

T2.7

$$\|x - a\|_2 \leq \|x - b\|_2$$

$$\Rightarrow (x - a)^T(x - a) \leq (x - b)^T(x - b)$$

$$\Rightarrow x^T x - 2a^T x + a^T a \leq x^T x - 2b^T x + b^T b$$

$$\Rightarrow (b - a)^T x \leq (b^T b - a^T a)/2$$

Therefore, $\{x \mid \|x - a\|_2 \leq \|x - b\|_2\}$ is a halfspace.

T2.12

(d)

$$\|x - x_0\|_2 \leq \|x - y\|_2$$

$$\Rightarrow (x - x_0)^T(x - x_0) \leq (x - y)^T(x - y)$$

$$\Rightarrow x^T x - 2x_0^T x + x_0^T x_0 \leq x^T x - 2y^T x + y^T y$$

$$\Rightarrow (y - x_0)^T x \leq (y^T y - x_0^T x_0)/2$$

For a given $y \in S$, $\{x \mid \|x - x_0\|_2 \leq \|x - y\|_2\}$ represents a halfspace in \mathbb{R}^n , and is a convex set. Therefore, $\{x \mid \|x - x_0\|_2 \leq \|x - y\|_2 \text{ for any } y \in S\}$ can be written as $\bigcap_{y \in S} \{x \mid \|x - x_0\|_2 \leq \|x - y\|_2\}$ and is a convex set.

(e)

We could apply the same method and conclude that for each x that satisfies $\text{dist}(x, S) \leq \text{dist}(x, T)$, there is always a $y \in S$ and $z \in T$ that makes it equivalent to $\|x - y\|_2 \leq \|x - z\|_2$, which is a halfspace. However, this does not mean all points that satisfies $\{x \mid \text{dist}(x, S) \leq \text{dist}(x, T)\}$ are also in that particular halfspace. To see this, consider $S = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 = 1, y \leq 0\}$ and $T = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 = 2, y \leq 0\}$ and $A = \{(x, y) \in \mathbb{R}^2 \mid \text{dist}(x, S) \leq \text{dist}(x, T)\}$. Obviously A is not a convex set.

(f)

Assume $S = \{x \mid \|x - a\|_2 \leq \theta \|x - b\|_2\}$. Again, we could rewrite the inequality as follow:

$$\underbrace{(1 - \theta^2)}_a x^T x + \underbrace{2(\theta^2 b - a)^T}_b x + \underbrace{(a^T a - \theta^2 b^T b)}_c \leq 0$$

$$\Rightarrow a\|x - h\|_2 + k \leq 0, \text{ where } h = -b/2a \text{ and } k = c - b^2/4a.$$

Now we could apply the definition and assume $x_1, x_2 \in S$ and $0 \leq \theta \leq 1$. We have

$$a\|\theta x_1 + (1 - \theta)x_2 + h\|_2 + k \leq a\theta\|x_1 + h\|_2 + a(1 - \theta)\|x_2 + h\|_2 + k \leq 0$$

Therefore, S is a convex set.

T2.16

Consider two points $(x', y'_1 + y'_2), (x'', y''_1 + y''_2) \in S$ with $(x', y'_1), (x'', y''_1) \in S_1$ and $(x', y'_2), (x'', y''_2) \in S_2$, and $0 \leq \theta \leq 1$. By applying the definition, we have

$$\begin{aligned} (x, y) &= \theta(x', y'_1 + y'_2) + (1 - \theta)(x'', y''_1 + y''_2) \\ &= (\theta x', \theta(y'_1 + y'_2)) + ((1 - \theta)x'', (1 - \theta)(y''_1 + y''_2)) \end{aligned}$$

Since both S_1 and S_2 are convex, $(\theta x', \theta y'_1) + ((1 - \theta)x'', (1 - \theta)y''_1) \in S_1$ and $(\theta x', \theta y'_2) + ((1 - \theta)x'', (1 - \theta)y''_2) \in S_2$. Therefore $(x, y) \in S$ since it is a partial sum of two points from S_1 and S_2 .

Add.1

(a)

We could simplify the original fitting problem as follow:

$$\begin{aligned} &\min \sum_{i=1}^m ((u_i - u_c)^2 + (v_i - v_c)^2 - R^2)^2 \\ &\Rightarrow \min \sum_{i=1}^m (u_i^2 + v_i^2 - 2u_i u_c - 2v_i v_c + (v_c^2 + u_c^2 - R^2))^2 \end{aligned}$$

To write it into a linear least-square problem, we could have $a_i^T = [-2u_i \ -2v_i \ 1]^T$ and $b_i = -u_i^2 - v_i^2$, which are the row vectors of A and b , and variable $x = [x_1 \ x_2 \ x_3]^T$.

