

有可能会遇到的问题

情况一：替换不同的动作序列导致的已经匹配好的人物位置不同

Solution:

First step：将需要匹配的动作序列（npz 文件）中的 transl 和 global_orient 替换成 /home/zhiyw/Desktop/AnimatableGaussians/configs/thuman4/pose_00.npz 中的 transl 和 global_orient

pose_00.npz — Ark						
Name	Original Size	Compressed Size	CRC checksum	Method	Date	
betas.npy	168 B	168 B	9B251BF4	Store	01.01.80 00:00	
body_pose.npy	615,4 KiB	615,4 KiB	608EABA0	Store	01.01.80 00:00	
expression.npy	97,8 KiB	97,8 KiB	5AD527A8	Store	01.01.80 00:00	
<u>global_orient.npy</u>	29,4 KiB	29,4 KiB	941FF499	Store	01.01.80 00:00	
jaw_pose.npy	29,4 KiB	29,4 KiB	55A7801E	Store	01.01.80 00:00	
left_hand_pose.npy	439,6 KiB	439,6 KiB	FF739207	Store	01.01.80 00:00	
right_hand_pose.npy	439,6 KiB	439,6 KiB	AE372EC4	Store	01.01.80 00:00	
<u>transl.npy</u>	29,4 KiB	29,4 KiB	391A2244	Store	01.01.80 00:00	

Second step：使用新生成的 npz 文件训练人物高斯

Run (python main_avatar.py -c configs/人物文件夹/avatar.yaml --mode=test)

```
test:
  dataset: MvRgbDatasetAvatarReX
  data:
    data_dir: /home/zhiyw/Desktop/AnimatableGaussians/configs/zrz
    frame_range: [0, 1]
    subject_name: avatarrex_zrz
  pose_data:
    data_path: /home/zhiyw/Desktop/AnimatableGaussians/configs/thuman4/01_modified.npz
    frame_range: [0, 1]
#   data_path: Z:/Data/Pose/AMASS/CMU/06/06_13_poses.npz
#   data_path: Z:/Data/Pose/AMASS/CMU/10/10_05_poses.npz
#   frame_interval: 4
```

Figure1: 使用新 npz 文件 (01_modified.npz) 训练，avatar.yaml 的配置

```
[animatable_gaussians] zhiyw@dst-jyk:~/Desktop/AnimatableGaussians$ python main_avatar.py -c configs/zrz/avatar.yaml --mode=test
# Using GL-based Renderer
Import AvatarNet from network.avatar
# Parameter number of AvatarNet is 223648936
# Selected frame indices: range(0, 1801, 1)
# Dataset contains 1801 items
/home/zhiyw/Desktop/ENTER/envs/animatable_gaussians/lib/python3.10/site-packages/scikit-learn/base.py:329: UserWarning: Trying to unpickle estimator PCA from version 0.23.2 when using version 1.1.3. This might lead to breaking code or invalid results. Use at your own risk. For more info please refer to:
https://scikit-learn.org/stable/model_persistence.html#security-maintainability-limitations
warnings.warn(
# Selected frame indices: range(0, 1)
# Pose list: []
# Dataset contains 1 items
Loading networks from /home/zhiyw/Desktop/AnimatableGaussians/results/avatarrex_zrz/avatar/batch_250000/net.pt
# Output dir: /test_results/avatarrex_zrz/avatar/thuman4_01_modified_free_view/batch_250000/pca_20_sigma_2.00
Rendering avatars...: 0%|                                     | 0/1 [00:00<?, ?it/s]
glx: failed to create dri3 screen
failed to load driver: nouveau
failed to get magic
failed to load driver: nouveau
Rendering avatars...: 100%|                                     | 1/1 [00:03<00:00,  3.93s/it]
[animatable_gaussians] zhiyw@dst-jyk:~/Desktop/AnimatableGaussians$
```

