Support Vector Machines

Máster Universitario en Ciencia de Datos - Métodos Avanzados en Aprendizaje Automático

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Support Vector Classifiers



Multiple Hyperplanes



- Support Vector Machines emerge in the framework of linearly separable classification problems.
- There are multiple hyperplanes that separate the data perfectly.
 - Some of them will **generalize better** than others.
 - Which one is the best?
- In the case of **logistic regression**, a probabilistic approach selects the best hyperplane.
- There are other geometrical interpretations that can be used.



Notebook

SVC: Multiple Hyperplanes





Maximum Margin Hyperplane (I)



• The geometrical intuition can be formalized with the concept of margin.

Definition (Margin)

The **margin** on a linearly separable 2-class classification problem is defined as the distance between the hyperplane and the nearest data point:

$$m = \min_{1 \le i \le N} \left\{ \frac{|\mathbf{w}^{\mathsf{T}} \mathbf{x}_i + b|}{\|\mathbf{w}\|_2} \right\}.$$

• Since the problem is linearly separated and assuming $y_i \in \{-1, 1\}$, the margin can also be written as:

$$m = \min_{1 \le i \le N} \left\{ \frac{y_i(\mathbf{w}^{\mathsf{T}} \mathbf{x}_i + b)}{\|\mathbf{w}\|_2} \right\}.$$

• The idea is to find the hyperplane that maximizes m.



Maximum Margin Hyperplane (II)



- The hyperplane defined by (\mathbf{w}, b) is the same as the one defined by $(c\mathbf{w}, cb)$.
- Some kind of normalization should be applied.
- Two different approaches:
 - **1** Fix the norm of **w**.
 - 2 Enforce that the closest points belong to the supporting hyperplanes $\mathbf{w}^{\intercal}\mathbf{x} + b = \pm 1$.
- With the second normalization:

$$y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1,$$

 $m = \frac{1}{\|\mathbf{w}\|_2}.$



Hard-Margin Support Vector Classifier



• The Hard-Margin Support Vector Classifier is defined as the solution of the problem:

$$\max_{\mathbf{w} \in \mathbb{R}^{d}} \left\{ \frac{1}{\|\mathbf{w}\|_{2}} \right\} \\
s.t. \begin{cases}
y_{i}(\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i} + b) \geq 1, \\
1 \leq i \leq N,
\end{cases} \equiv \min_{\substack{\mathbf{w} \in \mathbb{R}^{d} \\ b \in \mathbb{R}}} \left\{ \frac{1}{2} \|\mathbf{w}\|_{2}^{2} \right\} \\
s.t. \begin{cases}
y_{i}(\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i} + b) \geq 1, \\
1 \leq i \leq N.
\end{cases}$$

- This optimization problem is defined for binary classification problems.
- The problem has to be **linearly separable** (otherwise, it is not feasible).
- Since the margin of the model is maximized, a good generalization can be expected.



Hard-Margin Support Vector Classifier - Exercise



Exercise

Given the 2-dimensional linear classification model $\{b = 0, w_1 = 1, w_2 = 0\}$, and this dataset:

$x_{i,1}$	$x_{i,2}$	y_i
-1	-1	-1
-2	1	-1
1	0	1

- Is the model separating both classes?
- ② Compute the distances between each point and the hyperplane, using $\|\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b\|/\|\mathbf{w}\|_2$.
- Compute the margin of this model.

Solution

- Yes, since the predictions are:
 - $\mathbf{w}^{\mathsf{T}}\mathbf{x}_{1} = -1 < 0$.
 - $\mathbf{w}^{\mathsf{T}}\mathbf{x}_{2} = -2 \leq 0$
 - $\mathbf{w}^{\mathsf{T}}\mathbf{x}_3 = 1 \geq 0$.
- ② Since $\|\mathbf{w}\|_2 = 1$, the distances are the absolute value of the predictions above:
 - $d_1 = 1$.
 - $d_2 = 2$.
 - $d_3 = 1$.
- The margin is the minimum of the distances, m = 1.



Notebook

Hard-Margin SVC





Hard-Margin Support Vector Classifier - Optimization (I)



$$\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R}}} \left\{ \frac{1}{2} \|\mathbf{w}\|_2^2 \right\} \text{ s.t. } y_i(\mathbf{w}^\mathsf{T} \mathbf{x}_i + b) \ge 1, 1 \le i \le N.$$

- The objective function is **convex** and **differentiable**.
- The problem has linear constraints.
- It can be solved using Lagrangian duality.



