Attribute-Controlled Traffic Data Augmentation Using Conditional Generative Models

Elective in AI Final Project

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Presentation outline

1. Introduction
   - Autonomous vehicles
   - Generative Adverserial Networks (GANs)
2. Attribute Interpolation with Conditional Generative Models
   - Architecture
   - Dataset and tools
   - Preprocessing and Training
3. Results
4. Conclusions

Outline

Introduction

Autonomous vehicular systems

Use case in self-driving cars

- Require real-wrold data to train perception systems
- RGB images collected and further manually annotated
- Imbalanced datsets

Motivation and goals

- Balanced dataset
- Present day solutions:
  - 3D simulations $\rightarrow$ not realstic and models are susceptible to synthetic artifacts.

Introduction

Generative Adverserial Networks (GANs)

Advantages

- Able to capture the intricacies of natural images
- Generate natural, realistic transformations of input images.
- Allow for latent space interpolation (cheap data generation!)

What are GANs?

- Introduced in 2014 by Ian Goodfellow et al.
- Class of deep learning methods for unsupervised learning
- The aim is to be able to generate sample with the same features of the examples contained in a dataset

Introduction

Generative Adverserial Networks (GANs)

Basic intuition of generative models

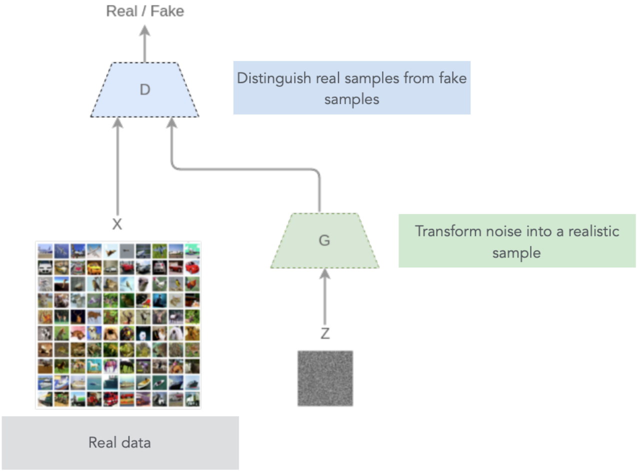
- A model $P(x;\theta)$ that we can draw samples from i.e. Gussian Mixture Model.
- GANs: pit a generator (G) and discriminator (D) against each other to play a minimax game.
- Goal is to capture the data distribution $p_{data}(x)$
- $P(x;\theta) \approx p_{data}(x)$

Why are they important?

- Model the probabilty density of images
- Generate novel content
- Artistic applications, Image completion and many more

Introduction

Generative Adverserial Networks (GANs)



source: https://indico.cern.ch/event/655447/contributions/2742176/attachments/1551254/2437141/gan-intro-iml.pdf

Outline

Architecture

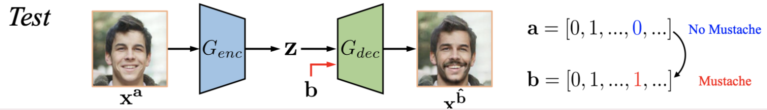
Formulation part 1

Binary attributes editing

- Two subnetworks:
  - Encoder G_{enc} and Decoder G_{dec}
  - Discriminator D and Attribute Classifier C
  - $a = [a_1 \ldots a_n]$ (original) and $b = [b_1 \ldots b_n]$ (desired).

Desired testing scenario

- $z = G_{enc}(x^a)$ latent representation
- $x^{\hat{b}} = G_{dec}(z, b)$ decoding
- $x^{\hat{b}} = G_{dec}(G_{enc}(x^a), b)$ whole editing process $\rightarrow$ unsupervised



Architecture

Formulation part 2

Training Roles

1. Attribute classifier: contrain images $x^{\hat{b}}$ to desired attributes
2. Adverserial learning: visual reality of $x^{\hat{b}}$
3. Reconstruction learning:
   - make z conserve enough information for attribute-excluding details recovery
   - Enable G_{dec} to restore attribute-excluding details. $x^{\hat{a}} = G_{dec}(z, a)$ should approximate itself.

