Management Sciences Topics: Convex Optimization Final Project

1 Problem setup

We need to solve the optimization problem of a one-hidden-layer neural network

$$\min_{x_k \in \mathbb{R}^d, y_k \in \mathbb{R}, z \in \mathbb{R}^K, w \in \mathbb{R}} \frac{1}{n} \sum_{i=1}^n \mathcal{L}\left(b_i w + b_i \sum_{k=1}^K \sigma(a_i^\top x_k + y_k) z_k\right),\tag{1.1}$$

where K is the number of neurons, $a_i \in \mathbb{R}^d$ is a data point, $b_i \in \{-1,1\}$ is the class label of a_i , $\sigma(z) = \max(z,0)$ or $\frac{\exp(z)}{1+\exp(z)}$, $\mathcal{L}(z) = \max(1-z,0)$ or $\log(1+\exp(-z))$.

2 Stochastic subgradient method

We first consider the subgradient with respect to each variables.

First, define the variables

$$X = [x_1, x_2, \dots, x_K] \in \mathbb{R}^{d \times K}, \quad Y = [y_1, y_2, \dots, y_k]^\top \in \mathbb{R}^{K \times 1}, \quad Z = [z_1, z_2, \dots, z_k]^\top \in \mathbb{R}^{K \times 1}.$$
 (2.1)

Then a forward pass through the network can be written as

$$A_{1} = AX \oplus Y^{\top},$$

$$A_{2} = \sigma(A_{1})Z \oplus w$$

$$f = \frac{1}{n}1^{\top}L(b \odot A_{2}).$$

$$(2.2)$$

By chain rule, the subgradients of f with respect to each variable are

$$\frac{\partial f}{\partial A_2} = \frac{1}{n} L'(b \odot A_2) \odot b$$

$$\frac{\partial f}{\partial w} = \frac{\partial f}{\partial A_2} \frac{\partial A_2}{\partial w} = \text{rowsum}(\frac{\partial f}{\partial A_2} \odot 1) = \left(\frac{\partial f}{\partial A_2}\right)^{\top} 1,$$

$$\frac{\partial f}{\partial Z} = \frac{\partial f}{\partial A_2} \frac{\partial A_2}{\partial Z} = \sigma(A_1)^{\top} \frac{\partial f}{\partial A_2},$$

$$\frac{\partial f}{\partial A_1} = \frac{\partial f}{\partial A_2} \frac{\partial A_2}{\partial A_1} = \frac{\partial f}{\partial A_2} Z^{\top} \odot \sigma'(A_1),$$

$$\frac{\partial f}{\partial Y} = \frac{\partial f}{\partial A_1} \frac{\partial A_1}{\partial Y} = \left(\frac{\partial f}{\partial A_1}\right)^{\top} 1,$$

$$\frac{\partial f}{\partial X} = \frac{\partial f}{\partial A_1} \frac{\partial A_1}{\partial X} = A^{\top} \frac{\partial f}{\partial A_1}.$$
(2.3)

The stochastic subgradients can be chosen to be the subgradient when input is a minibatch of the whole dataset, i.e.

$$G(x,\xi_i) = \partial_x f(x; A_{\xi_i}, b_{\xi_i}) \tag{2.4}$$

for each variable x, where ξ_i is a uniformly sample index set for each i. We can control the size of each ξ_i to vary from online learning to full-batch learning.

3 Proximal Gradient method with line search

In order to use APG for this problem, we need to choose

$$\sigma(z) = \frac{\exp(z)}{1 + \exp(z)}, \quad \mathcal{L}(z) = \log(1 + \exp(-z))$$
(3.1)

to guarantee the objective function is smooth.

Remark 3.1. For the stop criterion of line search: We try two different methods. 1. After updating x_1 by x_0 , we still use x_0 to compute the derivative with respect to y, z, w. Similarly, we still use x_0, y_0 instead of the updated x_1, y_1 to compute the derivative of z, w, and etc. 2. Use the u[]

4 Accelerated proximal gradient method

In order to use APG for this problem, we need to choose

$$\sigma(z) = \frac{\exp(z)}{1 + \exp(z)}, \quad \mathcal{L}(z) = \log(1 + \exp(-z))$$
(4.1)

to guarantee the objective function is smooth. Notice

$$\mathcal{L}'(z) = -\frac{1}{1 + \exp(z)},\tag{4.2}$$

and

$$|\mathcal{L}''(z)| = \left| \frac{e^z}{(1+e^z)^2} \right| \le \frac{1}{4},$$
 (4.3)

by Lagrange mean value theorem, we know the Lipschitz constant for \mathcal{L}' is $L = \frac{1}{4}$. Now let's consider the Lipschitz constant for each derivatives. For ∂_{A_2} ,

$$\|\partial_{A_2}$$
 (4.4)

For $\frac{\partial f}{\partial w}$,

$$|\partial_{w}(w_{1}) - \partial_{w}(w_{2})| = \frac{1}{n} \sum_{i=1}^{n} b_{i} (\mathcal{L}'(b_{i}(\sigma(A_{1})Z)_{i} + b_{i}w_{1}) - \mathcal{L}'(b_{i}(\sigma(A_{1})Z)_{i} + b_{i}w_{2})$$

$$\leq \frac{1}{n} \sum_{i=1}^{n} b_{i} (\frac{1}{4}b_{i}|w_{1} - w_{2}|) = \frac{1}{4n} \sum_{i=1}^{n} |w_{1} - w_{2}|$$

$$= \frac{1}{4}|w_{1} - w_{2}|.$$

$$(4.5)$$

Then the Lipschitz constant for ∂_w is $L_w = \frac{1}{4}$.