Hard-Margin Support Vector Classifier - Optimization (II)



The Lagrangian becomes:

$$\mathcal{L}(\mathbf{w}, b; \boldsymbol{\alpha}) = \frac{1}{2} \|\mathbf{w}\|_2^2 + \sum_{i=1}^N \alpha_i (1 - y_i(\mathbf{w}^\mathsf{T} \mathbf{x}_i + b)).$$

The saddle-point problem is:

$$\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R}}} \left\{ \max_{\substack{\boldsymbol{\alpha} \in \mathbb{R}^N \\ \boldsymbol{\alpha} \geq \mathbf{0}}} \left\{ \mathcal{L}(\mathbf{w}, b; \boldsymbol{\alpha}) \right\} \right\} \equiv \max_{\substack{\boldsymbol{\alpha} \in \mathbb{R}^N \\ \boldsymbol{\alpha} \geq \mathbf{0}}} \left\{ \min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R}}} \left\{ \mathcal{L}(\mathbf{w}, b; \boldsymbol{\alpha}) \right\} \right\}.$$



Hard-Margin Support Vector Classifier - Optimization (III)



• Solving the inner problem (taking derivatives with respect to **w** and *b*) leads to:

$$\frac{\partial}{\partial b}\mathcal{L}(\mathbf{w},b;\boldsymbol{lpha}) = -\sum_{i=1}^{N} \alpha_{i}y_{i} = 0 \implies \sum_{i=1}^{N} \alpha_{i}y_{i} = 0;$$

$$\nabla_{\mathbf{w}} \mathcal{L}(\mathbf{w}, \mathbf{e}; \boldsymbol{\alpha}) = \mathbf{w} - \sum_{i=1}^{N} \alpha_i y_i \mathbf{x}_i = 0 \implies \mathbf{w} = \sum_{i=1}^{N} \alpha_i y_i \mathbf{x}_i.$$

• Substituting back leads to the dual function:

$$\mathcal{D}(\boldsymbol{\alpha}) = \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i \alpha_j y_i y_j \mathbf{x}_i^{\mathsf{T}} \mathbf{x}_j + \sum_{i=1}^{N} \alpha_i - \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i \alpha_j y_i y_j \mathbf{x}_i^{\mathsf{T}} \mathbf{x}_j - b \underbrace{\sum_{i=1}^{N} \alpha_i y_i}_{0}$$

$$= -\frac{1}{2} \boldsymbol{\alpha}^{\mathsf{T}} \tilde{\mathbf{X}} \tilde{\mathbf{X}}^{\mathsf{T}} \boldsymbol{\alpha} + \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{1},$$

where $\tilde{\mathbf{X}}$ is the labelled data matrix, in which the *i*-th row corresponds to $y_i \mathbf{x}_i^\mathsf{T}$.

Hard-Margin Support Vector Classifier - Optimization (IV)



• The resultant **dual problem** is hence:

$$\max_{\boldsymbol{\alpha} \in \mathbb{R}^{N}} \left\{ -\frac{1}{2} \boldsymbol{\alpha}^{\mathsf{T}} \tilde{\mathbf{X}} \tilde{\mathbf{X}}^{\mathsf{T}} \boldsymbol{\alpha} + \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{1} \right\} \equiv \min_{\boldsymbol{\alpha} \in \mathbb{R}^{N}} \left\{ \frac{1}{2} \boldsymbol{\alpha}^{\mathsf{T}} \tilde{\mathbf{X}} \tilde{\mathbf{X}}^{\mathsf{T}} \boldsymbol{\alpha} - \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{1} \right\} \\
\text{s.t.} \left\{ \begin{array}{l} \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{y} = 0, \\ \boldsymbol{\alpha} \ge \mathbf{0}, \end{array} \right. \\
\text{s.t.} \left\{ \begin{array}{l} \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{y} = 0, \\ \boldsymbol{\alpha} \ge \mathbf{0}. \end{array} \right.$$

- It is a constrained quadratic problem.
- There are different ad hoc algorithms for solving it.
- The data only appear in form of **inner products**.
- As a consequence of the Lagrangian duality, $\alpha_i(1 y_i(\mathbf{w}^\mathsf{T}\mathbf{x}_i + b)) = 0$, for $i = 1, \dots, N$.
 - If $\alpha_i > 0$, $y_i(\mathbf{w}^\mathsf{T} \mathbf{x}_i + b) = 1$ and this point over the supporting hyperplane is called a **support** vector.
 - If $\alpha_i = 0$, $y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1$ and the point has no impact on the model.
 - The model is **sparse** in terms of the training samples.

Notebook

Hard-Margin SVC: Optimization





Soft-Margin Support Vector Classifiers: Introduction



- Most of the problems are not linearly separable.
- Even if they are (e.g. because d large), maybe it is not convenient to perfectly classify the training data.
 - This can lead to **over-fitting**.
- Soft-margin Support Vector Classifiers allow for training errors introducing slack variables.
- These variables quantify the margin violation of each pattern.
- The constraints are modified to $y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \geq 1 \xi_i$, with $\xi_i \geq 0$ the distance to the corresponding supporting hyperplane.
- The slack variables are penalized to be as small as possible.



