Parametric Equations

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Abstract

Matlab is used to draw the graphs of parametric equations. $\mbox{\bf Prerequisites.} \ \ \mbox{None}$

1 Vectors in Matlab

You enter a row vector in Matlab as follows:¹

$$>> x=[1,2,3,4,5]$$

x =

1 2 3 4 5

The commas are optional.

$$>> x=[1 2 3 4 5];$$

Note that terminating a command with a semicolon suppresses output to the display. Use semicolons to separate rows and create a *column* vector.

x =

1

2

3

4

Matlab's transpose operator ² is the single apostrophe (').

¹The >> symbol is Matlab's prompt. You must enter the command that appears after the prompt. You must hit the Enter key on your keyboard to execute the command.

²The transpose of a row vector is a column vector, and vice-versa.

```
>> x=x=[1,2,3,4,5]'
x =

    1
    2
    3
    4
    5
>> x'
ans =
    1    2    3    4    5
```

1.1 Incremental Notation

The Matlab construct start:increment:finish is particularly useful for entering regularly spaced data.

```
>> x=1:3:13
x =
     1
            4
                  7
                       10
                              13
   You can also use a negative increment.
>> x=20:-2:10
x =
    20
           18
                              12
                 16
                        14
                                     10
   And you can get quite fancy.
>> x=0:pi/2:2*pi
               1.5708
                          3.1416
                                     4.7124
                                               6.2832
```

1.2 Vector Arithmetic

Vector addition and subtraction of equal length vectors occurs in a natural way.

x = y = >> x+y ans = >> x-y ans = -5 -5 -5 -5 You can multiply a vector by a scalar. >> x=(1:5), x = >> y=2*x

1.3 Element-wise Operations

Matlab is a matrix based environment. Therefore, you cannot multiply two vectors of equal size.

>> x=1:5,y=6:10 x = 1 2 3 4

y = 6 7 8 9 10

>> x*y
??? Error using ==> *
Inner matrix dimensions must agree.

You can, however, multiply vectors of equal length on an element-wise basis.

5

>> z=x.*y z = 6 14 24 36 50

Make sure that you note that each element in ${\bf z}$ is the product of the corresponding entries in ${\bf x}$ and ${\bf y}$. In a similar manner, you can raise each element of ${\bf x}$ to the second power.

z = 1 4 9 16 25

In a similar manner, you can divide each element of ${\tt x}$ by the corresponding element of ${\tt y}$.

>> z=x./y z = 0.1667 0.2857 0.3750 0.4444 0.5000

Many of Matlab's built-in functions perform on a vector in an element-wise manner.

>> x=0:pi/2:2*pi

x =

>> z=x.^2

2 Plotting Parametric Equations

Here is a set of parametric equations, the parameter being t.

$$x = \cos t \tag{(1a)}$$

$$y = \sin t \tag{(1b)}$$

If you were plotting these equations by hand, you would begin by making a table of values. First, select some arbitrary t-values.

t	\boldsymbol{x}	y
0		
$\pi/2$		
π		
$3\pi/2$		
2π		

Substitute each t-value in the table into equations (1a) and (1b).

t	\boldsymbol{x}	y
0	1	0
$\pi/2$	0	1
π	-1	0
$3\pi/2$	0	-1
2π	1	0

There are now a number of different plots that you can make. You can plot x versus t, y versus t, or y versus x. And, of course, to obtain a smooth plot, we'll need to plot more than the 5 points we have in our table. Matlab makes this task effortless. The following code should produce an image similar to that in Figure 1.

>> t=0:.1:2*pi; >> x=cos(t); >> y=sin(t); >> plot(x,y)

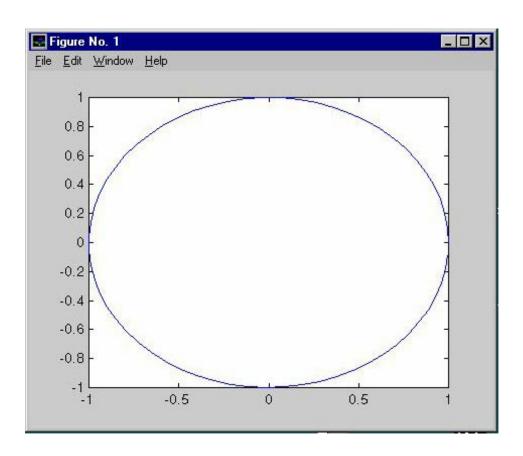


Figure 1:

2.1 Lissajous Curves

Let's plot the graph of the following set of parametric equations.

$$x = 2\cos 3t \tag{(2a)}$$

$$y = 3\sin 5t \tag{(2b)}$$

The following sequence of commands should give a plot similar to that in Figure $2.^3$

```
>> t=linspace(0,2*pi,500);
>> x=2*cos(3*t);
>> y=3*sin(5*t);
>> plot(x,y)
>> xlabel('x-axis')
>> ylabel('y-axis')
>> title('x=2*cos(3*t), y=3*sin(5*t)')
```

2.2 Comets

For a bit of fun with this "Lissajous Curve," enter the following command at the Matlab prompt.

```
>> close all, comet(x,y)
```

Think of the parametric equations (2a) and (2b) as describing the position (x, y) of a particle at time t. Matlab's **comet** command gives you an excellent feel for the motion of the particle with respect to time.

