



# Modeling and Designing High Permittivity Pads for MRI

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# Outline

- Dielectric pads
- Volume Integral Equation
- Different Discretization schemes
- Designing pads
- Perturbing Maxwell's equations
- Reduced order modeling



accuracy

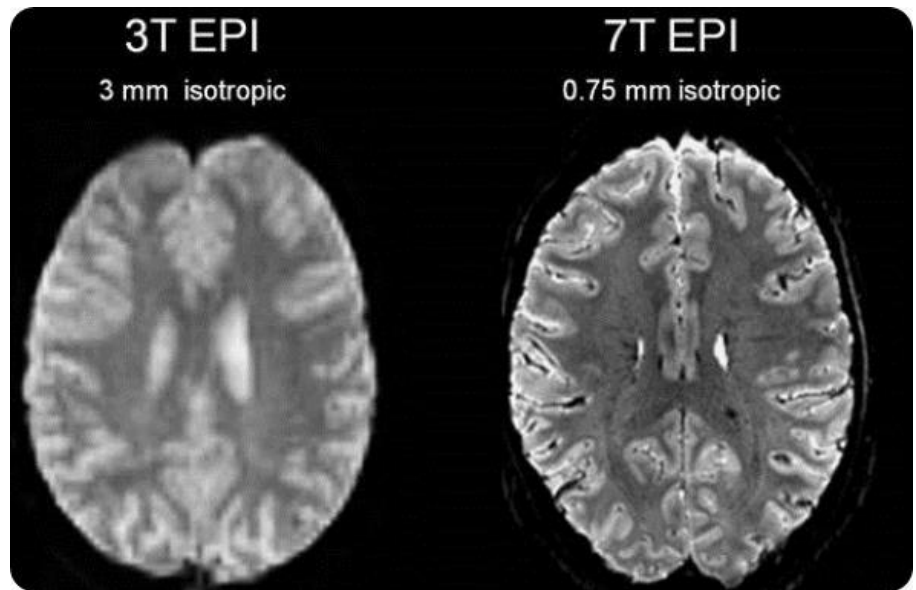


speed

# Introduction

## Magnetic Resonance Imaging (MRI)

$$\frac{S}{N} \propto B_0$$



[www.neurensics.com/technische-specificaties](http://www.neurensics.com/technische-specificaties)

<http://www.news-medical.net>

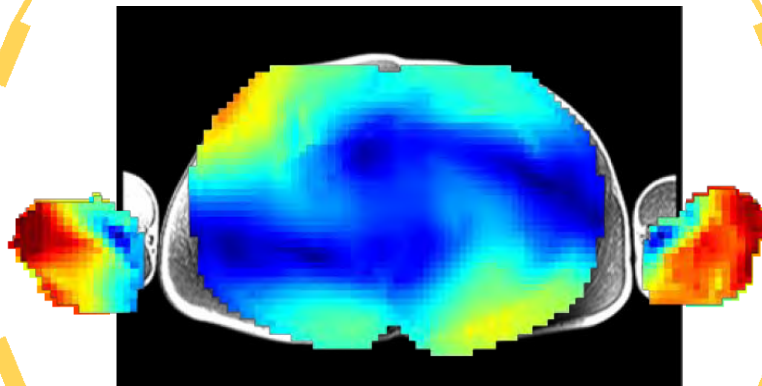
# Dielectric $B_1^+$ shimming

## Magnetic Resonance Imaging (MRI)

| $B_0$ | $f_L$   |
|-------|---------|
| 1.5 T | 64 MHz  |
| 3.0 T | 128 MHz |
| 7.0 T | 300 MHz |



high permittivity  
dielectric pad



135T



*de Heer et al., Magn Res Med, 68(4), 1317-24, 2012.*

# Challenges

## In Numerical Modeling

- Strong (localized) inhomogeneities in medium parameters
- Large computational domain due to the body model
- Accurate for low resolution!
- Fast!

# Maxwell's Equations

How to solve them?

$$-\nabla \times \mathbf{H} + \sigma \mathbf{E} + j\omega \epsilon \mathbf{E} = -\mathbf{J}^{\text{ext}}$$
$$\nabla \times \mathbf{E} + j\omega \mu \mathbf{H} = \mathbf{0}$$

Different discretization methods possible:

- Finite element method
- Finite difference method
- Method of Moments (or volume integral equation (VIE) approach)



Global approach instead of local

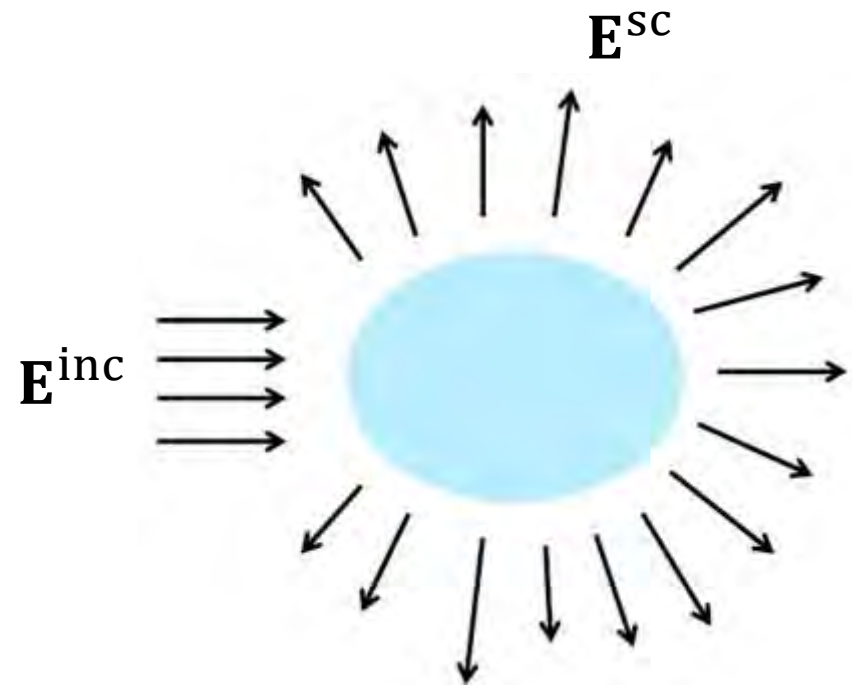
Efficient for problems with a small contrast domain

# The Volume Integral Equation

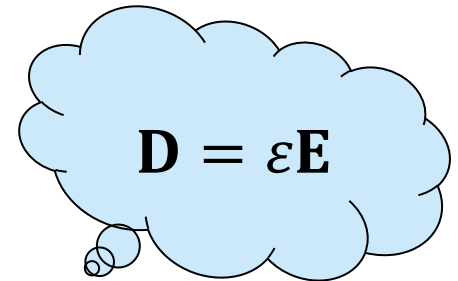
$$\mathbf{E} = \mathbf{E}^{\text{inc}} + \mathbf{E}^{\text{sc}}$$

$$\mathbf{E} = \mathbf{E}^{\text{inc}} + (k_b^2 + \nabla \nabla \cdot) \mathbf{S}(\chi_e \mathbf{E})$$

$$\mathbf{S}(\mathbf{J}) = \int_{\Omega} g(\mathbf{x}' - \mathbf{x}) \mathbf{J}(\mathbf{x}) d\mathbf{x}$$



# Different Formulations


$$\mathbf{D} = \varepsilon \mathbf{E}$$

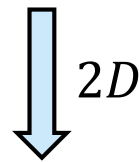
$$\text{EVIE:} \quad \mathbf{E}^{\text{inc}} = \mathbf{E} - (\mathbf{k}_b^2 + \nabla \nabla \cdot) \mathbf{S}(\chi_e \mathbf{E})$$

$$\text{DVIE:} \quad \mathbf{E}^{\text{inc}} = \frac{1}{\varepsilon} \mathbf{D} - (\mathbf{k}_b^2 + \nabla \nabla \cdot) \mathbf{S}\left(\frac{\chi_e}{\varepsilon} \mathbf{D}\right)$$



# The Volume Integral Equation

$$\mathbf{E}^{\text{inc}} = \mathbf{E} - (\mathbf{k}_b^2 + \nabla \nabla \cdot) \mathbf{S}(\chi_e \mathbf{E})$$

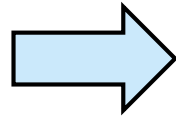


$$\begin{bmatrix} E_x^{\text{inc}} \\ E_y^{\text{inc}} \end{bmatrix} = \begin{bmatrix} E_x \\ E_y \end{bmatrix} - (\mathbf{k}_b^2 + \nabla \nabla \cdot) \begin{bmatrix} S_x(\chi_e E_x) \\ S_y(\chi_e E_y) \end{bmatrix}$$

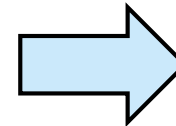
- The  $x$ - and  $y$ -components of the electric field are coupled via the  $\nabla \nabla \cdot$  operator.
- The vector potential  $\mathbf{S}$  depends on the material parameters.

# The Method of Moments

$$\mathcal{L}u = f$$

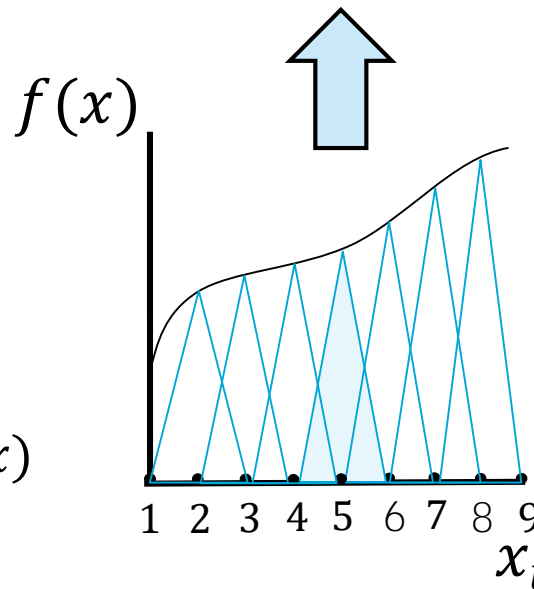


|    |    |    |    |       |
|----|----|----|----|-------|
| •  | •  | •  | •  | $n$ • |
| •  | •  | •  | •  | •     |
| •  | •  | •  | •  | •     |
| 6• | •  | •  | •  | •     |
| 1• | 2• | 3• | 4• | 5•    |



$$A\mathbf{x} = \mathbf{b}$$

1. Specify  $\varphi_i(x)$
2. Find  $f_i$  for all  $i$
3. Reconstruct  $f(x)$



$$f(x) = \sum_{i=1}^9 f_i \varphi_i(x)$$

# The Method of Moments

## Expansions

$$\begin{bmatrix} E_x^{\text{inc}} \\ E_y^{\text{inc}} \end{bmatrix} = \begin{bmatrix} E_x \\ E_y \end{bmatrix} - (k_b^2 + \nabla \nabla \cdot) \begin{bmatrix} S_x(\chi_e E_x) \\ S_y(\chi_e E_y) \end{bmatrix}$$

# The Method of Moments

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is solved via expanding

$$E_x(\mathbf{x}) = \sum_{i=1}^n e_i^x \psi_i^x(\mathbf{x})$$

$$E_y(\mathbf{x}) = \sum_{i=1}^n e_i^y \psi_i^y(\mathbf{x})$$

# The Method of Moments

## Expansions

$$\begin{bmatrix} E_x^{\text{inc}} \\ E_y^{\text{inc}} \end{bmatrix} = \begin{bmatrix} E_x \\ E_y \end{bmatrix} - (k_b^2 + \nabla \nabla \cdot) \begin{bmatrix} S_x(\chi_e E_x) \\ S_y(\chi_e E_y) \end{bmatrix}$$

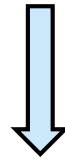
is solved via expanding

$$\begin{aligned} E_x(\mathbf{x}) &= \sum_{i=1}^n e_i^x \psi_i^x(\mathbf{x}) & S_x(\mathbf{x}) &= \sum_{i=1}^n s_i^x \psi_i^x(\mathbf{x}) \\ E_y(\mathbf{x}) &= \sum_{i=1}^n e_i^y \psi_i^y(\mathbf{x}) & S_y(\mathbf{x}) &= \sum_{i=1}^n s_i^y \psi_i^y(\mathbf{x}) \end{aligned}$$

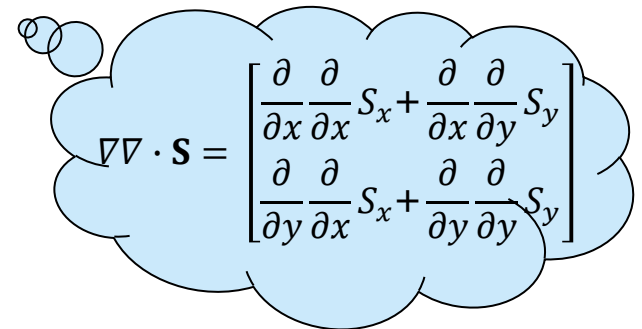
# The Method of Moments

## Expansions

$$\begin{bmatrix} E_x^{\text{inc}} \\ E_y^{\text{inc}} \end{bmatrix} = \begin{bmatrix} E_x \\ E_y \end{bmatrix} - (k_b^2 + \nabla \nabla \cdot) \begin{bmatrix} S_x(\chi_e E_x) \\ S_y(\chi_e E_y) \end{bmatrix}$$



$$\mathbf{A} \begin{bmatrix} e^x \\ e^y \end{bmatrix} = \begin{bmatrix} b^x \\ b^y \end{bmatrix}$$


$$\nabla \nabla \cdot \mathbf{S} = \begin{bmatrix} \frac{\partial}{\partial x} \frac{\partial}{\partial x} S_x + \frac{\partial}{\partial x} \frac{\partial}{\partial y} S_y \\ \frac{\partial}{\partial y} \frac{\partial}{\partial x} S_x + \frac{\partial}{\partial y} \frac{\partial}{\partial y} S_y \end{bmatrix}$$

- How do we incorporate the operator  $\mathbf{S}$  in the matrix  $\mathbf{A}$ ?
- How do we deal with the derivative terms?

# The Method of Moments

## Fast Fourier Transform

Remember,

$$\mathbf{S}(\chi_e \mathbf{E})(\mathbf{x}') = \int_{\Omega} g(\mathbf{x}' - \mathbf{x}) \chi_e(\mathbf{x}) \mathbf{E}(\mathbf{x}) d\mathbf{x} = g * \chi_e \mathbf{E}$$

And

$$\mathcal{F}\{\mathbf{S}\} = \mathcal{F}\{g * \chi_e \mathbf{E}\} = \mathcal{F}\{g\} \mathcal{F}\{\chi_e \mathbf{E}\}$$

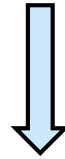
$$\Rightarrow \mathbf{S} = \mathcal{F}^{-1}\{\mathcal{F}\{g\} \mathcal{F}\{\chi_e \mathbf{E}\}\}.$$

So, use fast Fourier transform (FFT) algorithms to incorporate  $\mathbf{S}$  in the matrix  $\mathbf{A}$ !

# The Method of Moments

## Expansions

$$\begin{bmatrix} E_x^{\text{inc}} \\ E_y^{\text{inc}} \end{bmatrix} = \begin{bmatrix} E_x \\ E_y \end{bmatrix} - (k_b^2 + \nabla \nabla \cdot) \begin{bmatrix} S_x(\chi_e E_x) \\ S_y(\chi_e E_y) \end{bmatrix}$$



$$A \begin{bmatrix} e^x \\ e^y \end{bmatrix} = \begin{bmatrix} b^x \\ b^y \end{bmatrix}$$

$$\nabla \nabla \cdot \mathbf{S} = \begin{bmatrix} \frac{\partial}{\partial x} \frac{\partial}{\partial x} S_x + \frac{\partial}{\partial x} \frac{\partial}{\partial y} S_y \\ \frac{\partial}{\partial y} \frac{\partial}{\partial x} S_x + \frac{\partial}{\partial y} \frac{\partial}{\partial y} S_y \end{bmatrix}$$



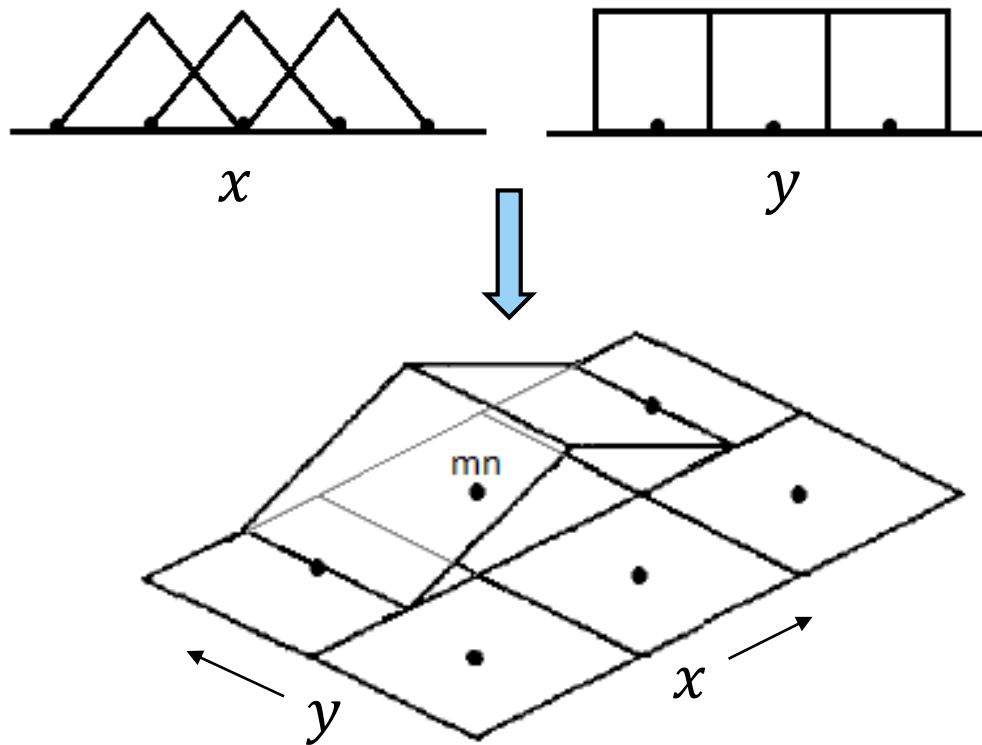
- How do we incorporate the operator  $\mathbf{S}$  in the matrix  $\mathbf{A}$ ?
- How do we deal with the derivative terms?



