資料結構 Data Structure

TZU-CHUN HSU¹

 $^{1}\mathrm{vm3y3rmp40719@gmail.com}$

¹Department of Computer Science, Zhejiang University



2020 年 10 月 19 日 Version 1.0

Disclaimer

本文「資料結構」為台灣研究所考試入學的「資料結構」考科使用,內容主要參考 wjungle 網友在 PTT 論壇上提供的資料結構筆記 [1]。

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1 Overview

- 1. 本文頁碼標記依照 TKB 筆記 [1] 的頁碼。
- 2. TKB 筆記 [1] 章節頁碼:

Chapter	Page No.	Importance
1	3	***
2	259	*
3	52	***
4	259	*
5	82	****
6	228	***
7	180	***
8	221	***
9	// 129	***

Data structure	Page No.
BST	9
Heap	11
Min-max heap	_13
Deap	14
SMMH	15 //
AVL tree	16 //
m-way ST	16/
Red-black tree	18
Splay tree	19
Leftist heap	10 20
Binomial heap	21
Fibonacci heap	21

- 3. 缺少 Red-black tree 删除。
- 4. OBST在「演算法」中,不再贅述。

Comparison between trees.					
Tree	Insert x	$sert x \mid Delete x \mid Search x$		Remark	
BST	$O(\log n) \sim O(n)$		(n)	Create: $O(n \log n) \sim O(n^2)$	
AVL tree	$O(\log_m n)$			$F_{n+2} - 1 \le n \le 2^h - 1$	
B tree				$1 + 2\frac{\lceil \frac{m}{2} \rceil^{h-1} - 1}{\lceil \frac{m}{2} \rceil - 1} \le n \le 2\lceil \frac{m}{2} \rceil^{h-1} - 1$	
RBT	(Gm)			$h \le 2\log(n+1)$	
Splay tree				Worst: $O(n)$	

Comparison between priority queues.					
Operations	Max (Min)	Min-max & Deap & SMMH	Leftist	Binomial	Fibonacci
Insert x	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(\log n), O(1)^*$	$O(1)^*$
Delete max	$O(\log n)$	$O(\log n)$			
Delete min	O(n)	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(\log n)^*$
Delete x				$O(\log n)$	$O(\log n)^*$
Merge	O(n)		$O(\log n)$	$O(\log n)$	$O(1)^*$
Decrease key				$O(\log n)$	$O(1)^*$
Search x	O(n)				
Find max	O(1)	O(1)			
Find min		O(1)		$O(\log n)$	O(1)
Remark		0 0	Merge faster than heap.	Find min can be down to $O(1)$.	Decrease key is faster than binomial heap



2 Summary

1. Theorem (12) Ackerman's function:

$$A(m,n) = \begin{cases} n+1 & , m = 0 \\ A(m-1,1) & , n = 0 \\ A(m-1,A(m,n-1)) & , \text{otherwise} \end{cases}$$
 (1)

2. Theorem (17) Permutation:

```
1: function PERM(list, i, n)
       if i == n then
2:
            Print(list)
3:
       else
4:
           for j := i \text{ to } n \text{ do}
5:
               SWAP(list, i, j)
6:
               PERM(list, i+1, n)
7:
               SWAP(list, i, j)
8:
           end for
9:
       end if
10:
11: end function
```

3. Theorem (21) Stirling's formula:

$$\lim_{n \to \infty} \frac{n!}{\sqrt{2\pi n} (\frac{n}{e})^n} = 1 \tag{2}$$

- 4. Theorem (58, 59)
 - Infix: Compiler 需 scan 多次, 耗時。
 - Postfix: Compiler 左到右 scan 一次即可。
 - Prefix: Compiler 右到左 scan 一次即可,但效率比 Postfix 差, Infix 轉 Postfix 只需 1 個 stack, 而 Infix 轉 Prefix 需要 2 個 stack。
 - Infix 轉 Postfix (Prefix):
 - 手算:
 - (a) 加上完整括號。
 - (b) 運算元取代最近的右(左)括號。

- (c) 删去左(右)括號。
- (d) 從左至右即是 Infix。
- 演算法:
 - (a) 數字直接 print。
 - (b) 運算元依照優先級比較;若小於等於 stack 中的運算元, pop 直到大於為止;若大於或相同於 stack 中的運算元, push;若為), pop 直到(為止,但不 print。