Soft-Margin Support Vector Classifier (I)



• The Soft-Margin Support Vector Classifier is defined as the solution of the problem:

$$\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R} \\ \boldsymbol{\xi} \in \mathbb{R}^N}} \left\{ \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^N \xi_i \right\} \\
\mathbf{s.t.} \begin{cases} y_i(\mathbf{w}^{\mathsf{T}} \mathbf{x}_i + b) \ge 1 - \xi_i, \\ \xi_i \ge 0, \\ 1 \le i \le N. \end{cases}$$

- This problem is defined for binary classification problems.
- The problem does **not** need to be **linearly separable**.
- The hyper-parameter *C* controls the balance between accuracy and complexity.



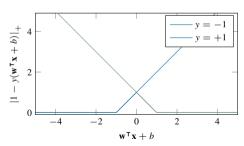
Soft-Margin Support Vector Classifier (II)



• Equivalently, the problem can be written without constraints as follows:

$$\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R}}} \left\{ \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{N} |1 - y_{i}(\mathbf{w}^{\mathsf{T}}\mathbf{x}_{i} + b)|_{+} \right\},\,$$

where $|x|_{+}$ denotes the positive part. The resultant measure is known as the **hinge loss function**.





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Soft-Margin Support Vector Classifier - Exercise



Exercise

Given the 2-dimensional linear classification model $\{b = 0, w_1 = 0.25, w_2 = -0.5\}$, and this dataset:

$x_{i,1}$	$x_{i,2}$	y_i
-1	-1	-1
-2	1	-1
1	0	1

- Is the model separating both classes?
- ② Compute the hinge loss error for each pattern, using $|1 y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b)|_{\perp}$.
- **3** Is the error 0 for any pattern? Is it 0 for all the correctly classified patterns?

Solution

- No, the first sample is wrongly classified. The predictions are:
 - $\mathbf{w}^{\mathsf{T}}\mathbf{x}_1 = 0.25 \leq 0.$
 - $\mathbf{w}^{\mathsf{T}}\mathbf{x}_{2} = -1 \leq 0.$
 - $\mathbf{w}^{\mathsf{T}}\mathbf{x}_3 = 0.25 \geq 0.$
- ② The corresponding errors are:
 - $e_1 = |1 0.25y_1|_+ = 1.25$.
 - $e_2 = |1 + y_2|_{\perp} = 0$.
 - $e_3 = |1 0.25y_3|_+ = 0.75$.
- § For \mathbf{x}_1 , wrongly classified, it is larger than 1. For \mathbf{x}_2 is 0 since it is respecting the margin. For \mathbf{x}_3 , not respecting the margin but correctly classified, it is between 0 and 1.

Notebook

Soft-Margin SVC





Soft-Margin Support Vector Classifier - Optimization (I)



$$\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R} \\ \boldsymbol{\xi} \in \mathbb{R}^N}} \left\{ \frac{1}{2} \|\mathbf{w}\|_2^2 \right\} \text{ s.t. } y_i(\mathbf{w}^\mathsf{T} \mathbf{x}_i + b) \ge 1 - \xi_i, \xi_i \ge 0, 1 \le i \le N.$$

- The objective function is **convex** and **differentiable**.
- The problem has linear constraints.
- It can be solved using **Lagrangian duality**.



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Soft-Margin Support Vector Classifier - Optimization (II)



• The Lagrangian becomes:

$$\mathcal{L}(\mathbf{w}, b, \boldsymbol{\xi}; \boldsymbol{\alpha}, \boldsymbol{\beta}) = \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{N} \xi_{i} + \sum_{i=1}^{N} \alpha_{i} (1 - \xi_{i} - y_{i} (\mathbf{w}^{\mathsf{T}} \mathbf{x}_{i} + b)) + \sum_{i=1}^{N} \beta_{i} (-\xi_{i}).$$

• The saddle-point problem is:

$$\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R} \\ \boldsymbol{\xi} \in \mathbb{R}^N}} \left\{ \max_{\substack{\boldsymbol{\alpha}, \boldsymbol{\beta} \in \mathbb{R}^N \\ \boldsymbol{\alpha}, \boldsymbol{\beta} \geq \boldsymbol{0}}} \left\{ \mathcal{L}(\mathbf{w}, b, \boldsymbol{\xi}; \boldsymbol{\alpha}, \boldsymbol{\beta}) \right\} \right\} \equiv \max_{\substack{\boldsymbol{\alpha}, \boldsymbol{\beta} \in \mathbb{R}^N \\ \boldsymbol{\alpha}, \boldsymbol{\beta} \geq \boldsymbol{0}}} \left\{ \min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R} \\ \boldsymbol{\xi} \in \mathbb{R}^N}} \left\{ \mathcal{L}(\mathbf{w}, b, \boldsymbol{\xi}; \boldsymbol{\alpha}, \boldsymbol{\beta}) \right\} \right\}.$$