# The Method of Moments

## Basis Functions: Rooftop

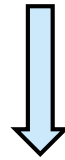
$$E_x(x) = \sum_{i=1}^n e_i^x \psi_i^x(x)$$



# The Method of Moments

## Expansions

$$\begin{bmatrix} E_x^{\text{inc}} \\ E_y^{\text{inc}} \end{bmatrix} = \begin{bmatrix} E_x \\ E_y \end{bmatrix} - (k_b^2 + \nabla \nabla \cdot) \begin{bmatrix} S_x(\chi_e E_x) \\ S_y(\chi_e E_y) \end{bmatrix}$$



$$A \begin{bmatrix} e^x \\ e^y \end{bmatrix} = \begin{bmatrix} b^x \\ b^y \end{bmatrix}$$

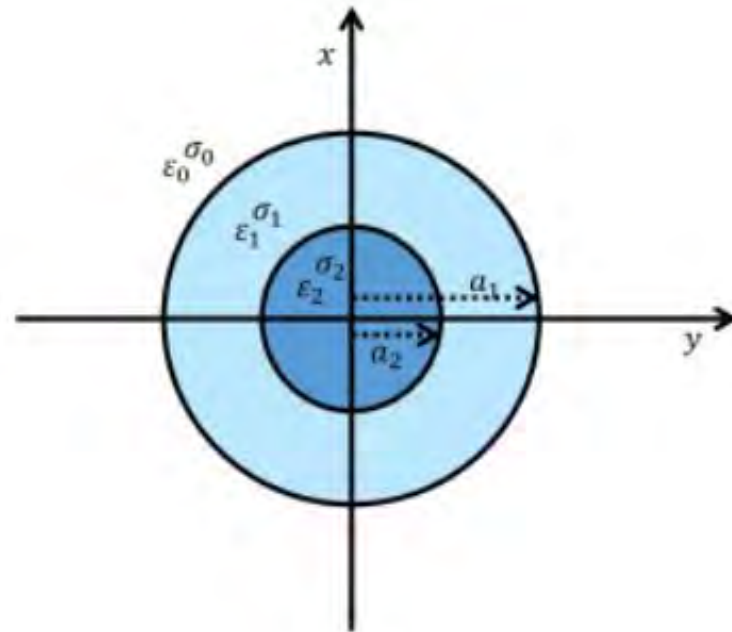
$$\nabla \nabla \cdot \mathbf{S} = \begin{bmatrix} \frac{\partial}{\partial x} \frac{\partial}{\partial x} S_x + \frac{\partial}{\partial x} \frac{\partial}{\partial y} S_y \\ \frac{\partial}{\partial y} \frac{\partial}{\partial x} S_x + \frac{\partial}{\partial y} \frac{\partial}{\partial y} S_y \end{bmatrix}$$

- ✓ • How do we incorporate the operator  $\mathbf{S}$  in the matrix  $\mathbf{A}$ ?
- ✓ • How do we deal with the derivative terms?

# Benchmark Problem

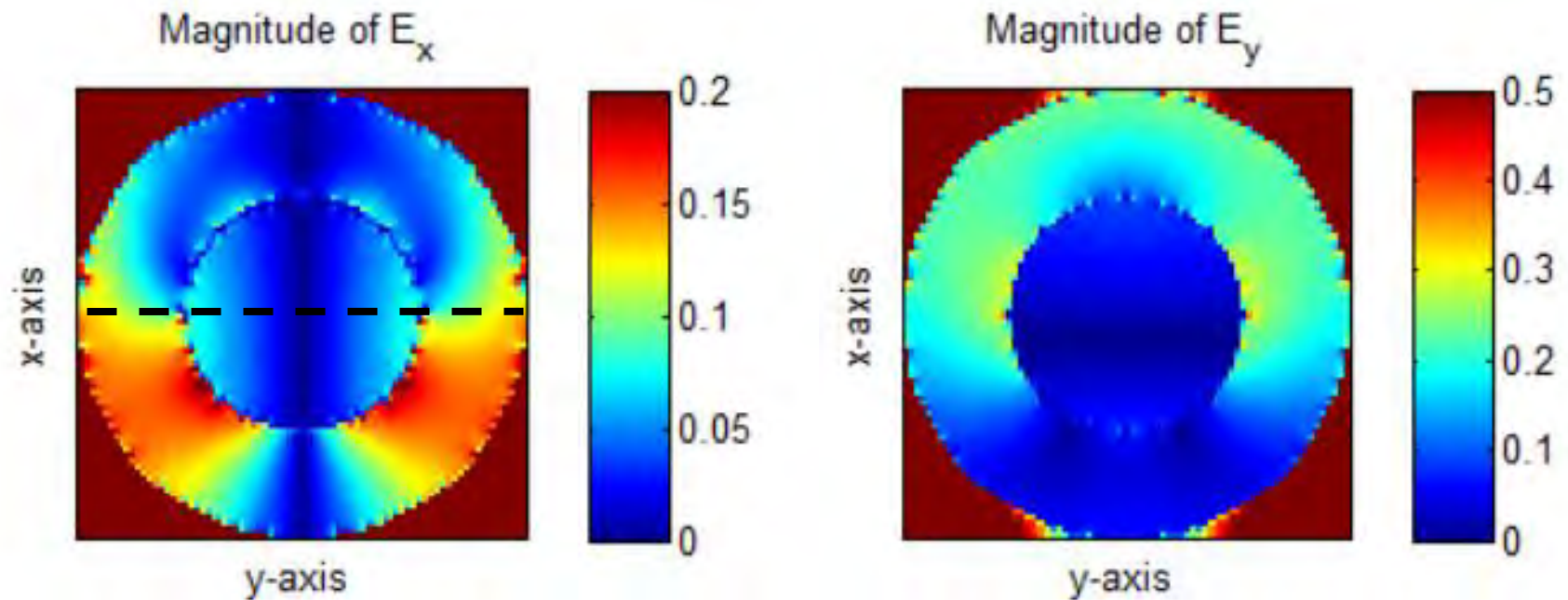
## Scattering on a Two-Layer Conducting Cylinder

- TE-polarization
- $f = 100$  MHz
- Plane wave incident field
- Muscle/fat tissue



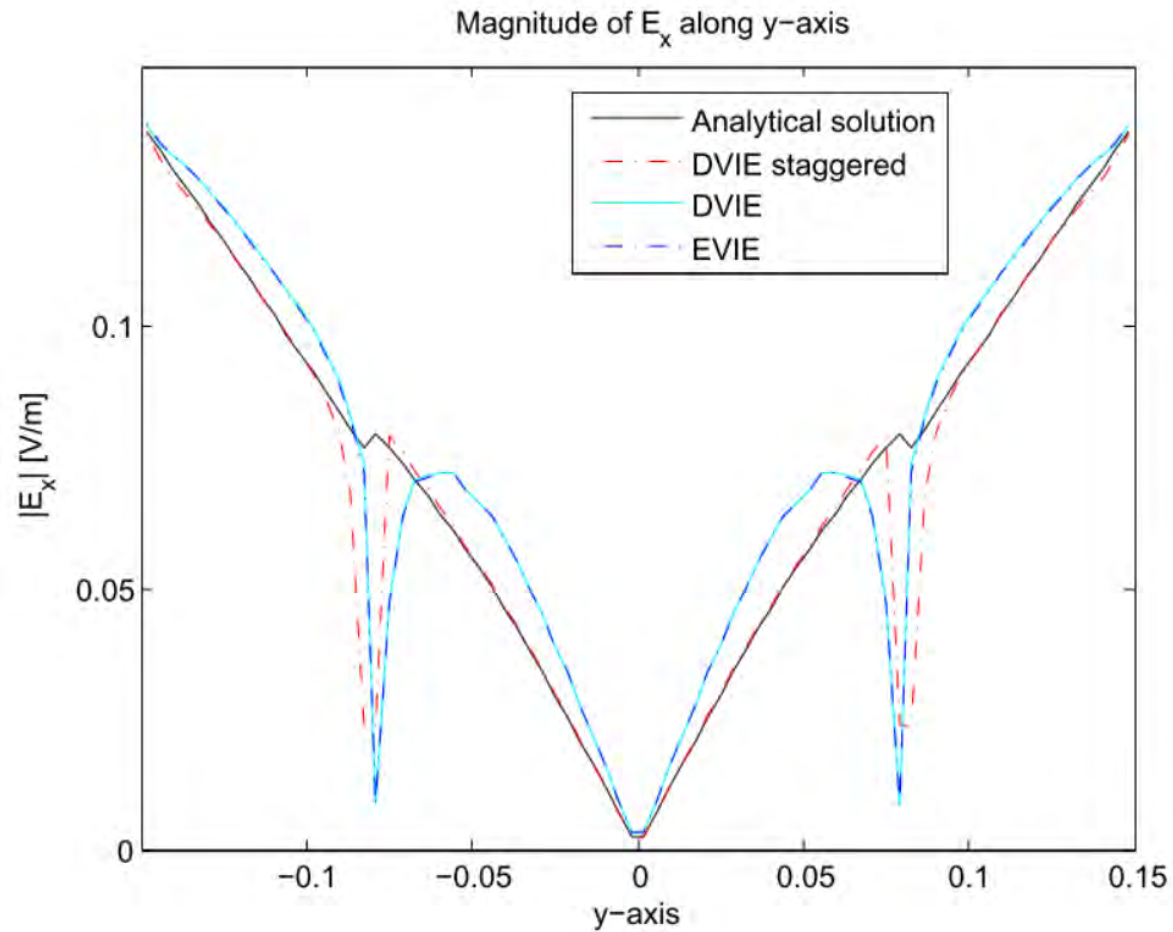
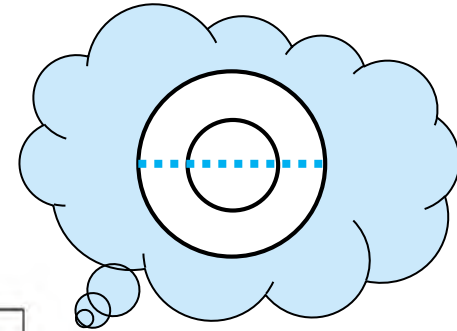
# Results

## Scattering on a Two-Layer Conducting Cylinder



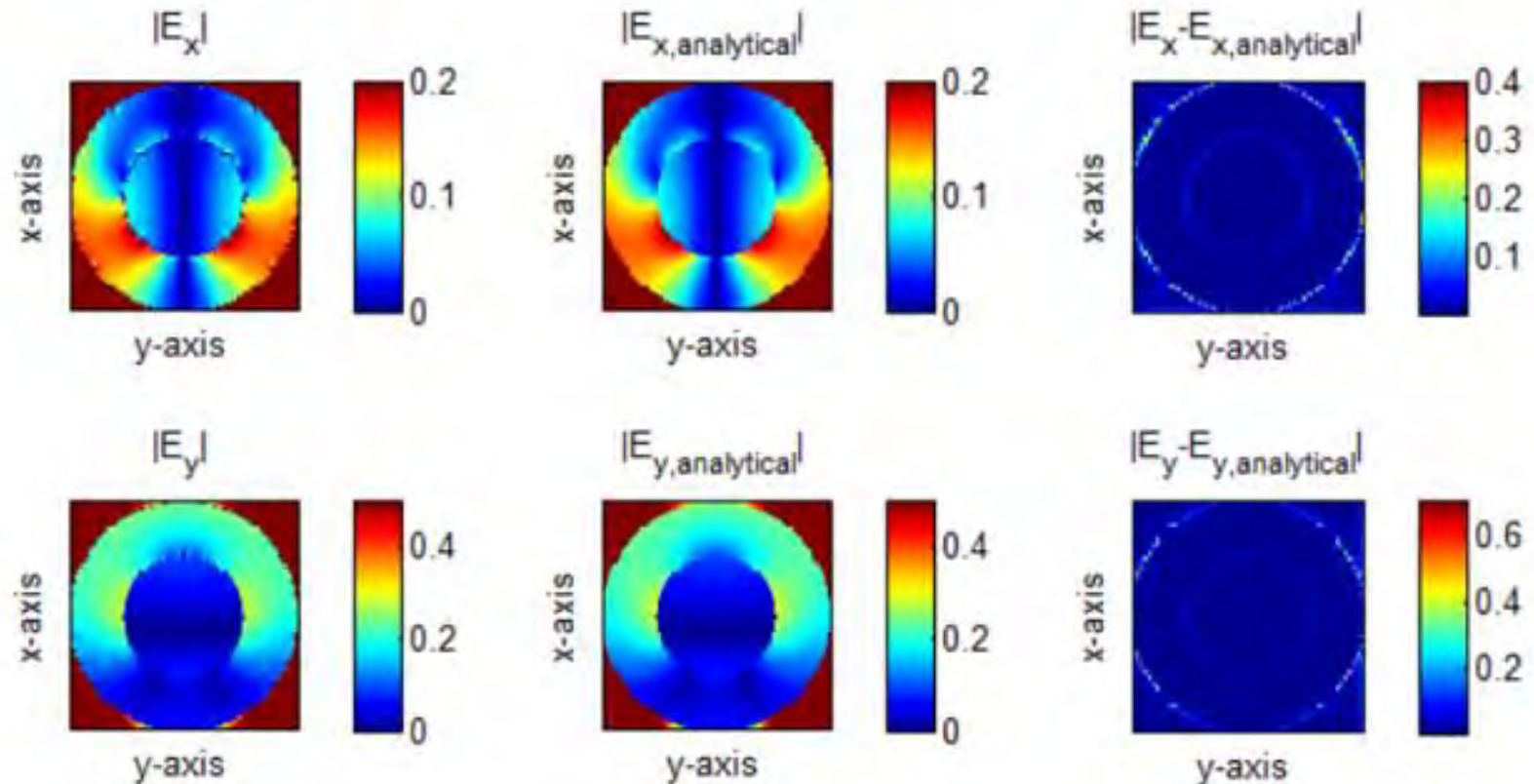
# Results

## Comparison of EVIE and DVIE



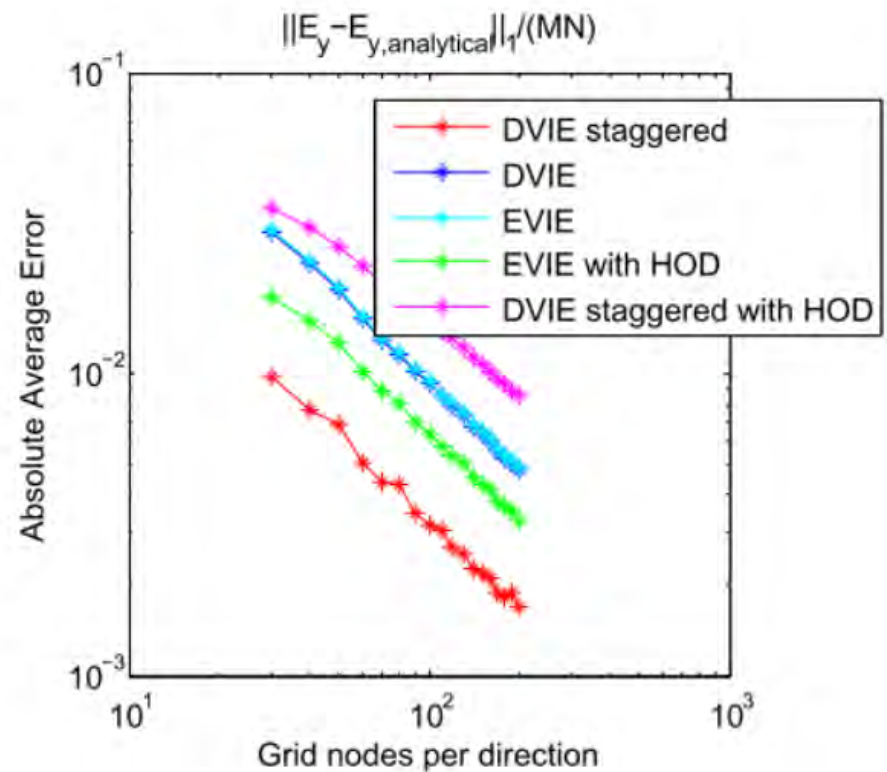
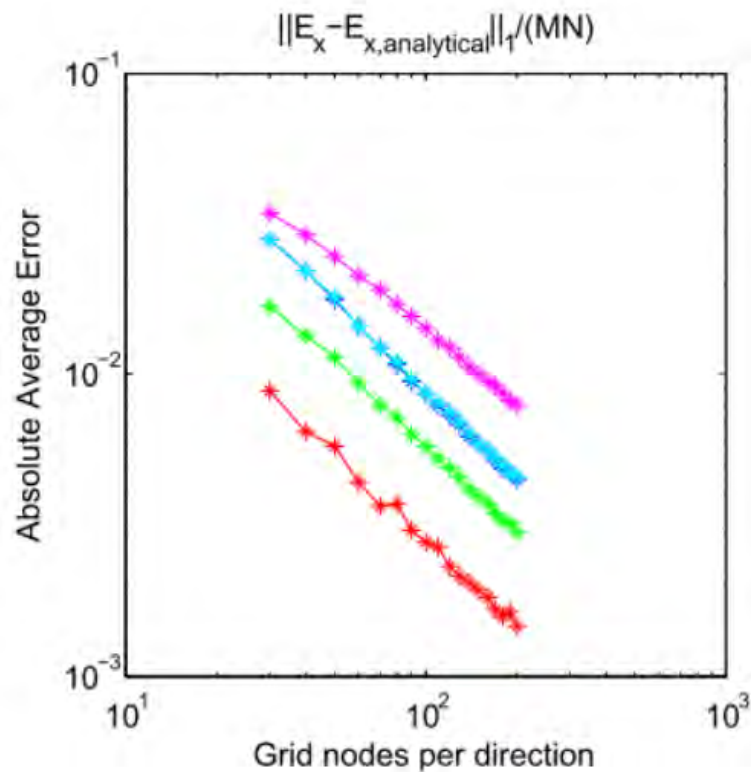
# Results

## Scattering on a Two-Layer Conducting Cylinder



# Results

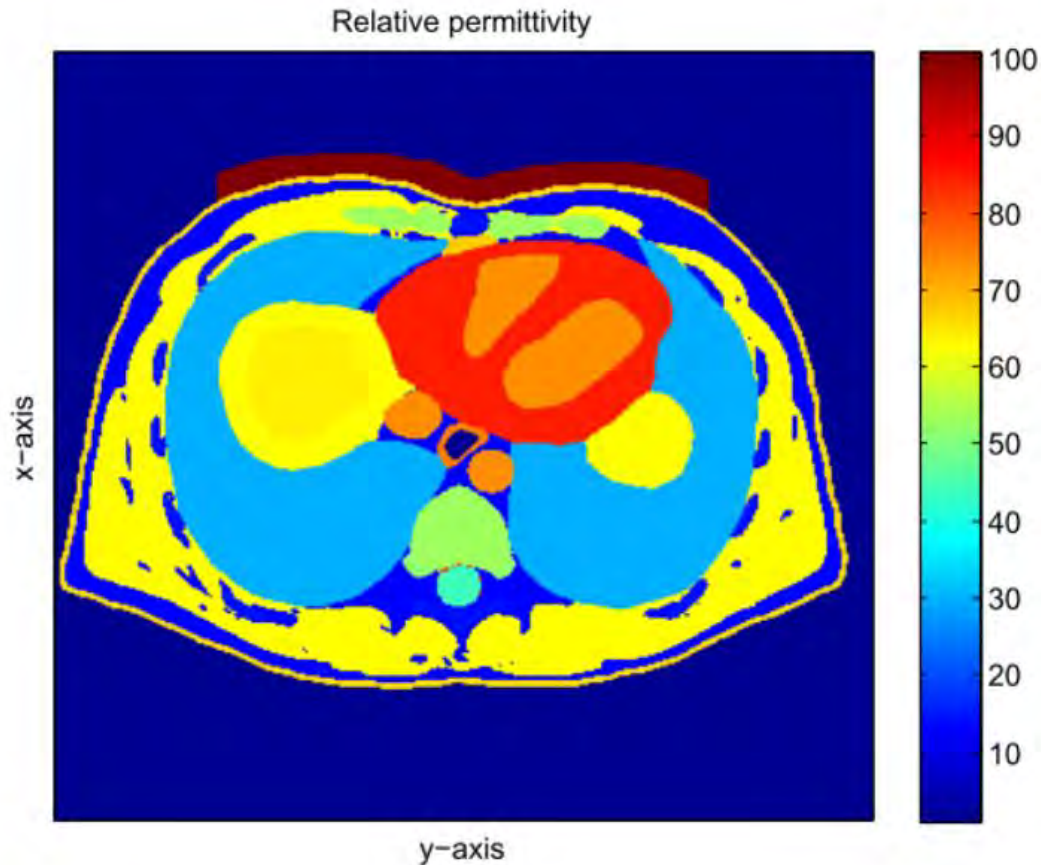
## Global Error Propagation





# Human Body Simulations

## Scattering on a Human Body with Dielectric Pad

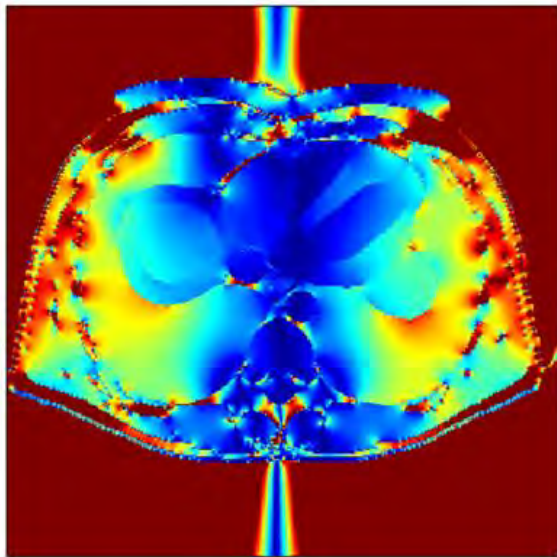




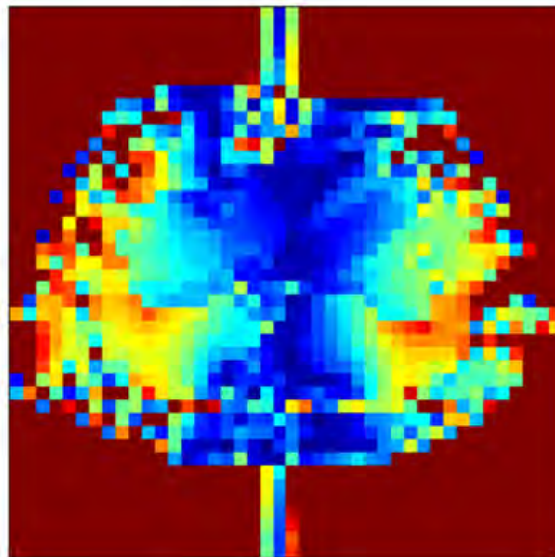
# Human Body Simulations

Comparison of the staggered and non-staggered grid

High resolution

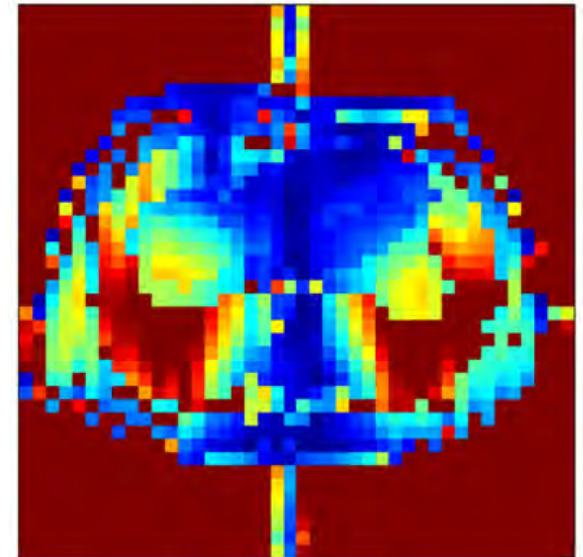


Low resolution



Staggered grid

Low resolution



Non-staggered grid

# Outline

- Dielectric pads
- Volume Integral Equation
- Different Discretization schemes
- Designing pads
- **Perturbing Maxwell's equations**
- Reduced order modeling

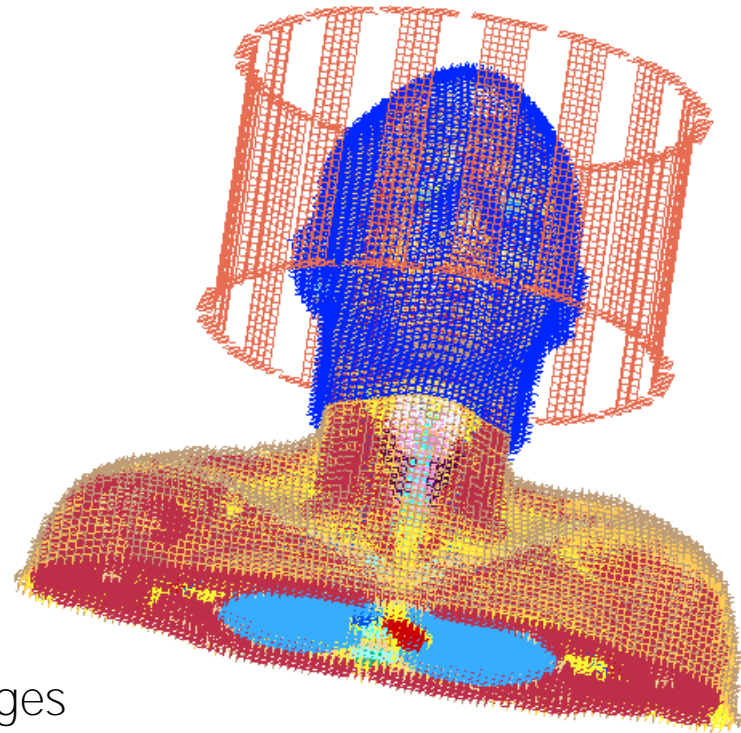
accuracy

speed

# Simulating dielectrics

## Useful properties

- Many trial-and-error simulations
- Choose optimum pad afterwards
- Time consuming (days)
- Properties
  - For every simulation only the pad changes
  - Pad close to ROI
  - Pad design domain is small w.r.t. computational domain