Priority			
Priority	Operator		
1	(out of stack		
2	↑ out of stack		
// 3	† in stack		
4	*, \		
5 (+ , = 0		
6	empty stack, (in stack		

- 5. Theorem (80, 81) Stack 與 Queue 相互製作:
 - 利用 Stack 製作 Queue:
 - Enqueue: 利用 Push 代替。
 - Dequeue:額外使用一個 Stack,將原本 Stack 全部 Pop 並且 Push 到另一個 Stack,最後 Pop 掉 top。
 - 利用 Queue 製作 Stack:
 - Push: 利用 Enqueue 代替。
 - Pop: 除了 rear 皆 Dequeue 並且 Enqueue 進 Queue, 最後 Dequeue 掉 front (原本的 rear)。
- 6. Theorem (87) 節點數:

- 7. Theorem (89, 92) 二叉樹種類:
 - Full (完滿): 最後一層有最多的樹葉節點,不能在更多。

- Complete (完整): 最後一層全靠左,非最後一層為 Full。若對節點從左而右,從 上而下編號,則對節點 *i* 有
 - 左子節點: 2i,但若 2i > n,則無左子節點。
 - 右子節點: 2i+1, 但若 2i+1>n, 則無右子節點。
 - 父節點: $\lfloor \frac{i}{2} \rfloor$, 但若 $\lfloor \frac{i}{2} \rfloor$ < 1, 則無父節點。
- Strict (嚴格): 所有非樹葉節點皆有兩個子節點。

8. Theorem (95, 97, 98)

- 可以確定二叉樹, 其他則否:
 - Preorder, Inorder.
 - Postorder, Inorder.
 - Level-order Inorder .
 - Complete 和任意排序。
- Preoder = Inoder: Empty, Root, Right-skewed tree.
- Postoder = Inoder: Empty, Root, Left-skewed tree.
- Preoder = Postoder: Empty, Root.

9. Theorem (100, 101, 102, 103, 104)

• 複製二叉樹:

```
1: function Copy(Tree s)
       if s = NIL then
2:
          t := NIL
3:
       else
4:
          t.data := s.data
5:
          t.lchild := Copy(s.lchild)
6:
          t.rchild := Copy(s.rchild)
7:
       end if
8:
       return t
9:
10: end function
```

• 判斷二二叉樹是否相同:

```
1: function EQUAL(Tree s, t)
       res := False
 2:
        if s = \text{NIL} \land t = \text{NIL} then
 3:
 4:
           res := True
        else if s \neq \text{NIL} \land t \neq \text{NIL} then
 5:
           if s.data = t.data then
 6:
                if Equal(s.lchild, t.lchild) then
 7:
                    res := EQUAL(s.rchild, t.rchild)
 8:
                end if
 9:
10:
            end if
11:
        end if
        return res
12:
13: end function
```

• 計算節點個數:

```
1: function Count(Tree s)
2: if s = \text{NIL then}
3: return 0
4: else
5: return Count(s.lchild) + Count(s.rchild) + 1
6: end if
7: end function
```

• 計算二叉樹高:

```
1: function HEIGHT(Tree s)
      if s = NIL then
2:
3:
          return 0
4:
      else
          n_l := \text{Height}(s.lchild)
5:
          n_r := \text{Height}(s.rchild)
6:
          return Max(n_l, n_r) + 1
7:
      end if
8:
9: end function
```

• 計算樹葉節點個數:

```
1: function LEAF(Tree s)
       if s = NIL then
2:
          return 0
3:
4:
       else
5:
          tmp := Leaf(s.lchild) + Leaf(s.rchild)
          if tmp > 0 then
6:
              return \ tmp
7:
          else
8:
              return 1
9:
10:
          end if
       end if
11:
12: end function
```

• 交換左右子樹:

```
1: function SWAPBT(Tree s)
2: if s \neq \text{NIL then}
3: SWAPBT(s.lchild)
4: SWAPBT(s.rchild)
5: SWAP(s.lchild, s.rchild)
6: end if
7: end function
```

