:

$$\begin{aligned} \partial_a J^K &= \mathbb{E} \left[\int_0^T \beta^k a_t \eta_t dt - \int_0^{T_1} \int_0^t \mathbb{1}_{X_{T_1} < R} \eta_u du dt \right. \\ &\quad - \int_0^{T_2} \int_0^t \mathbb{1}_{X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} \eta_u du dt \\ &\quad + \int_0^{T_1} \int_0^t \mathbb{1}_{X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} \eta_u du dt \\ &\quad \left. - \int_0^{T_1} \int_0^t \mathbb{1}_{X_{T_1} > R, X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} \eta_u du dt \right] \\ &= \mathbb{E} \left[\int_0^T \beta^k a_t \eta_t dt - \int_0^{T_1} \int_0^t (\mathbb{1}_{X_{T_1} < R} + \mathbb{1}_{X_{T_1} > R, \dots}) \eta_u du dt \right. \\ &\quad - \int_0^{T_2} \int_0^t \mathbb{1}_{X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} \eta_u du dt \\ &\quad \left. + \int_0^{T_1} \int_0^t \mathbb{1}_{X_{T_2} - \dots < R} \eta_u du dt \right] \end{aligned}$$

Change
order of
integration

$$\begin{aligned} &= \mathbb{E} \left[\int_0^T \beta^k a_t \eta_t dt - \int_0^{T_1} \int_u^{T_1} (\mathbb{1}_{X_{T_1} < R} + \mathbb{1}_{X_{T_1} > R, \dots}) \eta_u dt du \right. \\ &\quad - \int_0^{T_2} \int_u^{T_2} \mathbb{1}_{X_{T_2} - \dots} \eta_u dt du \\ &\quad \left. + \int_0^{T_1} \int_u^{T_1} \mathbb{1}_{X_{T_2} - \dots} \eta_u dt du \right] \end{aligned}$$

$$\begin{aligned}
& + \int_0^{T_1} \int_u^{T_1} \mathbb{1}_{X_{T_2} = \dots} \eta u dt du \Big) \\
= & \mathbb{E} \left\{ \int_0^T \beta^k a_t \eta_t dt - \int_0^{T_1} (T_1 - u) (\mathbb{1}_{X_{T_1} < Q} + \mathbb{1}_{\dots}) \eta u du \right. \\
& - \int_0^{T_2} (T_2 - u) [\mathbb{1}_{X_{T_2} = \dots}] \eta u du \\
& \left. + \int_0^{T_1} (T_1 - u) \mathbb{1}_{X_{T_2} = \dots} \eta u du \right\} \\
& \underbrace{\int_0^{T_1} (T_2 - u) \mathbb{1}_{X_{T_2} = \dots} - (T_2 - T_1) \mathbb{1}_{X_{T_2} = \dots}}_{\text{blue bracket}} \eta u du \\
= & \mathbb{E} \left\{ \int_0^T \left[\beta^k a_t - (T_1 - t) (V_t + U_t) - (T_2 - T_1) Y_t \right] \eta_t dt \right. \\
& \left. + \int_{T_1}^{T_2} \left[\beta^k a_t - (T_2 - t) Y_t \right] \eta_t dt \right\}
\end{aligned}$$

Arguing that these should vanish for all η when (g, γ, α) are optimal we get the first order conditions:

$$\begin{aligned}
g_t^* &= \frac{V_t + U_t}{\beta^k} \mathbb{1}_{t \in [0, T_1]} + \frac{Y_t}{\beta^k} \mathbb{1}_{t \in [T_1, T_2]} \\
r_t^* &= \frac{V_t + U_t - S_t}{\gamma^k} \mathbb{1}_{t \in [0, T_1]} + \frac{Y_t - S_t}{\gamma^k} \mathbb{1}_{t \in [T_1, T_2]} \\
\alpha_t^* &= \frac{(T_1 - t) (V_t + U_t) + (T_2 - T_1) Y_t}{\beta^k} \mathbb{1}_{t \in [0, T_1]} \\
&+ \frac{(T_2 - t) Y_t}{\beta^k} \mathbb{1}_{t \in [T_1, T_2]}
\end{aligned}$$

