

Point Cloud

Concepts, tools and technologies

Vincent Picavet, 2016

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#### Introduction

#### Oslandia

Open Source GIS Expertise

Training

Development

Consulting

Support

### Technologies

QGIS, PostGIS (core committers)

PDAL, pgpointcloud

Business applications C++/Python



# Working Environment

git clone https://github.com/Oslandia/workshop-pointcloud

#### Environnement

Slides: supports.ods

WS: README.md

Ubuntu virtual machine (Virtualbox)

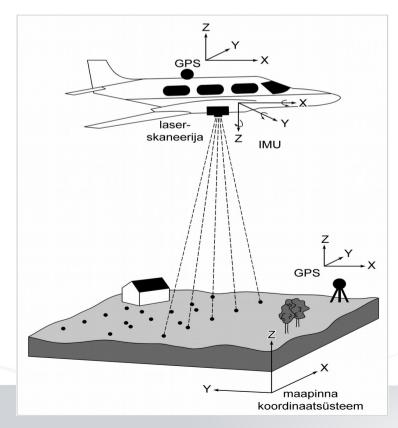


# LIDAR: Light Detection And Ranging (1)

Ground or embedded sensor (plane, car, ...)

More than 100 000 pulses per second

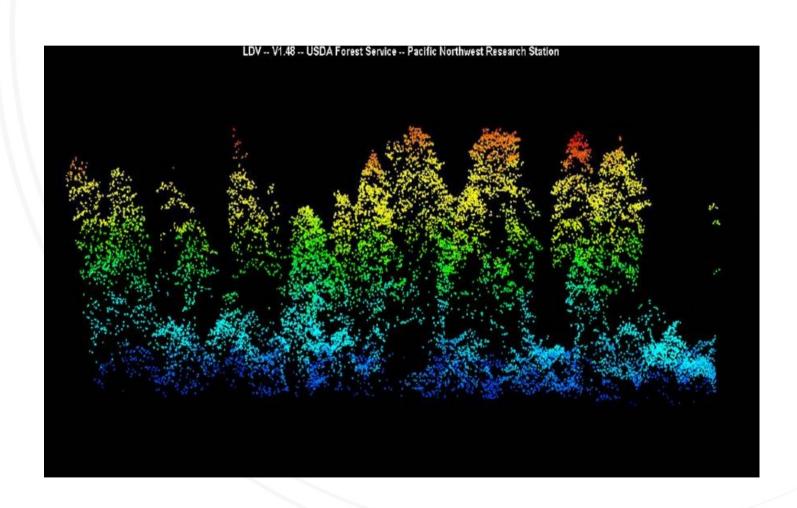
Reflected pulses (vegetation, buildings, ground, ...) are caught by the scanner





# LIDAR: Light Detection And Ranging (2)

Waveform analysis: we keep a "return" for each main intensity peak (threshold)



$$z = \frac{t * c}{2}$$

#### LAS

# Public file format for the interchange of point cloud data Specifications

http://www.asprs.org/committee-general/laser-las-file-formatexchange-activities.html

HEADER

VARIABLE LENGHT RECORDS

POINT DATA RECORDS

### LAZ: compressed version of LAS (public format)

https://www.cs.unc.edu/~isenburg/lastools/download/laszip.pdf



### LAStools/libLAS

#### Tools to work with LAS files

https://github.com/LAStools

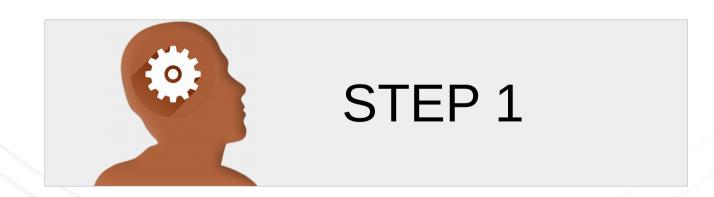
https://github.com/libLAS/libLAS





#### Which one?

http://www.liblas.org/lastools.html



#### **PostGIS**

#### Each point of the cloud is georeferenced

natural will to store points in a spatial database!

#### Database

PostgreSQL: ORDBMS, libre, possibility of adding new data type, operators, functions, ...

PostGIS: add support for geographic objects to PostgreSQL





# pgpointcloud (1)

## A point cloud

may contains several billions of points

... where each point can be represented by more than 10 dimensions



Store each point one by one in a database is unthinkable!

# pgpointcloud (2)

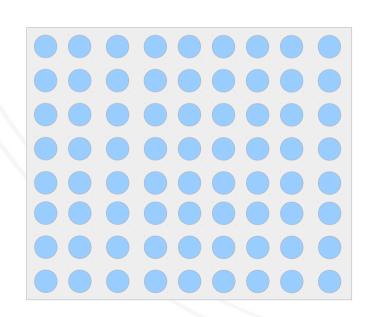
### pgpointcloud

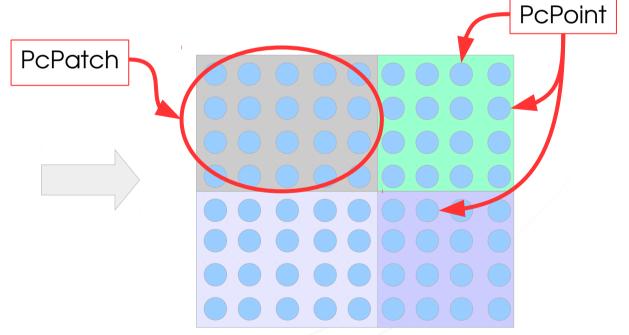
https://github.com/pgpointcloud/pointcloud

PotgreSQL extension for storing point cloud data

Organizes points by patch to reduce the size of the table stored in the

database!





# pgpointcloud (3)

#### Schema

Takes care of the variability of points' format

XML Document

Stored within the pointcloud\_formats table

```
INSERT INTO pointcloud_formats (pcid, srid, schema) VALUES (1, 4326,
'<?xml version="1.0" encoding="UTF-8"?>
<pc:PointCloudSchema xmlns:pc="http://pointcloud.org/schemas/PC/1.1"
    xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance">
  <pc:dimension>
    <pc:position>1</pc:position>
    <pc:size>4</pc:size>
    <pc:description>X coordinate as a long integer. You must use the
                    scale and offset information of the header to
                    determine the double value.</pc:description>
    <pc:name>X</pc:name>
    <pc:interpretation>int32_t</pc:interpretation>
    <pc:scale>0.01</pc:scale>
  </pc:dimension>
  <pc:dimension>
    <pc:position>2</pc:position>
    <pc:size>4</pc:size>
    <pc:description>Y coordinate as a long integer. You must use the
                    scale and offset information of the header to
                    determine the double value.</pc:description>
    <pc:name>Y</pc:name>
    <pc:interpretation>int32_t</pc:interpretation>
    <pc:scale>0.01</pc:scale>
```



## pgpointcloud (4)

### Patch compression

None, dimensional, GHT or LAZ

Defined in the XML schema

```
<pc: metadata>
  <Metadata name="compression">dimensional</Metadata>
</pc: metadata>
```

#### Dimensional compression

Well-suited for small patches (low variability)

Each dimension of a PcPatch uses it's own dimensional compression algorithm (RLE, ZLIB, SIGBITS)

```
int
pc_dimstats_update(PCDIMSTATS *pds, const PCPATCH_DIMENSIONAL *pdl)
```

### PDAL(1)

#### Point Data Abstraction Library

Command line tools

Allows to work with point cloud (reading, filtering, writing,...)

#### Pipeline

Sequence of operations for building a processing chain

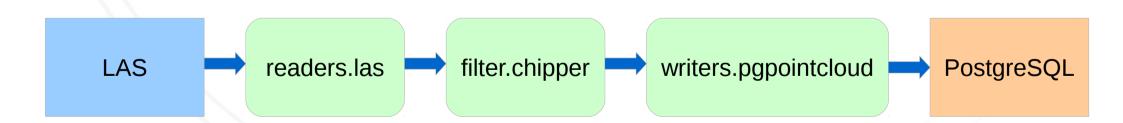
JSON format since v1.2 (XML for earlier version)



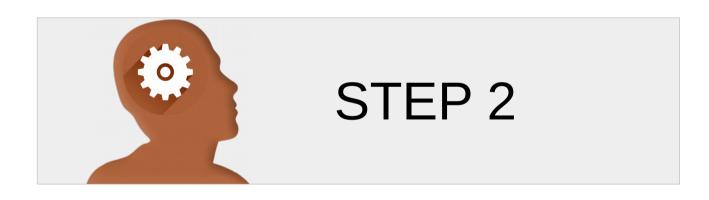
### PDAL (2)

#### Example:

```
{
"pipeline": [
    "/home/vpi/data/auvergne/lidarverne/opendata.craig.fr/opendata/lidar/agglos/2013_clermont-ferrand/clermont.las",
    {
        "type":"filters.chipper",
        "capacity":"1000"
    },
    {
        "type":"writers.pgpointcloud",
        "connection":"dbname='foss4g' user='postgres' port='5433'",
        "table":"lidar",
        "compression":"dimensional",
        "srid":"2154"
    }
}
```

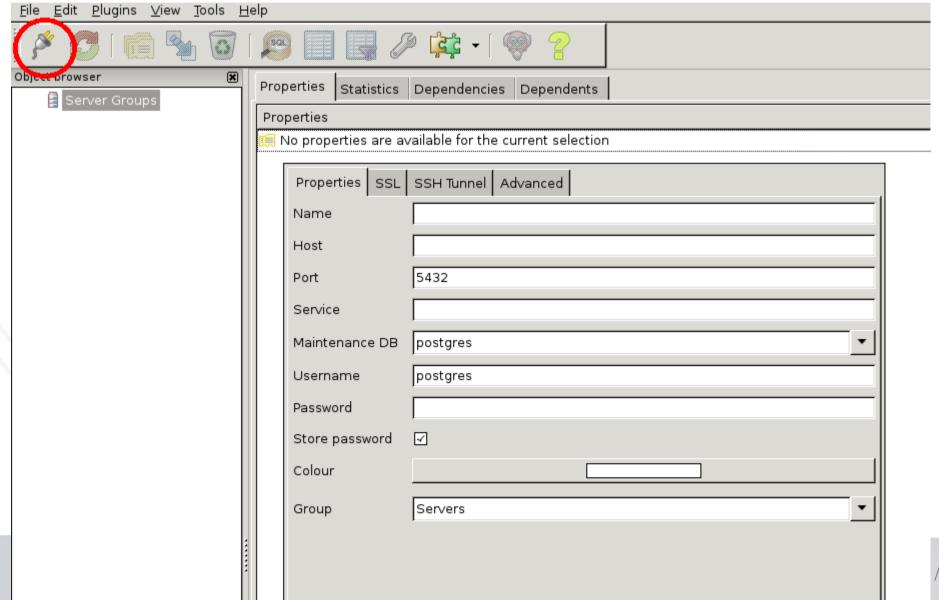


# PDAL (3)



# pgAdmin (1)

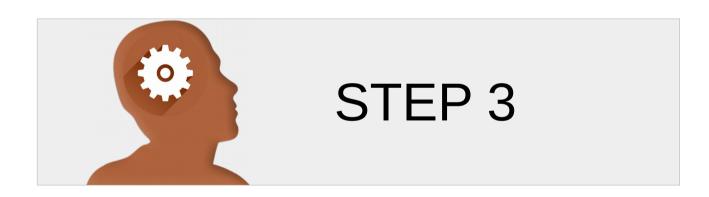
### GUI to work with PostgreSQL





# pgAdmin (2)





# **QGIS (1)**

#### GIS Software:

Libre

Cross-platform

C++, Python plugins



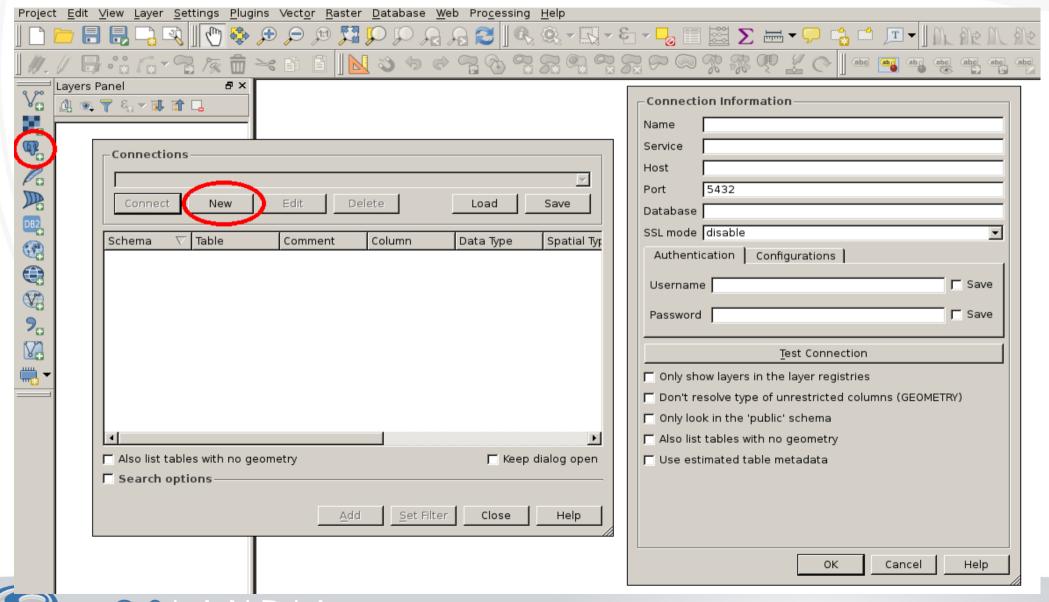
#### QGIS with point cloud??

Connexion with spatial databases like PostGIS

Knows what a PcPatch is!

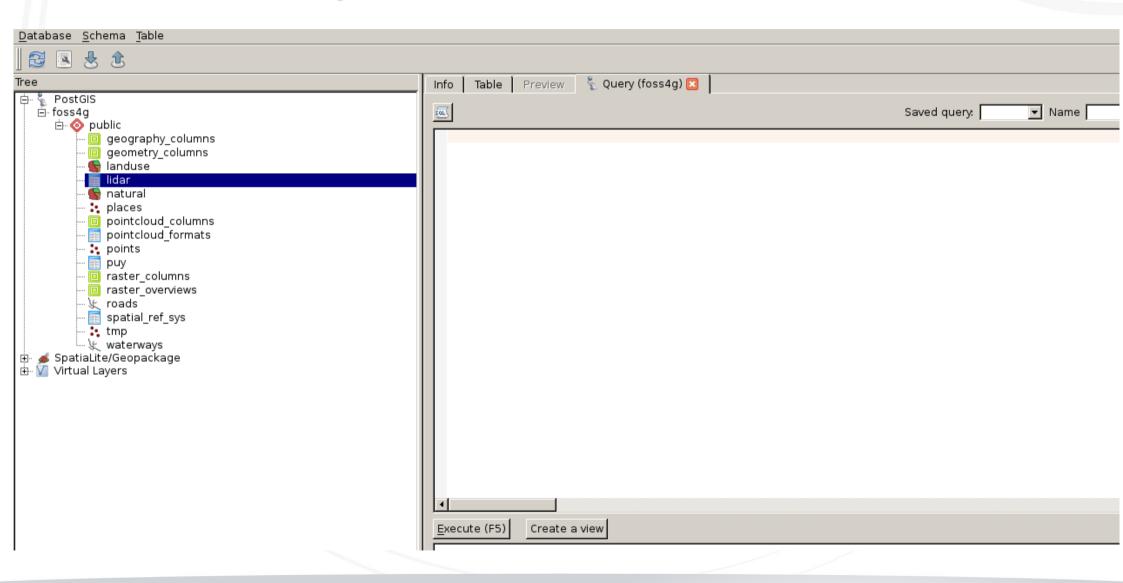
### QGIS (2)

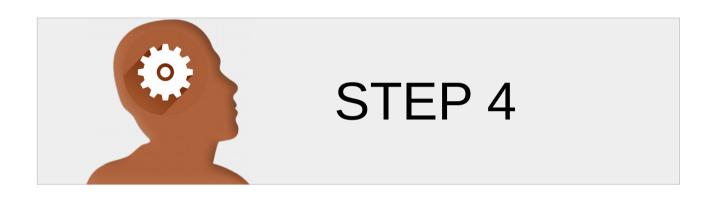
#### Add PostGIS layer



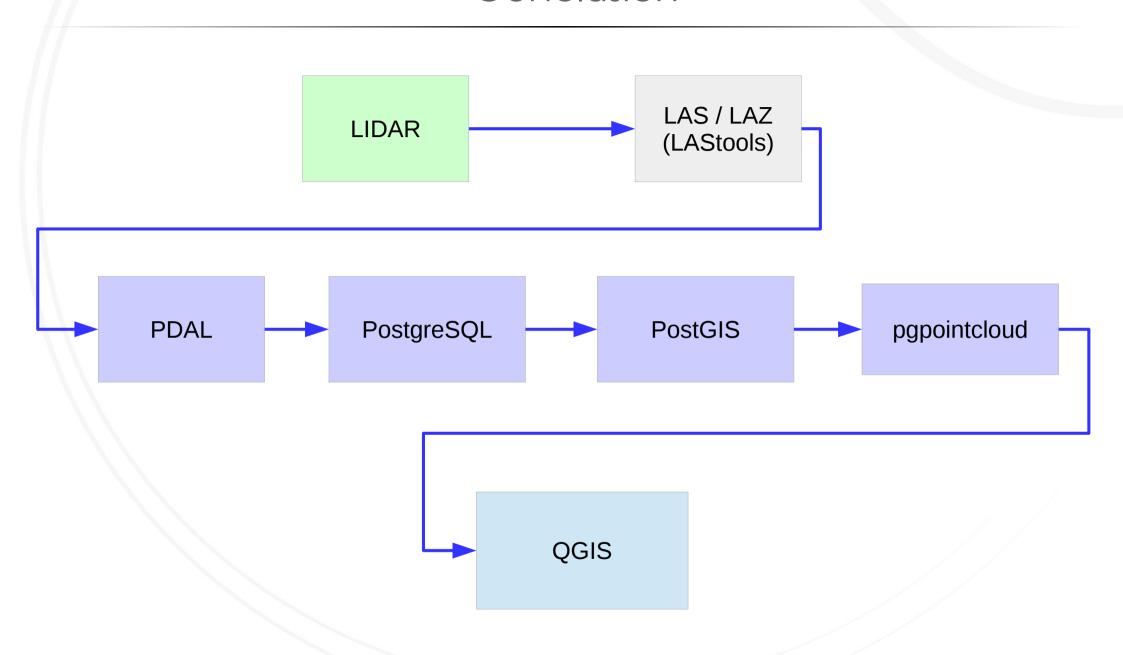
## **QGIS (3)**

## Database Manager:





#### Conclusion



# Questions