- 10. Theorem (107) Binary Search Tree (BST):
 - Inoder 即是從小到大排序。
 - CRUD:

```
1: function SearchBST(Tree s, Element x)
      if s = NIL then
2:
          return NIL
3:
      else if x < s.data then
4:
         return SearchBST(s.lchild, x)
5:
      else if x > s.data then
6:
         return SearchBST(s.rchild, x)
7:
8:
      else
          return s
9:
      end if
10:
11: end function
```

```
1: function INSERTBST(Tree s, Element x)
       if s = NIL then
 2:
           s.data := x
 3:
           s.lchild := NIL
 4:
           s.rchild := NIL
 5:
       else
 6:
 7:
          if x < s.data then
                                                 \triangleright Do nothing while x is already in the tree.
              s.lchild := InsertBST(s.lchild, x)
 8:
           else if x > s.data then
 9:
              s.rchild := InsertBST(s.rchild, x)
10:
           end if
11:
       end if
12:
13:
       return s
14: end function
```

```
1: function DeleteBST(Tree s, Element x)
 2:
       if s = NIL then
           return Error
 3:
       else if x < s.data then
 4:
           s.lchild = DeleteBST(s.lchild, x)
 5:
       else if x > s.data then
 6:
           s.rchild = DeleteBST(s.rchild, x)
 7:
                                                                                      \triangleright Found x.
 8:
       else
           if s.lchild \neq NIL \land s.rchild \neq NIL then
                                                                                     \triangleright 2 children.
 9:
10:
               min := SEARCHMIN(s.rchild)
               s.data = min.data
11:
               s.rchild = DeleteBST(s.rchild, s.data)
12:
                                                                                   \triangleright 0 or 1 child.
13:
           else
               if s.lchild = NIL then
14:
                   s := s.rchild
15:
               else if s.rchild = NIL then
16:
                   s := s.lchild
17:
               end if
18:
           end if
19:
       end if
20:
       return s
21:
22: end function
```

Operations of BST				
Operation	Time complexity		Remark	
Operation	Average	Worst	Remark	
Insert x			(Based on Height)	
Delete x	$O(\log n)$	O(n)	Skewed: $O(n)$,	
Search x			Full: $O(\log n)$	
Create	$O(n \log n)$	$O(n^2)$	Γ un. $O(\log n)$	

11. **Theorem (112, 113, 116, 117)** Heap:

- Complete o
- 適合用 Array 保存。
- CRUD (Use Min-Heap as example):

```
1: function CreateMinHeap(Tree s, size n)
       for i := n/2 to 1 do
                                                            > Start from parent of the last node.
 2:
           tmp := s[i]
 3:
           j := 2 \times i
                                                                                   \triangleright Left child of i.
 4:
           while j \leq n do
                                                                                 \triangleright There is a child.
 5:
                                                                               Right child exists.
               if j < n then
 6:
                   if |s[j]| > s[j+1] then
                                                                       ▷ Choose the smaller child.
 7:
                       j := j + 1
 8:
                   end if
 9:
               end if
10:
               if tmp \leq s[j] then
11:
                   Break.
12:
               else
                                                                              ▷ Percolate one level.
13:
                   s[j/2] := s[j]
14:
                   j := j \times 2
15:
               end if
16:
            end while
17:
            s[j/2] := tmp
18:
        end for
19:
20: end function
```

```
1: function InsertMinHeap(PriorityQueue s, Element x)
       if IsFull(s) then
2:
           Queue is full.
3:
4:
          return
       end if
       s.size := s.size + 1
6:
7:
       i := s.size
                                                                  ▶ Put at the last position.
       while s.data[i/2] > x do
                                                             ▷ Check if the parent is larger.
8:
          s.data[i] := s.data[i/2]
9:
          i := i/2
10:
11:
       end while
       s.data[i] := x
12:
13: end function
```

```
1: function DELETEMINMINHEAP(PriorityQueue-s)
       if ISEMPTY(s) then
 2:
 3:
           Queue is empty.
 4:
           return s.data[0]
       end if
 5:
       min := s.data[1]
 6:
       last := s.data[s.size]
 7:
       s.size := s.size - 1
 8:
 9:
       i := 1
       while i \times 2 \leq s.size do
10:
11:
           child := i \times 2
           if child \neq s.size \land s.data[child + 1] < s.data[child] then \gt Choose the smaller
12:
    child.
               child := child + 1
13:
           end if
14:
           if last > s.data[child] then
                                                                          ▷ Percolate one level.
15:
               s.data[i] := s.data[child]
16:
           else
17:
               Break.
18:
           end if
19:
           i := child
20:
       end while
21:
       s.data[i] := last
22:
23:
       return min
24: end function
```

