

# Quiz

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02 December 2016

1. We are working in three dimensions but we are using vectors that contain four elements (not three) and matrices that contain  $4 \times 4$  elements. What have we gained by choosing  $4 \times 4$  matrices rather than  $3 \times 3$  matrices?
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We have gained the ability to apply multiple transformations after one another using the same matrix. If we use  $4 \times 4$  matrices, then we gain the ability to represent translation using a matrix multiplication which can't be done in a 3D system with  $3 \times 3$  matrices. This means that for a complex transformation, the computationally intensive matrix multiplication can be done just once to get the matrix that we need that represents the transformation and then multiplied with all the relevant vectors. Using  $4 \times 4$  matrices makes the perspective projection expressible with a matrix too.

2. Many systems (including three.js, the system that we have chosen) support both RGB and HSL color. Distinguish between the two. How does a programmer specify a color using the two systems?
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An RGB color system works by defining a color by specifying the intensity levels of the colors red, green, and blue. A HSL color system works by defining a color by specifying the hue, saturation, and lightness. Each is a model of working with colors and a different way to specify a color. The advantage of HSL is that the transition from black to a hue to white is symmetric and is controlled solely by increasing lightness. However, RGB directly reflects how a Truecolor display renders colors.

3. Programmers can specify a cubic Bézier curve by providing four points.
  - (a) Which of the points will lie on the curve?

- (b) The curve will be contained in the convex hull of the four points. What is the convex hull?
  - (c) Let  $\vec{p}_0, \vec{p}_1, \vec{p}_2$  and  $\vec{p}_3$  be vectors that specify the location of the four points that specify a cubic Bézier curve. What is the geometric significance of  $\vec{p}_1 - \vec{p}_0$  and  $\vec{p}_3 - \vec{p}_2$ ?
  - (d) How can a programmer rotate a Bézier curve?
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- (a) The first and the last point specified will lie on the curve. The others usually do not.
  - (b) The convex hull is the smallest convex set that contains the set of points in question. A convex set is a region such that for every pair of points within the region, every point on the straight line segment that joins the pair of points is also within the region. This means that a Bézier curve will always be inside its convex hull.
  - (c) The tangent to the curve at point  $p_0$  is in the same direction as the vector  $\vec{p}_1 - \vec{p}_0$  and the tangent to the curve at point  $p_3$  is in the same direction as the vector  $\vec{p}_3 - \vec{p}_2$ . This means that the derivative at the first or last point of a Bézier curve is the same as the gradient of the line connecting the first and second point or the second last and last point respectively.
  - (d) To rotate a Bézier curve, the rotation matrix can be multiplied with the control points to rotate the entire Bézier curve.
4. The JavaScript language allows programmers to assign functions to variables, to pass a function  $a$  to another function  $b$ , and to return a function  $d$  from another function  $c$  to  $c$ 's caller. This is a powerful feature of the language. What is this feature called?
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JS supports functional programming because you can do the things mentioned above.

5. Let  $\vec{p}_0, \vec{p}_1$  and  $\vec{p}_2$  be vectors that describe the location of the three vertices of a triangle.

What is the geometric significance of the following expression?

$$\frac{1}{|(\vec{p}_1 - \vec{p}_0) \times (\vec{p}_2 - \vec{p}_0)|} ((\vec{p}_1 - \vec{p}_0) \times (\vec{p}_2 - \vec{p}_0))$$

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The expression will give the normal unit vector to any point on the triangle. This is what is used to calculate shading of the triangle in a 3D renderer.

6. Let  $\hat{n}$  and  $\hat{s}$  be two vectors. The magnitude of each vector is one. The vector  $\hat{n}$  is normal (perpendicular) to some small piece of a surface in our virtual world. The vector  $\hat{s}$  points toward the source of light.

What is the significance of the dot product of these two vectors?

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The dot product is used as a percentage of the amount of light that strikes the polygon region and thus can be used to emulate the effects of light and shadow.