



STA 5106

Computational Methods in Statistics I

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Chapter 3

Non-Linear Statistical Methods

3.1 Introduction



Non-linear Optimization

- This chapter is devoted to solving for the optimal points of given functions, linear or nonlinear.
- An instance of nonlinear optimization problems in statistics occurs in cases of **maximum likelihood estimation**.
- Example:

$$y = F(x, b) + \varepsilon$$

where x and y are random variables of interest, b is a constant vector of parameters, and ε is a random error with the density function given by f_ε .

- In many practical situations, we have the sampled values of y , x , and our goal is to estimate b according to some criterion.



Maximum Likelihood Estimation (MLE)

- Assuming sample size is n and different measurements are independent of each other, b can be estimated as follows:

$$\hat{b} = \arg \max_b \prod_{i=1}^n f_{\varepsilon}(y_i - F(x_i, b))$$

- The quantity on the right side of the above equation is called the *likelihood function*.
- \hat{b} is called the *maximum likelihood estimate (MLE)* of b .
- In general, a value of b which maximizes the likelihood function can be found out **by seeking the roots of the first derivative of the likelihood function**.



3.2 Numerical Root Finding: Scalar Case



Goal

- We are given a real-valued function $f(x)$ where $x \in \mathbf{R}$ and the goal is to find the roots of f , i.e., find x^* such that $f(x^*) = 0$.
- Due to the non-linearity of the cost function its roots are found in an iterative way: an initial estimate is chosen and is modified iteratively until some stopping criterion is met.
- There are many different methods for root-finding. They all have the following three essential elements:
 1. Some of determining the starting value, x_0 .
 2. Given the i -th iterate some formula for calculating the $(i+1)$ -th iterate.
 3. Some stopping criterion.



Order of Convergence

- For each of these algorithms we are interested in finding their rate of convergence towards the roots of the function.
- The rate of convergence is defined by a quantity called the **order of convergence**.
- **Definition 10** For a converging sequence $\{x_i\}$, the order of convergence is defined by β if,

$$\lim_{i \rightarrow \infty} \frac{E_{i+1}}{E_i^\beta} = K,$$

where $E_i = |x_i - x_{i-1}|$ and K is a constant.



Simple Iterations

- Instead of solving for the roots of f we solve an equivalent problem of finding the fixed point of another function g . g is found in such a way that

$$f(x^*) = 0 \Leftrightarrow g(x^*) = x^*.$$

- The selection depends on which g is easier to handle and solve for a fixed point. One choice which is always valid is

$$g(x) = x + f(x) .$$

- Let x_0 be some starting value for the iterative search of the roots of f . At the i -th stage of the algorithm, the next iterate is given by the formula:

$$x_{i+1} = g(x_i) = x_i + f(x_i) .$$

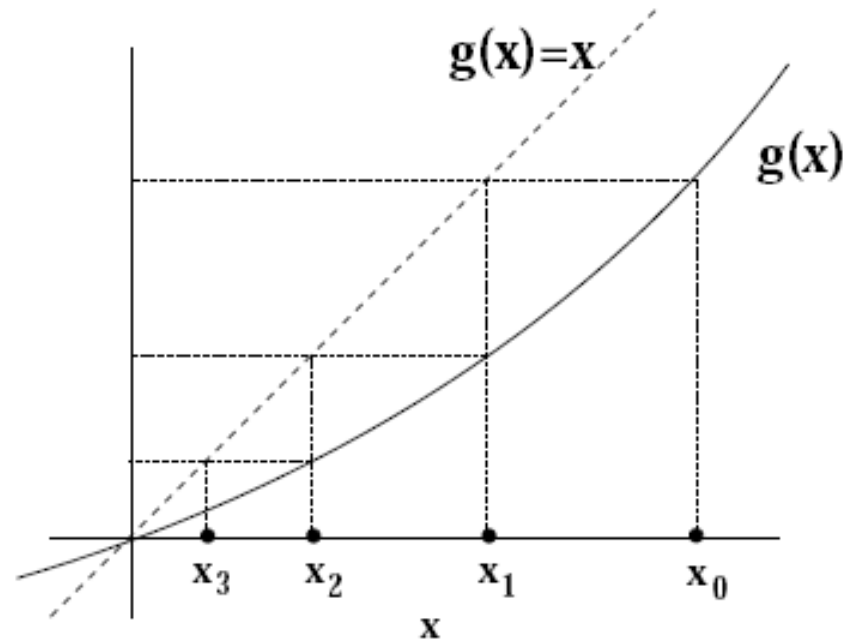


Algorithm

- **Algorithm:** Given a function $f(x)$ find its roots using simple iterations by defining $g(x) = x + f(x)$, and:
- **Algorithm 21** (Simple Iterations)
 $x(1) = x_0$;
 $gx = g(x(1))$;
 $i = 1$;
 while ($\text{abs}(x(i) - gx) > \varepsilon$)
 $gx = x(i)$;
 $x(i + 1) = g(x(i))$;
 $i = i + 1$;
 end



Illustration



- The order of convergence in simple iterations is 1, or the convergence is linear.