## **T9.3**

(a)

 $p^* = 1$ , with optimal point not attained.

(b)

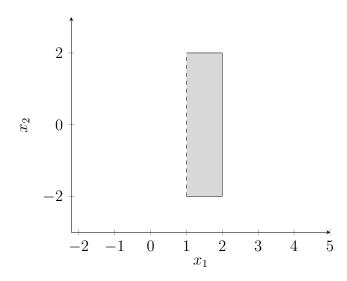


Figure 1: Level curve, constraints and feasible set

The grayed region is the sublevel set. It is not closed since on the boundary  $x_1 > 1$ . It is strongly convex since there exist  $m \ge 0$ , for instance, m = 1, such that the *Hessian* 

$$\nabla^2 f(x) = 2I \succeq mI$$

(c)

No, since it requires the sublevel set S to be closed.

## A8.1

(a)

For convenience we have  $x = [x_1 \sqrt{\gamma} x_2]^T$  and  $y = [y_1 \ y_2]^T$ . For  $x_1 \ge |x_2|$ ,

$$\sup_{||y|| \le 1} x^T y = ||x|| = \sqrt{x_1^2 + \gamma x_2^2}$$
 (1)

With y satisfying

$$y = \frac{1}{\sqrt{x_1^2 + \gamma x_2^2}} \begin{bmatrix} x_1 \\ \sqrt{\gamma} x_2 \end{bmatrix}$$

Now since we have  $x_1 \ge |x_2|$ ,

$$y_1 = \frac{x_1}{\sqrt{x_1^2 + \gamma x_2^2}} \ge \frac{1}{\sqrt{1+\gamma}}$$

This means that we can always find such a direction of y such that it satisfies the constraint and (1) can be established. For  $x_1 < |x_2|$ , since we have  $\gamma \ge 1$ , we always have  $|y_1| \le \sqrt{\gamma}|y_2|$ . Through inspection we have

$$\sup_{\|y\| \le 1, y_1 \ge 1/\sqrt{(1+\gamma)}} x^T y = \frac{x_1 + \gamma |x_2|}{\sqrt{(1+\gamma)}}$$

By taking  $y_1 = 1/\sqrt{(1+\gamma)}$  and  $y_2 = \pm \sqrt{\gamma}/\sqrt{(1+\gamma)}$ , with  $y_2$  taking the same sign as  $x_2$ . Since the set

$$f(x_1, x_2) = \sup\{x_1y_1 + \sqrt{\gamma}x_2y_2 \mid y_1^2 + y_2^2 \le 1, y_1 \ge 1/\sqrt{(1+\gamma)}\}\$$

is convex for a fixed y and we just showed its equivalence to the function, the function  $f(x_1, x_2)$  is also convex.

(b)

With  $x^{(0)} = (\gamma, 1)$ , we have

$$\nabla f = \frac{1}{\sqrt{x_1^2 + \gamma x_2^2}} \begin{bmatrix} x_1 \\ \gamma x_2 \end{bmatrix}$$

For convenience we write

$$t\Delta x = -t\nabla f = \frac{-t}{\sqrt{x_1^2 + \gamma x_2^2}} \begin{bmatrix} x_1 \\ \gamma x_2 \end{bmatrix} = -s \begin{bmatrix} x_1 \\ \gamma x_2 \end{bmatrix}$$

Therefore we have,

$$x^{(k+1)} = x^{(k)} - s^{(k)} \begin{bmatrix} x_1^{(k)} \\ \gamma x_2^{(k)} \end{bmatrix} \qquad s^{(k)} = \frac{t^{(k)}}{\sqrt{(x_1^{(k)})^2 + \gamma(x_2^{(k)})^2}}$$

With  $x^{(0)} = (\gamma, 1)$ , it fits the iterates at k = 0. Using induction assume at iteration k,

$$x_1^{(k)} = \gamma (\frac{\gamma - 1}{\gamma + 1})^k, \qquad x_2^{(k)} = (-\frac{\gamma - 1}{\gamma + 1})^k$$

$$x^{(k+1)} = \begin{bmatrix} \gamma - s^{(k)} \gamma \\ (-1)^k - (-1)^k \gamma s^{(k)} \end{bmatrix} (\frac{\gamma - 1}{\gamma + 1})^k$$

Plugging back to  $f(x_1, x_2)$  and take derivative over  $s^{(k)}$ , set it to zero, and we have

$$s^{(k)} = \frac{2}{\gamma + 1}$$

and

$$x_1^{(k+1)} = \gamma (\frac{\gamma - 1}{\gamma + 1})^{k+1}, \qquad x_2^{(k+1)} = (-\frac{\gamma - 1}{\gamma + 1})^{k+1}$$

## $\mathbf{A8.9}$

(a)

First we rewrite the problem as

minimize 
$$-\sum_{\bar{u}_i=1} \log \Phi(a_i^T x - b_i) - \sum_{\bar{u}_i=-1} \log \Phi(b_i - a_i^T x)$$

Where  $\Phi(x)$  is the cumulative Gaussian distribution function, which is log-concave. Therefore this problem is convex.

(b)

To simplify the problem, we redefine A and b as

$$A = \mathbf{diag}(y)A, \qquad b = \mathbf{diag}(y)b.$$

Thus the problem can be written as

minimize 
$$h(Ax - b)$$
,

where

$$h(\omega) = -\sum_{i=1}^{m} \log \Phi(\omega_i).$$

The gradient and Hessian of f(x) = H(Ax - b) are

$$\nabla f(x) = A^T \nabla h(Ax - b), \qquad \nabla f(x)^2 = A^T \nabla^2 h(Ax - b)A$$

The first derivative of h are

$$\frac{\partial h(\omega)}{\partial \omega_i} = \frac{-1/\sqrt{2\pi}}{\exp(\omega_i^2/2)\Phi(\omega_i)}$$

The Hessian of h are

$$\frac{\partial^2 h(\omega)}{\partial \omega_i^2} = \frac{\omega_i / \sqrt{2\pi}}{\exp(\omega_i^2 / 2)\Phi(\omega_i)} + (\frac{1/\sqrt{2\pi}}{\exp(\omega_i^2 / 2)\Phi(\omega_i)})^2$$

This converges within 5 steps and x = (0.27, 9.15, 7.98, 6.70, 6.02, 5.0, 4.30, 2.68, 2.02, 0.68).

```
clc;clear;
one_bit_meas_data;
A = diag(y)*A;
b = y.*b;
x = A \ b;
for k = 1 : 50
   w = A*x - b;
   Phi = 0.5*erfc(-w/sqrt(2));
   Phix = 0.5*sqrt(2*pi)*erfcx(-w/sqrt(2));
   obj = -sum(log(Phi));
   grad = -A'*(1./Phix);
   hess = A'*diag((w+1./(Phix))./Phix)*A;
   v = -hess \grad;
   f = grad'*v;
   if (-f/2 < 1e-8)
       break:
   end
   while (-sum(log(0.5*erfc(-(A*(x+t*v)-b)/sqrt(2)))) > ...
        obj + 0.01*t*f)
        t = t/2;
   end
   x = x + t*v;
end
```