

A\*NAV:
A\* Navigation for Cyclists with Tired Legs

## What does A\*NAV do?

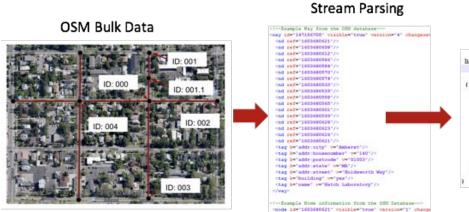
- A\*NAV is a web-based routing application that allows users to customize routes based on their own route preferences
- It provides a quick and efficient service that finds the best route based on these dynamic preferences
- Results are displayed in an intuitive and user-friendly interface on a visually appealing website

## What Factors Does A\*NAV Consider?

- Distance
- Incline
- Road Type
- Bike Lane Availability

## Architecture Open Street Map **PostgreSQL** Route Cloud-hosted optimization database API G ANAV: A\* Navigation for Cyclists with Tired Frontend Google UI Elevation API

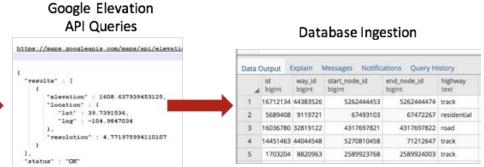
## Data Pipeline



OSM XML

'node 16"1603680600" visible"true" version"1" change
'node 16"1603680612" visible"true" version"1" change

-node id='1600680586' visible='true' version='1' change
-node id='1600680584' visible='true' version='1' change



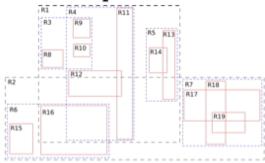
Data Cleaning and Transformation

## **Speed Optimization**

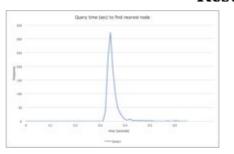
### How do we quickly get data from PostgreSQL?

# How do we limit the size of our graph? Solution Limit the graph to a search radius depending on the user's start and end coordinates

### R-Tree Spatial Indexes



### Results





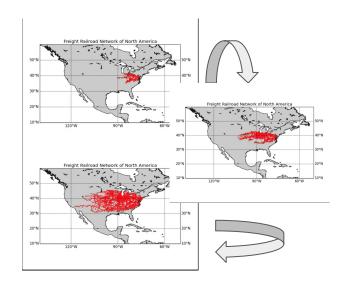
0.3 seconds to find nearest node Find nearby nodes in ~seconds

## Algorithm

## A\* Algorithm = Dijkstra + Heuristic Function

With heuristic function, A\* can prioritize the search on edges that are more "likely" to be on the shortest path

We use 2D distance for our heuristic function.



### **Take User Preference Into Account?**

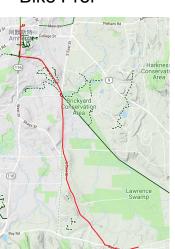
Add cost function to the edge based on preference!

incl = incline\_multiplier(float(incline))\*flatness\_pref
cost = float(distance) \* multiplier + incl

### No Pref



#### Bike Pref



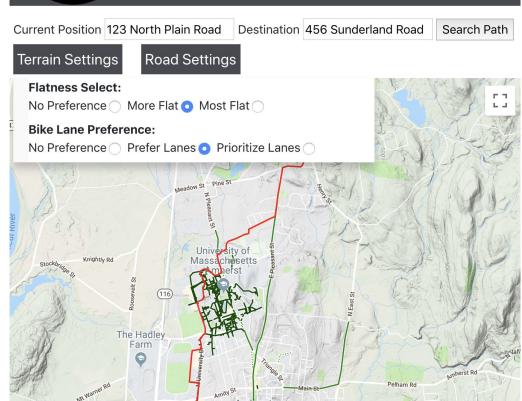
### Highway Pref



## Frontend

- Familiar, Contextual Ul
- Clean Readability
- Embedded Google Map
- Form validation
- Helpful error messages





## API

#### **HTML Page**



Python (Flask)



### **Display Route**



### Call Route Optimizer





Input Parameters Validation