(b)

If we expand the normal equation with A and b we selected from (a), we get the following equation from the third row of expansion:

$$\begin{aligned}
2x_1 \sum_{i=1}^n u_i + 2x_2 \sum_{i=1}^n v_i - nx_3 &= \sum_{i=1}^n (u_i^2 + v_i^2) \\
\Rightarrow nx_1^2 + nx_2^2 - nx_3 &= nx_1^2 + nx_2^2 - 2x_1 \sum_{i=1}^n u_i - 2x_2 \sum_{i=1}^n v_i + \sum_{i=1}^n (u_i^2 + v_i^2) \\
\Rightarrow n(x_1^2 + x_2^2 - x_3) &= \sum_{i=1}^n (x_1 - u_i)^2 + \sum_{i=1}^n (x_2 - v_i)^2 \geq 0
\end{aligned}$$

i.e. $\hat{x}_1^2 + \hat{x}_2^2 - \hat{x}_3 \geq 0$.

(c)

Figure 1 presents the least-square fit of a circle to points.

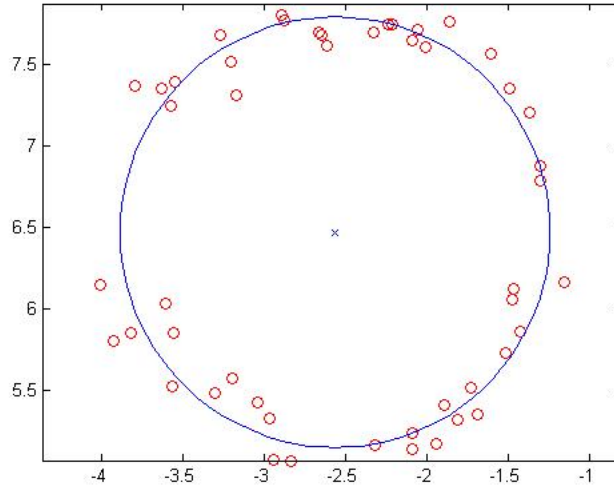


Figure 1: Least Square Fit

Add.2

(a)

From Figure 2. The optimal γ is 0.35 and the corresponding objective value is 0.4809.

(b)

$x = [1 \ 0 \ 1 \ 0 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1]^T$ and $p = 0.8628$.

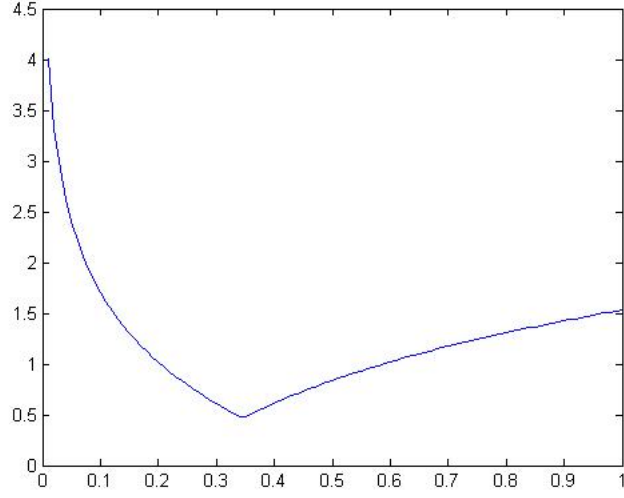


Figure 2: Equal Lamp Power

(c)

$\rho = 0.2200$, $x = [0.5 \ 0.4773 \ 0.0832 \ 0 \ 0.4559 \ 0.4353 \ 0.4595 \ 0.4306 \ 0.4035 \ 0.4525]^T$ and $p = 0.4440$.

(d)

With `cvx` we acquired a solution $x = [1 \ 0.1165 \ 0 \ 0 \ 1 \ 0 \ 1 \ 0.0249 \ 0 \ 1]^T$ and an objective value $p = 0.4198$.

(e)

With `cvx` we acquired a solution $x = [1 \ 0.1896 \ 0 \ 0 \ 1 \ 0 \ 1 \ 0.1640 \ 0 \ 1]^T$ and an objective value $p = 0.3664$.

(f)

With `cvx` we acquired the exact solution as $x = [1 \ 0.2023 \ 0 \ 0 \ 1 \ 0 \ 1 \ 0.1882 \ 0 \ 1]^T$ and objective value $p = 0.3575$.