Chapter 6

Eigenvalues and Eigenvectors

Application 6.2

Diagonalization of Matrices

Below we illustrate *Maple*, *Mathematica*, and MATLAB functions that enable us to find immediately the eigenvalues and corresponding eigenvectors

$$\lambda_1 = 14,$$
 $\mathbf{v}_1 = (2,0,3)$
 $\lambda_2 = 31,$ $\mathbf{v}_2 = (1,-1,4)$ (1)
 $\lambda_3 = 48,$ $\mathbf{v}_3 = (6,2,3)$

of the matrix

$$\mathbf{A} = \begin{bmatrix} 371 & -612 & -238 \\ 51 & -54 & -34 \\ 357 & -663 & -224 \end{bmatrix}. \tag{2}$$

We can then verify directly that the eigenvector matrix

$$\mathbf{P} = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \mathbf{v}_3 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 6 \\ 0 & -1 & 2 \\ 3 & 4 & 3 \end{bmatrix}$$
 (3)

provides the diagonalization

$$\mathbf{P}^{-1}\mathbf{A}\mathbf{P} = \begin{bmatrix} 2 & 1 & 6 \\ 0 & -1 & 2 \\ 3 & 4 & 3 \end{bmatrix}^{-1} \begin{bmatrix} 371 & -612 & -238 \\ 51 & -54 & -34 \\ 357 & -663 & -224 \end{bmatrix} \begin{bmatrix} 2 & 1 & 6 \\ 0 & -1 & 2 \\ 3 & 4 & 3 \end{bmatrix} = \begin{bmatrix} 14 & 0 & 0 \\ 0 & 31 & 0 \\ 0 & 0 & 48 \end{bmatrix},$$

which shows explicitly that A is similar to its diagonal eigenvalue matrix

$$\mathbf{D} = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}.$$

Textbook examples of eigenvalues and eigenvectors typically involve only matrices with carefully selected small-integer entries that are amenable to manual computation. The following problems may take greater advantage of automatic computation facilities. In each problem, first find the eigenvalues and eigenvectors of A, and then verify as above that $P^{-1}AP = D$.

$$\mathbf{1.} \qquad \mathbf{A} = \begin{bmatrix} 255 & -310 \\ 200 & -243 \end{bmatrix}$$

1.
$$\mathbf{A} = \begin{bmatrix} 255 & -310 \\ 200 & -243 \end{bmatrix}$$
 2. $\mathbf{A} = \begin{bmatrix} 447 & -391 \\ 450 & -392 \end{bmatrix}$

3.
$$\mathbf{A} = \begin{bmatrix} 2899 & -2664 \\ 3120 & -2867 \end{bmatrix}$$

$$\mathbf{4.} \qquad \mathbf{A} = \begin{bmatrix} 40255 & -41000 \\ 39396 & -40125 \end{bmatrix}$$

5.
$$\mathbf{A} = \begin{bmatrix} 252 & -476 & -1309 \\ 154 & -294 & -847 \\ -14 & 28 & 91 \end{bmatrix}$$

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$$\mathbf{A} = \begin{bmatrix} 252 & -476 & -1309 \\ 154 & -294 & -847 \\ -14 & 28 & 91 \end{bmatrix}$$
 6. $\mathbf{A} = \begin{bmatrix} 33769 & -28203 & 2638 \\ 27141 & -21487 & 2442 \\ -107466 & 103122 & -4522 \end{bmatrix}$

7.
$$\mathbf{A} = \begin{bmatrix} 101 & 174 & 94 & -76 \\ -139 & -158 & -43 & 145 \\ 271 & 345 & 98 & -277 \\ -27 & 27 & 51 & 58 \end{bmatrix}$$

8.
$$\mathbf{A} = \begin{bmatrix} 387 & -300 & 260 & -588 & 200 \\ 82 & 9 & 44 & -194 & 68 \\ -140 & 120 & -67 & 250 & -80 \\ 840 & -720 & 624 & -1389 & 480 \\ 2188 & -1812 & 1600 & -3812 & 1319 \end{bmatrix}$$

Using *Maple*

First we enter our matrix A:

Then the eigenvalues of **A** are given by

and the complete eigensystem by

eigs := [eigenvectors(A)];

$$eigs := \left[\left[48, 1, \left\{ \left[3, 1, \frac{3}{2} \right] \right\}, \right] \left[14, 1, \left\{ \left[1, 0, \frac{3}{2} \right] \right\}, \right] \left[31, 1, \left\{ \left[-1, 1, -4 \right] \right\} \right] \right]$$

We see here the three eigenvalues, each of multiplicity 1, with their corresponding eigenvectors (after multiplication by convenient factors to clear fractions)

Hence the eigenvector matrix $P = [v_1 \ v_2 \ v_3]$ is defined by

P := transpose(array([[6, 2, 3], [2, 0, 3], [1, -1, 4]]));
$$P := \begin{bmatrix} 6 & 2 & 1 \\ 2 & 0 & -1 \\ 3 & 3 & 4 \end{bmatrix}$$

and the desired diagonalization of A is given by

D := multiply(inverse(P),A,P);
$$D := \begin{bmatrix} 48 & 0 & 0 \\ 0 & 14 & 0 \\ 0 & 0 & 31 \end{bmatrix}$$

Using Mathematica

First we enter our matrix A:

$$A = \{ \{371, -612, -238\}, \\ \{51, -54, -34\}, \\ \{357, -663, -224\} \};$$

Then the eigenvalues of **A** are given by

Eigenvalues[A]

and the complete eigensystem by

$$\begin{pmatrix} 14 & 31 & 48 \\ \{2,0,3\} & \{1,-1,4\} & \{6,2,3 \end{pmatrix}$$

We see here the three eigenvalues with their corresponding eigenvectors

Hence the eigenvector matrix $P = [v_1 \ v_2 \ v_3]$ is defined by

$$P = Transpose[\{v1, v2, v3\}]$$

$$\begin{pmatrix}
2 & 1 & 6 \\
0 & -1 & 2 \\
3 & 4 & 3
\end{pmatrix}$$

and the desired diagonalization of A is given by

$$\begin{pmatrix}
14 & 0 & 0 \\
0 & 31 & 0 \\
0 & 0 & 48
\end{pmatrix}$$

Using MATLAB

First we enter our matrix **A**:

$$A = \begin{bmatrix} 371 & -612 & -238 \\ 51 & -54 & -34 \\ 357 & -663 & -224 \end{bmatrix};$$

Then the eigenvalues of **A** are given by

```
eig(A)
ans =
    14.0000
    48.0000
    31.0000
```

and the complete eigensystem by

Here we see both the eigenvector matrix $\mathbf{P} = [\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3]$ and the diagonal eigenvalue matrix \mathbf{D} . The matrix \mathbf{P} looks a bit unpleasant because MATLAB returns *unit* eigenvectors, but we can clean up its appearance by dividing the column eigenvectors by apparent common factors:

```
P(:,1) = P(:,1)/(P(1,1)/2);

P(:,2) = P(:,2)/(P(2,2)/2);

P(:,3) = P(:,3)/P(1,3)

P =

2.0000 6.0000 1.0000

-0.0000 2.0000 -1.0000

3.0000 3.0000 4.0000
```

Finally the desired diagonalization of **A** is given by