





Profile-guided optimization Speeding up LHCb software through compilation optimization

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CERN

Intergovernmental particle physics on France-Switzerland border.

About 15,000 people working at CERN.

Made discoveries that led to Nobel Prizes.

World Wide Web was invented at CERN.



Large Hadron Collider (LHC)

- Large Hadron Collider: particle collider
- 27km (biggest in the world)
- $\bullet \sim 100 m$ underground



LHCb

- One of the 4 main experiments installed on the LHC.
- More than 1,200 people working for the collaboration.
- Studies asymmetry between matter and antimatter via b-physics. Collision of hadrons (heavy particles).



Physics Computing

The detector needs an important computing infrastructure to work properly.

The detector produces about TB/s of data that are analyzed to reconstruct the trajectories and the properties of the particles.

Then statistics are made from these reconstructed particles.

Moreover simulations are made through the software. Then statistics are comapred to the simulations.

Some computing analysis are dispatched in servers arround the world (grid).

Computing group

A first level software will filter data to keep interresting tracks.

Then data are stored in a buffer for hours to be analyzed in a second level software.

Some computing analysis are dispatched in servers arround the world (grid).

The computing group has to maintain this infrastructure for LHCb.

Software

The software is a stack programms:

- The base of the stack is composed of software like ROOT or Gaudi that are shared with other experiments.
- On top of them there are Detector, LHCb or Lbcom that modelise the experiment.
- And then there are Rec that reconstruct the tracks and the simulation programms.
- Some other programms are to use or to test the others, like Moore.

There are several million lines of code which some are 30 years old. Moreover the code is mainly written by non-software engineers. All of this is running on thousands of multithreaded Linux servers.

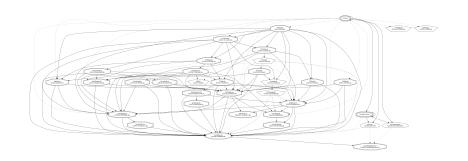
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Graphviz for printing graphs

Printing graphs was usefull to have an idea of the dependencies. Graphviz in CMake to create dependency graphs:

- CMake arg: --graphviz=path/to/files.dot
- Convert to SVG:
 dot -Tsvg -o path/to/file.svg path/to/file.dot
- Make arg: CMAKEFLAGS="--graphviz=path/to/files.dot"
- Setting GRAPHVIZ_EXTERNAL_LIBS to FALSE is usefull.



Context Library types Static libraries Static modules

Context

Worked on a stack with one main CMake:

https://gitlab.cern.ch/clemenci/lhcb-super-project-template/

Target: x86_64_v3-centos7-gcc11+detdesc-opt+g

Library types

- STATIC: an archive of object files that are merged to the executable at link time.
- SHARED: .so (Linux) file that is automatically linked to the executable at runtime (when starting it). Allows several executables to link with a library installed on the system.
- MODULE: same as shared but the module is loaded on demand via the dlopen function, so not automatically.

Static libraries

Gaudi provides CMake functions to create libraries, modules or executables. Then we just have to create a new function for static libraries by copying the one for shared libraries: gaudi_add_library \Rightarrow gaudi_add_static_library And inside remplacing SHARED by STATIC in add_library function call.

Static modules

By using previous static libraries. Need to add:

- -Wl,--whole-archive link option while linking to the final executable.
- -Wl,--whole-archive and
 -Wl,--allow-multiple-definition link option to the executable.
- the global link option -Wl, --export-dynamic

Explanation of flags

- -Wl, --whole-archive because without it the linker removes the code in the module that registers it. Note that this could be an error in the linker because that behavior was not the same when using object files instead of static libaries.
- -Wl,--allow-multiple-definition because
 -Wl,--whole-archive causes symbols to be included several times.
- -Wl,--export-dynamic to allow functors to access to symbols.

We have to notice that some of these flags seem to be Hacks and are not recommended to be used. Moreover there may still be bugs, especially with functors.



The final executable goes from $\sim 20kB$ to 2.5GB.

The standard method to run test with python is not working. Need to run directly the executable with a json options file:

```
\begin{array}{l} \texttt{build.x86\_64\_v3-centos7-gcc11+detdesc-opt+g/run.} \\ \texttt{./build.x86\_64\_v3-centos7-gcc11+detdesc-opt+g/Gaudi/Gaudi/Gaudi\_static.options.json} \end{array}
```

Profile-guided optimization

The compiler uses some heuristics to optimize some elements:

- Inlining
- Block ordering
- Register allocation
- Virtual call speculation
- Dead code separation

But sometimes these heuristics are wrong.

A better way for the compiler should having running data. The the principle of PGO is:

- Compiling the programm with instrumentation.
- Running it to create profiles (counters).
- Recompiling the programm with the profiles.

Link-time optimization

Allows the linker to perform optimizations that take account of all translation units.

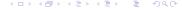
Final building pipeline

- Compiling the programm with -fprofile-generate
- Running it to create profiles
- Recompiling the programm with
 - -flto -fprofile-use -fprofile-correction

Results

Test: $hlt2_pp_thor (6 \times 1000 \text{ events})$

Optimization	Acceleration	Confidence interval (2σ)
LTO	0.17%	$\pm 1.12\%$
LTO & PGO	6.74%	$\pm 1.44\%$
Static LTO	0.87%	$\pm 0.60\%$
Static LTO & PGO	6.88%	$\pm 0.83\%$



Conclusion

- Using LTO & PGO makes the programm running faster.
- Using static libraries and modules doesn't seem to be usefull and leads to some bugs.