# Designing dielectrics

## Minimization

- Define a cost function

$$C(\text{pad}) = \frac{1}{2} \frac{\| \mathbf{b}_1^{+;\text{simulated}}(\text{pad}) - \mathbf{b}_1^{+;\text{desired}} \|_2^2}{\| \mathbf{b}_1^{+;\text{desired}} \|_2^2}$$

- IN: desired  $B_1^+$  field as target field in region of interest
- OUT: properties dielectric pad

# Maxwell's Equations

Solve for the fields

$$-\nabla \times \mathbf{H} + \sigma \mathbf{E} + j\omega \epsilon \mathbf{E} = -\mathbf{J}^{\text{ext}}$$

$$\nabla \times \mathbf{E} + j\omega \mu \mathbf{H} = \mathbf{0}$$

- Finding electromagnetic fields amounts to solving for  $\mathbf{f}$

$$\mathbf{Df} = -\mathbf{q}$$

- With EM fields

$$\mathbf{f} = \begin{bmatrix} \mathbf{e}_x \\ \mathbf{e}_y \\ \mathbf{e}_z \\ h_x \\ h_y \\ h_z \end{bmatrix}$$

and sources

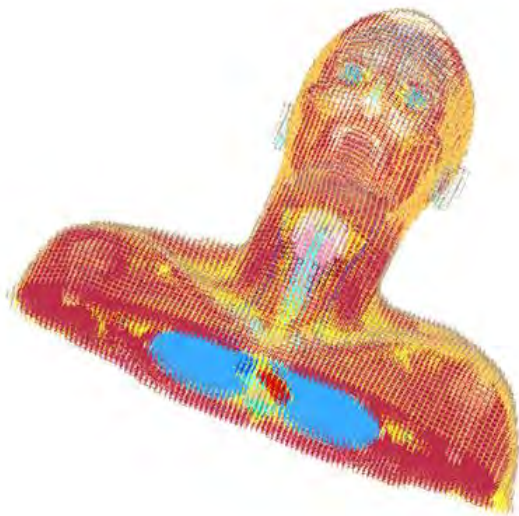
$$\mathbf{q} = \begin{bmatrix} j_x \\ j_y \\ j_z \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

# Maxwell's Equations

## Perturbation

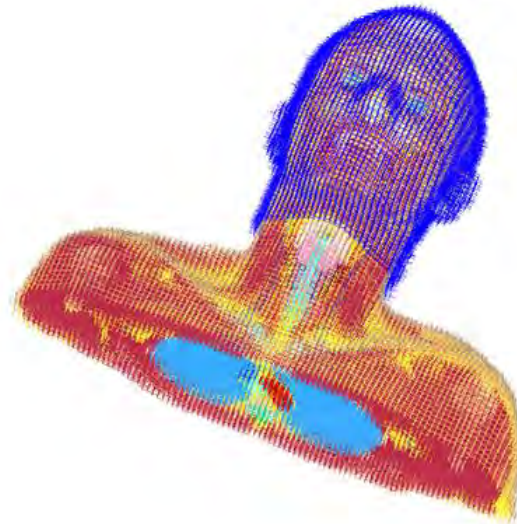
Antennas + body

$$Df = -q$$



Antennas + body + pad

$$(D + SX_{\text{pad}}S^T) f = -q$$



# Maxwell's Equations

## Woodbury-identity

- Solving the system

$$\mathbf{f} = -(\mathbf{D} + \mathbf{S}\mathbf{X}_{\text{pad}}\mathbf{S}^T)^{-1} \mathbf{q}$$

- Perturbing matrix inverse using Woodbury-identity

$$\mathbf{f} = -\mathbf{D}^{-1}\mathbf{q} + \mathbf{D}^{-1}\mathbf{S}(\mathbf{I}_P + \mathbf{X}_{\text{pad}}\mathbf{S}^T\mathbf{D}^{-1}\mathbf{S})^{-1}\mathbf{X}_{\text{pad}}\mathbf{S}^T\mathbf{D}^{-1}\mathbf{q}$$

- Which electromagnetically speaking represents

$$\mathbf{b}_1^+ = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+J}(\mathbf{I}_P - \mathbf{X}_{\text{pad}}\mathbf{G}^{EJ})^{-1}\mathbf{X}_{\text{pad}}\mathbf{e}^{\text{no pad}}$$

- But, we make it readable again

$$\mathbf{b}_1^+ = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+J}\mathbf{A}^{-1}\mathbf{b}$$



# Maxwell's Equations

## Woodbury-identity

- Solving the system

$$\mathbf{f} = -(\mathbf{D} + \mathbf{S}\mathbf{X}_{\text{pad}}\mathbf{S}^T)^{-1} \mathbf{q}$$

- Perturbing matrix inverse using Woodbury-identity

$$\mathbf{f} = -\mathbf{D}^{-1}\mathbf{q} + \mathbf{D}^{-1}\mathbf{S}(\mathbf{I}_P + \mathbf{X}_{\text{pad}}\mathbf{S}^T\mathbf{D}^{-1}\mathbf{S})^{-1}\mathbf{X}_{\text{pad}}\mathbf{S}^T\mathbf{D}^{-1}\mathbf{q}$$

Size  $\sim 10^7$

- Which electromagnetically speaking represents

$$\mathbf{b}_1^+ = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+J}(\mathbf{I}_P - \mathbf{X}_{\text{pad}}\mathbf{G}^{EJ})^{-1}\mathbf{X}_{\text{pad}}\mathbf{e}^{\text{no pad}}$$

but requires  $\sim 30$  GB of data  
Size  $\sim 10^4$

- But, we make it readable again

$$\mathbf{b}_1^+ = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+J}\mathbf{A}^{-1}\mathbf{b}$$

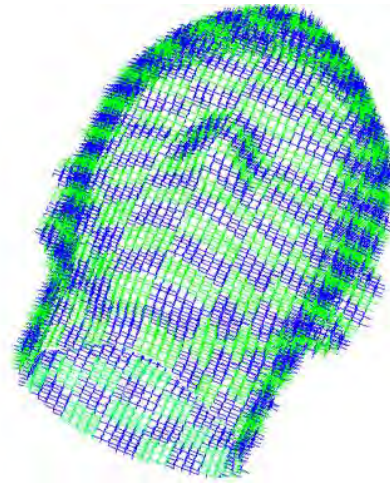


# Practical considerations

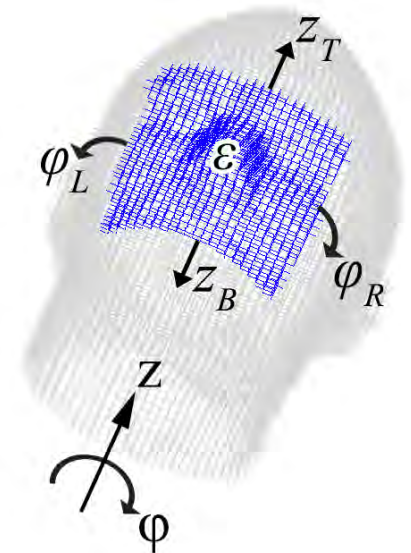
## Parametrization



30,000 edges



400 subdomains



5 parameters



combine edges



enforce rectangular pads

# Practical considerations

## Updating equations

- Before: control every edge

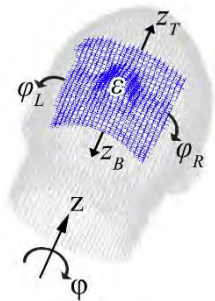
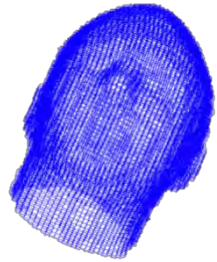
$$\mathbf{b}_1^+(n) = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+J} \mathbf{A}(n)^{-1} \mathbf{b}(n)$$

- Now: only p variables to define a rectangular pad

$$\mathbf{b}_1^+(p) = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+J} \mathbf{A}(p)^{-1} \mathbf{b}(p)$$

- Still 30 GB and of same size: [reduced order modeling](#)

$$\mathbf{b}_1^+(p) = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+J} \mathbf{j}(p)$$