Architecture

Overview

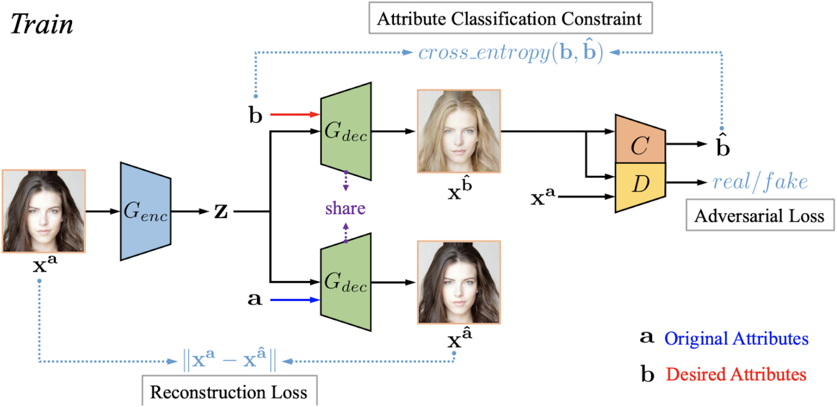


Figure: Architecture from the original Att-GAN paper [1]

Architecture

Losses

Losses

- Attribute Classification Constraint (cls):
  - $\min_{G_{enc}, G_{dec}} \mathcal{L}_{cls_g}$
  - $\min_{C} \mathcal{L}_{cls_c}$
- Reconstruction (rec): $\min_{G_{enc}, G_{dec}} \mathcal{L}_{rec}$ (l_1 loss)
- Adversarial (adv) (W-GAN style):
  - $\min_{|D \leq 1|} \mathcal{L}_{adv_d}$
  - $\min_{G_{enc}, G_{dec}} \mathcal{L}_{adv_g}$

Overall objective

- Generator: $\min_{G_{enc}, G_{dec}} = \lambda_1 \mathcal{L}_{rec} + \lambda_2 \mathcal{L}_{cls_g} + \mathcal{L}_{adv_g}$
- Discriminator: $\min_{D,C} = \lambda_1 \mathcal{L}_{cls_c} + \mathcal{L}_{adv_d}$

Architecture

network

<table>
<tr><th>Encoder (G_{enc})</th><th>Decoder (G_{dec})</th><th>Discriminator (D)</th><th>Classifier (C)</th></tr>
<tr><td>Conv(64,4,2), BN, Leaky ReLU</td><td>DeConv(1024,4,2), BN, ReLU</td><td colspan="2">Conv(64,4,2), LN/IN, Leaky ReLU</td></tr>
<tr><td>Conv(128,4,2), BN, Leaky ReLU</td><td>DeConv(512,4,2), BN, ReLU</td><td colspan="2">Conv(128,4,2), LN/IN, Leaky ReLU</td></tr>
<tr><td>Conv(256,4,2), BN, Leaky ReLU</td><td>DeConv(256,4,2), BN, ReLU</td><td colspan="2">Conv(256,4,2), LN/IN, Leaky ReLU</td></tr>
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<tr><td>Conv(1024,4,2), BN, Leaky ReLU</td><td>DeConv(3,4,2), Tanh</td><td colspan="2">Conv(1024,4,2), LN/IN, Leaky ReLU</td></tr>
<tr><td></td><td></td><td>FC(1024), LN/IN, Leaky ReLU</td><td>FC(1024), LN/IN, Leaky ReLU</td></tr>
<tr><td></td><td></td><td>FC(1)</td><td>FC(2), Sigmoid</td></tr>
</table>

Figure: Network details [1]

Dataset and tools

description

Datasets

- BDD100K: A Diverse Driving Video Database with Scalable Annotation Tooling [3]

Tools

Python 3.6 with Tensorflow 1.14 GPU

Preprocessing

Data storage

TF-records

- very useful tool for storing large data efficiently for training
- reintializable iterator
- optimizing performance through parallel data transformation

