

STA 5106 Computational Methods in Statistics I

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Review: Importance Sampling

- Instead of sampling from f(x), the **importance sampling** samples from another density h(x), and computes the estimate of Θ using averages of g(x)f(x)/h(x) instead of g(x) evaluated on those samples.
- Mathematically, we can rearrange the definition of Θ as follows:

$$\Theta = \int g(x)f(x)dx = \int \frac{g(x)f(x)}{h(x)}h(x)dx.$$

• Generate samples X_1, X_2, \ldots, X_n from the density h(x) and compute the estimate:

$$\hat{\Theta}_n = \frac{1}{n} \sum_{i=1}^n \frac{g(X_i) f(X_i)}{h(X_i)}.$$



6.5 Tilted Sampling



Tilted Sampling

- This is a specific case of importance sampling where the sampling distribution is simply a tilted version of the original density function.
- In cases where one is interested in estimating tail probabilities, and where these tails are negligible, it may be useful to tilt the density while raising the tail probability.
- Let f(x) be the original probability density function. Then, the tilted density is given by:

$$f_t(x) = \frac{\exp(tx)f(x)}{M(t)}$$
, where $M(t) = \int \exp(tx)f(x)dx$.



Tail Probability

- The amount of tilt is given by the parameter $-\infty < t < \infty$.
- For t > 0, the positive values of x increase in probability while the negative values decrease in probability. Opposite happens for t < 0.
- Consider the probability where we are interested in estimating the tail probability:

$$\theta = P\{X \ge a\} = \int_a^\infty f(x) dx,$$

and let a be much larger than the mean of X, i.e. $a \gg E[X]$.



Unbiased Estimator

• Using random sampling from the tilted density X_1, X_2, \ldots, X_n from $f_t(x)$, and the estimator is given by:

$$\hat{\theta}_n = \frac{1}{n} \sum_{i=1}^n I_{\{X_i \ge a\}} M(t) \exp(-tX_i).$$

Compute the expectation of the estimate:

$$E[\hat{\theta}_n] = \frac{1}{n} \sum_{i=1}^n E[I_{\{X_i \ge a\}} M(t) \exp(-tX_i)]$$

$$= \frac{1}{n} \sum_{i=1}^n \int_a^\infty M(t) \exp(-tx_i) \exp(tx_i) \frac{f(x_i)}{M(t)} dx_i$$

$$= \theta$$



Variance Estimate

• The variance of the estimator is given by:

$$var[\hat{\theta}_n] = E[(\frac{1}{n} \sum_{i=1}^n I_{\{X_i \ge a\}} M(t) \exp(-tX_i) - \theta)^2]$$

$$= \frac{1}{n} \left[\int I_{\{X_i \ge a\}}^2 M(t)^2 \exp(-2tx_i) f_t(x_i) dx_i - \theta^2 \right]$$

• The integration term on the right side simplifies to:

$$\int_{a}^{\infty} M(t)^{2} \exp(-2tx_{i}) f_{t}(x_{i}) dx_{i} = M(t) \int_{a}^{\infty} \exp(-tx_{i}) f(x_{i}) dx_{i}$$

• In the interest of reducing estimating variance, we seek a value of *t* that minimizes this term. However, this minimization is not straightforward and leads to an indirect solution.



Bound

• Assuming t > 0, we can bound this term as follows:

$$M(t) \int_{a}^{\infty} \exp(-tx_{i}) f(x_{i}) dx_{i} \le M(t) \int_{a}^{\infty} \exp(-ta) f(x_{i}) dx_{i}$$

$$\le M(t) \exp(-ta)$$

• It is easier to minimize this bounding term as follows:

$$\frac{d}{dt}[M(t)\exp(-ta)] = M'(t)\exp(-ta) - aM(t)\exp(-ta) = 0$$

• This implies that t should be chosen such that

$$a = \frac{M'(t)}{M(t)} = \int x \exp(tx) \frac{f(x)}{M(t)} dx = \int x f_t(x) dx.$$

• i.e. *t* should be chosen such that *a* is the mean of the tilted density.



Example

• Example: For a standard normal random variable X, find the probability $P\{X \ge a\}$ for a >> 0. The quantity to be estimated is given by:

 $\theta = \int_{a}^{\infty} f(x) dx.$

• The tilted version of f(x) is given by

$$f_t(x) = \frac{\exp(tx)f(x)}{M(t)},$$

where

$$M(t) = \int \exp(tx) f(x) dx = \int \frac{1}{\sqrt{2\pi}} \exp(tx) \exp(-x^2/2) dx$$
$$= \frac{1}{\sqrt{2\pi}} \exp(t^2/2) \int \exp(-\frac{1}{2}(x-t)^2) dx = \exp(t^2/2)$$



Tilted Density

• In fact, the tilted density can also be written as:

$$f_t(x) = \frac{1}{\sqrt{2\pi}} \exp(-\frac{1}{2}(x-t)^2)$$

- The tilted density is normal with mean t and variance 1.
- Choosing t such that the mean of the tilted density is a. That is, set the amount of tilt to be a.
- Let X_i 's be sampled from the tilted density. Then, θ can be estimated as follows.



Estimators

• Since the ratio

$$\frac{f(x)}{f_t(x)} = \exp(-tx)M(t) = \exp(-ax)\exp(a^2/2),$$

• An estimator of θ is given by:

$$\hat{\theta}_n = \frac{1}{n} \sum_{i=1}^n I_{\{X_i \ge a\}} \exp(a^2 / 2 - aX_i).$$