Operations of Max(Min)-Heap		
Operation	Time complexity	
Insert x	$O(\log n)$	
Delete max (min)	$O(\log n)$	
Search max (min)	O(1)	
Create (Bottom-up)	O(n)	

12. Theorem (118, 119, 120) 樹、森林和二叉樹之間轉換:

- Tree to binary tree:添加兄弟節點之間的邊;只留最左子節點與父節點的邊,其餘刪除。
- Binary tree to tree: 將所有 right-skewed subtree 作為其 root 的兄弟節點,補齊所有 subtree 中父節點與子節點的邊,並且刪除兄弟節點之間的邊。
- Forest to binary tree: 各個樹轉換為二叉樹, 並將所有二叉樹的 root 作為兄弟節點, 添加與旁邊兄弟的邊。
- Binary tree to forest: 將 root 右子樹及其所有右子樹, 作為 root 的兄弟節點, 刪除兄弟節點之間的邊。

13. Theorem (122, 123, 124, 125)) Disjoint set:

- Simple Find(x): 從 x 往上找 root, 並回傳 root。
- *Find with path compression(x)*: 從 *x* 往上找 root, 並且將路徑上經過除了 root 的節點的 link 改為連到 root。

Operations of disjoint set				
Combination	Union	Find		
Arbitrary Union &	0(1)	O(h)		
Simple find	0(1)	Worst: $O(n)$		
Union-by-height &	O(1)	$O(\log n)$		
Simple find	0(1)	$O(\log n)$		
Union-by-height &	O(1)	$O(\alpha(m,n)) = O(\log^* n)$		
Find with path compression	0(1)	close to $O(1)$		

14. **Theorem (129, 130, 131)** Min-max heap:

- Complete o
- Root 為最小值。
- 最大值在第二層其中一個。

• 越下層 min-level 越大, 越下層 max-level 越小。

```
1: function InsertMinMaxHeap (MinMaxHeap s, Element x)
2:
       Put x at the last position n, which has parent p.
       if p is at min-level then
3:
          if s[n].data < s[p].data then
4:
              SWAP(s[n], s[p])
5:
              VerifyMin(s, p, x)
6:
           else
 7:
              VerifyMax(s, n, x)
8:
           end if
9:
10:
       else
                                                                          \triangleright p is at max-level.
          if s[n].data > s[p].data then
11:
12:
              SWAP(s[n], s[p])
              VerifyMax(s, p, x)
13:
           else
14:
              VerifyMin(s, n, x)
15:
16:
           end if
       end if
17:
18: end function
```

```
1: function DELETEMINMINMAXHEAP(MinMaxHeap s)
2:
       Copy the data of the last node to the root and remove the last node.
       if Root has no children then
3:
          Exit.
4:
       else if Root has no grandchildren then
5:
          if Children k is smaller than the root then
6:
 7:
              SWAP(root, s[k])
8:
          end if
       else if Min grandchildren k and its parent p then
9:
          if root > s[k] then
10:
              SWAP(root, s[k])
11:
              if root > s[p] then
12:
                 SWAP(root, s[p])
13:
                 Recursively run the previous process.
14:
              end if
15:
16:
          end if
       end if
17:
18: end function
```

15. **Theorem (133, 134, 135)** Deap (Double-ended heap):

• Complete .

- root 不存 data, root 左子樹是 min-heap, 右子樹是 max-heap。
- root 左子樹中一節點必須 < 右子樹中對應的節點。

```
1: function InsertDeap(Deap s, Element x)
       Put x at the last position n.
2:
       if n is at min-heap then
3:
           j is the corresponding position in the max-heap.
 4:
          if s[n].data > s[j].data then
5:
              SWAP(s[n], s[j])
6:
              INSERTMAXHEAP(s, j, x)
 7:
           else
8:
              InsertMinHeap(s, n, x)
9:
           end if
10:
                                                                          \triangleright n is at max-heap.
11:
       else
           j is the corresponding position in the min-heap.
12:
           if s[n].data < s[j].data then
13:
              SWAP(s[n], s[j])
14:
              INSERTMINHEAP(s, j, x)
15:
           else
16:
              INSERTMAXHEAP(s, n, x)
17:
          end if
18:
19:
       end if
20: end function
```