Figure2: 训练动作序列

Step 3：将训练好的 ply 文件进行位置转换（应用 trans matrix）

Trans matrix 的文件在/home/zhiyw/Desktop/animatable_dataset/human_trans/trans.md

```
(hugs) zhiyw@dst-jyk:~/Desktop/ml-hugs$ python scripts/transform_human_sequence.py --input_dir /mnt/data_hdd/zhiyw/test/01pose/original/ply --output_dir /mnt/data_hdd/zhiyw/test/01pose/modified_free_view/batch_250000/pca_20_sigma_2.00/posed_gaussians --start_frame 0 --end_frame 0 --output_format ply --load_ply
2026-01-09 16:55:44.822 | INFO | __main__:_main:292 - Processing frames 0 to 0
2026-01-09 16:55:44.823 | INFO | __main__:_main:293 - Input directory: /mnt/data_hdd/zhiyw/test/01pose/original/ply
2026-01-09 16:55:44.823 | INFO | __main__:_main:294 - Output directory: /mnt/data_hdd/zhiyw/test/01pose/dj
2026-01-09 16:55:44.823 | INFO | __main__:_main:295 - Output format: pt
Processing frames: 0% | 0/1 [00:00<?, ?it/s] 2026-01-09 16:55:44.824 | INFO | __main__:_load_ply_
gaussians:24 - Loading PLY file: /mnt/data_hdd/zhiyw/test/01pose/original/ply/00000000.ply | 0/1 [00:00<?, ?it/s]
2026-01-09 16:55:44.824 | INFO | __main__:_save_gaussians_to_pt:294 - Saved transformed PT to: /mnt/data_hdd/zhiyw/test/01pose/dj/pt/00000000.pt
2026-01-09 16:55:44.824 | INFO | __main__:_main:322 - Processed frame 00000000
Processing frames: 100% | 1/1 [00:05<00:00, 5.95s/it] 2026-01-09 16:55:44.824 | INFO | __main__:_main:328 - All frames processed successfully!
=====
TRANFORMATION SUMMARY
=====
Input directory: /mnt/data_hdd/zhiyw/test/01pose/original/ply
Output directory: /mnt/data_hdd/zhiyw/test/01pose/dj
Frames processed: 0 to 0
Output format: pt
Transformation matrix applied:
[[ 0.00459684 -0.12459285 0.08340451 -3.7009557]
 [ 0.14971124 0.08826904 0.00426282 -2.73571191]
 [-0.08813661 0.08311586 0.12466145 -4.24491024]
 [ 0.          0.          0.          1.        ]]

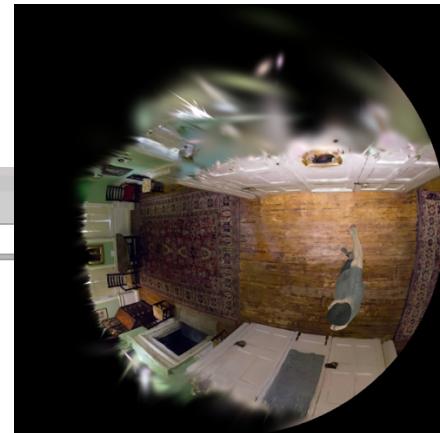
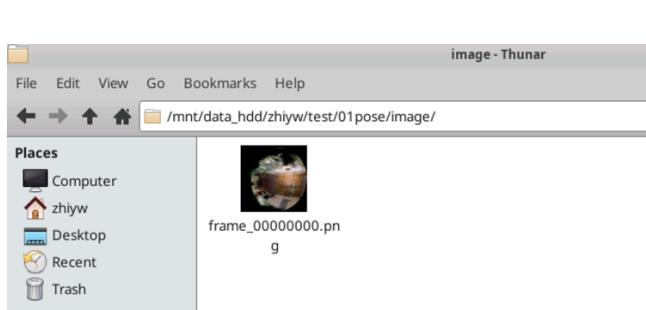
(hugs) zhiyw@dst-jyk:~/Desktop/ml-hugs$ python scripts/transform_human_sequence.py --input_dir /home/zhiyw/Desktop/AnimatableGaussians/test_results/avatarrex_zzr/avatar/thuman4_0_modified_free_view/batch_250000/pca_20_sigma_2.00/posed_gaussians --start_frame 0 --end_frame 0 --output_dir /mnt/data_hdd/zhiyw/test/01pose/original --output_format ply --load_ply
2026-01-09 16:54:23.576 | INFO | __main__:_main:292 - Processing frames 0 to 0
2026-01-09 16:54:23.576 | INFO | __main__:_main:293 - Input directory: /home/zhiyw/Desktop/AnimatableGaussians/test_results/avatarrex_zzr/avatar/thuman4_01_modified_free_view/batch_250000/pca_20_sigma_2.00/posed_gaussians
2026-01-09 16:54:23.577 | INFO | __main__:_main:294 - Output directory: /mnt/data_hdd/zhiyw/test/01pose/original
2026-01-09 16:54:23.577 | INFO | __main__:_main:295 - Output format: ply
Processing frames: 0% | 0/1 [00:00<?, ?it/s] 2026-01-09 16:54:23.578 | INFO | __main__:_load_ply_
gaussians:24 - Loading PLY file: /home/zhiyw/Desktop/AnimatableGaussians/test_results/avatarrex_zzr/avatar/thuman4_01_modified_free_view/batch_250000/pca_20_sigma_2.00/posed_gaussians/00000000.ply | 0/1 [00:00<?, ?it/s]
2026-01-09 16:54:23.833 | INFO | __main__:_save_gaussians_to_ply:290 - Saved transformed PLY to: /mnt/data_hdd/zhiyw/test/01pose/original/ply/00000000.ply
2026-01-09 16:54:23.861 | INFO | __main__:_main:322 - Processed frame 00000000
Processing frames: 100% | 1/1 [00:11<00:00, 11.50s/it] 2026-01-09 16:54:23.862 | INFO | __main__:_main:328 - All frames processed successfully!
=====
TRANFORMATION SUMMARY
=====
Input directory: /home/zhiyw/Desktop/AnimatableGaussians/test_results/avatarrex_zzr/avatar/thuman4_01_modified_free_view/batch_250000/pca_20_sigma_2.00/posed_gaussians
Output directory: /mnt/data_hdd/zhiyw/test/01pose/original
Frames processed: 0 to 0
Output format: ply
Transformation matrix applied:
[[ 1.417337 -3.710793 5.757977 20.600479]
 [-0.786681 -5.929179 -3.63677 2.822414]
 [ 6.86973 0.089329 -1.61852 25.560027]
 [ 0.          0.          0.          1.        ]]
```

Step 4: 使用 python /home/zhiyw/Desktop/ml-hugs/hugs/renderer/render_sequence_firstcamera.py 渲染

染

```
(hugs) zhiyw@dst-jyk:~/Desktop/ml-hugs$ python hugs/renderer/render_sequence_firstcamera.py --human_pt_dir "/mnt/data_hdd/zhiyw/test/01pose/dj/pt/" --scene_pt "/home/zhiyw/Desktop/animatable_dataset/scene/dj/dj_3dgs.pt" --output_dir "/mnt/data_hdd/zhiyw/test/01pose/image" --start_frame 0 --end_frame 0 --camera_json "/home/zhiyw/Desktop/ml-hugs/ml_camera/lab/train_camera_params/dj_im.json" --render_mode human_scene
2026-01-09 16:55:33.089 | INFO | __main__:_main:229 - Loading scene data from: /home/zhiyw/Desktop/animatable_dataset/scene/dj/dj_3dgs.pt
2026-01-09 16:55:34.181 | INFO | __main__:_main:231 - Scene loaded: 2567633 Gaussians
2026-01-09 16:55:34.181 | INFO | __main__:_main:235 - Starting batch rendering frames 0 to 0
Rendering frames: 0% | 0/1 [00:00<?, ?it/s] CUDA Kernel: Fisheye GS
2026-01-09 16:55:34.598 | INFO | __main__:_save_rendered_image:179 - Frame 00000000 rendered and saved
Rendering frames: 100% | 1/1 [00:00<00:00, 1.82it/s] 2026-01-09 16:55:34.653 | INFO | __main__:_main:306 - Completed! 1/1 frames rendered successfully.
```

生成的图片如下



情况二：需要生成新的位置摄像头

方法一 使用四元数生成虚拟摄像头

Step1: 使用四元数生成 json 文件

1. 使用 /home/zhiyw/Desktop/ml-hugs/data/neuman/dataset/lab/sparse/camera.txt 调整摄像头类型 (pinhole or fisheyes)

2. 使用 /home/zhiyw/Desktop/ml-hugs/data/neuman/dataset/lab/sparse/image.txt 调整摄像头位置

```
# Image list with two lines of data per image:  
#   IMAGE_ID, QW, QX, QY, QZ, TX, TY, TZ, CAMERA_ID, NAME  
#   POINTS2D[] as (X, Y, POINT3D_ID)  
# Number of images: 40, mean observations per image: 1477.504854368932  
57 0.714468 0.699646 0.002177 -0.005021 -0.224419 -0.03972 3.042475 1 00038.png
```

