Machine learning Exercise 3

Part 1 - Probability theory part

Q1 - MLE for Poisson.

Given a random sample $\{x1, x2, \dots, xn\}$, derive the maximum likelihood estimator λ of the Poisson distribution.

$$Pig(x,\lambdaig)=rac{e^{-\lambda}\lambda^x}{x!}$$

We will look at $L(\theta) = lnP(D|\theta)$:

$$egin{aligned} L(heta) &= &= lnP(D| heta) = \ &= ln\Big(\Pi_{j=1}^n e^{-\lambda} rac{\lambda^{X_j}}{x_j!}\Big) = \ &= \sum_{j=1}^n lnig(e^{-\lambda} rac{\lambda^{X_j}}{x_j!}ig) = \ &= \sum_{j=1}^n \left(ln(e^{-\lambda}) + ln(\lambda^{x_j}) - ln(X_j!)\right) = \ &= \sum_{j=1}^n \left(-\lambda + x_j ln\lambda - ln(x_j!)\right) = \ &= -n\lambda + ln\lambda \sum_{j=1}^n x_j - \sum_{j=1}^n ln(x_j!) \end{aligned}$$

$$rac{dL(heta)}{d\lambda} = -n + rac{1}{\lambda} \Sigma_{j=1}^n x_j = 0 \quad \Rightarrow \quad \lambda = rac{1}{n} \Sigma_{j=1}^n x_j$$

Q2 - A radar at the beach is used to detect ships.

Ships are located in one of four zones: *A*, *B*, *C* and *D*.

The probability of detection per zone is 0.75, 0.5, 0.3, 0.4 for A, B, C,D respectively.

The probability of being at a specific zone is 0.4, 0.2, 0.3, 0.1 for A, B, C,D, respectively.

a. What is the probability that a ship will be detected?

$$P(detected) = P(detected|A)P(A) + P(detected|B)P(B) + P(detected|C)P(C) + P(detected|D)P(D) = 0.75 \cdot 0.4 + 0.5 \cdot 0.2 + 0.3 \cdot 0.3 + 0.4 \cdot 0.1 = 0.53$$

b. Given that a ship is detected, what is the probability that it was in zone C?

$$P(C|detected) = rac{P(detected|C)P(C)}{P(detected)} = rac{0.3 \cdot 0.3}{0.53} = 0.17$$

c. Given that a ship is detected, what is the probability that it was in zone B?

$$P(B|detected) = rac{P(detected|B)P(B)}{P(detected)} = rac{0.5 \cdot 0.2}{0.53} = 0.189$$

Q3 - Find 3 random variables X, Y, C such that:

- a. $X \perp Y \mid C (X \text{ and } Y \text{ are independent given } C.)$
- b. X and Y are not independent.
- c. X, Y take integer values such that $1 \le X$, $Y \le 10$ and C is binary.
- d. The following conditions hold:

i.
$$P(1 \le X \le 5) = 0.3$$

ii.
$$P(1 \le Y \le 5) = 0.3$$

iii.
$$P(C = 0) = 0.5$$

Let's define C as a uniform binary variable:

$$C \sim Uig(0,1ig)$$

$$P(C=0)=0.5$$

$$P(C=1) = 0.5$$

Let's Define X as follows:

$$X \in \{1, 2, 3...10\}$$

$$P(1 \le X \le 10 \mid C = 0) = 0$$

$$P(1 \le X \le 5 \mid C = 1) = 0.12$$

$$P(6 \le X \le 9 \mid C = 1) = 0.2$$

$$P(X = 10 \mid C = 1) = 0.6$$

Let's Define Y as follows:

$$Y \in \{1, 2, 3...10\}$$

$$P(1 \le Y \le 10 \mid C = 1) = 0$$

$$P(1 \le Y \le 5 \mid C = 0) = 0.12$$

$$P(6 \le Y \le 9 \mid C = 0) = 0.2$$

$$P(Y = 10 \mid C = 0) = 0.6$$

Thus X and Y are dependent(not independent)!

Because, For example, P(X=10) < Pr(X=10|Y=10) .

Keepiing with the conditions:

$$P(1 \le X \le 5) = P(1 \le X \le 5 \mid C = 0) \cdot P(C = 0) + P(1 \le X \le 5 \mid C = 1) \cdot P(C = 1) = 0 \cdot 0.5 + (0.12 \cdot 5) \cdot 0.5 = 0.3$$

$$P(1 \le Y \le 5) = P(1 \le Y \le 5 \mid C = 0) \cdot P(C = 0) + P(1 \le Y \le 5 \mid C = 1) \cdot P(C = 1) = (0.12 \cdot 5) \cdot 0.5 + 0 \cdot 0.5 = 0.3$$

$$P(C=0) = 0.5$$

Done!