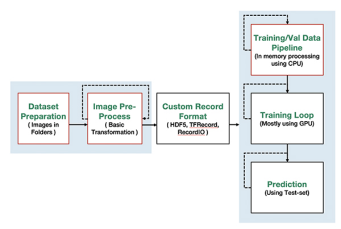

Figure: pipeline source: http://www.adeveloperdiary.com/

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Results

from the paper

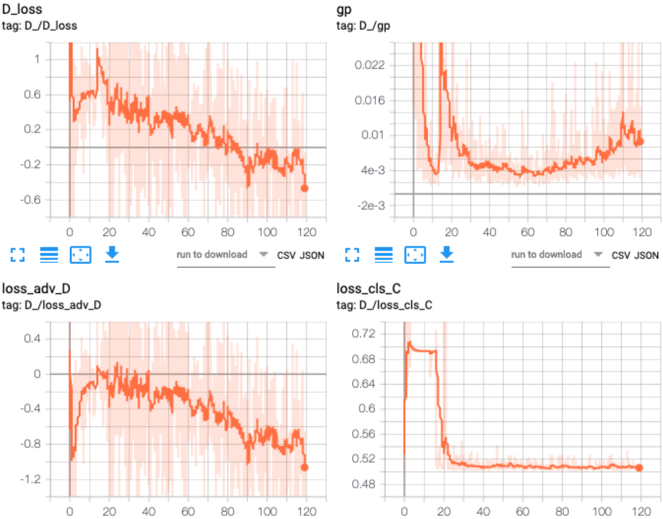
Figure: Results from the re-implemented paper [2]

Results

Our implementation

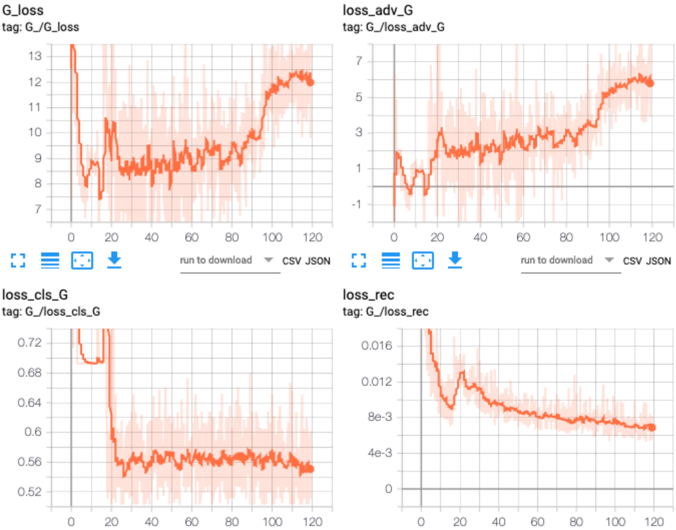
Results

Discriminator Losses



Results

Generator Losses



Results

Training

hyperparemeters

- Adam optimizer with a decaying learning rate
- batch size 64, 128, 100+ epochs

Overcoming issues

- Balancing Generator and Discriminator weight updates
- Minibatch discrimination
- Adding noise
- Two Time-Scale Update Rule (different learning rates for G and D)

Outline

Conclusions

Conclusions and possible improvements

1. Use cropped images
2. Very unstable training phase, needs multiple overhauls to see results
3. Data Augmentation idea is a success.

Attributes	Day		Night	
Type	Original	Generated	Original	Generated
Count	54563	19178	19178	54563

References

- Original Paper: Zhenliang He, Wangmeng Zuo, Meina Kan, Shiguang Shan, and Xilin Chen. Attgan: Facial attribute editing by only changing what you want. arxiv preprint, 2017.
- Re-implemented paper: Mukherjee, Amitangshu et al. "Attribute-Controlled Traffic Data Augmentation Using Conditional Generative Models." CVPR Workshops (2019).
- Dataset: Fisher Yu, Wenqi Xian, Yingying Chen, Fangchen Liu, Mike Liao, Vashisht Madhavan, Trevor Darrell. BDD100K: A Diverse Driving Video Database with Scalable Annotation Tooling arXiv, 2018
- Dataset link: `https://bdd-data.berkeley.edu/`
- Code: `https://github.com/Ostyk/self-driving-AttGAN`

How training GANs looks like from reading papers vs how it actually is