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Soft-Margin Support Vector Classifier - Optimization (III)



• Solving the inner problem (taking derivatives with respect to w and b) leads to:

$$\frac{\partial}{\partial b} \mathcal{L}(\mathbf{w}, b, \boldsymbol{\xi}; \boldsymbol{\alpha}, \boldsymbol{\beta}) = -\sum_{i=1}^{N} \alpha_{i} y_{i} = 0 \implies \sum_{i=1}^{N} \alpha_{i} y_{i} = 0;$$

$$\nabla_{\mathbf{w}} \mathcal{L}(\mathbf{w}, b, \boldsymbol{\xi}; \boldsymbol{\alpha}, \boldsymbol{\beta}) = \mathbf{w} - \sum_{i=1}^{N} \alpha_{i} y_{i} \mathbf{x}_{i} = 0 \implies \mathbf{w} = \sum_{i=1}^{N} \alpha_{i} y_{i} \mathbf{x}_{i};$$

$$\frac{\partial}{\partial \xi_{i}} \mathcal{L}(\mathbf{w}, b, \boldsymbol{\xi}; \boldsymbol{\alpha}, \boldsymbol{\beta}) = C - \alpha_{i} - \beta_{i} = 0 \implies 0 \leq \alpha_{i} \leq C.$$



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Soft-Margin Support Vector Classifier - Optimization (IV)



• Substituting back leads to the dual function:

$$\mathcal{D}(\boldsymbol{\alpha}) = \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} \mathbf{x}_{i}^{\mathsf{T}} \mathbf{x}_{j} + C \sum_{i=1}^{N} \xi_{i} + \sum_{i=1}^{N} \alpha_{i} - \sum_{i=1}^{N} \alpha_{i} \xi_{i}$$

$$- \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} \mathbf{x}_{i}^{\mathsf{T}} \mathbf{x}_{j} - \sum_{i=1}^{N} \alpha_{i} y_{i} b - \sum_{i=1}^{N} \beta_{i} \xi_{i}$$

$$= -\frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} \alpha_{j} y_{i} y_{j} \mathbf{x}_{i}^{\mathsf{T}} \mathbf{x}_{j} + \sum_{i=1}^{N} \xi_{i} \underbrace{(C - \alpha_{i} - \beta_{i})}_{0} + \sum_{i=1}^{N} \alpha_{i} - b \underbrace{\sum_{i=1}^{N} \alpha_{i} y_{i}}_{0}$$

$$= -\frac{1}{2} \boldsymbol{\alpha}^{\mathsf{T}} \tilde{\mathbf{X}} \tilde{\mathbf{X}}^{\mathsf{T}} \boldsymbol{\alpha} + \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{1}.$$



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Soft-Margin Support Vector Classifier - Optimization (V)



• The resultant dual problem is:

$$\min_{\boldsymbol{\alpha} \in \mathbb{R}^{N}} \left\{ \frac{1}{2} \boldsymbol{\alpha}^{\mathsf{T}} \tilde{\mathbf{X}} \tilde{\mathbf{X}}^{\mathsf{T}} \boldsymbol{\alpha} - \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{1} \right\}$$
s.t.
$$\begin{cases} \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{y} = 0, \\ \mathbf{0} \le \boldsymbol{\alpha} \le C. \end{cases}$$

- It is again a constrained quadratic problem.
- The dual coefficients have an additional upper bound *C*.
 - If *C* is larger than a certain value the hard-margin SVC is recovered.
- There are different *ad hoc* algorithms for solving it.
- The data only appear in form of inner products.
- As a consequence of the Lagrangian duality, $\alpha_i(1 \xi_i y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b)) = 0$, for $i = 1, \dots, N$.
 - If $\alpha_i = 0$, $y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1$ and the point has no impact on the model.
 - If $0 < \alpha_i < C$, $y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) = 1$.
 - If $\alpha_i = C$, $y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) = 1 \xi_i \le 1$.
 - The model is **sparse** in terms of the training samples.



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Support Vector Regression



Introduction



- The SVC models have certain desirable properties:
 - They can be trained using a dual problem.
 - They are sparse in terms of the training samples.
 - They control naturally the complexity.
- These properties motivate its extension to a regression setting.
- What is the origin of these good properties?
 - 1 Maximizing the margin (minimizing the complexity of the model).
 - 2 Having a sparse-inducing error term.
- Can this be extended to a regression framework?
 - 1 It is already done in (Kernel) Ridge Regression, but without sparsity.
 - A new loss function is needed.



