# Convex Optimization 10-725, Lecture 30: Optimization for Sampling.

#### Yuanzhi Li

Assistant Professor, Carnegie Mellon University Visiting Researcher, Microsoft Research

Today

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• We have been focusing on minimizing function f(x) under different conditions.

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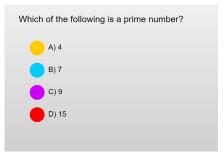
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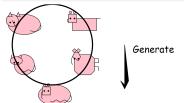
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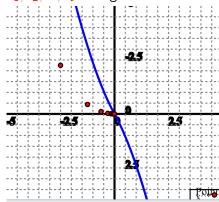
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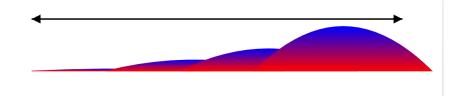
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- Can we create a sequence of distributions  $q_t$  that gets closer and closer to the target distribution  $q^*$ , where  $q_0$  is some simple distribution (such as standard Gaussian)?
- We will talk about the so-called diffusion approach.

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- We first create a sequence that starts from  $q^*$ , and make it get closer and closer to standard Gaussian as we increase t.
- We then reverse the process to go from Gaussian to  $q^*$ .

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- Starting from  $X_0 \sim q^*$ , we can apply: ( $B_t$  is the brownian motion, you can think  $dB_t$  as adding independent, standard Gaussian noise.)

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- Theorem (classical result): As  $t \to \infty$ , the distribution of  $X_t \to \mathcal{N}(0, I)$ .
- In fact, we even know the explicit form:  $(\gamma \sim \mathcal{N}(0, I))$  is the standard Gaussian)

$$X_t = e^{-t}X_0 + \sqrt{1 - e^{-2t}}\gamma$$

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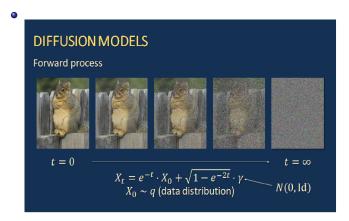
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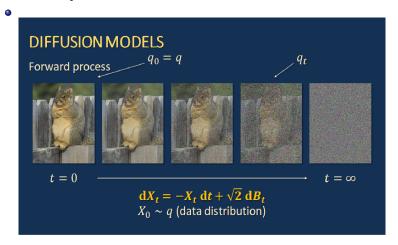
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By Fokker–Planck equation:

More generally, if

 $d\mathbf{X}_{t} = \mu(\mathbf{X}_{t}, t) dt + \sigma(\mathbf{X}_{t}, t) d\mathbf{W}_{t}$ 

where  $\mathbf{X}_t$  and  $\boldsymbol{\mu}(\mathbf{X}_t,t)$  are N-dimensional random vectors,  $\boldsymbol{\sigma}(\mathbf{X}_t,t)$  is an  $N \times M$  matrix and  $\mathbf{W}_t$  is an M-dimensional standard Wiener process, the probability density  $\boldsymbol{p}(\mathbf{x},t)$  for  $\mathbf{X}_t$  satisfies the Fokker-Planck equation

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with drift vector  $\boldsymbol{\mu}=(\mu_1,\ldots,\mu_N)$  and diffusion tensor  $\mathbf{D}=\frac{1}{2}\boldsymbol{\sigma}\boldsymbol{\sigma}^\mathsf{T}$ , i.e.

$$D_{ij}(\mathbf{x}, t) = \frac{1}{2} \sum_{k=1}^{M} \sigma_{ik}(\mathbf{x}, t) \sigma_{jk}(\mathbf{x}, t).$$

Let  $q_t(X)$  be the density function of  $X_t$ , then we have: for every X,

$$\frac{\partial q_t(X)}{\partial t} := \langle \nabla, Xq_t(X) \rangle + \langle \nabla^2 q_t(X), E \rangle$$

Here E is the all one matrix.  $\nabla$  is taken w.r.t. X

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Look at Fokker-Planck equation again

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 We know that the backward process is a stochastic process with  $(Y_t \sim p_t)$ 

$$dY_t = Y_t + 2\nabla \ln p_t(Y_t)dt + \sqrt{2}dB_t$$

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• This is due to

$$2\nabla \ln p_t(Y) = \frac{2\nabla p_t(Y)}{p_t(Y)}$$

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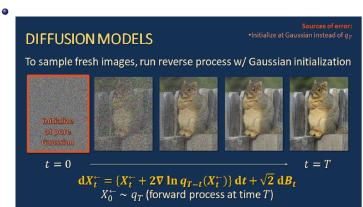
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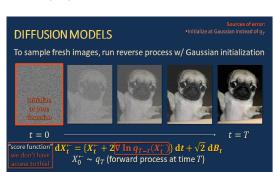
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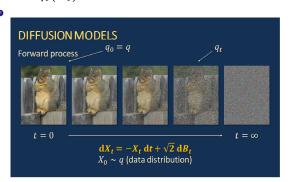
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• Remark:  $(\nabla \cdot \mathbf{s})(e^{-t}X_0 + \sqrt{1 - e^{-2t}}\gamma)$  means we compute the value of  $\nabla \cdot \mathbf{s}$  at the point  $X_t = (e^{-t}X_0 + \sqrt{1 - e^{-2t}}\gamma)$ .

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Statement of the lemma [edit]

Suppose X is a normally distributed random variable with expectation  $\mu$  and variance  $\sigma^2$ . Further suppose g is a function for which the two expectations  $E(g(X)(X - \mu))$  and E(g'(X)) both exist. (The existence of the expectation of any random variable is equivalent to the finiteness of the expectation of its absolute value.) Then

 $E(g(X)(X - \mu)) = \sigma^{2}E(g'(X)).$ 

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• Eventually, we know that we would like to minimize:

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Which is equivalent to:

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Where  $X_0 \sim q^*$  is sampled from the target distribution.

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• (2). Then use the backward diffusion process to sample  $Y_T$ : starting from  $Y_0 \sim \mathcal{N}(0, I)$  and

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# **DIFFUSION MODELS** Reverse process (in practice) t = 0t = Tk = |t/h|