1: function DeleteMinDeap(Deap s)

- 2: Replace the data of the left child of the root with the smaller of its children and recursively run the same process to its subtree, making an empty node n at the last level.
- 3: Copy the data of the last node as x and remove the node.
- 4: INSERTDEAP(x) to position n.
- 5: end function

16. Theorem (136, 137) SMMH (Symmetric min-max heap):

- Complete o
- root 不存 data。
- 左兄弟節點 < 右兄弟節點。
- 對一節點 x, 祖父節點的左子節點 < x, 祖父節點的右子節點 > x。
- 以一節點為 root,則該子樹最小值(不含 root)為左子節點,最大值(不含 root) 為右子節點。

- 1: **function** INSERTSMMH(SMMH s, Element x)
- 2: Put x at the last position.
- 3: Recursively swap those nodes which break the rules.
- 4: end function
- 1: **function** DeleteminSMMH(SMMH s)
- 2: Copy the data of the last node as x and remove the node.
- 3: Replace the left child of the root with the smaller of the leftmost grandchild and the third grandchild of the root and replace the chosen the node with x.
- 4: Recursively swap those nodes which break the rules.
- 5: end function

17. **Theorem ()**

Operations of Min	n-max heap, Deap, SMMH
Operation	Time complexity
Insert	$O(\log n)$
Delete min/max	$O(\log n)$
Find min/max	O(1)

- 18. **Theorem (144)** Huffman's algorithm: $O(n \log n)$,採用 Greedy,但可以求出最佳解。
- 19. Theorem (145, 151) AVL tree:
 - Height balanced BST.
 - 平衡係數: 左子樹高度減去右子樹高度。
 - 左右子樹高度相差不超過 1, 即平衡係數只能為 -1,0,1。
 - 若不符合條件,根據父節點和祖父節點類型(LL,LR,RL,RR)調整樹。
 - 高度為 h 的 AVL tree 且節點數為 n,則

$$F_{n+2} - 1 \le n \le 2^h - 1 \tag{4}$$

其中F是費氏數列,最大值為Full。

- 20. **Theorem** (154, 155, 156, 158, 161) *m*-way search tree:
 - 節點表示 data block,從左到右為小到大,每個節點有 m-1 個 key。

- 用於 external search/sort, 資料量大時, 需要分批載入 search, 因為無法全部放 memory。
- B tree:
 - Balanced m-way search tree \circ
 - 所有 failure nodes 都在同一層。
 - -m = 3, 2-3 tree; m = 4, 2-3-4 tree.
 - 若 order m、高度 h 且節點數為 n,則

$$1 + 2\frac{\lceil \frac{m}{2} \rceil^{h-1} - 1}{\lceil \frac{m}{2} \rceil - 1} \le n \le 2\lceil \frac{m}{2} \rceil^{h-1} - 1 \tag{5}$$

 $2 \le \deg(v) \le m, v \text{ is root}$ $\lceil \frac{m}{2} \rceil \le \deg(v) \le m, v \text{ is NOT root or failure nodes}$ (6)

- 1: function InsertBTree(BTree s, Element x)
- 2: Put x at proper position, which is at position n.
- 3: **while** n overflow **do**
- 4: Choose the $\lceil \frac{m}{2} \rceil$ -th key of n (started from 1), move it to its parent, and split n.
- 5: n := n.parent
- 6: end while
- 7: end function

```
1: function DeleteBTree(BTree s, Element x)
       n := SearchBTree(s, x)
       if n is leaf then
3:
4:
          Delete n.
          while n underflow do
5:
              if Can be rotated then
6:
7:
                  Rotate.
                  Break.
8:
              else
9:
                  Combine.
10:
                  n := n.parent
11:
              end if
12:
          end while
13:
                                                                                  ▷ Non-leaf
14:
       else
          Replace n with the max key of the left subtree, which is at position m.
15:
           while m underflow do
                                                                     \triangleright Same as leaf deletion.
16:
              if Can be rotated then
17:
18:
                  Rotate.
                  Break.
19:
              else
20:
21:
                  Combine.
                  m := m.parent
22:
              end if
23:
24:
           end while
25:
       end if
26: end function
```

21. Theorem (162) Red-black tree:

- BST.
- root 和 NIL 皆黑色,紅色節點的兩個子節點必定是黑色。
- root 到不同樹葉節點路徑上皆有相同數量黑色節點。
- 若一 Red-black tree 高度為 h 且節點數為 n 的,則

$$h \le 2\log(n+1) \tag{7}$$

- 1: **function** InsertRedBlackTree s, Element x)
- 2: $n := \text{SEARCHREDBLACKTREE}(s, x) \rightarrow \text{If a node has two red children during the path to } n$, change the node to red and two children to black.
- 3: while Adjacent red nodes exist do
- 4: Rotate.

▶ Parent is black and two children are red.

- 5: end while
- 6: n.data := x
- 7: n.color := red
- 8: while Adjacent red nodes exist do
- 9: Rotate.
- 10: end while
- 11: **if** root is red **then**
- 12: Mark root black.
- 13: end if
- 14: end function

22. Theorem (170, 171) Splay Tree:

- BST.
- · 每一次 splay 運算都將 splay 起點最終變為 root。
- Rotation 和 AVL tree 不同。
- 1: function InsertSplayTree (SplayTree s, Element x)
- 2: n := INSERTBST(x)
- 3: SPLAY(n)
- 4: end function
- 1: function SEARCHSPLAYTREE(SplayTree s, Element x)
- 2: n := SEARCHBST(x)
- 3: SPLAY(n)
- 4: end function
- 1: **function** DeleteSplayTree s, Element x)
- 2: n := SEARCHBST(x)
- 3: SPLAY(n)
- 4: Remove n and get its left and right subtrees T_L and T_R .
- 5: $max := FINDMAXBST(T_L)$
- 6: SPLAY(max)
- 7: $max.rchild := T_R$
- 8: end function

Comparison between AVL tree, B tree, and Splay tree			
	AVL tree and B tree Splay tree		
Worst	$O(\log n)$	O(n)	
Amortized	$O(\log n)$	$O(\log n)$	

Operations of AVL tree, B tree, Red-black tree, and Splay tree		
Operation	Time complexity	
Insert x		
Delete x	$O(\log_m n)$	
Search x		

23. Theorem ()

24. Theorem (172, 173, 174) Leftist heap:

 $shortest(x) = \begin{cases} 0 & , x \text{ is external node} \\ 1 + \min\{shortest(x.lchild), shortest(x.rchild)\} \end{cases}, x \text{ is internal node}$

(8)

- $\forall n \in \text{leftist tree}$, $shortest(n.lchild) \geq shortest(n.rchild)$.
- Min(Max)-leftist heap: leftist tree and min(max)-tree.
- -n 個節點的 leftist tree, root 距離 $\leq \log(n+1) = 1$.

1: function MergeLeftistHeap s, t)

- 2: **if** s.data < t.data) **then**
- 3: MERGELEFTISTHEAP(s.rchild, t)
- 4: else
- 5: MERGELEFTISTHEAP(t.rchild, s)
- 6: end if
- 7: Check the *shortest* value of each node, if breaking the rule, swap the node and its sibling.
- 8: end function

1: **function** DeltetMinLeftistHeap (LeftistHeap s)

- 2: Remove root and get its left and right subtrees T_L and T_R .
- 3: MERGELEFTISTHEAP (T_L, T_R)
- 4: end function

- 1: **function** InsertLeftistHeap (LeftistHeap s, Element x)
- 2: Let x be a tree n.
- 3: MERGELEFTISTHEAP(s, n)
- 4: end function

Comparison between heap and leftist heap			
Operation Heap Leftist heap			
Insert x	$O(\log n)$		
Delete min	$O(\log n)$		
Merge one or two heaps	O(n)	$O(\log n)$	

25. Theorem (174, 175, 176) Binomial heap:

- root level 為 0。
- B_k 為高度為 k 的 binomial tree,由兩個高度 k-1 的 B_{k-1} 組成,其中 B_0 只有 root 一個節點。
- B_k 第 ilevel 的節點數為 $\binom{k}{i}$, 總共 2^k 個節點。
- Binomial heap: 一組 binomial tree 且皆為 min-tree 組成的 forest。
- 1: function MergeBinomialHeap (BinomialHeap s, t)
- 2: Merge all trees with same height recursively by choosing the smaller root as new root.
- 3: end function
- 1: **function** DELETEMINBINOMIALHEAP(BinomialHeap s)
- 2: Delete the smallest root from tree p and get new trees u, and the others are q.
- 3: MERGEBINOMIALHEAP(q, u)
- 4: end function
- 1: **function** InsertBinomialHeap s, Element x)
- 2: Let x be a tree n.
- 3: MergeBinomialHeap(s, n)
- 4: end function

26. Theorem (179) Fibonacci heap:

• Binomial heap 的 superset,又稱 Extended binomial heap。

- 比 binomial heap 多 DeleteNode 和 DecreaseKey。
- 與 binomial heap 差異:
 - insert 與 delete 皆不合併。
 - 所有節點用一個 double-linked circular linked list 連結起來,同時紀錄左右兄弟、父節點。
 - DecreaseKey 若使該節點小於其父節點,則將該子樹獨立出來。

Comparison between binomial heap and Fibonacci heap				
Operation	Binomial heap	Fibonacci heap		
Insert x	$O(\log n), O(1)^*$	$O(1)^*$		
Delete x/\min	$O(\log n)$	$O(\log n)^*$		
Merge	$O(\log n)$	Q(1)*		
Decrease key	$O(\log n)$	O(1)*		
Find min	$O(\log n)$	O(1)		
Remark	Find min can be	Decrease key is faster		
Ttemark	down to $O(1)$.	than binomial heap		

27. Theorem (184, 188, 190, 192, 195, 200, 203, 206, 208, 210, 213) Sorting:

- Internal/External sorting:
 - Internal sorting: 一次在 memory sorting。
 - External sorting: 資料量太大, 無法一次 sorting, 例如 Merge sort + selection tree, *m*-way search tree。
- Shell sort 使用 insertion sort。
- 基於 comparison 的 sorting algorithm time complexity 上限 $\Omega(nlogn)$,因為有 n! 種排序,生成 decision tree 高度 $\geq n\log n$ 。
- Quick sorting:

```
1: function QuickSort(Array A, index p, r) \triangleright Sorting from A[p] to A[r]
2: if p < r then
3: q := \text{Partition}(A, p, r)
4: QuickSort(A, p, q - 1)
5: QuickSort(A, q + r)
6: end if
7: end function
```

```
1: function Partition(Array A, index p, r)
       x := A[r]
                                                                                    ▷ Pivot.
2:
       i := p - 1
3:
4:
       for j := p to r - 1 do
          if A[j] \leq x then
5:
              i := i + 1
6:
              SWAP(A[i], A[j])
7:
          end if
8:
       end for
9:
10:
       SWAP(A[r], A[i+1])
11:
       return i+1
12: end function
```

- Slection tree: 分 Winner/Loser tree, time complexity 皆為 $O(n \log k)$,但後者比較次數較少,只需要跟父節點比較。
- Heap sort:

```
\triangleright s[1\cdots n]
1: function HEAPSORT(Array s, length n)
       for i := \lceil \frac{n}{2} \rceil to 1 do
                                                                                      ▷ Build heap.
2:
           Adjust Heap(s, i, n)
3:
       end for
4:
       for i := n - 1 to 1 do
5:
           SWAP(s[1], s[i+1])
                                                                  ▷ Swap root and the last node.
6:
           AdjustHeap(s, 1, i)
7:
       end for
9: end function
```

• Counting sort: 若位數較大,從個位開始一個個位數做 counting sort,輸出作為下一輪的輸入。

28. Theorem ()

Comparison between sorting methods					
Method	Time complexity		Space complexity	Stable	
Meniod	Best	Worst	Average	Space complexity	Stable
Insertion	O(n)	$O(n^2)$		O(1)	
Selection		$O(n^2)$		O(1)	×
Bubble	O(n)	$O(n^2)$		O(1)	
Shell	$O(n^{1.5})$	$O(n^2)$		O(1)	×
Quick	$O(n \log n)$	$O(n^2)$	$O(n \log n)$	$O(n\log n) \sim O(n)$	×
Merge	$O(n \log n)$		O(n)		
Heap	$O(n \log n)$		O(1)	×	
LSD Radix	$O(n \times k)$		O(n+k)		
Bucket/MSD Radix	O(n)	$O(n^2)$	O(n+k)	$O(n \times k)$	
Counting	O(n+k)				

