Calibration results
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Camera-system parameters:
cam0 (/front_camera/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [-0.43397636 0.20863354 -0.00296265 -0.00081494] +- [0.0081725 0.02567294 0.00098762 0.00094923]
projection: [852.15918378 850.16998796 613.43834373 308.19908328] +- [5.68503747 5.63288335 4.79706855 4.79664356]
reprojection error: [0.000002, -0.000001] +- [0.503095, 0.526452]

Target configuration
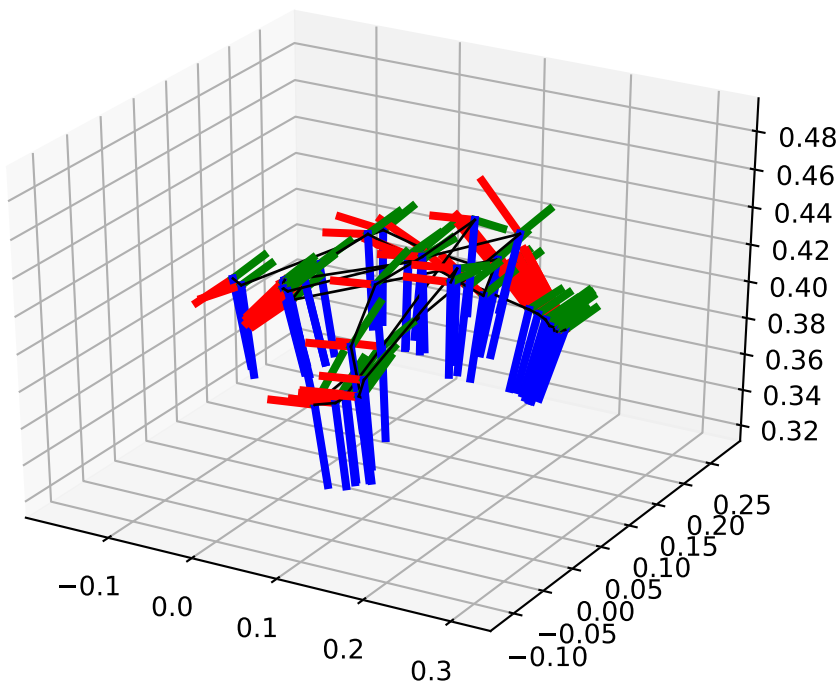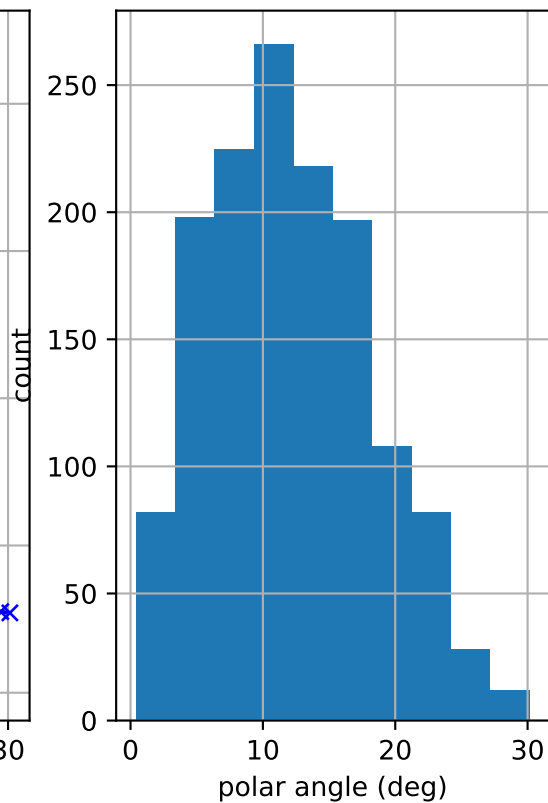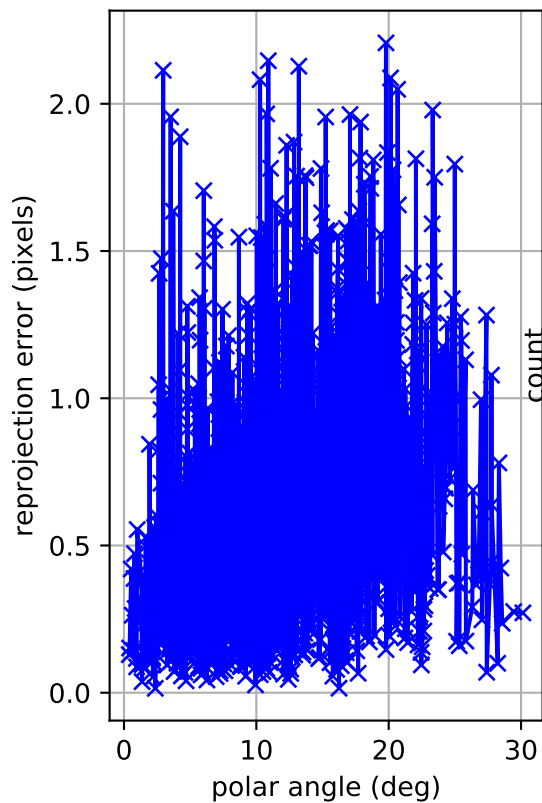====================

Type: aprilgrid
Tags:
Rows: 3
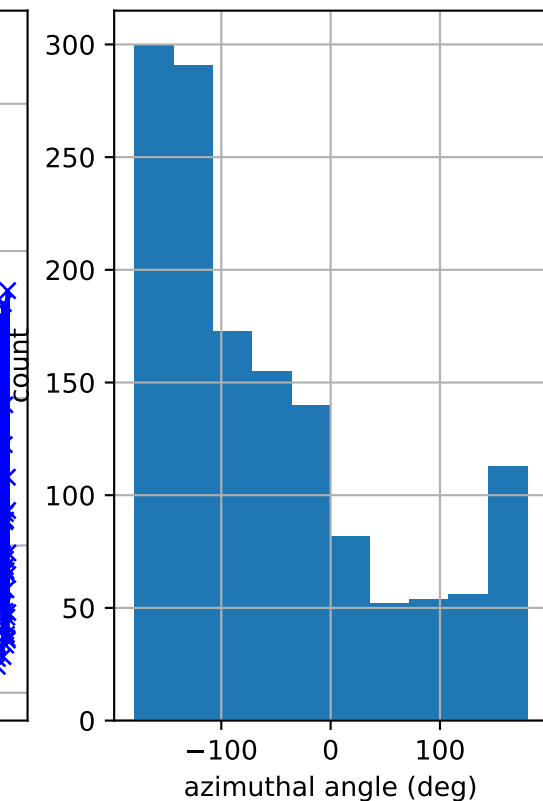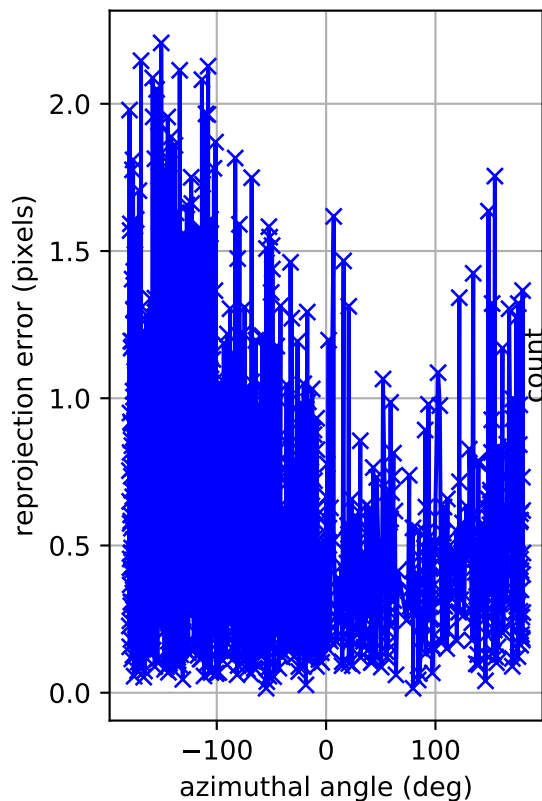Cols: 3
Size: 0.04848 [m]
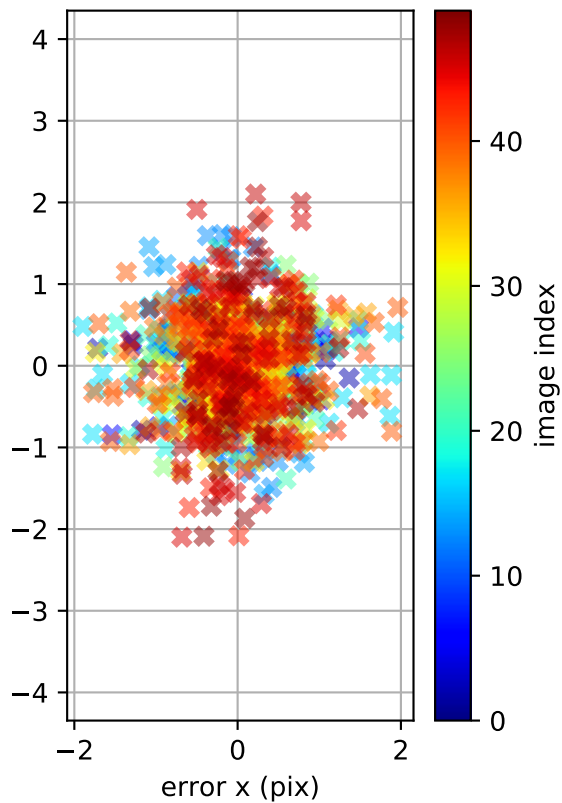Spacing 0.009982032 [m]
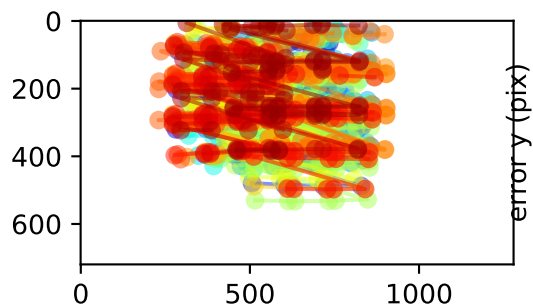
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners