

MAT1120

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## 4.1 Vector spaces and subspaces

### Theory

#### Vector Space

**Definition 1** A vector space is a nonempty set  $V$  of objects, called vectors, on which are defined two operations, called addition and multiplication by scalars (real numbers), subject to the ten axioms listed below. The axioms must hold for all vectors  $\mathbf{u}, \mathbf{v}$  and  $\mathbf{w}$  in  $V$  and for all scalars  $c$  and  $d$ .

1. The sum of  $u$  and  $v$ , denoted by  $\mathbf{u} + \mathbf{v}$ , is in  $V$
2.  $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$
3.  $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$
4. There is a zero vector  $\vec{0}$  in  $V$  such that  $\mathbf{u} + \mathbf{0} = u$
5. For each  $\mathbf{u}$  in  $V$ , there is a vector  $-\mathbf{u}$  in  $V$  such that  $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$
6. The scalar multiple of  $u$  by  $c$  denoted by  $c\mathbf{u}$  is in  $V$
7.  $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$
8.  $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$
9.  $c(d\mathbf{u}) = (cd)\mathbf{u}$
10.  $1\mathbf{u} = \mathbf{u}$

**Definition 2** A subspace of a vector space  $V$  is a subset  $H$  of  $V$  that has three properties:

- The zero vector of  $V$  is in  $H$
- $H$  is closed under vector addition. That is, for each  $\mathbf{u}$  and  $\mathbf{v}$  in  $H$ , the sum  $\mathbf{u} + \mathbf{v}$  is in  $H$
- $H$  is closed under multiplication by scalars. That is, for each  $\mathbf{u}$  in  $H$  and each scalar  $c$ , the vector  $c\mathbf{u}$  is in  $H$

**Theorem 1** If  $\vec{v}_1, \dots, \vec{v}_n \in V$  then  $\text{span}\{\vec{v}_1, \dots, \vec{v}_n\}$  is a subspace of  $V$

### Exercises

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Let  $W$  be the set of all vectors of the form  $\begin{pmatrix} s + 3t \\ s - t \\ 2s - t \\ 4t \end{pmatrix}$ . Show that  $W$  is a subspace of  $\mathbb{R}^4$ .

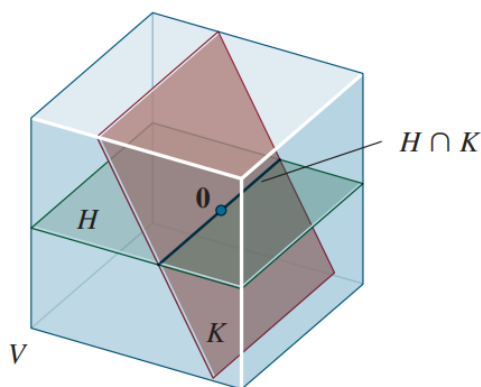
We can split  $W$  up into a sum of other vectors.

$$\begin{pmatrix} s+3t \\ s-t \\ 2s-t \\ 4t \end{pmatrix} = s \begin{pmatrix} 1 \\ 1 \\ 2 \\ 0 \end{pmatrix} + t \begin{pmatrix} 3 \\ -1 \\ -1 \\ 4 \end{pmatrix}$$

$$W = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ -1 \\ -1 \\ 4 \end{pmatrix} \right\} \rightarrow ?? \text{ says } W \text{ is a subspace of } \mathbb{R}^4$$

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Let  $H$  and  $K$  be subspaces of a vector space  $V$ . The intersection of  $H$  and  $K$ , written  $H \cap K$  is a subspace of  $V$ . Give an example in  $\mathbb{R}^2$  to show that the union of two subspaces is not, in general, a subspace



Figur 1

The intersection of the two planes creates a line going across the x-axis which we already know is a subspace of both  $\mathbb{R}^3$  and  $\mathbb{R}^2$ . Same goes for all straight lines going through origin. The union of two subspaces, (lets use the x and y-axis) will often create vectors outside the subspace, thus not being closed by addition. If we take a vector from the x-axis and a vector from the y-axis and add them together, they will create a vector outside both axis.

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Determine if  $\mathbf{y}$  is in the subspace of  $\mathbb{R}^4$  spanned by the columns of  $A$ , where

$$\mathbf{y} = \begin{pmatrix} -4 \\ -8 \\ 6 \\ -5 \end{pmatrix}, \quad A = \begin{pmatrix} 3 & -5 & -9 \\ 8 & 7 & -6 \\ -5 & -8 & 3 \\ 2 & -2 & -9 \end{pmatrix}$$

We can divide  $A$  into three vectors where each one is a column in  $A$ . If these three vectors can form a linear combination which can create  $\mathbf{y}$  (in other words,  $\mathbf{y}$  is in the span of these vectors), then  $\mathbf{y}$  will be in the subspace of  $\mathbb{R}^4$  spanned by the columns of  $A$ . To test this we append the vector  $\mathbf{y}$  to the end of  $A$  and then reduce it to row echelon form. As seen above

```
ans = 4x4
    1.0000    0    0   -0.2000
    0    1.0000    0   -0.4000
    0    0    1.0000    0.6000
    0    0    0    0
```

Figur 2: Results using matlab

the equation has a solution which means  $\mathbf{y}$  is in the subspace of  $\mathbb{R}^4$  spanned by the columns of  $A$ .

## 4.2 Null Spaces, Column Spaces, Row Spaces, and Linear Transformations

### Theory

#### The Null Space of a Matrix

**Definition 3** The null space of an  $m \times n$  matrix  $A$ , written as  $\text{Nul } A$ , is the set of all solutions of the homogenous equation  $A\mathbf{x} = \mathbf{0}$ . In set notation,

$$\text{Nul } A = \{\mathbf{x} : \mathbf{x} \text{ is in } \mathbb{R}^n \text{ and } A\mathbf{x} = \mathbf{0}\}$$

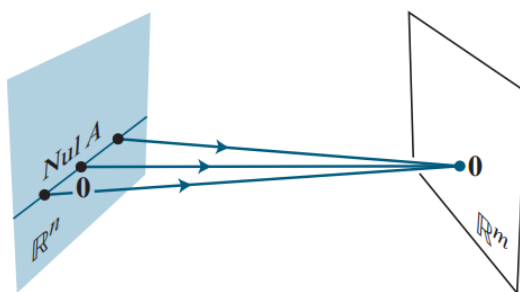


Figure 3: Visualization of the subspace (in this case a line) formed by the null space of  $A$

**Theorem 2** The null space of an  $m \times n$  matrix  $A$  is a subspace of  $\mathbb{R}^n$ . Equivalently, the set of all solutions to a system  $A\mathbf{x} = \mathbf{0}$  of  $m$  homogeneous linear equations in  $n$  unknowns is a subspace of  $\mathbb{R}^n$ .

### The Column Space of a Matrix

**Definition 4** The Column space of an  $m \times n$  matrix  $A$ , written as  $\text{Col } A$ , is the set of all linear combinations of the columns of  $A$ . If  $A = [\mathbf{a}_1 \dots \mathbf{a}_n]$ , then

$$\text{Col } A = \text{Span} = \{\mathbf{a}_1 \dots \mathbf{a}_n\}$$

**Theorem 3** The column space of an  $m \times n$  matrix  $A$  is a subspace of  $\mathbb{R}^n$ .

### Exercises

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Find the explicit definition of  $\text{Nul } A$  by listing vectors that span the null space.

$$A = \begin{bmatrix} 1 & -6 & 4 & 0 \\ 0 & 0 & 2 & 0 \end{bmatrix}$$

We start by reducing it to echelon form multiplying by  $\mathbf{x}$  and set as equal to the zero vector.

$$A\mathbf{x} = \mathbf{0}$$

$$\text{rref}(A) = \begin{bmatrix} 1 & -6 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -6 & 4 & 0 \\ 0 & 0 & 2 & 0 \end{bmatrix} \mathbf{x} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\mathbf{x} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\text{Nul } A = \text{span} \left\{ \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right\}$$

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Let  $H = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$  and  $K = \text{Span}\{\mathbf{v}_3, \mathbf{v}_4\}$ , where

$$\mathbf{v}_1 = \begin{pmatrix} 5 \\ 3 \\ 8 \end{pmatrix}, \mathbf{v}_2 = \begin{pmatrix} 1 \\ 3 \\ 4 \end{pmatrix}, \mathbf{v}_3 = \begin{pmatrix} 2 \\ -1 \\ 5 \end{pmatrix}, \mathbf{v}_4 = \begin{pmatrix} 0 \\ -12 \\ -28 \end{pmatrix}$$

Then  $H$  and  $K$  are subspaces of  $\mathbb{R}^3$ . In fact,  $H$  and  $K$  are planes in  $\mathbb{R}^3$  through origin, and they intersect in a line through  $\mathbf{0}$ . Find a nonzero vector  $\mathbf{w}$  that generates that line. [Hint:  $\mathbf{w}$  can be written as  $c_1\mathbf{v}_1 + c_2\mathbf{v}_2$  and also as  $c_3\mathbf{v}_3 + c_4\mathbf{v}_4$ . To build  $\mathbf{w}$ , solve the equation  $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 = c_3\mathbf{v}_3 + c_4\mathbf{v}_4$  for the unknown  $c_j$ 's]