Q4 - The probability of having a decent meal in Karnaf is 0.65.

a. What is the probability of having 3 descent meals in a week (5 days)?

$$P(x=3) = {5 \choose 3} 0.65^3 \cdot 0.35^2 = 0.34$$

b. What is the probability of having at least 2 descent meals in a week?

$$egin{align} P(2 \leq x) = \ &= 1 - \left(P(x=0) + P(x=1)
ight) = \ &= 1 - \left(inom{5}{0}0.65^0 \cdot 0.35^5 + inom{5}{1}0.65^1 \cdot 0.35^4
ight) = \ &= 1 - \left(0.0053 + 0.049
ight) = 0.946 \ \end{array}$$

c. A class of 300 students recorded the number of descent meals they had during a specific week.

They averaged their results. What do you expect the value of that average to be?

let's note X as total number of decent meals.

$$X \sim Bin(5, 0.65)$$

Average of Number of descemt meals =
$$\frac{Student_1 + student_2 + ... + Student_{300}}{300} =$$

And as we make our sample size larger it should be close to the mean for a single sample which is

$$\Rightarrow E(X) = n \cdot p = 5 \cdot 0.65 = 3.25$$

Q5 - Bivariate Normal Distribution

you are given a dataset of 1,000 (x1, x2) points drawn from a Bivariate Normal distribution with unknown parameters (data/bivariate_normal_data.csv).

```
In [1]: import numpy as np
   import pandas as pd
   import matplotlib.pyplot as plt
   from mpl_toolkits.mplot3d import Axes3D
   from scipy.stats import multivariate_normal
```

a. Estimate the distribution parameters using the following (these are the MLE parameters):

 $\rho = 0.6619576045042657$

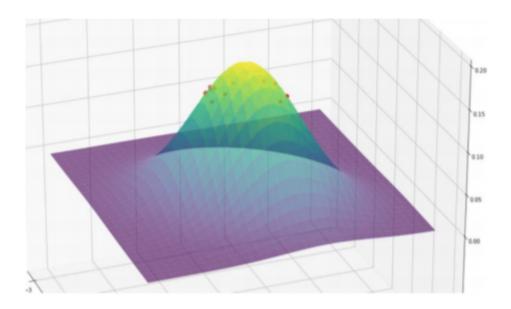
$$\mu_i = rac{1}{N}\sum_{k=1}^N x_i^{(k)}$$

$$\sigma_i = rac{1}{N} \sum_{k=1}^N \left(x_i^{(k)} - \mu
ight)^2$$

$$ho = rac{1}{N} \sum_{k=1}^{N} ig(x_1^{(k)} - \mu_1 ig) \cdot ig(x_2^{(k)} - \mu_2 ig)$$

b. Using the parameters you found:

- plot the distribution in 3d
- mark on the plot the points from the dataset we provided you that correspond to some narrow equiprobable range.
- For example, given the range $P(0.14 \le X \le 0.15)$:



```
In [3]: # Sort values
         x = df.x1.sort values()
         y = df.x2.sort_values()
         # Surface - Create grid and multivariate normal
         X, Y = np.meshgrid(np.linspace(x.min(),x.max(),500),np.linspace(y.min(),y.max(),500))
         pos = np.emptv(X.shape + (2,))
         pos[:, :, 0] = X
         pos[:, :, 1] = Y
         Z = multivariate normal(\mu.values, np.square(\sigma.values)).pdf(pos)
         # points - Create z values by range
         x \min_{x} \max = 0.14, 0.15
         xy = np.empty(x.shape + (2,))
         xy[:,0] = x
         xy[:,1] = y
         z = multivariate normal(\mu.values, np.square(\sigma.values)).pdf(xy)
         x \text{ range} = (x \text{ min } <= x) \& (x <= x \text{ max})
         #Make a 3D plot
         fig = plt.figure(figsize=(14,8))
         ax = fig.gca(projection='3d')
         ax.plot surface(X, Y, Z,cmap='viridis',linewidth=0)
         ax.plot(x[x range], y[x range], z[x range], marker='.', linestyle='None', label='Label', color='red', zorder=10,alpha=
         0.2)
         ax.set xlabel('X axis')
         ax.set ylabel('Y axis')
         ax.set zlabel('Z axis')
         # ax.view init(elev=30,azim=200) # change view of the 3D plot
         plt.show()
```