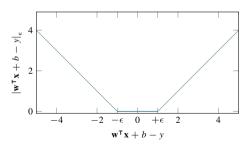
The ϵ -Insensitive Loss



• The ϵ -insensitive loss of a linear model $\{\mathbf{w}, b\}$ over a pattern (\mathbf{x}, y) is defined as:

$$|\mathbf{w}^{\mathsf{T}}\mathbf{x} + b - \mathbf{y}|_{\epsilon} = \max\{0, |\mathbf{w}^{\mathsf{T}}\mathbf{x} + b - \mathbf{y}| - \epsilon\}.$$

- Errors smaller than ϵ are simply ignored.
- Errors larger than ϵ are penalized linearly.
- It avoids over-fitting by ignoring small errors, but the hyper-parameter ϵ has to be tuned.





Support Vector Regression



• The Support Vector Regression is defined as the solution of the problem:

$$\min_{\mathbf{w} \in \mathbb{R}^{d} \atop b \in \mathbb{R}} \left\{ \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{N} |\mathbf{w}^{\mathsf{T}} \mathbf{x}_{i} + b - y_{i}|_{\epsilon} \right\} \equiv \begin{bmatrix} \min_{\substack{\mathbf{w} \in \mathbb{R}^{d} \\ b \in \mathbb{R}} \\ \boldsymbol{\xi}, \boldsymbol{\xi}^{*} \in \mathbb{R}^{N} \end{bmatrix}} \left\{ \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{N} (\xi_{i} + \xi_{i}^{*}) \right\}$$
s.t.
$$\begin{cases} \mathbf{w}^{\mathsf{T}} \mathbf{x}_{i} + b - y_{i} \leq \epsilon + \xi_{i}, \\ y_{i} - \mathbf{w}^{\mathsf{T}} \mathbf{x}_{i} - b \leq \epsilon + \xi_{i}^{*}, \\ \xi_{i}, \xi_{i}^{*} \geq 0, \\ 1 \leq i \leq N. \end{cases}$$

• The hyper-parameter C controls the balance between accuracy and complexity.



Support Vector Regression - Exercise



Given the 2-dimensional linear regression model $\{b = 0, w_1 = 1, w_2 = 1\}$, and this dataset:

$x_{i,1}$	$x_{i,2}$	y_i
-1	-1	-1.9
-2	1	-1
1	0	2

- Compute the prediction for each pattern.
- Compute the ϵ -insensitive loss for each pattern, using $\max\{0, |\mathbf{w}^{\mathsf{T}}\mathbf{x} + b - y| - \epsilon\}$, with $\epsilon = 0.25$

Solution

- The predictions are:
 - $\mathbf{w}^{\mathsf{T}}\mathbf{x}_{1} = -2$.
 - $\mathbf{w}^{\mathsf{T}}\mathbf{x}_{2} = -1$
 - $\mathbf{w}^{\mathsf{T}}\mathbf{x}_{2} = 1$.
- ② The corresponding errors are:
 - $e_1 = \max\{0, |-2 v_1| 0.25\} = 0$.
 - $e_2 = \max\{0, |-1 y_2| 0.25\} = 0.$
 - $e_3 = \max\{0, |1 v_3| 0.25\} = 0.75$.



Notebook

SVR





Support Vector Regression - Optimization (I)



$$\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R}}} \left\{ \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^N (\xi_i + \xi_i^*) \right\}$$

$$\xi, \xi^* \in \mathbb{R}^N$$
s.t.
$$\begin{cases} \mathbf{w}^\mathsf{T} \mathbf{x}_i + b - y_i \le \epsilon + \xi_i, \\ y_i - \mathbf{w}^\mathsf{T} \mathbf{x}_i - b \le \epsilon + \xi_i^*, \\ \xi_i, \xi_i^* \ge 0, \\ 1 \le i \le N. \end{cases}$$

- The objective function is **convex** and **differentiable**.
- The problem has linear constraints.
- It can be solved using Lagrangian duality.



Support Vector Regression - Optimization (II)



• The Lagrangian becomes:

$$\mathcal{L}\left(\mathbf{w}, b, \boldsymbol{\xi}^{(*)}; \boldsymbol{\alpha}^{(*)}, \boldsymbol{\beta}^{(*)}\right) = \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{N} (\xi_{i} + \xi_{i}^{*}) + \sum_{i=1}^{N} \alpha_{i} (\mathbf{w}^{\mathsf{T}} \mathbf{x}_{i} + b - y_{i} - \epsilon - \xi_{i}) + \sum_{i=1}^{N} \alpha_{i}^{*} (y_{i} - \mathbf{w}^{\mathsf{T}} \mathbf{x}_{i} - b - \epsilon - \xi_{i}^{*}) + \sum_{i=1}^{N} \beta_{i} (-\xi_{i}) + \sum_{i=1}^{N} \beta_{i}^{*} (-\xi_{i}^{*}).$$