$Q_w \quad Q_x \quad Q_y \quad Q_z \quad T_x \quad T_y \quad T_z$

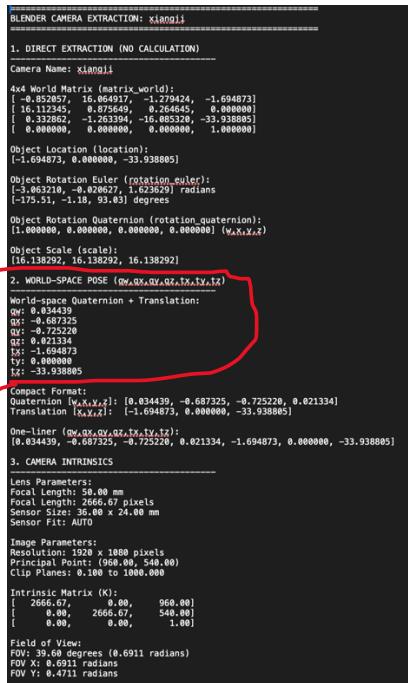
- Step 2:** 在 hugs 的环境中 run python run_extract_camera.py --seq lab. --split. train. --output (地址自选) 就会生成新的 json 文件

方法二 使用 blender 生成虚拟摄像头

Step1: 高斯场景导入 blender (File → Import → PLY (.ply))

Step2: 在想要观测人物的位置创建虚拟摄像头 (Shift + A → Camera)

Step3: 使用 /home/zhiyw/Desktop/ml-hugs/scripts/ blender_camera.py 导出摄像头参数，导出的 txt 文件如图



```
BLENDER CAMERA EXTRACTION: xiangji
=====
1. DIRECT EXTRACTION (NO CALCULATION)
Camera Name: xiangji

4x4 World Matrix (matrix_world):
[ -0.852057, 16.064917, -1.279424, -1.694873]
[ 16.064917, 0.852057, 1.279424, -1.694873]
[ 0.332862, -1.263394, -16.085374, -33.938805]
[ 0.000000, 0.000000, 0.000000, 1.000000]

Object Location (location):
[-1.694873, 0.000000, -33.938805]

Object Rotation Euler (rotation_euler):
[-3.063210, -0.826827, 1.623629] radians
[-175.51, -1.18, 93.03] degrees

Object Rotation Quaternion (rotation_quaternion):
[1.000000, 0.000000, 0.000000, 0.000000] (w,x,y,z)

Object Scale (scale):
(16.138292, 16.138292, 16.138292)

2. WORLD-SPACE POSE (qw,qx,qy,qz,tx,ty,tz)
World-Space Quaternion + Translation:
qw: 0.834439
qx: -0.687325
qy: 0.021334
qz: 0.213334
tx: -1.694873
ty: 0.000000
tz: -33.938805

Compact Format:
Quaternion [w,x,y,z]: [0.834439, -0.687325, 0.021334]
Translation [x,y,z]: [-1.694873, 0.000000, -33.938805]

One-liner (qw,qx,qy,qz,tx,ty,tz):
[0.834439, -0.687325, 0.021334, -1.694873, 0.000000, -33.938805]

3. CAMERA INTRINSICS
Lens Parameters:
Focal Length: 50.00 mm
Focal Distance: 50.00 pixels
Sensor Size: 36.00 x 24.00 mm
Sensor Fit: AUTO

Image Parameters:
Resolution: 1920 x 1080 pixels
Principal Point: (960.00, 540.00)
Clip Planes: 0.100 to 1000.000

Intrinsic Matrix (K):
[ 2666.67, 0.00, 960.00]
[ 0.00, 2666.67, 540.00]
[ 0.00, 0.00, 1.00]

Field of View:
FOV: 39.68 degrees (0.6911 radians)
FOV X: 0.6911 radians
FOV Y: 0.4711 radians
```

使用导出后的 $qw, qx, qy, qz, tx, ty, tz$ 来代替 image.txt 中的 $qw, qx, qy, qz, tx, ty, tz$

Step4: 在 hugs 的环境中 run python run_extract_camera.py --seq lab. --split. train. --output (地址自选) 就会生成新的 json 文件

情况三：使用 raw data 生成 smplx 参数以适配 animatable_gaussians pipeline

我在 GitHub 提问怎样把 easymocap 得到的 smplx 参数转换成标准 smplx 参数的问题有人回答我了，具体链接在 <https://github.com/lizhe00/AnimatableGaussians/issues/8#issuecomment-3650704853>



Figure3: 问题的回答截图

如果能通过这个方法生成标准 smplx 参数，那么 dna rendering 就可以作为 animatable_gaussians 的数据集使用 (animatable_gaussians 的 input: 1.smplx 参数, 2.rgb image, 3.mask, 4.camera calibration)

情况四：使用新的人物与场景对齐

Step1: 使用 cloudcompare 导入人物和场景

Step2: 选中人物点云，将人物点云放置在场景点云的地面上

Step3: 导出 trans