29. Theorem (221, 223, 224, 225, 227) Hashing:

• 若 T 為所有 identifier 個數,n 為目前使用的 identifier 個數, $B \times S$ 為 hash table size,則

identifier density =
$$\frac{n}{T}$$
loading density = $\frac{n}{B \times S} = \alpha$
(9)

- Perfect hashing function: 保證無 collision。
- Uniform hashing function: 使資料量 n 大致平均分布在所有 B 個 bucket, 每個 bucket 內資料量大約 $\frac{n}{B}=\alpha$, 則
 - 成功搜尋平均比較次數為 $\frac{1+2+\cdots+\alpha}{\alpha} = \frac{1+\alpha}{2} \approx 1 + \frac{\alpha}{2}$ 。
 - 失敗搜尋平均比較次數為 α。
- Hash function design:
 - Middle square: 平方後取中間適當位數值。
 - Division:

$$H(x) = x \% M$$
 s.t. M is prime $\land M \nmid (r^k \pm \alpha), \ k, a$ are small integers (10)

- Folding addition:
 - * Shift: 切成相同長度的片段,再將所有片段相加。
 - * Boundary: 切成相同長度的片段,將偶數片段反過來,再將所有片段相加。

- Digits analysis: 分析每個位數分布情況,若集中,則捨棄該位數,反之選擇該位數。
- Linear probing: 易發生 primary clustering problem,即相同 hashing address 的 data 易儲存在附近,增加 searching time。
- Quadratic probing: Overflow 發生時, 改變 hashing function 為

$$(H(x) \pm i^2) \% B, \forall i = 1, 2, \cdots, \lceil \frac{B-1}{2} \rceil$$
 (11)

其中 B 為 bucket 數,i 找到有空 bucket 或是所有格皆滿為止。解決 primary clustering problem,但易發生 secondary clustering problem,即相同 hashing address 的 data overflow probe 的位置距規律性,增加 searching time。

• Double hashing: Overflow 發生時, 改變 hashing function 為

$$(H(x) + i \times H'(x)) \% B, \forall i = 1, 2, \cdots$$

 $H'(x) = R - (x \% R), R \text{ is prime}$
(12)

其中 B 為 bucket 數, i 找到有空 bucket 或是所有格皆滿為止。解決 secondary clustering problem,但不保證 table 充分利用。

- Rehashing: 提供一系列 hashing functions, 一個個試, 直到有空 bucket 或是所有格皆滿為止。
- 除了 chain 是 close addressing mode, 其他皆是 open addressing mode。

30. Theorem (233, 236, 240) Graph:

- Adjacency multilists: 每個節點儲存 v_i , v_j , $link_for_v_i$ 指向 v_i 下一個相鄰的點所在的節點, $link_for_v_j$ 指向 v_j 下一個相鄰的點所在的節點。
- 無向圖只有 tree edge 和 back edge。判斷無向圖 back edge (cycle):兩個點都 gray,但是不為父子節點。

Operation	Adjacency matrix	Adjacency lists
Lots of vertices		
# of edges or		$\sqrt{(O(V + E))}$
if it's connected, etc.		$\left[\begin{array}{cc} V & (O(V + E)) \\ \end{array}\right]$

Data structure	DFS	BFS
Adjacency matrix	$O(V ^2)$	
Adjacency lists	O(V	+ E)

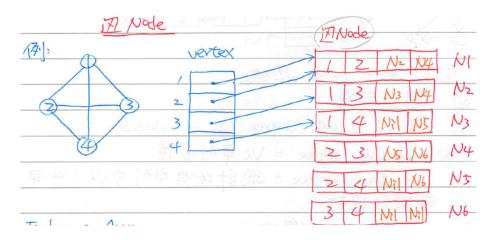


Figure 1: Example for adjacency multilists.

31. Theorem (257) 尋找 articulation point:

• dfn 為 DFS number。

 $low(v) = \begin{cases} dfn(v) \\ \min\{low(u)|u \text{ is child of } v\} \\ dfn(u), u \text{ is descendant of } v, \text{ which is reachable by a back edge} \end{cases}$

• 若 root 有 ≥ 2 子節點,則 root 為 articulation point;非 root 節點 u,若 $\exists v$ 為 u 子 節點,且 $low(v) \geq dfn(u)$,則 u 為 articulation point。

 $,\forall v\in G$

(13)

References

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