• The saddle-point problem is:

$$\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R} \\ \boldsymbol{\xi}, \boldsymbol{\xi}^* \in \mathbb{R}^N}} \left\{ \max_{\substack{\boldsymbol{\alpha}^{(*)} \in \mathbb{R}^N \\ \boldsymbol{\beta}^{(*)} \in \mathbb{R}^N \\ \boldsymbol{\alpha}^{(*)} \geq \mathbf{0} \\ \boldsymbol{\beta}^{(*)} \geq \mathbf{0}}} \left\{ \mathcal{L} \Big(\mathbf{w}, b, \boldsymbol{\xi}^{(*)}; \boldsymbol{\alpha}^{(*)}, \boldsymbol{\beta}^{(*)} \Big) \right\} \right\} = \max_{\substack{\boldsymbol{\alpha}^{(*)} \in \mathbb{R}^N \\ \boldsymbol{\beta}^{(*)} \in \mathbb{R}^N \\ \boldsymbol{\alpha}^{(*)} \geq \mathbf{0} \\ \boldsymbol{\beta}^{(*)} \geq \mathbf{0}}} \left\{ \min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ b \in \mathbb{R} \\ \boldsymbol{\xi} \in \mathbb{R}^N}} \left\{ \mathcal{L} \Big(\mathbf{w}, b, \boldsymbol{\xi}^{(*)}; \boldsymbol{\alpha}^{(*)}, \boldsymbol{\beta}^{(*)} \Big) \right\} \right\}.$$

Support Vector Regression - Optimization (III)



• Solving the inner problem (taking derivatives with respect to w and b) leads to:

$$\frac{\partial}{\partial b} \mathcal{L}\left(\mathbf{w}, b, \boldsymbol{\xi}^{(*)}; \boldsymbol{\alpha}^{(*)}, \boldsymbol{\beta}^{(*)}\right) = \sum_{i=1}^{N} \alpha_{i} - \sum_{i=1}^{N} \alpha_{i}^{*} = 0 \implies \sum_{i=1}^{N} (\alpha_{i}^{*} - \alpha_{i}) = 0;$$

$$\nabla_{\mathbf{w}} \mathcal{L}\left(\mathbf{w}, b, \boldsymbol{\xi}^{(*)}; \boldsymbol{\alpha}^{(*)}, \boldsymbol{\beta}^{(*)}\right) = \mathbf{w} + \sum_{i=1}^{N} \alpha_{i} \mathbf{x}_{i} - \sum_{i=1}^{N} \alpha_{i}^{*} \mathbf{x}_{i} = 0 \implies \mathbf{w} = \sum_{i=1}^{N} (\alpha_{i}^{*} - \alpha_{i}) \mathbf{x}_{i};$$

$$\frac{\partial}{\partial \boldsymbol{\xi}_{i}^{(*)}} \mathcal{L}\left(\mathbf{w}, b, \boldsymbol{\xi}^{(*)}; \boldsymbol{\alpha}^{(*)}, \boldsymbol{\beta}^{(*)}\right) = C - \alpha_{i}^{(*)} - \beta_{i}^{(*)} = 0 \implies 0 \le \alpha_{i}^{(*)} \le C.$$



Support Vector Regression - Optimization (IV)



• Substituting back leads to the dual function:

$$\mathcal{D}(\alpha^{(*)}) = \frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} (\alpha_{i}^{*} - \alpha_{i}) (\alpha_{j}^{*} - \alpha_{j}) \mathbf{x}_{i}^{\mathsf{T}} \mathbf{x}_{j} + C \sum_{i=1}^{N} (\xi_{i} + \xi_{i}^{*})$$

$$+ \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i} (\alpha_{j}^{*} - \alpha_{j}) \mathbf{x}_{i}^{\mathsf{T}} \mathbf{x}_{j} + \sum_{i=1}^{N} \alpha_{i} b - \sum_{i=1}^{N} \alpha_{i} y_{i} - \sum_{i=1}^{N} \alpha_{i} \epsilon - \sum_{i=1}^{N} \alpha_{i} \xi_{i} + \sum_{i=1}^{N} \alpha_{i}^{*} y_{i}$$

$$- \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{i}^{*} (\alpha_{j}^{*} - \alpha_{j}) \mathbf{x}_{i}^{\mathsf{T}} \mathbf{x}_{j} - \sum_{i=1}^{N} \alpha_{i}^{*} b - \sum_{i=1}^{N} \alpha_{i}^{*} \epsilon - \sum_{i=1}^{N} \alpha_{i}^{*} \xi_{i}^{*} - \sum_{i=1}^{N} \beta_{i} \xi_{i} - \sum_{i=1}^{N} \beta_{i}^{*} \xi_{i}^{*}$$

$$= -\frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} (\alpha_{i}^{*} - \alpha_{i}) (\alpha_{j}^{*} - \alpha_{j}) \mathbf{x}_{i}^{\mathsf{T}} \mathbf{x}_{j} - \sum_{i=1}^{N} (\alpha_{i} - \alpha_{i}^{*}) y_{i} - \epsilon \sum_{i=1}^{N} (\alpha_{i} + \alpha_{i}^{*})$$

$$+ b \sum_{i=1}^{N} (\alpha_{i} - \alpha_{i}^{*}) + \sum_{i=1}^{N} \xi_{i} (C - \alpha_{i} - \beta_{i}) + \sum_{i=1}^{N} \xi_{i}^{*} (C - \alpha_{i}^{*} - \beta_{i}^{*})$$