$$P^F = \mathbb{E}[T_1, T_2]$$

Enforcing the equilibrium clearing condition at optimality:

$$0 = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N p^i = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \left\{ \frac{1}{\delta_i} \left((V_t^i + U_t^i - S_t^i) \mathbb{1}_{t \in [0, T_1]} + (V_t^i - S_t^i) \mathbb{1}_{t \in [T_1, T_2]} \right) \right. \\ \left. + \frac{1}{\delta_2} (- \dots) \mathbb{1}_{k=2} \right\}$$

Assuming proportion of total pop. from k is π_k
we have!

$$\left(\frac{\pi_1}{\delta_1} + \frac{\pi_2}{\delta_2} \right) S_t = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \left\{ \frac{1}{\delta_i} \left[(V_t^i + U_t^i) \mathbb{1}_{t \in [0, T_1]} + V_t^i \mathbb{1}_{t \in [T_1, T_2]} \right] \right. \\ \left. + \frac{1}{\delta_2} (- \dots) \mathbb{1}_{k=2} \right\}$$

"Law of large
numbers
type of result" ↗

$$= \frac{\pi_1}{\delta_1} \left[\mathbb{E}[V_t^1 + U_t^1] \mathbb{1}_{t \in [0, T_1]} + \mathbb{E}[Y_t^1] \mathbb{1}_{t \in [T_1, T_2]} \right] \\ + \frac{\pi_2}{\delta_2} \left[\mathbb{E}[V_t^2 + U_t^2] \mathbb{1}_{t \in [0, T_1]} + \mathbb{E}[Y_t^2] \mathbb{1}_{t \in [T_1, T_2]} \right]$$

We conclude:

$$S_t^* = \left(\omega_1 \mathbb{E}[V_t^1 + U_t^1] + \omega_2 \mathbb{E}[V_t^2 + U_t^2] \right) \mathbb{1}_{t \in [0, T_1]} \\ + \left(\omega_1 \mathbb{E}[Y_t^1] + \omega_2 \mathbb{E}[Y_t^2] \right) \mathbb{1}_{t \in [T_1, T_2]}$$

where

$$\omega_1 = \frac{\frac{\pi_1}{\delta_1}}{\pi_1 + \pi_2}, \quad \omega_2 = \frac{\frac{\pi_2}{\delta_2}}{\pi_1 + \pi_2}$$

where

$$\omega_1 = \frac{\frac{\delta_1}{\pi_1} + \frac{\pi_2}{\delta_2}}{\frac{\delta_1}{\pi_1} + \frac{\pi_2}{\delta_2}}, \quad \omega_2 = \frac{\frac{\delta_2}{\pi_2} + \frac{\pi_1}{\delta_1}}{\frac{\delta_2}{\pi_2} + \frac{\pi_1}{\delta_1}}$$

Using the Mfg representation then we have, for
 $k \in \{1, 2\}$ the PBSDE system:

$$\left\{ \begin{array}{l} dX_t^k = (h^k + g_{t+}^{*,k} + \Gamma_t^{*,k} + C_x^{*,k}) dt + \sigma^k dW_t, \quad X_0^k \sim \xi^k \\ dC_t^{*,k} = a_{t+}^{*,k} dt, \quad C_a^{*,k} = 0 \\ dV_t^k = Z_t^{V,k} dW_t, \quad V_{T_1}^k = \mathbb{1}_{X_{T_1} < R} \\ dU_t^k = Z_t^{U,k} dW_t, \quad U_{T_1}^k = \mathbb{1}_{X_{T_1} > R} Y_{T_1} \\ dY_t^k = Z_t^{Y,k} dW_t, \quad Y_{T_2}^k = \mathbb{1}_{X_{T_2} - X_{T_1} + (X_{T_1} - R)_+ < R} \end{array} \right.$$

And the definitions of g^* , Γ^* , a^* are given above.

highlighted in red