2.3 A Parabola

Plot the image of the following set of parametric equations over the time interval [-2, 2].

$$x = 2t + 2 \tag{(3a)}$$

$$y = t^2 - 1 \tag{(3b)}$$

The first two steps are straightforward.

```
>> t=-2:.01:2;
>> x=2*t+3;
```

The following produces an error.

³linspace(0,2*pi,500) produces 500 equally spaced points starting with 0 and ending with 500. Type help linspace at the Matlab prompt to learn more about the linspace command.

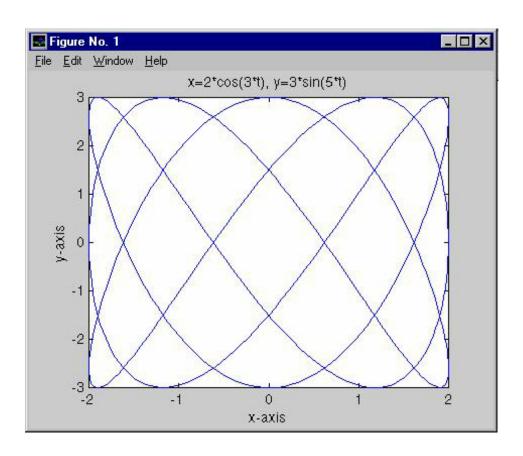


Figure 2:

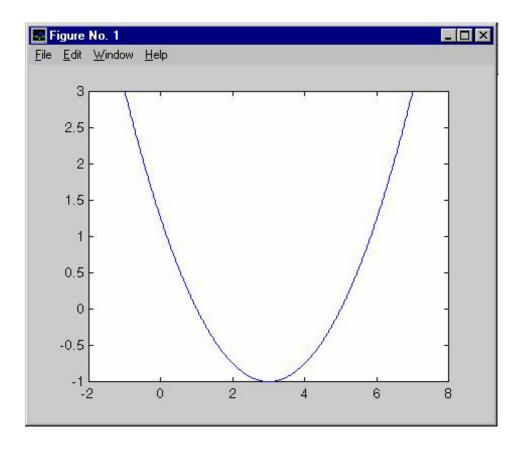


Figure 3:

>> y=t^2-1
??? Error using ==> ^
Matrix must be square.

This error is expected, particularly in light of the discussion in the section "Element-wise Operations." What you actually want to do is square each element of t, then subtract 1.

>> y=t.^2-1;

The following command should now produce an image similar to that in Figure 3.

>> plot(x,y)

Be sure to also try the comet command on this data.

2.4 An Astroid

The curve defined by the following set of parametric equations is called an "astroid."

$$x = \cos^3 t \tag{(4a)}$$

$$y = \sin^3 t \tag{(4b)}$$

When you cube, you want to cube $each\ element$, so use the .^ notation for this purpose. The following sequence of commands should produce an image similar to that in Figure 4.⁴

- >> t=linspace(0,2*pi,500);
- >> x=(cos(t)).^3;
- >> y=(sin(t)).^3;
- >> plot(x,y)
- >> axis square

Be sure to try the comet command on this data.

2.5 Homework

Use Matlab to plot each of the following sets of parametric equations. Obtain a printout of each plot and hand in next class.

1.
$$x = t - \sin t$$
, $y = 1 - \cos t$, $0 < t < 2\pi$

2.
$$x = 1 + 2t$$
, $y = 4 - t^2$, $0 < t < 1$

3.
$$x = 2\cos t + \cos 2t, y = 2\sin t - \sin 2t, -\pi \le t \le \pi$$

4.
$$x = 4(1 + \sin t), 4\cos t(1 + 2\sin t), -\pi \le t \le \pi$$

 $^{^4}$ The axis square command "squares up" the image. For more help on the axis command, type help axis at the Matlab prompt.

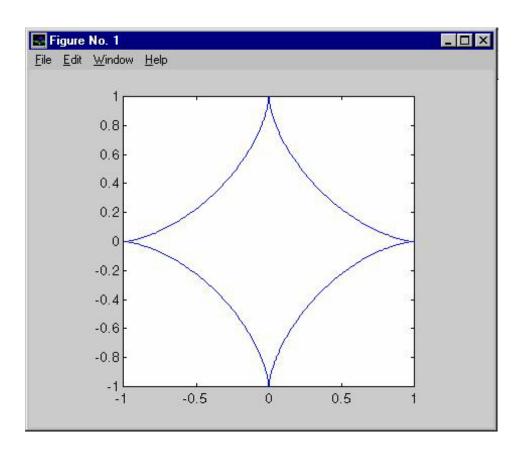


Figure 4: