



## Point Cloud

## Concepts, tools and technologies

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# Plan

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# Introduction

## Oslandia

Open Source GIS Expertise

Training

Development

Consulting

Support

## Technologies

QGIS, PostGIS (core committers)

PDAL, PGPointCloud

Business applications C++/Python

# Working Environment

```
git clone https://github.com/Oslandia/workshop-pointcloud
```

## Environnement

Slides : *supports.ods*

WS : *README.md*

Ubuntu virtual machine (Virtualbox)

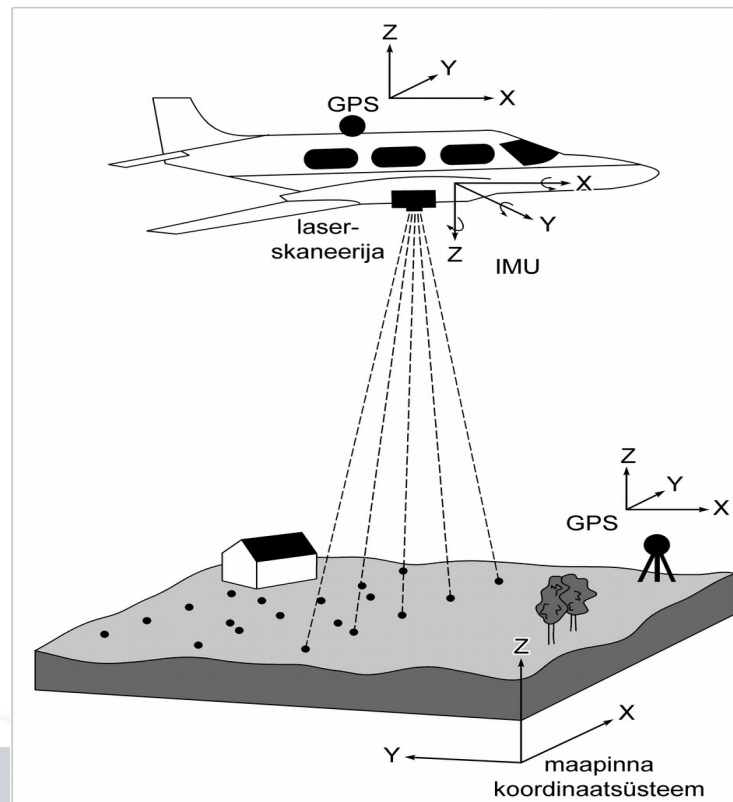


# LIDAR : Light Detection And Ranging (1)

Ground or embedded sensor (plane, car, ...)

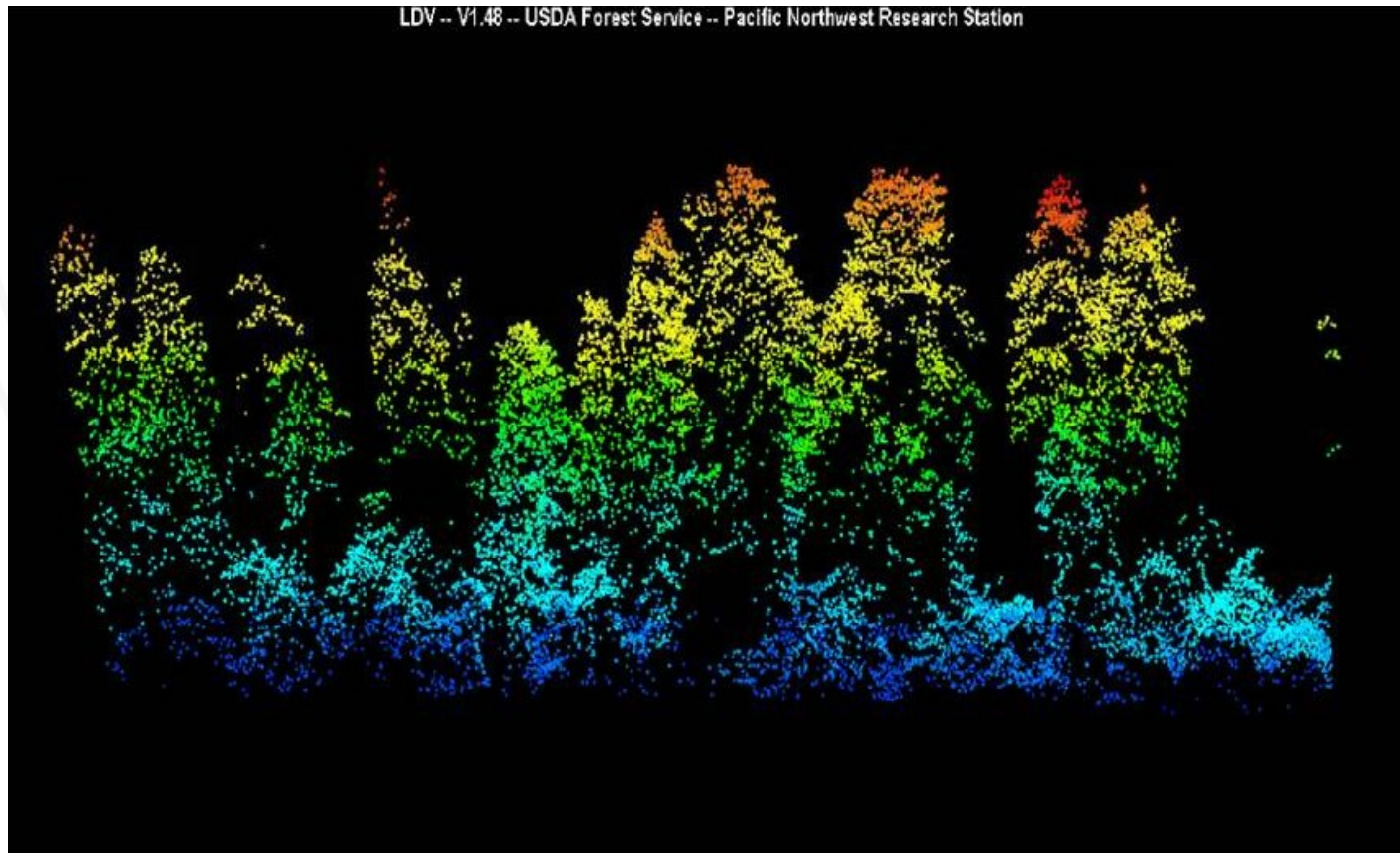
More than 100 000 pulses per second

Reflected pulses (vegetation, buildings, ground, ...) are caught by the scanner



# LIDAR : Light Detection And Ranging (2)

Waveform analysis: we keep a “return” for each main intensity peak (threshold)



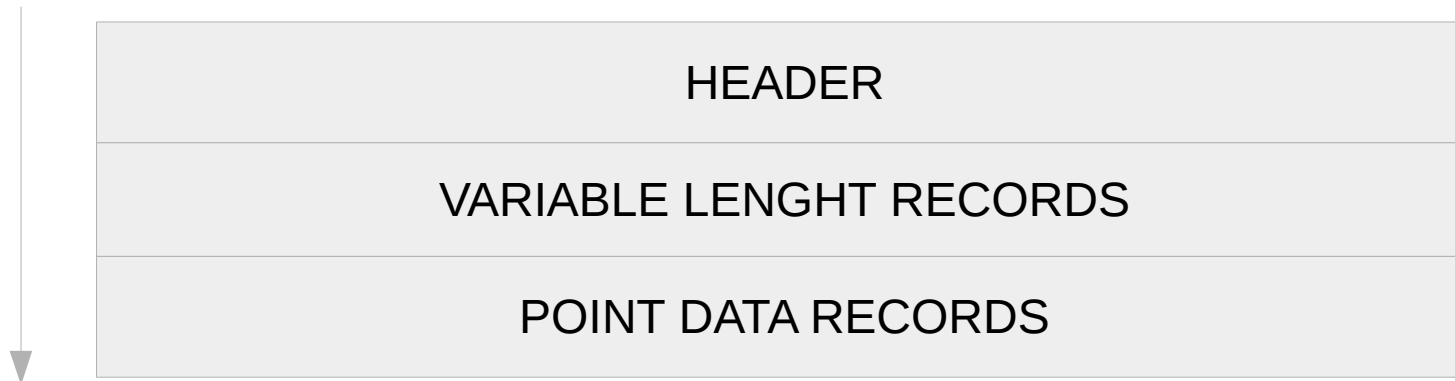
$$z = \frac{t * c}{2}$$



Public file format for the interchange of point cloud data

## Specifications

<http://www.asprs.org/committee-general/laser-las-file-format-exchange-activities.html>



LAZ: compressed version of LAS (public format)

<https://www.cs.unc.edu/~isenburg/lastools/download/laszip.pdf>

## Tools to work with LAS files

<https://github.com/LAStools>

<https://github.com/libLAS/libLAS>



## Which one ?

<http://www.liblas.org/lastools.html>





Each point of the cloud is georeferenced

natural will to store points in a spatial database!

## Database

PostgreSQL : ORDBMS, libre, possibility of adding new data type, operators, functions, ...

PostGIS : add support for geographic objects to PostgreSQL



## A point cloud

may contains several billions of points

... where each point can be represented by more than 10 dimensions



Store each point one by one in a database is unthinkable!

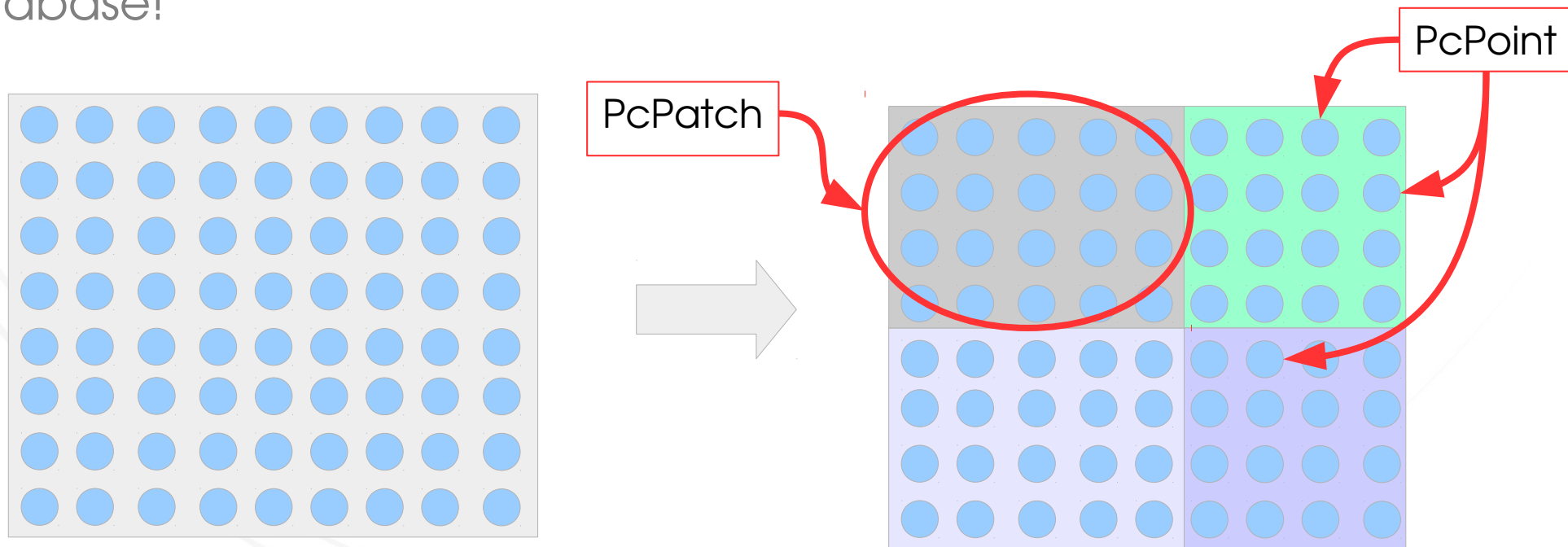
# PGPointcloud (2)

## PGPointcloud

<https://github.com/pgpointcloud/pointcloud>

PotgreSQL extension for storing point cloud data

Organizes points by patch to reduce the size of the table stored in the database!



# PGPointcloud (3)

## Schema

Takes care of the variability of points' format

XML Document

Stored within the *pointcloud\_formats* table

```
INSERT INTO pointcloud_formats (pcid, srid, schema) VALUES (1, 4326,
'<?xml version="1.0" encoding="UTF-8"?>
<pc:PointCloudSchema xmlns:pc="http://pointcloud.org/schemas/PC/1.1"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance">
  <pc:dimension>
    <pc:position>1</pc:position>
    <pc:size>4</pc:size>
    <pc:description>X coordinate as a long integer. You must use the
                        scale and offset information of the header to
                        determine the double value.</pc:description>
    <pc:name>X</pc:name>
    <pc:interpretation>int32_t</pc:interpretation>
    <pc:scale>0.01</pc:scale>
  </pc:dimension>
  <pc:dimension>
    <pc:position>2</pc:position>
    <pc:size>4</pc:size>
    <pc:description>Y coordinate as a long integer. You must use the
                        scale and offset information of the header to
                        determine the double value.</pc:description>
    <pc:name>Y</pc:name>
    <pc:interpretation>int32_t</pc:interpretation>
    <pc:scale>0.01</pc:scale>
```

## Patch compression

None, dimensional, GHT or LAZ

Defined in the XML schema

```
<pc:metadata>  
  <Metadata name="compression">dimensional</Metadata>  
</pc:metadata>
```

## Dimensional compression

Well-suited for small patches (low variability)

Each dimension of a PcPatch uses it's own dimensional compression algorithm (RLE, ZLIB, SIGBITS)

```
int  
pc_dimstats_update(PCDIMSTATS *pds, const PCPATCH_DIMENSIONAL *pdl)
```



## Point Data Abstraction Library

Command line tools

Allows to work with point cloud (reading, filtering, writing,...)

## Pipeline

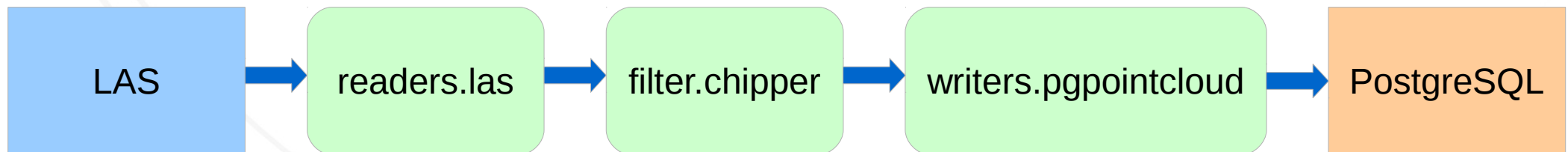
Sequence of operations for building a processing chain

JSON format since v1.2 (XML for earlier version)



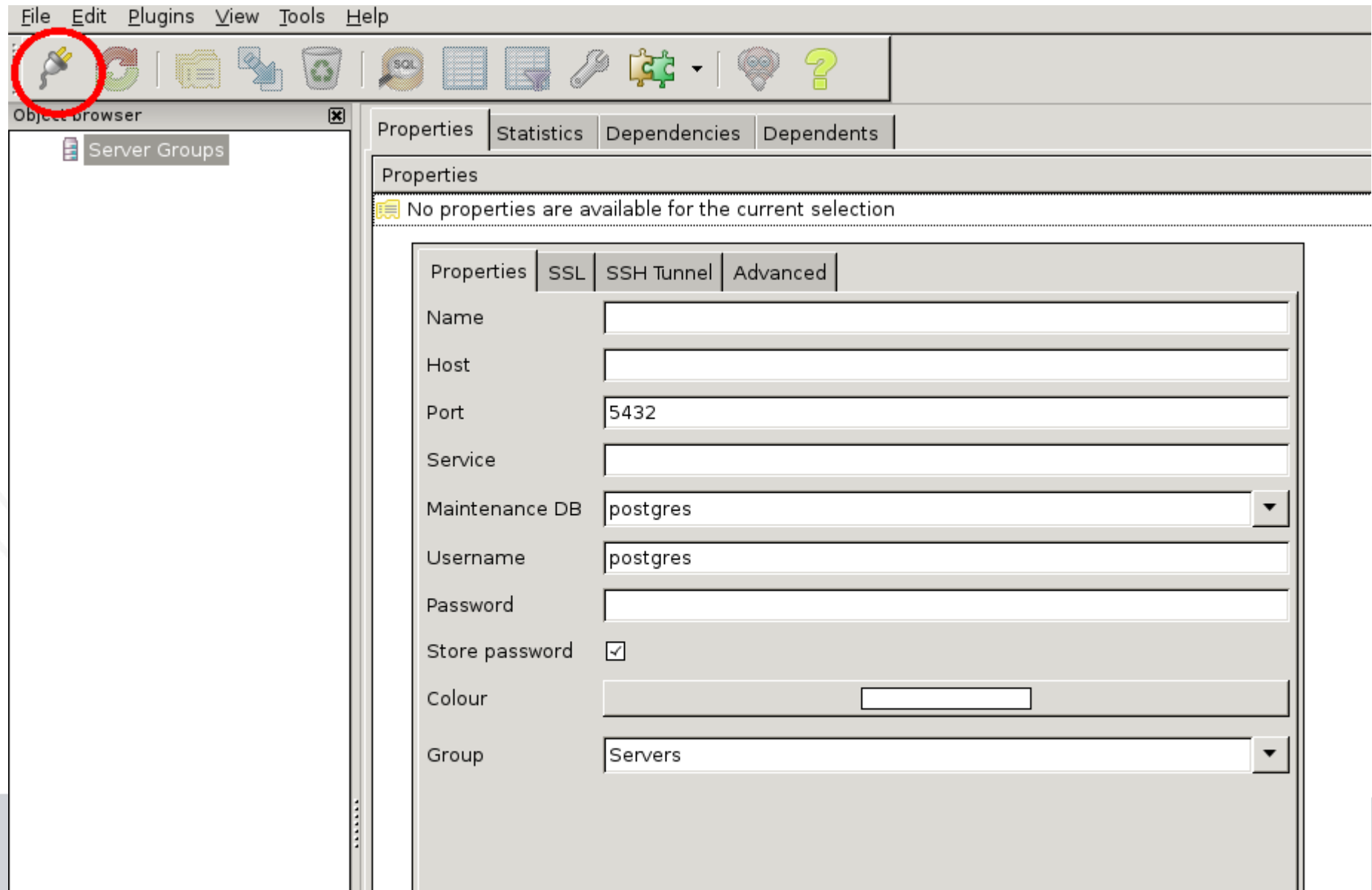
## Example :

```
{
  "pipeline": [
    "/home/vpi/data/auvergne/lidarverne/.opendata.craig.fr/.opendata/lidar/agglos/2013_clermont-ferrand/clermont.las",
    {
      "type": "filters.chipper",
      "capacity": "1000"
    },
    {
      "type": "writers.pgpointcloud",
      "connection": "dbname='foss4g' user='postgres' port='5433'",
      "table": "lidar",
      "compression": "dimensional",
      "srid": "2154"
    }
  ]
}
```



# PgAdmin (1)

## GUI to work with PostgreSQL





# PgAdmin (2)



## GIS Software :

Libre

Cross-platform

C++, Python plugins



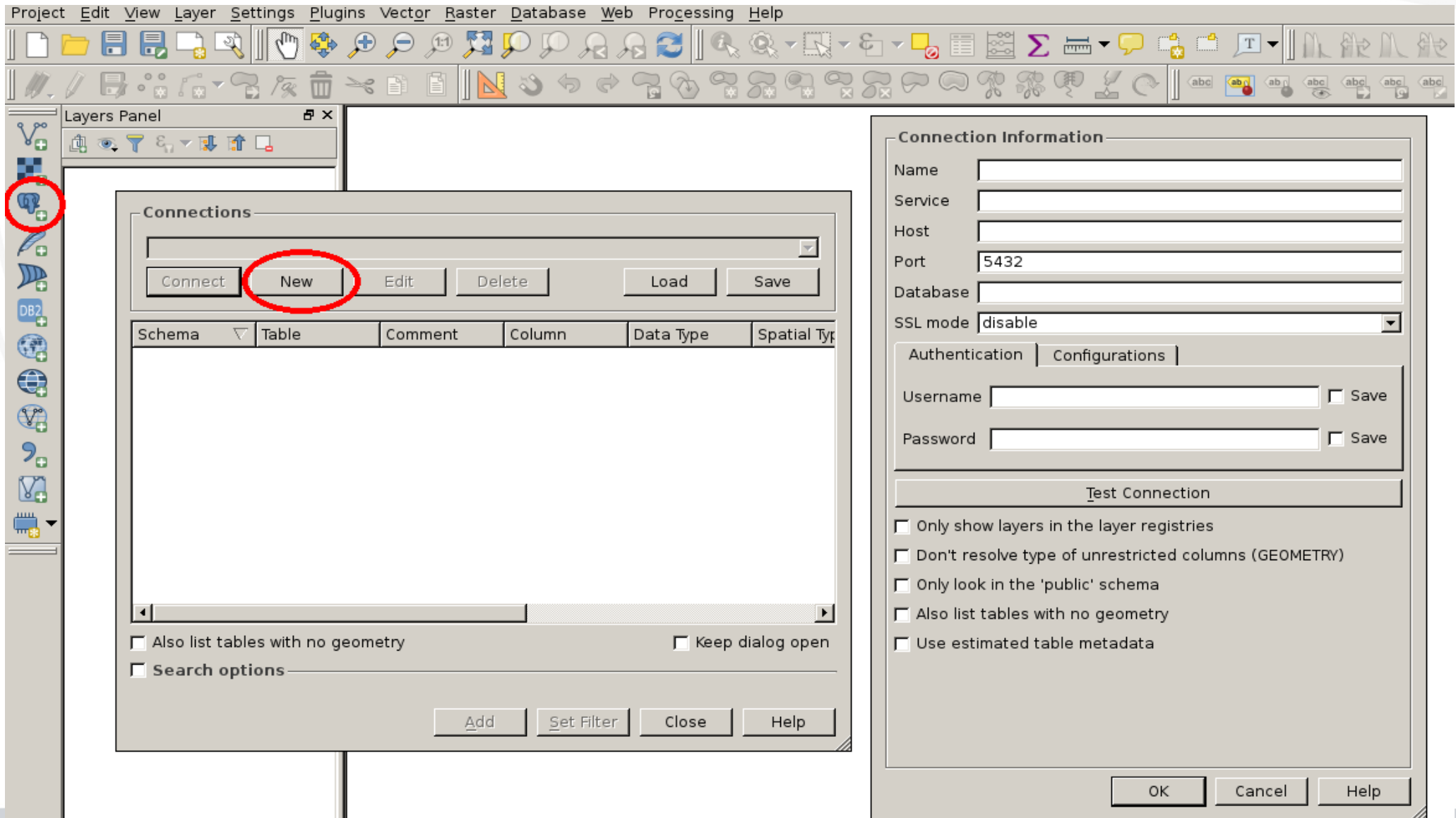
## QGIS with point cloud??

Connexion with spatial databases like PostGIS

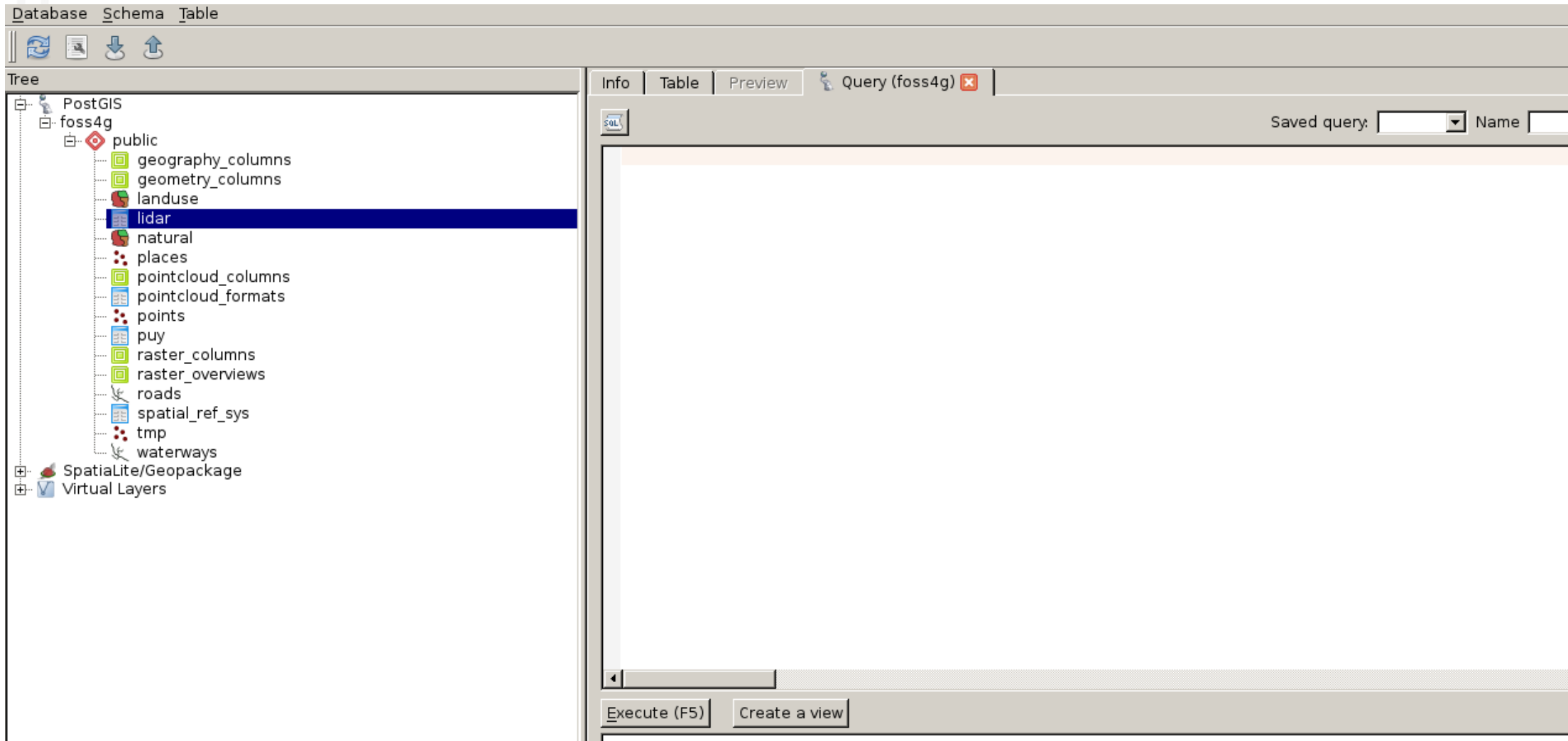
Knows what a PcPatch is!

# QGIS (2)

## Add PostGIS layer



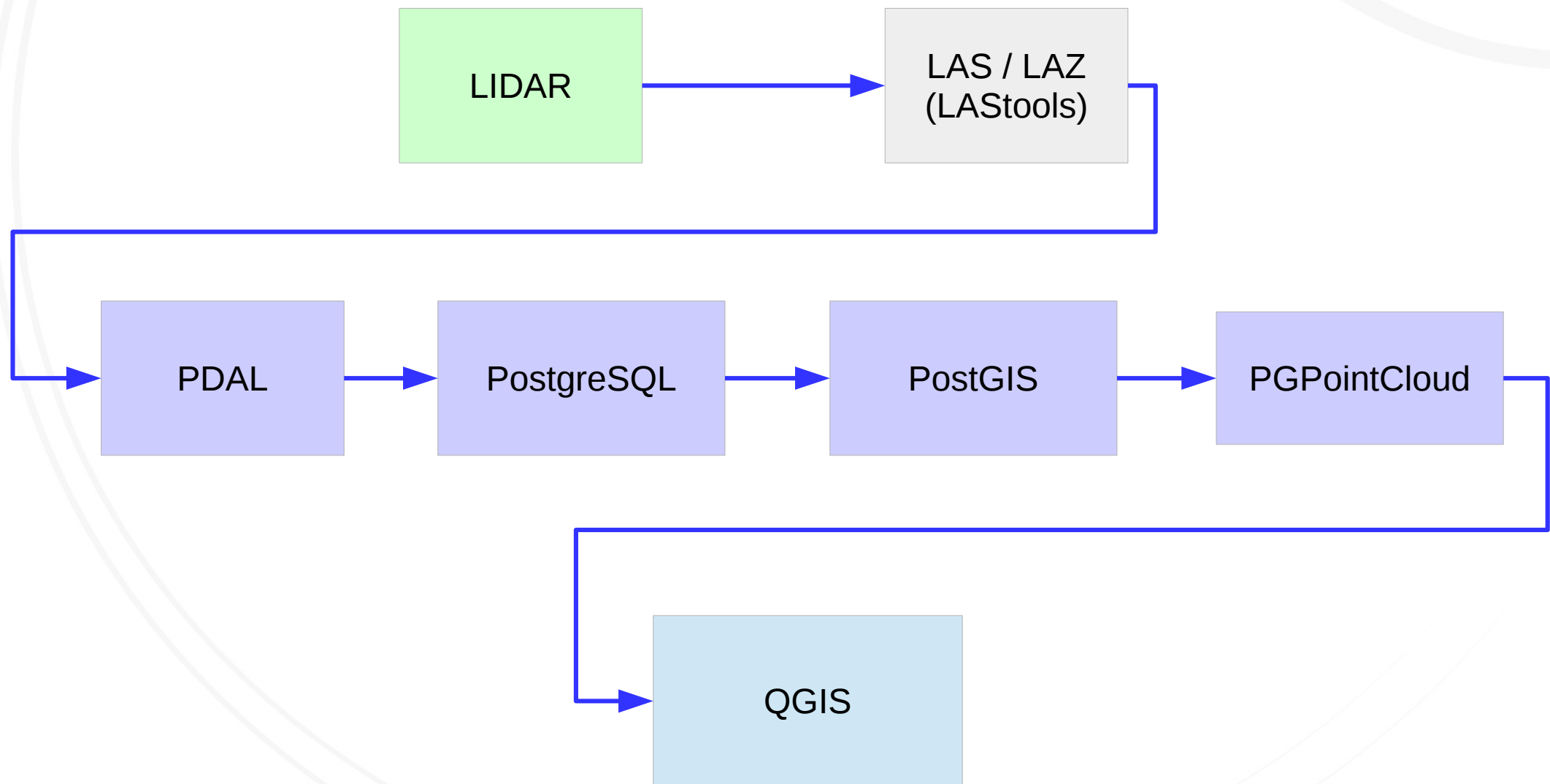
## Database Manager :





**STEP 3**

# Conclusion



# Questions

