

The Discrete Steklov-Poincaré Operator using dual Polynomials

Multilevel and Multigrid Methods

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Constrained minimization

Given a bounded domain Ω with a Lipschitz continuous boundary $\partial\Omega$. Find the vector field \mathbf{u} with minimal L^2 -norm subject to the constraint $\nabla \cdot \mathbf{u} = f$ for a given $f \in L^2(\Omega)$.

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Characterization of the affine subspace $\nabla \cdot \mathbf{u} = f$, generally not easy therefore, constraint included by means of Lagrange multipliers

Mixed formulation

For $\mathbf{v} \in H(\text{div}; \Omega)$ and $q \in L^2(\Omega)$ consider the functional

$$\mathcal{L}(\mathbf{v}, q) = \|\mathbf{v}\|_{L^2(\Omega)}^2 + \int_{\Omega} q (\nabla \cdot \mathbf{v} - f) \, d\Omega.$$

Mixed formulation

The optimality conditions for this functional are given by

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Find $\mathbf{u} \in H(\operatorname{div}; \Omega)$ and $p \in L^2(\Omega)$ such that

$$\begin{cases} (\mathbf{v}, \mathbf{u})_{L^2(\Omega)} + (\nabla \cdot \mathbf{v}, p)_{L^2(\Omega)} &= 0 & \forall \mathbf{v} \in H(\operatorname{div}; \Omega) \\ (q, \nabla \cdot \mathbf{u})_{L^2(\Omega)} &= (q, f)_{L^2(\Omega)} & \forall q \in L^2(\Omega) \end{cases}$$

This problem is **well-posed**. Note that here we solve the **Poisson problem** for p with right hand side functions f and $p = 0$ along the boundary $\partial\Omega$.

For non-homogeneous Dirichlet boundary conditions we take $p_b \in H^{\frac{1}{2}}(\partial\Omega)$ and modify the mixed formulation to

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For every $p_b \in H^{\frac{1}{2}}(\partial\Omega)$

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yields a **unique solution \mathbf{u}** and therefore a **unique $\gamma(\mathbf{u}) = \mathbf{u} \cdot \mathbf{n} \in H^{-\frac{1}{2}}(\partial\Omega)$** .

So we can define the map **$S : H^{\frac{1}{2}}(\partial\Omega) \rightarrow H^{-\frac{1}{2}}(\partial\Omega)$** given by **$S(p_b) = \mathbf{u} \cdot \mathbf{n}$** .

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The **Steklov-Poincaré operator** is:

- 1 **linear**;
- 2 The operator is **not** surjective, because

$$\int_{\partial\Omega} \mathbf{u} \cdot \mathbf{n} \, d\Gamma = \int_{\Omega} f \, d\Omega$$

- 3 The operator is **not** injective. For $f \equiv 0$, $S(p) = 0$, when $p = \text{const.}$

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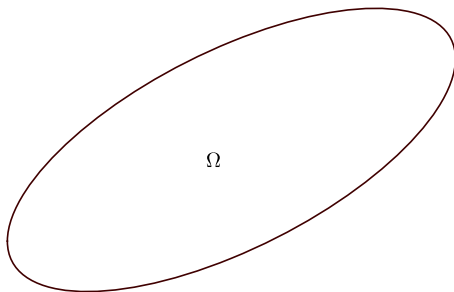
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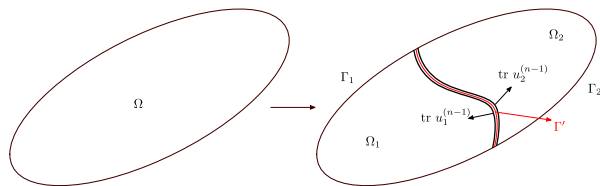
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Domain Decomposition I



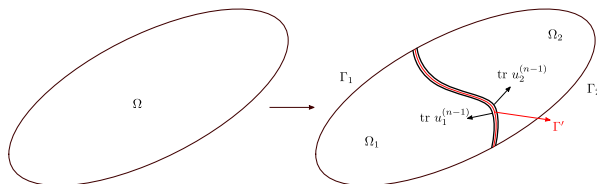
The mixed formulation can be solved on a single domain.

Domain Decomposition I



Domain decomposition

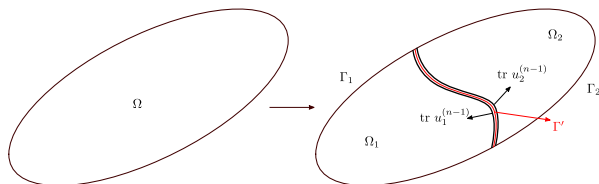
Domain Decomposition I



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Advantage: Problems on sub-domains are **smaller** and can be **solved in parallel**

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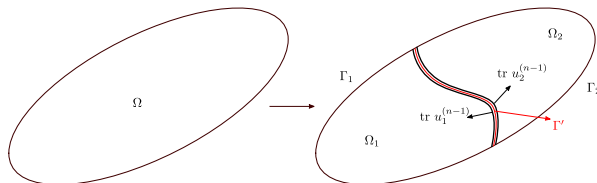


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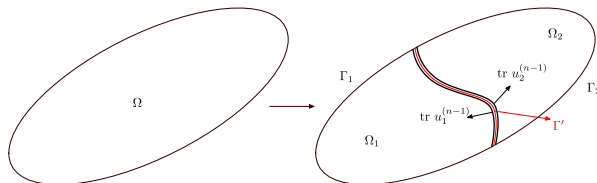
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Find $\mathbf{u}_i \in H(\text{div}; \Omega_i)$, $p_i \in L^2(\Omega_i)$ and $\bar{p} \in H^{\frac{1}{2}}(\Gamma')$ such that for $f_i \in L^2(\Omega_i)$

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$$\forall \mathbf{v}_i \in H(\text{div}; \Omega_i), \quad \forall q_i \in L^2(\Omega_i), \quad \forall \bar{q} \in H^{\frac{1}{2}}(\Gamma').$$

Domain Decomposition II

Domain decomposition

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$$\forall \mathbf{v}_i \in H(\operatorname{div}; \Omega_i), \quad \forall q_i \in L^2(\Omega_i), \quad \forall \bar{q} \in H^{\frac{1}{2}}(\Gamma').$$

This system is **symmetric and indefinite**.

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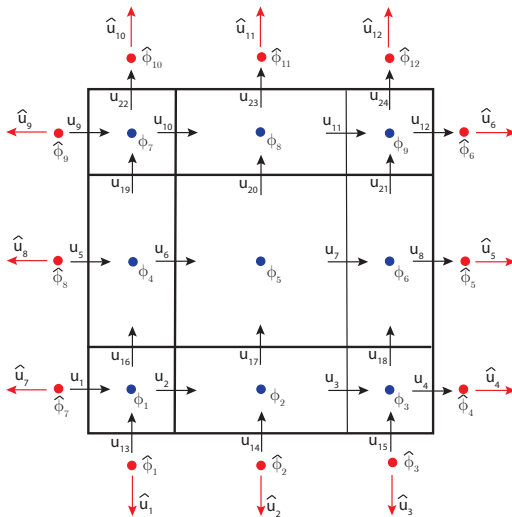
This system is **symmetric and indefinite**.

We can eliminate the internal unknowns within the elements and set up an equations for **the interface unknowns only**. This equation can be directly expressed in terms of the Steklov-Poincaré operators in both sub-domains.

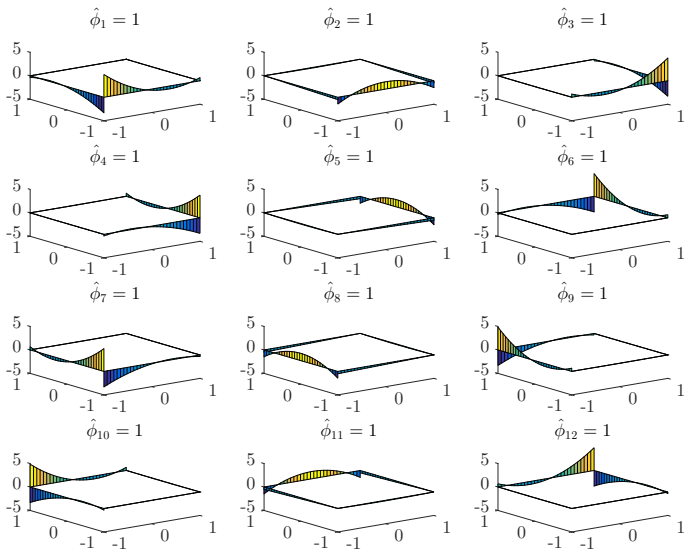
Interface equation

$$\langle S_1(\bar{p}), \bar{q} \rangle + \langle S_2(\bar{p}), \bar{q} \rangle = 0 \quad \forall \bar{q} \in H^{\frac{1}{2}}(\Gamma').$$

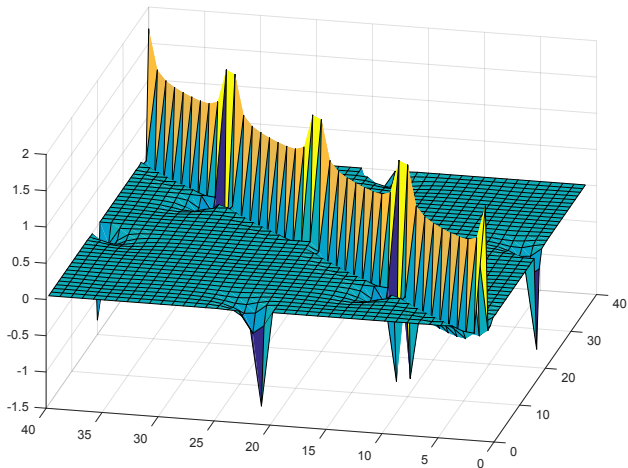
Discrete representation



Pressure-flux relation



Pressure-flux relation



Discrete Steklov-Poincaré matrix I

Domain decomposition

Find $\mathbf{u}_i \in H(\operatorname{div}; \Omega_i)$, $p_i \in L^2(\Omega_i)$ and $\bar{p} \in H^{\frac{1}{2}}(\Gamma')$ such that for $f_i \in L^2(\Omega_i)$

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$$\forall \mathbf{v}_i \in H(\operatorname{div}; \Omega_i), \quad \forall q_i \in L^2(\Omega_i), \quad \forall \bar{q} \in H^{\frac{1}{2}}(\Gamma').$$

Discrete Steklov-Poincaré matrix I

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$$\left\{ \begin{array}{l} (\mathbf{v}_i, \mathbf{u}_i)_{L^2(\Omega_i)} + (\nabla \cdot \mathbf{v}_i, p_i)_{L^2(\Omega_i)} - \int_{\Gamma' \cap \partial\Omega_i} \bar{p}(\mathbf{v}_i \cdot \mathbf{n}_i) \, d\Gamma = \int_{\partial\Omega \cap \partial\Omega_i} \bar{p}_b(\mathbf{v}_i \cdot \mathbf{n}_i) \, d\Gamma \\ (q_i, \nabla \cdot \mathbf{u}_i)_{L^2(\Omega_i)} = (q_i, f_i)_{L^2(\Omega_i)} \\ - \int_{\Gamma' \cap \partial\Omega_i} \bar{q}(\mathbf{u}_i \cdot \mathbf{n}_i) \, d\Gamma = 0 \end{array} \right.$$

$$\forall \mathbf{v}_j \in H(\operatorname{div}; \Omega_j), \quad \forall q_j \in L^2(\Omega_j), \quad \forall \bar{q} \in H^{\frac{1}{2}}(\Gamma').$$



Discrete Representation

$$\begin{pmatrix} \mathbb{M}_i^{(1)} & \mathbb{E}^{d,d-1^T} & \mathbb{N}_{i,l}^T \\ \mathbb{E}^{d,d-1} & \mathbf{0} & \mathbf{0} \\ \mathbb{N}_{i,l} & \mathbf{0} & \mathbf{0} \end{pmatrix} \begin{pmatrix} \mathbf{u}_i \\ \mathbf{p}_i \\ \bar{\mathbf{p}} \end{pmatrix} = \begin{pmatrix} -\mathbb{N}_{i,B}^T \hat{\mathbf{p}}_i \\ \mathbf{f}_i \\ \mathbf{0} \end{pmatrix}$$

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$$\begin{pmatrix} \mathbb{M}_i^{(1)} & \mathbb{E}^{d,d-1^T} & \mathbb{N}_{i,I}^T \\ \mathbb{E}^{d,d-1} & 0 & 0 \\ \mathbb{N}_{i,I} & 0 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{u}_i \\ \mathbf{p}_i \\ \bar{\mathbf{p}} \end{pmatrix} = \begin{pmatrix} -\mathbb{N}_{i,B}^T \hat{\mathbf{p}}_i \\ \mathbf{f}_i \\ 0 \end{pmatrix}$$



Discrete Steklov-Poincaré matrix

$$\mathbb{S}_i = -\mathbb{N}_{i,I} \mathbb{M}_i^{(1)-1} \left(\mathbb{M}_i^{(1)} - \mathbb{E}^{d,d-1^T} \left(\mathbb{E}^{d,d-1} \mathbb{M}_i^{(1)-1} \mathbb{E}^{d,d-1^T} \right)^{-1} \mathbb{E}^{d,d-1} \right) \mathbb{M}_i^{(1)-1} \mathbb{N}_{i,I}^T$$

Discrete Steklov-Poincaré matrix II

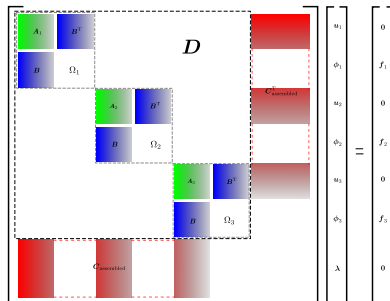
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Discrete Steklov-Poincaré matrix II

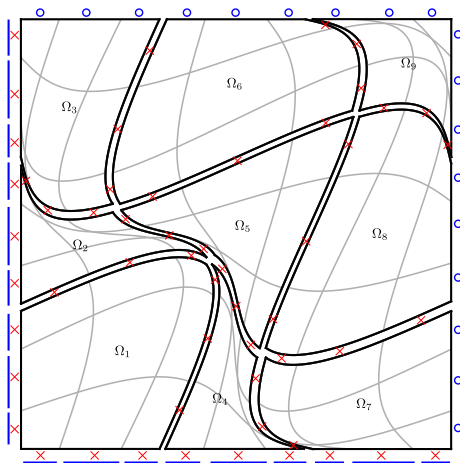
$$\mathbb{E}^{d,d-1} = \begin{pmatrix} -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