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Support Vector Regression - Optimization (V)



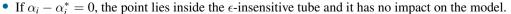
In matrix notation, the dual function becomes:

$$\mathcal{D}\left(\boldsymbol{\alpha}^{(*)}\right) = -\frac{1}{2}(\boldsymbol{\alpha}^* - \boldsymbol{\alpha})^\mathsf{T}\mathbf{X}\mathbf{X}^\mathsf{T}(\boldsymbol{\alpha}^* - \boldsymbol{\alpha}) - \epsilon(\boldsymbol{\alpha}^* + \boldsymbol{\alpha})^\mathsf{T}\mathbf{1} + (\boldsymbol{\alpha}^* - \boldsymbol{\alpha})^\mathsf{T}\mathbf{y}.$$

The resultant dual problem is:

$$\min_{\substack{\boldsymbol{\alpha}, \boldsymbol{\alpha}^* \in \mathbb{R}^N \\ \text{s.t.} }} \left\{ \frac{1}{2} (\boldsymbol{\alpha}^* - \boldsymbol{\alpha})^\mathsf{T} \mathbf{X} \mathbf{X}^\mathsf{T} (\boldsymbol{\alpha}^* - \boldsymbol{\alpha}) + \epsilon (\boldsymbol{\alpha}^* + \boldsymbol{\alpha})^\mathsf{T} \mathbf{1} - (\boldsymbol{\alpha}^* - \boldsymbol{\alpha})^\mathsf{T} \mathbf{y} \right\}$$
s.t.
$$\left\{ \begin{array}{l} (\boldsymbol{\alpha}^* - \boldsymbol{\alpha})^\mathsf{T} \mathbf{1} = 0, \\ \mathbf{0} \leq \boldsymbol{\alpha}, \boldsymbol{\alpha}^* \leq C. \end{array} \right.$$

- It is again a constrained quadratic problem.
- There are different ad hoc algorithms for solving it.
- The data only appear in form of **inner products**.
- As a consequence of the Lagrangian duality:



• Otherwise, the point lies outside the tube (or over the border) and it is a support vector.



SVR: Optimization





One-Class Support Vector Machine



Novelty Detection



Outlier Detection

- In many cases, the training data contains outliers (data points generated by a different distribution).
- In practice, outlier detection estimators try to find the regions where the data is more concentrated, ignoring the data points far away from the mean.

Novelty Detection

- The training data in this case has no outliers.
- The goal is instead to detect **anomalies** in new observations.

One-Class SVM

- One-Class SVM is an unsupervised learning algorithm used for novelty detection.
 - Given a set of samples, it will define a soft boundary around the regions with high density of points.
 - It will provide good results also in outlier problems.



One-Class Support Vector Machine



• The One-Class Support Vector Machine is defined as the solution of the problem:

$$\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ \rho \in \mathbb{R}}} \left\{ \frac{1}{2} \|\mathbf{w}\|_2^2 - \rho + \frac{1}{\nu N} \sum_{i=1}^N |\rho - \mathbf{w}^\mathsf{T} \mathbf{x}_i|_+ \right\}.$$

- Similar idea than a classical SVC (with ν -SVM formulation), but separating "data" from "no data".
- It is defined in terms of a hinge loss function.
- The hyper-parameter $\nu \in (0,1]$ controls the anomaly detection sensitivity.
 - It is an upper-bound of the fraction of errors allowed.
 - It is a lower-bound of the number of support vectors.



OC-SVM





One-Class Support Vector Machine - Optimization (I)



$$\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ \rho \in \mathbb{R}}} \left\{ \frac{1}{2} \|\mathbf{w}\|_{2}^{2} - \rho + \frac{1}{\nu N} \sum_{i=1}^{N} |\rho - \mathbf{w}^{\mathsf{T}} \mathbf{x}_{i}|_{+} \right\} \equiv \left[\min_{\substack{\mathbf{w} \in \mathbb{R}^d \\ \rho \in \mathbb{R}}} \left\{ \frac{1}{2} \|\mathbf{w}\|_{2}^{2} - \rho + \frac{1}{\nu N} \sum_{i=1}^{N} \xi_{i} \right\} \right]$$
s.t.
$$\left\{ \mathbf{w}^{\mathsf{T}} \mathbf{x}_{i} \ge \rho - \xi_{i}, \\ \xi_{i} \ge 0, \\ 1 \le i \le N. \right\}$$

- The objective function is **convex** and **differentiable**.
- The problem has linear constraints.
- It can be solved using Lagrangian duality.