# Reduced order modeling

## New basis

- Original model with

$$\mathbf{b}_1^+(\mathbf{p}) = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+} \mathbf{j}(\mathbf{p}) \quad \mathbf{j}(\mathbf{p}) = \mathbf{A}(\mathbf{p})^{-1} \mathbf{b}(\mathbf{p})$$

- Find approximation for current density  $\mathbf{j}(\mathbf{p})$

$$\mathbf{j}_r(\mathbf{p}) = \alpha_1(\mathbf{p}) \mathbf{u}_1 + \alpha_2(\mathbf{p}) \mathbf{u}_2 + \dots + \alpha_r(\mathbf{p}) \mathbf{u}_r = \mathbf{U}_r \mathbf{a}_r(\mathbf{p})$$

- Introduces a residual

$$\mathbf{r} = \mathbf{A}(\mathbf{p}) \mathbf{j}_r(\mathbf{p}) - \mathbf{b}(\mathbf{p})$$

# Reduced order modeling

## Galerkin condition

- Residual

$$r = A(p)j_r(p) - b(p)$$

$$r = A(p)U_r a_r(p) - b(p)$$

- Galerkin condition

$$U_r^H r = 0$$

- Two equations, two unknowns:

$$a_r(p) = [U_r^H A(p) U_r]^{-1} U_r^H b(p)$$

# Reduced order modeling

## Update equations

- We started with

$$\mathbf{b}_1^+(\mathbf{p}) = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+ \mathbf{J}} \mathbf{j}(\mathbf{p})$$

- Approximated it by

$$\mathbf{b}_1^+(\mathbf{p}) = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+ \mathbf{J}} \mathbf{U}_r^H \mathbf{a}_r(\mathbf{p})$$

- And end up with

$$\mathbf{b}_1^+(\mathbf{p}) = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+ \mathbf{J}} \mathbf{U}_r^H \underbrace{[\mathbf{U}_r^H \mathbf{A}(\mathbf{p}) \mathbf{U}_r]^{-1}}_{\text{Size } r \text{ instead of } 10^4} \mathbf{U}_r^H \mathbf{b}(\mathbf{p})$$

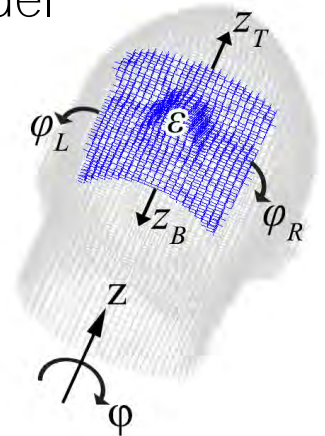
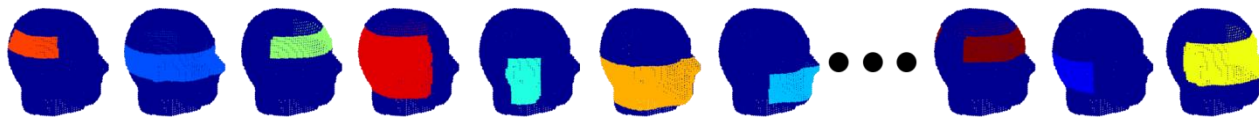
What to choose for the basis  $\mathbf{U}_r$ ?

# Reduced order modeling

## Projection Based Model Reduction

- Create snapshots: random pad parameters in the model

$$S = [j_1(p_1) \dots j_S(p_S)]$$



- Compute SVD of S

and take  $r$  most significant LSV

$$S = U \Sigma V^H$$

$$U_r = U(1:r, :)$$

# Reduced order modeling

## Complexity

- We take the 500 first LSV as new basis

$$\mathbf{b}_1^{+,r}(\mathbf{p}) = \mathbf{b}_1^{+;\text{no pad}} + \mathbf{G}^{B_1^+ \mathbf{J}} \mathbf{U}_r^H \underbrace{[\mathbf{U}_r^H \mathbf{A}(\mathbf{p}) \mathbf{U}_r]^{-1}}_{\text{Size: } 10^4 \Rightarrow 500} \mathbf{U}_r^H \mathbf{b}(\mathbf{p})$$

Size:  $10^4 \Rightarrow 500$

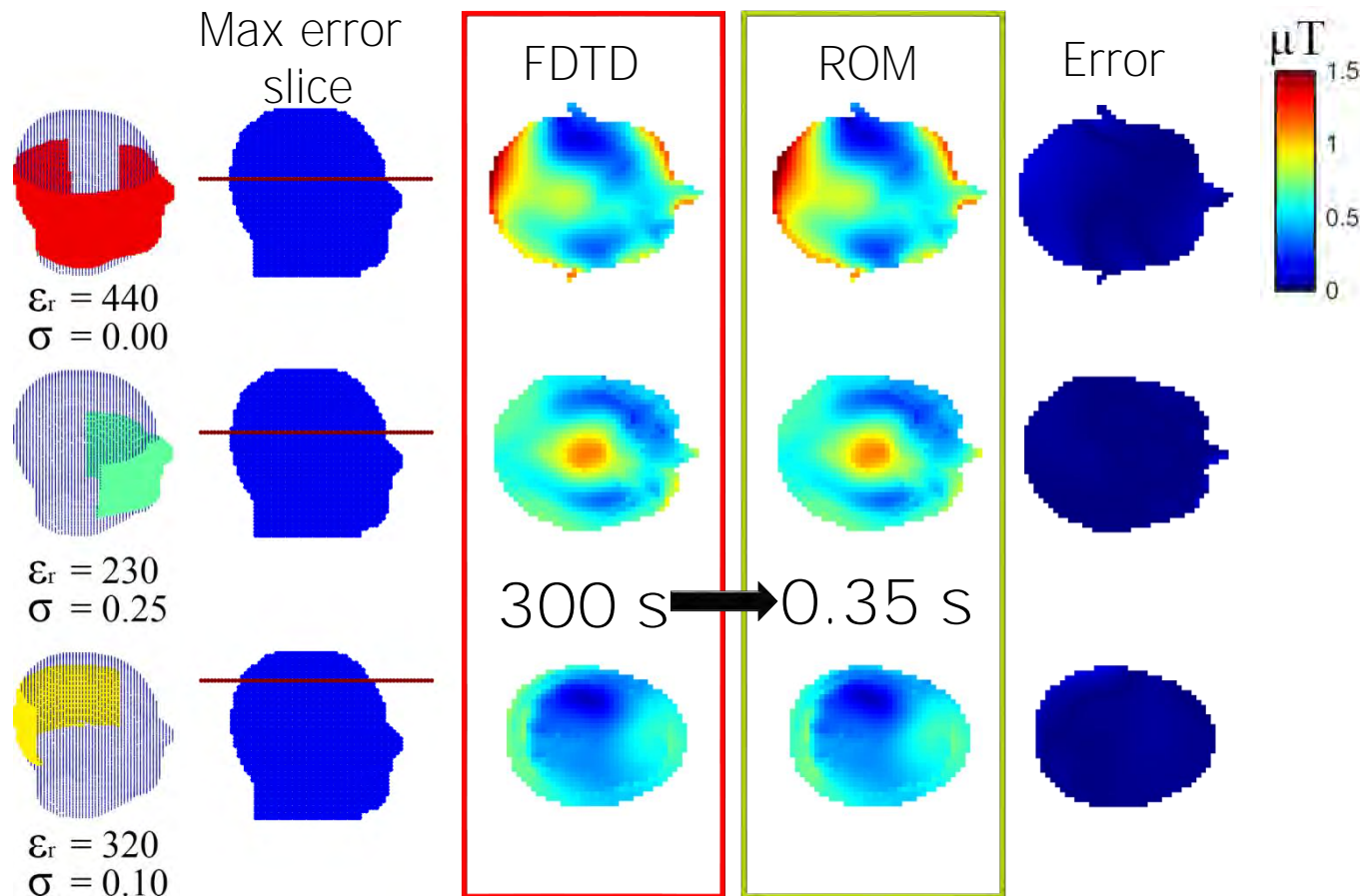
Data: 30 GB  $\Rightarrow$  1 GB

- Reduced order models introduce errors in fields



# Reduced order modeling

## Comparison $B_1^+$ fields





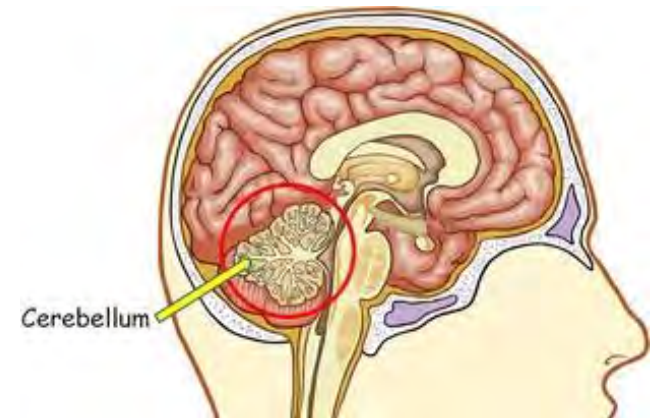
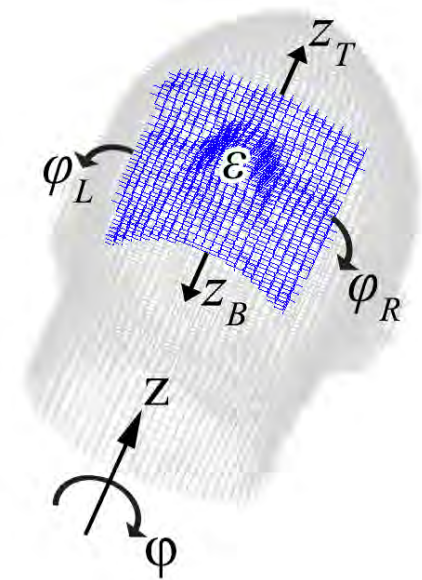
# Pad design