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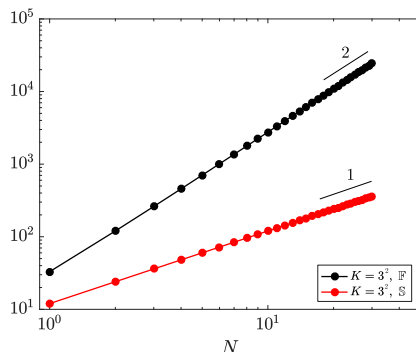
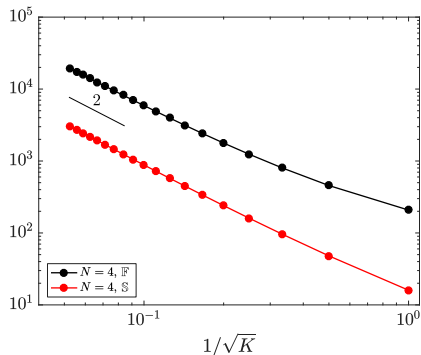
$$\begin{pmatrix} \mathbb{M}_I^{(1)} & \mathbb{E}^{d,d-1^T} & \mathbb{N}_{I,I}^T \\ \mathbb{E}^{d,d-1} & 0 & 0 \\ \mathbb{N}_{I,I} & 0 & 0 \end{pmatrix} \begin{pmatrix} u_i \\ p_i \\ \bar{p} \end{pmatrix} = \begin{pmatrix} -\mathbb{N}_{I,B}^T \hat{p}_i \\ f_i \\ 0 \end{pmatrix}$$



Numerical test

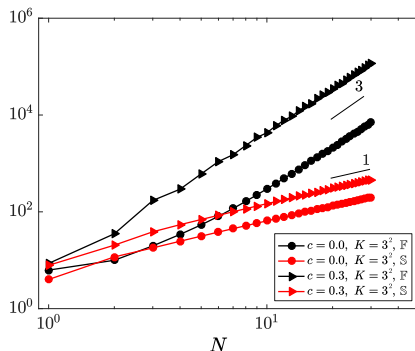
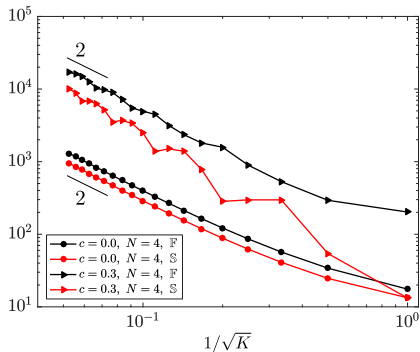


Numerical test



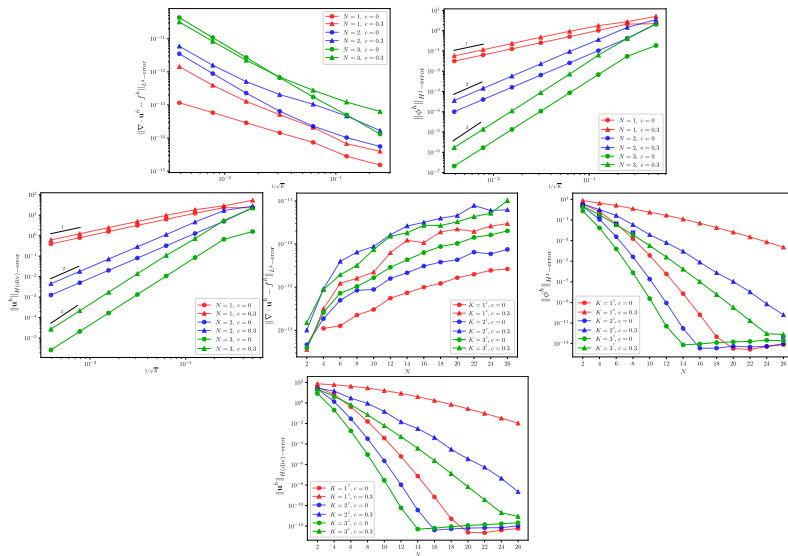
Growth of the size of the full system \mathbb{F} and the assembled Steklov-Poincaré matrix \mathbb{S} as a function of the mesh size (left) and the polynomial degree (right).

Numerical test



Growth of the condition number of the full system \mathbb{F} and the assembled Steklov-Poincaré matrix \mathbb{S} as a function of the mesh size (left) and the polynomial degree (right).

Numerical test



Thank you

Questions?

If you are interested, please send an email and we will send you a manuscript of this work.