One-Class Support Vector Machine - Optimization (II)



• After the corresponding derivations, the resultant **dual problem** is:

$$\min_{\boldsymbol{\alpha} \in \mathbb{R}^{N}} \left\{ \frac{1}{2} \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{X} \mathbf{X}^{\mathsf{T}} \boldsymbol{\alpha} \right\}$$
s.t.
$$\left\{ \begin{array}{l} \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{1} = 1, \\ \mathbf{0} \leq \boldsymbol{\alpha} \leq \frac{1}{\nu N}. \end{array} \right.$$

• The primal hyperplane is recovered as:

$$\mathbf{w} = \sum_{i=1}^{N} \alpha_i \mathbf{x}_i.$$

- It is again a constrained quadratic problem.
- There are different ad hoc algorithms for solving it.
- The data only appear in form of **inner products**.
- As a consequence of the Lagrangian duality:
 - If $\alpha_i = 0$, the point lies on the correct side and it has no impact on the model.
 - Otherwise, the point is a support vector.



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OC-SVM: Optimization





The Kernel Trick



The Kernel Trick



- Linear models are not enough in many problems.
- In the optimization problem for training SVMs, the data only appear as inner products.
- Moreover, the prediction for a new data point, $\mathbf{w}^{\mathsf{T}}\mathbf{x} + b$, can also be computed using only inner products.
- The SVMs can be extended to a non-linear framework using a mapping $\phi : \mathbb{R}^d \to \mathbb{R}^D$.
- Thanks to the kernel trick, instead of defining explicitly ϕ , a kernel function $\mathcal{K}: \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}$ is used.
 - The selection of the kernel, and its hyper-parameters, is crucial.
 - One of the most common choices is the RBF kernel $\mathcal{K}(\mathbf{x}, \mathbf{x}') = \exp(-\gamma \|\mathbf{x} \mathbf{x}'\|_2^2)$.
- The samples \mathbf{x}_i are substituted by $\phi(\mathbf{x}_i)$.
- The matrix XX^{T} is substituted by the kernel matrix $K = \Phi\Phi^{\mathsf{T}}$.



Non-Linear SVMs (I)



SVC: Training

$$\min_{\boldsymbol{\alpha} \in \mathbb{R}^N} \left\{ \frac{1}{2} \boldsymbol{\alpha}^\mathsf{T} \tilde{\mathbf{K}} \boldsymbol{\alpha} - \boldsymbol{\alpha}^\mathsf{T} \mathbf{1} \right\} \text{ s.t. } \left\{ \begin{array}{c} \boldsymbol{\alpha}^\mathsf{T} \mathbf{y} = 0, \\ \mathbf{0} \le \boldsymbol{\alpha} \le C. \end{array} \right.$$

SVR: Training

$$\min_{\boldsymbol{\alpha}, \boldsymbol{\alpha}^* \in \mathbb{R}^N} \left\{ \frac{1}{2} (\boldsymbol{\alpha}^* - \boldsymbol{\alpha})^\mathsf{T} \mathbf{K} (\boldsymbol{\alpha}^* - \boldsymbol{\alpha}) + \epsilon (\boldsymbol{\alpha}^* + \boldsymbol{\alpha})^\mathsf{T} \mathbf{1} - (\boldsymbol{\alpha}^* - \boldsymbol{\alpha})^\mathsf{T} \mathbf{y} \right\} \text{ s.t. } \left\{ \begin{array}{l} (\boldsymbol{\alpha}^* - \boldsymbol{\alpha})^\mathsf{T} \mathbf{1} = 0, \\ \mathbf{0} \leq \boldsymbol{\alpha}, \boldsymbol{\alpha}^* \leq C. \end{array} \right.$$

OC-SVM: Training

$$\min_{\alpha \in \mathbb{R}^N} \left\{ \frac{1}{2} \alpha^\mathsf{T} \mathbf{K} \alpha \right\} \text{ s.t. } \left\{ \begin{array}{c} \alpha^\mathsf{T} \mathbf{1} = 1, \\ \mathbf{0} \le \alpha \le \frac{1}{\nu N}. \end{array} \right.$$



Non-Linear SVMs (II)



SVC: Prediction

$$f(\mathbf{x}) = \sum_{i=1}^{N} y_i \alpha_i \mathcal{K}(\mathbf{x}_i, \mathbf{x}) + b.$$

SVR: Prediction

$$f(\mathbf{x}) = \sum_{i=1}^{N} (\alpha_i^* - \alpha_i) \mathcal{K}(\mathbf{x}_i, \mathbf{x}) + b.$$

OC-SVM: Prediction

$$f(\mathbf{x}) = \sum_{i=1}^{N} \alpha_i \mathcal{K}(\mathbf{x}_i, \mathbf{x}) - \rho.$$



Non-Linear SVC

Non-Linear SVR

Non-Linear OC-SVM





Support Vector Machines

Carlos María Alaíz Gudín

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