## Minimization

- Define a cost function

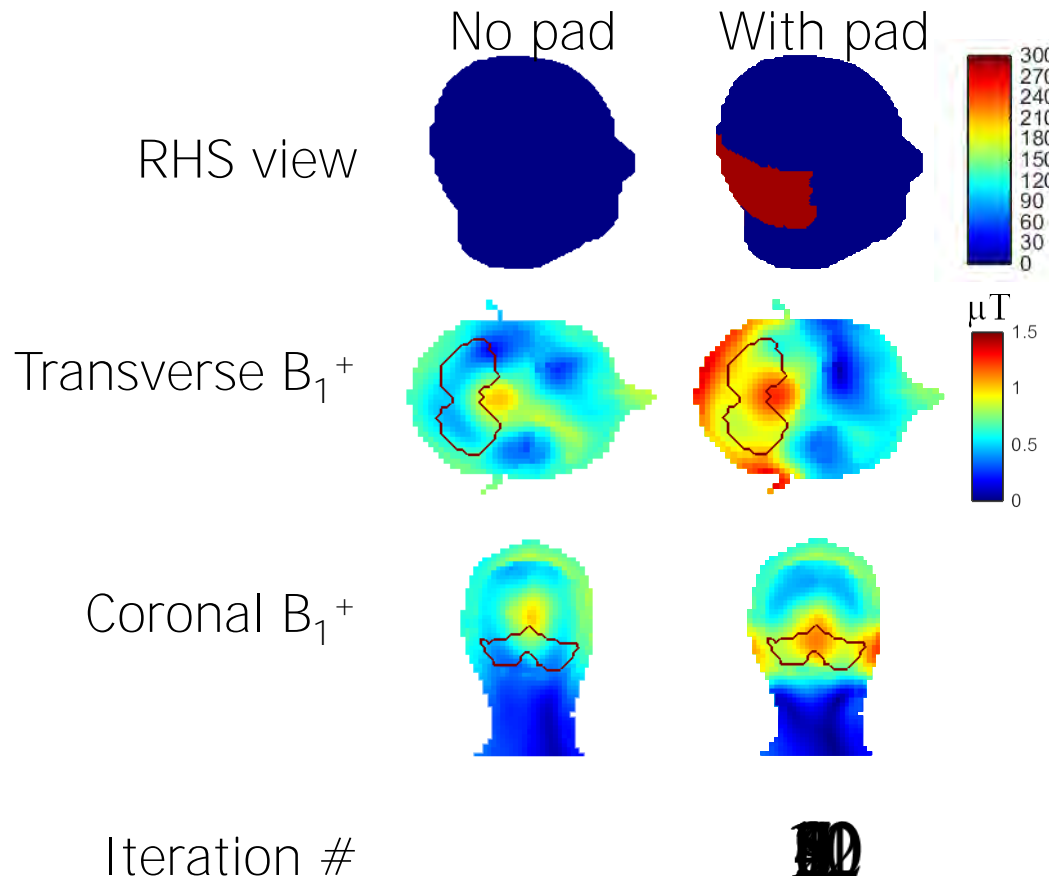
$$\mathbf{C}(\mathbf{p}) = \frac{1}{2} \frac{\|\mathbf{b}_1^{+;r}(\mathbf{p}) - \mathbf{b}_1^{+;\text{desired}}\|_2^2}{\|\mathbf{b}_1^{+;\text{desired}}\|_2^2}$$

- We set a desired  $B_1^+$  field as target field
- Solved using Gauss-Newton approach



# Pad design

## Optimization



Pad found in 30 seconds:

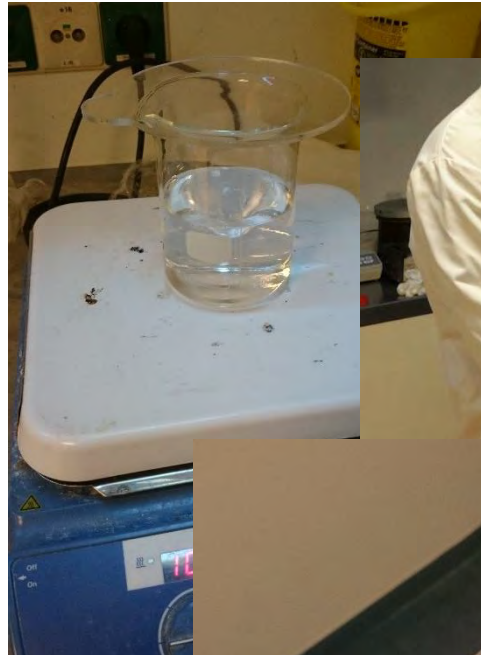
$$L \times W \times H = 35 \times 10 \times 1 \text{ cm}^3$$

$$\epsilon_r = 295$$

$$\sigma = 0.25 \text{ S/m}$$

# Pad design

## Fabrication



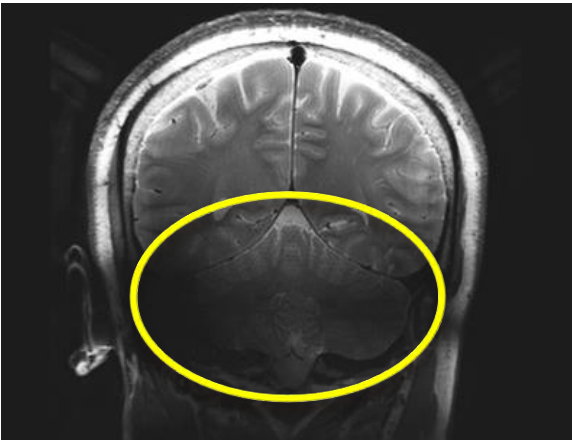
# Results

Without pad

T1 GRE

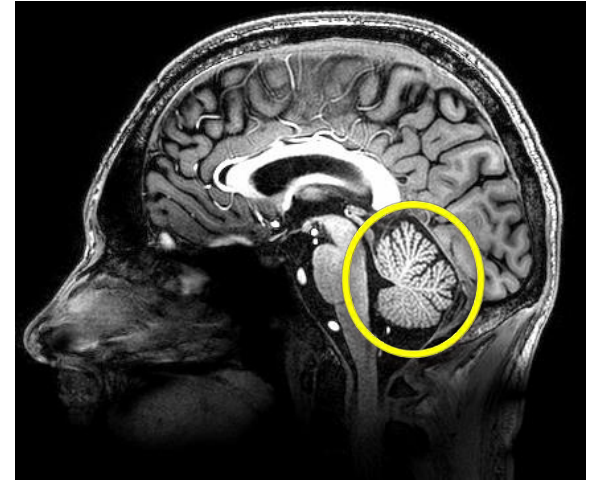


T2 TSE

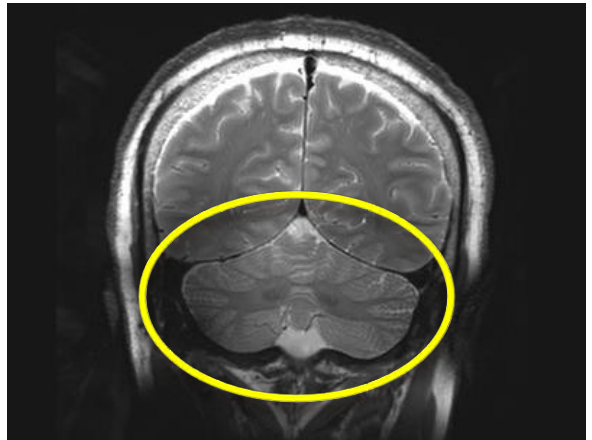


With pad

T1 GRE



T2 TSE



# Summary/ Conclusion

There are different methods to solve **Maxwell's** equations

The VIE approach is an efficient method for solving **Maxwell's** equations, which can be used to construct **Green's** tensors

ROM reduces complexity with small loss in accuracy

Designing dielectrics in 30 seconds instead of days





# Modeling and Designing High Permittivity Pads for MRI

Kirsten Koolstra and Jeroen van Gemert  
May 31<sup>st</sup>, 2017