PHYS:5905 Homework 2

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- 1. Larmor Motion in constant, uniform magnetic field with zero electric field.
 - (a) Figure 1 shows the plots of x(t), where the numerical solution is computed with N=2000 timesteps:
 - (b) Figure 2 is the error plot with respect to the number of timesteps. The slope is k = -1.00393.
- 2. $E\times B$ drift in a constant, uniform magnetic and perpendicular electric field.
 - (a) Figure 3 shows the plots of x(t), where the numerical solution is computed with N=2000 timesteps:
 - (b) Figure 4 is the error plot with respect to the number of timesteps. The slope is k=-1.00389.

We notice that the slopes in both problems are just the same when the number of timesteps N is large enough. This shows that the forward difference method is asymptotically linear.

- 3. Second-order timestepping for $E \times B$ drift.
 - (a) Figure 5 shows the plots of x(t), where the numerical solution is computed with N = 1000 timesteps and with leapfrog method:
 - (b) Figure 6 is the error plot with respect to the number of timesteps. The slope is k = -2.
- 4. Use Taylor expansion to demonstrate the order of Leapfrog method In fact, consider the equation

$$\frac{dx}{dt} = v. (1)$$

The Taylor expansion at x_j leads to

$$x_{j+1} = x_j + v_j \Delta t + \frac{1}{2} v'(t_j) (\Delta t)^2 + O((\Delta t)^3),$$
 (2)

 $\quad \text{and} \quad$

$$x_{j-1} = x_j - v_j \Delta t + \frac{1}{2} v'(t_j) (\Delta t)^2 + O((\Delta t)^3).$$
 (3)

Hence

$$x_{j+1} - x_{j-1} = 2v_j \Delta t + O((\Delta t)^3),$$
 (4)

and we get

$$v_j = \frac{dx}{dt}\Big|_{t=t_j} = \frac{x_{j+1} - x_{j-1}}{2\Delta t} + O((\Delta t)^2).$$
 (5)

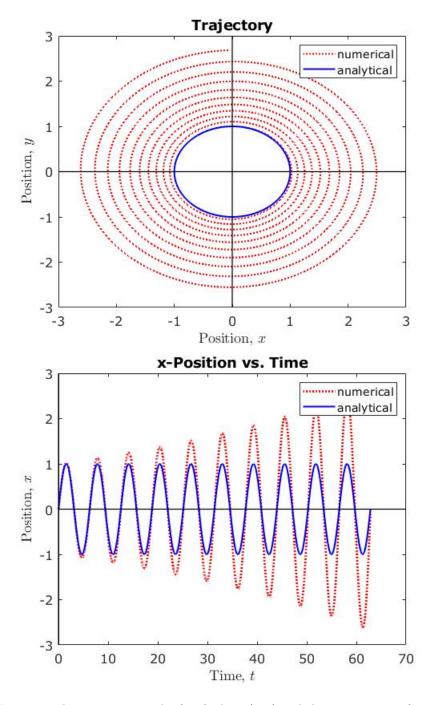


Figure 1: The trajectory in the (x, y) plane (top) and the position x as function of time t (bottom). The dot lines are numerical solutions solved with N=2000 timesteps and the solid lines are the analytical solutions.

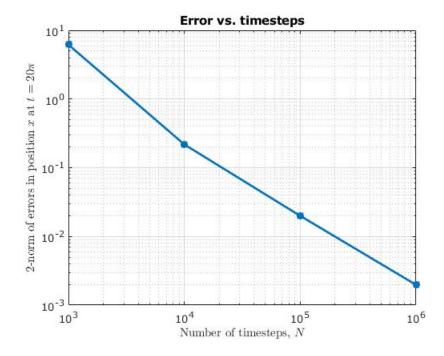


Figure 2: The error at $t=20\pi$ with respect to the number of timesteps N.

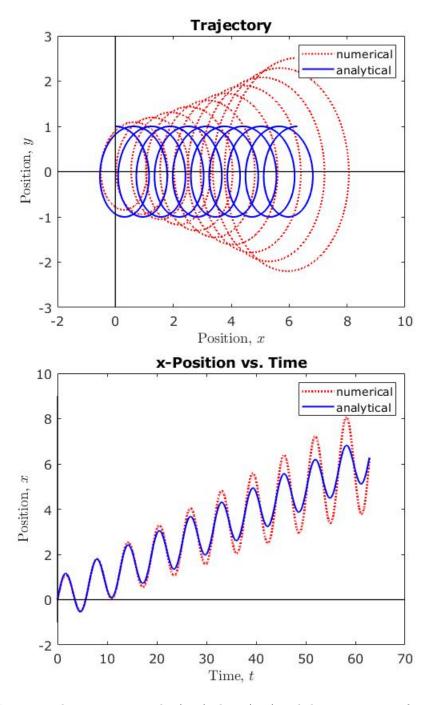


Figure 3: The trajectory in the (x, y) plane (top) and the position x as function of time t (bottom). The dot lines are numerical solutions solved with N=2000 timesteps and the solid lines are the analytical solutions.

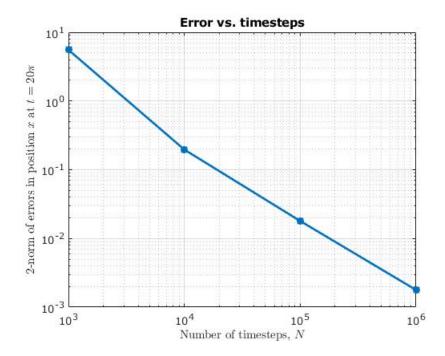


Figure 4: The error at $t=20\pi$ with respect to the number of timesteps N.

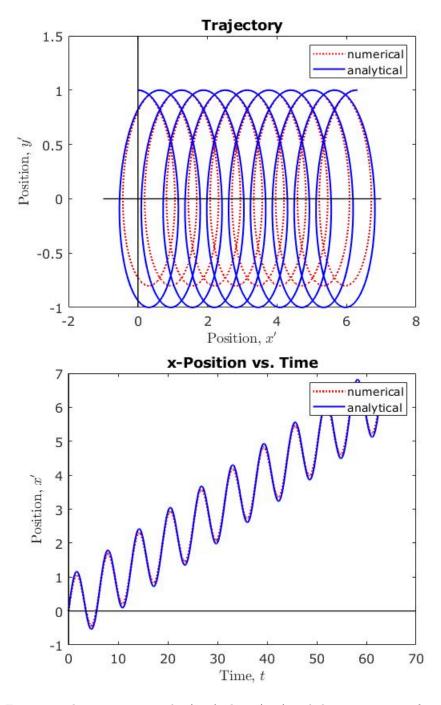


Figure 5: The trajectory in the (x,y) plane (top) and the position x as function of time t (bottom). The dot lines are numerical solutions solved with N=1000 timesteps and the solid lines are the analytical solutions.

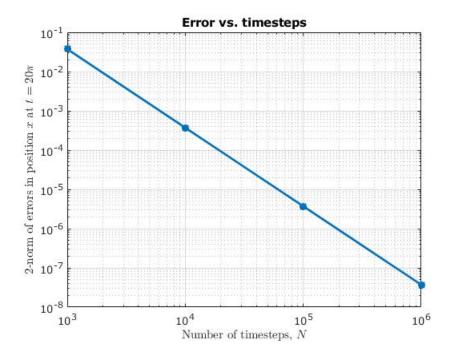


Figure 6: The error at $t=20\pi$ with respect to the number of timesteps N.